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ECON 61001: *Lecture 7*

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- Time series regression models with non-spherical errors

- OLS-based inference

- GLS-based inference

- Testing for serial correlation

- Instrumental Variables estimation

- Models with endogenous regressors

- OLS as MoM \rightarrow IV

- Examples of instruments

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In Lecture 5 we show that conventional OLS inference framework goes through under the following assumptions.

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- Assumption TS1: $y_t = x_t' \beta_0 + u_t$, $t = 1, 2, \dots, T$
- Assumption TS2: (y_t, h_t') is a weakly stationary, weakly dependent time series.
- Assumption TS3: $E[x_t x_t'] = Q$, a finite, positive definite matrix.

- Assumption TS4: $E[u_t | x_t] = 0$ for all $t = 1, 2, \dots, T$.
- Assumption TS5: $\text{Var}[u_t | x_t] = \sigma_0^2$.
- Assumption TS6: For all $t \neq s$, $E[u_t u_s | x_t, x_s] = 0$.

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In video on “OLS-based inference in time series regression models with conditionally heteroscedastic errors” we consider OLS based inference in models satisfying:

- Assumption TS1: $y_t = x_t' \beta_0 + u_t$, $t = 1, 2, \dots, T$
- Assumption TS2-SS: (y_t, h_t') is a strongly stationary, weakly dependent time series.
- Assumption TS3: $E[x_t x_t'] = Q$, a finite, positive definite matrix.
- Assumption TS4: $E[u_t | x_t] = 0$ for all $t = 1, 2, \dots, T$.
- Assumption TS5-H: $\text{Var}[y_t | \mathcal{I}_t] = \sigma_t^2$.
- Assumption TS6: For all $t \neq s$, $E[u_t u_s | x_t, x_s] = 0$

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Alternatively, we can impose Assumptions TS1, TS2, TS3 and TS5 (or TS1, TS2-SS, TS3 and (TS5-H)) and

- **Assumption TS7** $E[y_t | \mathcal{I}_t] = x_t' \beta_0$, where \mathcal{I}_t is information set at time t .

- if Assumption TS7 holds then the model is said to be *dynamically complete*.

Serial correlation in errors

The framework adopted affects how we view the consequences of serial correlation in the errors and so how we proceed.

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If Assumptions TS1, TS2, TS3, TS4, and TS5-H hold but TS6 does not (so $E[u_t u_s | x_t, x_s] \neq 0$) then:

- OLS is still consistent as Assumption TS4 holds.
- <https://powcoder.com> Scope for serial correlation robust inference based on OLS

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If Assumptions TS1, TS2, TS3 & TS5 (or TS1, TS2-S5, TS3 & TS5-H) hold but Assumption TS7 does not (so $E[y_t | \mathcal{I}_t] \neq x_t' \beta_0$) then:

- OLS is likely inconsistent as TS4 may not hold.
- Need to reconsider specification.

If Assumptions TS1, TS2-SS, TS3, TS4, & TS5-H hold then: $\hat{\beta}_T$ is consistent and

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$$T^{1/2}(\hat{\beta}_T - \beta_0) \xrightarrow{d} N(0, V_{sc})$$

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where

- $V_{sc} = Q^{-1}\Omega Q^{-1},$

- $\Omega = \Gamma_0 + \sum_{i=1}^{\infty} (\Gamma_i + \Gamma_i'), \text{ for } \Gamma_i = E[u_t u_{t-i}' x_t x_{t-i}']$

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Estimation of long run variance Ω ?

Use heteroscedasticity and autocorrelation covariance (HAC) matrix estimator:

$$\hat{\Omega}_{HAC} = \hat{\Gamma}_0 + \sum_{i=1}^{T-1} \omega(i, T)(\hat{\Gamma}_i + \hat{\Gamma}_i')$$

where

- $\hat{\Gamma}_i = T^{-1} \sum_{t=i+1}^T e_t e_{t-i} x_t x_{t-i}'$

- $\omega(\cdot, \cdot)$ known as **kernel**

- $\omega(\cdot, \cdot)$ chosen so that $\hat{\Omega}_{HAC}$ is both consistent and psd.

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Popular choice of kernel:

- Bartlett (Newey & West, 1987): putting $a_i = i/(b_T + 1)$

$$\begin{aligned}\omega(i, T) &= 1 - a_i, \text{ for } a_i < 1 \\ &= 0, \text{ else}\end{aligned}$$

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- This is an example of a truncated kernel estimator:

$$\hat{\Omega}_{HAC} = \hat{\Gamma}_0 + \sum_{i=1}^{b_T} \omega(i, T) \left\{ \hat{\Gamma}_i + \hat{\Gamma}_i' \right\}$$

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- Set $\hat{Q} = T^{-1}X'X$.

- Set $\hat{V}_{sc} = \hat{Q}^{-1}\hat{\Omega}_{HAC}\hat{Q}^{-1}$.

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- Then can show $\hat{V}_{sc} \xrightarrow{P} V_{sc}$.

So can perform inference based on OLS provided substitute \hat{V}_{sc} for $\sigma_T^2 \hat{Q}^{-1}$ in statistics discussed in Lecture 5. (See Tutorial 7)

OLS if Assumption TS7 fails

If justify standard OLS-based inference framework via Assumptions TS1-TS3, TS5 & TS7 then serial correlation arises through failure of Assumption TS7 and so:

$$E[y_t | \mathcal{I}_t] \neq x_t' \beta_0$$

This means model is misspecified and so either:

- model is linear but have omitted variables

- model is nonlinear

So need to re-consider specification.

Recall need model for Σ .

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Here consider model with AR(1) errors.

$$\begin{aligned} y_t &= x_t' \beta_0 + u_t \\ u_t &= \rho_0 u_{t-1} + \varepsilon_t \end{aligned}$$

where

- $\varepsilon_t \sim iid(0, \sigma_\varepsilon^2)$.

- Regularity conditions hold (esp $E[x_t u_t] = 0$) $\Rightarrow \hat{\beta}_T \xrightarrow{P} \beta_0$.

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Then GLS is OLS applied to:

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where

- $\ddot{y}_t = y_t - \rho_0 y_{t-1}$ etc. \sim "quasi-difference".

Consistency of GLS requires

$$E[\ddot{x}_t \ddot{u}_t] = E[(x_t - \rho_0 x_{t-1})(u_t - \rho_0 u_{t-1})] = 0,$$

\rightarrow (in general) need $E[x_s u_t] = 0$ for $s = t-1, t, t+1$.

So conditions for consistency of GLS are stronger than for OLS.
Thus, the conditions for the consistency of GLS are stronger than those for the consistency of OLS.

If sub $u_t = y_t - x_t'\beta_0$ in regression model then:

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 $y_t = \rho_0 y_{t-1} + x_t'\beta_0 - x_{t-1}'(\rho_0\beta_0) + \varepsilon_t$
which is same as (re-written) transformed model in GLS.

Also special case of the linear regression model
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$$y_t = \delta_0 y_{t-1} + x_t'\delta_1 + x_{t-1}'\delta_2 + \varepsilon_t,$$

in which the parameters satisfy:
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$$\delta_2 + \delta_0 * \delta_1 = 0,$$

known as the **common factor** or COMFAC restrictions.

(c.f. response to violation of *TS7*.)

Breusch-Godfrey test for serial correlation

Assume errors follow AR(p) process that is,

$$u_t = \rho_{0,1}u_{t-1} + \rho_{0,2}u_{t-2} + \dots + \rho_{0,p}u_{t-p} + \varepsilon_t, \text{ where } \varepsilon_t \sim iid(0, \sigma_\varepsilon^2).$$

$$\begin{aligned} H_0: & \rho_{0,i} = 0, \text{ for all } i = 1, 2, \dots, p \\ H_A: & \rho_{0,i} \neq 0, \text{ for at least one } i = 1, 2, \dots, p \end{aligned}$$

Test stat is:

$$LM_p = TR^2$$

where R^2 is from regression of e_t on $x_t, e_{t-1}, e_{t-2}, \dots, e_{t-p}$.

Under H_0 : $LM_p \xrightarrow{d} \chi_p^2$.

Choice of p ?

- trade off
- may reflect sampling frequency of data

Interpretation of significant test

- can be caused by AR(p) errors
- can also be caused by misspecified model

Empirical example: See Section 4.4.5 of Lecture Notes

Consequences of $E[x_t u_t] \neq 0$ (violation of CS4 or TS4).

Recall

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$$\hat{\beta}_T - \beta_0 = \left(T^{-1} \sum_{t=1}^T x_t x_t' \right)^{-1} T^{-1} \sum_{t=1}^T x_t u_t,$$

and using the WLLN we have

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$$T^{-1} \sum_{t=1}^T x_t x_t' \xrightarrow{p} E[x_t x_t'] = Q,$$

$$T^{-1} \sum_{t=1}^T x_t u_t \xrightarrow{p} E[x_t u_t] = \mu \neq 0.$$

So using Slutsky's Theorem: $\hat{\beta}_T \xrightarrow{p} \beta_0 + Q^{-1}\mu \neq \beta_0$.

So OLS is an inconsistent estimator of β_0 .

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Source of problem is endogenous regressor(s).

This can arise in three main ways in econometric models:

- reverse causality
- omitted variables
- measurement error

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Now consider an example of each.

Acemoglu et al (2001):

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$$\ln[y_i] = \beta_0 + r_i\beta_1 + \text{controls} + u_i$$

where

- y_i is income per capita in developing country i
- r_i is quality of institutions in developing country i

r is likely correlated with u_i due to reverse causality.

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Angrist & Krueger (1991):

$$\ln[w_i] = \theta_1 + \theta_e \text{ed}_i + \text{controls} + u_i$$

where

- w_i equals the weekly wage of individual i ;
- ed_i is the number of years of education of individual i ;

ed_i likely correlated with u_i due to omitted variables such as “ability” that affect w_i and ed_i .

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Example 3: monetary policy reaction function

Clarida, Gali & Gertler (2000):

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$$r_t = \bar{r} + \beta_\pi E[\pi_{t+1} | \Omega_t] + \beta_y E[y_{t+1} | \Omega_t] + \beta_1 r_{t-1} + \beta_2 r_{t-2} + u_t,$$

- r_t = Federal Funds rate in year quarter t

- π_{t+1} = inflation in $t + 1$

- Ω_t information set at time t

- y_{t+1} = output gap in $t + 1$

- u_t is error satisfying $E[u_t | \Omega_t] = 0$

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Example 3: monetary policy reaction function

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Expectations not observed. If replace by actual values then introduce measurement error because:

$$r_t = c + \beta_\pi \pi_{t+1} + \beta_y y_{t+1} + \beta_1 r_{t-1} + \beta_2 r_{t-2} + \underbrace{(u_t - \beta_\pi v_{\pi,t+1} - \beta_y v_{y,t+1})}_{\equiv e_t}$$

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where

- $v_{(\cdot),t+1} = (\cdot)_{t+1} - E[(\cdot)_{t+1} | \Omega_t]$,
 - $E[(\cdot)_{t+1} e_t] = \beta_{(\cdot)} \text{Var}[v_{(\cdot),t+1}] \neq 0$.
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To motivate IV estimation, we reinterpret OLS as a Method of Moments (MoM) estimator.

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From normal equations: OLS is MoM based on the population moment condition:

$$E[x_t u_t(\beta_0)] = 0 \quad (*)$$

where $u_t(\beta) = y_t - x_t' \beta$ (and so $u_t(\beta_0) = u_t$).

From this perspective, estimation is based on information in $(*)$ about β_0 . So if

- $E[x_t u_t(\beta_0)] = 0 \rightarrow$ consistent estimator.
- $E[x_t u_t(\beta_0)] \neq 0 \rightarrow$ inconsistent estimator.

Find a $q \times 1$ vector z_t such that:

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- need $q \geq k$ and z_t “sufficiently related to” x_t + certain other conditions discussed in the next lecture
- z_t known as an instrument

Use the population moment equation in (‡) as basis for estimation

→ Instrumental Variables (IV) estimator of β_0

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Discuss next time how to calculate IV estimator and what its properties are. Conclude by looking at choices of instruments in our three examples.

Example 1: Economic development and institutions

Acemoglu *et al* (2001):

$$\ln[y_i] = \beta_0 + r\beta_1 + \text{controls} + u_i$$

where

- y_i is income per capita in developing country i
- r is quality of institutions in developing country i

r is likely correlated with u_i due to reverse causality.

Base estimation on the population moment condition:

$$E[z_i u_i] = 0$$

where $z_i = [1, \text{controls}, M_i]'$ and M_i is settler mortality in country i .

Example 2: returns to education

Angrist & Krueger (1991):

$$\ln[w_i] = \theta_0 + \theta_1 \text{ed}_i + \text{controls} + u_i$$

where

- w_i equals the weekly wage of individual i ;
- ed_i is the number of years of education of individual i ;

ed_i likely correlated with u_i due to omitted variables such as “ability” that affect w_i and ed_i .

Base estimation on

$$E[z_i u_i] = 0$$

where $z_i = [1, \text{controls}, Q_i]'$ and Q_i is quarter of birth of i .

Example 3: monetary policy reaction function

Clarida, Gali & Gertler (2000):

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$$r_t = \bar{r} + \beta_\pi E[\pi_{t+1} | \Omega_t] + \beta_y E[y_{t+1} | \Omega_t] + \beta_1 r_{t-1} + \beta_2 r_{t-2} + u_t,$$

- r_t = Federal Funds rate in year quarter t

- π_{t+1} = inflation in $t + 1$

- Ω_t information set at time t

- y_{t+1} = output gap in $t + 1$

- u_t is error satisfying $E[u_t | \Omega_t] = 0$

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Example 3: monetary policy reaction function

Expectations not observed if replace by actual values then

Introduce measurement error because:

$$r_t = c + \beta_\pi \pi_{t+1} + \beta_y y_{t+1} + \beta_1 r_{t-1} + \beta_2 r_{t-2} + \underbrace{(u_t - \beta_\pi v_{\pi,t+1} - \beta_y v_{y,t+1})}_{= e_t}$$

where

- $v_{(\cdot),t+1} = (\cdot)_{t+1} - E[(\cdot)_{t+1} | \Omega_t],$
- $E[(\cdot)_{t+1} | \Omega_t] = E[(\cdot)_{t+1} | \Omega_t] \neq 0.$

However: $E[z_t e_t] = 0$ for any $z_t \in \Omega_t$ (e.g. macro variables).

- Notes: Sections 4.4, 5.1, 5.2

- Greene.

- Time series regression models with serial correlation,

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- OLS 20.4 (but 20.4.1 and 20.4.2 go into more detail on “other conditions” in limit theorems than needed for the course), 20.5

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- GLS, FGLS 20.8, 20.9

- Testing for serial correlation 20.7

- IV 8.1, 8.2 and 8.3