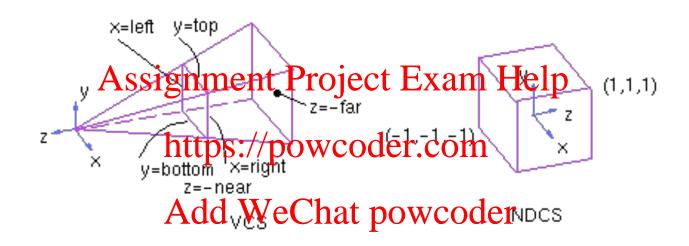
Derivation of the perspective transformation



- It is basically a mapping of planes
- Normalized view volume is a left handed system
- However, there is an easier derivation

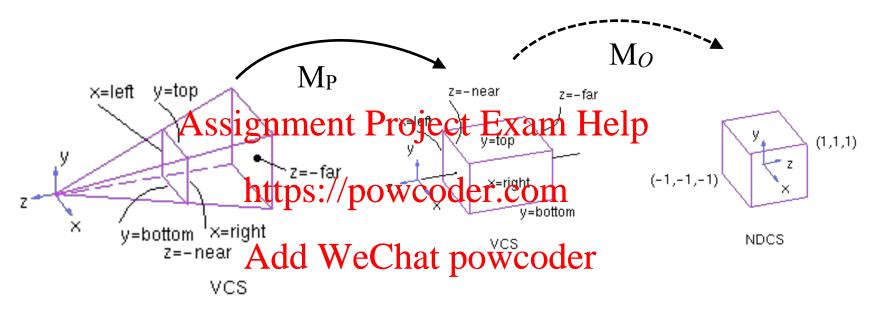
Interpretation of the Perspective transformation

Warps the view volume and the objects in it

• Eye becomes a point at infinity, and the projection rays become parallel lines (orthographic projection) We Chat powcoder.

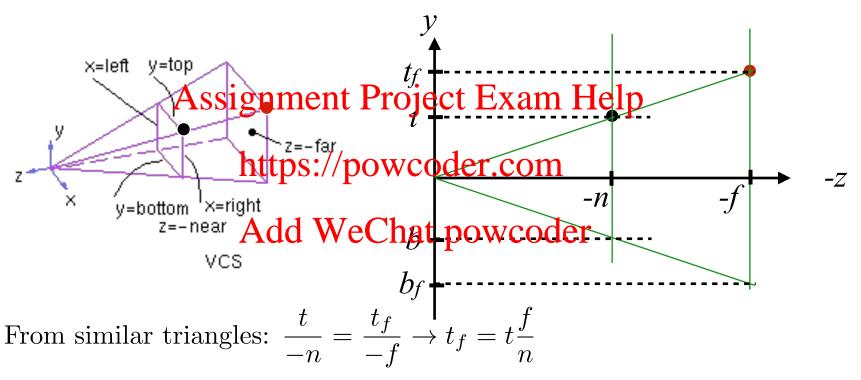
• We also want to keep z

Two step derivation



- Start with the Canonical Perspective Projection matrix
- Adjust CPP to scale z so that after the application of CPP z = -near maps to z'=-near and z=-far maps to z'=-far)
- We now have the standard orthographic view volume
- Use the previously derived orthographic projection matrix Mo

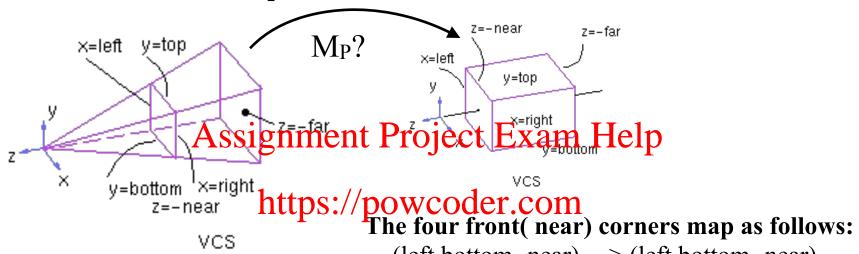
First: What are the view volume points in viewing coordinates?



Similarly y = b, and for x = r and x = l

So for example: black point: $(r, t, -n) \to \text{Red point}$: (rf/n, tf/n, -f)

First step: What does the CPP produce?



• $P'_x = n P_x/P_z$

•
$$P'_y = n P_y/P_z$$

• $P'_{7} = -n$

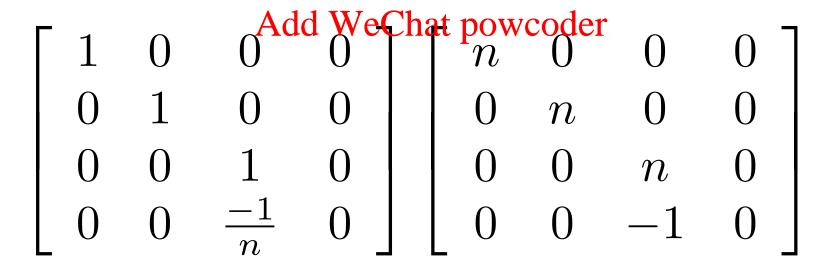
Add Wecleft, bottom, -near) --> (left, bottom, -near) (left, top, -near) --> (left, bottom, -near) (right,bottom,-near) --> (right,bottom,-near) (right,top,-near) --> (right,top,-near)

The four back (far) corners map as follows:

 $(1*f/n,b*f/n, -f) \longrightarrow (1, b,-n)$ instead of (1,b,-f) $(1*f/n,t*f/n,-f) \longrightarrow (1, t, -n)$ instead of (1,t,-f) $(r*f/n,b*f/n, -f) \longrightarrow (r,b,-n)$ instead of (r,b,-f) $(r*f/n,t*f/n,-f) \longrightarrow (r,t,-n)$ instead of (r,t,-f)So we just have to adjust the matrix for z

First step:Adjust the matrix to keep and scale Z

- We want to keep z and
- We want $P'_z = -n$ for $P_z = -n$ and $P'_z = -f$ for $P_z = -f$ after the perspective division
- Where do we dotthe changes com



First step: With some intuition...

Reminder: n,f are positive

$$\mathbf{M}_{P} \begin{bmatrix} P_{x} \\ P_{y} \\ P_{z} \\ 1 \end{bmatrix} = \begin{bmatrix} \mathbf{A}_{ssignment} & \mathbf{P}_{roject} & \mathbf{E}_{sam} & \mathbf{He} \\ \mathbf{A}_{ssignment} & \mathbf{P}_{roject} & \mathbf{E}_{sam} & \mathbf{He} \\ P_{z} & \mathbf{P}_{z} & \mathbf{P}_{z} \\ \mathbf{A}_{ssignment} & \mathbf{P}_{roject} & \mathbf{E}_{sam} & \mathbf{He} \\ P_{z} & \mathbf{P}_{z} & \mathbf{P}_{z} \\ \mathbf{P}_{z} & \mathbf{P}_{z} & \mathbf{P}_{z} \end{bmatrix} / \mathbf{powcoder.com} \begin{bmatrix} \mathbf{P}_{x} & \mathbf{P}_{x} & \mathbf{P}_{z} \\ \mathbf{P}_{z} & \mathbf{P}_{z} & \mathbf{P}_{z} \\ \mathbf{P}_{z} & \mathbf{P}_{z} & \mathbf{P}_{z} \end{bmatrix}$$

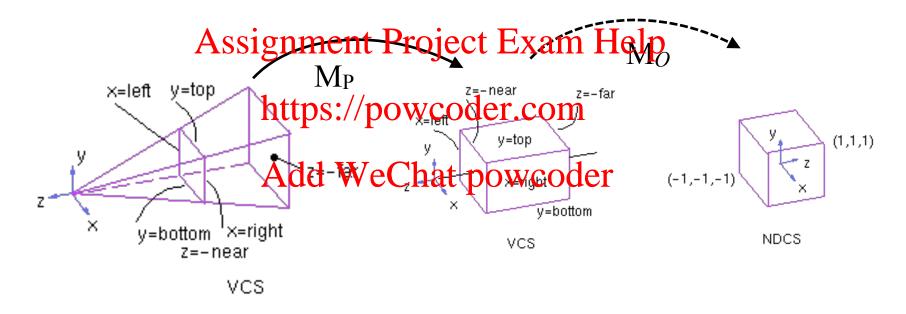
Therefore

Sanity check

- (I*f/n,b*f/n,-f) --> (I,b,-f)
- (I,b,-n) --> (I,b,-n)

First step: M_P

Creates the previous orthographic view volume



Which can then be transformed to NDCS with Mo

Second Step: Combine with Orthographic Projection Matrix

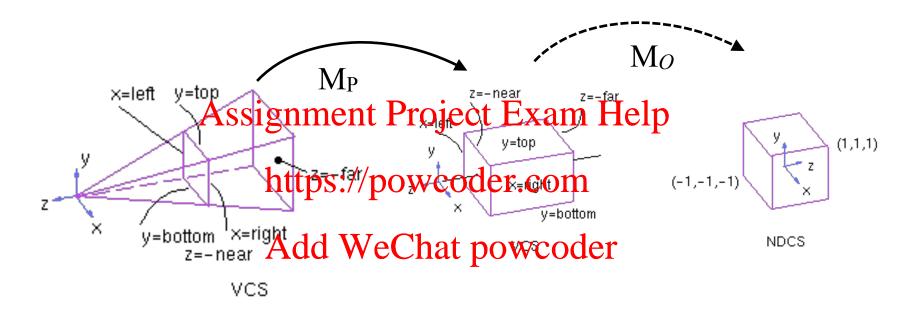
Now all we need to do is an orthographic transformation Assignment Project Exam Help

• We can use matrix Mo that transforms an orthographic view volume to https://pawcedenee(NDCS)

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$$\mathbf{M}_{O} = \begin{bmatrix} \frac{2}{r-l} & 0 & 0 & -\frac{r+l}{r-l} \\ 0 & \frac{2}{t-b} & 0 & -\frac{t+b}{t-b} \\ 0 & 0 & \frac{-2}{f-n} & -\frac{f+n}{f-n} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Second Step: Combine with Orthographic Projection Matrix



$$\mathbf{M}_{\mathtt{prom}} = \mathbf{M}_O \mathbf{M}_P$$

OpenGL Perspective Matrix

Old form

 Still widely used Assignment Project Exam Help

$$\mathbf{M}_{\mathtt{OpenGL}} = egin{bmatrix} rac{2|n|}{\mathtt{pttps://powcoder}} rac{r+l}{\mathtt{copn}} & 0 \ rac{\mathrm{Add}}{\mathrm{M}_{f e}^{f Chat}} rac{b+t}{\mathtt{powcoder}} & 0 \ 0 & 0 & rac{|n|+|f|}{|n|-|f|} & rac{2|f||n|}{|n|-|f|} \ 0 & 0 & -1 & 0 \end{bmatrix}$$

Projections in OpenGL (mimicking the old way)

New way

```
projMat = frassignment Project Exam, Help near, far);
projMat = ortho(-left, right, bottom, top, near, far);
projMat = Perspehtips(//powsoeletr.com
far);
near plane at z = Antal WeChat powcoder
far plane at z = -far
```

Matrix Order

Normally projection has to apply to all objects (i.e. the entire scene) thus it must Assignment Project Exam Help pre-multiply the modelview matrix

- $M = M_{proj} M_{modelview} or^{https://powcoder.com}$
- $M = M_{proj}M_{view}M_{rio}d_{el}WeChat powcoder$

Important

Projection parameters are given in CAMERA Coordinate system (Viewing).
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So if camera is at z = 50, is aligned with the world CS, and you give hear = 10 where is the near plane with respect to the world?

Important

Projection parameters are given in CAMERA Coordinate system (Viewing).
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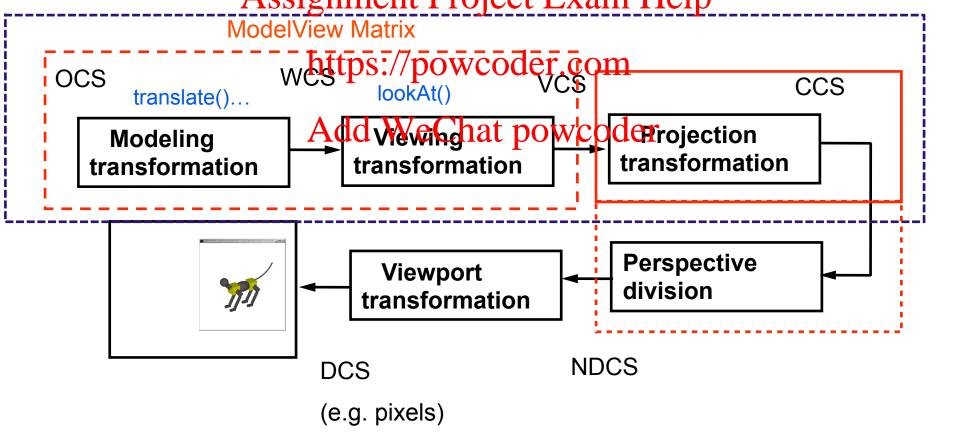
So if the camera is at z = 50, is aligned with the world CS, and you give [near] = 10 where is the near plane with respect to the world?

- Transformed by inverse(Mvcs)
- i.e. (0,0,40)

Perspective Division in Pipeline

The perspective division is done automatically

Typically the vertex shaders writes CCS in gl_Position.
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Perspective Division in Pipeline

However, we can do it ourselves if we want.

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The vertex shader has total freedom on how https://powcoder.com
to deal with projections

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