

Week 3 – Data Link Layer

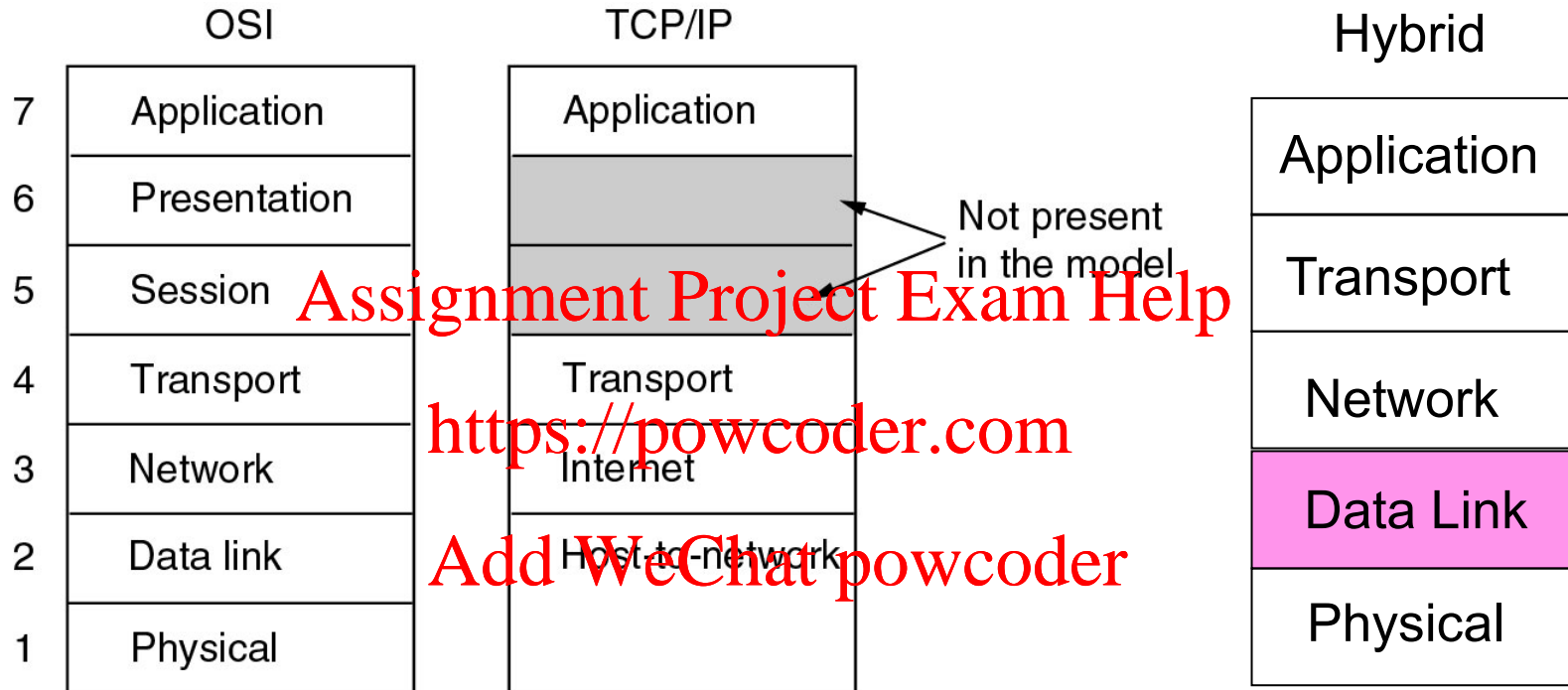
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COMP90007 Internet Technologies
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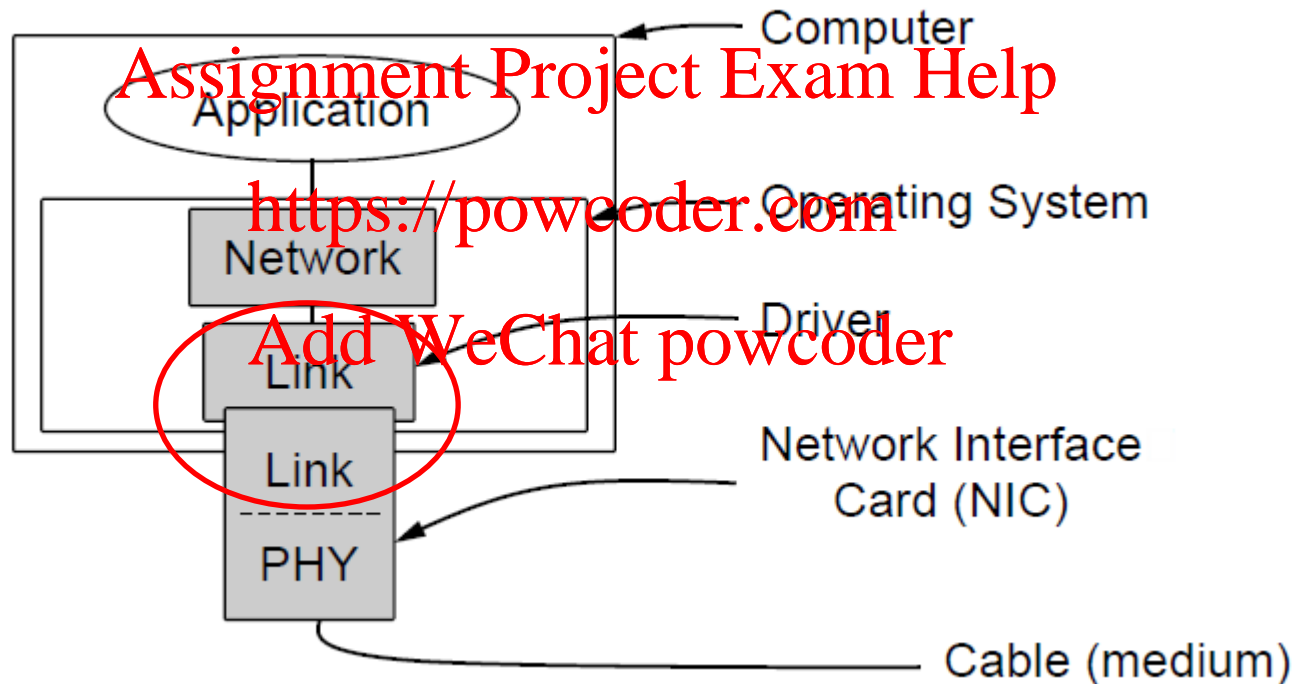
Semester 2, 2021

The Data Link Layer in OSI and TCP/IP



- **Reliable, efficient** communication of “**frames**” between two adjacent machines.
- Handles transmission errors and flow control.

Typical Implementation

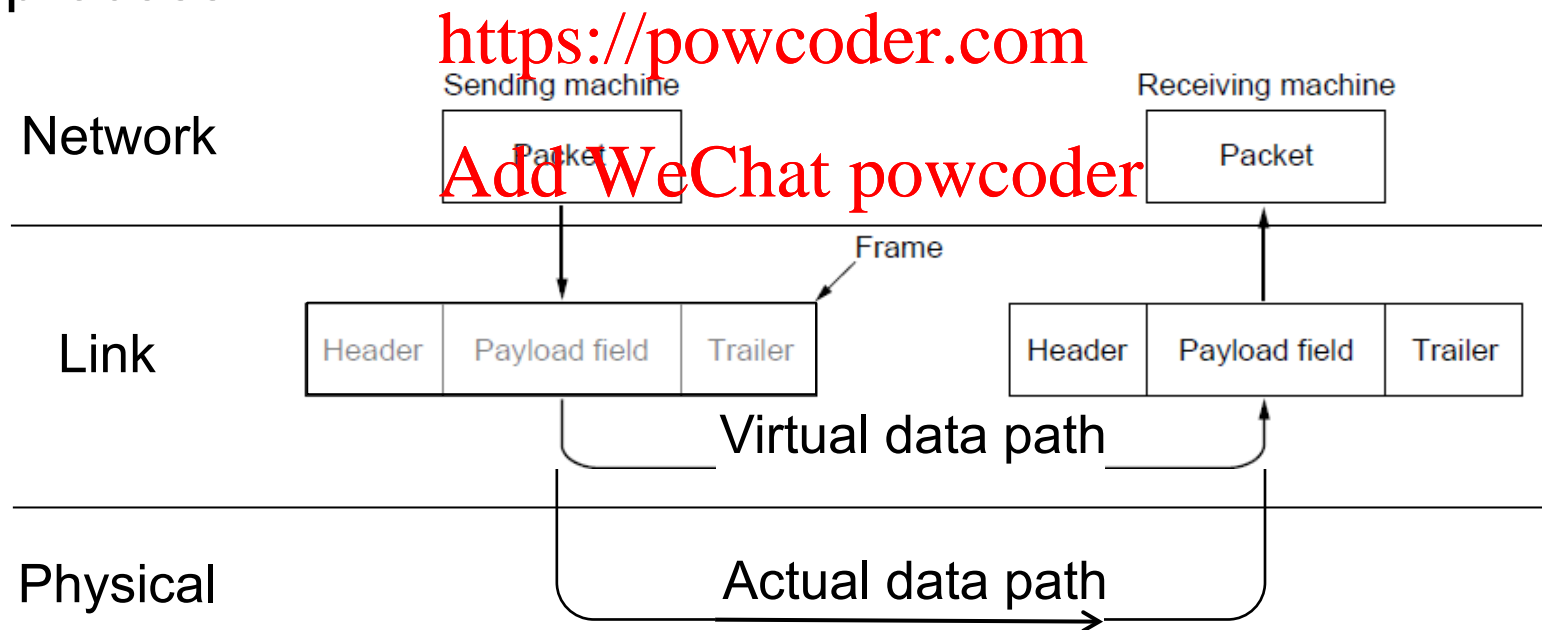


Functions of the Data Link Layer

- Functions of the data link layer:
 1. Provide a well-defined service interface to network layer
 2. Handling transmission errors
 3. Data flow regulation
- Primary process:
 - ❑ Take **packets** from network layer, and encapsulate them into **frames**

Relation Between Packets and Frames

- Each frame contains a header, a payload and a trailer
- Link layer accepts packets from the network layer, and encapsulates them into frames that it sends using the physical layer; reception is the opposite process



Type of Services

- **Connection-Oriented vs Connectionless:**
Whether a connection is setup before sending a message
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- **Acknowledged vs Unacknowledged:**
Whether the receiver gives the sender an acknowledgement upon receiving the message
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Services Provided to Network Layer

- Transferring data from the network layer on source host to the network layer on destination host

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- Services provided:

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- Unacknowledged connectionless service
- Acknowledged connectionless service
- Acknowledged connection-oriented service

Unacknowledged Connectionless Service

- Source host transmits independent frames to recipient host with no acknowledgement
- No logical connection establishment or release
- No lost frame recovery mechanism (or left to higher levels)
- Applications:
 - ❑ Ethernet LANs
 - ❑ Real-time traffic, e.g. voice

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Acknowledged Connectionless Service

- Source host transmits independent frames to recipient host with acknowledgement
- No logical connection establishment or release <https://powcoder.com>
- Each frame is individually acknowledged, and retransmitted if lost or errors [Add WeChat powcoder](#)
- Application: Wireless – IEEE 802.11 WiFi

Acknowledged Connection-Oriented Service

- Source host transmits independent frames to recipient host after connection establishment and with acknowledgement
- Connection established and released (communicate rate and details of message)
- Frames are numbered, counted, acknowledged with logical order enforced
- Application: Unreliable links such as satellite channel

Framing (1)

- Framing: breaks raw bit stream into discrete units
 - Physical layer provides no guarantee a raw stream of bits is error free
 - The primary purpose of framing is to provide some level of reliability over the unreliable physical layer
 - Checksums can be computed and embedded at the source, then computed and compared at the destination
- $\text{checksum} = f(\text{payload})$

Framing (2)

- Methods:
 - ❑ Character (Byte) count
 - ❑ Flag bytes with byte stuffing
 - ❑ Start and end flags with bit stuffing
- Most data link protocols use a combination of character count and one other method

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Character Count

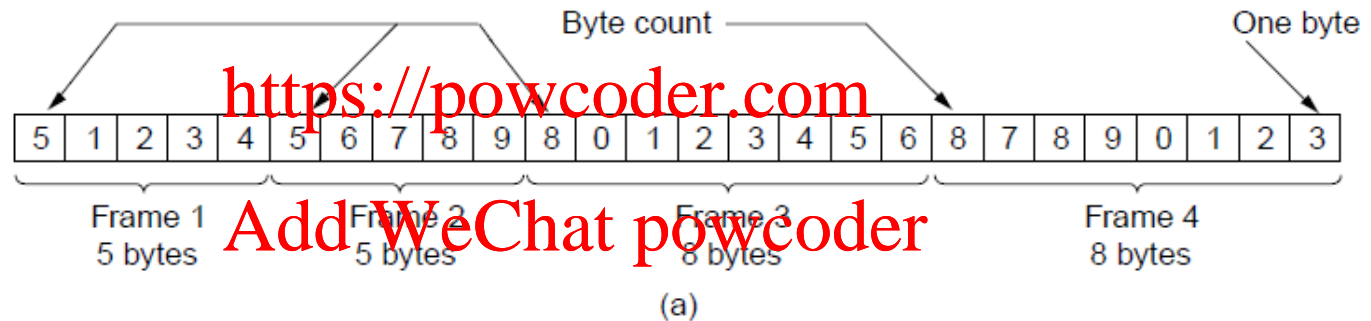
- Uses a field in the frame header to specify the number of characters in a frame

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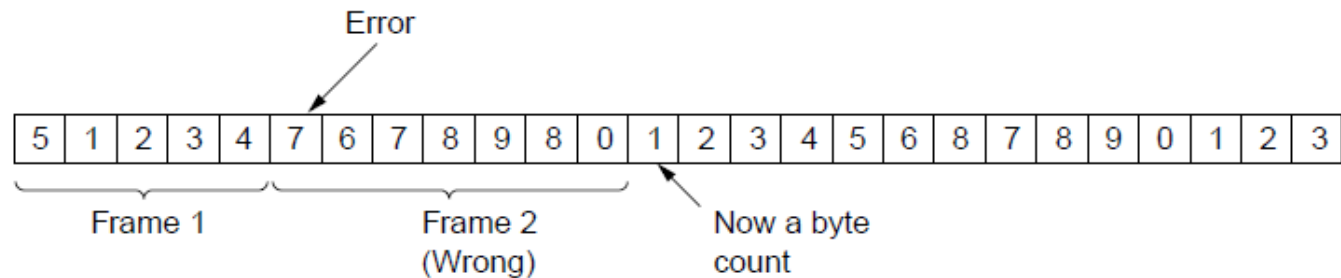
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No error



Case with error



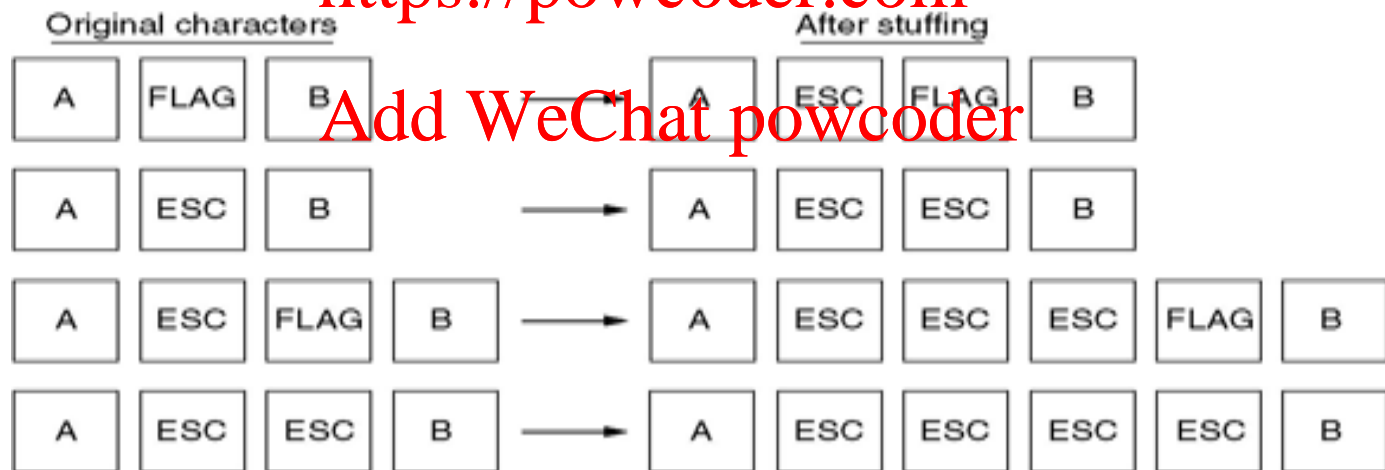
Flag Bytes with Byte Stuffing

- Each frame starts and ends with a special byte -“flag byte”



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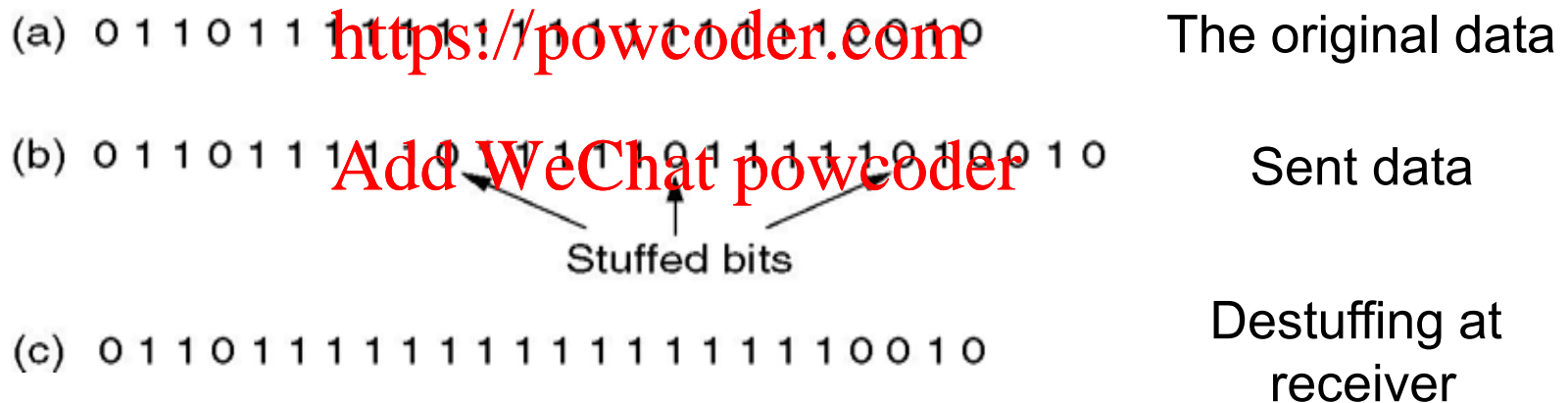


(b)

Start and End Flags with Bit Stuffing

- Frames contain an arbitrary number of bits
- Each frame begins and ends with a special bit pattern **01111110**

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Insert 0 after five ones (11111)

Error Control

- Adding check bits to ensure that a garbled message by the physical layer is not considered as the original message by the receiver
- Error Control deals with
 - **Detecting** the error, and retransmitting
 - **Correcting** the error

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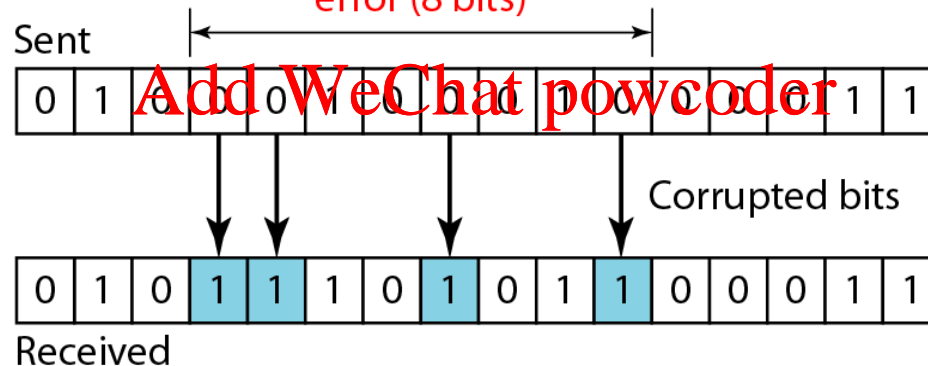
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Error Detection and Correction (1)

- Physical media may be subject to errors
- Errors may occur **randomly or in bursts**
 - ❑ Single-bit error
 - ❑ Burst error: two or more bits have changed

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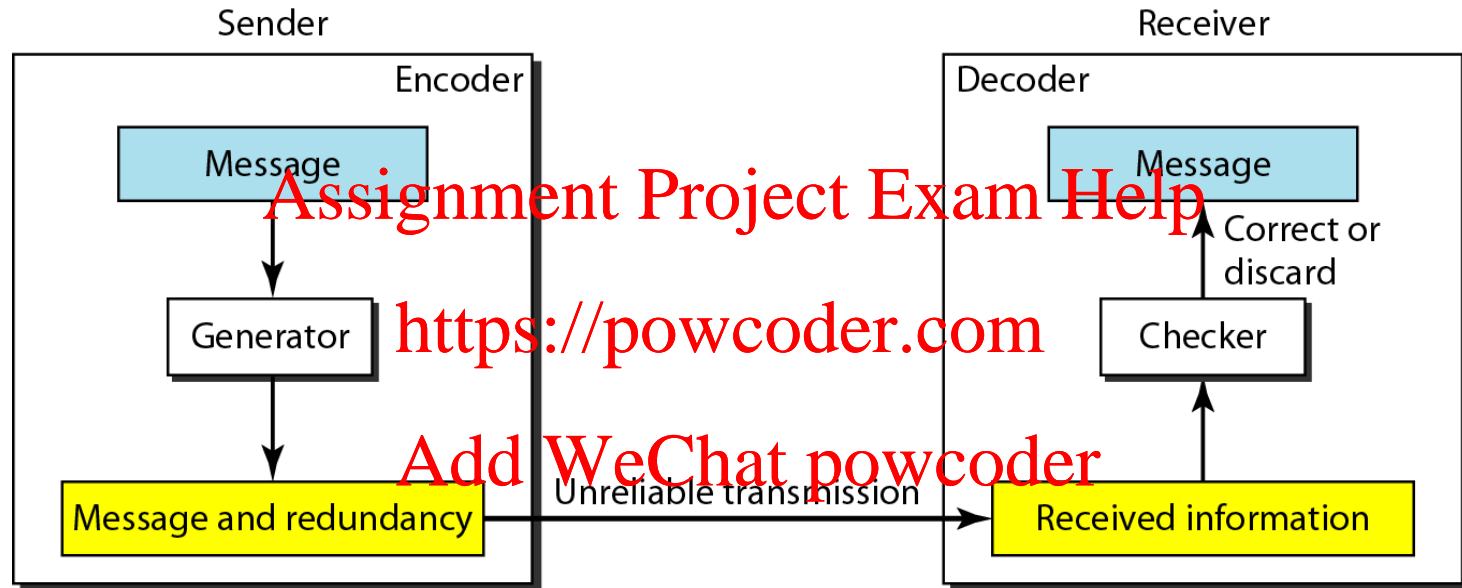
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Bursts of errors are easier to detect but harder to resolve

Error Detection and Correction (2)

- Resolution needs to occur before handing data to network layer



- Key issues
 - ❑ **Fast** mechanism and **low computational overhead**
 - ❑ **Minimum amount of extra bits** sent with the data
 - ❑ Detection of **different kinds of error**

Example

- Repeat the bits, if a copy is different than the other, there is an error
 - 0 -> 000 and 1 -> 111
- What is the overhead?
- Given the 3 bits received,
 - How many errors can receiver detect?
 - How many errors can receiver correct?
 - What is the minimum number of errors that can fail the algorithm?

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Error Bounds – Hamming Distance

- A code turns **data** of n bits into **codewords** of $n+k$ bits
- Hamming distance is the **minimum bit flips** to turn one valid codeword into any other valid one.
 - Example with 4 codewords of 10 bits ($n=2, k=8$):
 - 0000000000
 - 0000011111
 - 1111100000
 - 1111111111Hamming distance is 5
- A code with Hamming distance:
 - $d+1 \rightarrow$ can detect up to d errors (e.g., 4 errors above)
 - $2d+1 \rightarrow$ can correct up to d errors (e.g., 2 errors above)

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Error Bounds – Detection

Q: Why can a code with distance $d+1$ **detect** up to d errors?

- Errors are detected by receiving an invalid codeword, e.g. 00001 11111.
- If there are more than d errors, then the received codeword may become another valid codeword.
- Can receiver detect errors in 11100 00011?
The receiver cannot detect all 5-bit errors.

Error Bounds – Correction

Q: Why can a code with distance $2d+1$ **correct** up to d errors?

- Errors are corrected by **mapping** a received invalid codeword **to the nearest valid codeword** i.e., the one that can be reached with the fewest bit flips
- If there are more than d bit flips, then the received codeword may be closer to another valid codeword than the codeword that was sent

Example: Sending 0000000000 with 2 flips might give 1100000000 which is closest to 0000000000, correcting the error.

But with 3 flips 1110000000 might be received, which is closest to 1111100000, which is still an error