

# ECS 150 - The Kernel Abstraction

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*Prof. Joël Porquet-Lupine*

**Assignment Project Exam Help**

UC Davis - 2020/2021

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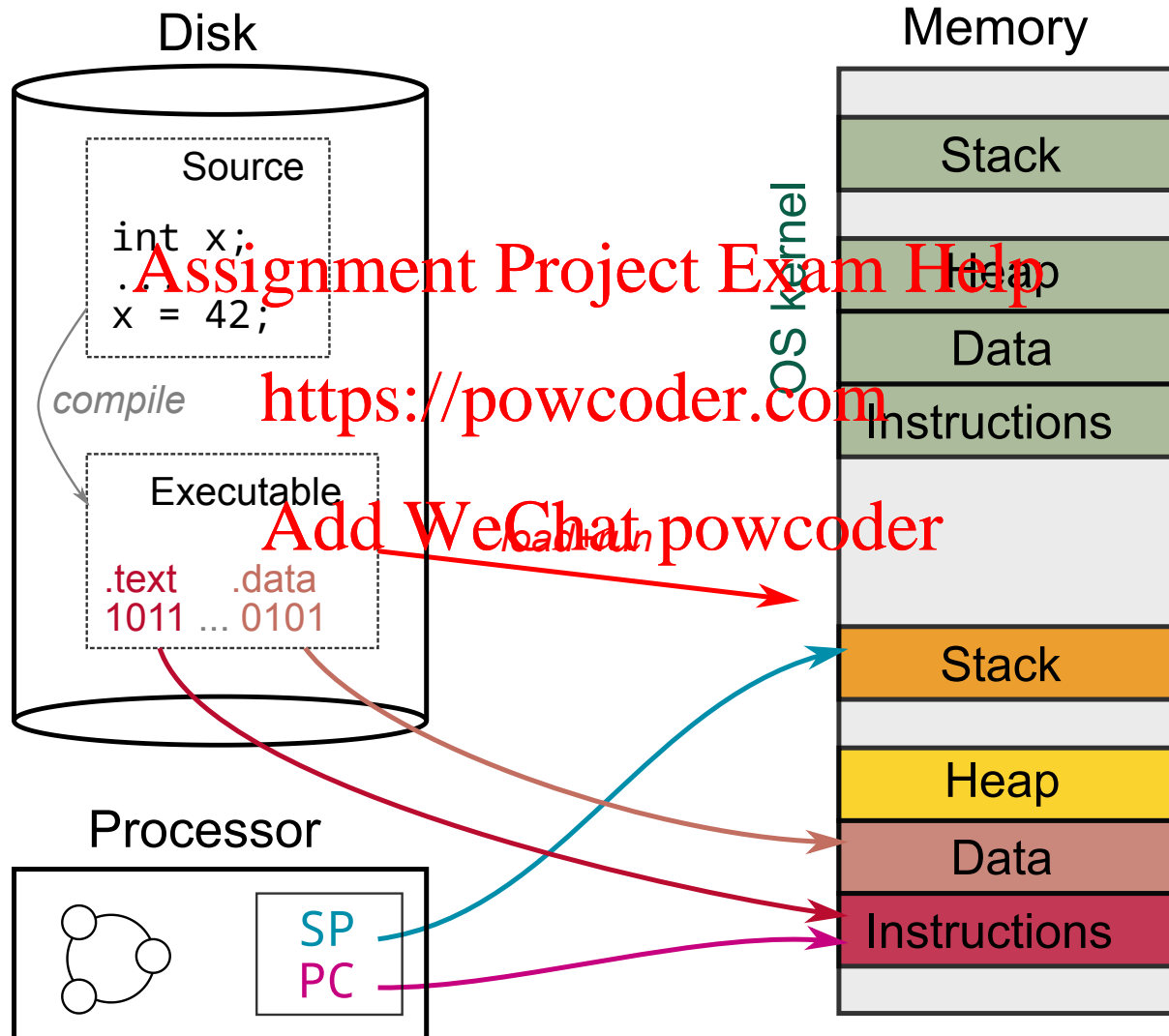
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# Process abstraction

## Process definition

A process is a program in execution



# Process abstraction

## Lack of protection

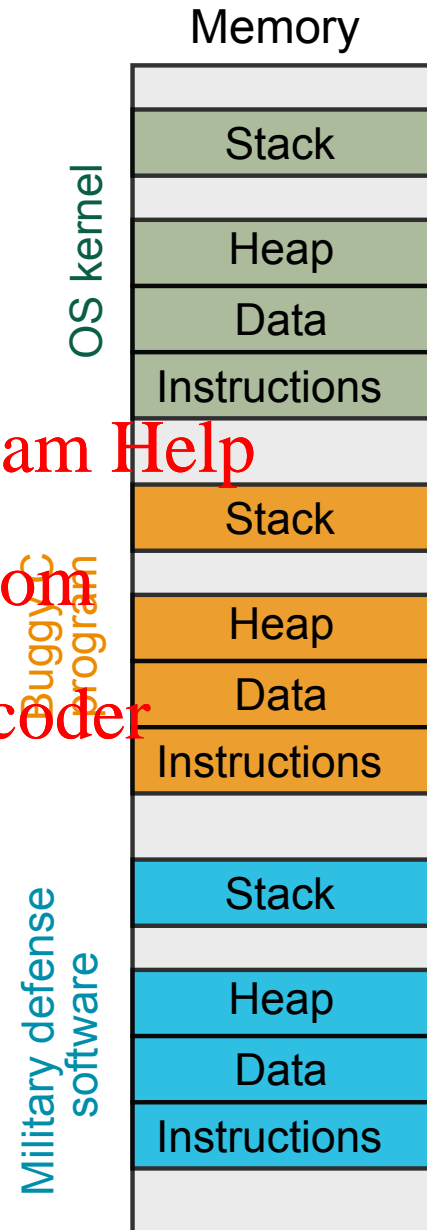
Multiple processes can be loaded in memory and run concurrently

### Issues

- Buggy process
  - Crash other processes
  - Crash the OS
  - Hog all the resources
- Malicious process

### Solution

- Redefine process abstraction
- Include notion of protection



# Process abstraction

## Process RE-definition

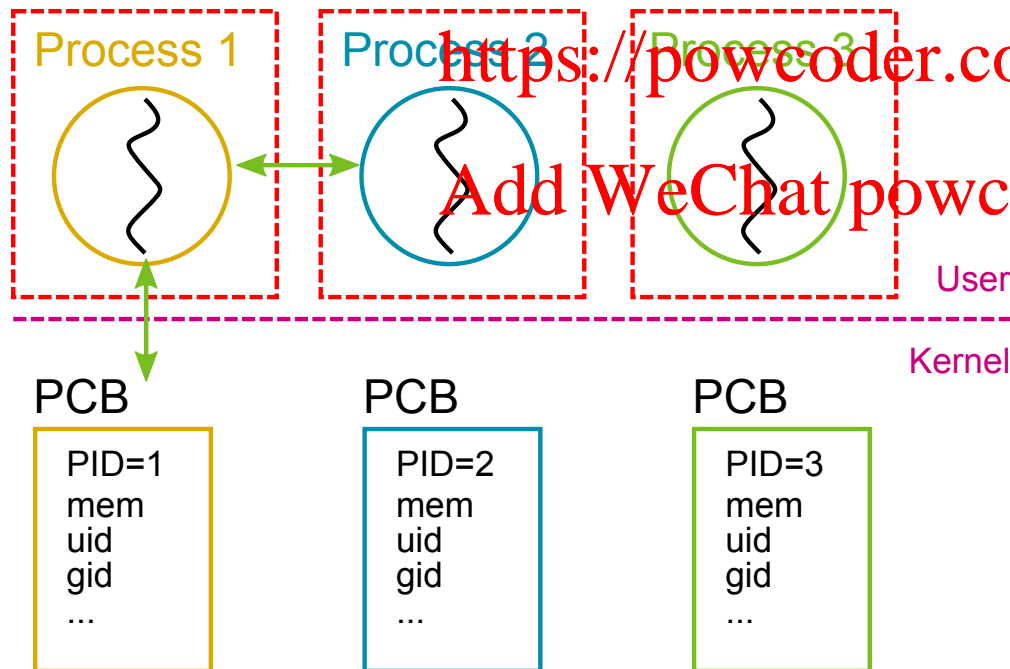
A process is a program in execution, **running with limited rights**

### Protected execution

- Memory segments process can access
- Other permissions process has
  - E.g., what files it can access
  - Based on process user ID, group ID

### But efficient

- Restricting rights must not hinder functionality
- Efficient use of hardware
- Communication with OS and between processes is safe

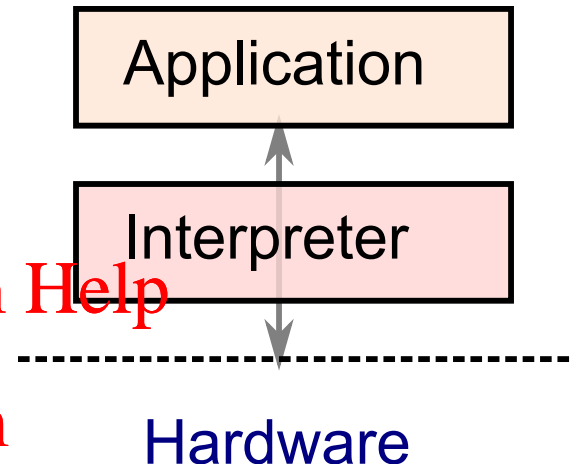


# Process abstraction

## Limited privilege execution

### Interpreted execution

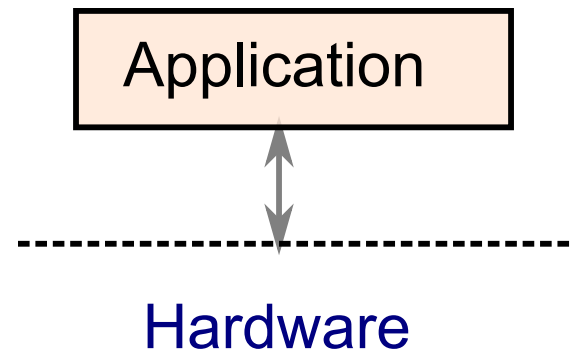
- Basic model in interpreted languages
  - Javascript, Python, etc.
- Emulate each program instruction
  - If instruction is permitted, then perform it
  - Otherwise, stop process
- But execution quite slow...



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### Native execution

- Run unprivileged code directly on the CPU
  - Very fast execution
- But safe execution needs specific hardware support...



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# Dual-mode operation

## Concept

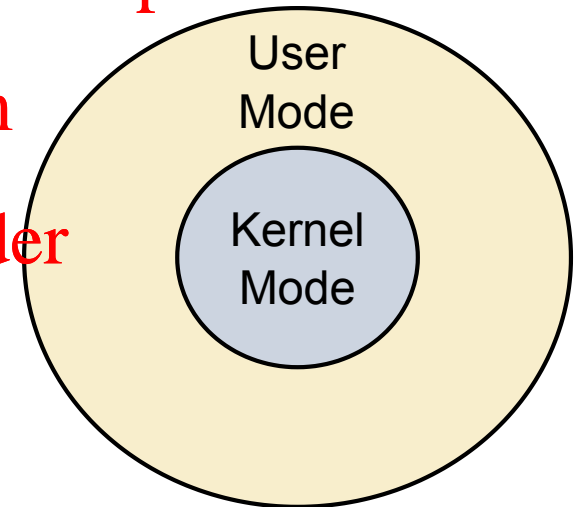
- Distinct execution modes supported directly in hardware
  - Indicated by a bit in processor status register (e.g., 0 or 1)
  - Can be more than one mode on some processor architectures

## Kernel mode

- Execution with full privileges on the hardware
  - Read/write to any memory/location
  - Access to any I/O device
  - Read/write to any disk sector
  - Send/receive any packet
  - Etc.

## User mode

- Limited privileges on the hardware
  - As granted by the operating system



# Dual-mode operation

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## Hardware support

### Privileged instructions

- Potentially unsafe instructions prohibited when in user mode
- Only available in kernel mode

### Memory protection

- Memory accesses outside of process' memory limits prohibited
- Prevent process from overwriting kernel's or other processes' memory

### Timer interrupts

- Kernel periodically regains control on CPU
- Prevent running process from hogging hardware

### Mode switch

- Safe and efficient way to switch mode
- From user mode to kernel mode, and vice-versa

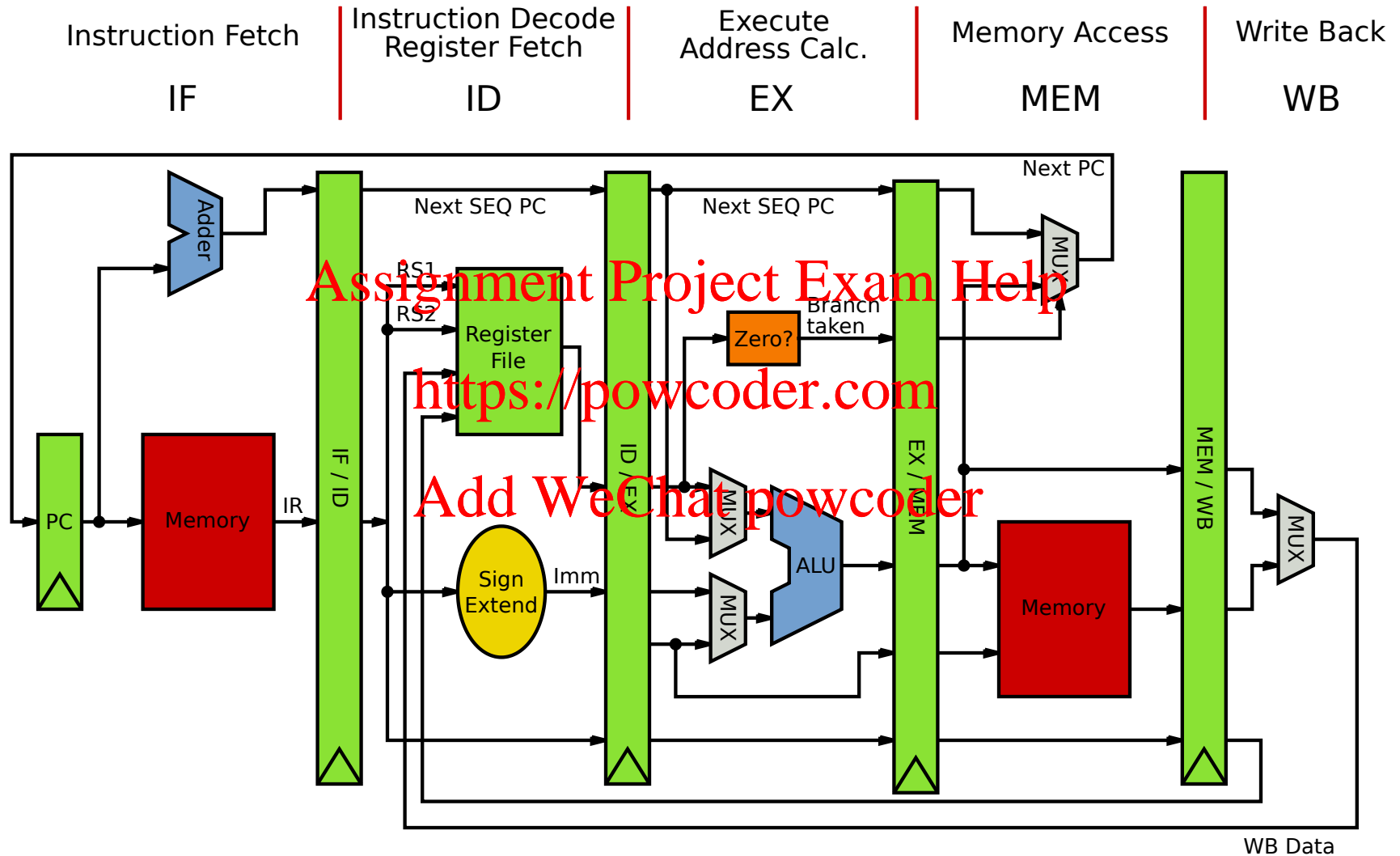
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# Dual-mode operation

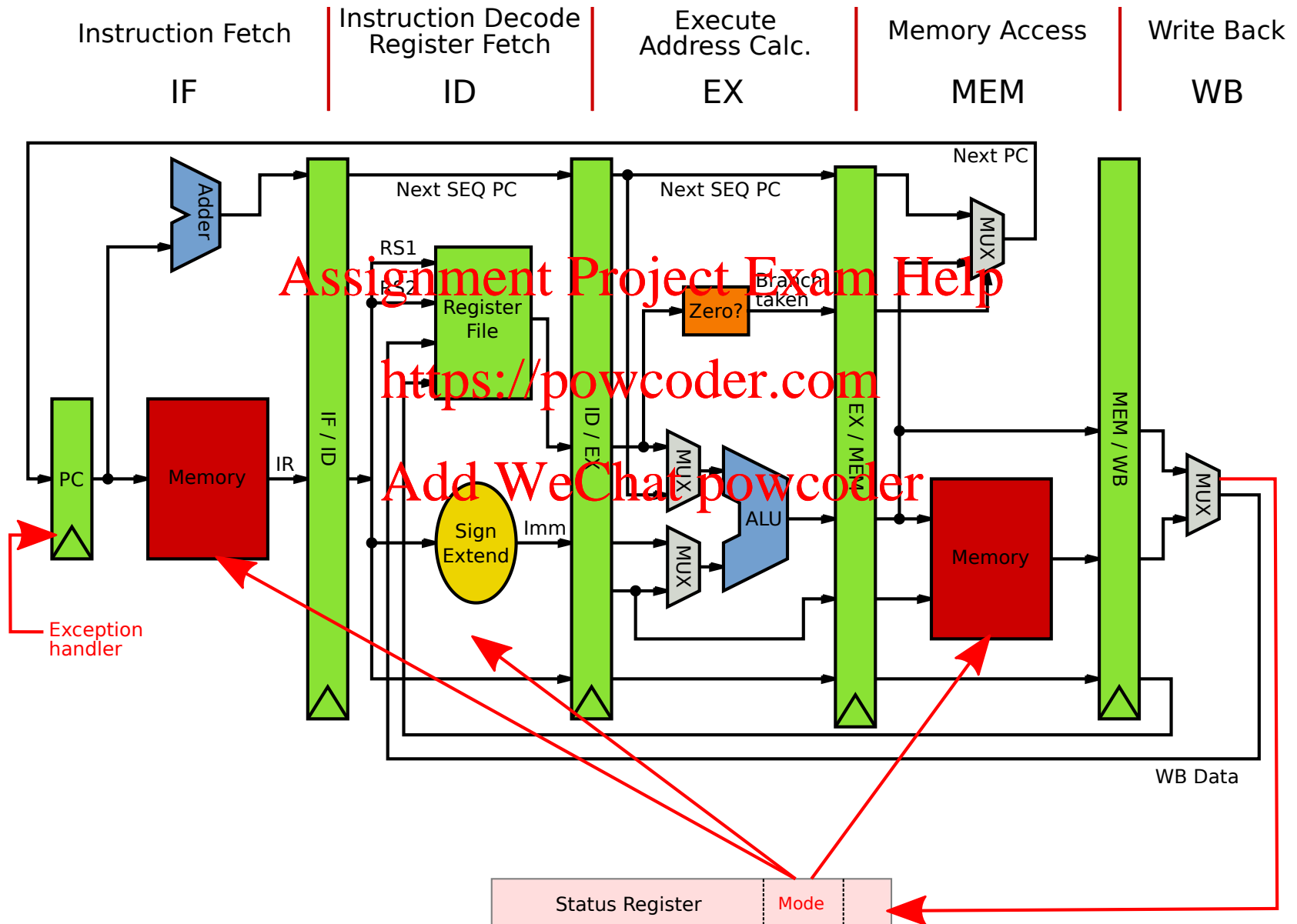
## Typical 5-stage pipeline





# Dual-mode operation

## "Dual-mode" 5-stage pipeline



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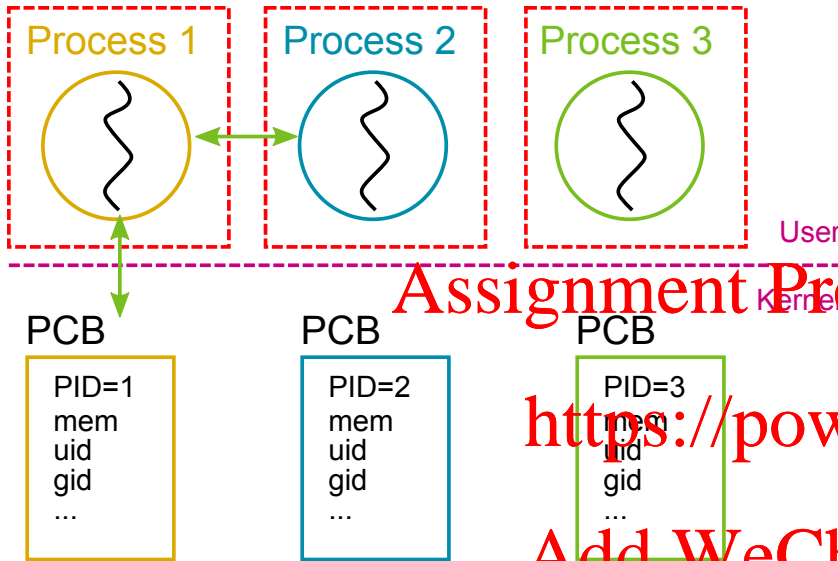
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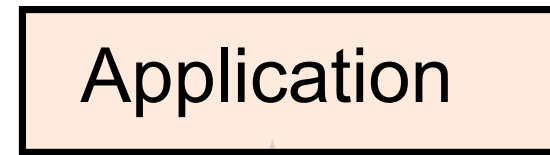
# Recap

## Process abstraction, v2.0

### Protected execution



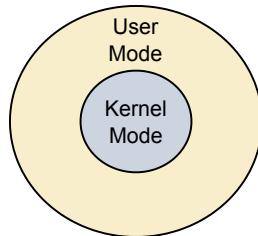
### Native execution



Hardware

## Dual-mode operation

### User mode vs kernel mode



### Hardware support

- Privileged instructions
- Memory protection
- Timer interrupts
- Mode switch

# Privileged instructions

## Definition

- Instructions only available to code running in kernel mode
- Processor exception if user code tries to execute privileged instruction

## Example

```
int main(void)
{
    printf("Hello!\n");

    /* Try deactivating
     * hardware interrupts */
    asm ("cli" ::: "memory");

    while (1)
        printf("I win?\n");

    return 0;
}
```

x86\_cli.c

```
$ ./x86_cli
Hello!
Segmentation fault (core dumped)
```

Illegal instructions are reported as segmentation faults on x86/Linux

## And more...

- Toggle processor mode
- Modify memory protection
- Flush/invalidate caches/TLBs
- Halt or reset processor
- Etc.

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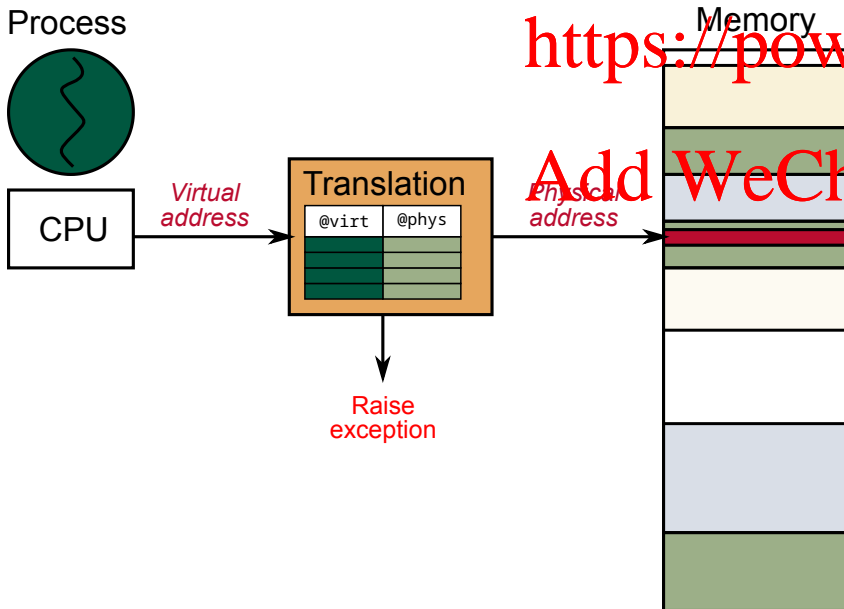
# Memory protection

## Concept

- Enforce memory boundaries to processes
- Processor exception if code tries to access unauthorized memory

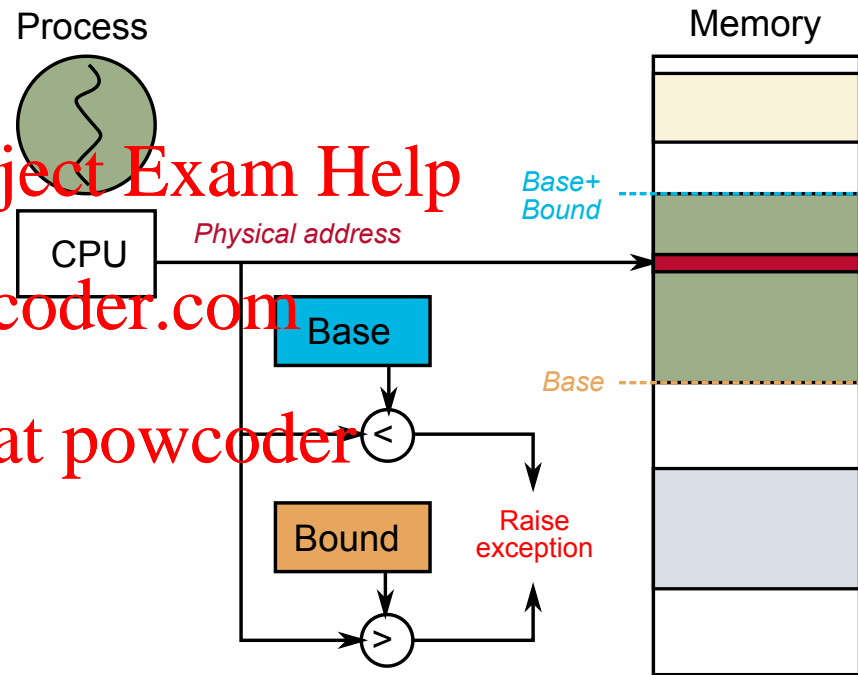
## Virtual memory

- Runtime translation between virtual and physical address spaces



## Basic segmentation

- Memory area defined by base and bound pair



# Timer interrupts

## Boot sequence

- Upon powering on the computer
  - Privilege mode set to kernel mode
  - PC set to address of boot code (e.g., BIOS)
- Boot code runs
  - Loads kernel image into memory
  - Jumps to kernel's entry point
- Kernel code runs
  - Machine setup (devices, virtual memory, interrupt vector table, etc.)
  - Chooses the first *user* process to run, loads it, and jumps to it
    - Privilege bit set to user mode
    - PC set to process' entry point
- First process runs
  - Need a way for kernel to re-take control...



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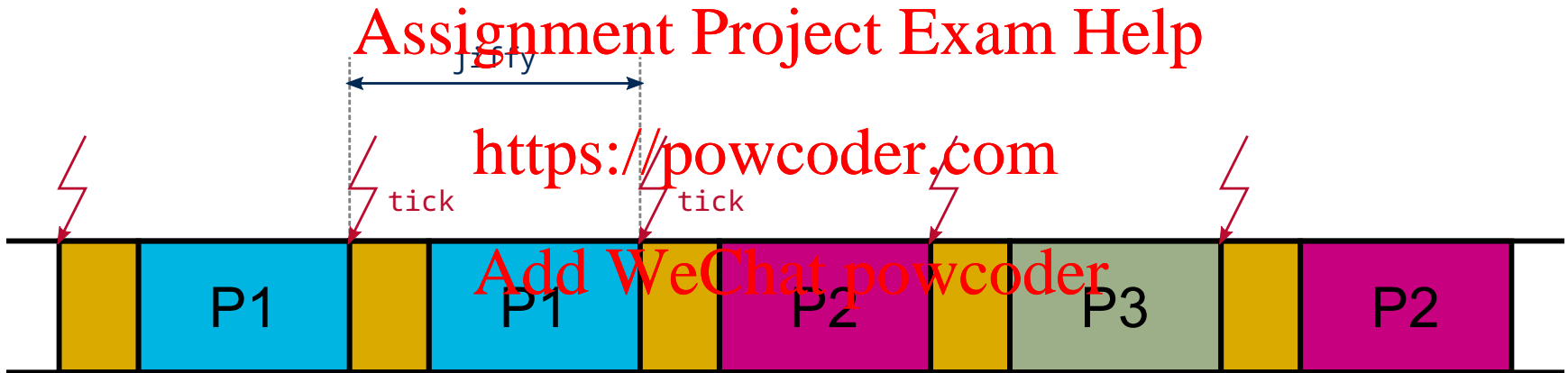
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# Timer interrupts

## Hardware timer

- Periodically interrupts the processor
  - Frequency of interruption set by the kernel
  - Returns control to the kernel exception handler
- Also used to maintain accurate and precise time of day



# Mode switching

## User mode to kernel mode

### Exceptions

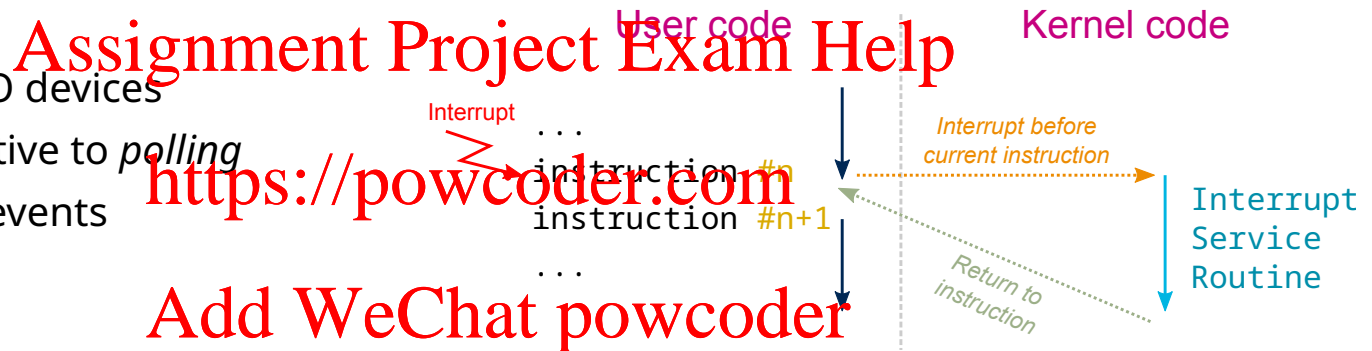
- Triggered by program behavior
- Intentional or unintentional
- Synchronous events

```
asm ("cli" ::: "memory");
```

```
int *a = NULL;  
*a = 42;
```

### Interrupts

- Triggered by I/O devices
- (Better) alternative to *polling*
- Asynchronous events



### System calls

- Request from process for kernel to perform operation on its behalf
- Intentional, synchronous events

```
read:  
    movq $SYS_read, rax  
    movq $fd, rdi  
    movq $buf, rsi  
    ...  
    syscall
```



# Mode switching

## Kernel mode to user mode

Return from interrupt or system call

- Resume suspended execution



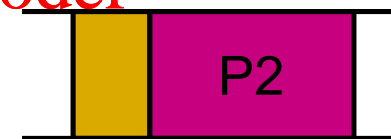
## Process context switch

- Resume some other process



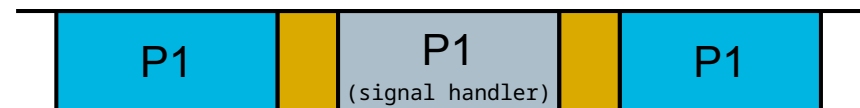
## New process start

- Jump to first instruction in program



## Signal

- Asynchronous notification
- If signal handler defined



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# Recap

## Mode switching

### User to kernel

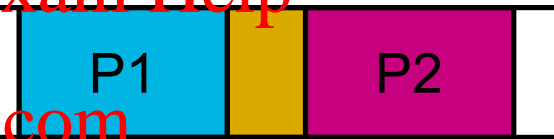
- Exceptions
  - Caused by program behavior
  - Synchronous
- Interrupts
  - Triggered by I/O devices
  - Asynchronous
- System calls
  - Service request to kernel
  - Synchronous

### Kernel to user

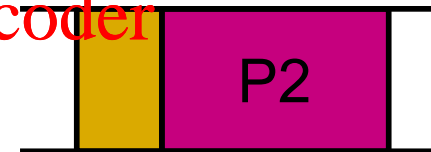
- Return from interrupt or system call



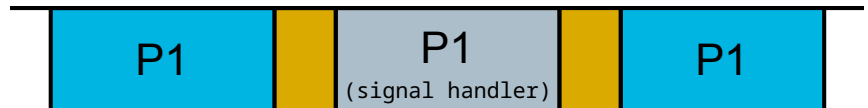
- Context switch between processes



- New process start



- Signal handler



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# Mode switching

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## Safe and efficient switching

- Protect from corrupting the kernel
  - Entry door to the kernel for processes
- Reduce overhead of kernel
  - Maximize CPU cycles for processes

## Requirements

1. Atomic transfer of control
2. Exception vector
3. Transparent, restartable execution

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# Mode switching

## Atomic transfer of control

- Safe transition between modes must be atomic
  - I.e., in one *unbreakable*, logical step
- CPU mode, PC, stack, memory protection, etc. changed at the same time

### User to kernel switch

- Save cause for jump
  - Interrupt, Exception, Syscall
- Save current PC
- Jump to kernel entry point (sp)
- Switch from user to kernel mode
- Change memory protection
- Disable interrupts

### Kernel to user switch

- Jump to process (restore PC)
- Switch from kernel to user mode
- Change memory protection
- Restore interrupts



# Mode switching

## Exception vector

- Provide limited number of entry points into the kernel
- Table set up by kernel: function pointers to exception handlers

Example MIPS processor

```
/* Exception handler init */
exception_handlers[0] = handle_int;
exception_handlers[8] = handle_sys;
exception_handlers[10] = handle_ri;
...
```

## Software-managed

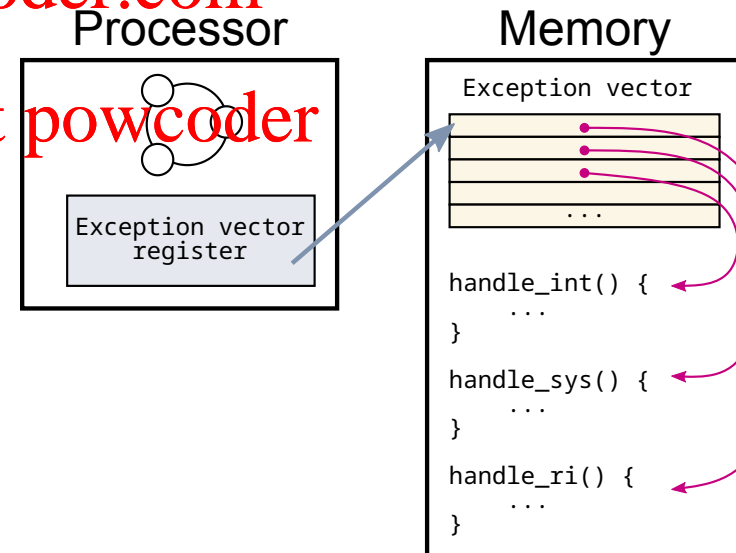
- Single kernel entry point for CPU
  - Fixed or configurable address
- Software dispatch based on exception cause

```
exception_vector:  # Kernel entry point
# Retrieve cause from system register
mfc0    k1, CP0_CAUSE
# Extract exception code
andi    k1, k1, 0x7c
# Use code as index in array
lw      k0, exception_handlers(k1)
# Jump to proper handler
jr      k0
```

Example MIPS processor

## Hardware-managed

- CPU aware of vector
- Automatic hardware dispatch



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# Mode switching

## Transparent, restartable execution

- Processes should never know when they are interrupted
- Save/restore execution context (processor registers)

### Software-managed

```
handle_int:
    # Save all registers
    SW $1, 4(sp)
    SW $2, 8(sp)
    SW $3, 12(sp)
    ...
    # Jump to C function
    # that processes interrupt requests
    jal do_irq

    # Restore all registers
    ...
    lw $3, 12(sp)
    lw $2, 8(sp)
    lw $1, 4(sp)

    # Jump back to process
    eret
```

Example MIPS processor

### Hardware-managed

- Processor saves all the registers in a provided memory region
  - Task state segment (TSS) on x86 processors
- Barely used in practice
  - E.g., not used by Linux or Windows

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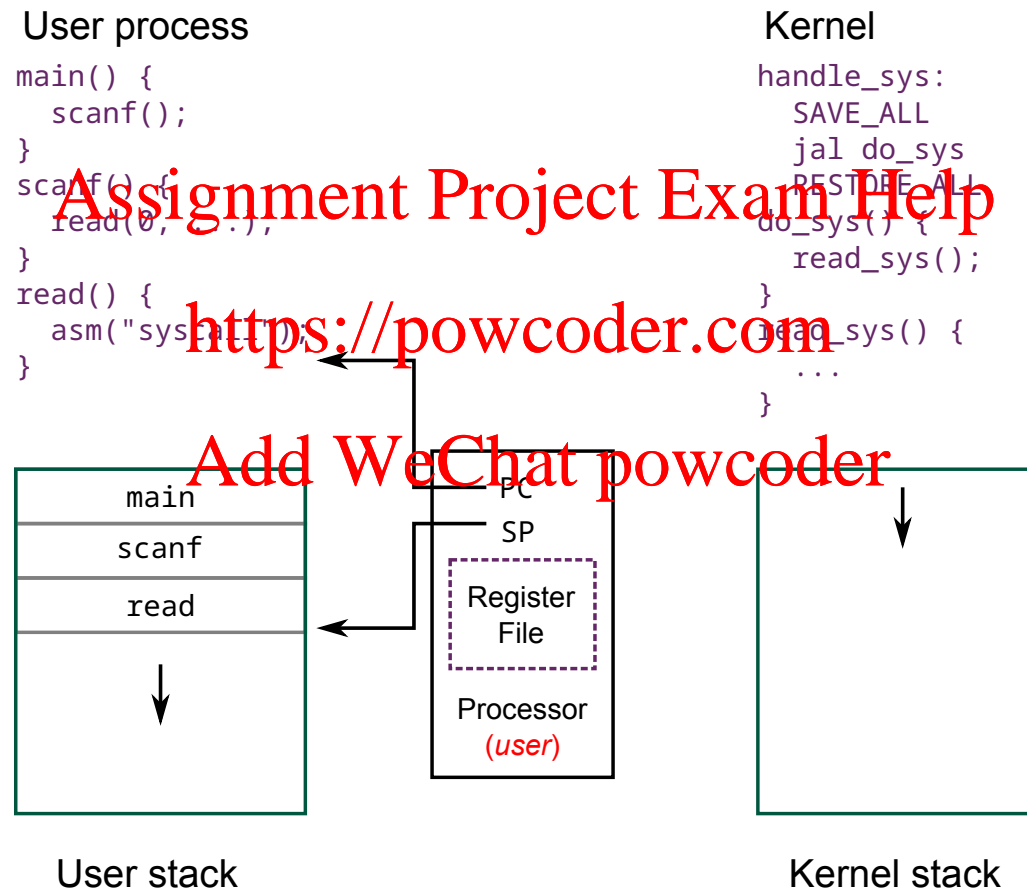
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# Kernel stack

## Definition

- Kernel has its own stack, located in kernel memory
- Different from process' stack





# Kernel stack

## Context saving

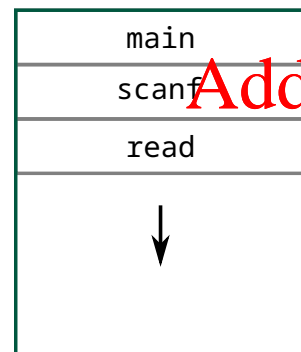
- Kernel stack is used to save associated process context

### User process

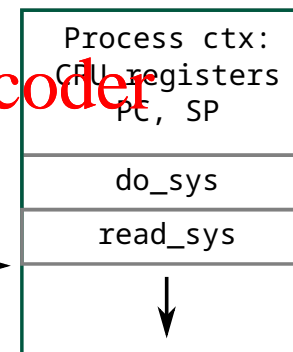
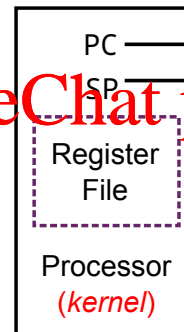
```
main() {  
    scanf();  
}  
scanf() {  
    read(0, ...);  
}  
read() {  
    asm("syscall");  
}
```

### Kernel

```
handle_sys:  
    SAVE_ALL  
    jal do_sys  
    RESTORE_ALL  
do_sys() {  
    read_sys();  
}  
read_sys() {  
    ...  
}
```



User stack



Kernel stack

- Not a good idea to reuse process's stack pointer
  - Reliability: no guarantee user stack is valid
  - Security: kernel data shouldn't leak to user space

# Kernel stack

## One kernel stack per process

- Kernel saves its own state when switching between two processes

