

Computer Architecture and Low Level Programming

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Outline

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□ x86 Assembly

- Why use assembly?

- Basic concepts

- Different ways of using assembly

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Main reasons for using assembly nowadays

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- Understand how hardware works
 - ▣ This way, we can write more efficient software in terms of execution time, memory size, energy consumption and security
 - ▣ Reverse engineering to identify software flaws
- Making compilers, hardware drivers, processors
- Optimization
 - ▣ execution time
 - ▣ memory size
 - ▣ energy consumption

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Main reasons for NOT writing assembly nowadays

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- Development time

- Reliability and security

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- Debugging

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- Maintainability

- Portability

X86, X64 and IA-32

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- What is **x86** and what **x64**?
 - **x86** is an Intel CPU architecture that originated with the 16-bit 8086 processor in 1978.
 - Today, the term "**x86**" is used generally to refer to any 32-bit processor compatible with the **x86** instruction set
 - **IA-32** (short for "Intel Architecture, 32-bit", sometimes also called i386 is the 32-bit version of the **x86** instruction set architecture
 - **x86-64** or x64 is the general name of a series of 64-bit processors and their associated instruction set architecture. These processors are compatible with **x86**.
- What 32bit mean?
 - 32bit Data/address bus, registers, ...

Introduction to x86 Assembly Programming

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- There are many different assemblers out there: MASM, NASM, GAS, AS86, TASM, A86, Terse, etc. All use radically different assembly languages.
- There are differences in the way you have to code for Linux, Windows, etc.
- GNU Assembler (GAS)
 - ▣ AT&T syntax for writing the assembly language
- Microsoft Macro Assembler (MASM)
- Netwide Assembler (NASM)

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Pillars of assembly language

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- Reserved words

- Identifiers

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- Directives

- Sections (or segments) <https://powcoder.com>

- Instructions Add WeChat powcoder

Reserved Words

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- Predefined purpose, e.g. mov is a reserved word and an instruction

- These cannot be used in any other way, e.g. for variable names

- **Case-insensitive:** Mov \equiv mov \equiv MOV

MASM
<pre>.386 .MODEL FLAT, stdcall .STACK 4096 ExitProcess PROTO, dwExitCode:DWORD .data sum DWORD 0 .code _main PROC mov eax, 25 mov ebx, 50 add eax, ebx mov sum, eax INVOKE ExitProcess, 0 _main ENDP END</pre>

Identifiers

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- **Programmer defined names given to items** such as variables, constants and procedures
- Length is limited to 247 characters
- Must begin with a letter (A-Z, a-z), underscore, question mark (?), at symbol (@) or dollar symbol (\$)
- Please do not use: question mark (?), at symbol (@) or dollar symbol (\$)
- Use camelCase for variables, e.g. sumOfProducts
- Use CamelCase for procedures, e.g. ExitProcess
- Use CONSTANT NAME for constants, e.g. GRAVITATIONAL ACCELERATION

MASM
.386 .MODEL FLAT, stdcall .STACK 4096 ExitProcess PROTO, dwExitCode:DWORD .data sum DWORD 0 .code _main PROC mov eax, 25 mov ebx, 50 add eax, ebx mov sum, eax INVOKE ExitProcess, 0 _main ENDP END

Directives

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- ❑ **Assembler specific commands: direct the assembler to do something**

- ❑ Example: ask the assembler to reserve 32-bit memory with literal value 42 in a variable called *answer* with **DWORD** directive. Code: *answer* **DWORD** 42

- ❑ **Other useful directives:**

- ❑ **.386** Enables 80386 processor instructions
- ❑ **.model** Sets the memory model. FLAT for 32-bit instructions, and stdcall for assembly instructions
- ❑ **.stack** Sets the size of the stack memory segment for the program

MASM
<pre>.386 .MODEL FLAT, stdcall .STACK 4096 ExitProcess PROTO, dwExitCode:DWORD .data sum DWORD 0 .code _main PROC mov eax, 25 mov ebx, 50 add eax, ebx mov sum, eax INVOKE ExitProcess, 0 _main ENDP END</pre>

Program sections (or segments)

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- Special sections pre-defined by the assembler
- Common segments:
 - ▣ **.data** uninitialised and initialised variables
 - ▣ **.code** executable code and instructions

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MASM
<pre>.386 .MODEL FLAT, stdcall STACK 4096 ExitProcess PROTO, dwExitCode:DWORD .data sum DWORD 0 .code _main PROC mov eax, 25 mov ebx, 50 add eax, ebx mov sum, eax INVOKE ExitProcess, 0 _main ENDP END</pre>

Instructions

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- ❑ **Executable statements in a program**
- ❑ **Two basic parts:** *mnemonic* and *[operands]*
- ❑ *Mnemonic* is the instruction name as defined in the architecture's instruction sets
- ❑ Some do not require operands, some one or more
- ❑ Common code examples:
 - ❑ `stc` no operands sets the carry flag `inc eax` increment `eax` by one
 - ❑ `mov eax, 5` moves literal value 5 to `eax` register

MASM
<code>.386</code>
<code>.MODEL FLAT, stdcall</code>
<code>.STACK 4096</code>
<code>ExitProcess PROTO,</code> <code>dwExitCode:DWORD</code>
<code>.data</code>
<code>sum DWORD 0</code>
<code>main PROC</code>
<code>mov eax, 25</code>
<code>mov ebx, 50</code>
<code>add eax, ebx</code>
<code>mov sum, eax</code>
<code>INVOKE ExitProcess, 0</code>
<code>_main ENDP</code>
<code>END</code>

Label:

Mnemonic

Operand(s)

;Comment

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```
0FFFF0342h ; the actual value is FFFF0342 in hexadecimal
```

"I don't understand contractions."	; strings that have one
'"Good job," said the father to his son.'	; type of quotes on the
	; outside and a different
	; type on the inside

String Literals

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String Characters	D	a	i	s	y	,		d	a	i	s	y
ASCII Decimal Values	68	97	105	115	121	44	32	100	97	105	115	121

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; motd contains a single-line string

motd BYTE "Welcome to Earth C.I.T."

; motd2 contains a multi-line string with a newline at the end

motd2 BYTE "Thank you for using our system.",0Dh,0Ah

BYTE "All of your activity will be monitored"

BYTE "by our system administrators",0Dh,0Ah,0

- Stored as Byte array, each character occupies one byte
- Must end with '0'
- Carriage return: '0Dh'
- Line-feed: '0Ah'

Data Types

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- BYTE – 8bit unsigned integer
- SBYTE – 8bit signed integer
- WORD - 16bit unsigned integer
- SWORD - 16bit signed integer
- DWORD - 32bit unsigned integer
- SDWORD - 32bit signed integer
- QWORD – 64bit unsigned integer
- REAL4 – single precision floating point numbers (32bit)
- REAL8 - double precision floating point numbers (64bit)

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Variables

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```
charInput    BYTE 'A'  
myArray      DWORD 41h, 75, 0C4h, 01010101b
```

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```
.data  
num DWORD 6 ; defines an initialized identifier  
sum SDWORD ? ; defines an uninitialized identifier  
myArray BYTE 10 DUP (1) ; defines an array of initialized bytes  
myUArray BYTE 10 DUP (?) ; defines an array of uninitialized bytes
```

myArray BYTE 10 DUP (1) ; duplicates 1 into the 10-bytes

Storage methods:

Little Endian vs Big Endian

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- x86 and x86 64 typically use *Little-Endian*, i.e., **all the bytes are stored in reverse order** (the bits inside a bit are stored normally)
- Store 12345678₁₆ in memory

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Big-Endian

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Little-Endian

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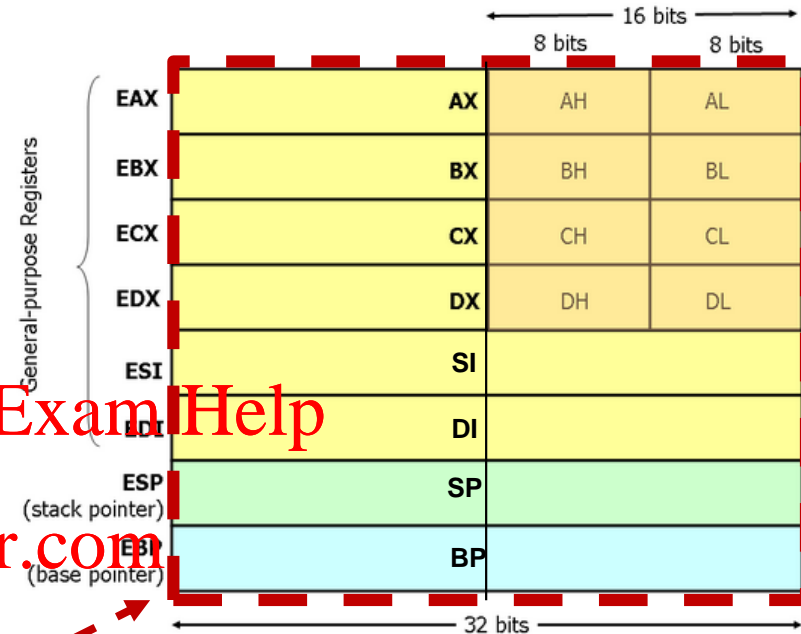
Memory Address	Data
0x00000000	12
0x00000008	34
0x00000010	56
0x00000018	78

Memory Address	Data
0x00000000	78
0x00000008	56
0x00000010	34
0x00000018	12


Registers (1)

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- The lower bytes of some of these registers may be accessed independently as 32, 16 or 8-bit registers
- Older processors use 8-bit, 16-bit or 32-bit registers only – compatibility exists
- There are other registers too... (next slide)



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General purpose registers				Segment registers			
64-bit	32-bit	16-bit		64-bit	32-bit	16-bit	
RAX	EAX	AX		N/A	CS	CS	
RBX	EBX	BX		DS	DS		
RCX	ECX	CX		ES	ES		
RDX	EDX	DX		SS	SS		
RSI	ESI	SI		FS			
RDI	EDI	DI		GS			
RBP	EBP	BP					
RSP	ESP	SP					
R8 – R15							
				Instruction pointer	RIP	EIP	IP
				Flags register	RFLAGS	EFLAGS	FLAGS

Registers (2)

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- **There are also eight 80bit floating point registers**
 - ▣ ST(0)-ST(7), arranged as a stack
- **Eight 64bit MMX vector registers**
 - ▣ Used with MMX instructions (physically they are the same as above)
- **Eight/Sixteen 128/256/512 bit vector registers**
 - ▣ 128bit use SSE instructions
 - ▣ 256bit use AVX instructions
 - ▣ 512bit use AVX2 instructions

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Registers (3)

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- **rax/eax**: Default accumulator register.
 - ▣ Used for arithmetical operations
 - ▣ Function calls place return value.
 - ▣ Do not use it for data storage while performing such operations.
- **rcx/ecx**: Hold loop counter. Do not overwrite when looping!
- **rbp/ebp**: Reference data on the stack; more on this later.
- **rsp/esp**: Used for managing the stack – typically points to the top of the stack.
- **rsi/esi** and **rdi/edi**: Index registers used in string operations.
- **rip/eip**: Instruction pointer - shows next instruction to be executed
- **rflags/eflags**: Status and control registers; cannot be modified directly!

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Notations

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L A literal value (e.g. 42)

M A memory (variable) operand (e.g. numOfStudents)

R A register (e.g. eax)

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- If you see a number followed by one of these notations, it represents the size of the notation. For instance, L8 means that it is a 8-bit literal value.
- If multiple notations appear segregated by a slash ('/'), it means that either of these two types may be used. For example, M/R means that either a memory type of a register may be used.

Data movement

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- **mov** `eax, sum` ; `mov M/R, L/M/R` (moving)
- **xchg** `eax, sum` ; `xchg M/R, M/R` (swapping)

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- For moving data: <https://powcoder.com>
 - ▣ Both operands must be the same size.
 - ▣ Both operands cannot be memory operands (must use a register as an intermediary).

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Addition and subtraction

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- **inc** *sum* ; *inc M/R* (increment by one)
 - **dec** *sum* ; *dec M/R* (decrement by one)
 - **add** *eax, sum* ; *add M/R, I/M/R* (addition)
 - **sub** *eax, val* ; *sub M/R, I/M/R* (subtraction)
 - **neg** *sum* ; *neg M/R* (negate: 2's complement), this operation is equivalent to subtracting the operand from 0
- <https://powcoder.com>
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- In MASM, for addition and subtraction, the second component is added/subtracted from the first component, and the result is stored back into the first component.
 - In AT&T the exact opposite

MUL (unsigned multiply)

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$2 \times 3 = 6$

Multiplier	Multiplicand	Product
M8/R8 al	al	ax
M16/R16 ax	ax	dx:ax
M32/R32 eax	eax	edx:eax
M64/R64 rax	rax	rdx:rax

- Multiplication may require more bytes to hold the results. Consider the following 2-bit multiplicand 310 (112) and 2-bit multiplier 310 (112). The product is 910 (10012), and it cannot be contained in 2-bits; it requires 4-bits. At most we require double the size of the multiplier or the multiplicand.
- Also, note that the parts of the product are saved in *high:low* format.

MUL - example

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$2 \times 3 = 6$

Multiplier	Multiplicand	Product
16/32	ax	dx:ax
M16/R16	ax	dx:ax
M32/R32	eax	edx:eax
M64/R64	rax	rdx:rax

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```
.data
var1 WORD 3000h
var2 WORD 100h
```

```
.code ; 16bit multiplication
mov ax,var1
mul var2 ; DX:AX = 00300000h, CF=1
```

CF=1 as DX contains non zero data

```
.data
var1 DWORD 3000h
var2 DWORD 100h
```

```
.code ; 32bit multiplication
mov eax,var1
mul var2 ; EDX:EAX = 0000000000300000h, CF=0
```

CF=0 as EDX is zero

IMUL – signed multiply

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- **imul** is similar to **mul**
- However:
 - ▣ It preserves the sign of the product by sign-extending it into the upper half of the destination register
 - ▣ It sets OF flag to '1' when the less significant register cannot store the result (including its sign)

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```
.data
var1 BYTE 48 ; this is decimal
var2 BYTE 4 ; this is decimal

.code ; 8bit multiplication
mov al,var1
mul var2 ; AH:AL = 00C0h, OF=1
```

OF=1 as 8bits are not enough to hold the signed number $C0_{16}$ (01100000_2). A '0' is needed in AH to hold the sign

DIV (Unsigned Divide)

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Divisor	Dividend	Quotient	Remainder
M8/R8	ax	al	ah
M16/R16	dx:ax	ax	dx
M32/R32	edx:eax	eax	edx
M64/R64	rdx:rax	rax	rdx

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.code ; **16bit division**

```
mov dx,0h          ; clear dividend, high
mov ax,8003h       ; dividend, low
mov cx,100h        ; divisor
div cx              ; AX = 0080h, DX = 3
```

.code ; **32bit division**

```
mov edx,0          ; clear dividend, high
mov eax,8003h      ; dividend, low
mov ecx,100h       ; divisor
div ecx             ; EAX = 0000 0080h, EDX = 3
```

Different Ways of writing Assembly

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- There are 3 ways to write assembly

- ▣ **Use Assembler**

- It hard and time consuming
- Best choice regarding performance

- ▣ **Inline assembly (normally in C/C++)**

- Very good choice regarding performance
- However, different compilers use different syntax.

- ▣ **Use Intrinsic from C/C++ as it is the most compatible language with assembly**

- Much easier, no need to know assembly and deal with hardware details
- Portable
- Not all assembly instructions supported