

# High Performance Computing Course Notes

## Performance I

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# Metrics to measure the parallelization quality of parallel programs

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Degree of Parallelism, average parallelism

Effective work

Speedup

Parallel efficiency

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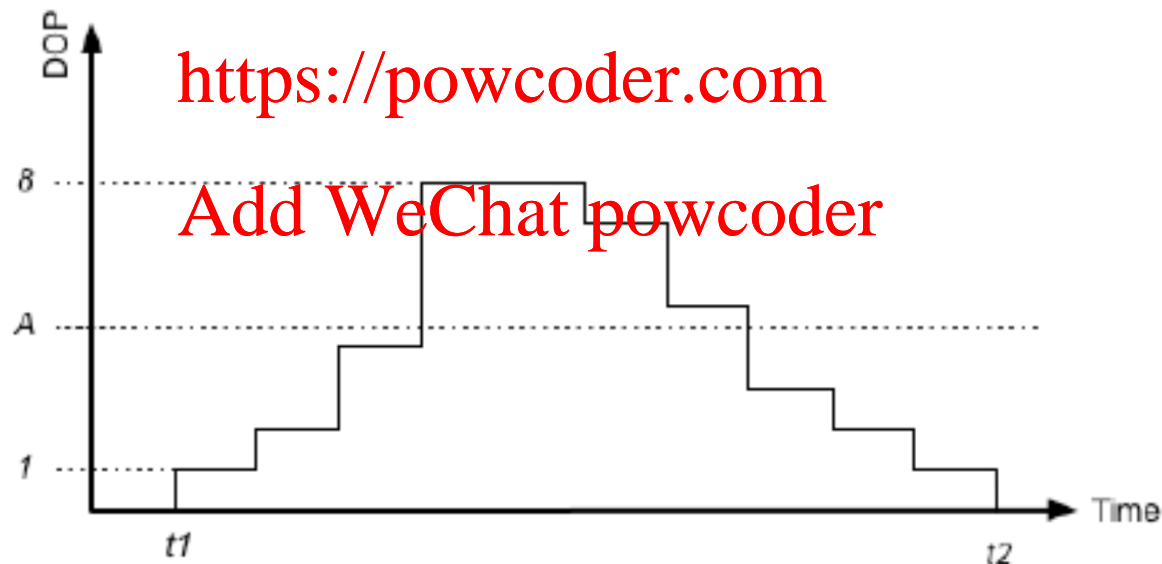
# Degree of Parallelism

- Degree of Parallelism (DOP)
  - The number of processors **engaged in execution at the same time**
  - Two forms of functions: continuous form and discrete form

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# Degrees of Parallelism

Factors that affect the DOP include:

- Application properties

- Data dependency,  
Assignment, Partition, Overhead

- Resource limitations

- number of processors,  
memory, I/O

- Algorithms

- how does the algorithm divide up work?

# Effective Work

## Effective Work

- This is the total amount of computation executed within a given time interval.

- Effective work relates to DOP

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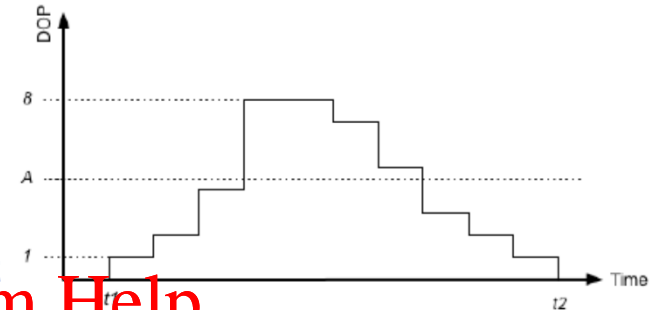
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# Effective work

## Calculating Effective work

- $m$  homogeneous processors
- processing capacity of a single processor (execution rate) =  $\Delta$
- $DOP(t)$  = Number of busy PEs at time  $t$  in  $[t_1, t_2]$
- Total effective work in discrete form



$$W = \Delta \sum_{i=1}^m i \cdot t_i$$

where  $t_i$  is the total time that  $DOP = i$  and  $\sum_{i=1}^m t_i = t_2 - t_1$

- Total effective work in continuous form:

$$W = \Delta \int_{t_1}^{t_2} DOP(t) dt$$

# Average Parallelism

## Average parallelism:

### □ Continuous form:

$$A = \frac{1}{t_2 - t_1} \int_{t_1}^{t_2} \text{DOP}(t) dt$$

### □ Discrete form: <https://powcoder.com>

$$A = \frac{\sum_{i=1}^m i \cdot t_i}{\sum_{i=1}^m t_i}$$

# Speedup

We desire to know the improvement (or not) brought about by parallelising an application code.

The improvement can be measured by *speedup*

- In the simplest form, speedup is the ratio of execution time of a serial implementation to the execution time of a parallel implementation.

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If  $n$  processors are used, then:

$$S(n) = t_1 / t_n$$

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- $t_1$  is the **worst case** execution time of the **optimal** serial implementation.
- $t_n$  is the **worst case** execution time of the parallel algorithm using  $n$  processors.



# Speedup

## What is “good” speedup?

- Linear speedup is regarded as optimal
- Maximum speedup for a parallel algorithm with  $n$  processors is  $n$ .
- To illustrate this:
  - Consider the execution time of an application is  $t_1$
  - The application is split into  $n$  processes
  - Assume no overheads, communications, synchronisation etc.
  - The least execution time is  $t_1/n$
  - So the maximum speedup is  $S(n) = t_1 / (t_1 / n) = n$
- Not always true (we may achieve superlinearity in some special circumstances)

# Speedup

**Some tasks can exceed linear speedup.**

- This is superlinear speedup ( $S(n) > n$ )

## Reasons

- Cache or memory effects
- Evidence of sub-optimal sequential implementation

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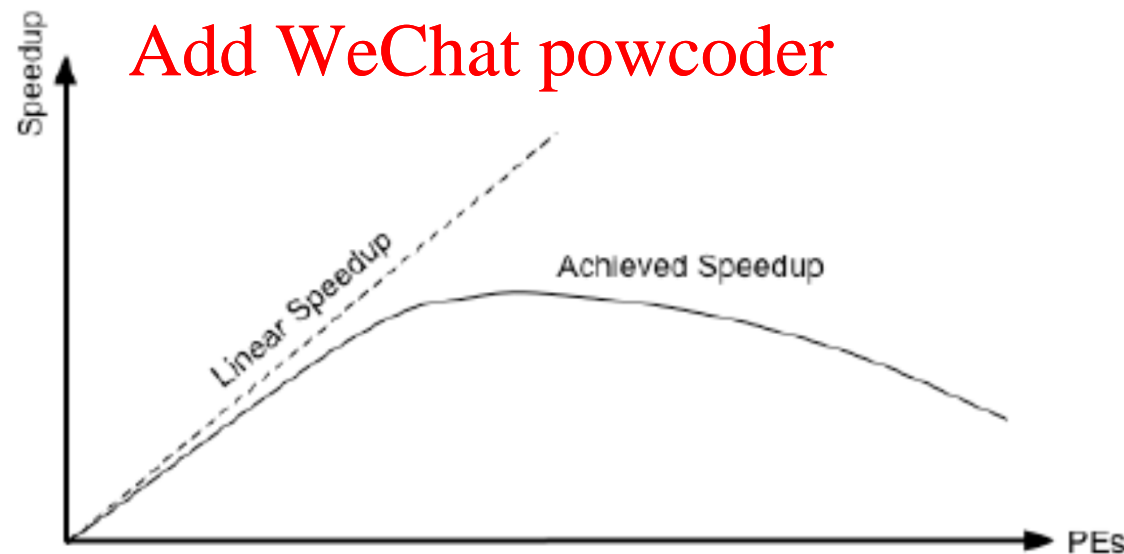
# Speedup

## □ The general trend of speedup as the number of processors increases

- First, speedup increases as the number of PE increases, but the gap with the maximum speed also increases
- After speedup reaches a maximum speedup, adding processors further is of no benefit and will harm performance

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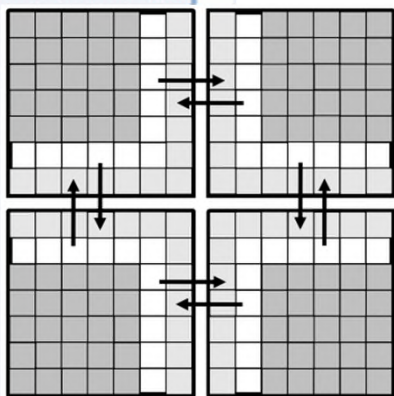


# Speedup

## How to obtain good $S(n)$ for large $n$ ?

- ❑ Algorithm design: Minimal sequential component and good percentage of inherent (data) parallelism.
- ❑ workload management: balancing workload among processors
- ❑ When there are different ways to partition data and achieve load balance, try to maintain a high ratio of computation to communication (computation represents effective work while communication represents overhead)

- Use the way which leads to less communication
- Low frequency of communications between processors
- increase the size of the work run by each processor.



# Reducing the Impact of Communication

Communication has crucial impact on the performance of parallel programming

How to reduce the impact of communication:

- ❑ Minimize the amount of communication (e.g. by maintaining a good data locality)
- ❑ Overlap communications with computation where possible.
- ❑ Reduce latency and overhead by sending a few large messages, rather than a lot of small messages.
- ❑ At the hardware level, can reduce latency by using fast (but expensive) communications.

# Parallel efficiency

Parallel efficiency:

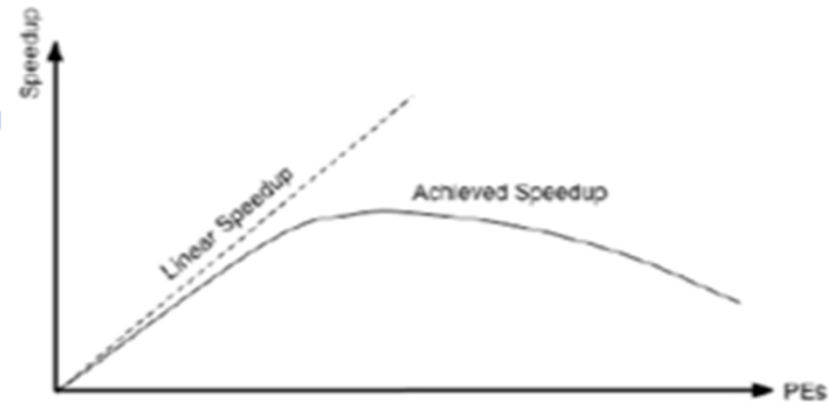
$$E(n) = S(n) / n$$

Parallel programs are not usually 100% efficient, i.e.  $S(n) \ll n$

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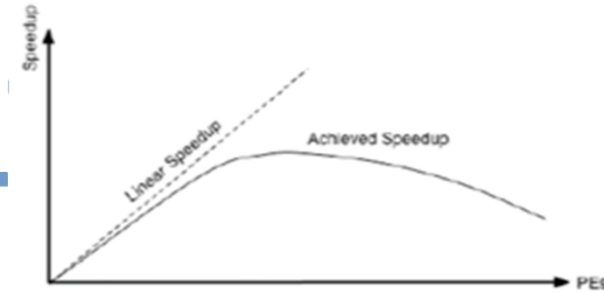
Main issues that affect parallel efficiency are:

- ☐ Same as the factors for affecting speedup
- ☐ Plus the impact of  $n$ ; typically, greater  $n$ , lower efficiency





# Iso-efficiency



## Constant Efficiency:

- ❑ How the amount of computation performed ( $N$ ) must scale with processor number  $P$  to keep parallel efficiency  $E$  constant
- ❑ The function of  $N$  over  $P$  is called an algorithm's iso-efficiency function
- ❑ An algorithm with an iso-efficiency function of  $O(P)$  is highly scalable
  - E.g., Increase  $p$  by three times, only need to increase  $N$  by three times to maintain efficiency
- ❑ An algorithm with a quadratic or exponential iso-efficiency function is less scalable
  - E.g. increase  $p$  by three times, need to increase  $N$  by 9 times and 8 times, respectively

## Work out the iso-efficiency function

- ⑩ Given the parallel efficiency function as follows, work out the iso-efficiency function.

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$$E_2 = \frac{5N^2}{5N^2 + 2P^2 + 4NP}$$

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Answer:  $N=O(P)$

# Four approaches to modelling the performance of a parallel application

Speedup

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Amdahl's law

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Asymptotic analysis

Modelling execution time

# Speedup approach

Using speedup approach, we can say something like “this algorithm achieved a speedup of  $S$  on  $p$  processors with problem size  $N$ ”

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This approach can give us some ideas about the algorithm quality, but we cannot judge the quality of an algorithm by a single speedup data

Elaborate this point in the following example

# Speedup approach

Consider a sequential algorithm and its optimal execution time  $T = N + N^2$ , where  $N$  is the problem size

□ Parallel Algorithm 1:  $T = N + (N^2 / p)$

- Partitions the computationally expensive  $O(N^2)$
- No other costs.

□ Parallel Algorithm 2:  $T = ((N + N^2) / p) + 100$

- Partitions the whole computation
- Introduces fixed overhead cost of 100.

□ Parallel Algorithm 3:  $T = ((N + N^2) / p) + 0.6p^2$

- Partitions the whole computation
- Introduces variable overhead cost of  $0.6p^2$

# Speedup approach

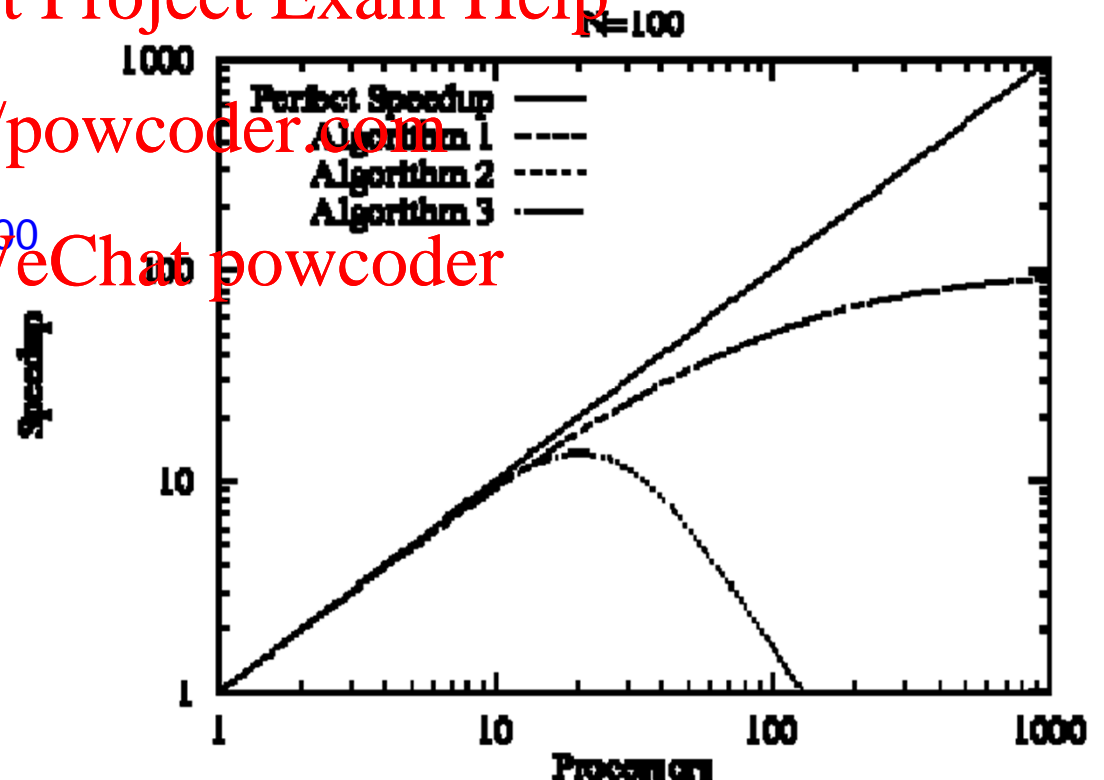
These algorithms all achieve a speedup of about 10.8 when  $p = 12$  and  $N = 100$ , but differentiates with each other when  $p$  becomes large.

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Algorithm 1:  $T = N + (N^2 / p)$

Algorithm 2:  $T = ((N + N^2) / p) + 100$

Algorithm 3:  $T = ((N + N^2) / p) + 0.6p^2$





# Amdahl's Law

Applications may contain elements that are not amenable to parallelisation.

Let this serial fraction be  $f$ :

- If we make the remaining part  $n$  times faster by running it on  $n$  processors, then the time  $T_n$  is:

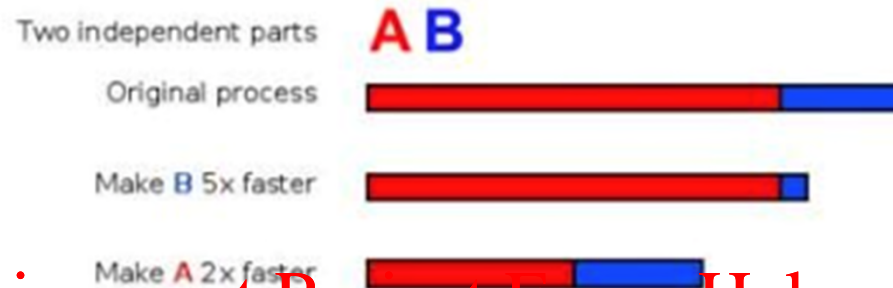
$$T_n = \frac{(1-f)T_1}{n} + fT_1$$

- Hence, speedup is:  $S(n) = \frac{n}{(1-f) + nf} \leq \frac{1}{f}$

□ For example, an application does a final (non-parallelisable) collective operation at the end of each iteration which accounts for 8% of the computation time - the maximum achievable speedup is 12.5.

□ This is Amdahl's Law.

# Application of Amdahl's Law



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- Part A takes 75% and part B takes 25% of the whole computation time

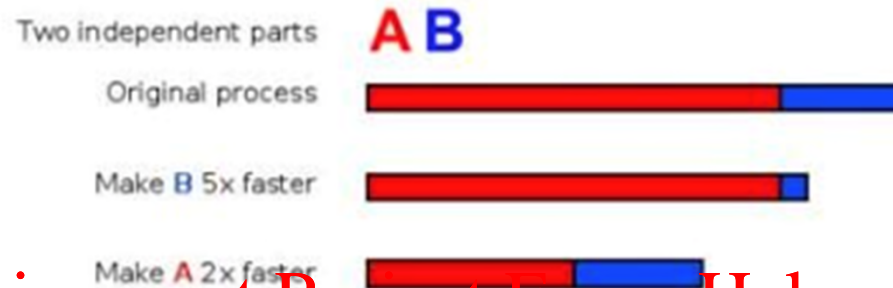
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- If we decide to parallelize part B, then the upper bound of the speedup is  $1/0.75=1.33$

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- If we decide to parallelize part A, then the upper bound of the speedup is  $1/0.25=4$

# Application of Amdahl's Law



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- Part A takes 75% and part B takes 25% of the whole computation time

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- If we make part B 5 times faster, then

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$$\text{speedup} = \frac{1}{\frac{0.25}{5} + 0.75} = 1.25$$

- If we make part A 2 times faster, then

$$\text{speedup} = \frac{1}{0.25 + \frac{0.75}{2}} = 1.6$$

- Therefore, making A twice faster is better (and typically be much easier) than making B five times faster;

# Amdahl's Law

→ Amdahl's law shows us the limitation of parallelising codes

→ Disadvantages

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- Can only tell the upper bound of the speedup for a particular algorithm.  
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- Cannot tell whether greater parallelism exist for the problem.  
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# Asymptotic analysis

→ In this modelling approach, we can say something like “the algorithm takes the time of  $O(n \log n)$  on  $n$  processors”

→ Disadvantage:

☐ ignore the lower-order term:

- e.g. given an algorithm with time complexity of  $O(n \log n)$ , the actual time complexity could be  $10n + n \log n$ , when  $n$  is small,  $10n$  dominates

☐ Only tell the order of the execution time of a program, not its actual execution time:

- e.g. given two algorithms, one's time complexity is  $1000n \log n$  while the other's is  $10n^2$ .  $1000n \log n$  is better than  $10n^2$  when  $n$  exceeds a certain value, but  $10n^2$  is less than  $1000n \log n$  when  $n$  is less than the value