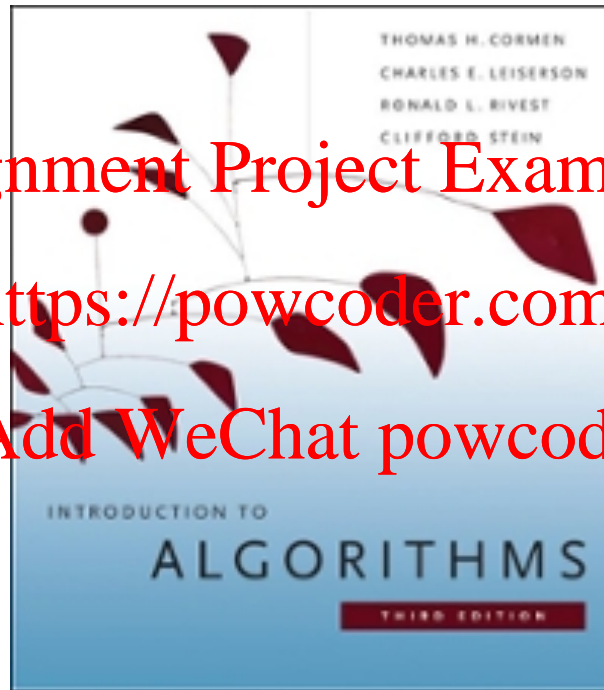


# CS146 Data Structures and Algorithms

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## Chapter 7: Quicksort

# Quicksort

- Sorts in place
- Sorts  $O(n \lg n)$  in the average case
- Sorts  $O(n^2)$  in the worst case
  - But in practice, it's quick
  - And the worst case doesn't happen often (but more on this later...)
  - Empirical and analytical studies show that quicksort can be *expected* to be twice as fast as its competitors.

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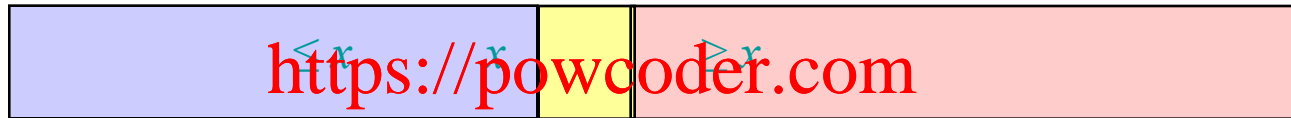
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# 7.1 Description of Quicksort

Quicksort an  $n$ -element array:

- *Divide*: Partition the array into two subarrays around a *pivot*  $x$  such that elements in lower subarray  $\leq x$  elements in upper subarray.

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- *Conquer*: Recursively sort the two subarrays.
- *Combine*: The subarrays are sorted in place – no work is needed to combine them.
- How do the divide and combine steps of quicksort compare with those of merge sort?

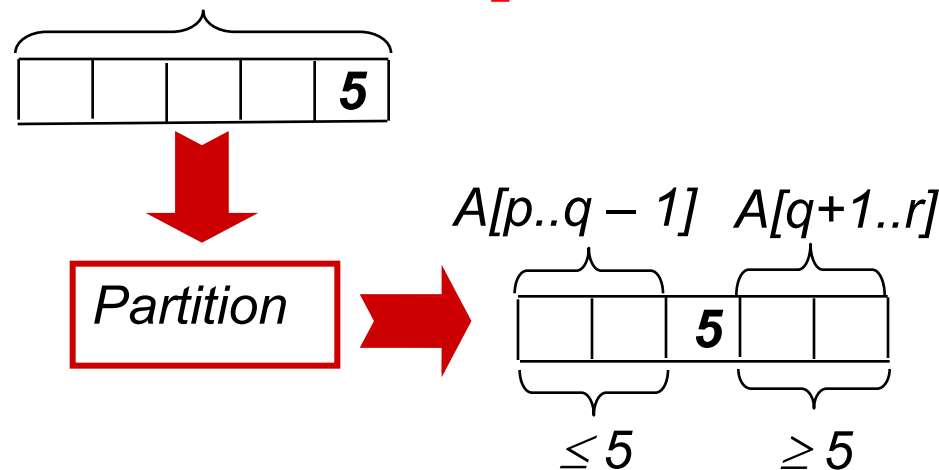
# Design

- **Key:** Linear-time partitioning subroutine.
- **Divide:** Partition (separate) the array  $A[p..r]$  into two (possibly empty) subarrays  $A[p..q-1]$  and  $A[q+1..r]$ .
  - Each element in  $A[p..q-1] \leq A[q]$ .
  - $A[q] \leq$  each element in  $A[q+1..r]$ .
  - Index  $q$  is computed as part of the partitioning procedure.

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QUICKSORT( $A, p, r$ )

1 if  $p < r$

2      $q = \text{PARTITION}(A, p, r)$

3     QUICKSORT( $A, p, q-1$ )

4     QUICKSORT( $A, q+1, r$ )

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*Initial call: QUICKSORT( $A, 1, n$ )*

# Loop Invariant

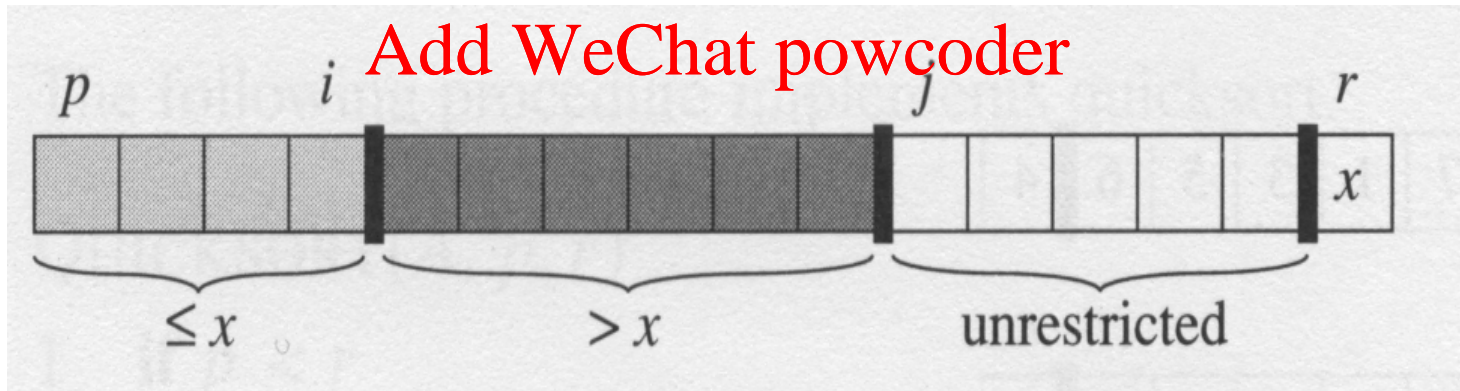
## Loop Invariant

1. All entries in  $A[p..i]$  are  $\leq$  pivot.
2. All entries in  $A[i+1..j-1]$  are  $>$  pivot.
3.  $A[r] = \text{pivot}$ .

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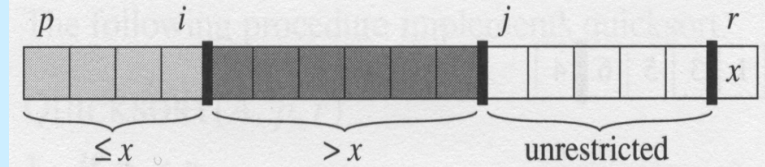
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# Partition(A, p, r)

```
1  x = A[r]
2  i = p - 1
3  for j = p to r - 1
4      if A[j] ≤ x
5          i = i + 1
6          exchange A[i] ↔ A[j]
7  exchange A[i+1] ↔ A[r]
8  return i+1
```

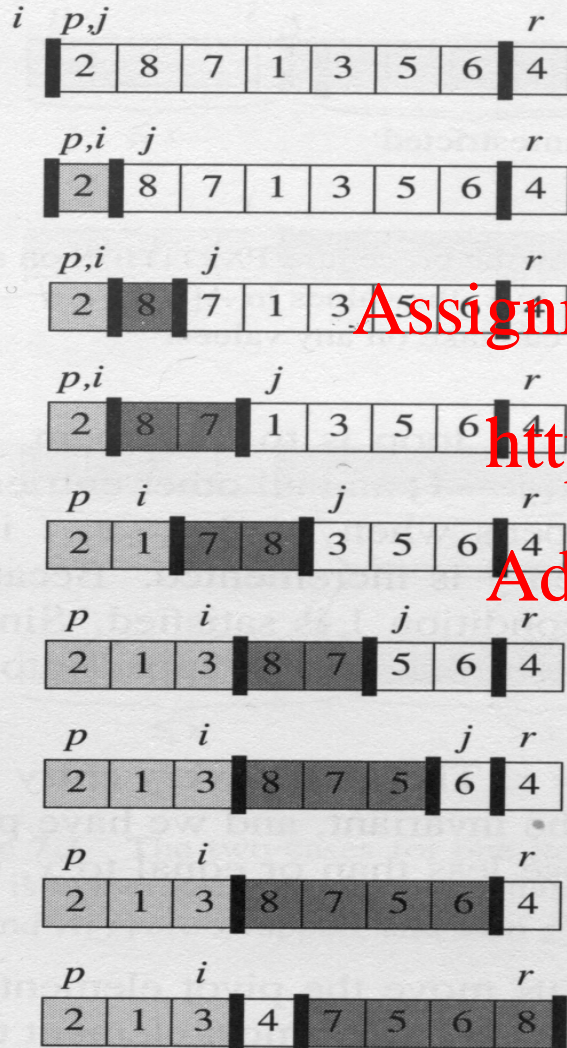


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# The operation of *Partition* on a sample array



```
1  $x = A[r]$ 
```

```
2  $i = p - 1$ 
```

```
3 for  $j = p$  to  $r - 1$ 
```

```
4   if  $A[j] \leq x$ 
```

```
5      $i = i + 1$ 
```

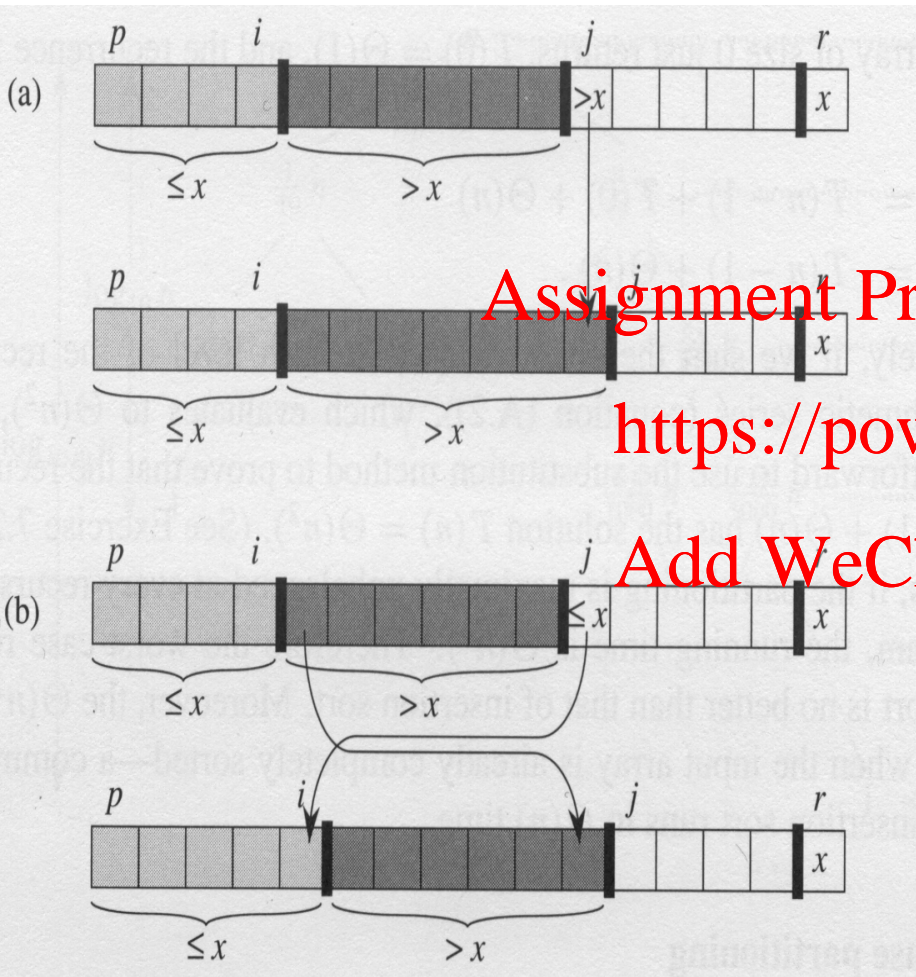
```
6   exchange  $A[i] \leftrightarrow A[j]$ 
```

```
7 exchange  $A[i+1] \leftrightarrow A[r]$ 
```

```
8 return  $i+1$ 
```



# Two cases for one iteration of procedure *Partition*



```

1  x = A[r]
2  i = p - 1
3  for j = p to r - 1
4    if A[j] ≤ x
5      i = i + 1
6    exchange A[i] ↔ A[j]
7  exchange A[i+1] ↔ A[r]
8  return i+1
    
```

**Complexity:**

**Partition on  $A[p \dots r]$  is  $\Theta(n)$**   
where  $n = r - p + 1$

**Why???**  
**(Exercise 7.1-3)**

## Exercise 7.1-3

- Give a brief argument that the running time of PARTITION on a subarray of size  $n$  is  $\Theta(n)$ .

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Answer:

The for loop makes exactly  $r - p$  iterations, each of which takes at most constant time. The part outside the for loop takes at most constant time. Since  $r - p$  is the size of the subarray, PARTITION takes at most time proportional to the size of the subarray it is called on.

# Another partitioning example

initially:

	$p$								$r$	
	2	5	8	3	9	4	1	7	10	6
	$i$	$j$								

note: pivot ( $x$ ) = 6

next iteration:

	2	5	8	3	9	4	1	7	10	6
	$i$	$j$								

next iteration:

	2	5	8	3	9	4	1	7	10	6
	$i$	$j$								

next iteration:

	2	5	8	3	9	4	1	7	10	6
	$i$		$j$							

next iteration:

	2	5	3	8	9	4	1	7	10	6
		$i$		$j$						

```
1 x = A[r]
2 i = p - 1
3 for j = p to r - 1
4   if A[j] ≤ x
5     i = i + 1
6     exchange A[i] ↔ A[j]
7 exchange A[i+1] ↔ A[r]
8 return i+1
```

# Another example (Continued)

next iteration:    2 5 3 8 9 4 1 7 10 6  
                          i        j

next iteration:    2 5 3 8 9 4 1 7 10 6  
                          i        j

next iteration:    2 5 3 4 9 8 1 7 10 6  
                          i        j

next iteration:    2 5 3 4 1 8 9 7 10 6  
                          i        j

next iteration:    2 5 3 4 1 8 9 7 10 6  
                          i                    j

next iteration:    2 5 3 4 1 8 9 7 10 6  
                          i                    j

after final swap:    2 5 3 4 1 6 9 7 10 8  
                          i                    j

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```
1 x = A[r]
2 i = p - 1
3 for j = p to r - 1
4   if A[j] ≤ x
5     i = i + 1
6   exchange A[i] ↔ A[j]
7 exchange A[i+1] ↔ A[r]
8 return i+1
```

# Partitioning

- Select the **last element**  $A[r]$  in the subarray  $A[p..r]$  as the *pivot* – the element around which to partition.
- As the procedure executes, the array is partitioned into four (possibly empty) regions.
  1.  $A[p..i]$  — All entries in this region are  $\leq$  *pivot*.
  2.  $A[i+1..j-1]$  — All entries in this region are  $>$  *pivot*.
  3.  $A[r] = \textit{pivot}$ .
  4.  $A[j..r-1]$  — Not known how they compare to *pivot*.
- The above hold before each iteration of the *for* loop, and constitute a *loop invariant*. (4 is not part of the LI.)

# Correctness of Partition

- Use loop invariant.
- **Initialization:**
  - Before first iteration
    - $A[p..i]$  and  $A[i+1..j-1]$  are empty – Conds. 1 and 2 are satisfied (trivially).
    - $r$  is the index of the *pivot* – Cond. 3 is satisfied.

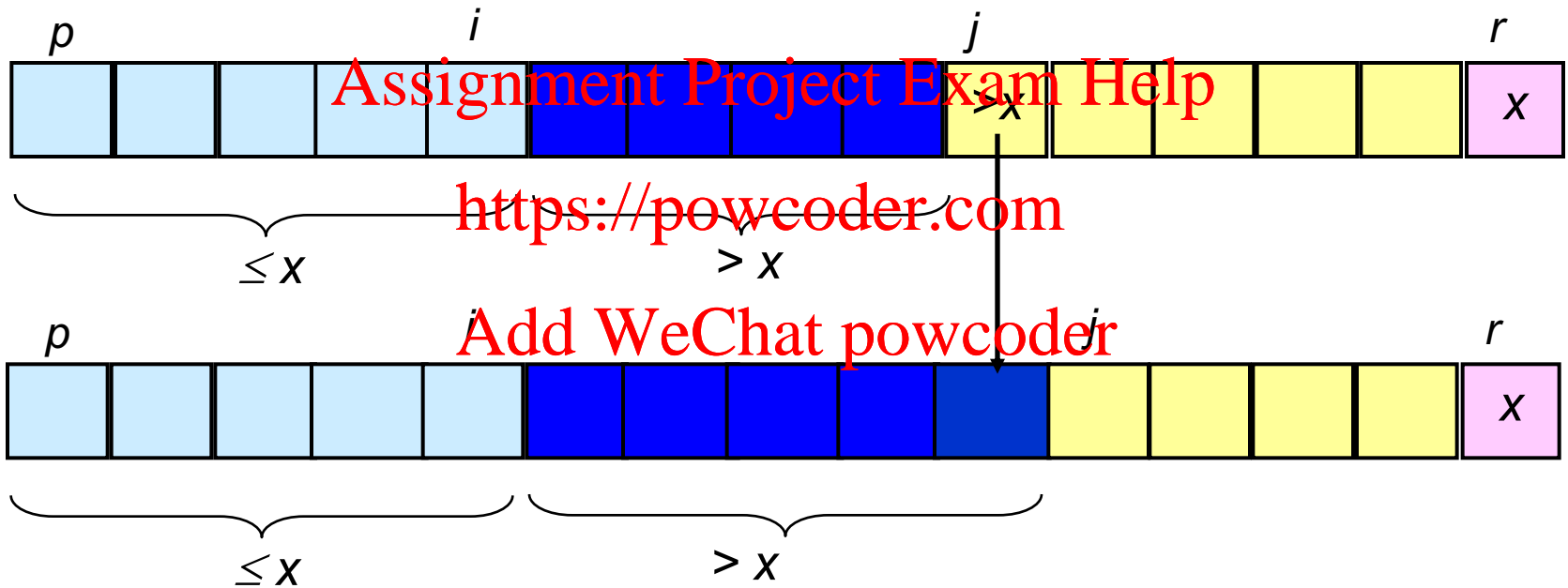
- **Maintenance:**

- Case 1:  $A[j] > x$ 
  - Increment  $j$  only.
  - LI is maintained.

```
1 x = A[r]
2 i = p - 1
3 for j = p to r - 1
4   if A[j] ≤ x
5     i = i + 1
6     exchange A[i] ↔ A[j]
7 exchange A[i+1] ↔ A[r]
8 return i+1
```

# Correctness of Partition

## Case 1:



# Correctness of Partition

- **Case 2:**  $A[j] \leq x$

- Increment  $i$

- Swap  $A[i]$  and  $A[j]$

- Condition 1 is maintained.

- Increment  $j$

- Condition 2 is maintained.

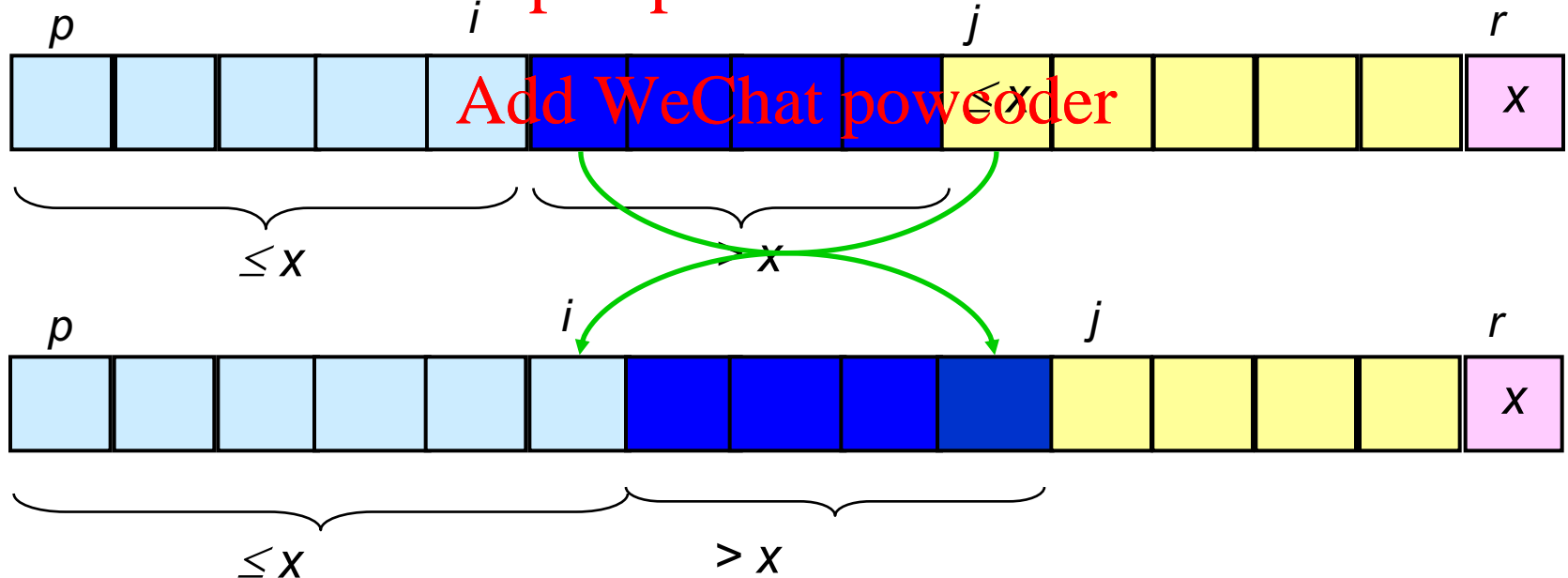
»  $A[r]$  is unaltered.

- Condition 3 is maintained.

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# Correctness of Partition

- Termination:

- When the loop terminates,  $j = r$ , so all elements in  $A$  are partitioned into one of the three cases:

- $A[p..i] \leq \text{pivot}$
- $A[i+1..j-1] > \text{pivot}$
- $A[r] = \text{pivot}$

- The last two lines swap  $A[i+1]$  and  $A[r]$ .

- *Pivot* moves from the end of the array to **between** the two subarrays.
- Thus, procedure *partition* correctly performs the divide step.

# Complexity of Partition

- $\text{PartitionTime}(n)$  is given by the number of iterations in the *for* loop.
- $\Theta(n) : n = r - p + 1.$

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```
1 x = A[r]
2 i = p - 1
3 for j = p to r - 1
4   if A[j] ≤ x
5     i = i + 1
6     exchange A[i] ↔
      A[j]
7 exchange A[i+1] ↔ A[r]
8 return i+1
```

QUICKSORT( $A, p, r$ )

1 if  $p < r$   
2      $q = \text{PARTITION}(A, p, r)$   
3     QUICKSORT( $A, p, q-1$ )  
4     QUICKSORT( $A, q+1, r$ )

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Sorting Animation

*Initial call: QUICKSORT( $A, 1, n$ )*

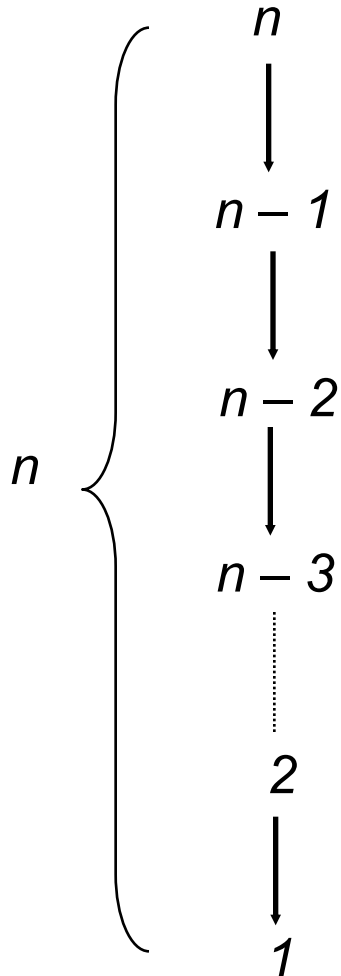
# Algorithm Performance

Running time of quicksort depends on whether the partitioning is balanced or not.

- Worst-Case Partitioning (Unbalanced Partitions):
  - Occurs when every call to partition results in the most unbalanced partition.
  - Partition is most unbalanced when
    - Subarray 1 is of size  $n - 1$ , and subarray 2 is of size 0 or vice versa.
    - $pivot \geq$  every element in  $A[p..r - 1]$  or  $pivot <$  every element in  $A[p..r - 1]$ .
  - Every call to partition is most unbalanced when
    - Array  $A[1..n]$  is sorted or reverse sorted!

# Worst-case Partition Analysis

Recursion tree for  
worst-case partition



Running time for worst-case partitions at  
each recursive level:

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$$T(n) = T(n-1) + T(0) + \text{PartitionTime}(n)$$

$$= T(n-1) + \Theta(n)$$

$$= \sum_{k=1 \text{ to } n} \Theta(k)$$

$$= \Theta\left(\sum_{k=1 \text{ to } n} k\right) = \Theta(n(n+1)/2)$$

$$= \Theta(n^2)$$

# Best-case Partitioning

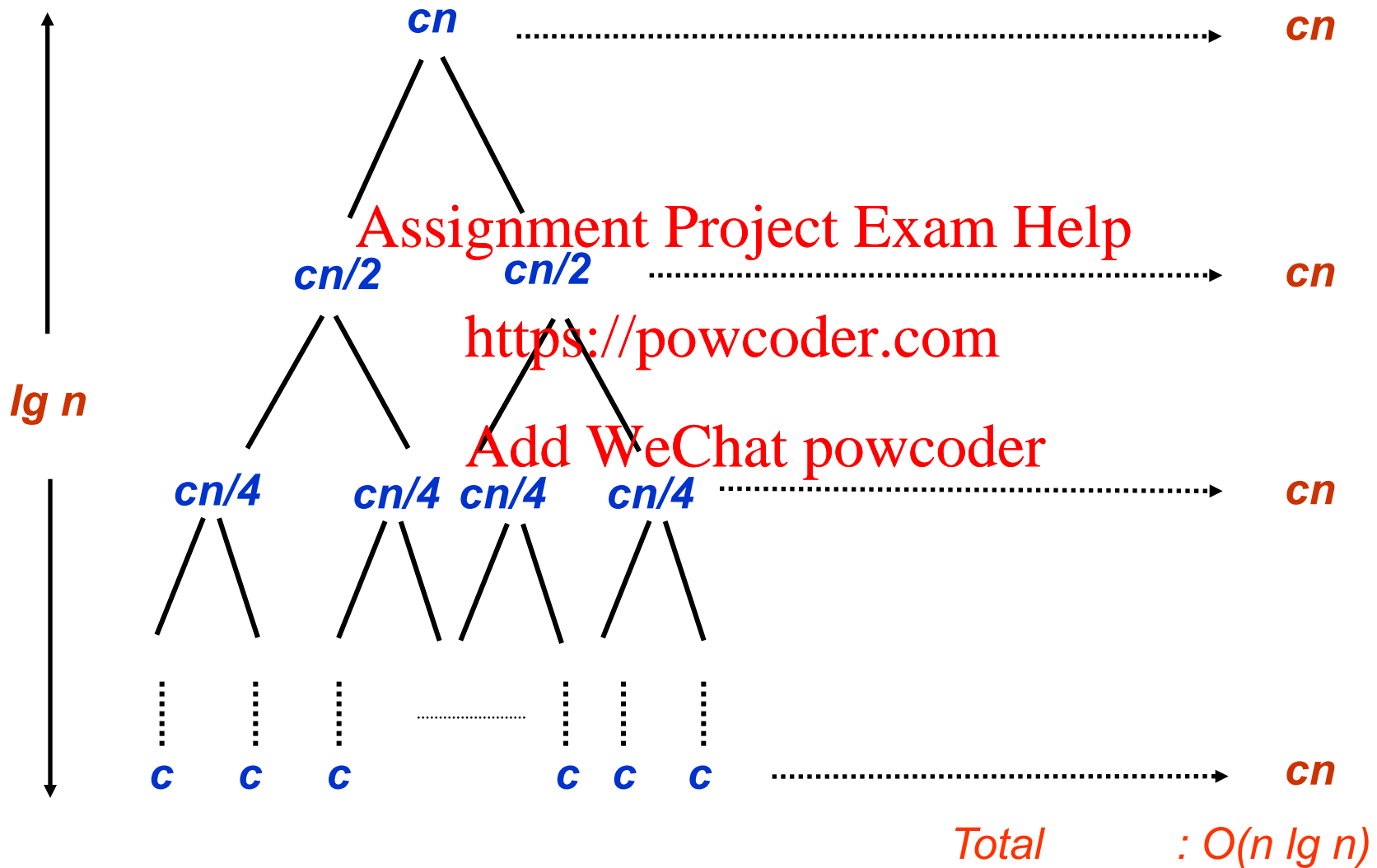
- Size of each subarray  $\leq n/2$ .
  - One of the subarray is of size  $\lfloor n/2 \rfloor$
  - The other is of size  $\lceil n/2 \rceil - 1$ .
- Recurrence for running time
  - $T(n) \leq 2T(n/2) + \text{Partition Time}(n)$   
 $= 2T(n/2) + \Theta(n)$
- $T(n) = \Theta(n \lg n)$

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# Recursion Tree for Best-case Partition



# Variations

- Quicksort is not very efficient on small lists.
- This is a problem because Quicksort will be called on lots of small lists.  
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- **Fix 1:** Use Insertion Sort on small arrays.  
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- **Fix 2:** Leave small arrays unsorted. Fix with one final Insertion Sort at end.
  - **Note:** Insertion Sort is very fast on almost-sorted lists.



# Unbalanced Partition Analysis

What happens if we get poorly-balanced partitions,

e.g., something like:  $T(n) \leq T(9n/10) + T(n/10) + \Theta(n)$ ?

Still get  $\Theta(n \lg n)$ !! (As long as the split is of constant proportionality.)

**Intuition:** Can divide  $n$  by  $c > 1$  only  $\Theta(\lg n)$  times before getting 1.

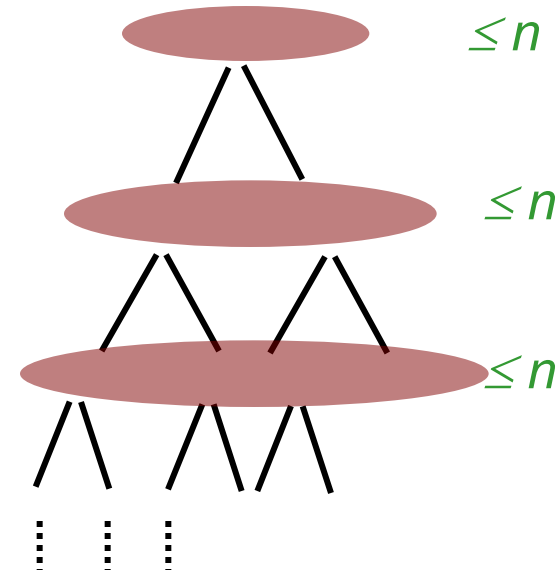
$n$   
 $\downarrow$   
 $n/c$   
 $\downarrow$   
 $n/c^2$   
 $\downarrow$   
 $\vdots$   
 $\downarrow$   
 $1 = n/c^{\log_c n}$

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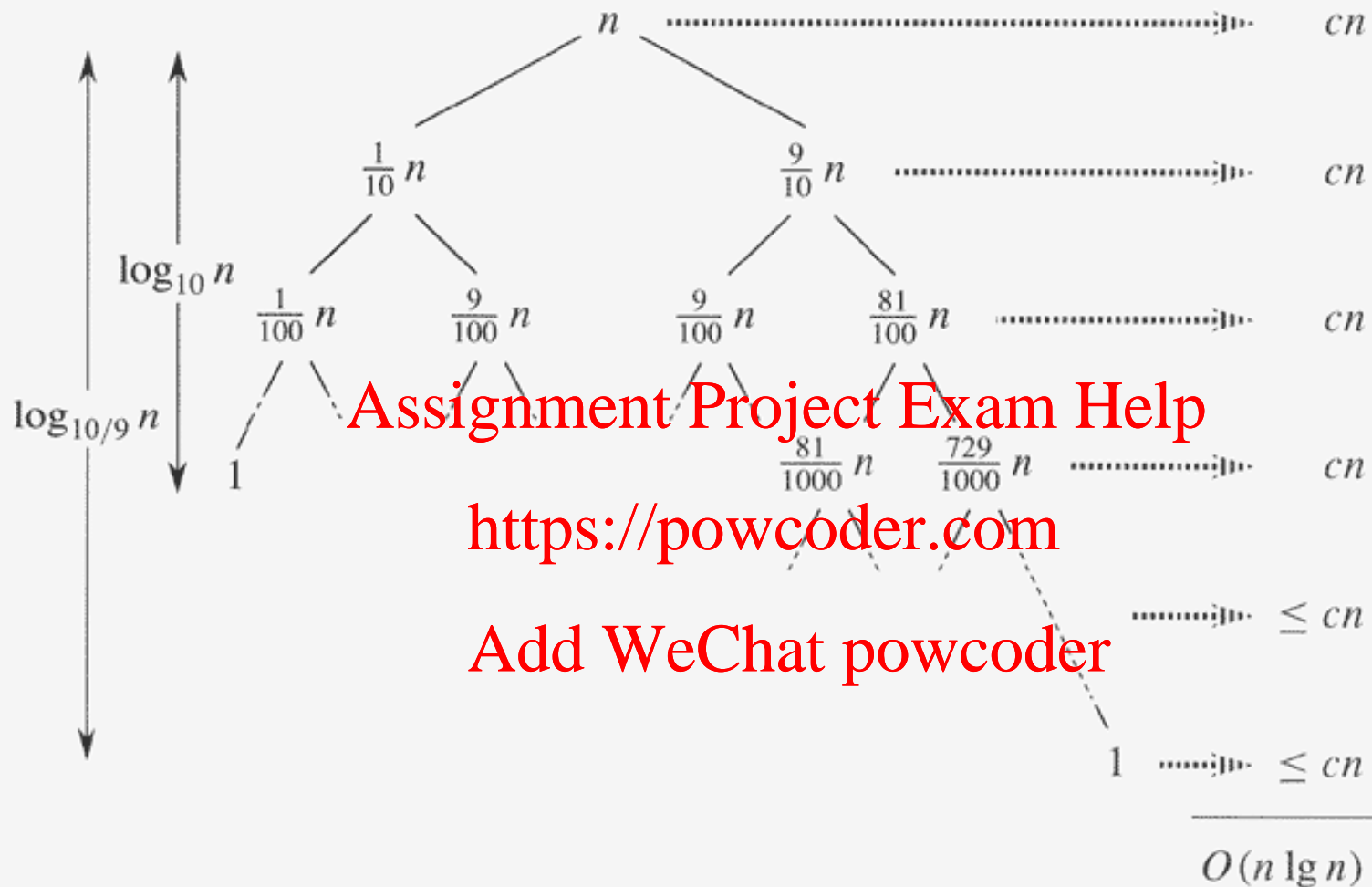
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Roughly  $\lg n$  levels;  
Cost per level is  $O(n)$ .



(**Remember:** Different base logs are related by a constant.)



**Figure 7.4** A recursion tree for QUICKSORT in which PARTITION always produces a 9-to-1 split, yielding a running time of  $O(n \lg n)$ . Nodes show subproblem sizes, with per-level costs on the right. The per-level costs include the constant  $c$  implicit in the  $\Theta(n)$  term.

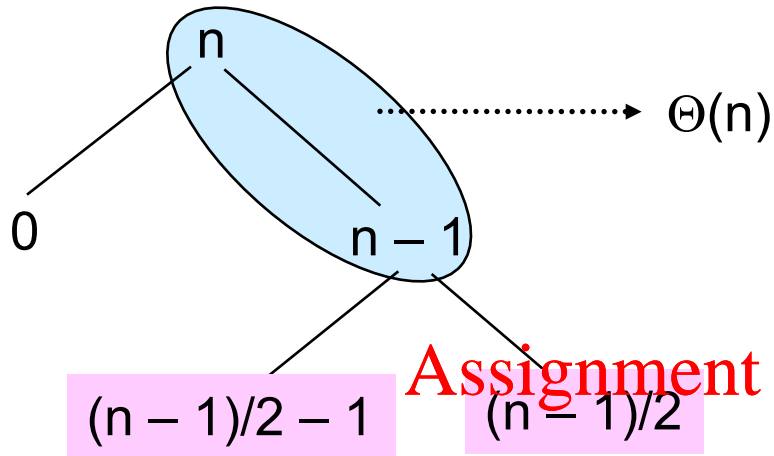
# Intuition for the Average Case

- Partitioning is unlikely to happen in the same way at every level.
  - Split ratio is different for different levels.  
(Contrary to our assumption in the previous slide.)
- Partition produces a mix of “good” and “bad” splits, distributed randomly in the recursion tree.
- What is the running time likely to be in such a case?

# Analyzing Quicksort: Average Case

- Intuitively, a real-life run of quicksort will produce a mix of “bad” and “good” splits
  - Randomly distributed among the recursion tree
  - Pretend for intuition that they alternate between best-case ( $n/2 : n/2$ ) and worst-case ( $n-1 : 1$ )
  - *What happens if we bad-split root node, then good-split the resulting size  $(n-1)$  node?*
    - We end up with three subarrays, size 1,  $(n-1)/2$ ,  $(n-1)/2$
    - Combined cost of splits =  $n + n - 1 = 2n - 1 = O(n)$
    - No worse than if we had good-split the root node!

# Intuition for the Average Case



Bad split followed by a good split:

Produces subarrays of sizes 0,  $(n-1)/2 - 1$ , and  $(n-1)/2$ .

Cost of partitioning :

$$\Theta(n) + \Theta(n-1) = \Theta(n).$$

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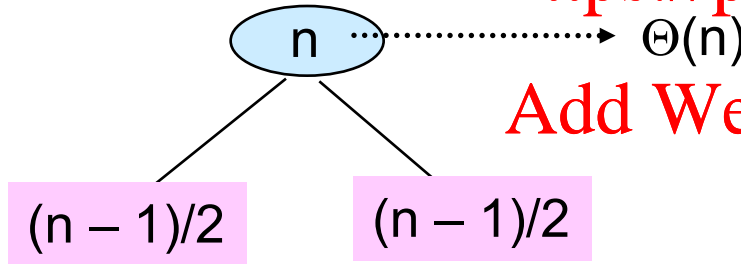
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Good split at the first level:

Produces two subarrays of size  $(n-1)/2$ .

Cost of partitioning :

$$\Theta(n).$$



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Situation at the end of case 1 is not worse than that at the end of case 2. When splits alternate between good and bad, the **cost of bad split can be absorbed into the cost of good split.**

Thus, running time is  $O(n \lg n)$ , though with larger hidden constants.

# Randomized Quicksort

- ♦ Want to make running time independent of input ordering.
- ♦ How can we do that?
  - » Make the algorithm randomized.
  - » Make every possible input equally likely.
    - Can randomly shuffle to permute the entire array.
    - For quicksort, it is sufficient if we can ensure that every element is equally likely to be the pivot.
    - So, we choose an element in  $A[p..r]$  and exchange it with  $A[r]$ .
    - Because the pivot is randomly chosen, we expect the partitioning to be well balanced on average.

# Randomized Version

Want to make running time independent of input ordering.

```
Randomized-Partition(A, p, r)
  i = Random(p, r);
  exchange A[r] = A[i];
  Partition(A, p, r)
```

```
Randomized-Quicksort(A, p, r)
  if p < r
```

```
    q = Randomized-Partition(A, p, r);
    Randomized-Quicksort(A, p, q - 1);
    Randomized-Quicksort(A, q + 1, r)
```

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# 7.4 Analysis of quicksort

## 7.4.1 Worst-case analysis

$$T(n) = \max_{0 \leq q \leq n-1} (T(q) + T(n-q-1)) + \Theta(n)$$

guess  $T(n) \leq cn^2$

$$T(n) \leq \max_{0 \leq q \leq n-1} (cq^2 + c(n-q-1)^2) + \Theta(n)$$

$$= c \max_{0 \leq q \leq n-1} (q^2 + (n-q-1)^2) + \Theta(n)$$

$$\leq cn^2 - 2c(n-1) + \Theta(n)$$

$$\leq cn^2$$

pick the constant  $c$  large enough so that the  $2c(n-1)$  term dominates the  $\Theta(n)$  term.

$$\Rightarrow T(n) = \Theta(n^2)$$



## 7.4.2 Expected running time

- Running time and comparisons
- Lemma 7.1
  - Let  $X$  be the number of comparisons performed in line 4 of *partition* over the entire execution of *Quicksort* on an  $n$ -element array. Then the running time of *Quicksort* is  $O(n+X)$

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we define

$$X_{ij} = I \{z_i \text{ is compared to } z_j\},$$

$$X = \sum_{i=1}^{n-1} \sum_{j=i+1}^n X_{ij}.$$

$$E[X] = E \left[ \sum_{i=1}^{n-1} \sum_{j=i+1}^n X_{ij} \right]$$

$$= \sum_{i=1}^{n-1} \sum_{j=i+1}^n E[X_{ij}]$$

$$= \sum_{i=1}^{n-1} \sum_{j=i+1}^n \Pr \{z_i \text{ is compared to } z_j\}$$

$$\Pr\{z_i \text{ is compared to } z_j\} = \Pr\{z_i \text{ or } z_j \text{ is first pivot chosen from } Z_{ij}\}$$

$$= \Pr\{z_i \text{ is first pivot chosen from } Z_{ij}\} + \Pr\{z_j \text{ is first pivot chosen from } Z_{ij}\}$$

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$$= \frac{1}{j-i+1} + \frac{1}{j-i+1} = \frac{2}{j-i+1}$$

$$\therefore E[X] = \sum_{i=1}^{n-1} \sum_{j=i+1}^n \frac{2}{j-i+1}.$$

$$E[X] = \sum_{i=1}^{n-1} \sum_{j=i+1}^n \frac{2}{j-i+1}$$

$$= \sum_{i=1}^{n-1} \sum_{k=1}^{n-i} \frac{2}{k+1}$$

$$< \sum_{i=1}^{n-1} \sum_{k=1}^n \frac{2}{k}$$

$$= \sum_{i=1}^{n-1} O(\lg n)$$

$$= O(n \lg n)$$

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