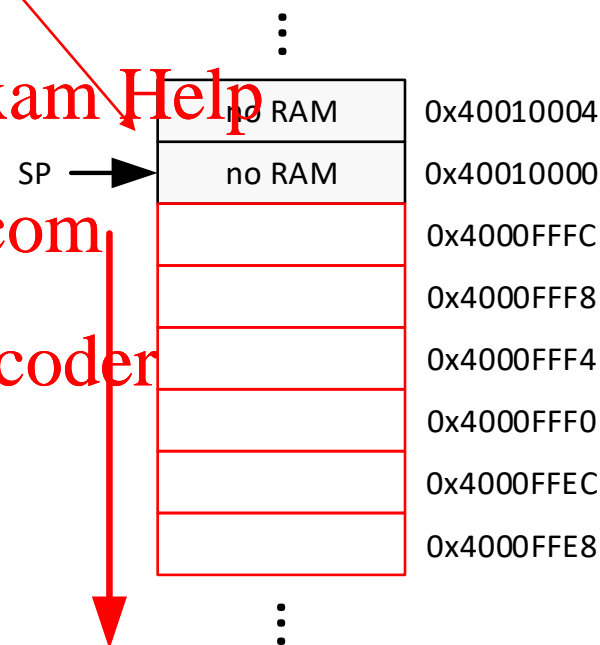


## System Stack

- area of RAM used as a stack
- item(s) can be pushed onto stack
- item(s) can be popped from stack
- with ARM, item(s) means register(s)
- SP (stack pointer = R13) points to last item pushed on stack and the stack grows down in memory (RAM)
- SP initialised to 0x40010000
- why 0x40010000?
- because hardware has RAM from 0x40000000 to 0x4000FFFF
- SP initially points to word beyond top of RAM (i.e. stack is empty)

top of EMPTY stack



stack grows  
down in memory

## System Stack...

- consider the stack after the following instructions are executed

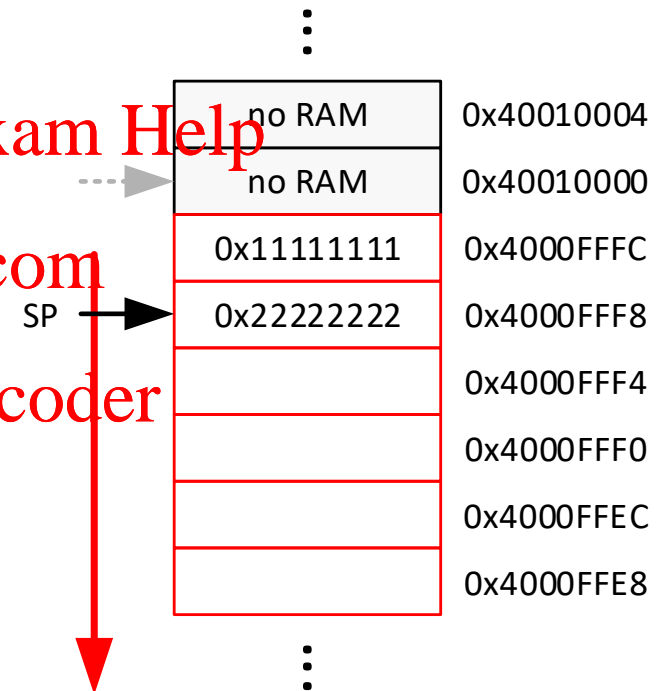
```
LDR    R1, =0x11111111
LDR    R2, =0x22222222
PUSH   {R1}
PUSH   {R2}
```

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- PUSH pre-decrements SP by 4 and saves register on stack at address in SP
- SP = 0x4000FFF8 (decremented by 8 as 8 bytes have been pushed on to the stack)
- SP (top of stack) -> pushed R2 (0x22222222)



stack grows down  
in memory

## System Stack...

- now consider the stack after the following instructions are executed

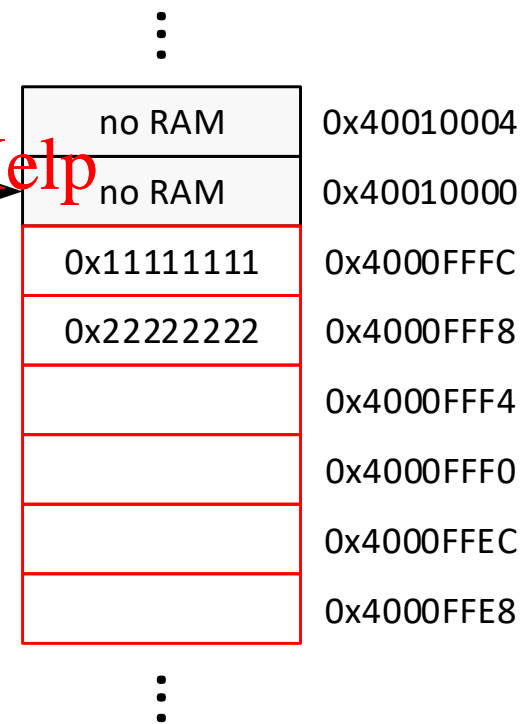
```
POP {R1}  
POP {R2}
```

- POP reads item from address in SP into specified register and then increments SP by 4

R1 = 0x22222222

R2 = 0x11111111

- have used stack to swap contents of R1 and R2
- SP = 0x40010000 (incremented by 8 as 8 bytes have been popped from stack)
- stack is a LIFO - last in, first out data structure



stack grows down  
in memory

## System Stack...

- ARM instruction set allows stacks to grow up or down in memory and for the SP to point to the first free location or last item pushed on stack
- STMxx instructions (store multiple) used to push a list of registers onto stack
- LDMxx instructions (load multiple) used to pop a list of registers from stack
- much easier, **FOR OUR PURPOSES**, to use the PUSH and POP pseudonyms for STMDB and LDMIA respectively
- example PUSH and POP instructions

PUSH {R3, R4, R5, R12} ; push R12, R5, R4 and R3  
PUSH {R0-R15} ; push **ALL** registers R15, R14, R13 ... R1 and R0  
POP {R3-R5, R12} ; pop R3, R4, R5 and R12

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D = decrement B = before

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I = increment A = after

## System Stack...

- in what order are the registers pushed? and popped?
- registers pushed/popped with “*highest register number at the highest address*”
- with a stack that grows down in memory...

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PUSH {R4-R12} ; registers pushed in order R12, R11, R10, ... R4  
; R12 will be at the highest address

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POP {R4-R12} ; registers popped in order R4, R5, R6, ... R12  
; R12 will be at the highest address

- if using a stack, remember to initialise the SP

LDR SP, =0x40010000 ; for CS1021 Keil uVision configuration

## System Stack...

- note that the LDR and STR instructions can be used to push and pop a single register to and from the stack

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**D = decrement B = before**

STR	R5, [SP, #-4]!	; push R5 (pre-decrement by 4)	DB
STR	R4, [SP, #-4]!	; push R4 (pre-decrement by 4)	DB
LDR	R4, [SP], #4	; pop R4 (post-increment by 4)	IA
LDR	R5, [SP], #4	; pop R5 (post-increment by 4)	IA

**I = increment A = after**

- code above equivalent to using the following PUSH and POP instructions

PUSH	{R4, R5}	; push R5 and R4
POP	{R4, R5}	; pop R4 and R5

## Subroutines

- a **subroutine** is a sequence of instructions that performs a particular task
- subroutine called wherever task needs to be performed
- divide
  - find the length of a NUL terminated string
  - compute  $x^y$
  - decrypt an email
  - ...
- subdivide a program into many “short” subroutines
- write subroutines so they can be called with different parameters
- breaking a large program into many subroutines will reduce development and maintenance costs and improve code quality and reliability

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## Subroutines...

- facilitates good program design
- facilitates code reuse
- can be called (“executed”, “invoked”) whenever needed
- can be called with different parameters
- can call other subroutines (and themselves recursively)
- correspond to procedures/functions/methods in high-level languages
- each subroutine can be programmed, tested and debugged independently

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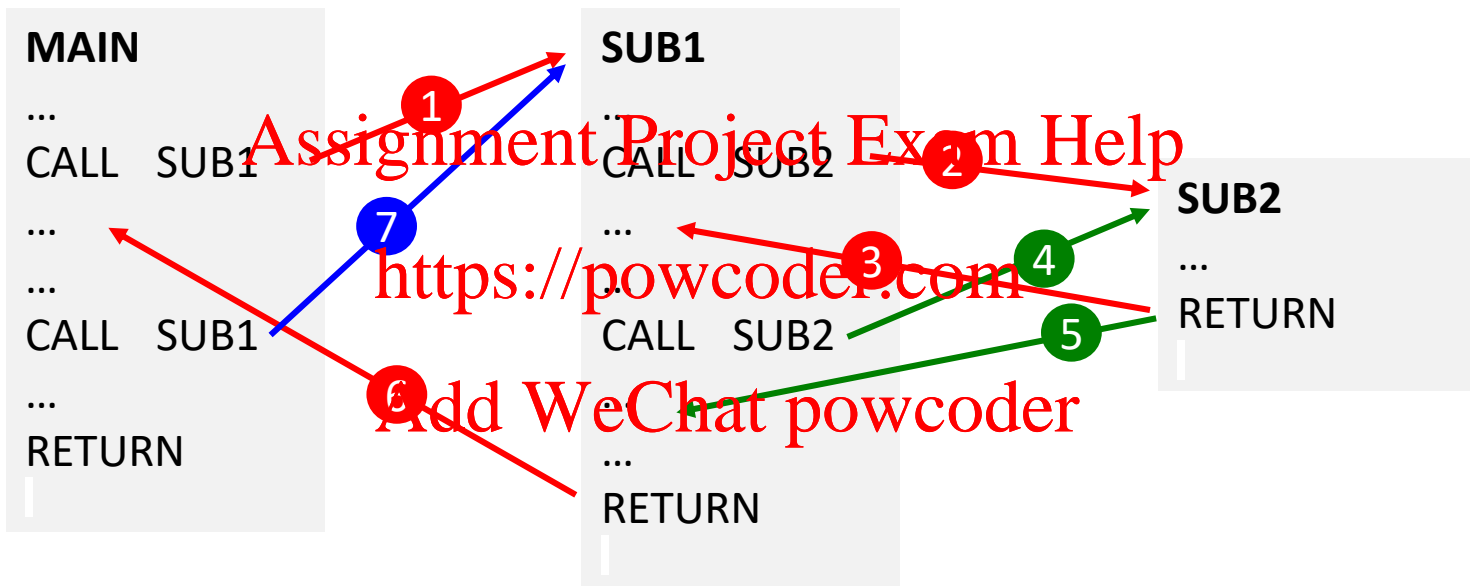
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# SUBROUTINES

## Subroutine call and return mechanism



- MAIN calls SUB1 (1), SUB1 calls SUB2 (2), SUB2 returns (3), SUB1 calls SUB2 again (4), SUB2 returns (5), SUB1 returns (6), MAIN calls SUB1 again (7), and so on
- RETURN returns to execute the instruction immediately following the call

## ARM call and return mechanism

- to call a subroutine use the BL (branch and link) instruction
- saves return address in link register (LR = R14)

0x00000400    BL    SUB1, LR = 0x00000404 (return address)  
0x00000404    ...    ;

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return address = address of next instruction

- to return from a subroutine use BX (branch and exchange) specifying the link register (LR)

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BX      LR      ; PC (program counter) = LR

- works for **leaf** subroutines (subroutines which do NOT call other subroutines), but if a subroutine calls another subroutine the return address saved in the link register will be overwritten
- need to save and restore return address(es) on a stack

## Using the stack to save and restore return addresses

- at the start of every **non leaf** subroutine, push the contents of LR (link register), which contains the return address, onto the system stack
- return from a **non leaf** subroutine by popping return address from stack and assigning to the PC (program counter)
- both steps accomplished easily using PUSH and POP instructions

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```
;
; non leaf subroutine
;
SUB1  PUSH   {LR}    ; push link register onto stack
...
...
      POP    {PC}    ; return by popping saved return address into PC
```

## ARM Procedure Calling Convention

- **ARM Architecture Procedure Call Standard (AAPCS)** is a technical document that describes the procedure calling convention that should be followed by high-level language compilers and writers of assembly language subroutines

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- simplified version (for CS1021)
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- first four subroutine parameters passed in R0, R1, R2 and R3 (respectively)
- result returned in R0
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- R0, R1, R2, R3 are considered volatile (subroutines can change/modify these registers)
- R4, R5, R6, R7, R8, R9, R10, R11, R12 are considered non volatile (subroutines **must return** these registers unchanged/unmodified)
- from a caller's perspective
  - R4 - R12 will be unchanged/unmodified by subroutine call
  - MUST ASSUME R0 - R3 will be changed/modified by subroutine call

## Subroutine entry and exit

- already seen how stack can be used to save and restore return addresses
- can also use stack to save and restore any of the registers R4 to R12 that the subroutine modifies so that they are returned to the caller unmodified
- again easily accomplished using PUSH and POP instructions at subroutine entry and exit

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- assume that the code for the subroutine modifies R5, R6 and R7

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```
SUB1  PUSH    {R5, R6, R7, LR} ; push return address (LR), R7, R6 and R5
```

```
...                                     ; subroutine body...
```

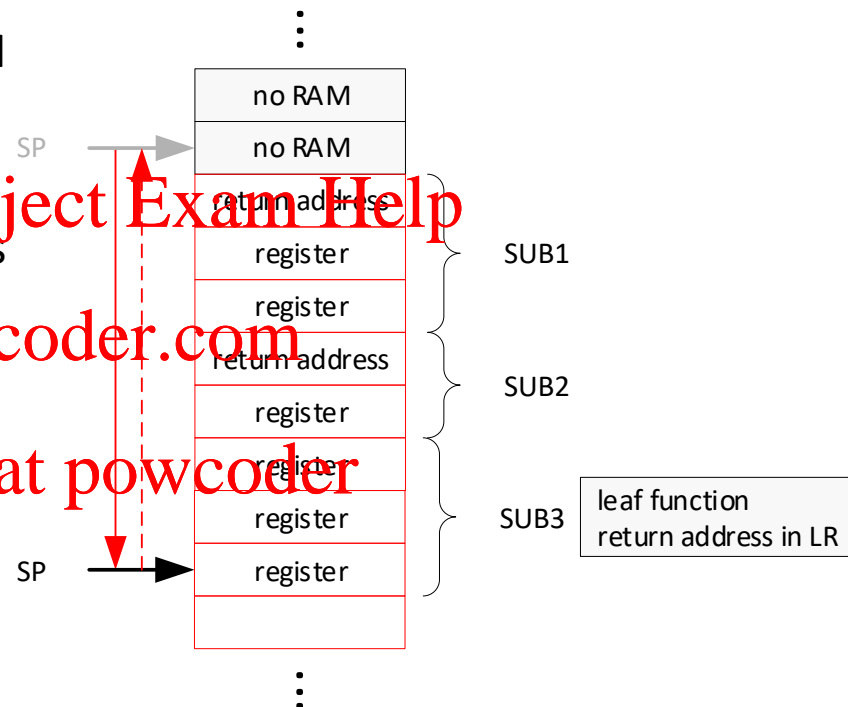
```
...                                     ; modifies R5, R6 and R7
```

```
POP    {R5, R6, R7, PC} ; pop R5, R6, R7 and return
```

- important that each subroutine pushes and pops the same number of registers at entry and exit otherwise the stack can become corrupted

## Subroutine Stack Frames

- subroutine stack frames pushed on and popped from stack
- for non-leaf subroutines return address and saved registers pushed
- for leaf subroutines, no need to push return address (in LR)



subroutine stack frames for  
SUB1, SUB2 and SUB3

# SUBROUTINES

## Example 1: UPPER (convert ASCII character to UPPER case)

```
;
; at entry: R0 = ch
; at exit:  R0 = UPPERCASE(ch)
;
; leaf function
;
UPPER    CMP    R0, #'a'      ; ch < 'a' ?
        BLO    UPPER1       ; nothing to do
        CMP    R0, #'z'      ; ch > 'z' ?
        BHI    UPPER1       ; nothing to do
        SUB    R0, R0, #0x20  ; ch = ch - 0x20
UPPER1   BX     LR           ; return
```

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## Example 2: STRUPR (convert string to upper case using UPPER)

```
;
; at entry:  R0 -> NUL terminated string
; at exit:   R0 -> string converted to UPPER case (in situ)
;
; non leaf function
; MUST ASSUME that calls to UPPER will change R0, R1, R2 and R3
; need to return from STRUPR with R0 unchanged
;
```

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```
STRUPR    PUSH    {R0, R4, LR}    ; push R0, R4 and return address
          MOV     R4, R0          ; make a copy of R0
STRUPRO   LDRB    R0, [R4]        ; get ch
          BL      UPPER          ; convert ch in R0 to UPPER case
          STRB    R0, [R4], #1    ; store ch AND R4 = R4 + 1
          CMP     R0, #0          ; ch == 0 ?
          BNE     STRUPRO         ; next ch
          POP     {R0, R4, PC}    ; pop R0, R4 and return
```



## Example 3: UDIV (unsigned divide)

- convert the “divide code” developed in lab4 into a subroutine
- parameters passed in R0 (Numerator) and R1 (Divisor)
- results returned in R0 (Quotient) and R1 (Remainder)
- code uses R0, R1, R2, R3, R4, R5, R6
- need to save and restore R4, R5 and R6 at entry and exit
- although UDIV is a leaf subroutine, decided to push LR at entry so that only a single PUSH and POP is needed to convert existing code into a subroutine

UDIV          PUSH          {R4, R5, R6, LR} ; push R4, R5, R6 and return address

...

<UDIV body which modifies R0, R1, R2, R3, R4, R5 and R6>

...

POP            {R4, R5, R6, PC} ; pop R4, R5, R6 and return

# SUBROUTINES

## Example 3: UDIV ...

```

;
; at entry  R0 = N (numerator)
;          R1 = D (divisor)
; at exit  R0 = Q (quotient)
;          R1 = R (remainder)
;
;
UDIV  PUSH    {R4, R5, R6, LR} ; push R4, R5, R6 and return address
      MOV     R2, R0           ; R2 = N
      MOV     R3, R1           ; R3 = D
      MOV     R0, #0           ; R0 = Q = 0
      MOV     R1, #0           ; R1 = R = 0
      MOV     R4, #31          ; R4 = i = 31
      MOV     R5, #1           ; R5 = 1 (used as a mask)
UDIV0  CMP     R4, #0           ; i = 0 ?
      BLT     UDIV2            ; finished
      MOV     R1, R1, LSL #1    ; R = R << 1
      AND     R6, R5, R2, LSR R4 ; R[0] = N[i]
      ORR     R1, R1, R6        ;
      CMP     R1, R3           ; R >= D?
      BLT     UDIV1            ;
      SUB     R1, R1, R3        ; R = R - D
      ORR     R0, R0, R5, LSL R4 ; Q[i] = 1
UDIV1  SUB     R4, R4, #1        ; i = i - 1
      B       UDIV0            ; next bit
UDIV2  POP     {R4, R5, R6, PC} ; pop into R4, R5, R6 and return

```

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alternative entry/exit code

**PUSH**        {R4, R5, R6}

...

...

**POP**         {R4, R5, R6}

**BX**          LR

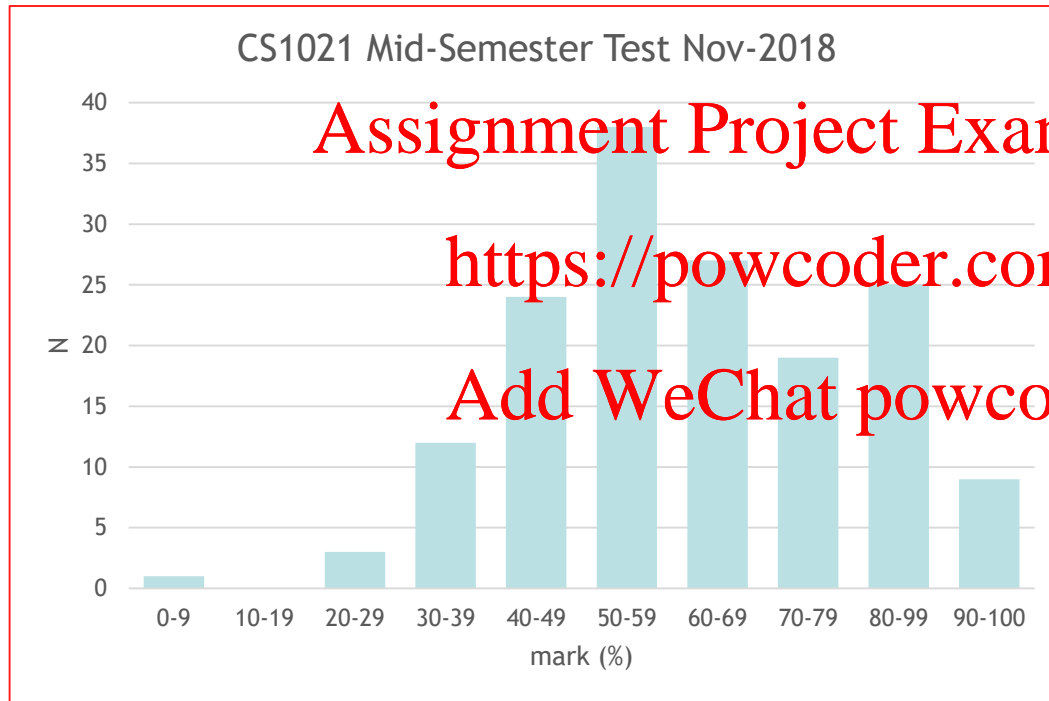
## Example 3: calling UDIV

- an array **b** of 8 x 32 bit unsigned integers is stored in memory @ 0x40000000
- write code to divide each integer by 42
- MUST ASSUME that UDIV modifies R2 and R3 as well as R0 and R1, so use R4 and R5 as address registers

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```
L    LDR    R4, =0x40000000    ; R4 -> b
      ADD    R5, R4, #32       ; R5 -> end of array b
      LDR    R0, [R4]          ; load integer from b
      LDR    R1, =42           ; divide by ...
      BL     UDIV              ; 42
      STR    R0, [R4], #4      ; store result AND R4 = R4 + 4
      CMP    R4, R5           ; finished?
      BNE    L                ; next integer
```

## Mid-Semester Test 2018



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< 40	F
40-49	III
50-59	II.2
60-69	II.1
70 - 100	I

N = 158 avg = 61.5%

# SUBROUTINES

## lab6

- “9,589 prime numbers in the first 100,000 integers” is incorrect

- need to compute  $n / 8$  and  $n \% 8$  ( $n \bmod 8$ )

- 8 is a  $2^3$  (a power of 2)

- decimal analogy  $1234 / 100$  and  $1234 \% 100$

- binary equivalent

- $\text{XXXX XXXX XXXX XXXX}_2$

- $n / 8 = n >> 3$

- $n \% 8 = n \& 0x07$  (where  $7 = 2^3 - 1$ )

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$1234 / 100 = 12 \text{ r } 34$

$2^3$

## What has not been covered in module

- ROR (rotate right) and ASR (arithmetic shift right) as per LSL and LSR
- details of LDR instruction (including ROR of immediate operand)
- LDRH (load halfword) and STRH (store halfword)
- LDRSB (load byte with sign extend) and LDRSH (load halfword with sign extend)
- other types of stacks
- subroutines with more than 4 parameters
- subroutines with more local variables than available registers
- recursion
- ...

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## CS1021 Learning Outcomes

at the end of the module you will be able to:

- describe the basic components and operation of a computer system
- represent and interpret information stored in binary form (integers, text, ...)
- design, write, test and document assembly language programs to solve simple problems
- translate high-level programming language constructs into their assembly language equivalents
- evaluate the efficiency of simple algorithms
- make use of appropriate documentation and reference material

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