

# CS118 Discussion Week 7: The Network Layer (Control Plane)

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# Questions?

- From this week or about the HW/Midterm

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# This week

- Review the two main types of traditional routing algorithms
  - Dijkstra's/Link-State
  - Bellman-Ford/Distance-Vector
- Vagrant/Mininet Tutorial

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# The Network Layer (The Control Plane)

- Two Key Features to the Network Layer as a whole:
  - Forwarding (move packets from a router's input link to appropriate router output link)
  - Routing (determine route taken by packets from source to destination)

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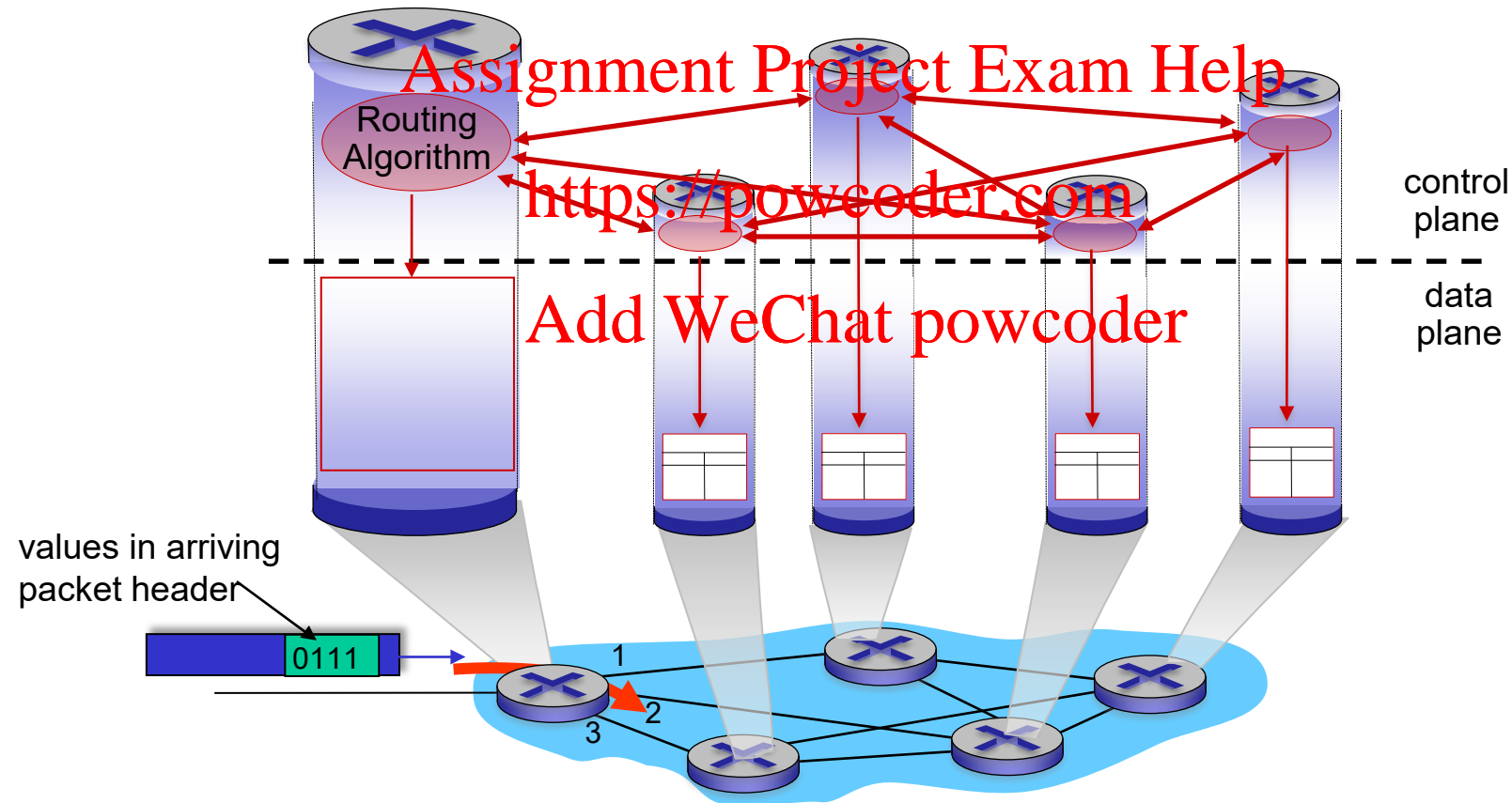
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## Two approaches to structuring network control plane:

- per-router control (traditional)
- logically centralized control (software defined networking)
- Can anyone give some guesses as to advantages/disadvantages?

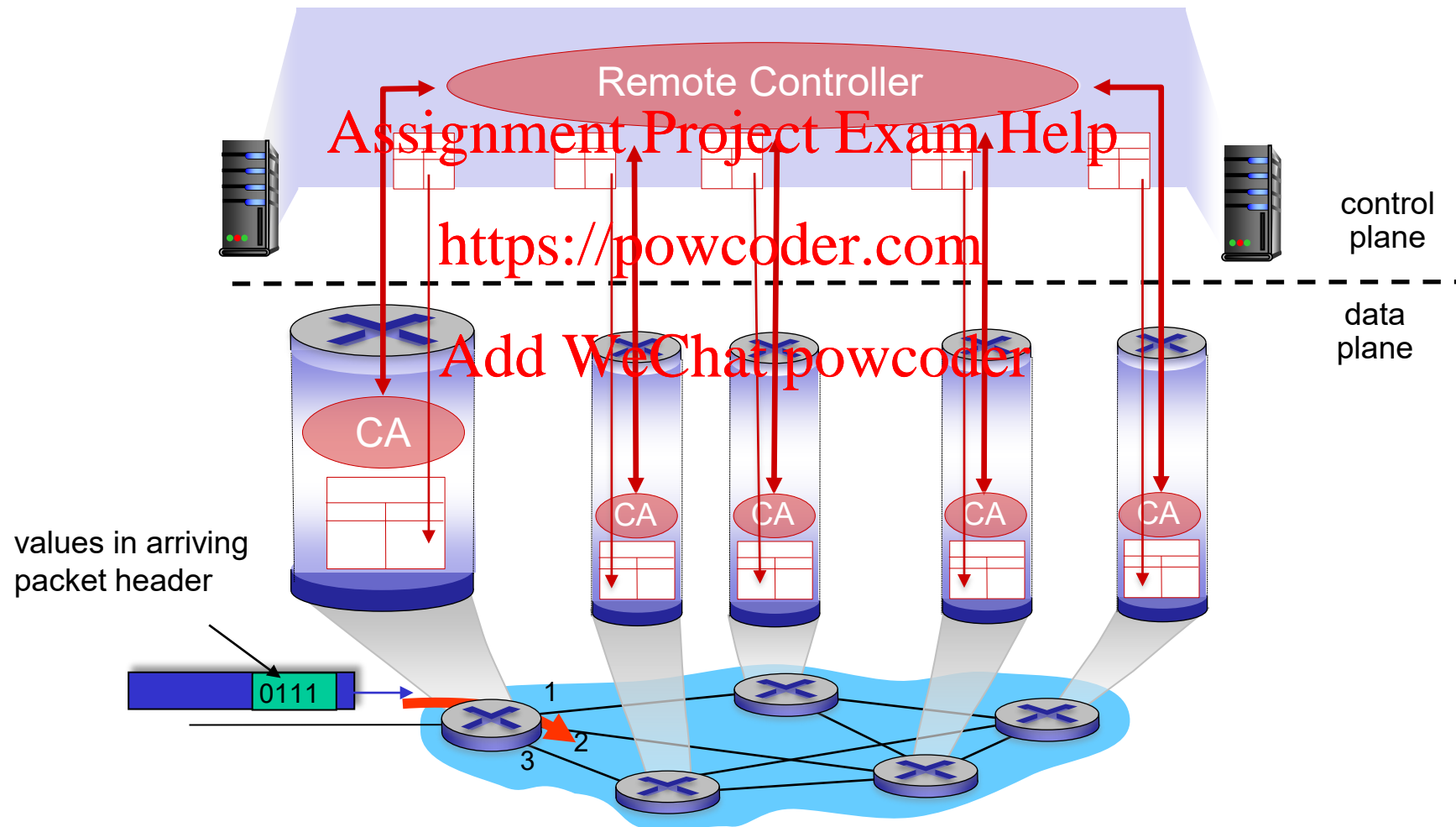
# Per-router control plane

Individual routing algorithm components *in each and every router* interact in the control plane – aka each router runs something like Dijkstra's



# Software-Defined Networking (SDN) control plane

Remote controller computes, installs forwarding tables in routers



# What is a Routing Protocol?

- The purpose of a routing protocol is to find a 'good' (where good can mean least cost, fewest hops, least congested, etc) path from the sender to receiver, through the network.
- The path is the sequence of routers the packet traverses on this journey.
- Non-trivial problem!

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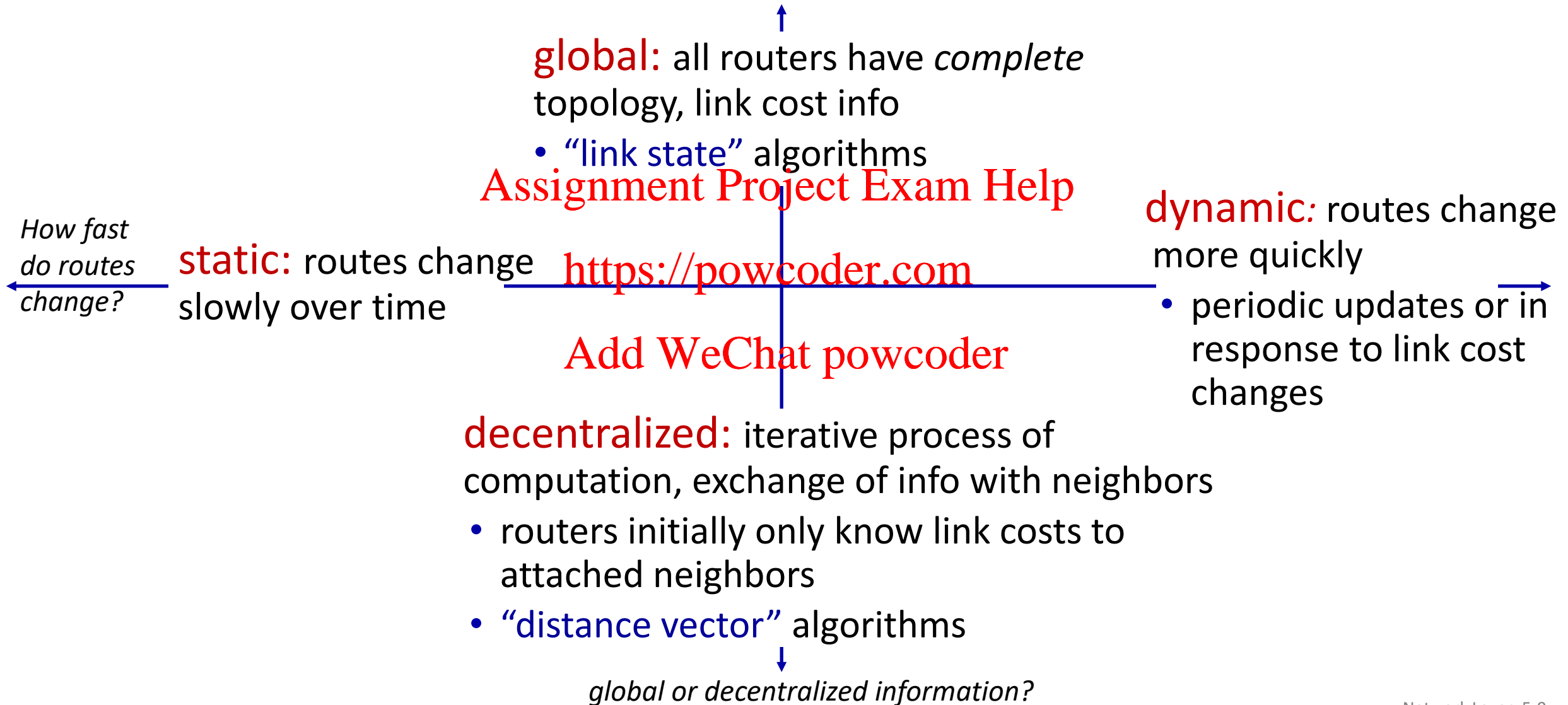
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# Formalizing the Problem

- Definitions: A graph  $G(V, E)$  is composed of a set  $V$  of vertices and a set  $E$  of edges between these vertices. Let  $e(v_1, v_2)$  denote the presence of an edge between vertices  $v_1$  and  $v_2$ . Each edge  $e$  in  $E$  has a weight  $w(e)$ . Let  $dist_G(v_1, v_2)$  denote the length of the shortest path between vertices  $v_1$  and  $v_2$  in the graph
- The problem, then, is finding the path with value  $dist_G(v_1, v_2)$  for each pair of nodes/vertices.
  - This is the simple version of the problem, where we don't worry about anything like 'this type of packet must go along this route'.



# Routing algorithm classification



# Dijkstra's link-state routing algorithm

- **centralized:** network topology, link costs known to *all* nodes

- accomplished via “link state broadcast”
- all nodes have same info

- computes least cost paths from one node (“source”) to all other nodes

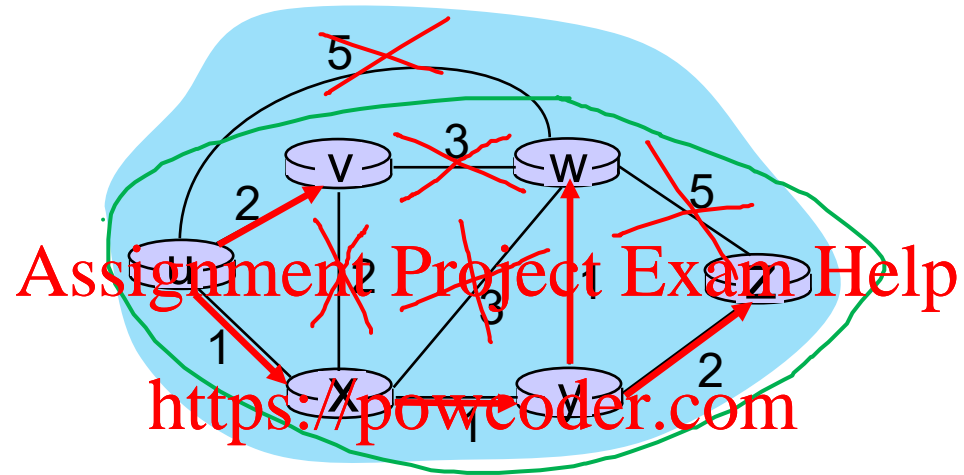
- gives *forwarding table* for that node

- **iterative:** after  $k$  iterations, know least cost path to  $k$  destinations

## notation

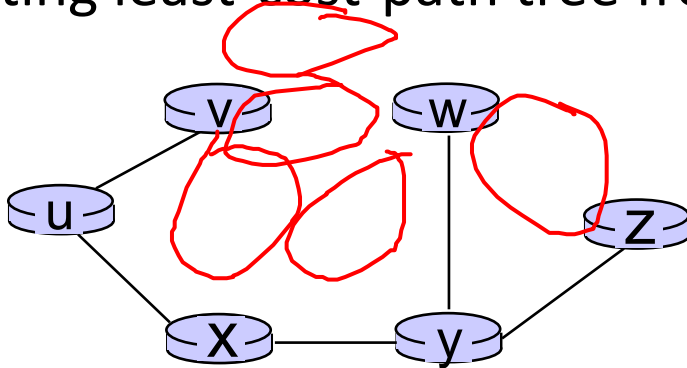
- $c_{x,y}$ : direct link cost from node  $x$  to  $y$ ;  $= \infty$  if not direct neighbors
- $D(v)$ : *current* estimate of cost of least-cost-path from source to destination  $v$
- $p(v)$ : predecessor node along path from source to  $v$
- $N'$ : set of nodes whose least-cost-path *definitively* known

# Dijkstra's algorithm: an example



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resulting least-cost-path tree from u:



resulting forwarding table in u:

destination	outgoing link
v	(u,v)
x	(u,x)
y	(u,x)
w	(u,x)
x	(u,x)

route from  $u$  to  $v$  directly

route from  $u$  to all other destinations via  $x$

# Dijkstra's algorithm: discussion

Alg Complexity:  $n$  nodes

- each of  $n$  iteration: need to check all nodes not already in the completed set
- $n(n+1)/2$  comparisons:  $O(n^2)$  complexity (where  $n$  is the number of nodes)
- more efficient implementations possible:  $O(n \log n)$

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Message Complexity:

- each router must *broadcast* its link state information to other  $n$  routers
- efficient (and interesting!) broadcast algorithms:  $O(n)$  link crossings to disseminate a broadcast message from one source
- each router's message crosses  $O(n)$  links: overall message complexity:  $O(n^2)$

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# Distance Vector Routing

- Key idea is that each node communicates with each other, sending their own distance vector estimates to neighbors

- when  $x$  receives new DV estimate from any neighbor, it updates its own DV using Bellman-Ford equation:

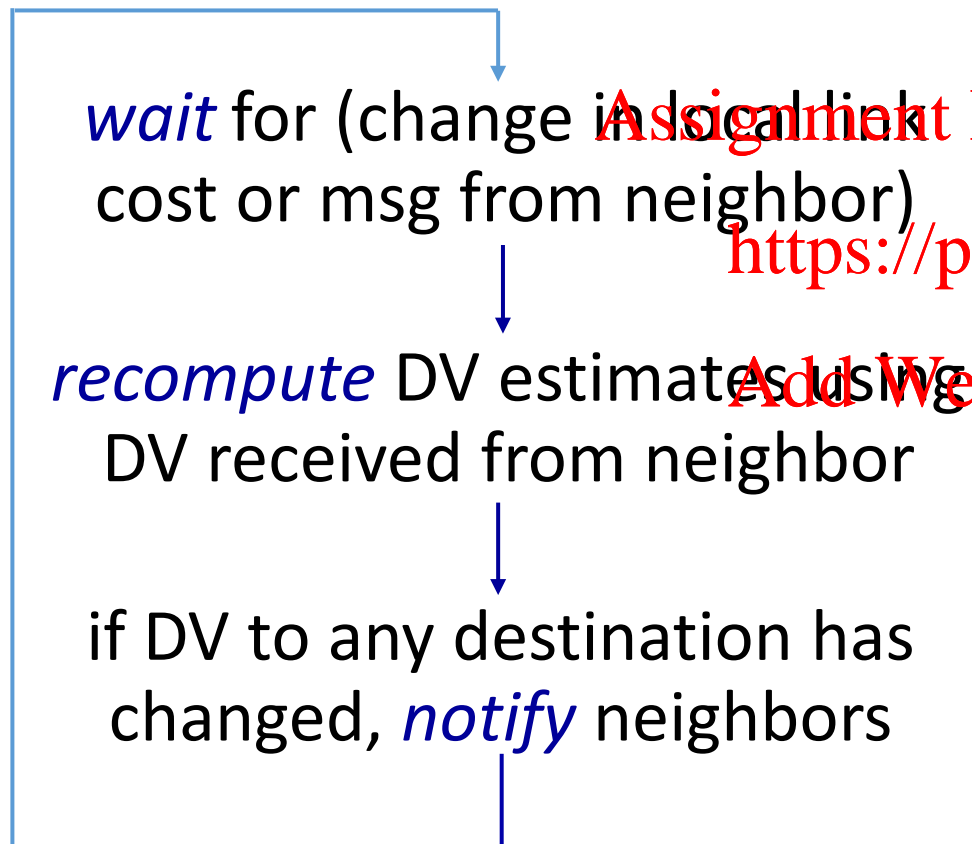
$$D_x(y) \leftarrow \min_v \{c_{x,v} + D_v(y)\} \text{ for each node } y \in N$$

$\min$  taken over all neighbors  $v$  of  $x$  | direct cost of link from  $x$  to  $v$  |  $v$ 's estimated least-cost-path cost to  $y$

- under minor, natural conditions, the estimate  $D_x(y)$  converge to the actual least cost  $d_x(y)$

# Distance vector algorithm:

each node:



iterative, asynchronous: each local iteration caused by:

- local link cost change
- DV update message from neighbor

distributed, self-stopping: each node notifies neighbors *only* when its DV changes

- neighbors then notify their neighbors – *only if necessary*
- no notification received, no actions taken!

# Distance Vector Discussion

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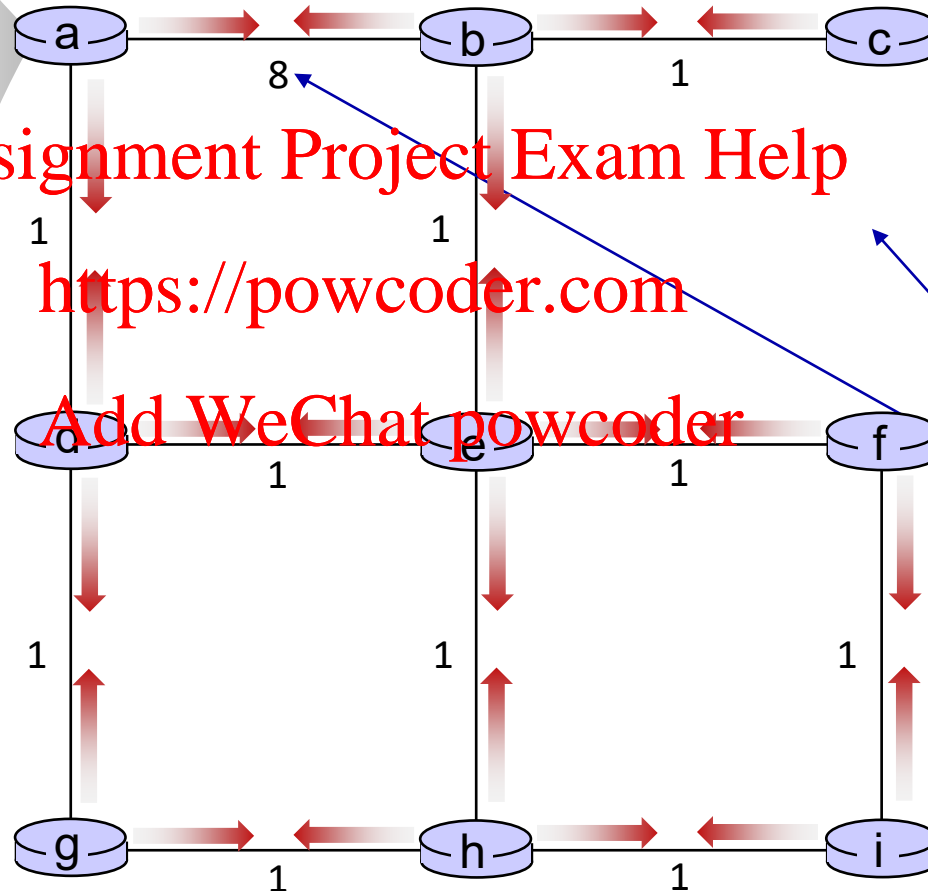
# Distance vector: example



t=0

- All nodes have distance estimates to nearest neighbors (only)
- All nodes send their local distance vector to their neighbors

DV in a:
$D_a(a)=0$
$D_a(b)=8$
$D_a(c)=\infty$
$D_a(d)=1$
$D_a(e)=\infty$
$D_a(f)=\infty$
$D_a(g)=\infty$
$D_a(h)=\infty$
$D_a(i)=\infty$



A few asymmetries:

- missing link
- larger cost



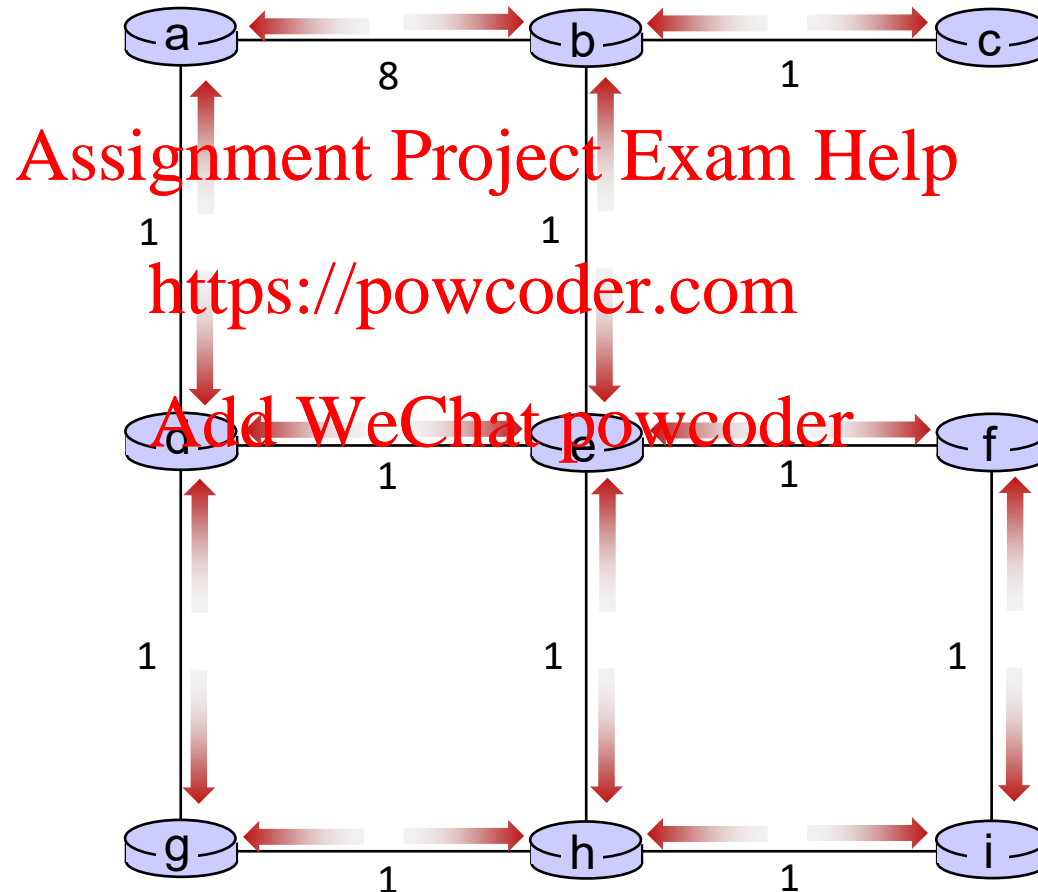
# Distance vector example: iteration



$t=1$

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



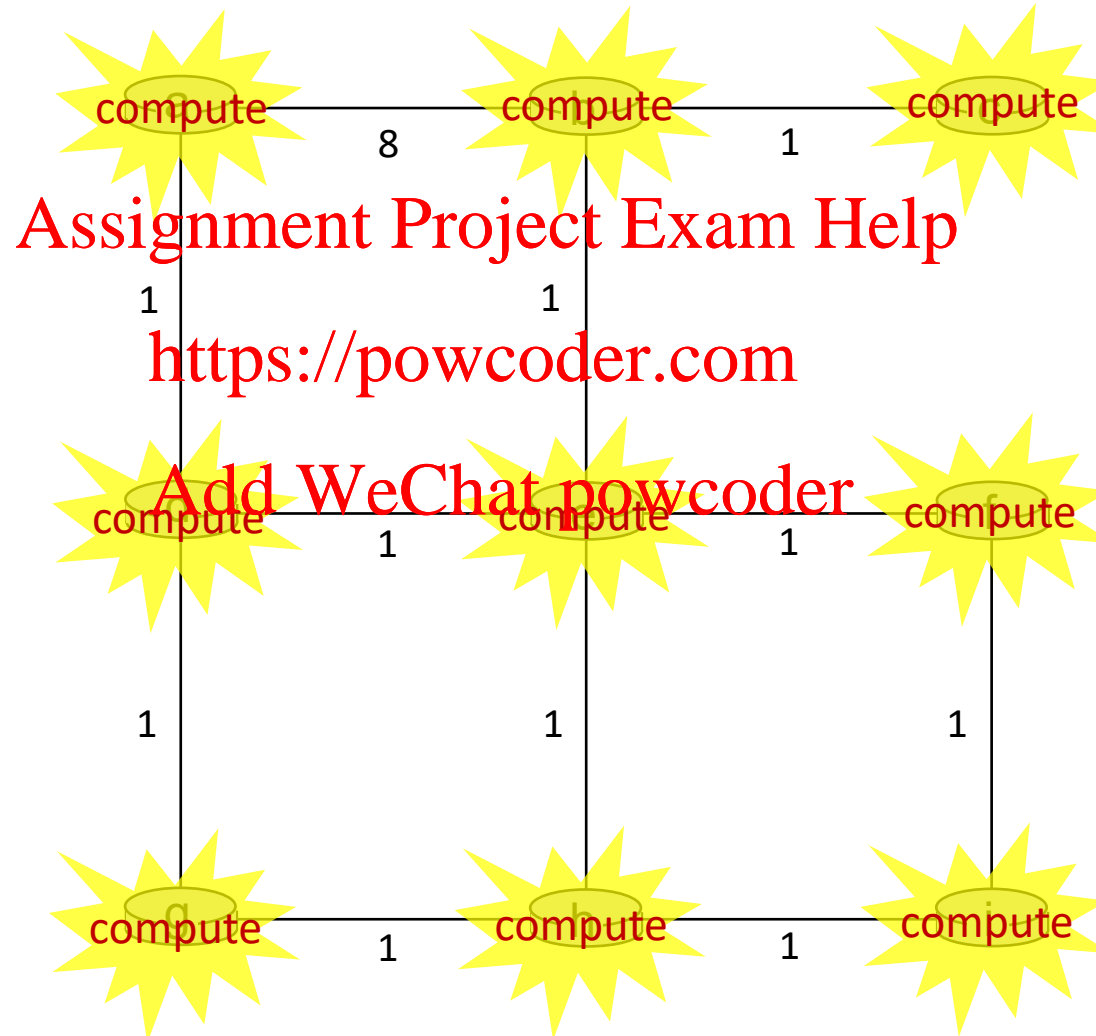
# Distance vector example: iteration



$t=1$

All nodes:

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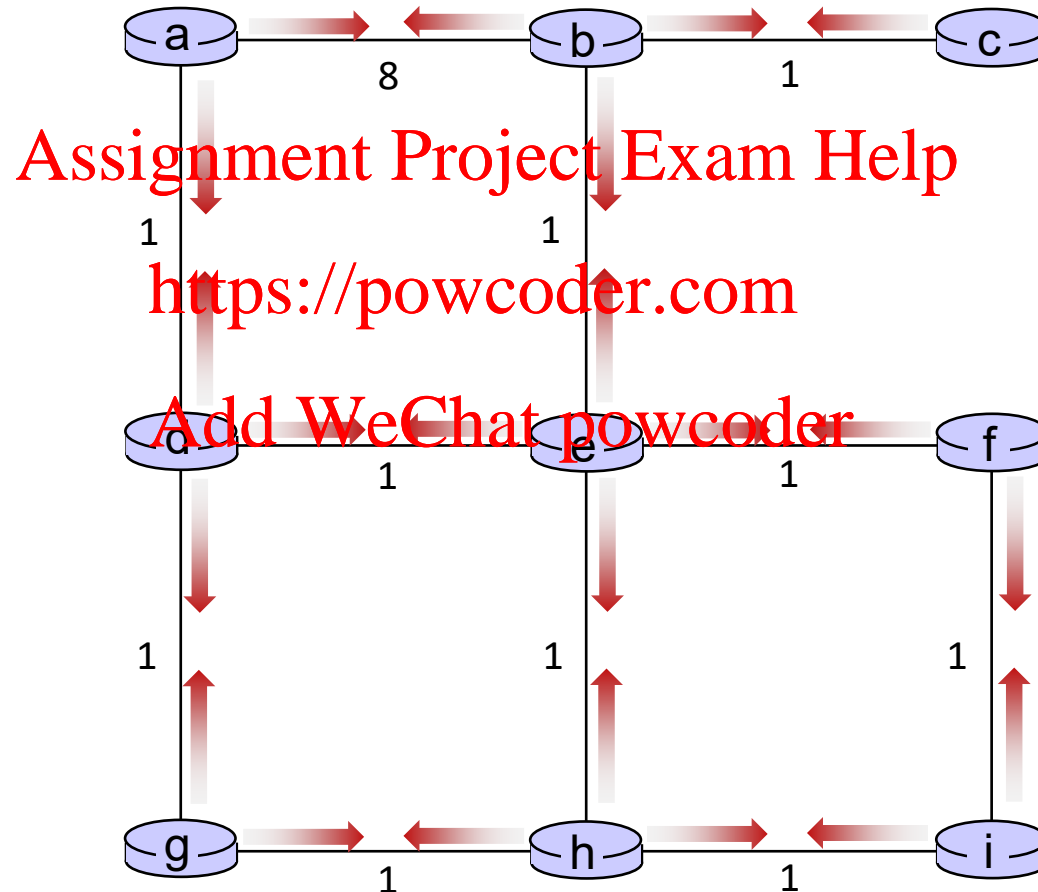
# Distance vector example: iteration



$t=1$

All nodes:

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- send their new local distance vector to neighbors



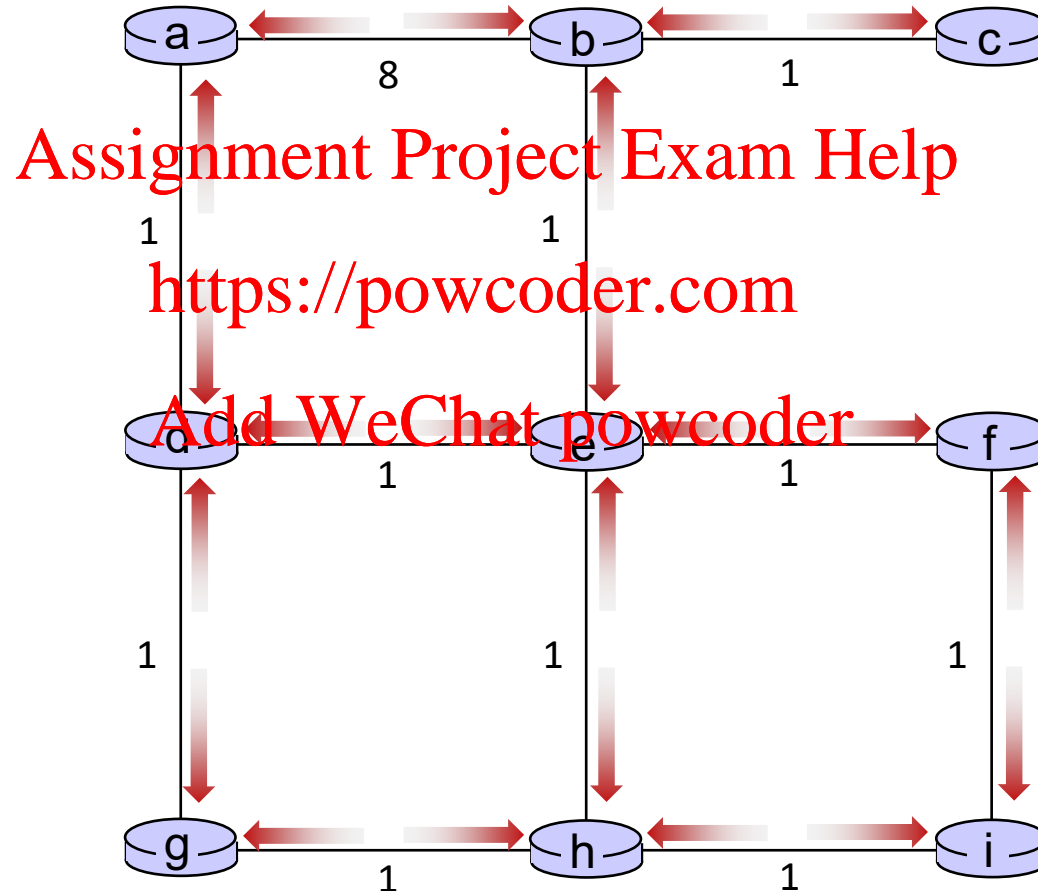
# Distance vector example: iteration



t=2

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



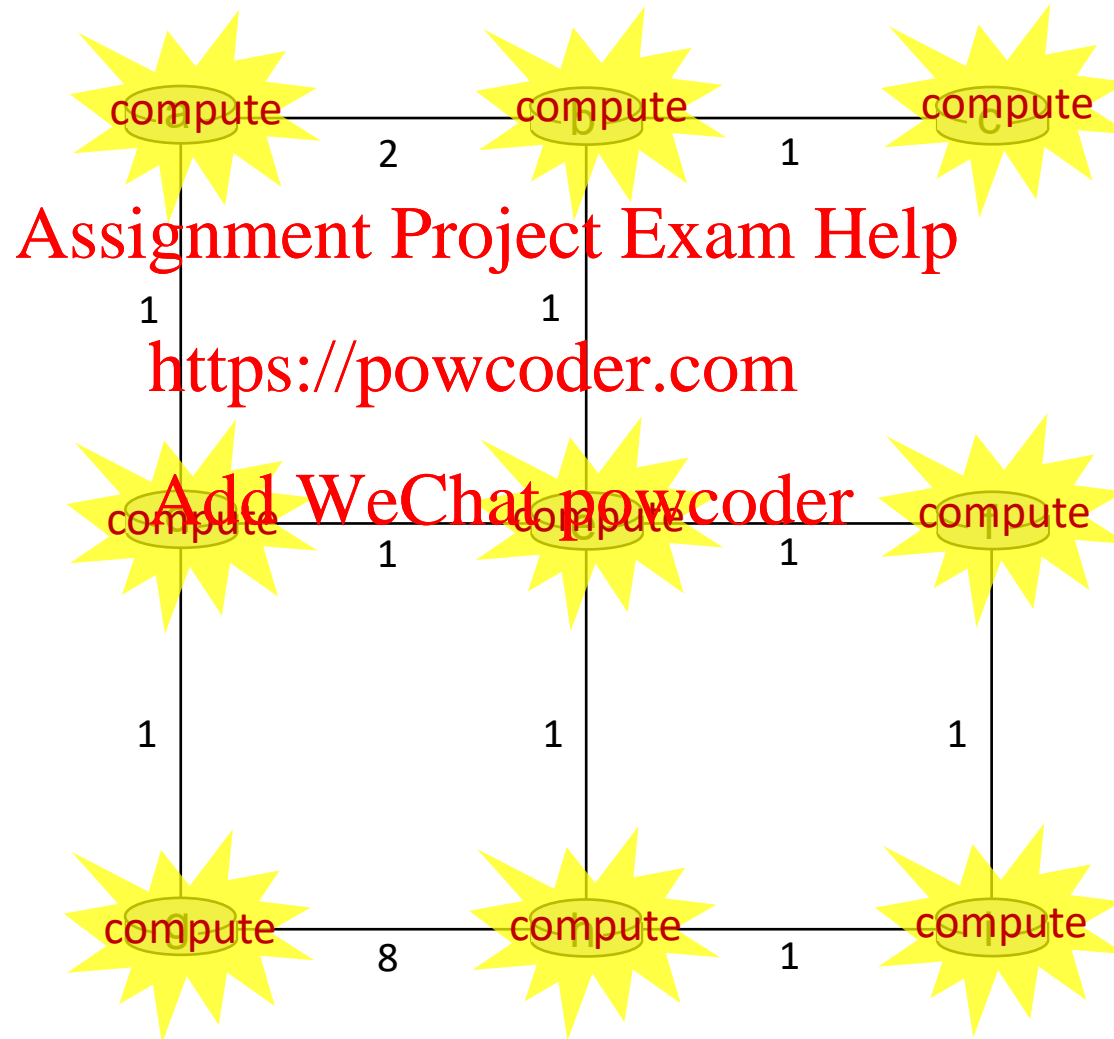
# Distance vector example: iteration



t=2

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



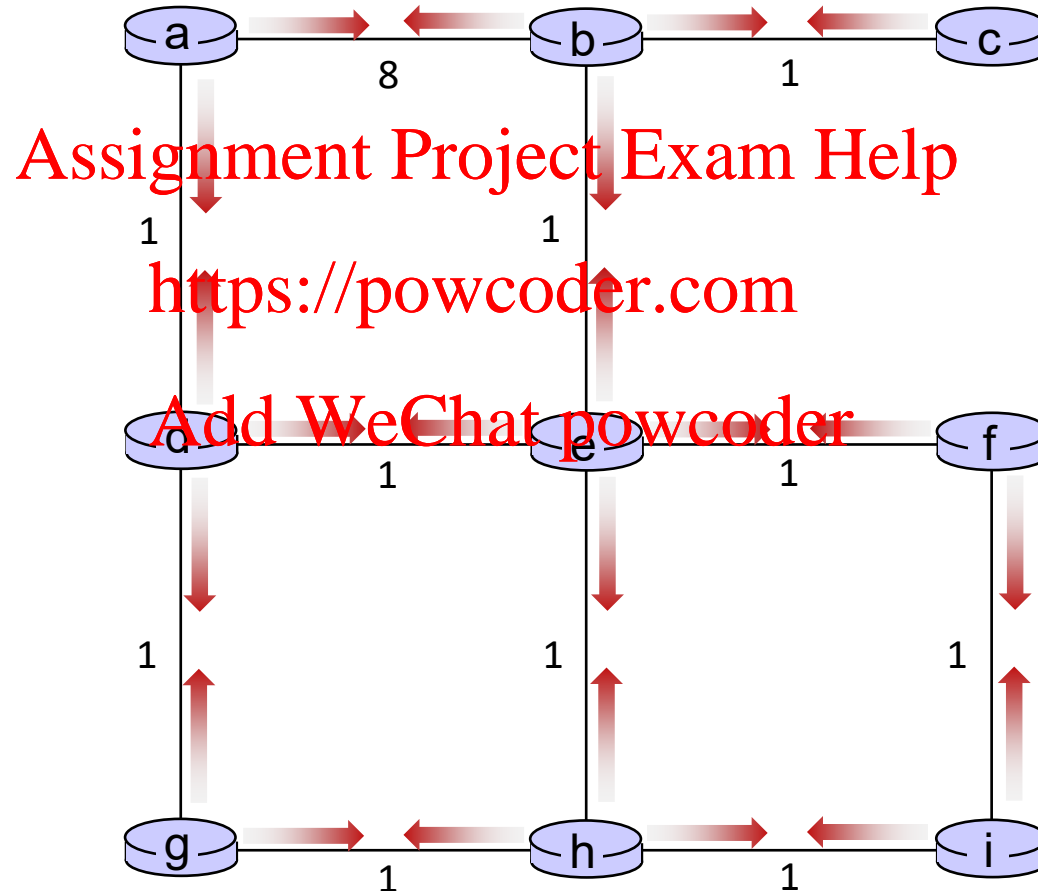
# Distance vector example: iteration



t=2

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



# Distance vector example: iteration

.... and so on

Let's next take a look at the iterative *computations* at nodes

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# Distance vector example:



**t=1**

- b receives DVs from a, c, e

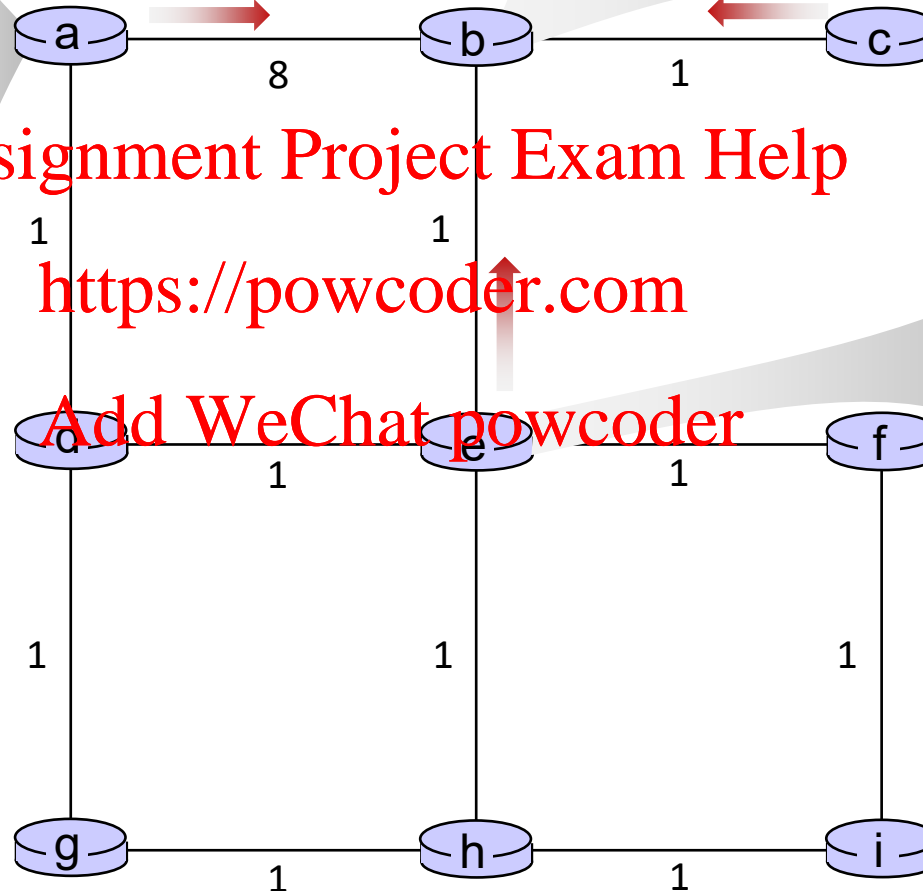
DV in a:
$D_a(a)=0$
$D_a(b)=8$
$D_a(c)=\infty$
$D_a(d)=1$
$D_a(e)=\infty$
$D_a(f)=\infty$
$D_a(g)=\infty$
$D_a(h)=\infty$
$D_a(i)=\infty$

DV in b:

$D_b(a) = 8$	$D_b(f) = \infty$
$D_b(c) = 1$	$D_b(g) = \infty$
$D_b(d) = \infty$	$D_b(h) = \infty$
$D_b(e) = 1$	$D_b(i) = \infty$

DV in c:
$D_c(a)=\infty$
$D_c(b)=1$
$D_c(c)=0$
$D_c(d)=\infty$
$D_c(e)=\infty$
$D_c(f)=\infty$
$D_c(g)=\infty$
$D_c(h)=\infty$
$D_c(i)=\infty$

DV in e:
$D_e(a)=\infty$
$D_e(b)=1$
$D_e(c)=\infty$
$D_e(d)=1$
$D_e(e)=0$
$D_e(f)=1$
$D_e(g)=\infty$
$D_e(h)=1$
$D_e(i)=\infty$



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# Comparison of LS and DV algorithms

## message complexity

LS:  $n$  routers,  $O(n^2)$  messages sent

DV: exchange between neighbors;  
convergence time varies

robustness: what happens if router malfunctions, or is compromised?

## speed of convergence

LS:  $O(n^2)$  algorithm,  $O(n^2)$  messages

- may have oscillations

DV: convergence time varies

- may have routing loops
- count-to-infinity problem

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- router can advertise incorrect *link* cost
- each router computes only its own table

DV:

- DV router can advertise incorrect *path* cost (“I have a *really* low cost path to everywhere”): black-holing
- each router’s table used by others: error propagate thru network

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# Mininet and Vagrant

