CS114 (Spring 2020) Programming Assignment 4 Part-of-speech Tagging with Hidden Markov Models

Due April 3, 2020

You are given pos_tagger.py, and brown.zip, the Brown corpus (of part-of-speech tagged sentences). Sentences are separated into a training set (\$80% of the data) and a development set (\$10% of the data). A testing set (\$10% of the data) has been held out and is not given to you. You are also given data_small.zip, the toy corpus from HW2, in the same format. Lath School train [mail, Cost small collaboration of documents, each of which contains a number of tokenized, tagged sentences in the following format: [<word>/<tag>]. For example:

The/at Fulton policounty nnvt Quarty for Cory nn-tl said/vbd Friday/nr an/at investigation/nn of/in Atlanta's/np\$ recent/jj primary/nn election/nn produced/vbd ''/' no/at evidence/nn ''/' any/dtj tirpolayities/nlectook/vbd place/nn ''/'

Assignment

Your task is to implement a supervised hidden Markov model to perform part-of-speech tagging. Specifically, in pos_tagger.py, you should fill in the following functions:

- train(self, train_set): This function should, given a folder of training documents, fill in self.initial, self.transition and self.emission, such that:
 - \circ self.initial[POS] = $\log(P(\text{the initial tag is POS}))$
 - \circ self.transition[POS1][POS2] = $\log(P(\text{the current tag is POS2}|\text{the previous tag is POS1}))$
 - \circ self.emission[POS] [word] = $\log(P(\text{the current word is word}|\text{the current tag is POS}))$

As in PA2, you should use Numpy arrays for self.initial, self.transition, and self.emission. Again, you should use self.pos_dict and self.word_dict to translate between indices and words/parts of speech; you will need to fill these in yourself, based on the training data. Be sure to account for $\langle \text{UNK} \rangle$ (as a word, but not as a POS tag). You do not need to account for $\langle \text{S} \rangle$ or $\langle \text{S} \rangle$. Finally, you should implement add-k smoothing (on all three arrays); as in PA3, you should try to find the value of k that results in the maximum accuracy on the dev set.

Note that although / is the separator between words and parts of speech, some words also contain / in the middle of the word. In these cases, it is the last / that separates the word from the POS.

• viterbi(self, sentence): Implement the Viterbi algorithm!

A Specifically, for each derelopment (or testing), sentence, volustioned and filt in two crelises. Nampy arrays), v (for viters) and

backpointer. You can look at the pseudo-code given in Figure 8.5 of the Jurafsky and Martin book, reproduced below. Note that π_s are elements of the transition matrix, and $b_s(o_t) \in B$ are elements of the emission matrix.

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create a path probability matrix viterbi[N,T] for each state s from 1 to N do ; initialization step $viterbi[s,1] \leftarrow T_s * b_s(o_1)$ backpointer $[s,1] \leftarrow 0$; recursion step for each time step t from 2 to T do ; recursion step for each state s from 1 to N do $viterbi[s,t] \leftarrow \max_{s'=1}^N viterbi[s',t-1] * a_{s',s} * b_s(o_t)$ backpointer $[s,t] \leftarrow \max_{s'=1}^N viterbi[s',t-1] * a_{s',s} * b_s(o_t)$ bestpathprob $\leftarrow \max_{s=1}^N viterbi[s,T]$; termination step

bestpathprob $\leftarrow \max_{s=1} viterbi[s, T]$; termination step bestpathpointer $\leftarrow \arg\max viterbi[s, T]$; termination step

 $\textit{bestpath} \leftarrow \text{the path starting at state } \textit{bestpathpointer}, \text{ that follows backpointer}[] \text{ to states back in time } \textbf{return } \textit{bestpath}, \textit{bestpathprob}$

Figure 8.5 Viterbi algorithm for finding the optimal sequence of tags. Given an observation sequence and an HMM $\lambda = (A, B)$, the algorithm returns the state path through the HMM that assigns maximum likelihood to the observation sequence.

Some notes:

- The input sentence is a list. A list of what? You will need to translate from words to indices at some point in your code; it is recommended to do this translation outside of the viterbi function, so that the input to the function is a list of indices.
- Remember that when working in log-space, you should add the logs, rather than multiply the probabilities.
- Note that operations like + are Numpy universal functions, meaning that they automatically operate element-wise over arrays. This results in a substantial reduction in running time, compared with looping over each element of an array. As such, your viterbi implementation should not contain any for loops that range over states (for loops that range over time steps are fine).
- Assignment of the property of the second matrix is copied a times.
 - When rerfording iteg n array indexity the reside is an array of lower rank (number of dimensions). For example, if v is a matrix of shape (a, b), then v[:, t-1] is a vector of shape (a,). Broadcasting to a matrix of rank 2, however, results in a matrix of shape (1, a): our column becomes a row. To get a matrix of shape (a, 1), you can either use slice indexing instead (i.e. v[:, t-1:t]), append a new axis of None after your integer index (i.e. v[:, t-1, None]), or use the numpy.reshape function (i.e. numpy.reshape(v[:, t-1], (a, 1))).
 - In self.transition, each row represents a previous tag, while each column represents a current tag. Do not mix them up!
 - Finally, you do not have to return the path probability, just the backtrace path.

- test(self, dev_set): This function should, given a folder of development (or testing) documents, return a dictionary of results such that:
 - o results[sentence_id]['correct'] = correct sequence of POS
 tags
 - results[sentence_id]['predicted'] = predicted sequence of POS tags (hint: call the viterbi function)

You can assign each sentence a sentence_id however you want. Your sequences of POS tags can just be lists, e.g. ['at', 'np', ...].

• evaluate(self, results): This function should return the overall accuracy (# of words correctly tagged / total # of words). You don't have to calculate precision, recall, or F1 score.

Assignment Project Exam Help

- How you set the value of k
- Your Malution had to include any results on the toy data)

Submission Instructions

Please submit two files: your write-up (in PDF format), and pos_tagger.py. Do not include any data.