

CS373 Data Mining and Machine Learning

Lecture 4
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(originally prepared by Tommi Jaakkola, MIT CSAIL)

Today's topics

- Perceptron solution and kernels
- Support vector machine with kernels
 - dual solution, with offset, slack
- Homework 1 due today Sep 4, 11.59pm EST
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The perceptron solution

- Suppose the training set is linearly separable through origin given a particular feature mapping, i.e.,

$$y_i(\underline{\theta} \cdot \underline{\phi}(x_i)) > 0, \quad i = 1, \dots, n$$

for some $\underline{\theta}$

- The perceptron algorithm, applied repeatedly over the training set, will find a solution of the form

$$\underline{\theta} = \sum_{i=1}^n \alpha_i y_i \underline{\phi}(x_i), \quad \alpha_i \in \{0, 1, \dots\}$$

the number of mistakes made on
the i th training example until convergence

- We can recast the algorithm entirely in terms of these “mistake counts” α_i

Kernel perceptron

- We don't need the parameters nor the feature vectors explicitly
- All we need for predictions as well as updates is the value of the discriminant function

$$\underline{\theta} \cdot \underline{\phi}(\underline{x}) = \sum_{i=1}^n \alpha_i y_i [\underline{\phi}(\underline{x}_i) \cdot \underline{\phi}(\underline{x})] = \sum_{i=1}^n \alpha_i y_i \underbrace{K(\underline{x}_i, \underline{x})}_{\text{kernel}}$$

Initialize: $\alpha_i = 0, i = 1, \dots, n$
Repeat until convergence:

for $t = 1, \dots, n$

if $y_t \left(\sum_{i=1}^n \alpha_i y_i K(\underline{x}_i, \underline{x}_t) \right) \leq 0$ (mistake)

$$\alpha_t \leftarrow \alpha_t + 1$$

value of the discriminant
function prior to the update

Kernels

- By writing the algorithm in a “kernel” form, we can try to work with the kernel (inner product) directly rather than explicating the high dimensional feature vectors

$$\begin{aligned} K(\underline{x}, \underline{x}') &= \phi(\underline{x}) \cdot \phi(\underline{x}') \\ &= \begin{bmatrix} ? \\ \vdots \\ ? \end{bmatrix} \cdot \begin{bmatrix} ? \\ \vdots \\ ? \end{bmatrix} \\ &= \exp(-\|\underline{x} - \underline{x}'\|^2) \quad (\text{e.g.}) \end{aligned}$$

- All we need to ensure is that the kernel is “valid”, i.e., there exists some underlying feature representation

Valid kernels

- A kernel function is valid (is a kernel) if there exists some feature mapping such that

$$K(\underline{x}, \underline{x}') = \phi(\underline{x}) \cdot \phi(\underline{x}')$$

- Equivalently, a kernel is valid if it is symmetric and for all training sets, the Gram matrix

$$\begin{bmatrix} K(\underline{x}_1, \underline{x}_1) & \cdots & K(\underline{x}_1, \underline{x}_n) \\ \vdots & \ddots & \vdots \\ K(\underline{x}_n, \underline{x}_1) & \cdots & K(\underline{x}_n, \underline{x}_n) \end{bmatrix}$$

is positive semi-definite

Primal SVM

- Consider a simple max-margin classifier through origin

$$\text{minimize } \frac{1}{2} \|\underline{\theta}\|^2 \text{ subject to}$$
$$y_i(\underline{\theta} \cdot \underline{\phi}(x_i)) \geq 1, \quad i = 1, \dots, n$$

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- We claim that the solution has the same form as in the perceptron case <https://powcoder.com>

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$$\underline{\theta}(\alpha) = \sum_{i=1}^n \alpha_i y_i \underline{\phi}(x_i), \quad \alpha_i \geq 0$$

non-negative Lagrange multipliers
used to enforce the classification
constraints

- As before, we focus on estimating α_i which are now non-negative real numbers

Primal SVM

- Consider a simple max-margin classifier through origin

$$\text{minimize } \frac{1}{2} \|\underline{\theta}\|^2 \text{ subject to}$$

$$y_i(\underline{\theta} \cdot \underline{\phi}(x_i)) \geq 1, \quad i = 1, \dots, n$$

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- To solve this, we can introduce Lagrange multipliers for the classification constraints and minimize the resulting Lagrangian with respect to the parameters $\underline{\theta}$

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$$L(\underline{\theta}, \alpha) = \frac{1}{2} \|\underline{\theta}\|^2 - \sum_{i=1}^n \alpha_i [y_i(\underline{\theta} \cdot \underline{\phi}(x_i)) - 1]$$

$$\alpha_i \geq 0, \quad i = 1, \dots, n$$

Primal SVM

- Consider a simple max-margin classifier through origin

$$\text{minimize } \frac{1}{2} \|\underline{\theta}\|^2 \text{ subject to}$$

$$y_i(\underline{\theta} \cdot \underline{\phi}(x_i)) \geq 1, \quad i = 1, \dots, n$$

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- To solve this, we can introduce Lagrange multipliers for the classification constraints and minimize the resulting Lagrangian with respect to the parameters $\underline{\theta}$

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should become non-negative

$$L(\underline{\theta}, \alpha) = \frac{1}{2} \|\underline{\theta}\|^2 - \sum_{i=1}^n \alpha_i [y_i(\underline{\theta} \cdot \underline{\phi}(x_i)) - 1]$$

$$\alpha_i \geq 0, \quad i = 1, \dots, n$$

positive values
enforce classification
constraints

Understanding the Lagrangian

$$L(\underline{\theta}, \alpha) = \frac{1}{2} \|\underline{\theta}\|^2 - \sum_{i=1}^n \alpha_i [y_i(\underline{\theta} \cdot \underline{\phi}(x_i)) - 1]$$

$$\alpha_i \geq 0, \quad i = 1, \dots, n$$

- We can recover the primal problem by maximizing the Lagrangian with respect to the Lagrange multipliers

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since $y_i(\underline{\theta} \cdot \underline{\phi}(x_i)) - 1 \geq 0$, for all i
make $\alpha_i = 0$

$$\max_{\alpha \geq 0} L(\underline{\theta}, \alpha) = \begin{cases} \frac{1}{2} \|\underline{\theta}\|^2, & \text{if } y_i(\underline{\theta} \cdot \underline{\phi}(x_i)) \geq 1, \quad i = 1, \dots, n \\ \infty, & \text{otherwise} \end{cases}$$

to maximize:

$y_i(\underline{\theta} \cdot \underline{\phi}(x_i)) - 1 < 0$, for some i
make $\alpha_i = \infty$

Note: to **minimize** $\max_{\alpha \geq 0} L(\theta, \alpha)$ with respect to θ , we should always fulfill constraints, to avoid ∞

Primal - Dual

$$\text{minimize } \frac{1}{2} \|\underline{\theta}\|^2 \text{ subject to}$$
$$y_i(\underline{\theta} \cdot \underline{\phi}(x_i)) \geq 1, \quad i = 1, \dots, n$$

?

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$$\min_{\underline{\theta}} \left[\overbrace{\max_{\alpha \geq 0} L(\underline{\theta}, \alpha)}^{\text{primal}(\underline{\theta})} \right]$$

- expressed in terms of $\underline{\theta}$
- explicit feature vectors $\underline{\phi}(x)$

Primal - Dual

minimize $\frac{1}{2} \|\underline{\theta}\|^2$ subject to
 $y_i(\underline{\theta} \cdot \underline{\phi}(\underline{x}_i)) \geq 1, \quad i = 1, \dots, n$

Slater conditions
 (linear constraints \rightarrow strong duality)

?

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$$\min_{\underline{\theta}} \left[\overbrace{\max_{\alpha \geq 0} L(\underline{\theta}, \alpha)}^{\text{primal}(\underline{\theta})} \right] = \max_{\alpha \geq 0} \left[\underbrace{\min_{\underline{\theta}} L(\underline{\theta}, \alpha)}_{\text{step 1}} \right] \quad \text{step 2}$$

- expressed in terms of $\underline{\theta}$
- explicit feature vectors $\underline{\phi}(\underline{x})$

- expressed in terms of α
- kernels $K(\underline{x}, \underline{x}')$

Lagrangian Dual (step 1)

$$L(\underline{\theta}, \alpha) = \frac{1}{2} \|\underline{\theta}\|^2 - \sum_{i=1}^n \alpha_i [y_i(\underline{\theta} \cdot \underline{\phi}(\underline{x}_i)) - 1]$$

$$\frac{\partial}{\partial \underline{\theta}} L(\underline{\theta}, \alpha) = 0$$

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Lagrangian Dual (step 1)

$$L(\underline{\theta}, \alpha) = \frac{1}{2} \|\underline{\theta}\|^2 - \sum_{i=1}^n \alpha_i [y_i(\underline{\theta} \cdot \underline{\phi}(\underline{x}_i)) - 1]$$

$$\frac{\partial}{\partial \underline{\theta}} L(\underline{\theta}, \alpha) = \underline{\theta} - \quad = 0$$

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Lagrangian Dual (step 1)

$$L(\underline{\theta}, \alpha) = \frac{1}{2} \|\underline{\theta}\|^2 - \sum_{i=1}^n \alpha_i [y_i(\underline{\theta} \cdot \phi(\underline{x}_i)) - 1]$$

$$\frac{\partial}{\partial \underline{\theta}} L(\underline{\theta}, \alpha) = \underline{\theta} - \sum_{i=1}^n \alpha_i y_i \phi(\underline{x}_i) = 0$$

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Lagrangian Dual (step 1)

$$L(\underline{\theta}, \alpha) = \frac{1}{2} \|\underline{\theta}\|^2 - \sum_{i=1}^n \alpha_i [y_i(\underline{\theta} \cdot \phi(\underline{x}_i)) - 1]$$

$$\frac{\partial}{\partial \underline{\theta}} L(\underline{\theta}, \alpha) = \underline{\theta} - \sum_{i=1}^n \alpha_i y_i \phi(\underline{x}_i) = 0$$

$$\Rightarrow \underline{\theta} = \sum_{i=1}^n \alpha_i y_i \phi(\underline{x}_i) = \underline{\theta}(\alpha) \quad \text{(unique solution as a function of } \alpha \text{)}$$

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Lagrangian Dual (step 1)

$$L(\underline{\theta}, \alpha) = \frac{1}{2} \|\underline{\theta}\|^2 - \sum_{i=1}^n \alpha_i [y_i(\underline{\theta} \cdot \phi(\underline{x}_i)) - 1]$$

$$\frac{\partial}{\partial \underline{\theta}} L(\underline{\theta}, \alpha) = \underline{\theta} - \sum_{i=1}^n \alpha_i y_i \phi(\underline{x}_i) = 0$$

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- The dual problem is obtained by substituting this solution back into the Lagrangian and recalling that the Lagrange multipliers are non-negative

$$\text{dual}(\alpha) = \min_{\underline{\theta}} L(\underline{\theta}, \alpha) = L(\underline{\theta}(\alpha), \alpha) \quad \alpha_i \geq 0$$

Dual SVM (step 2)

$$\underline{\text{maximize}} \quad \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j \underbrace{[\phi(\underline{x}_i) \cdot \phi(\underline{x}_j)]}_{\text{kernel}}$$

subject to $\alpha_i \geq 0, i = 1, \dots, n$

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- This is again a quadratic programming problem but with simpler “box” constraints

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Dual SVM (step 2)

$$\underline{\text{maximize}} \quad \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j \underbrace{[\phi(\underline{x}_i) \cdot \phi(\underline{x}_j)]}_{\text{kernel}}$$

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the solution α^* is not necessarily unique

Dual SVM (step 2)

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the solution α^* is not necessarily unique

$$\underline{\theta}(\alpha^*) = \sum_{i=1}^n \alpha_i^* y_i \phi(\underline{x}_i) \quad \text{is unique } (= \underline{\theta}^*)$$

Dual SVM (step 2)

$$\underline{\text{maximize}} \quad \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j \underbrace{[\phi(\underline{x}_i) \cdot \phi(\underline{x}_j)]}_{\text{kernel}}$$

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$$\underline{\theta}(\alpha^*) = \sum_{i=1}^n \alpha_i^* y_i \phi(\underline{x}_i) \quad \text{is unique } (= \underline{\theta}^*)$$

if $\alpha_i^* > 0 \Rightarrow y_i(\underline{\theta}(\alpha^*) \cdot \phi(\underline{x}_i)) = 1$ (support vector)

Dual SVM (step 2)

$$\underline{\text{maximize}} \quad \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j \underbrace{[\phi(\underline{x}_i) \cdot \phi(\underline{x}_j)]}_{\text{kernel}}$$

subject to $\alpha_i \geq 0, i = 1, \dots, n$

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the solution α^* is not necessarily unique

$$\underline{\theta}(\alpha^*) = \sum_{i=1}^n \alpha_i^* y_i \phi(\underline{x}_i) \quad \text{is unique } (= \underline{\theta}^*)$$

$$\text{if } \alpha_i^* > 0 \Rightarrow y_i(\underline{\theta}(\alpha^*) \cdot \phi(\underline{x}_i)) = 1 \quad (\text{support vector})$$

$$\text{if } \alpha_i^* = 0 \Rightarrow y_i(\underline{\theta}(\alpha^*) \cdot \phi(\underline{x}_i)) \geq 1$$

Dual SVM

$$\underline{\text{maximize}} \quad \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j \underbrace{[\phi(\underline{x}_i) \cdot \phi(\underline{x}_j)]}_{\text{kernel}}$$

subject to $\alpha_i \geq 0, i = 1, \dots, n$

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- This is again a quadratic programming problem but with simpler “box” constraints

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- Once we solve for α_i^* , we predict labels according to

$$\begin{aligned} f(\underline{x}; \alpha^*) &= \text{sign}(\theta(\alpha^*) \cdot \phi(\underline{x})) \\ &= \text{sign}\left(\sum_{i=1}^n \alpha_i^* y_i \underbrace{[\phi(\underline{x}_i) \cdot \phi(\underline{x})]}_{\text{kernel}}\right) \end{aligned}$$

Kernel SVM

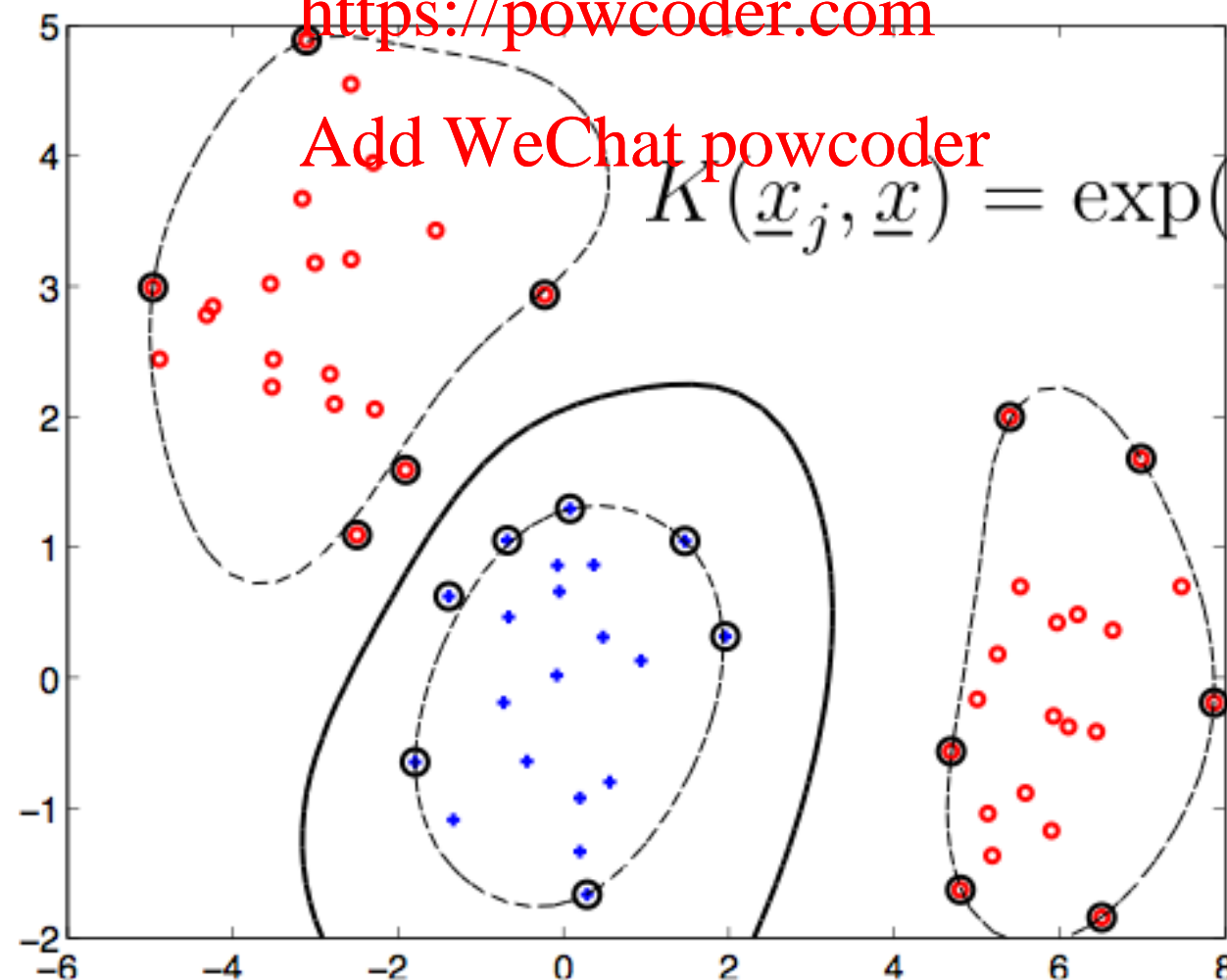
- Solving the SVM dual implicitly finds the max-margin linear separator in the feature space

$$f(\underline{x}; \alpha) = \text{sign}\left(\sum_{i=1}^n \alpha_i y_i K(\underline{x}_i, \underline{x})\right)$$

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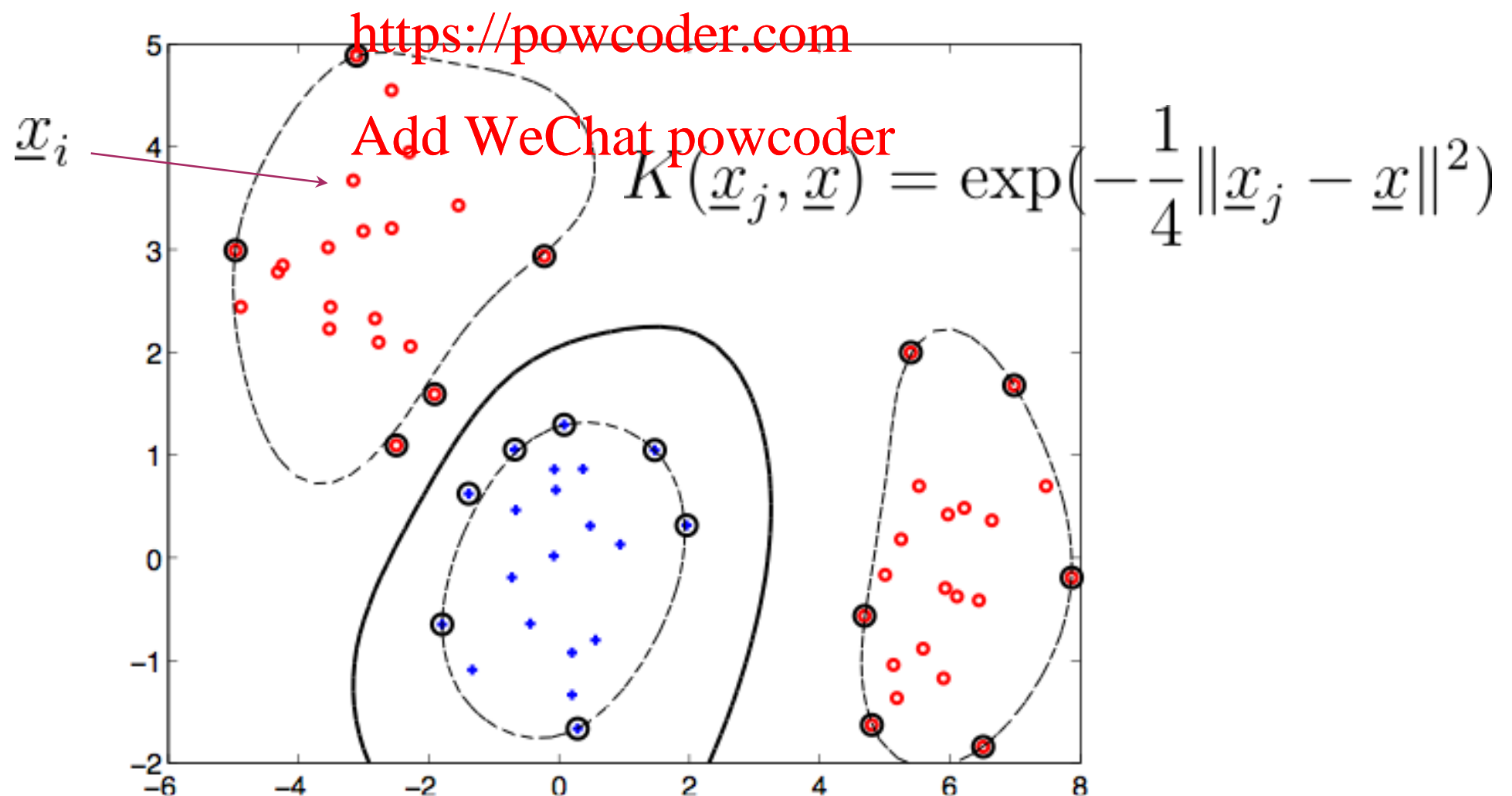
$$K(\underline{x}_j, \underline{x}) = \exp\left(-\frac{1}{4}\|\underline{x}_j - \underline{x}\|^2\right)$$

RBF kernel, support vectors

- Assume no offset, no slack. A point is not a support vector if the margin constraint is satisfied without it (otherwise it has to be a SV)

$$y_i \sum_{j \neq i} \alpha_j y_j K(\underline{x}_j, \underline{x}_i) \geq 1 \Leftrightarrow \underline{x}_i \text{ not a SV} \quad (\text{if } \alpha_i = 0)$$

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Dual SVM with offset

$$\underline{\text{maximize}} \quad \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j \underbrace{[\phi(\underline{x}_i) \cdot \phi(\underline{x}_j)]}_{\text{kernel}}$$

subject to $\alpha_i \geq 0, i = 1, \dots, n,$

$$\sum_{i=1}^n \alpha_i y_i = 0$$

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- Where's the offset parameter? How do we solve for it?

Dual SVM with offset

$$\underline{\text{maximize}} \quad \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j \underbrace{[\phi(\underline{x}_i) \cdot \phi(\underline{x}_j)]}_{\text{kernel}}$$

subject to $\alpha_i \geq 0, i = 1, \dots, n, \sum_{i=1}^n \alpha_i y_i = 0$

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- Where's the offset parameter? How do we solve for it?
- We know that the classification constraints are tight for support vectors. If the i th point is a support vector, then

$$y_i(\theta(\alpha^*) \cdot \phi(\underline{x}_i) + \theta_0^*) = 1$$

Dual SVM with offset

$$\underline{\text{maximize}} \quad \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j \underbrace{[\phi(\underline{x}_i) \cdot \phi(\underline{x}_j)]}_{\text{kernel}}$$

subject to $\alpha_i \geq 0, i = 1, \dots, n, \sum_{i=1}^n \alpha_i y_i = 0$

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- Where's the offset parameter? How do we solve for it?
- We know that the classification constraints are tight for support vectors. If the i th point is a support vector, then

$$y_i(\theta(\alpha^*) \cdot \phi(\underline{x}_i) + \theta_0^*) = 1$$

$$\Rightarrow \theta_0^* = y_i - \theta(\alpha^*) \cdot \phi(\underline{x}_i) = y_i - \sum_{j=1}^n \alpha_j^* y_j \underbrace{[\phi(\underline{x}_j) \cdot \phi(\underline{x}_i)]}_{\text{kernel}}$$

Note: you can pick any SV

Dual SVM with offset and slack

$$\begin{aligned} & \underline{\text{maximize}} \quad \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n \alpha_i \alpha_j y_i y_j \underbrace{[\phi(\underline{x}_i) \cdot \phi(\underline{x}_j)]}_{\text{kernel}} \\ & \text{subject to} \quad 0 \leq \alpha_i \leq C, i = 1, \dots, n, \quad \sum_{i=1}^n \alpha_i y_i = 0 \end{aligned}$$

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- C is the same slack penalty as in the primal formulation