

Announcements

Reminder: self-grading forms for ps1 and ps2 due 10/5 at midnight (Boston)

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- ps3 out on Thursday, due 10/8 (1 week)
<https://powcoder.com>
- LAB this week: go over solutions for the first two homeworks **Add WeChat powcoder**

Agglomerative Clustering Example

(bottom-up clustering)

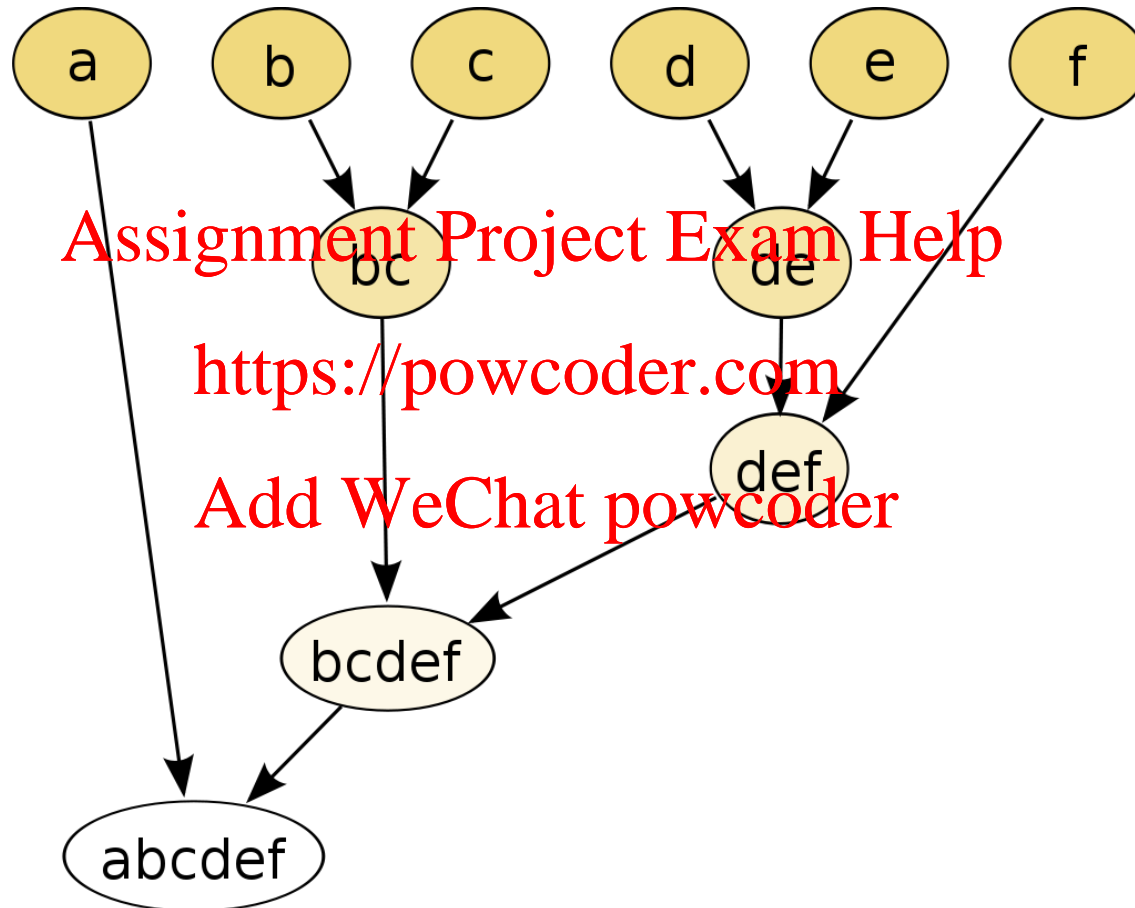


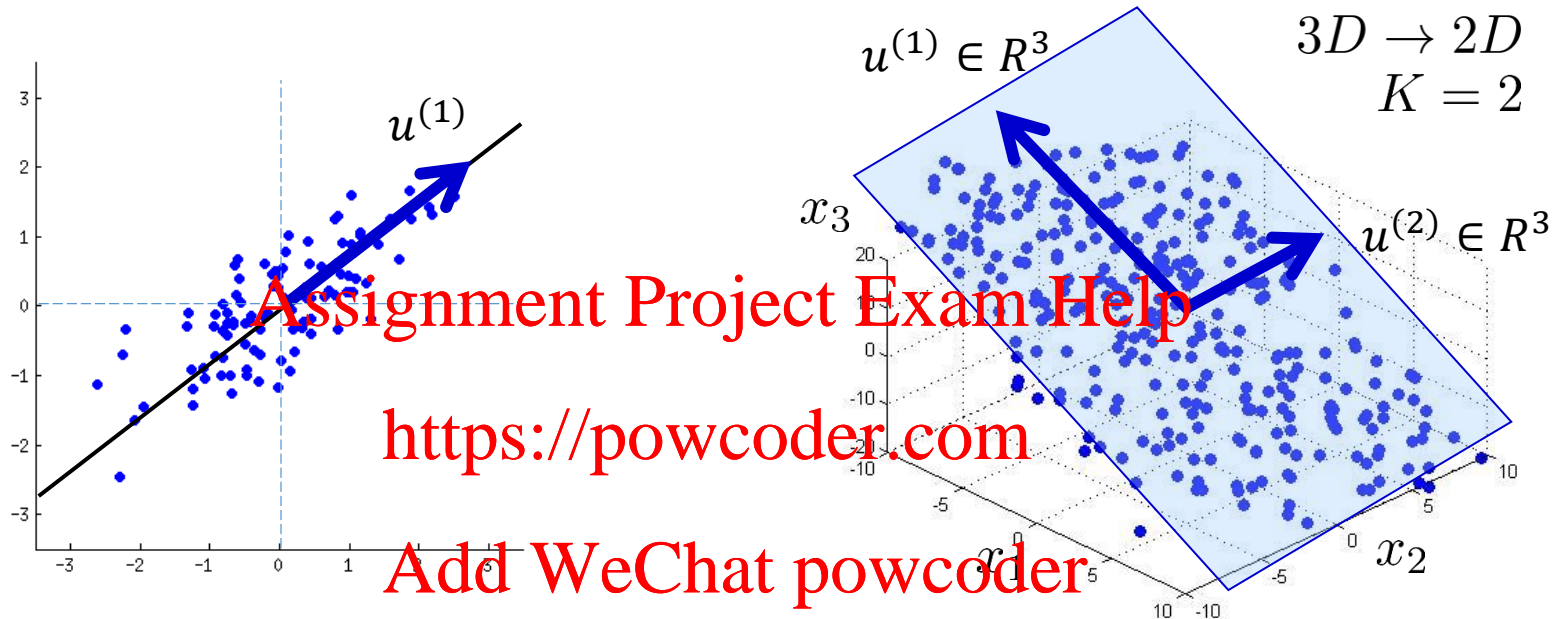
Image source: https://en.wikipedia.org/wiki/Hierarchical_clustering

K-Means for Image Compression



Figure 9.3 Two examples of the application of the K -means clustering algorithm to image segmentation showing the initial images together with their K -means segmentations obtained using various values of K . This also illustrates the use of vector quantization for data compression, in which smaller values of K give higher compression at the expense of poorer image quality.

Choose subspace with minimal “information loss”



Reduce from 2-dimension to 1-dimension: Find a direction (a vector $u^{(1)}$) onto which to project the data, so as to minimize the projection error.

Reduce from n-dimension to K-dimension: Find K vectors $u^{(1)}, u^{(2)}, \dots, u^{(K)}$ onto which to project the data so as to minimize the projection error.

PCA Solution

- The solution turns out to be the first K eigenvectors of the data covariance matrix (see Bishop 12.1 for details)

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- Closed-form, use Singular Value Decomposition (SVD) on covariance matrix

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What features to use?



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Edges?

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Today: Outline

- **Neural networks:** artificial neuron, MLP, sigmoid units; neuroscience inspiration; output vs hidden layers; linear vs nonlinear networks;

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- **Feed-forward networks**



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Intro to Neural Networks

Motivation

Recall: Logistic Regression

$$0 \leq h_{\theta}(x) \leq 1$$

$$h_{\theta}(x) = g(\theta^T x) = \frac{1}{1 + e^{-\theta^T x}}$$

$$g(z) = \frac{1}{1 + e^{-z}}$$

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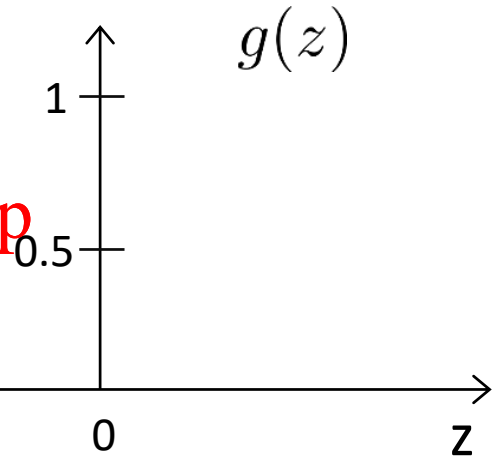
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Output is probability of label 1 given input

$$p(y = 1|x) = \frac{1}{1 + e^{-\theta^T x}}$$

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sigmoid/logistic function



predict “ $y = 1$ ” if $h_{\theta}(x) \geq 0.5$

predict “ $y = 0$ ” if $h_{\theta}(x) < 0.5$

Recall: Logistic Regression Cost

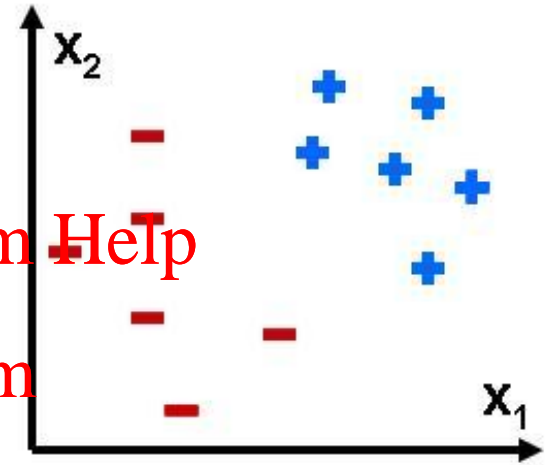
Logistic Regression Hypothesis:

$$h_{\theta}(x) = g(\theta^T x) = \frac{1}{1 + e^{-\theta^T x}}$$

θ : parameters

$D = \{x^i, y^i\}$: data

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Logistic Regression Cost Function:

$$\begin{aligned} J(\theta) &= \frac{1}{m} \sum_{i=1}^m \text{Cost}(h_{\theta}(x^{(i)}), y^{(i)}) \\ &= -\frac{1}{m} \left[\sum_{i=1}^m y^{(i)} \log h_{\theta}(x^{(i)}) + (1 - y^{(i)}) \log (1 - h_{\theta}(x^{(i)})) \right] \end{aligned}$$

Goal: minimize cost $\min_{\theta} J(\theta)$

Cost: Intuition

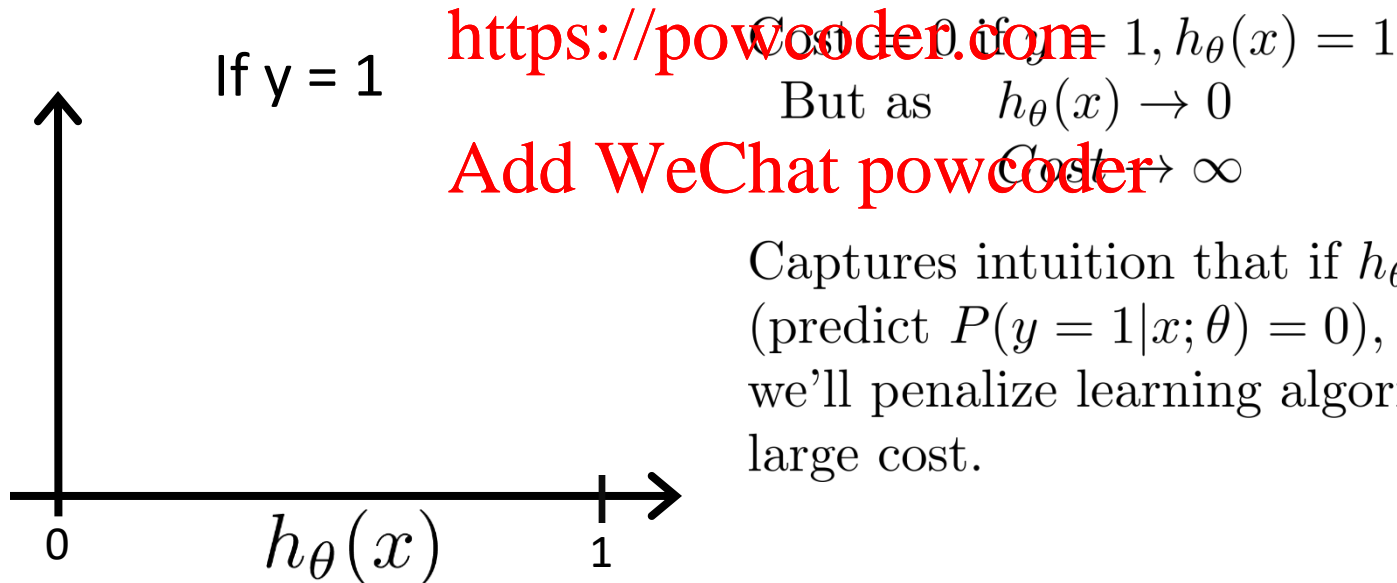
Logistic regression cost function

$$\text{Cost}(h_{\theta}(x), y) = \begin{cases} -\log(h_{\theta}(x)) & \text{if } y = 1 \\ -\log(1 - h_{\theta}(x)) & \text{if } y = 0 \end{cases}$$

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Captures intuition that if $h_{\theta}(x) = 0$, (predict $P(y = 1|x; \theta) = 0$), but $y = 1$, we'll penalize learning algorithm by a very large cost.

Cost: Intuition

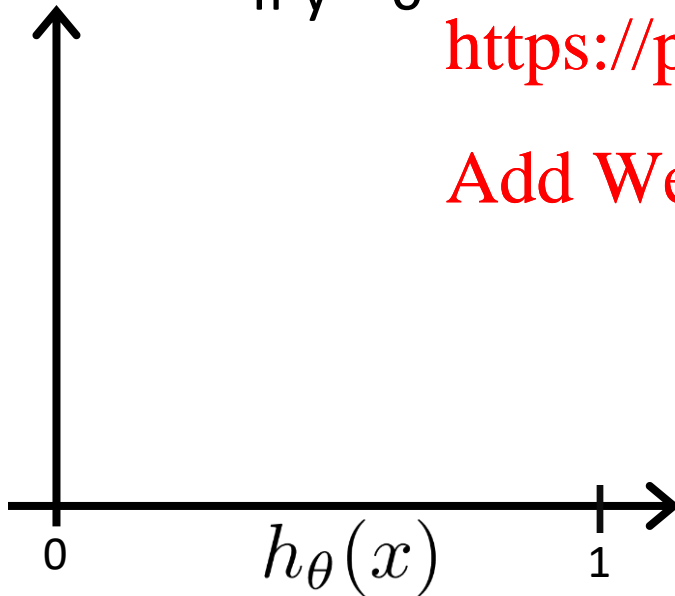
Logistic regression cost function

$$\text{Cost}(h_{\theta}(x), y) = \begin{cases} -\log(h_{\theta}(x)) & \text{if } y = 1 \\ -\log(1 - h_{\theta}(x)) & \text{if } y = 0 \end{cases}$$

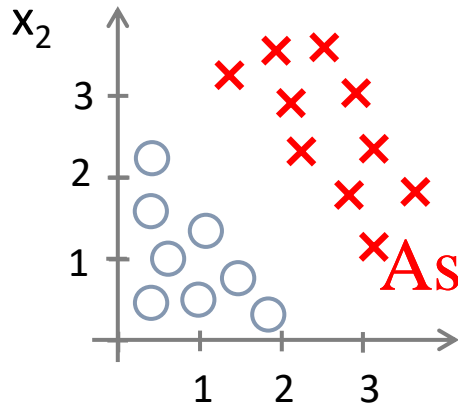
If $y = 0$

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Decision boundary



$$h_{\theta}(x) = g(\theta_0 + \theta_1 x_1 + \theta_2 x_2)$$

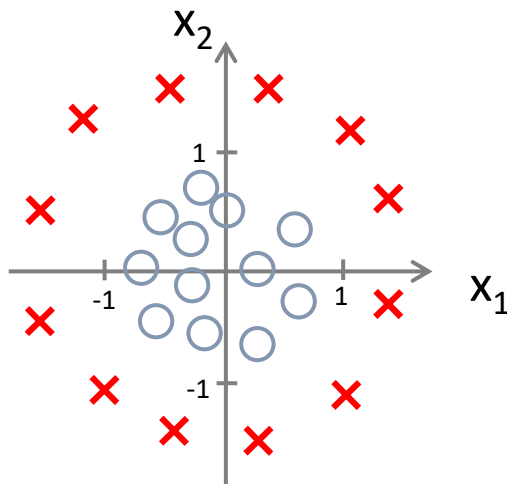
Predict “ $y = 1$ ” if $-3 + x_1 + x_2 \geq 0$

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Non-linear decision boundaries

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Replace features with non-linear functions
e.g. log, cosine, or polynomial

$$h_{\theta}(x) = g(\theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_1^2 + \theta_4 x_2^2)$$

Predict “ $y = 1$ ” if $-1 + x_1^2 + x_2^2 \geq 0$

Limitations of linear models

- Logistic regression and other linear models cannot handle nonlinear decision boundaries

- Must use non-linear feature transformations

- Up to designer to specify which one

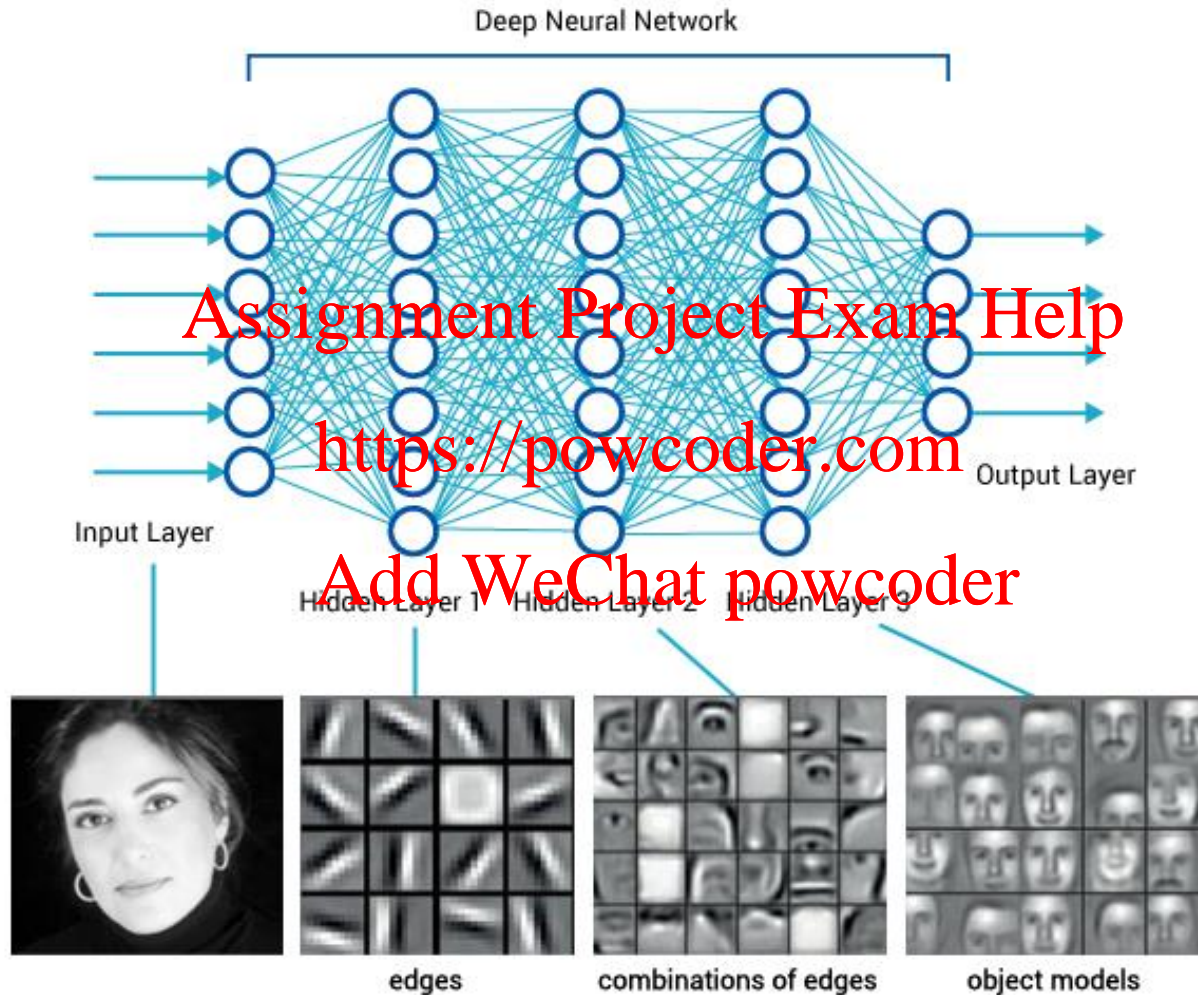
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- Can we instead learn the transformation?

- Yes, this is what neural networks do!

- A **Neural network** chains together many layers of “neurons” such as logistic units (logistic regression functions)

Neural Networks learn features



Neurons in the Brain

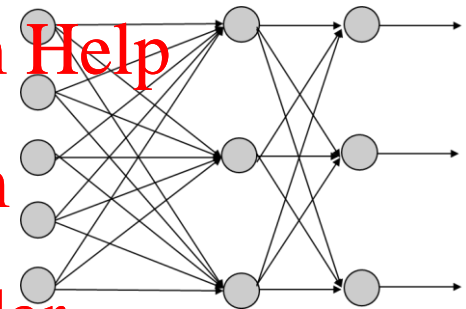


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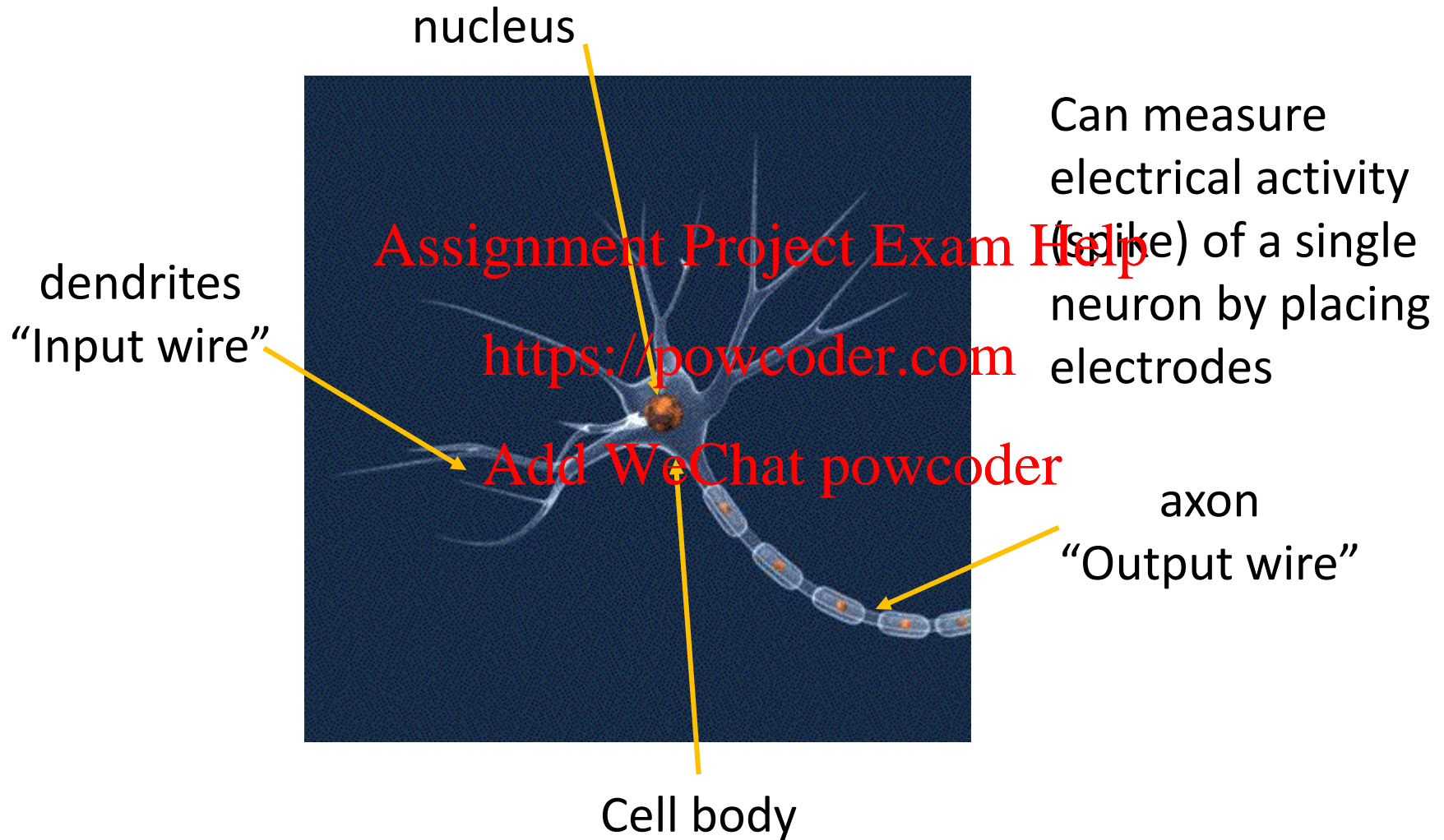
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Inspired “Artificial Neural Networks”



Neurons are cells that process chemical and electrical signals and transmit these signals to neurons and other types of cells

Neuron in the brain



Neural network in the brain



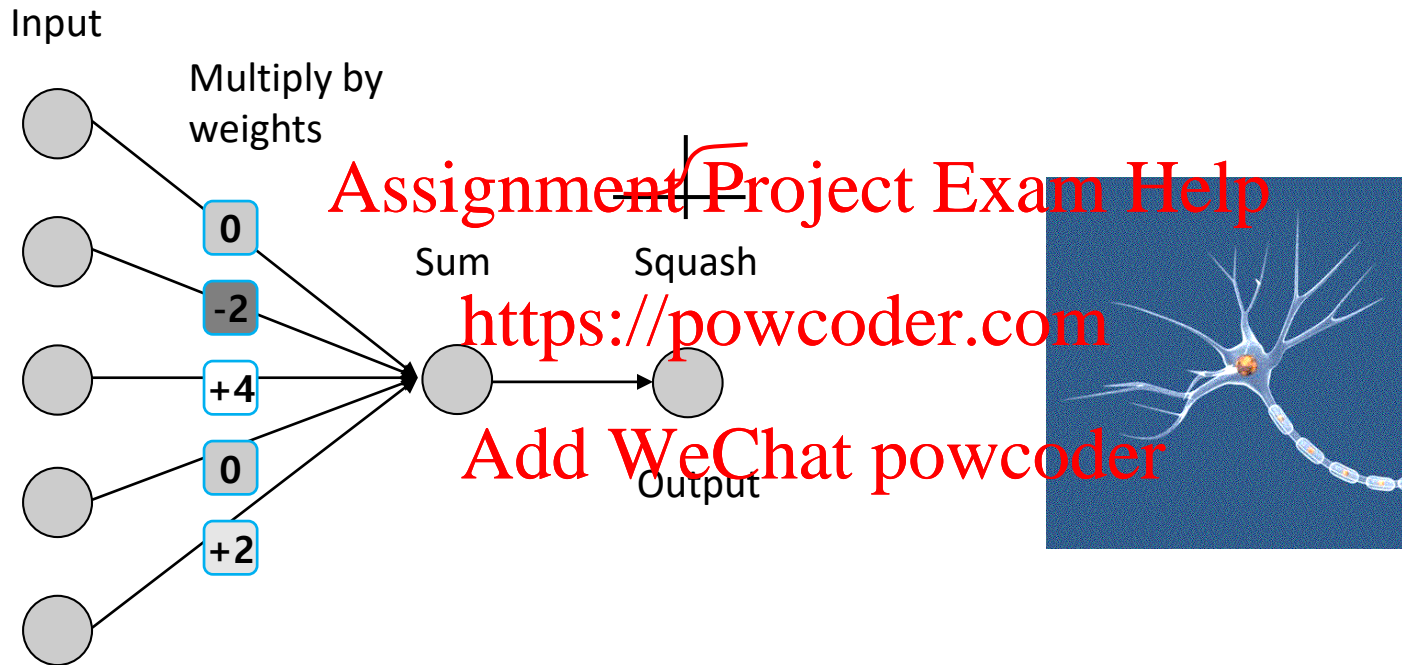
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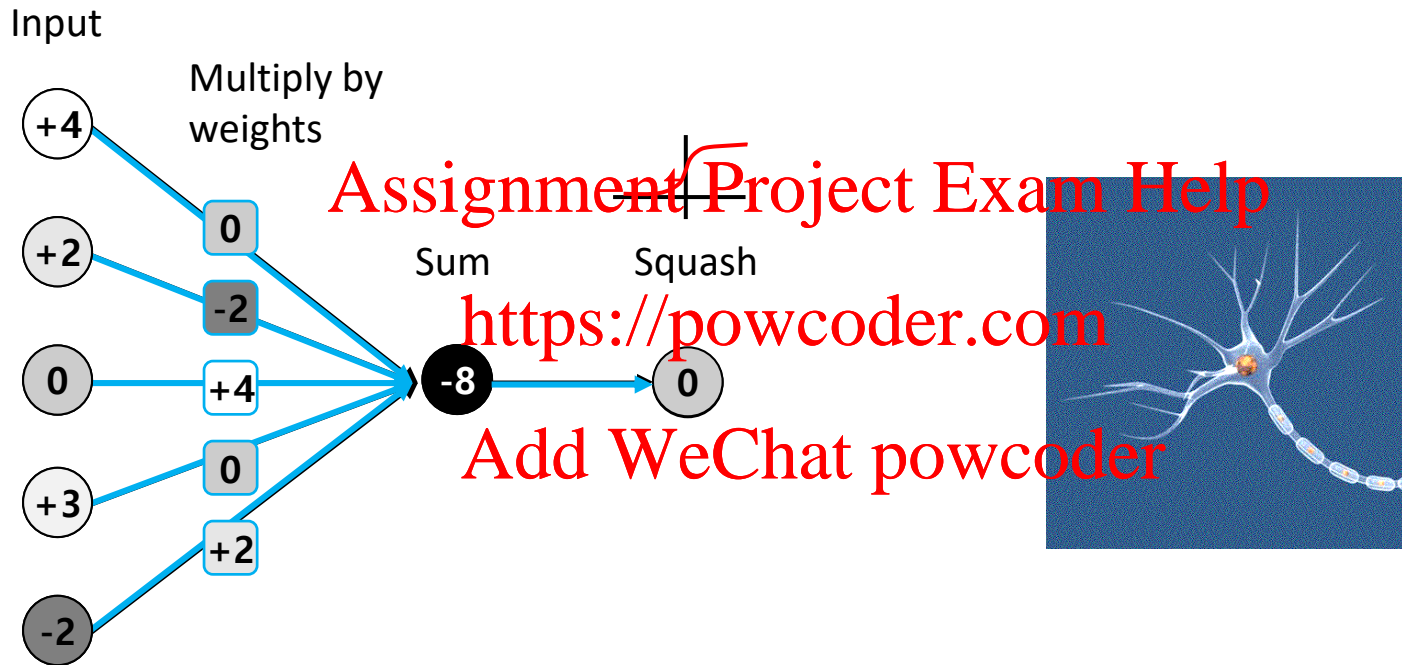
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- **Micro networks:** several connected neurons perform sophisticated tasks: mediate reflexes, process sensory information, generate locomotion and mediate learning and memory.
- **Macro networks:** perform higher brain functions such as object recognition and cognition.

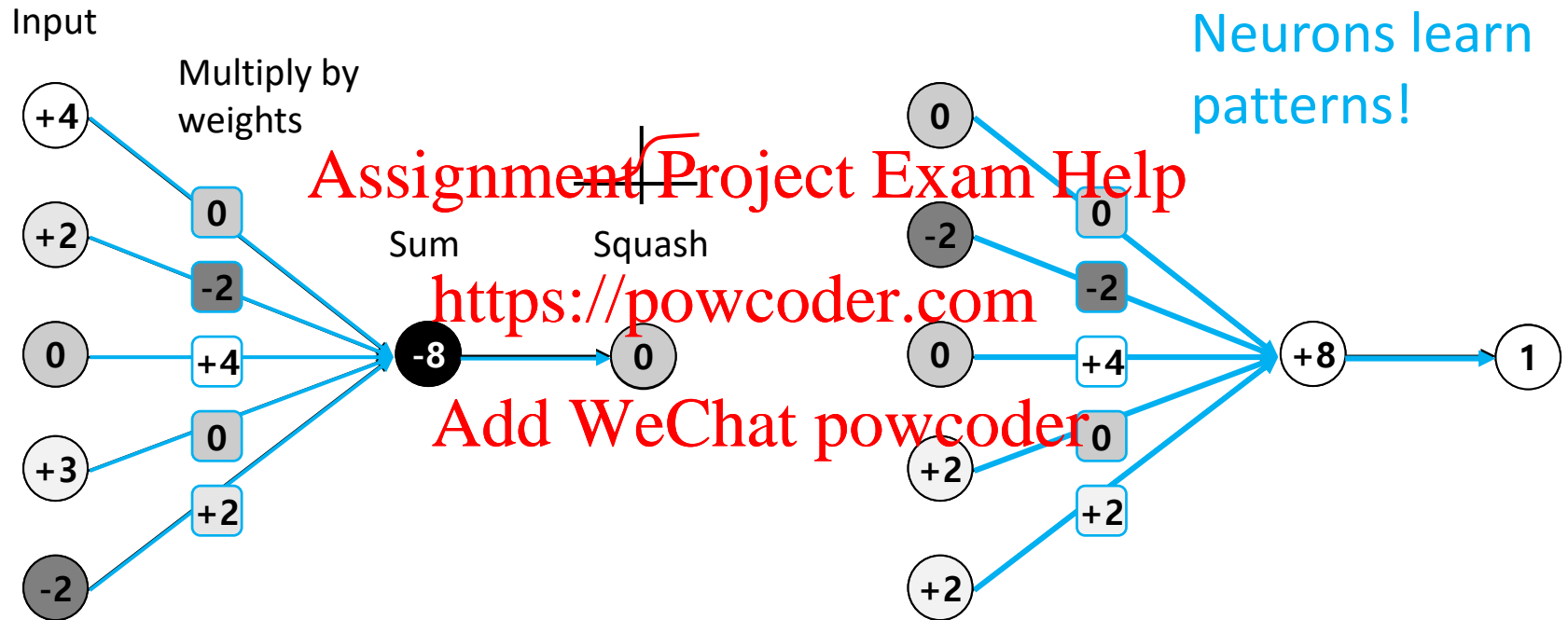
Logistic Unit as Artificial Neuron



Logistic Unit as Artificial Neuron

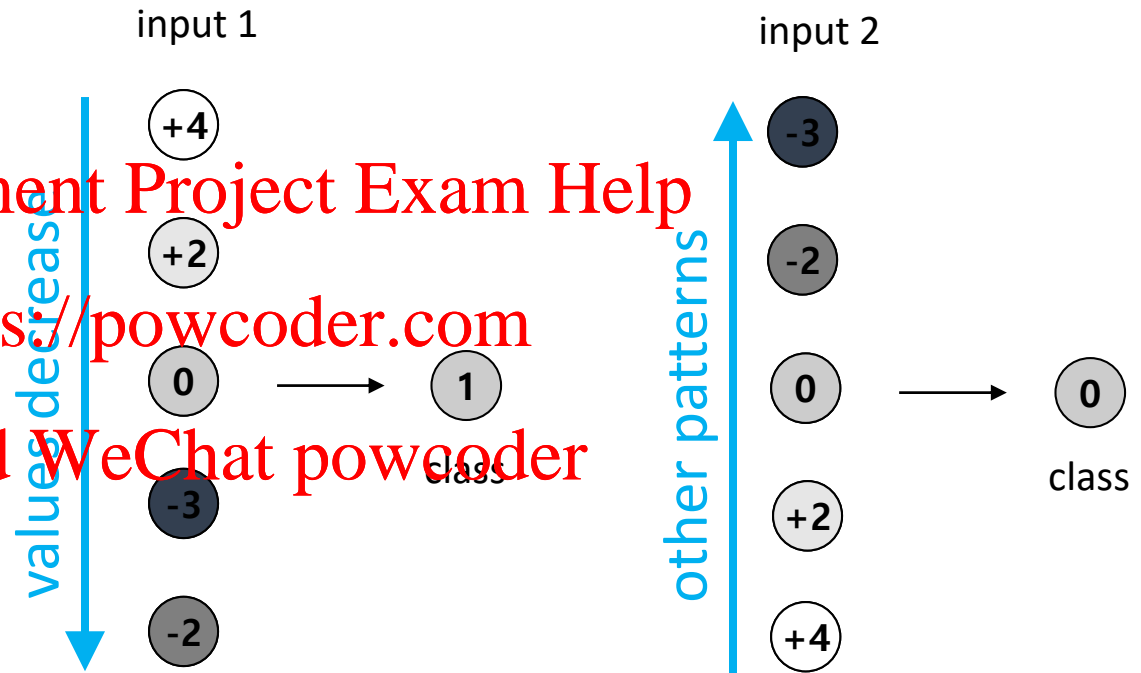


Logistic Unit as Artificial Neuron



Artificial Neuron Learns Patterns

- Classify input into class 0 or 1
- Teach neuron to predict correct class label
- Detect presence of a simple “feature”



Example



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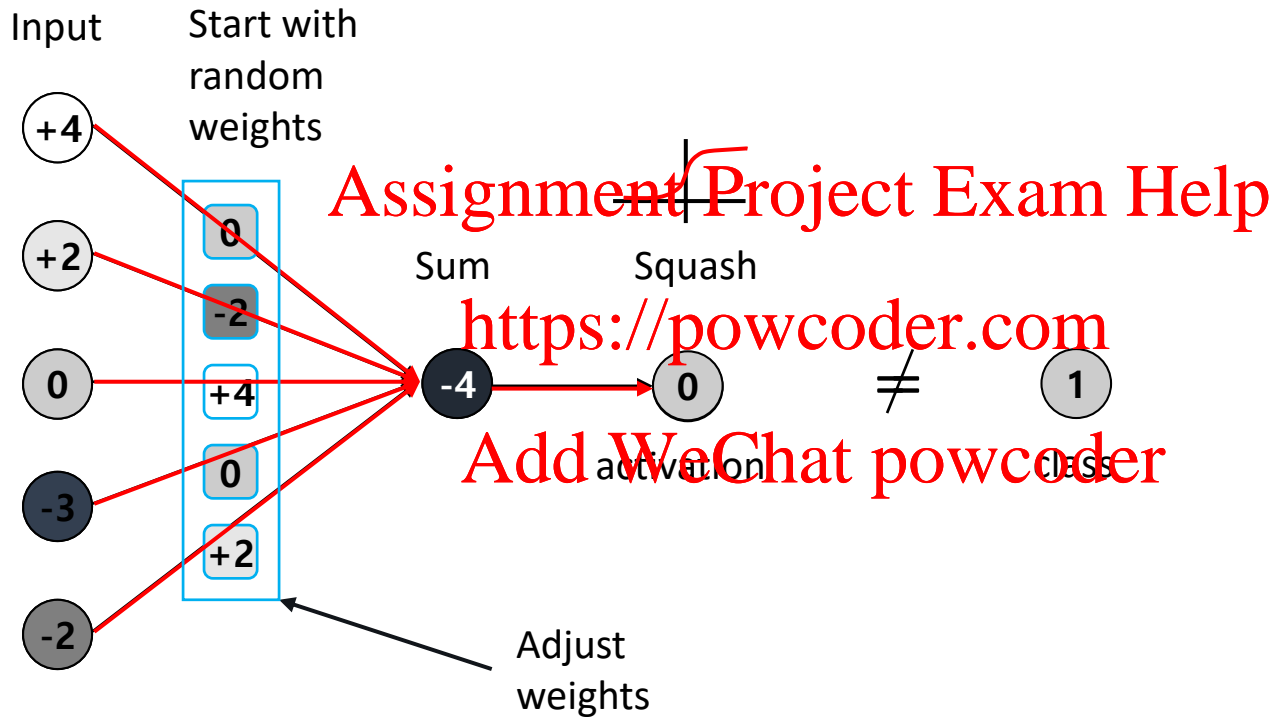
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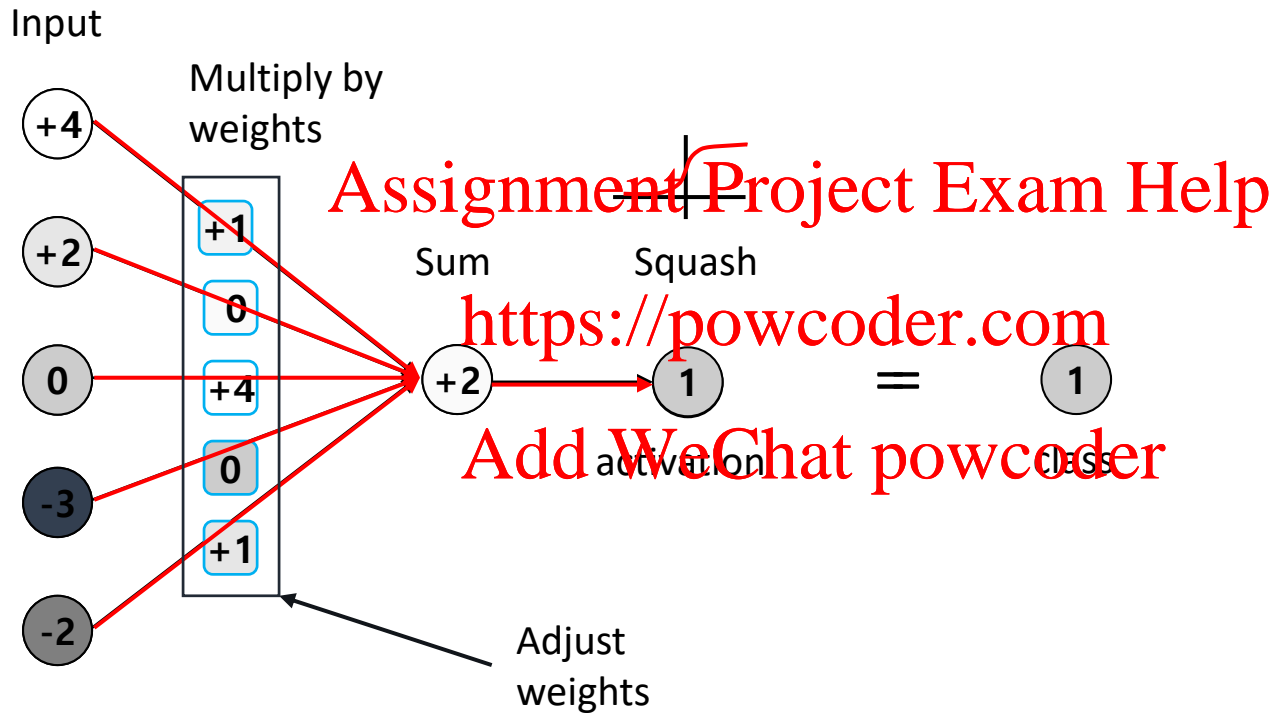
Neural Networks: Learning

Intuition

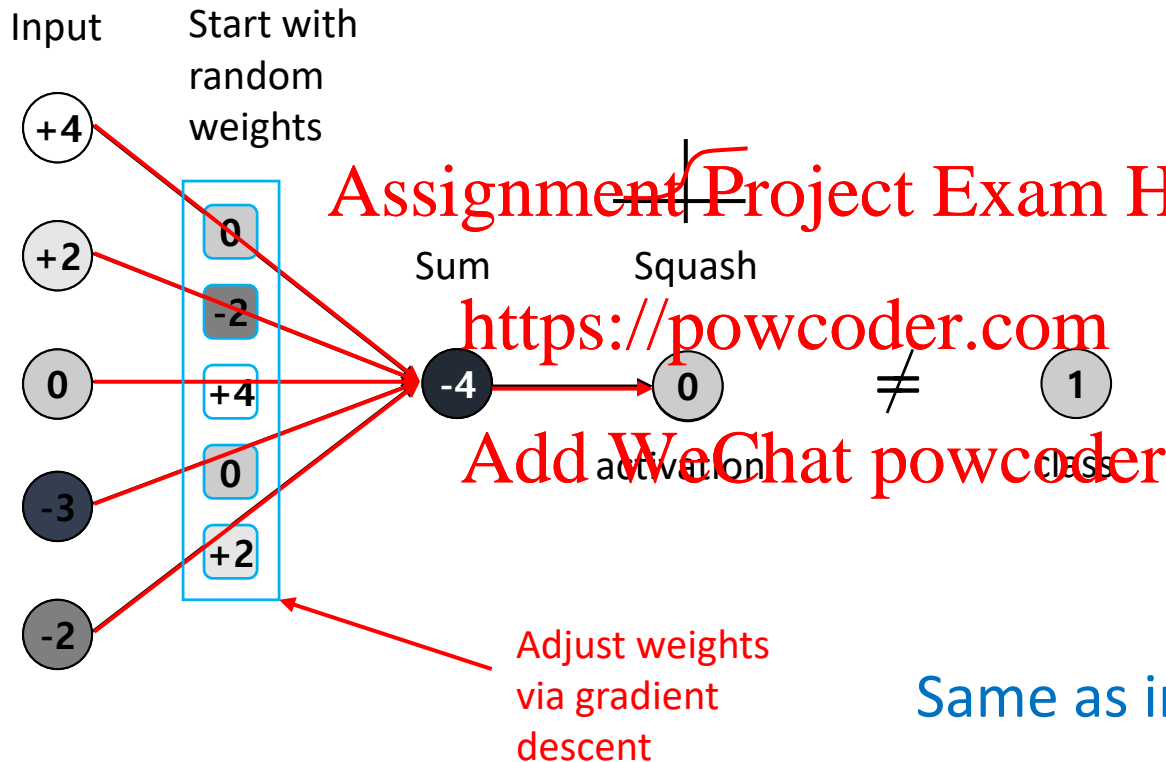
Artificial Neuron: Learning



Artificial Neuron: Learning



Artificial Neuron: Learning



Same as in logistic regression



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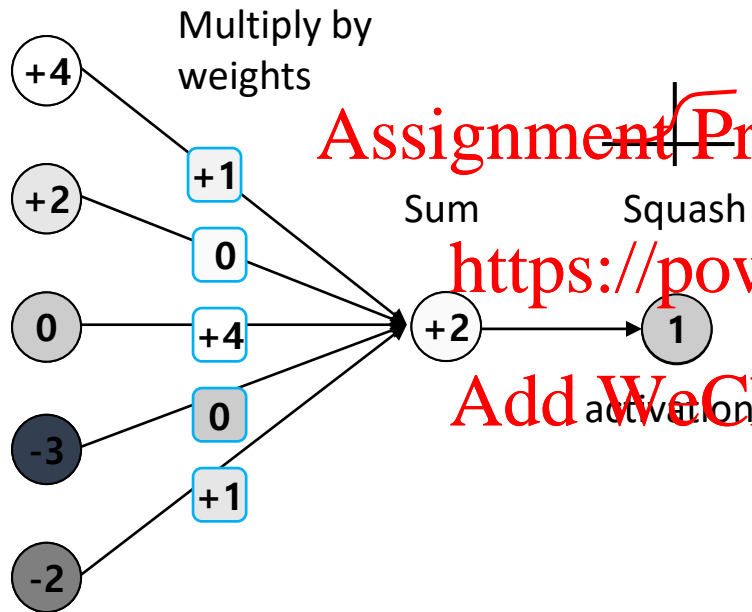
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Neural Networks: Learning

Multi-layer network

Artificial Neuron: simplify

Input



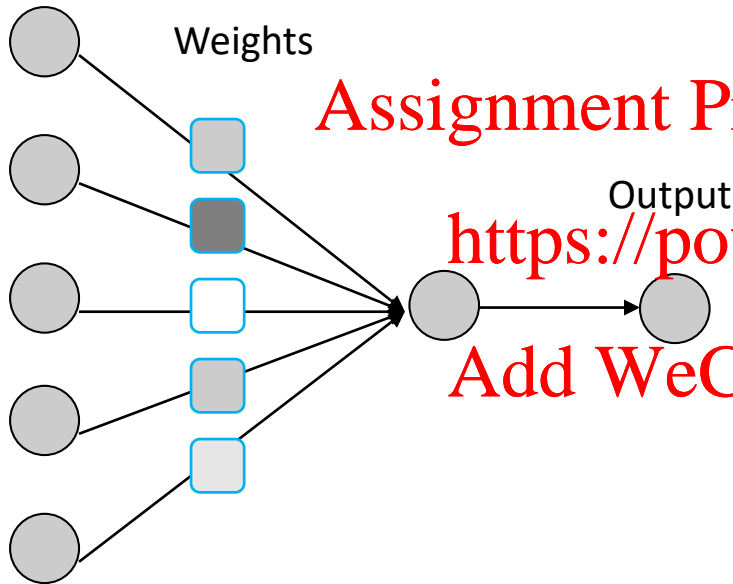
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Artificial Neuron: simplify

Input

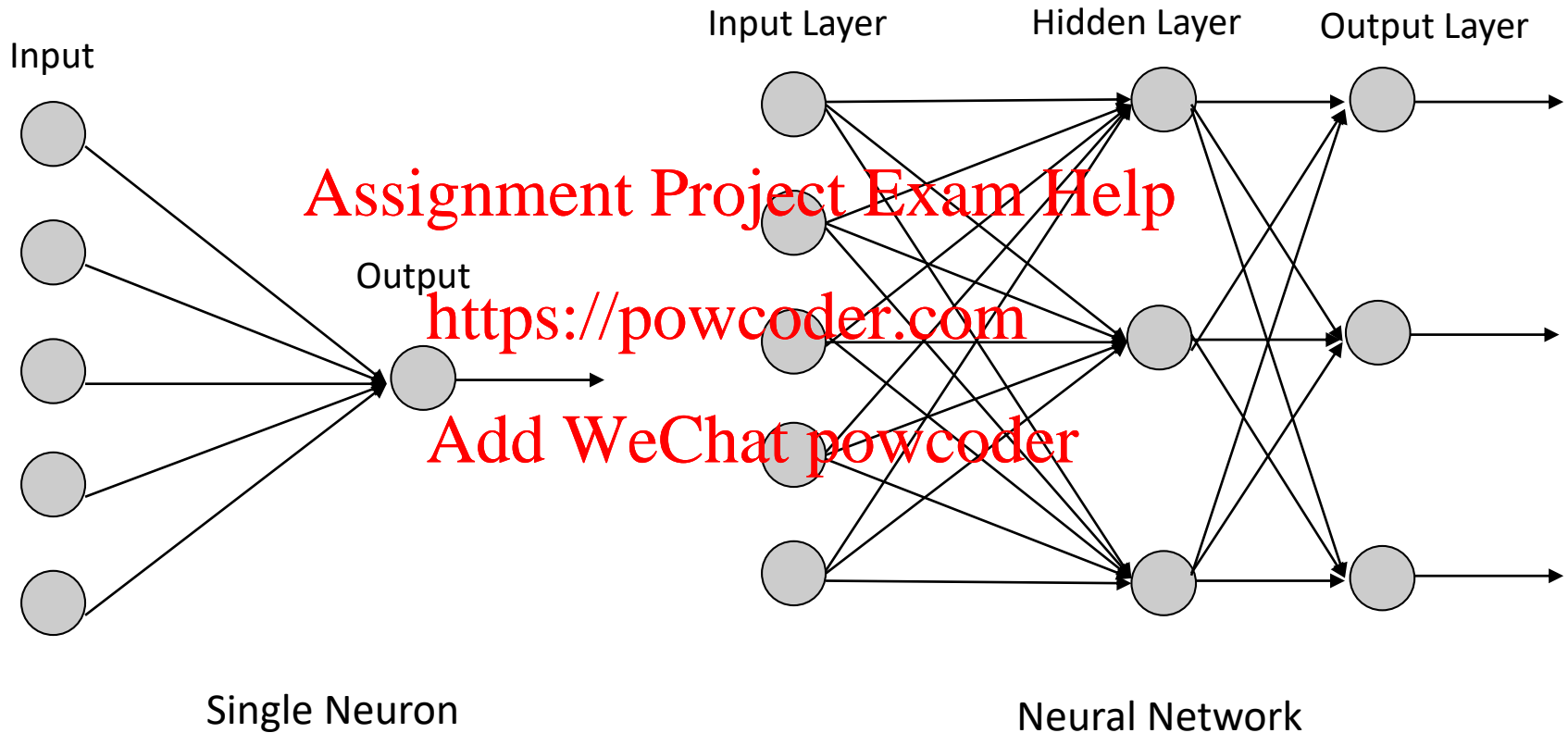


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Artificial Neural Network



Deep Network: many hidden layers

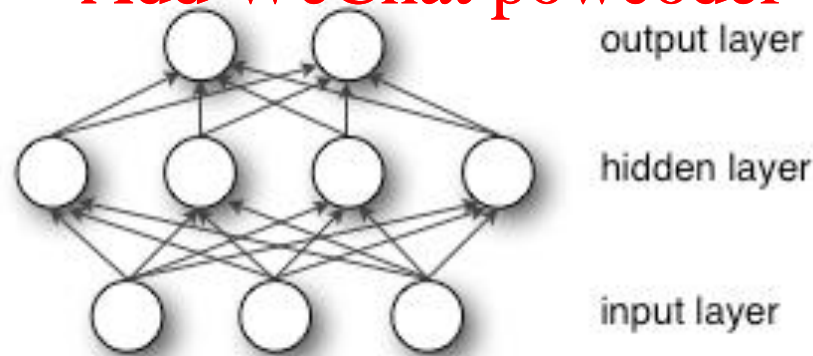
Multi-layer perceptron (MLP)

- Just another name for a feed-forward neural network
- Logistic regression is a special case of the MLP with no hidden layer and sigmoid output

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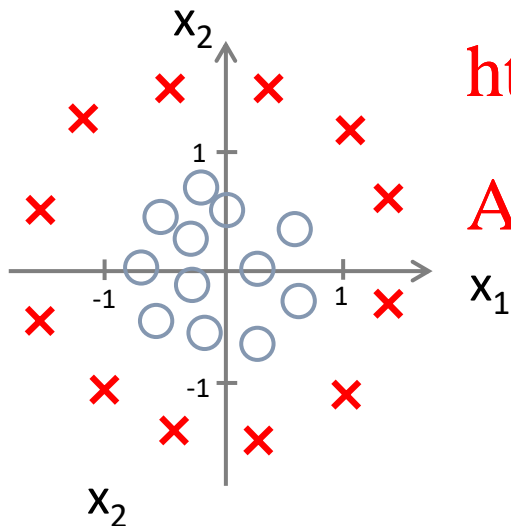
Neural Networks Learn Features

logistic regression unit == artificial neuron

chain several units together == neural network

“earlier” units learn non-linear feature transformation

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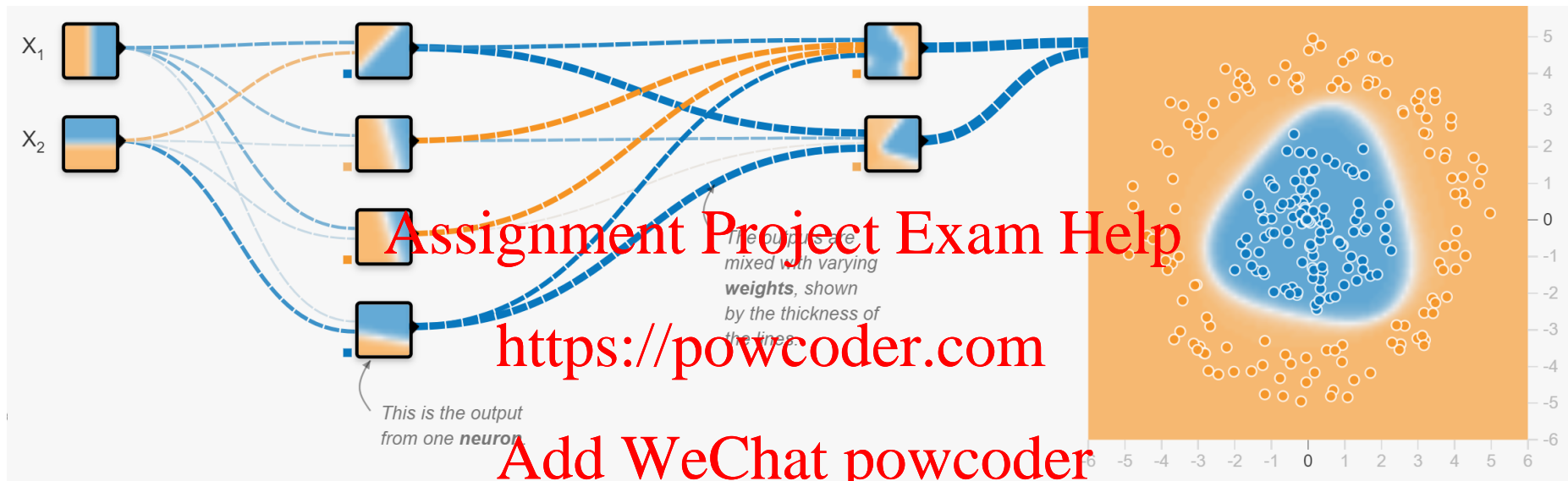
$$h_{\theta}(x) = g(\theta_0 + \theta_1 x_1 + \theta_2 x_2)$$

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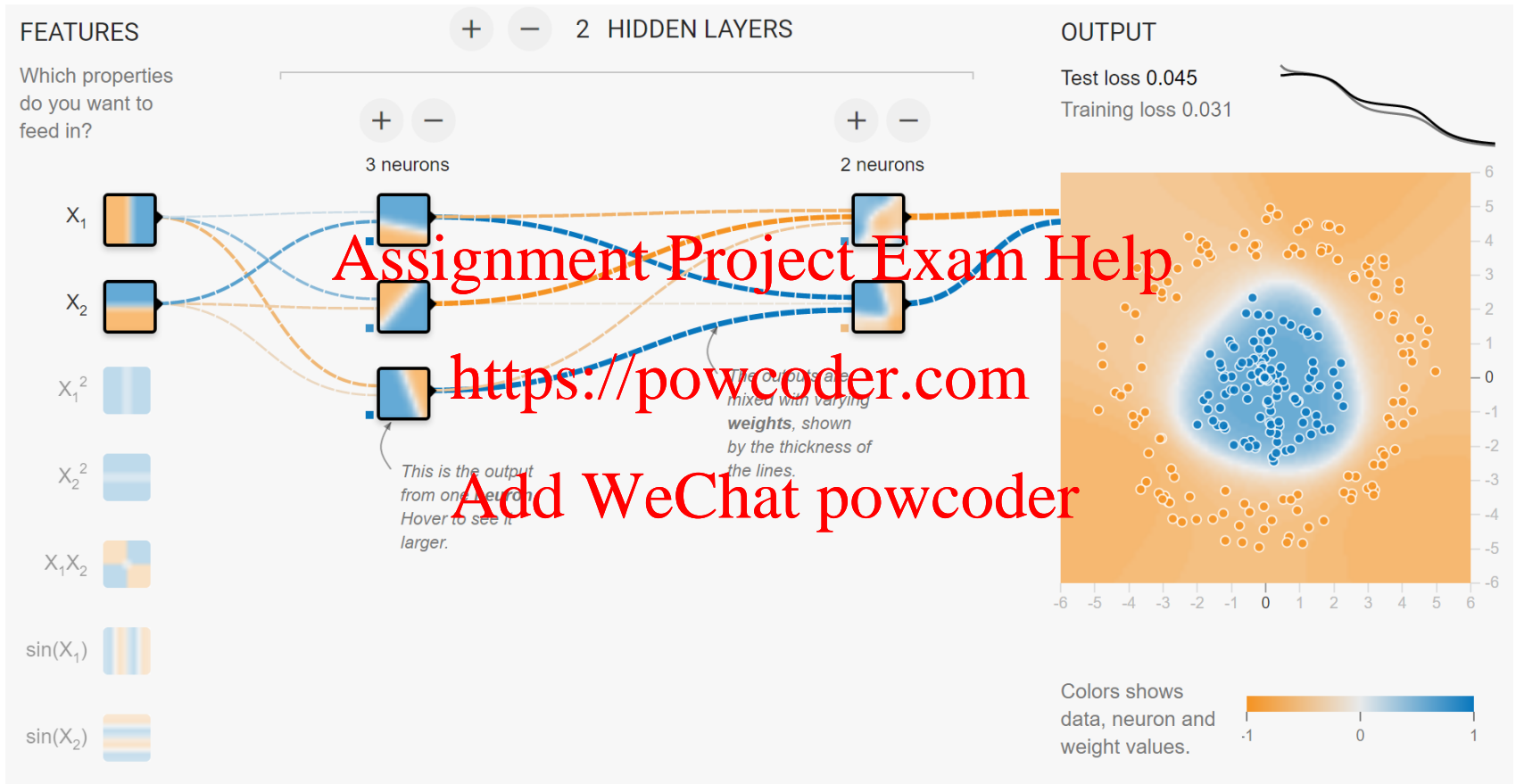
simple neural network

$$h(x) = g(\theta + \theta_1 h^{(1)}(x) + \theta_2 h^{(2)}(x) + \theta_3 h^{(3)}(x))$$

Example



Training a neural net: Demo



Tensorflow playground

Artificial Neural Network:

general notation

input

$$x = \begin{bmatrix} x_1 \\ \dots \\ x_5 \end{bmatrix}$$

hidden layer activations

$$h^i = g(\Theta^{(i)}x)$$

$$g(z) = \frac{1}{1 + \exp(-z)}$$

output

$$h_{\Theta}(x) = g(\Theta^{(2)}a)$$

weights

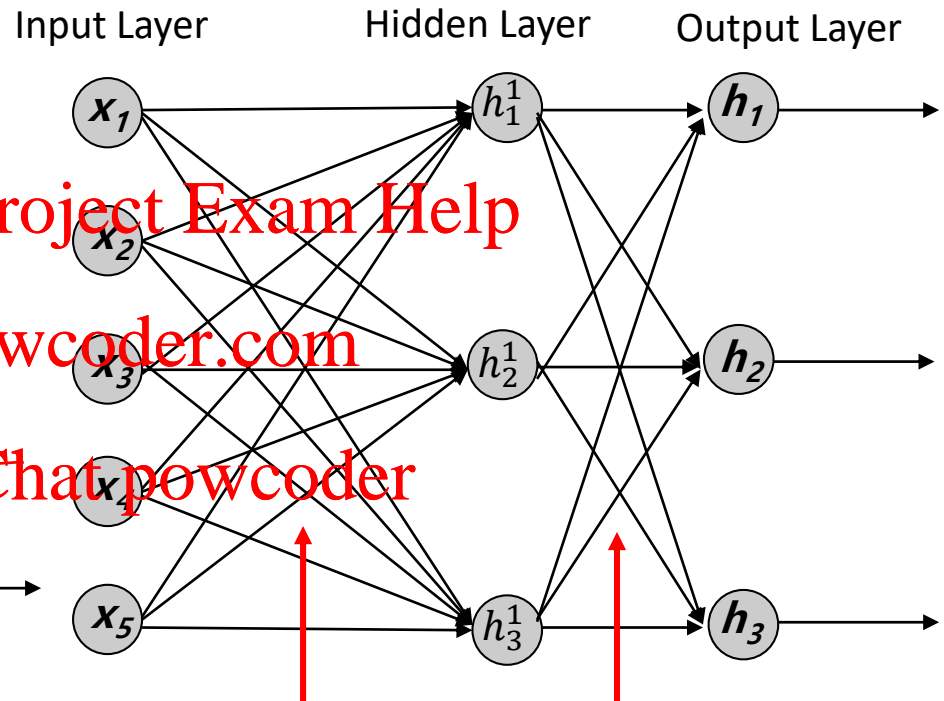
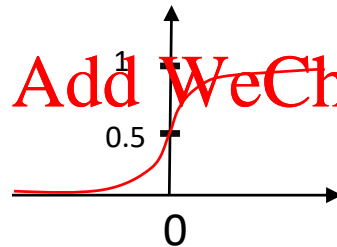
$$\Theta^{(1)} = \begin{pmatrix} \theta_{11} & \dots & \theta_{15} \\ \vdots & \ddots & \vdots \\ \theta_{31} & \dots & \theta_{35} \end{pmatrix}$$

$$\Theta^{(2)} = \begin{pmatrix} \theta_{11} & \dots & \theta_{13} \\ \vdots & \ddots & \vdots \\ \theta_{31} & \dots & \theta_{33} \end{pmatrix}$$

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Cost function

Neural network: $h_{\Theta}(x) \in \mathbb{R}^K$ $(h_{\Theta}(x))_i = i^{th}$ output

Assignment Project Exam Help training error

$$J(\Theta) = -\frac{1}{m} \left[\sum_{i=1}^m \sum_{k=1}^K y_k^{(i)} \log(h_{\Theta}(x^{(i)}))_k + (1 - y_k^{(i)}) \log(1 - (h_{\Theta}(x^{(i)}))_k) \right]$$

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$$+ \frac{\lambda}{2m} \sum_{l=1}^{L-1} \sum_{i=1}^{s_l} \sum_{j=1}^{s_{l+1}} (\Theta_{ji}^{(l)})^2$$

regularization

Gradient computation

$$J(\Theta) = -\frac{1}{m} \left[\sum_{i=1}^m \sum_{k=1}^K y_k^{(i)} \log h_{\theta}(x^{(i)})_k + (1 - y_k^{(i)}) \log(1 - h_{\theta}(x^{(i)})_k) \right] + \frac{\lambda}{2m} \sum_{l=1}^{L-1} \sum_{i=1}^{s_l} \sum_{j=1}^{s_{l+1}} (\Theta_j^{(l)})^2$$

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Cover next time!

$$\min_{\Theta} J(\Theta)$$

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Use “Backpropagation algorithm”

Need code to compute:

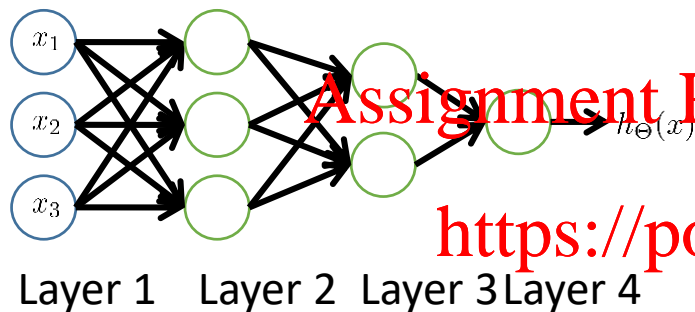
- $J(\Theta)$
- $\frac{\partial}{\partial \Theta_{ij}^{(l)}} J(\Theta)$

- Efficient way to compute $\frac{\partial}{\partial \Theta_{ij}^{(l)}} J(\Theta)$
- Computes gradient incrementally by “propagating” backwards through the network

Network architectures

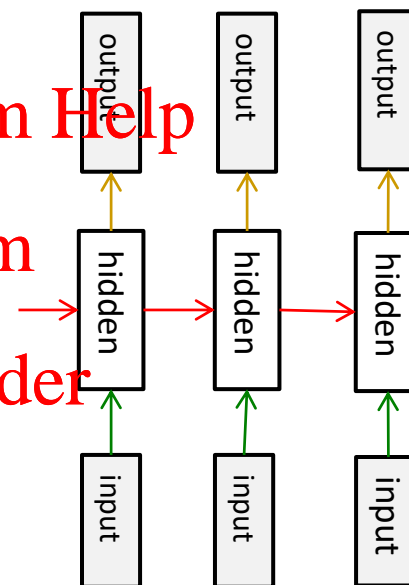
Feed-forward

Fully connected

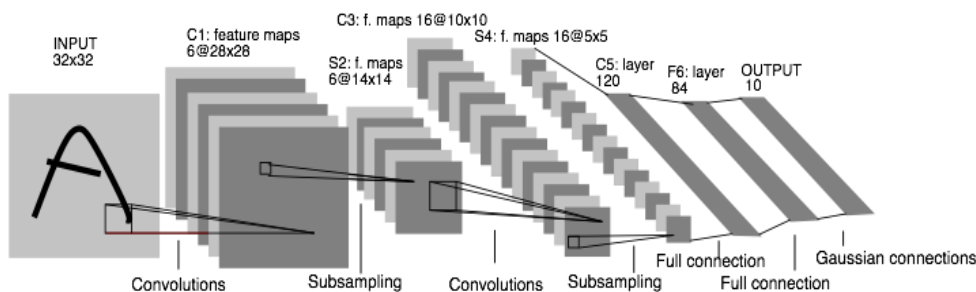


Recurrent

time \rightarrow



Convolutional



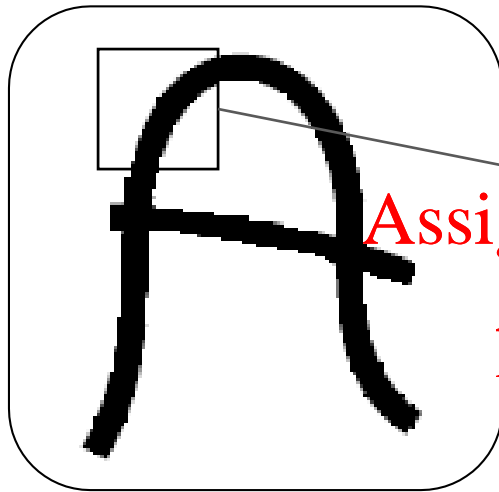
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Representing images

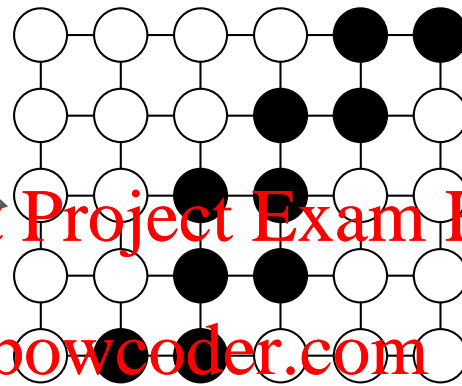
Fully connected



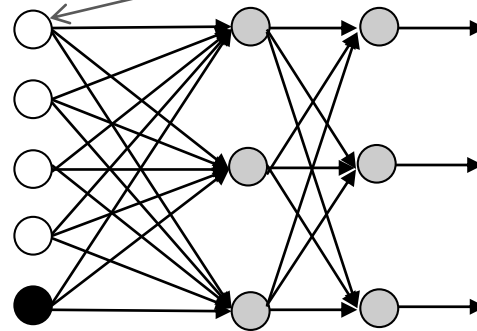
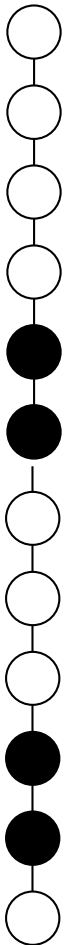
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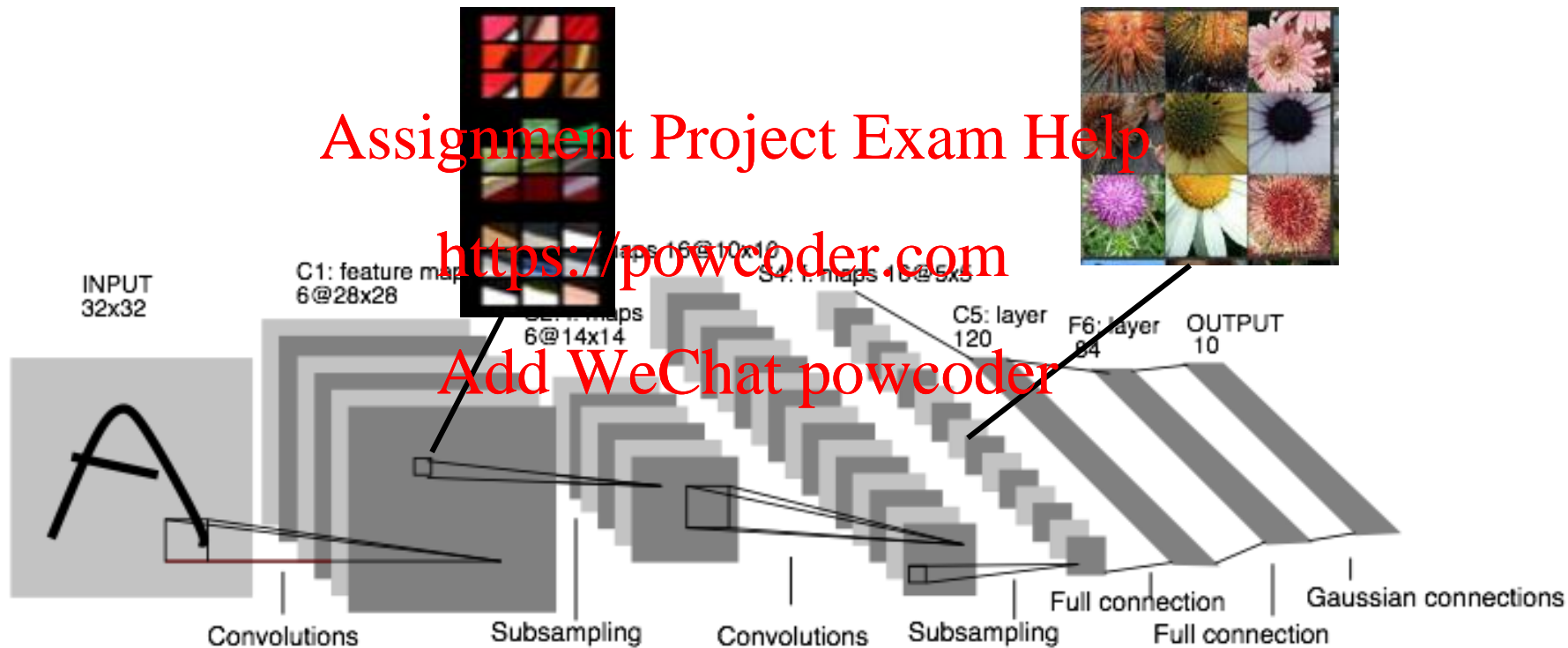


Reshape into a vector



Convolutional Neural Network

A better architecture for 2d signals



LeNet

Why Deep Learning?

The Unreasonable Effectiveness of Deep Features



Maximal activations of pool₅ units

[R-CNN]

Rich visual structure of features deep in hierarchy.



conv₅ DeConv visualization

[Zeiler-Fergus]

Summary so far

- **Neural network** chains together many layers of “neurons” such as logistic units

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- **Hidden neurons** learn more and more abstract non-linear features

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Next Class

Neural Networks I: Learning:

Learning via gradient descent; computation graphs, backpropagation algorithm.

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Reading: Bishop Ch 5.1-5.3

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