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# Procedures

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# Overview

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- **C Functions**
- **MIPS Instructions for Procedures**
- **The Stack**
- **Register Conventions**
- **Another Example**

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# C functions

```
main() {
    int i, j, k, m;
```

```
    i = mult(j, k); ...
    m = mult(i, i); ...
```

**What information must  
compiler/programmer  
keep track of?**

```
}
```

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```
/* really dumb mult function */
```

```
int mult (int mcand, int mlier) {
    int product;
```

```
    product = 0;
    while (mlier > 0) {
        product = product + mcand;
        mlier = mlier - 1;
    }
    return product;
```

```
}
```

**What instructions can  
accomplish this?**

# Function Call Bookkeeping

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- Registers play a major role in keeping track of information for function calls.
- **Register conventions:**
  - Return address `$ra`
  - Arguments `$a0, $a1, $a2, $a3`
  - Return value `$v0, $v1`
  - Local variables `$s0, $s1, ... , $s7`
- The stack is also used.
- More on this later.

# Instruction Support for Functions (1/4)

**C** ... sum(a,b) ; ... /\* a,b:\$s0,\$s1 \*/  
 }  
 int sum(int x, int y) {  
     return x+y;  
 }

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**MIPS**

address			
1000	add	\$a0, \$s0, \$zero	# x = a
1004	add	\$a1, \$s1, \$zero	# y = b
1008	addi	\$ra, \$zero, 1016	#\$ra=1016
1012	j	sum	#jump to sum
1016	...		
2000	sum:	add \$v0, \$a0, \$a1	
2004	jr	\$ra	# new instruction

## Instruction Support for Functions (2/4)

- Single instruction to jump and save return address: jump and link (jal)

- Before:

1008 addi \$ra, \$zero, 1016 # \$ra=1016  
1012 j sum # go to sum

- After:

1012 jal sum # \$ra=1016, go to sum

- Why have a jal? Make the common case fast: functions are very common.

# Instruction Support for Functions (3/4)

- ° Syntax for `jal` (jump and link) is same as for `j` (jump):

`jal label`

- ° `jal` should really be called `la j` for “link and jump”:
  - Step 1 (link): Save address of *next* instruction into `$ra` (Why next instruction? Why not current one?)
  - Step 2 (jump): Jump to the given label

# Instruction Support for Functions (4/4)

- **Syntax for `jr` (jump register):**

`jr     register`

- **Instead of providing a label to jump to, the `jr` instruction provides a register which contains an address to jump to.**

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- **Only useful if we know exact address to jump to: rarely applicable.**

- **Very useful for function calls:**

- `jal` stores return address in register (\$ra)
- `jr` jumps back to that address



# Nested Procedures (1/2)

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```
int sumSquare(int x, int y) {  
    return mult(x,x) + y;  
}
```

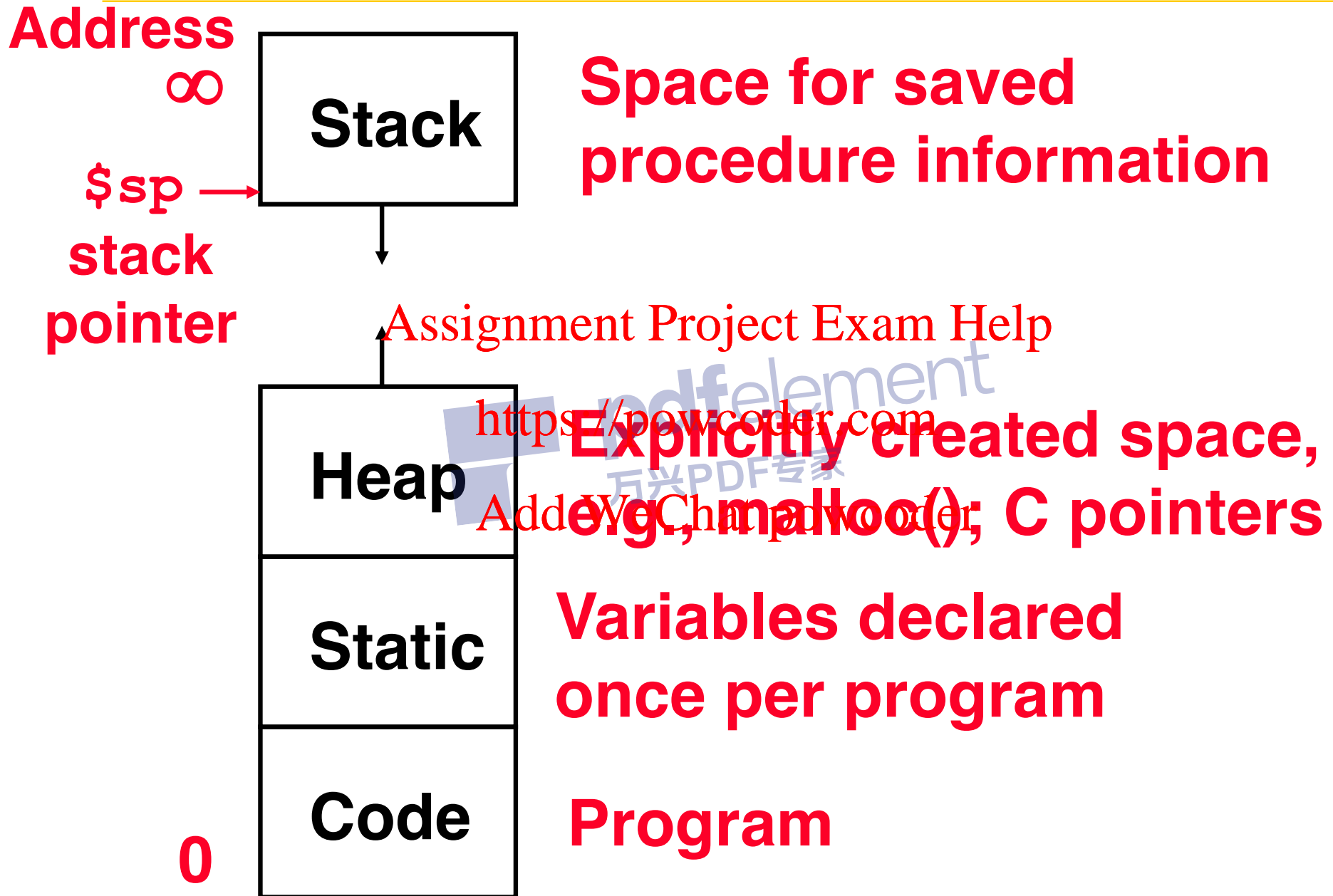
- Something called `sumSquare`, now `sumSquare` is calling `mult`.  
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- So there's a value in `$ra` that `sumSquare` wants to jump back to, but this will be overwritten by the call to `mult`.  
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- Need to save `sumSquare` return address before call to `mult`.

## Nested Procedures (2/2)

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- In general, may need to save some other info in addition to \$ra.
- When a C program is run, there are 3 important memory areas allocated:
  - Static: Variables declared once per program, cease to exist only after execution completes
  - Heap: Variables declared dynamically
  - Stack: Space to be used by procedure during execution; this is where we can save register values

# C memory Allocation



# Using the Stack (1/2)

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- So we have a register `$sp` which always points to the last used space in the stack.
- To use stack, we decrement this pointer by the amount of space we need and then fill it with info.
- So, how do we compile this?

```
int sumSquare(int x, int y) {  
    return mult(x,x)+ y;  
}
```

## Using the Stack (2/2)

### °Compile by hand

sumSquare:

```
addi $sp,$sp,-8 #space on stack
sw $ra, 4($sp) # save ret addr
sw $a1, 0($sp) # save y

add $a1,$a0,$zero # mult(x,x)
jal mult # call mult

lw $a1, 0($sp) # restore y
add $v0,$v0,$a1 # mult()+y
lw $ra, 4($sp) # get ret addr
addi $sp,$sp,8 # restore stack
jr $ra
```

# Steps for Making a Procedure Call

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- 1) Save necessary values onto stack.
- 2) Assign argument(s), if any.
- 3) `jal call`
- 4) Restore values from stack.

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# Rules for Procedures

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- Called with a `jal` instruction, returns with a `jr $ra`
- Accepts up to 4 arguments in `$a0`, `$a1`, `$a2` and `$a3`
- Return value is always in `$v0` (and if necessary in `$v1`)
- Must follow **register conventions** (even in functions that only you will call)!  
So what are they?

# MIPS Registers (1/2)

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The constant 0	\$0	\$zero
Reserved for Assembler	\$1	\$at
Return Values	\$2-\$3	\$v0-\$v1
Arguments	\$4-\$7	\$a0-\$a3
Temporary	\$8-\$15	\$t0-\$t7
Saved	\$16-\$23	\$s0-\$s7
More Temporary	\$24-\$25	\$t8-\$t9

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# MIPS Registers (2/2)

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Used by Kernel	\$26-27	\$k0-\$k1
Global Pointer	\$28	\$gp
Stack Pointer	\$29	\$sp
Frame Pointer	\$30	\$fp
Return Address	\$31	\$ra

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- In general, feel free to use either the name or the number, but try not to use both within the same piece of code.
- We prefer names, they make code more readable.

# Register Conventions (1/5)

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- **Caller:** the calling function
- **Callee:** the function being called
- **When callee returns from executing,** the caller needs to know which registers may have changed and which are guaranteed to be unchanged.
- **Register Conventions:** A set of generally accepted rules as to which registers will be unchanged after a procedure call (ja1) and which may be changed.

## Register Conventions (2/5)

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- **\$0: No Change. Always 0.**
- **\$v0-\$v1: Change. These are expected to contain new values.**
- **\$a0-\$a3: Change. These are volatile argument registers.**
- **\$t0-\$t9: Change. That's why they're called temporary: any procedure may change them at any time.**

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## Register Conventions (3/5)

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- **\$s0-\$s7: No Change.** Very important, that's why they're called saved registers. If the callee changes these in any way, it must restore the original values before returning.  
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- **\$sp: No Change.** The stack pointer must point to the same place before and after the `jal` call, or else the caller won't be able to restore values from the stack.  
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- **\$ra: Change.** The `jal` call itself will change this register.

# Register Conventions (4/5)

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- What do these conventions mean?
  - If function A calls function B, then function A must save any temporary registers that it may be using onto the stack before making a `jal` call.
  - Function B must save any S (saved) registers it intends to use before garbling up their values
  - Remember: Caller/callee need to save only temporary/saved registers they are using, not all registers.

# Register Conventions (5/5)

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- Note that, if the *callee* is going to use some s registers, it must:
  - save those s registers on the stack
  - use the registers
  - restore s registers from the stack
  - jr \$ra
- With the temp registers, the callee doesn't need to save onto the stack.
- Therefore the *caller* must save those temp registers that it would like to preserve though the call.

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# Other Registers

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- **\$at**: may be used by the assembler at any time; unsafe to use
- **\$k0-\$k1**: may be used by the kernel at any time; unsafe to use
- **\$gp**: don't worry about it
- **\$fp**: don't worry about it
- **Note**: Feel free to read up on \$gp and \$fp in Appendix A, but you can write perfectly good MIPS code without them.

# Example: Compile This (1/5)

---

```
main() {  
    int i,j,k,m; /* i-m:$s0-$s3 */  
  
    i = mult(j,k); ... ;  
    m = mult(i,i); ...  
  
}
```

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```
int mult (int mcand, int mlier) {  
    int product;  
  
    product = 0;  
    while (mlier > 0) {  
        product += mcand;  
        mlier -= 1; }  
    return product;  
  
}
```

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## Example: Compile This (2/5)

**\_\_start:**

```
add $a0,$s1,$0      # arg0 = j
add $a1,$s2,$0      # arg1 = k
jal mult            # call mult
add $s0,$v0,$0      # i = mult()
...
add $a0,$s0,$0      # arg0 = i
add $a1,$s0,$0      # arg1 = i
jal mult            # call mult
add $s3,$v0,$0      # m = mult()
...
```

**done**

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# Example: Compile This (3/5)

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## ◦ Notes:

- `main` function ends with `done`, not `jr $ra`, so there's no need to save `$ra` onto stack
- all variables used in `main` function are saved registers, so there's no need to save these onto stack

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## Example: Compile This (4/5)

```
mult:
    add    $t0,$0,$0        # prod=0

Loop:
    slt    $t1,$0,$a1       # mlr > 0?
    beq    $t1,$0,Fin       # no=>Fin
    add    $t0,$t0,$a0       # prod+=mc
    addi   $a1,$a1,-1        # mlr-=1
    j      Loop             # goto Loop

Fin:
    add    $v0,$t0,$0       # $v0=prod
    jr     $ra              # return
```

# Example: Compile This (5/5)

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## ° Notes:

- no `jal` calls are made from `mult` and we don't use any saved registers, so we don't need to save anything onto stack
- temp registers are used for intermediate calculations (could have used `s` registers, but would have to save the caller's on the stack.)
- `$a1` is modified directly (instead of copying into a temp register) since we are free to change it
- result is put into `$v0` before returning

# Things to Remember (1/2)

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- ° Functions are called with `jal`, and return with `jr $ra`.
- ° The stack is your friend: Use it to save anything you need. Just be sure to leave it the way you found it.  
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- ° **Register Conventions:** Each register has a purpose and limits to its usage. Learn these and follow them, even if you're writing all the code yourself.  
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# Things to Remember (2/2)

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## ◦ Instructions we know so far

**Arithmetic:**    `add, addi, sub, addu, addiu, subu, sll`

**Memory:**        `lw, sw`

**Decision:**       `beq, bne, slt, slti, sltu, sltiu`

**Unconditional Branches (Jumps):**  
                  `j, jal, jr`

## ◦ Registers we know so far

- All of them!