

# High Performance Computing

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Models of Parallel Programming

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# Models of Parallel Programming

## Different approaches for programming on parallel and distributed computing systems include:

- Dedicated languages designed specifically for parallel computers
- Smart compilers, which automatically parallelise sequential codes
- Data parallelism: multiple processors run the same operation on different elements of a data structure
- Task parallelism: multiple processors run different operations

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## - Two classes of parallelism according to computer architecture

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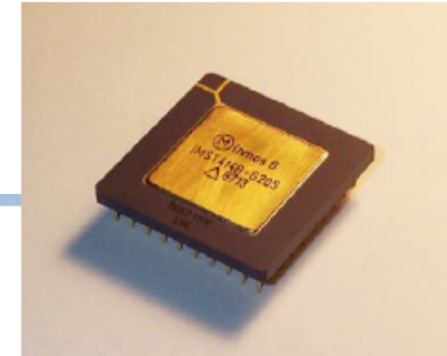
- Shared memory: processors share a common address space
- distributed memory: the memory in each processor has its own address space

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**Specially Designed Language**  
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# Occam



**Occam is a concurrent programming language**

**Occam is an executable implementation of Communicating Sequential Processes (CSP) theory**

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**CSP: a mathematical theory for describing the interactions of tasks in a concurrent system**

**Can theoretically prove if the program written in Occam is correct**

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**Occam is specially designed to make full use of the features of a custom-designed computer system, which is built with the *transputer* (transistor computer) chips, developed by INMOS**

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**Transputer is the first microprocessor specially designed for parallel computing**  
**A number of transputer chips are wired to form a complete computer system (no bus, RAM or OS)**

**In Occam, the processes communicate through channels**

**Channel can be regarded as the message passing mechanism within a computer**

# Occam

Sequential execution:

SEQ

```
x := x + 1  
y := x * x
```

Parallel execution:

PAR

```
p()  
q()
```

Communication between processes:

ProcessA ! Channel\_var

ProcessB ? Channel\_var

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# Occam

**The Occam language was not popular**

Poor portability

Transputer chip is very expensive

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**For more information:**

**<https://powcoder.com>**

Occam 2 reference manual

[www.wotug.org/occam/documentation/oc21refman.pdf](http://www.wotug.org/occam/documentation/oc21refman.pdf)

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Occam archive

<http://vl.fmnet.info/occam/>

Transputer

[http://en.wikipedia.org/wiki/INMOS\\_Transputer](http://en.wikipedia.org/wiki/INMOS_Transputer)

# Dedicated languages

**In general dedicated languages are going to do a better job**

- 1. Designed with the hardware architecture**
- 2. Structure of the language reflects the nature of parallelism**

**However**

- 1. Niche languages are not generally popular**
- 2. It's hard to port existing code**

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**Much better to modify and extend an existing language to include parallelism, because**

- 1. Better audience**
- 2. Only need to learn new constructs or API, not a new language**
- 3. Porting is a lot easier**

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**Compiler Approach**

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# Compiler Approach

- Automatically parallelize the sequential codes
- Very conservative
- Re-implementing the code in an more efficient way
- Can remove the dependency if possible

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# Re-implement the code in compilation

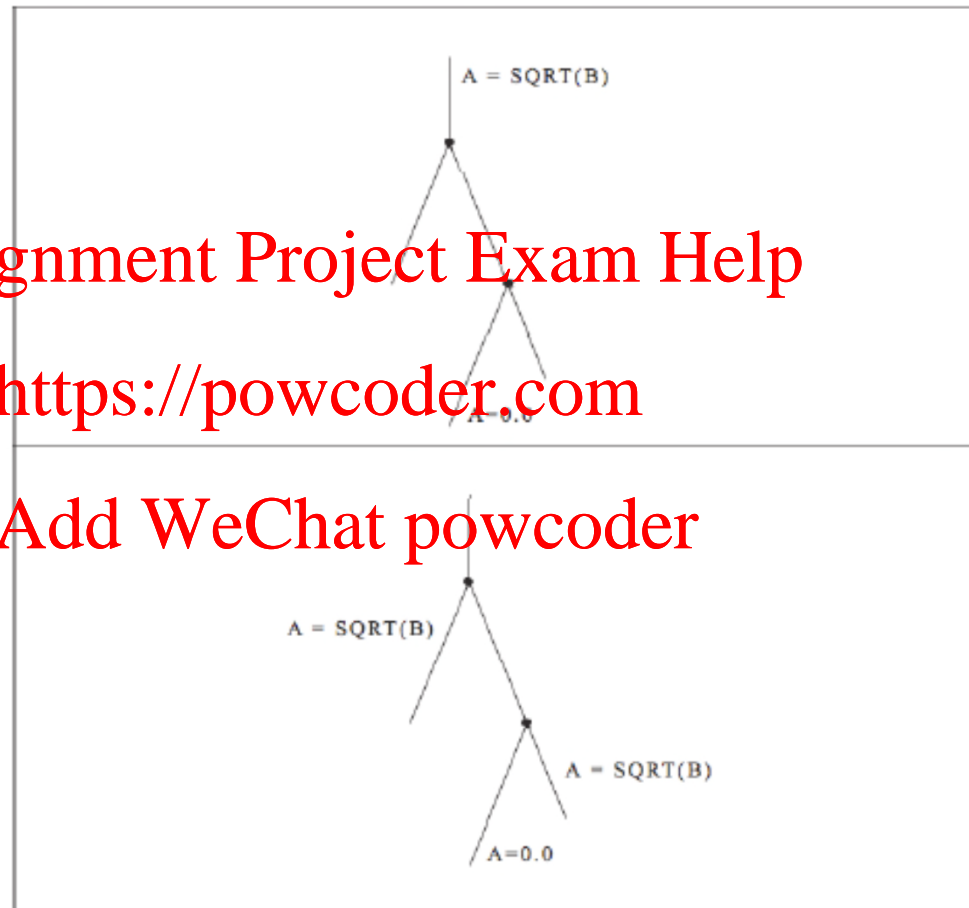
**Before:**

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**After:**



# Removing the dependency

**Anti-dependency and output-dependency can be removed by renaming the variables**

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# Dependency and Parallelism (revisit)

→ **Dependency:** If instruction A must finish before instruction B can run, then B is dependent on A

→ **Two types of Dependency**

❑ **Control dependency:** waiting for the instruction which controls the execution flow to be completed

- **IF ( $X \neq 0$ ) Then  $Y = 1.0/X$ :  $Y = 1.0/X$  has the control dependency on  $X \neq 0$**

❑ **Data dependency:** dependency because of calculations or memory access

- **Flow dependency:**  $A = X + Y$ ;  $B = A + C$ ;
- **Anti-dependency:**  $B = A + C$ ;  $A = X + Y$ ;
- **Output dependency:**  $A = 2$ ;  $X = A + 1$ ;  $A = 5$ ;

# Removing the dependency

Anti-dependency and output-dependency can be removed by renaming the variables

Anti-dependency: Assignment Project Exam Help

Before:

$Y = 2 * X$   
 $X = 5$

After:

$Y = 2 * X$   
 $X1 = 5$

Output-dependency

Before:

$X = A/B$   
 $Y = X + 2.0$   
 $X = D - E$

After:

$X = A/B$   
 $Y = X + 2.0$   
 $X1 = D - E$

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# Examples of automatic parallelization by compiler

A compiler takes code written in a standard language (e.g. C or Fortran) and automatically compiles it to be run in parallel (e.g. by parallelizing loops)

Example 1:

```
DO I=1, N
  A(I)=A(I)+B(I)
ENDDO
```

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Example 2: **Add WeChat powcoder**

```
DO I=2, N
  A(I)=A(I-1)+B(I)
ENDDO
```

Compiling the code:

```
f90 -O3 -autopar foo.f
```

**Can this loop be parallelised?**

**Example 3:** **Assignment Project Exam Help**

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**DO I=2, N** **Add WeChat powcoder**

**A(I)=2\*B(I)**

**C(I)=A(I)+C(I);**

**ENDDO**

# Features of the Compiler approach

- Can work fairly well for some regular problems

- Fully automatic (efficient) parallelisation is difficult, and unlikely to be efficient in general

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# Assisting Compiler

Programmers can assist the compiler by writing the code in a way that explicitly expresses the parallelism in the program

- ☐ Usually done using directives (pseudo-comments that instruct the compiler where parallelism lies)
- ☐ During 1990s OpenMP emerged as a common set of directives for implementing various types of parallel execution and synchronization
- ☐ Add these to serial code (and ignored if targeting a single processor machine)
- ☐ Explicit parallelism: we are instructing the compiler what to do
- ☐ We cannot blame the compiler but ourselves if there is something wrong

# Examples of Assisting Compilers

Correct:

```
C$OMP PARALLEL
```

```
  DO I=1, N
```

```
    A(I)=A(I)+B(I)
```

```
  ENDDO
```

```
C$OMP END PARALLEL
```

Wrong:

```
C$OMP PARALLEL
```

```
  DO I=2, N
```

```
    A(I)=A(I-1)+B(I)
```

```
  ENDDO
```

```
C$OMP END PARALLEL
```



# Compilers

For more information on this subject area see:

- ❑ Further reading in High Performance Compilers for Parallel Computing, Michael Wolfe  
<https://powcoder.com>
- ❑ Vectorizing C Compilers: how good are they? Lauren Smith, ACM/IEEE Conference on Supercomputing  
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- ❑ Parallelizing and Vectorizing Compilers, Eigenmann and Hoeflinger, (also on course web page)

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# Task parallelism vs. Data parallelism

Task parallelism:

```
if CPU="a" then
    do task "A"
else if CPU="b" then
    do task "B"
end if
```

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Data parallelism:

```
d is an one-dimensional array
if CPU="a" then
    low_limit=1; upper_limit=50
else if CPU="b" then
    low_limit=51; upper_limit=100
end if
do i = low_limit , upper_limit
    Task on d(i)
end do
```

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# Data parallelism

- If we are applying the same operation to every element in an array (or list, set, tree, database or whatever) then we may be able to exploit data parallelism
- F90 and HPF provide the support for Data parallelism
- F90 and HPF allow scalar operations to be applied to arrays to support the data parallelism

- adding two matrixes can be written as

$$A = B + C \quad \text{! } A, B, C \text{ are arrays}$$

which is equivalent to

```
do i = 1,m
```

```
  do j = 1,n
```

$$A(i,j) = B(i,j) + C(i,j)$$

```
  enddo
```

```
enddo
```

The former expression is called explicit parallel statement while the latter expression called implicit parallel statements (the latter can be parallelised by the compiler if possible)

# Data parallelism

A *data parallel* program is a sequence of explicitly and/or implicitly parallel statements

The compiler can partition the data into disjoint sub-domains, one per processor

Data placement is an essential part of data-parallelism, and if you get *the data locality* wrong, you will take a performance hit

Fortunately, compilers can achieve data partition, data allocation/placement, data communications



# Data parallelism

A data-parallel programming is higher-level than the message passing-type approach

- ☐ programmer does not need to specify communication structures
- ☐ this is done by the compiler (inferred from the program and underlying computer architecture)

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- ☐ not all algorithms can be specified in data parallel terms
- ☐ if the program has irregular communication patterns then this will be compiled less efficiently

Examples of data parallel languages include F90 and HPF