

Last time

System F_ω

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$$\frac{K_1 \text{ is a kind} \quad K_2 \text{ is a kind}}{K_1 \Rightarrow K_2 \text{ is a kind}} \Rightarrow\text{-kind}$$

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$$\frac{\Gamma, \alpha :: K_1 \vdash A :: K_2}{\Gamma \vdash \lambda \alpha :: K_1. A :: K_2 \Rightarrow K_2} \Rightarrow\text{-intro} \quad \frac{\Gamma \vdash A :: K_1 \Rightarrow K_2 \quad \Gamma \vdash B :: K_1}{\Gamma \vdash A B :: K_2} \Rightarrow\text{-elim}$$

(and encoding data types: 1, 2, \mathbb{N} , +, lists, nested types and \equiv)

This time

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What is type inference?

```
# fun f g x -> f (g x);;
```

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What is type inference?

```
# fun f g x -> f (g x);;
```

```
- :: ('a -> 'b) -> (('c -> 'a) -> 'c -> 'b) = <fun>
```

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Goal

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+

succinctness of annotation-free code
safety and expressiveness of System F ω

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What is type inference?

```
# fun f g x -> f (g x);;
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```
- :: ('a -> 'b) -> (('c -> 'a) -> 'd -> 'b) = <fun>
```

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Goal

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+

succinctness of annotation-free code
safety and expressiveness of System F ω

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Bad news

the goal is unachievable

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The ML calculus

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Prenex quantification

$\forall \alpha. \alpha \rightarrow \alpha$

$\forall \alpha. (\forall \beta. \alpha \rightarrow (\beta \rightarrow \beta))$

$\forall \alpha. (\forall \beta. \beta \rightarrow \beta) \rightarrow \alpha$

$\forall \alpha. \alpha \rightarrow (\forall \beta. \beta \rightarrow \beta)$

Let-bound polymorphism

```
let id = fun x -> x
in id id
```

```
let id x = x
in id id
```

```
let f id = id id
in f (fun x -> x)
```

```
(fun id -> id id)
  (fun x -> x)
```

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Prenex quantification

$\forall \alpha. \alpha \rightarrow \alpha$ ✓

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$\forall \alpha. (\forall \beta. \beta \rightarrow \beta) \rightarrow \alpha$ ✗

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$\forall \alpha. \alpha \rightarrow (\forall \beta. \beta \rightarrow \beta)$ ✗

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Prenex quantification

$\forall \alpha. \alpha \rightarrow \alpha$ ✓

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Prenex quantification

$\forall \alpha. \alpha \rightarrow \alpha$ ✓

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Let-bound polymorphism

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Prenex quantification

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Let-bound polymorphism

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```

```
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in f (fun x -> x)
```

```
(fun id -> id id)
(fun x -> x)
```

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Prenex quantification

$\forall \alpha. \alpha \rightarrow \alpha$ ✓

$\forall \alpha. \forall \beta. \alpha \rightarrow (\beta \rightarrow \beta)$ ✓

$\forall \alpha. (\forall \beta. \beta \rightarrow \beta) \rightarrow \alpha$ ✗

$\forall \alpha. \alpha \rightarrow (\forall \beta. \beta \rightarrow \beta)$ ✗

Let-bound polymorphism

```
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in id id
```

```
let id x = x
in id id
```

```
let f id = id id
in f (fun x -> x)
```

```
(fun id -> id id)
(fun x -> x)
```

✗

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Assignment Project Exam Help

$\frac{}{\Gamma \vdash B \text{ is a type}}$ β -types
 $\frac{\alpha \in \Gamma}{\Gamma \vdash \alpha \text{ is a type}}$ α -types
 $\frac{\Gamma \vdash A \text{ is a type} \quad \Gamma \vdash B \text{ is a type}}{\Gamma \vdash A \rightarrow B \text{ is a type}}$ \rightarrow -types
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 $\frac{\Gamma, \bar{\alpha} \vdash A \text{ is a type}}{\Gamma \vdash \forall \bar{\alpha}. A \text{ is a scheme}}$ scheme

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$$\frac{}{\cdot \text{ is an environment}} \Gamma \vdash \cdot$$

Γ is an environment

$\Gamma \vdash S$ is a scheme

$$\frac{\Gamma \vdash S \text{ is a scheme}}{\Gamma \vdash S \text{ is an environment}} \Gamma \vdash S$$

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$$\frac{\Gamma \text{ is an environment}}{\Gamma, \alpha \text{ is an environment}} \Gamma \vdash \alpha$$

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Typing rules for \rightarrow

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$$\frac{\Gamma, x:A \vdash M:B}{\Gamma \vdash \lambda x.M : A \rightarrow B} \rightarrow\text{-intro} \qquad \frac{\Gamma \vdash M:A \rightarrow B \quad \Gamma \vdash N:A}{\Gamma \vdash M N : B} \rightarrow\text{-elim}$$

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$$\frac{\Gamma \vdash M : A \quad \bar{\alpha} \cap \text{fv}(\Gamma) = \emptyset \quad \Gamma, x : \forall \bar{\alpha}. A \vdash N : B}{\Gamma \vdash \text{let } x = M \text{ in } N : B} \text{scheme-intro}$$

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$$\frac{x : \forall \bar{\alpha}. A \in \Gamma \quad \Gamma \vdash B \text{ is a type (for } B \in \bar{B})}{\Gamma \vdash x : A[\bar{\alpha} := B]} \text{scheme-elim}$$

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Milner's algorithm

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Substitutions

$[a_1 \mapsto A_1, a_2 \mapsto A_2, \dots, a_n \mapsto A_n]$

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For example, let

σ be $\{a \mapsto B, b \mapsto (B \rightarrow B)\}$

A be $a \mapsto b \mapsto a$

Then

σA is $B \rightarrow (B \rightarrow B) \rightarrow B$.

If

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$\sigma A = B$ (for some σ)

then we say

B is a *substitution instance* of A .

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$a \rightarrow b = \mathcal{B} \rightarrow b$
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$\mathcal{B} = \mathcal{B}$

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$\text{unify} : \text{ConstraintSet} \rightarrow \text{Substitution}$

$$\text{unify}(\emptyset) = []$$

$$\text{unify}(\{A = A\} \cup C) = \text{unify}(C)$$

$$\text{unify}(\{a = A\} \cup C) = \text{unify}([a \mapsto A]C) \circ [a \mapsto A]$$

when $a \notin \text{ftv}(A)$

$$\text{unify}(\{A = a\} \cup C) = \text{unify}([a \mapsto A]C) \circ [a \mapsto A]$$

$$\text{unify}(\{A = B\} \cup C) = \text{unify}([a \mapsto A]C) \circ [a \mapsto A]$$

when $a \notin \text{ftv}(A)$

$$\text{unify}(\{A \rightarrow B = A' \rightarrow B'\} \cup C) = \text{unify}(\{A = A', B = B'\} \cup C)$$

$$\text{unify}(\{A = B\} \cup C) = \text{FAIL}$$

Algorithm J

$J : \text{Environment} \times \text{Expression} \rightarrow \text{Type}$

$J(\Gamma, \lambda x.M) = b \rightarrow A$
where $A = J(\Gamma, x:b, M)$
and b is fresh

$J(\Gamma, x) = A[\bar{\alpha} := \bar{b}]$
where $\Gamma(x) = \forall \bar{\alpha}. A$
and \bar{b} are fresh

$J(\Gamma, M N) = b$
where $A = J(\Gamma, M)$
and $B = J(\Gamma, N)$
and unify $\{A = B \rightarrow b\}$
succeeds
and b is fresh

$J(\Gamma, \text{let } x = M \text{ in } N) = B$
where $A = J(\Gamma, M)$
and $B = J(\Gamma, x:\forall \bar{\alpha}. A, N)$
and $\bar{\alpha} = \text{ftv}(A) \setminus \text{ftv}(\Gamma)$

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Algorithm J in action

```
J(., let apply = λf.λx.f x in  
  let id = λy.y in  
  apply id) =
```

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Algorithm J in action

```
J(., let apply = λf.λx.f x in  
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```

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Algorithm J in action

```
J(., let apply =  $\lambda f.\lambda x.f\ x$  in  
  let id =  $\lambda y.y$  in  
    apply id) =  
J(.,  $\lambda f.\lambda x.f\ x$ ) =  
J(.,  $f:b_1, \lambda x.f\ x$ ) =
```

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Algorithm J in action

```
J(·, let apply = λf.λx.f x in
```

```
  let id = λy.y in
```

```
  apply id) =
```

```
J(·, λf.λx.f x) =  $b_1 \rightarrow b_2 \rightarrow b_3$ 
```

```
J(·, f:b1, λx.f x) =  $b_2 \rightarrow b_3$ 
```

```
J(·, f:b1, x:b2, f x) =  $b_3$ 
```

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Algorithm J in action

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J(·, let apply = λf.λx.f x in
```

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```
J(·, f:b1, λx.f x) =  $b_2 \rightarrow b_3$ 
```

```
J(·, f:b1, x:b2, f x) =  $b_3$ 
```

```
J(·, f:b1, x:b2, f) =
```

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Algorithm J in action

```
J(·, let apply = λf.λx.f x in
```

```
  let id = λy.y in
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```

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J(·, λf.λx.f x) =  $b_1 \rightarrow b_2 \rightarrow b_3$ 
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J(·, f:b1, λx.f x) =  $b_2 \rightarrow b_3$ 
```

```
J(·, f:b1, x:b2, f x) =  $b_3$ 
```

```
J(·, f:b1, x:b2, f) =  $b_1$ 
```

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Algorithm J in action

```
J(·, let apply = λf.λx.f x in
```

```
  let id = λy.y in
```

```
  apply id) =
```

```
J(·, λf.λx.f x) =  $b_1 \rightarrow b_2 \rightarrow b_3$ 
```

```
J(·, f:b1, λx.f x) =  $b_2 \rightarrow b_3$ 
```

```
J(·, f:b1, x:b2, f x) =  $b_3$ 
```

```
J(·, f:b1, x:b2, f) =  $b_1$ 
```

```
J(f:b1, ::b2, x) =
```

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Algorithm J in action

```
J(·, let apply = λf.λx.f x in
```

```
  let id = λy.y in
```

```
  apply id) =
```

```
J(·, λf.λx.f x) =  $b_1 \rightarrow b_2 \rightarrow b_3$ 
```

```
J(·, f:b1, λx.f x) =  $b_2 \rightarrow b_3$ 
```

```
J(·, f:b1, x:b2, f x) =  $b_3$ 
```

```
J(·, f:b1, x:b2, f) =  $b_1$ 
```

```
J(·, f:b1, ::b2, x) =  $b_2$ 
```

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Algorithm J in action

```
J(., let apply = λf.λx.f x in
```

```
  let id = λy.y in
```

```
  apply id) =
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```
J(., λf.λx.f x) =  $b_1 \rightarrow b_2 \rightarrow b_3$ 
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```
J(., f:b1, λx.f x) =  $b_2 \rightarrow b_3$ 
```

```
J(., f:b1, x:b2, f x) =  $b_3$ 
```

```
J(., f:b1, x:b2, f) =  $b_1$ 
```

```
J(., f:b1, ::b2, x) =  $b_2$ 
```

```
unify({ $b_1 = b_2 \rightarrow b_3$ }) =
```

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Algorithm J in action

```
J(., let apply = λf.λx.f x in
```

```
  let id = λy.y in
```

```
  apply id) =
```

```
J(., λf.λx.f x) =  $b_1 \rightarrow b_2 \rightarrow b_3$ 
```

```
J(., f:b1, λx.f x) =  $b_2 \rightarrow b_3$ 
```

```
J(., f:b1, x:b2, f x) =  $b_3$ 
```

```
J(., f:b1, x:b2, f) =  $b_1$ 
```

```
J(., f:b1, ::b2, x) =  $b_2$ 
```

```
unify({ $b_1 = b_2 \rightarrow b_3$ }) = { $b_1 \mapsto b_2 \rightarrow b_3$ }
```

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Algorithm J in action

```
J(., let apply =  $\lambda f.\lambda x.f\ x$  in
```

```
  let id =  $\lambda y.y$  in
```

```
    apply id) =
```

```
J(.,  $\lambda f.\lambda x.f\ x$ ) =  $(b_2 \rightarrow b_3) \mapsto b_2 \rightarrow b_3$ 
```

```
J(.,  $f:b_2 \rightarrow b_3, \lambda x.f\ x$ ) =  $b_2 \rightarrow b_3$ 
```

```
J(.,  $f:b_2 \rightarrow b_3, x:b_2, f\ x$ ) =  $b_3$ 
```

```
J(.,  $f:b_2 \rightarrow b_3, x:b_2, f$ ) =  $b_2 \rightarrow b_3$ 
```

```
J(.,  $f:b_2 \rightarrow b_3, x:b_2, x$ ) =  $b_2$ 
```

```
unify( $\{b_1 = b_2 \rightarrow b_3\}$ ) =  $\{b_1 \mapsto b_2 \rightarrow b_3\}$ 
```

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Algorithm J in action

```
J(., let apply =  $\lambda f.\lambda x.f\ x$  in
  let id =  $\lambda y.y$  in
  apply id) =  $(b_2 \rightarrow b_3) \rightarrow b_2 \rightarrow b_3$ 
J(.,  $\lambda f:\mathcal{b}_2 \rightarrow \mathcal{b}_3.\lambda x.f\ x$ ) =  $\mathcal{b}_2 \rightarrow \mathcal{b}_3$ 
J(.,  $f:\mathcal{b}_2 \rightarrow \mathcal{b}_3, x:\mathcal{b}_2, f\ x$ ) =  $\mathcal{b}_3$ 
J(.,  $f:\mathcal{b}_2 \rightarrow \mathcal{b}_3, x:\mathcal{b}_2, f$ ) =  $\mathcal{b}_2 \rightarrow \mathcal{b}_3$ 
J(.,  $f:\mathcal{b}_2 \rightarrow \mathcal{b}_3, x:\mathcal{b}_2, x$ ) =  $\mathcal{b}_2$ 
ftv( $((\mathcal{b}_2 \rightarrow \mathcal{b}_3) \rightarrow \mathcal{b}_2 \rightarrow \mathcal{b}_3)$ ) =  $\{\mathcal{b}_2, \mathcal{b}_3\}$ 
ftv(.) =  $\{\}$ 
 $\{\mathcal{b}_2, \mathcal{b}_3\} \setminus \{\}$  =  $\{\mathcal{b}_2, \mathcal{b}_3\}$ 
```

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Algorithm J in action

```
J(·, let apply = λf.λx.f x in  
  let id = λy.y in  
  apply id) =  
J(·, λf.λx.f x) =  $(b_2 \rightarrow b_3) \rightarrow b_2 \rightarrow b_3$   
J(·, apply:  $\forall \alpha_2 \alpha_3. (\alpha_2 \rightarrow \alpha_3) \rightarrow \alpha_2 \rightarrow \alpha_3$ ,  
  let id = λy.y in apply id) =
```

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Algorithm J in action

```
J(., let apply =  $\lambda f.\lambda x.f\ x$  in  
  let id =  $\lambda y.y$  in  
  apply id) =  
 $J(., \lambda f.\lambda x.f\ x) = (b_2 \rightarrow b_3) \rightarrow b_2 \rightarrow b_3$   
J(., apply:  $\forall \alpha_2 \alpha_3. (\alpha_2 \rightarrow \alpha_3) \rightarrow \alpha_2 \rightarrow \alpha_3$ ,  
  let id =  $\lambda y.y$  in apply id) =  
J(., apply:  $\forall \alpha_2 \alpha_3. (\alpha_2 \rightarrow \alpha_3) \rightarrow \alpha_2 \rightarrow \alpha_3$ ,  
   $\lambda y.y$ ) =
```

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Algorithm J in action

```
J(., let apply =  $\lambda f.\lambda x.f\ x$  in
  let id =  $\lambda y.y$  in
  apply id) =
J(.,  $\lambda f.\lambda x.f\ x$ ) =  $(b_2 \rightarrow b_3) \rightarrow b_2 \rightarrow b_3$ 
J(., apply:  $\forall \alpha_2 \alpha_3. (\alpha_2 \rightarrow \alpha_3) \rightarrow \alpha_2 \rightarrow \alpha_3$ ,
  let id =  $\lambda y.y$  in apply id) =
J(., apply:  $\forall \alpha_2 \alpha_3. (\alpha_2 \rightarrow \alpha_3) \rightarrow \alpha_2 \rightarrow \alpha_3$ ,
   $\lambda y.y$ ) =  $b_4 \rightarrow b_4$ 
J(., apply:  $\forall \alpha_2 \alpha_3. (\alpha_2 \rightarrow \alpha_3) \rightarrow \alpha_2 \rightarrow \alpha_3$ ,  $y: b_4$ ,  $y$ )
  =  $b_4$ 
```

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Algorithm J in action

```
J(·, let apply = λf.λx.f x in
  let id = λy.y in
  apply id) =
  J(·, λf.λx.f x) = (b2 → b3) → b2 → b3
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
  let id = λy.y in apply id) =
  J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
    λy.y) = b4 → b4
ftv(b4 → b4) = {b4}
ftv(·, apply:∀α2α3.(α2 → α3) → α2 → α3) = {}
{b4} \ {} = {b4}
```

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Algorithm J in action

```
J(·, let apply = λf.λx.f x in
  let id = λy.y in
  apply id) =
J(·, λf.λx.f x) = (b2 → b3) → b2 → b3
J(·, apply:∀α2α3. (α2 → α3) → α2 → α3,
  let id = λy.y in apply id) =
J(·, apply:∀α2α3. (α2 → α3) → α2 → α3,
  λy.y) = b4 → b4
J(·, apply:∀α2α3. (α2 → α3) → α2 → α3, id:∀α4. α4 → α4,
  apply id) = b5
```

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Algorithm J in action

```
J(·, let apply = λf.λx.f x in  
  let id = λy.y in  
    apply id) =
```

```
λf.λx.f x = (b2 → b3) → b2 → b3
```

```
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
```

```
  let id = λy.y in apply id) =
```

```
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
```

```
  λy.y) = b4 → b4
```

```
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3, id:∀α4.α4 → α4,
```

```
  apply id) = b5
```

```
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
```

```
  id:∀α4.α4 → α4, apply)
```

```
= (b6 → b7) → b6 → b7
```

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Algorithm J in action

```
J(·, let apply = λf.λx.f x in
  let id = λy.y in
    apply id) =
  J(·, λf.λx.f x) = (b2 → b3) → b2 → b3
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
  let id = λy.y in apply id) =
  J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
    λy.y) = b4 → b4
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3, id:∀α4.α4 → α4,
  apply id) = b5
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
  id:∀α4.α4 → α4, apply)
= (b6 → b7) → b6 → b7
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
  id:∀α4.α4 → α4, id)
= b8 → b8
```

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$$\text{unify}(\{(b_6 \rightarrow b_7) \rightarrow b_6 \rightarrow b_7 = (b_8 \rightarrow b_8) \rightarrow b_5\})$$
$$= \text{unify}(\{b_6 \rightarrow b_7 = b_8 \rightarrow b_8,$$
$$b_6 \rightarrow b_7 = b_5\})$$

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```
unify ({(b6 → b7) → b6 → b7 = (b8 → b8) → b5})  
= unify ({b6 → b7 = b8 → b8,  
          b6 → b7 = b5})
```

```
= unify ({b6 = b8,  
          b7 = b8,  
          b6 → b7 = b5})
```

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```
unify ({(b6 → b7) → b6 → b7 = (b8 → b8) → b5})  
= unify ({b6 → b7 = b8 → b8,  
          b6 → b7 = b5})
```

```
= unify ({b6 = b8,  
          b7 = b8,  
          b6 → b7 = b5})
```

```
= {b6 ↦ b8, b7 ↦ b8, b5 ↦ b6 → b7}
```

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Algorithm J in action

```
J(·, let apply = λf.λx.f x in
  let id = λy.y in
    apply id) =
  J(·, λf.λx.f x) = (b2 → b3) → b2 → b3
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
  let id = λy.y in apply id) =
  J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
    λy.y) = b4 → b4
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3, id:∀α4.α4 → α4,
  apply id) = b5
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
  id:∀α4.α4 → α4, apply)
= (b6 → b7) → b6 → b7
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
  id:∀α4.α4 → α4, id)
= b8 → b8
```

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Algorithm J in action

```
J(·, let apply = λf.λx.f x in
  let id = λy.y in
    apply id) =
  J(·, λf.λx.f x) = (b2 → b3) → b2 → b3
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
  let id = λy.y in apply id) =
  J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
    λy.y) = b4 → b4
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3, id:∀α4.α4 → α4,
  apply id) = b8 → b8
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
  id:∀α4.α4 → α4, apply)
= (b8 → b8) → b8 → b8
J(·, apply:∀α2α3.(α2 → α3) → α2 → α3,
  id:∀α4.α4 → α4, id)
= b8 → b8
```

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Algorithm J in action

```
J(·, let apply = λf.λx.f x in  
  let id = λy.y in  
    apply id) =
```

```
λf.λx.f x = (b2 → b3) → b2 → b3
```

```
J(·, apply: ∀α2α3. (α2 → α3) → α2 → α3,
```

```
let id = λy.y in apply id) =
```

```
J(·, apply: ∀α2α3. (α2 → α3) → α2 → α3,
```

```
λy.y) = b4 → b4
```

```
J(·, apply: ∀α2α3. (α2 → α3) → α2 → α3, id: ∀α4α1. α4 → α4,
```

```
apply id) = b8 → b8
```

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Algorithm J in action

```
J(·, let apply = λf.λx.f x in
```

```
  let id = λy.y in
```

```
    apply id) =  
J(·, λf.λx.f x) =  $(b_2 \rightarrow b_3) \rightarrow b_2 \rightarrow b_3$ 
```

```
J(·, apply:  $\forall \alpha_2 \alpha_3. (\alpha_2 \rightarrow \alpha_3) \rightarrow \alpha_2 \rightarrow \alpha_3$ ,
```

```
  let id = λy.y in apply id) =  $b_8 \rightarrow b_8$ 
```

```
J(·, apply:  $\forall \alpha_2 \alpha_3. (\alpha_2 \rightarrow \alpha_3) \rightarrow \alpha_2 \rightarrow \alpha_3$ , id:  $\forall \alpha_4. \alpha_4 \rightarrow \alpha_4$ ,  
  apply id) =  $b_8 \rightarrow b_8$ 
```

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Algorithm J in action

```
J(·, let apply = λf.λx.f x in  
  let id = λy.y in  
  apply id) = λx.x
```

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Type inference in practice

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$$\frac{\Gamma, x:A \vdash M:A \quad \bar{\alpha} \notin f_v(\Gamma) \quad \Gamma, x:\forall \bar{\alpha}.A \vdash N:B}{\Gamma \vdash \text{let rec } x = M \text{ in } N:B} \text{ let-rec}$$

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Supporting imperative programming: the value restriction

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```
type 'a ref = { mutable contents : 'a }  
val ref : 'a -> 'a ref  
val (!) : 'a ref -> 'a  
val (:=) : 'a ref -> 'a -> unit
```

```
let r = ref None in  
  r := Some "boom";  
  match !r with  
  | None -> ()  
  | Some f -> f ()
```

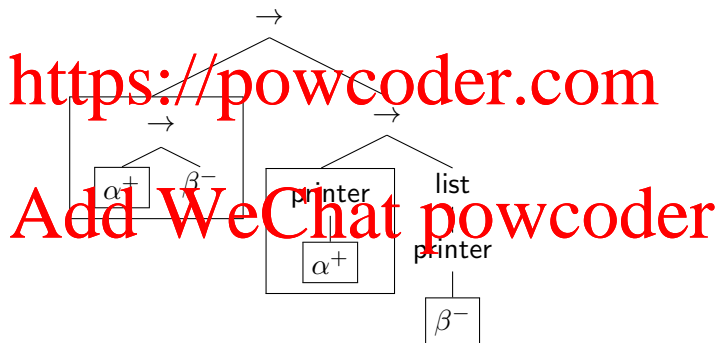
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Relaxing the value restriction: variance

```
type 'a printer = 'a -> string
```

```
(('a -> 'b) -> 'a printer -> 'b printer) list
```



Relaxing the value restriction: the rules

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Should we generalize?

- ▶ covariant type variables
- ▶ invariant type variables
- ▶ contravariant type variables
- ▶ bivariant type variables

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Relaxing the value restriction: the rules

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Should we generalize?

- ▶ covariant type variables ✓
- ▶ invariant type variables
- ▶ contravariant type variables
- ▶ bivariant type variables

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Relaxing the value restriction: the rules

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Should we generalize?

- ▶ covariant type variables ✓
- ▶ invariant type variables ✗
- ▶ contravariant type variables
- ▶ bivariant type variables

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Assignment Project Exam Help

Should we generalize?

- ▶ covariant type variables ✓
- ▶ invariant type variables ✗
- ▶ contravariant type variables ✗
- ▶ bivariant type variables

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Relaxing the value restriction: the rules

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Should we generalize?

- ▶ covariant type variables ✓
- ▶ invariant type variables ✗
- ▶ contravariant type variables ✗
- ▶ bivariant type variables ✓

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Next time

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$$\frac{\Gamma \vdash M : A \rightarrow B \quad \Gamma \vdash N : A}{\Gamma \vdash M N : B}$$

$$\frac{\Gamma \vdash A \rightarrow B \quad \Gamma \vdash A}{\Gamma \vdash B}$$

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