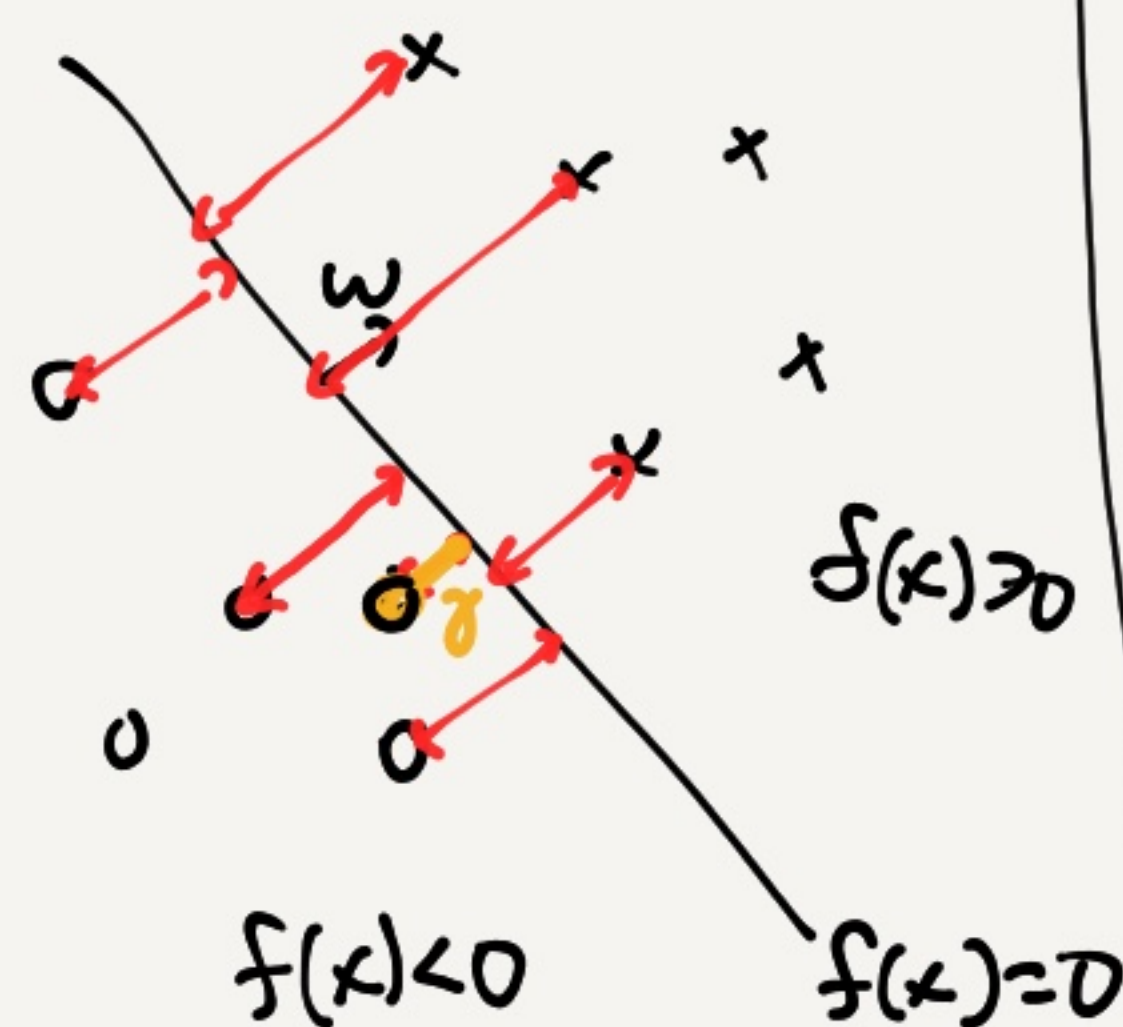


Support Vector Machines (SVM) [Lecture 9]

Linear Classifier

$$f(x) = w^T x + b$$

$$y^* = \begin{cases} +1, & f(x) > 0 \\ -1, & f(x) < 0 \end{cases} = \text{sign}(f(x))$$



Distance from x to boundary is $\frac{f(x)}{\|w\|}$ (PS 9-1)

- Assume data $\{X, y\}$ is linearly separable:
- "Margin" - distance from the boundary to the closest point in X .

$$\gamma = \min_i \frac{|f(x_i)|}{\|w\|} = \min_i \frac{|w^T x_i + b|}{\|w\|} = \min_i \frac{y_i (w^T x_i + b)}{\|w\|}$$

Idea: Maximize the margin, i.e. the separation between the boundary & closest point.

Why?

1) w/ perceptron - margin determines the learning complexity.

2) training points - as random samples



→ leave a margin to be safe from uncertainty.

3) w is an uncertain estimate



max margin → allow more variance in w estimate w/o causing errors.

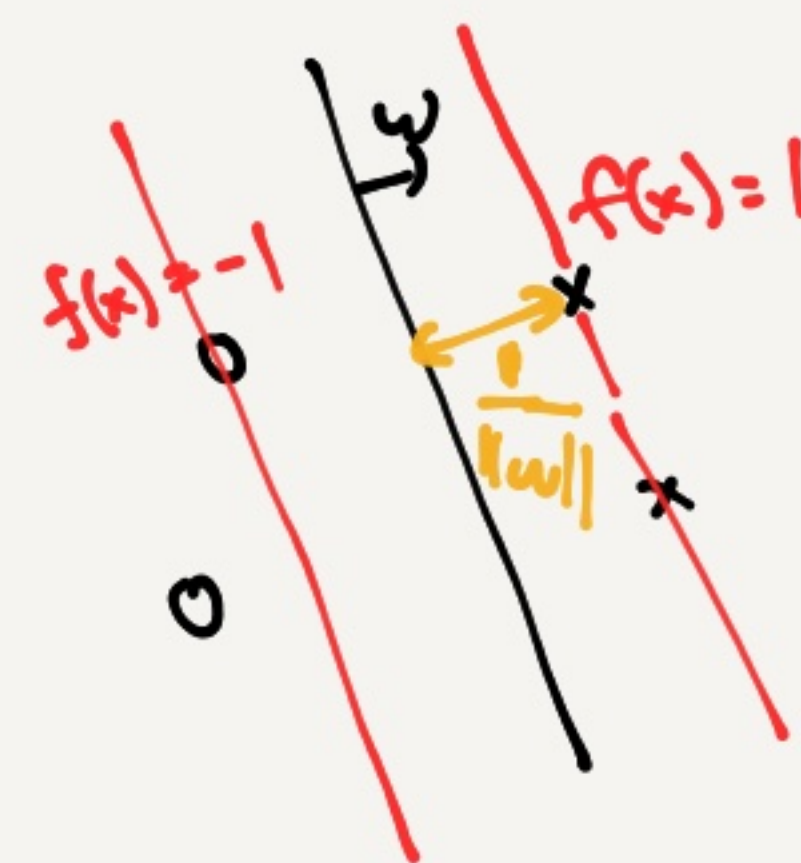
CS5487 Lecture Notes (2020)
Dr. Antoni B. Chan
Dept of Computer Science
City University of Hong Kong

Formulation

Need a normalization ⇒ fix the numerator.

$$\Rightarrow \min_i y_i (w^T x_i + b) = 1$$

$$\Rightarrow \gamma = \frac{1}{\|w\|}$$



Find w :

$$\arg \max_{w, b} \gamma \quad \text{s.t.} \quad \min_i y_i (w^T x_i + b) = 1$$

$$\arg \max \frac{1}{\|w\|} \quad \text{s.t.} \quad \min_i y_i (w^T x_i + b) = 1$$

↓ apply xform: $\arg \max \frac{1}{x} = \arg \min x^2$

$$\arg \min \frac{1}{2} \|w\|^2 \quad \text{s.t.} \quad \min_i y_i (w^T x_i + b) = 1$$

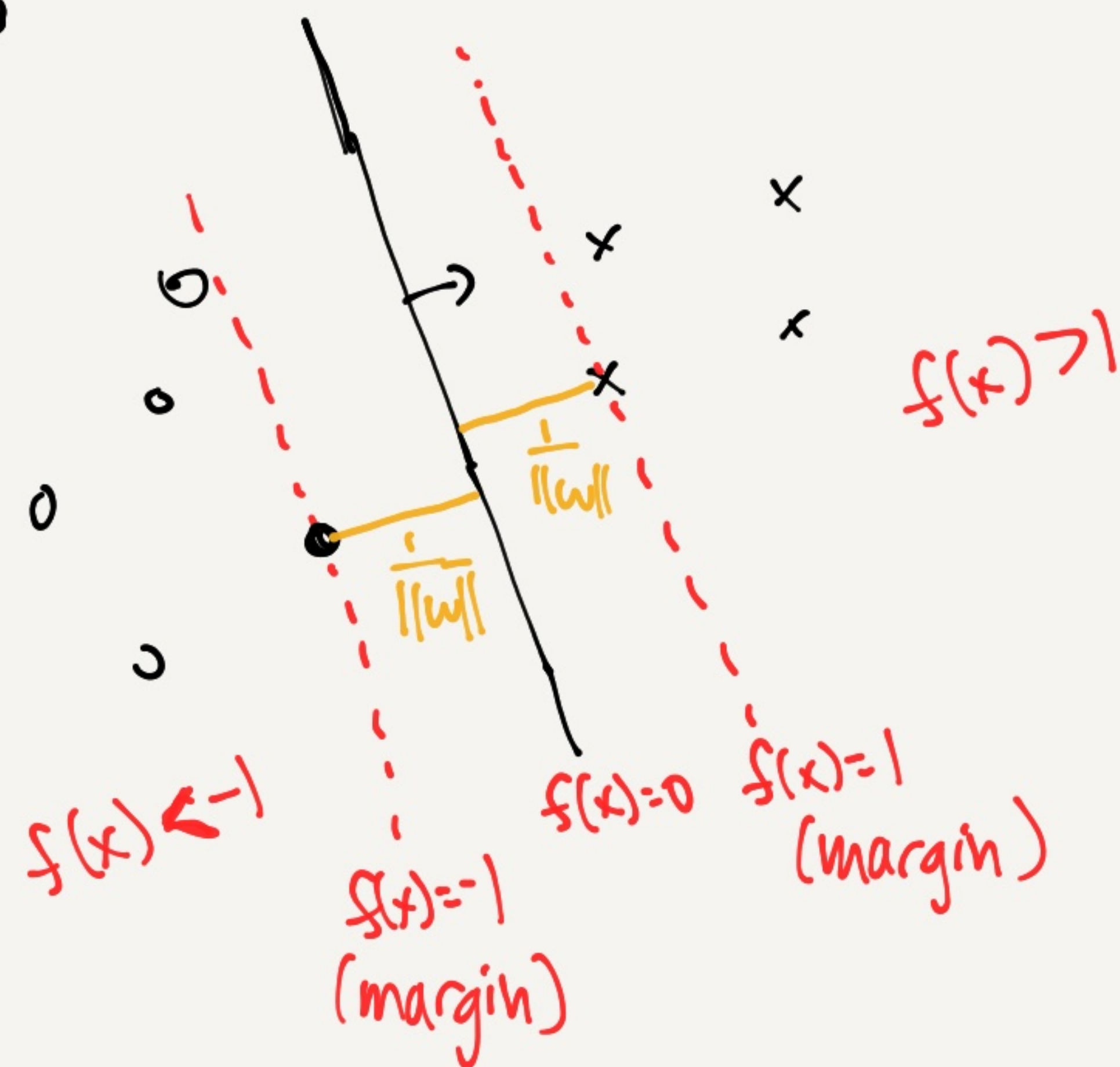
$$\arg \min \frac{1}{2} \|w\|^2 \quad \text{s.t.} \quad y_i (w^T x_i + b) \geq 1 \quad \forall i$$

at the optimum, the smallest w will shrink $y_i (w^T x_i + b) = 1$ for some x_i .

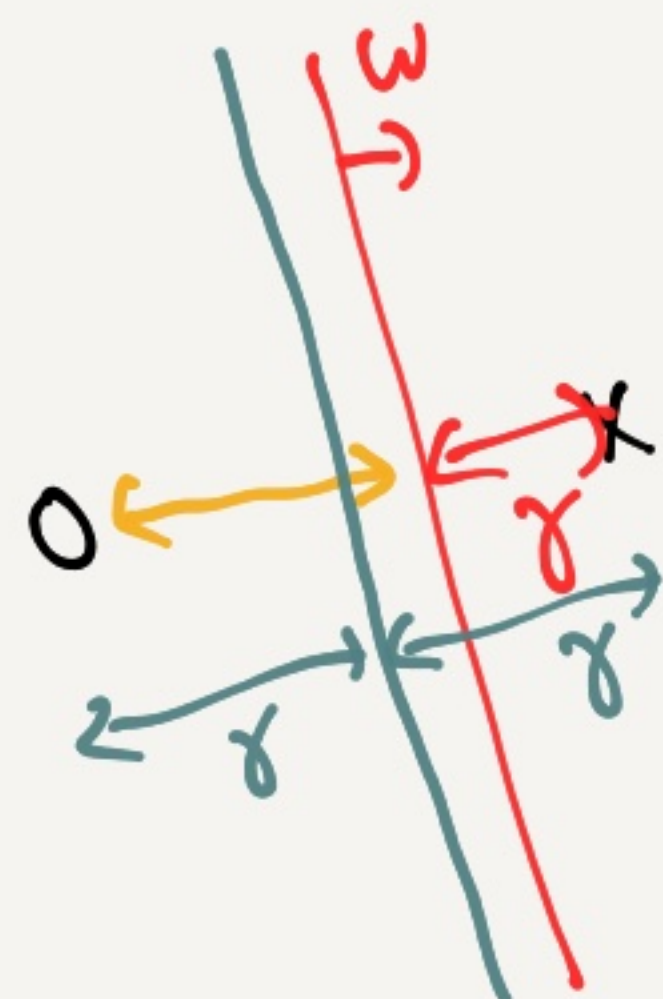
$$\begin{aligned} \arg \max \frac{1}{\|w\|} &= \arg \max \log \frac{1}{\|w\|} = \arg \min -\log \frac{1}{\|w\|} = \arg \min \log \|w\| \\ &= \arg \min 2 \log \|w\| = \arg \min \|w\|^2 \end{aligned}$$

SVM primal problem

argmin $\frac{1}{2} \|w\|^2$ s.t. $y_i (w^T x_i + b) \geq 1, \forall i$
 w, b



• by symmetry there should be at least 1 point on the margin on each side.



What are the support vectors ???

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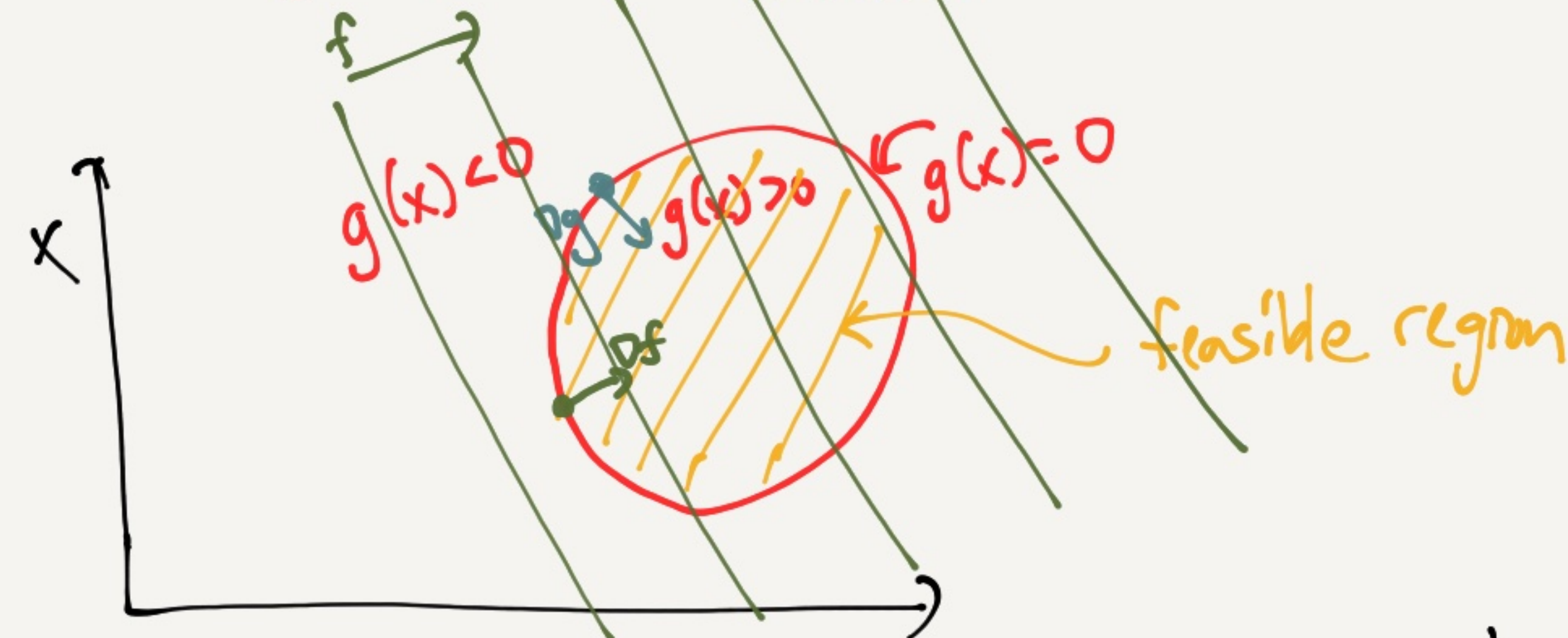
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Optimization w/ inequality Constraints

Goal:

min $f(x)$ s.t. $g(x) \geq 0$
 objective constraint function



Note: $\nabla g(x)$ points into the feasible region, when x is on the boundary.

Find 2 solutions

1) x^* is on boundary $\Rightarrow g(x^*) = 0$ (active equality)

\Rightarrow min when $\nabla f(x) = \lambda \nabla g(x)$, $\lambda > 0$
 f cannot decrease except by leaving the feasible region.

2) x^* is inside feasible region $\Rightarrow g(x^*) > 0$ (inactive)

min when $\nabla f(x) = 0$, i.e. $\lambda = 0$

Combine 2 cases:

Find stationary point of L

s.t.

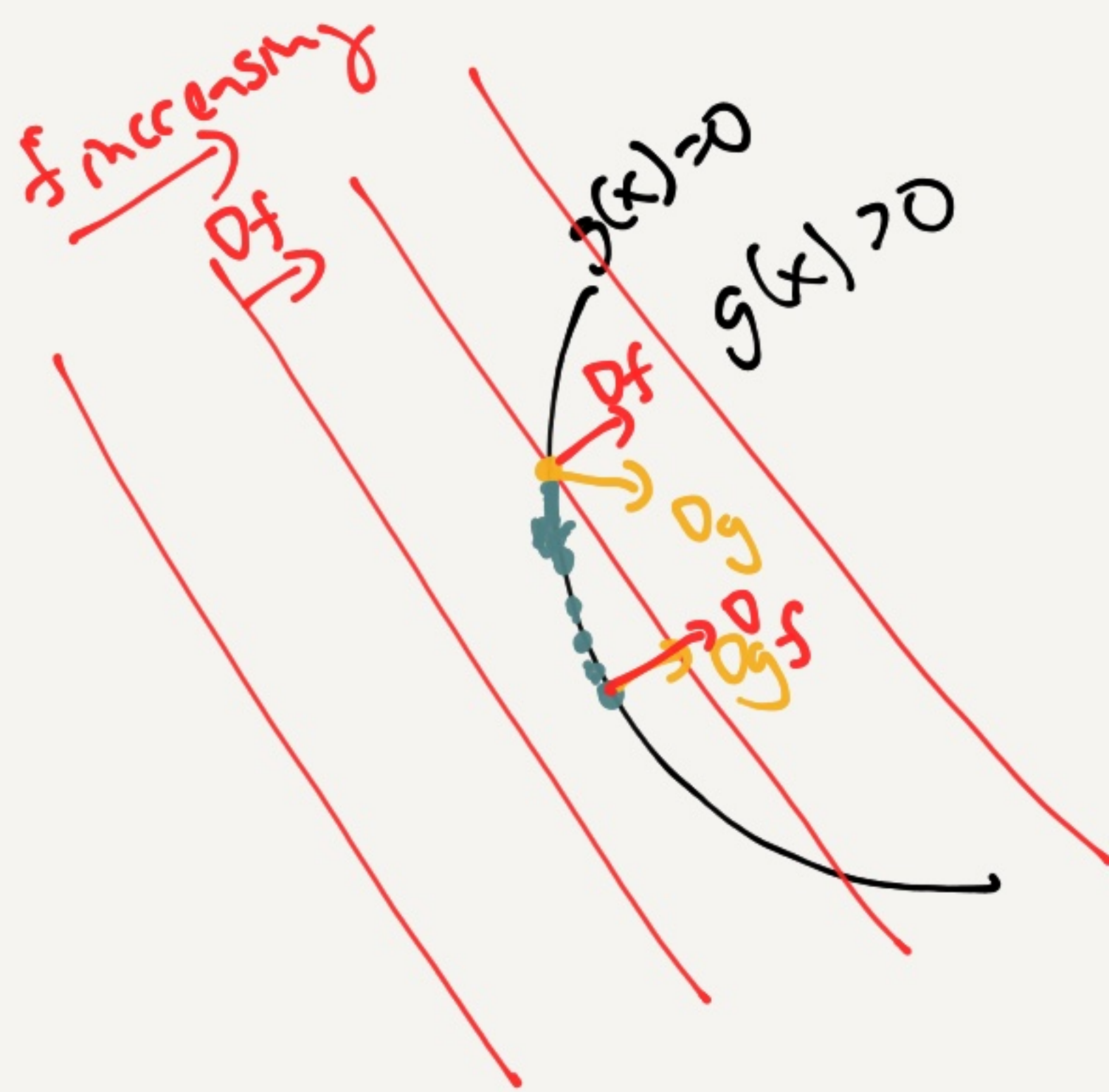
$L(x, \lambda) = f(x) - \lambda g(x)$

$\nabla f(x) - \lambda \nabla g(x) = 0$

$\begin{cases} g(x) \geq 0 \\ \lambda \geq 0 \end{cases}$

$\lambda g(x) = 0$ (combine 2 cases)

KKT conditions



Duality

Suppose optimal λ^* is known, then consider minimizing $L(x, \lambda^*)$:

$$L^* = \min_x L(x, \lambda^*) = \min_x [f(x) - \lambda^* g(x)]$$

= 0 at the optimum

$$= \min_x f(x) = f(x^*) = f^*$$

(the minimum)

Define $q(\lambda) = \min_x L(x, \lambda) = \min_x [f(x) - \lambda g(x)]$

for every λ , find the min w.r.t. x .

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Note: $\lambda \geq 0, g(x) \geq 0$

$$\Rightarrow q(\lambda) \leq \min_{\substack{x \\ g(x) \geq 0}} f(x) = f^*$$

i.e. $q(\lambda)$ is a lower bound to $f^* = f(x^*)$

Thus maximizing $q(\lambda)$ could yield $f(x^*)$ under some conditions.

The dual problem: $q^* = \max_{\lambda \geq 0} q(\lambda)$

Weak duality Thm: $q^* \leq f^*$ ($q^* \neq f^*$ we call it a "duality gap")

Strong Duality Thm: if 1) $f(x)$ is convex; 2) the feasible region is convex (and not degenerate)
 \Rightarrow then $q^* = f^*$. i.e. solving the dual is equivalent to solving the primal.

SVM dual

primal: argmin_{w, b} $\frac{1}{2} \|w\|^2$ s.t. $y_i(w^T x_i + b) \geq 1$

1) let $\alpha_i \geq 0$ be the Lagrange multiplier for $y_i(w^T x_i + b) \geq 1$

2) Lagrangian

$$L(w, b, \alpha) = \frac{1}{2} \|w\|^2 - \sum_{i=1}^N \alpha_i (y_i (w^T x_i + b) - 1)$$

3) Dual function:

$$L(\alpha) = \min_{w, b} L(w, b, \alpha)$$

$$\frac{\partial L}{\partial w} = w - \sum_i \alpha_i y_i x_i = 0 \Rightarrow w^* = \sum_{i=1}^N \alpha_i y_i x_i$$

$$\frac{\partial L}{\partial b} = -\sum_{i=1}^N \alpha_i y_i = 0 \Rightarrow \sum_{i=1}^N \alpha_i y_i = 0$$

plug into $L(w, b, \alpha)$

$$L(\alpha) = \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j y_i y_j x_i^T x_j$$

4) SVM dual problem

$$\max_{\alpha} L(\alpha)$$

$$\text{s.t. } \alpha_i \geq 0 \quad \forall i$$

$$\sum_{i=1}^N \alpha_i y_i = 0$$

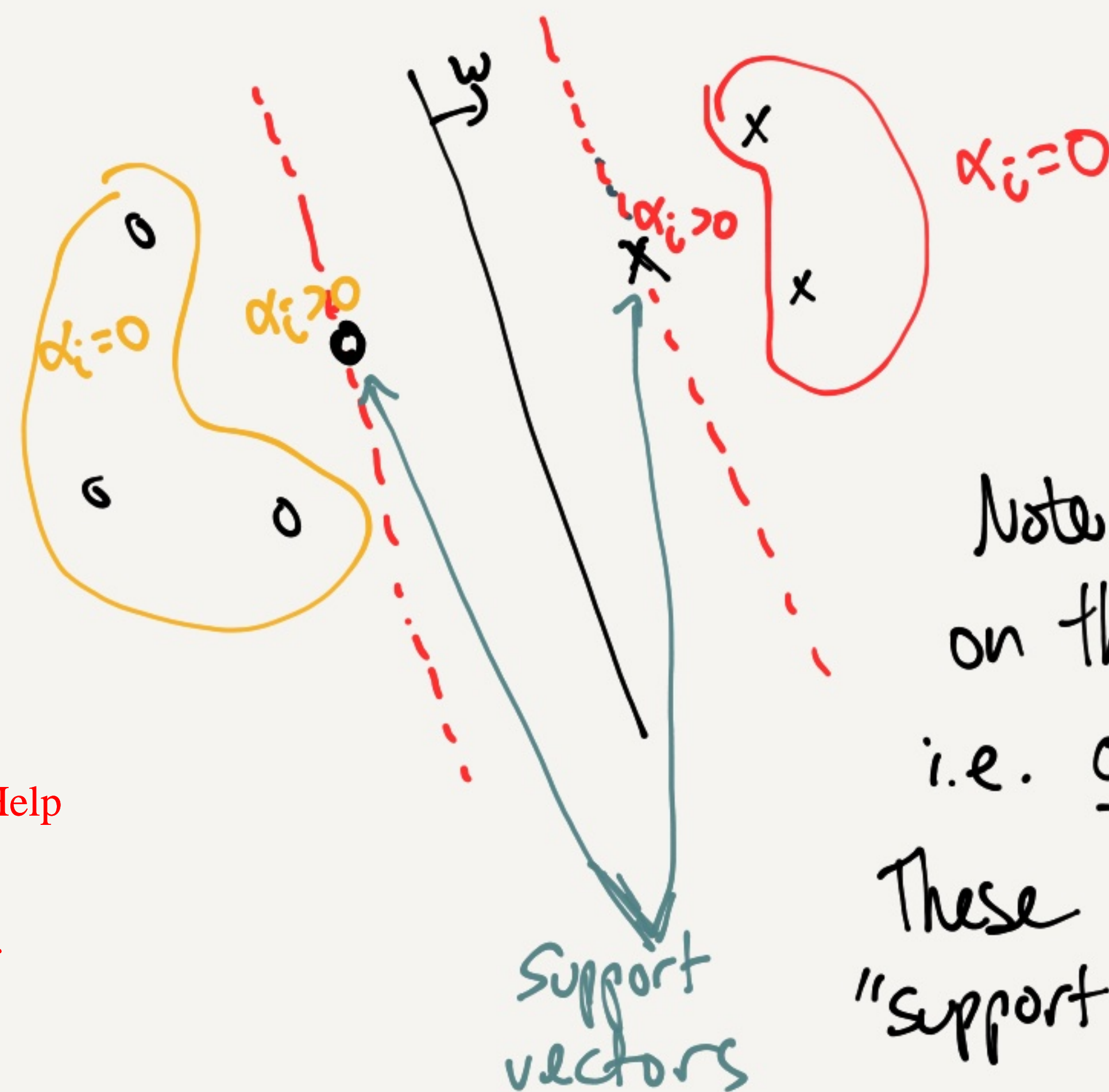
5) Given α^* ,

$$w^* = \sum_{i=1}^N \alpha_i^* y_i x_i$$

Recall KKT conditions:

1) $g(x) = 0$ (active): $\alpha_i > 0$, $y_i(w^T x_i + b) - 1 = 0 \Rightarrow y_i(w^T x_i + b) = 1 \Rightarrow x_i$ is on margin

2) $g(x) > 0$ (inactive): $\alpha_i = 0$, $y_i(w^T x_i + b) - 1 > 0 \Rightarrow y_i(w^T x_i + b) > 1 \Rightarrow x_i$ is not on margin.



Note: w^* only depends on the x_i 's with $\alpha_i > 0$, i.e. on the margin.

These points are the "support vectors".

Note: the primal solves $w \in \mathbb{R}^D$
the dual solves $\alpha \in \mathbb{R}^N$

primal more efficient when $D < N$,
and vice versa.

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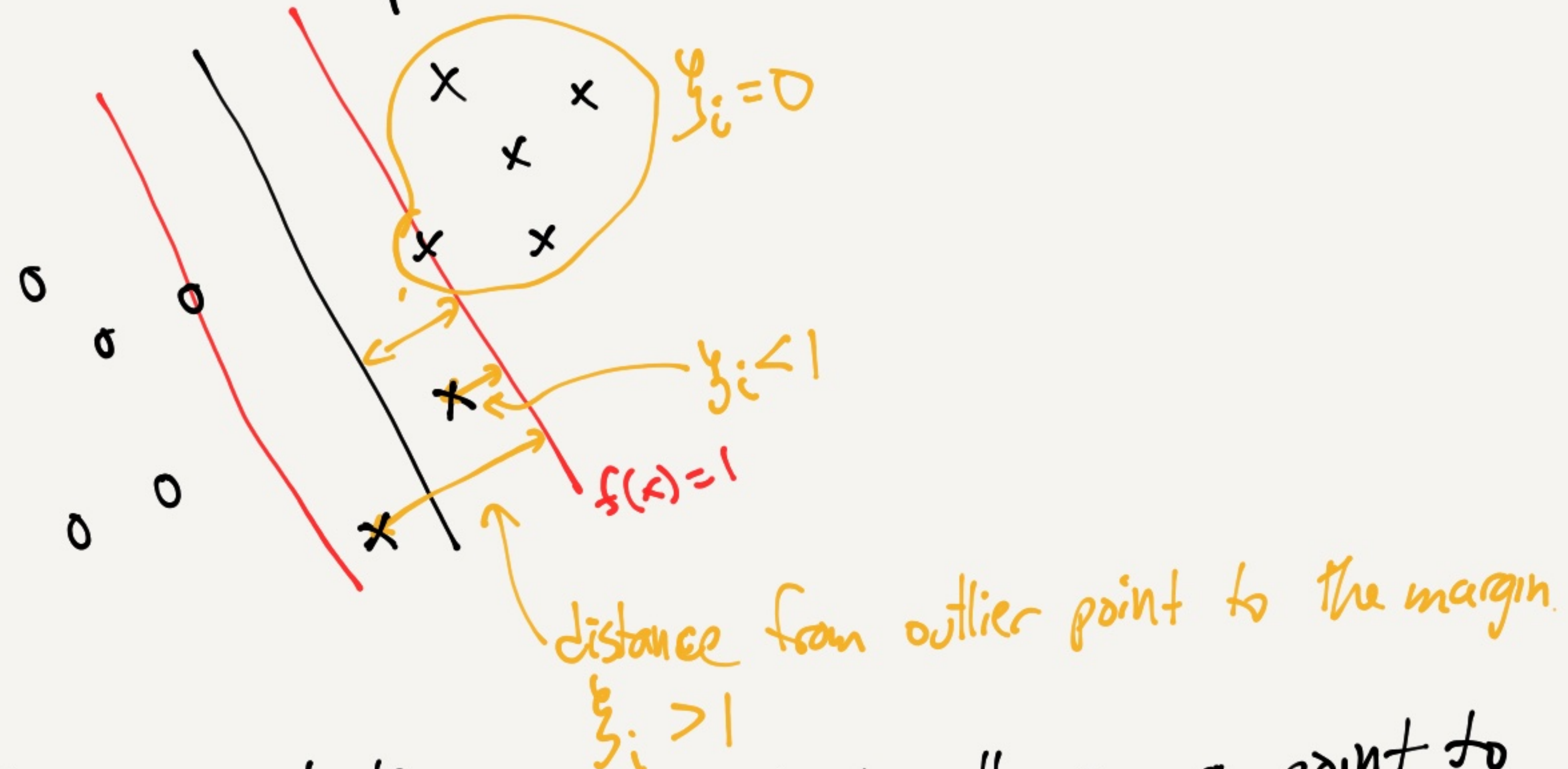
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What about when the data is not linearly separable?

Soft-SVM

"soft-margin" - most points are on the margin or beyond, except a few outliers.



- ξ_i is a slack variable, which allows a point to violate the margin. $\xi_i \geq 0$

- New margin constraint: $y_i(w^T x_i + b) \geq 1 - \xi_i$
 $\xi_i \geq 0$
 \uparrow
margin becomes < 1 when $\xi_i > 0$

- New objective problem

$$\min_{w, b} \frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i$$

$$\text{s.t. } y_i(w^T x_i + b) \geq 1 - \xi_i, \forall i$$

$$\xi_i \geq 0, \forall i$$

penalty on large ξ_i , i.e. too many points violating margin.

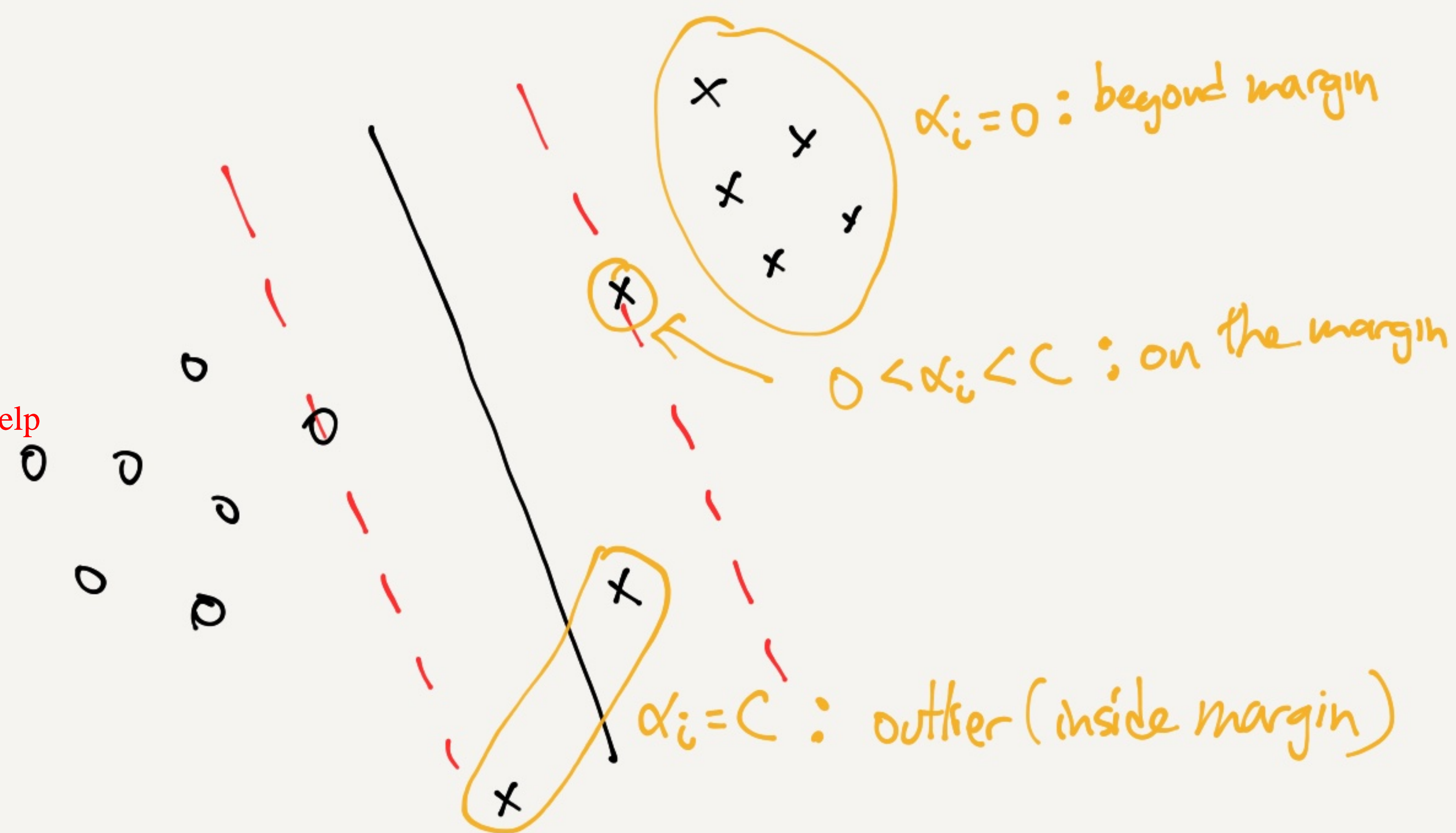
Dual SVM

$$\max_{\alpha \geq 0} \sum_i \alpha_i - \frac{1}{2} \sum_i \sum_j \alpha_i \alpha_j y_i y_j x_i^T x_j$$

$$\text{s.t. } \sum_i \alpha_i y_i = 0$$

$$0 \leq \alpha_i \leq C, \forall i$$

new constraint on max value of α_i .



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