

Assignment Project Exam Help

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CS:3620 Operating Systems  
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Locks

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## Locks: Basic idea

- Consider update of shared variable

```
balance = balance + 1;
```

- We can use a special lock variable to protect it

```
1 lock_t mutex; // some globally allocated lock 'mutex'
2 ...
3 lock(&mutex);
4 balance = balance + 1;
5 unlock(&mutex);
```

- All threads accessing a critical section share a lock
- One thread succeeds in locking – owner of lock
- Other threads that try to lock cannot proceed further until lock is released by the owner
- Pthreads library in Linux provides such locks

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## Building a lock

- Goals of a lock implementation
  - Mutual exclusion (obviously!)
  - Fairness: all threads should eventually get the lock, and no thread should starve
  - Low overhead: acquiring, releasing, and waiting for lock should not consume too many resources
- Implementation of locks are needed for both userspace programs (e.g., pthreads library) and kernel code
- Implementing locks needs support from hardware and OS

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# Is disabling interrupts enough?

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```
1 void lock() {  
2     DisableInterrupts();  
3 }  
4 void unlock() {  
5     EnableInterrupts();  
6 }
```

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- Is this enough?
- No, not always!
- Many issues here:
  - Disabling interrupts is a privileged instruction and user program can misuse it (e.g., run forever)
  - Will not work on multiprocessor systems, since another thread on another core can enter critical section
- This technique is used to implement locks on single processor systems inside the OS
  - Need better solution for other situations

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# A failed lock implementation (1)

- Lock: spin on a flag variable until it is unset, then set it to acquire lock
- Unlock: unset flag variable

```
1  typedef struct __lock_t { int flag; } lock_t;
2
3  void init(lock_t *mutex) {
4      // 0 -> lock is available, 1 -> held
5      mutex->flag = 0;
6  }
7
8  void lock(lock_t *mutex) {
9      while (mutex->flag == 1) // TEST the flag
10         ; // spin-wait (do nothing)
11     mutex->flag = 1; // now SET it!
12 }
13
14 void unlock(lock_t *mutex) {
15     mutex->flag = 0;
16 }
```

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## A failed lock implementation (2)

- Thread 1 spins, lock is released, ends spin
- Thread 1 interrupted just before setting flag
- Race condition has moved to the lock acquisition code!

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```
1 typedef struct __lock_t { int flag; } lock_t;
2
3 void init(lock_t *mutex) {
4     // 0 -> lock is available, 1 -> held
5     mutex->flag = 0;
6 }
7
8 void lock(lock_t *mutex) {
9     while (mutex->flag == 1) // TEST the flag
10         ; // spin-wait (do nothing)
11     mutex->flag = 1; // now SET it!
12 }
13
14 void unlock(lock_t *mutex) {
15     mutex->flag = 0;
16 }
```

**Thread 1**

call lock()  
while (flag == 1)  
**interrupt: switch to Thread 2**

flag = 1; // set flag to 1 (too!)

**Thread 2**

call lock()  
while (flag == 1)  
flag = 1;  
**interrupt: switch to Thread 1**

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# Solution: Hardware atomic instructions

- Very hard to ensure atomicity only in software
- Modern architectures provide hardware atomic instructions
- Example of an atomic instruction: test-and-set
  - Update a variable and return old value, all in one hardware instruction

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```
1  int TestAndSet(int *old_ptr, int new) {  
2      int old = *old_ptr; // fetch old value at old_ptr  
3      *old_ptr = new;      // store 'new' into old_ptr  
4      return old;          // return the old value  
5  }
```

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## Simple lock using test-and-set

```
1 int TestAndSet(int *old_ptr, int new) {
2     int old = *old_ptr; // fetch old value at old_ptr
3     *old_ptr = new;     // store 'new' into old_ptr
4     return old;         // return the old value
5 }
```

- If *TestAndSet(flag,1)* returns 1, it means the lock is held by someone else, so wait busily
- This lock is called a spinlock – spins until lock is acquired

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```
1 typedef struct __lock_t { int flag; } lock_t;
2
3 void init(lock_t *mutex) {
4     // 0 -> lock is available, 1 -> held
5     mutex->flag = 0;
6 }
7
8 void lock(lock_t *mutex) {
9     while (mutex->flag == 1) // TEST the flag
10         ; // spin-wait (do nothing)
11     mutex->flag = 1;         // now SET it!
12 }
13
14 void unlock(lock_t *mutex) {
15     mutex->flag = 0;
16 }
```

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```
1 typedef struct __lock_t {
2     int flag;
3 } lock_t;
4
5 void init(lock_t *lock) {
6     // 0: lock is available, 1: lock is held
7     lock->flag = 0;
8 }
9
10 void lock(lock_t *lock) {
11     while (TestAndSet(&lock->flag, 1) == 1)
12         ; // spin-wait (do nothing)
13 }
14
15 void unlock(lock_t *lock) {
16     lock->flag = 0;
17 }
```



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# Spinlock using compare-and-swap

- Another atomic instruction: compare-and-swap

```
1  int CompareAndSwap(int *ptr, int expected, int new) {  
2      int original = *ptr;  
3      if (original == expected)  
4          *ptr = new;  
5      return original;  
6  }
```

- Spinlock using compare-and-swap

```
1  void lock(lock_t *lock) {  
2      while (CompareAndSwap(&lock->flag, 0, 1) == 1)  
3          ; // spin  
4  }
```

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# Alternative to spinning

- Alternative to spinlock: a (sleeping) mutex
- Instead of spinning for a lock, a contending thread could simply give up the CPU and check back later
  - *yield()* moves thread from running to ready state

```
1  void init() {  
2      flag = 0;  
3  }  
4  
5  void lock() {  
6      while (TestAndSet(&flag, 1) == 1)  
7          yield(); // give up the CPU  
8  }  
9  
10 void unlock() {  
11     flag = 0;  
12 }
```

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# Spinlock vs. sleeping mutex

- Most userspace lock implementations are of the sleeping mutex kind
  - CPU wasted by spinning contending threads
  - More so if a thread holds spinlock and blocks for long
- Locks inside the OS are always spinlocks
  - Why? Who will the OS yield to?
- When OS acquires a spinlock:
  - It must disable interrupts (on that processor core) while the lock is held. Why? An interrupt handler could request the same lock, and spin for it forever.
  - It must not perform any blocking operation – never go to sleep with a locked spinlock!
- In general, use spinlocks with care, and release as soon as possible

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# How should locks be used?

- A lock should be acquired before accessing any variable or data structure that is shared between multiple threads of a process
  - “Thread-safe” data structures
- All shared kernel data structures must also be accessed only after locking
- Coarse-grained vs. fine-grained locking: one big lock for all shared data vs. separate locks
  - Fine-grained allows more parallelism
  - Multiple fine-grained locks may be harder to manage
- OS only provides locks, correct locking discipline is left to the user

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## Disclaimer

- *These lecture slides are based on a slide set by Youjip Won (Hanyang University) and Mythili Vutukuru (IIT Bombay)*

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