

Point estimation
(Module 2)

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Statistics (MAST20005) &
Elements of Statistics
(MAST90038)

School of Mathematics and Statistics
University of Melbourne

Semester 2, 2022

Aims of this module

- Introduce the main elements of statistical inference and estimation, especially the idea of a sampling distribution
- Show the simplest type of estimation: that of a single number
- Show some general approaches to estimation, especially the method of maximum likelihood

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Outline

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Estimation & sampling distributions

Estimation <https://powcoder.com>

Method of moments

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Maximum likelihood estimation

Motivating example

On a particular street, we measure the time interval (in minutes) between each car that passes:

2.55 2.13 3.18 5.94 2.29 2.41 8.72 3.71

We believe these follow an exponential distribution:

$$X_i \sim \text{Exp}(\lambda)$$

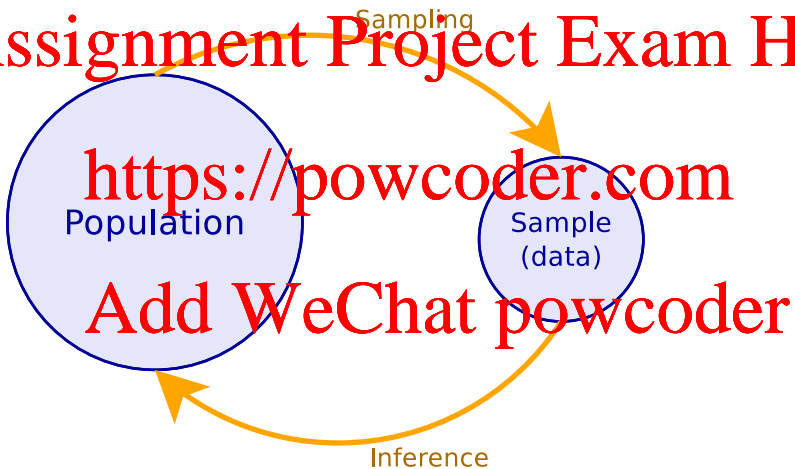
What can we say about λ ?

Can we approximate from the data?

Yes! We can do it using a statistic. This is called **estimation**.

Statistics: the big picture

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Distributions of statistics

Consider sampling from $X \sim \text{Exp}(\lambda = 1/5)$.

Convenient simplification: set $\theta = 1/\lambda$.

This makes $\mathbb{E}(X) = \theta$ and $\text{var}(X) = \theta^2$.

Note: There are two common parameterisations,

$$f_X(x) = \lambda e^{-\lambda x}, \quad x \in [0, \infty)$$

$$f_X(x) = \frac{1}{\theta} e^{-\frac{1}{\theta} x}, \quad x \in [0, \infty)$$

λ is called the *rate parameter* (relates to a Poisson process)

Be clear about which is being used!

Consider sampling from $X \sim \text{Exp}(\lambda = 1/5)$.

Take a large number of samples, each of size $n = 100$:

1.	1.84	1.19	11.73	5.64	17.98	0.26	...
2.	2.67	7.15	5.19	1.03	6.65	3.18	...
3.	16.99	2.15	2.60	5.40	3.64	2.01	...
4.	2.21	1.54	4.27	5.29	3.65	0.83	...
5.	12.24	1.59	2.56	1.38	5.72	0.69	...
...							

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Then calculate some statistics (\bar{x} , $x_{(1)}$, $x_{(n)}$, etc.) for each one:

	Min.	Median	Mean	Max.
1.	0.02	4.10	5.17	23.96
2.	0.16	4.48	5.84	39.90
3.	0.17	3.39	4.38	15.61
4.	0.03	3.73	5.43	34.02
5.	0.01	3.12	4.71	19.94

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As we continue this process, we get some information on the distributions of these statistics.

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Sampling distribution (definition)

Recall that any statistic $T = \phi(X_1, \dots, X_n)$ is a random variable.

The **sampling distribution** of a statistic is its probability distribution, given an assumed population distribution and a sampling scheme (e.g. random sampling).

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Sometimes we can determine it exactly, but often we might resort to simulation.

In the current example, we know that

$$X_{(1)} \sim \text{Exp}(100\lambda)$$

$$\sum X_i \sim \text{Gamma}(100, \lambda)$$

How to estimate?

Suppose we want to estimate θ from the data. What should we do?

Reminder:

- Population mean, $\mathbb{E}(X) = \theta = 5$
- Population variance, $\text{var}(X) = \theta^2 = 5^2$
- Population standard deviation, $\text{sd}(X) = \theta = 5$

Can we use the sample mean, \bar{X} , as an estimate of θ ?

Yes!

Can we use the sample standard deviation, S , as an estimate of θ ?

Yes!

Will these statistics be good estimates? Which one is better?

Let's see...

We need to know properties of their sampling distributions, such as their mean and variance.

Note: we are referring to the distribution of the statistic, T , rather than the population distribution from which we draw samples, X .

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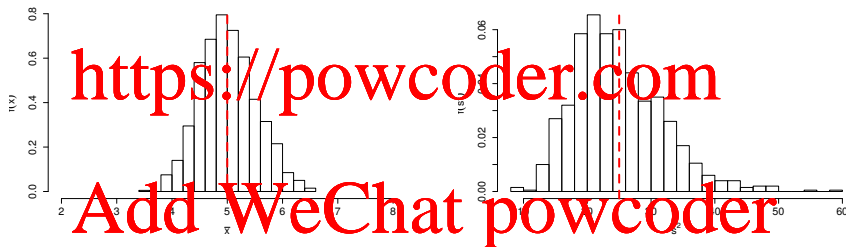
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For example, it is natural to expect that:

- $\mathbb{E}(\bar{X}) \approx \mu$ (sample mean \approx population mean)
- $\mathbb{E}(S^2) \approx \sigma^2$ (sample variance \approx population variance)

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Let's see for our example:



Left: distribution of \bar{X} . Right: distribution of S^2 .

Vertical dashed lines: true values, $\mathbb{E}(X) = 5$ and $\text{var}(X) = 5^2$.

- Should we use \bar{X} or S to estimate θ ?

Which one is the better **estimator**?

- We would like the sample distribution of the estimator to be as close as possible to the true value $\theta = 5$.
- In practice, for any given dataset, we don't know which estimate is the closest, since we don't know the true value.
- We should use the one that is **more likely** to be the closest.
- Simulation: consider 250 samples of size $n = 100$ and compute:

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$$\bar{x}_1, \dots, \bar{x}_{250},$$

$$s_1, \dots, s_{250}$$

```
> summary(x.bar)
```

Min.	1st Qu.	Median	Mean	3rd Qu.	Max.
3.789	4.663	4.972	5.015	5.365	6.424

```
> sd(x.bar)  
[1] 0.4888185
```

```
> summary(s)
```

Min.	1st Qu.	Median	Mean	3rd Qu.	Max.
3.502	4.473	4.916	5.002	5.512	7.456

```
> sd(s)
```

```
[1] 0.7046119
```

From our simulation, $sd(\bar{X}) \approx 0.49$ and $sd(S) \approx 0.70$.

So, in this case it looks like \bar{X} is superior to S .

Outline

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Estimation & sampling distributions

Estimators <https://powcoder.com>

Method of moments

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Maximum likelihood estimation

Definitions

- A **parameter** is a quantity that describes the population distribution, e.g. μ and σ^2 for $N(\mu, \sigma^2)$.
- The **parameter space** is the set of all possible values that a parameter might take, e.g. $-\infty < \mu < \infty$ and $0 \leq \sigma < \infty$.
- An **estimator** (or **point estimator**) is a statistic that is used to estimate a parameter. It refers specifically to the random variable version of the statistic, e.g. $T = u(X_1, \dots, X_n)$.
- An **estimate** (or **point estimate**) is the observed value of the estimator for a given dataset. In other words, it is a realisation of the estimator, e.g. $t = u(x_1, \dots, x_n)$, where x_1, \dots, x_n is the observed sample (data).
- **'Hat' notation**: If T is an estimator for θ , then we usually refer to it by $\hat{\theta}$ for convenience.

Examples

We will now go through a few important examples:

- Sample mean
- Sample variance
- Sample proportion

In each case, we assume a sample of iid rvs, X_1, \dots, X_n , with mean μ and variance σ^2 .

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Sample mean

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$$\bar{X} = \frac{1}{n}(X_1 + X_2 + \dots + X_n) = \frac{1}{n} \sum_{i=1}^n X_i$$

Properties:

- $\mathbb{E}(\bar{X}) = \mu$
- $\text{var}(\bar{X}) = \frac{\sigma^2}{n}$

Also, the Central Limit Theorem implies that usually,

$$\bar{X} \approx N\left(\mu, \frac{\sigma^2}{n}\right)$$

Often used to estimate the population mean, $\hat{\mu} = \bar{X}$.

Sample variance

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$$S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2$$

Properties:

- $\mathbb{E}(S^2) = \sigma^2$
- $\text{var}(S^2) = (\text{a messy formula})$

Often used to estimate the population variance $\hat{\sigma}^2 = S^2$

Sample proportion

For a discrete random variable, we might be interested in how often a particular value appears. Counting this gives the sample frequency:

$$\text{freq}(a) = \sum_{i=1}^n I(X_i = a)$$

Let the population proportion be $p = \Pr(X = a)$. Then we have:

$$\text{freq}(a) \sim \text{Bi}(n, p)$$

Divide by the sample size to get the sample proportion. This is often used as an estimator for the population proportion:

$$\hat{p} = \frac{\text{freq}(a)}{n} = \frac{1}{n} \sum_{i=1}^n I(X_i = a)$$

For large n , we can approximate this with a normal distribution:

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Note:

- The sample pmf and the sample proportion are the same, both of them estimate the probability of a given event or set of events.
- The pmf is usually used when the interest is in many different events/values, and is written as a function e.g. $\hat{p}(g)$
- The proportion is usually used when only a single event is of interest (getting heads for a coin flip, a certain candidate winning an election, etc.).

Examples for a normal distribution

If the sample is drawn from a normal distribution, $X_i \sim N(\mu, \sigma^2)$, we can derive exact distributions for these statistics.

Sample mean:

$$\bar{X} \sim N\left(\mu, \frac{\sigma^2}{n}\right)$$

Sample variance:

$$S^2 \sim \frac{\sigma^2}{n-1} \chi_{n-1}^2$$
$$\mathbb{E}(S^2) = \sigma^2, \quad \text{var}(S^2) = \frac{2\sigma^4}{n-1}$$

χ_k^2 is the chi-squared distribution with k degrees of freedom.
(more details in Module 3)

Bias

Consider an estimator $\hat{\theta}$ of θ

- If $\mathbb{E}(\hat{\theta}) = \theta$, the estimator is said to be unbiased
- The bias of the estimator is, $\mathbb{E}(\hat{\theta}) - \theta$

Examples:

- The sample variance is unbiased for the population variance, $\mathbb{E}(S^2) = \sigma^2$.
(problem 1 in week 3 tutorial)
- What if we divide by n instead of $n - 1$ in the denominator?

Transformations and biasedness

$$\mathbb{E}\left(\frac{n-1}{n}S^2\right) = \frac{n-1}{n}\sigma^2 < \sigma^2$$

\Rightarrow biased!

In general, if $\hat{\theta}$ is unbiased for θ , then it will usually be the case that $g(\hat{\theta})$ is biased for $g(\theta)$.

Unbiasedness is not preserved under transformations.

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Challenge problem

Is the sample standard deviation, $S = \sqrt{S^2}$, biased for the population standard deviation, σ ?

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Choosing between estimators

- Evaluate and compare the sampling distributions of the estimators.
- Generally, prefer estimators that have **smaller bias** and **smaller variance** (and it can vary depending on the aim of your problem).
- Sometimes, we only know asymptotic properties of estimators (will see examples later).

Note: this approach to estimation is referred to as **frequentist** or **classical** inference. The same is true for most of the techniques we will cover. We will also learn about an alternative approach, called **Bayesian** inference, later in the semester.

Challenge problem (uniform distribution)

Take a random sample of size n from the uniform distribution with pdf

$$f(x) = 1 \quad \left(\theta - \frac{1}{2} < x < \theta + \frac{1}{2} \right)$$

Can you think of some estimators for θ ?

What is their bias and variance?

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Challenge problem (boundary problem)

Take a random sample of size n from the shifted exponential distribution with pdf:

$$f(x) = e^{-(x-\theta)} \quad (x \geq \theta)$$

Equivalently:

$$X_i \sim \theta + \text{Exp}(1)$$

Can you think of some estimators for θ ?

What is their bias and variance?

Coming up with (good) estimators?

How can we do this for any given problem?

We will cover two general methods:

- Method of moments
- Maximum likelihood

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Outline

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Estimation & sampling distributions

Estimation <https://powcoder.com>

Method of moments

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Maximum likelihood estimation

Method of moments (MM)

- Idea:

- Make the population distribution resemble the empirical (data) distribution. . .
 - . . . by equating theoretical moments with sample moments
 - Do this until you have enough equations, and then solve them
- Example: if $E(X) = \theta$, then the method of moments estimator of θ is \bar{X} .

- General procedure (for r parameters):

1. X_1, \dots, X_n i.i.d. $f(x; \theta_1, \dots, \theta_r)$
 2. k th moment is $\mu_k = E(X^k)$
 3. k th sample moment is $M_k = \frac{1}{n} \sum X_i^k$
 4. Set $\mu_k = M_k$, for $k = 1, \dots, r$ and solve for $(\theta_1, \dots, \theta_r)$.
- Alternative: Can use the variance instead of the second moment (sometimes more convenient).

Remarks

- An intuitive approach to estimation
- Can work in situations where other approaches are too difficult
- Usually biased
- Usually not optimal (but may suffice)
- Note: some authors use a 'la' ($\hat{\theta}$) or a 'tiller' ($\tilde{\theta}$) to denote MM estimators rather than a 'hat' ($\hat{\theta}$). This helps to distinguish different estimators when comparing them to each other.

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Example: Geometric distribution

- Sampling from: $X \sim \text{Geom}(p)$
- The first moment:

$$E(X) = \sum_{x=1}^{\infty} xp(1-p)^{x-1} = \frac{1}{p}$$

- The MM estimator is obtained by solving

$$\bar{X} = \frac{1}{\tilde{p}}$$

which gives

$$\tilde{p} = \frac{1}{\bar{X}}$$

Example: Normal distribution

- Sampling from: $X \sim N(\mu, \sigma^2)$
- Population moments: $\mathbb{E}(X) = \mu$ and $\mathbb{E}(X^2) = \sigma^2 + \mu^2$
- Sample moments: $M_1 = \bar{X}$ and $M_2 = \frac{1}{n} \sum X_i^2$
- Equating them:

$$\bar{X} = \mu \quad \text{and} \quad \frac{1}{n} \sum X_i^2 = \sigma^2 + \mu^2$$

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Solving these gives:

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$$\tilde{\mu} = \bar{X} \quad \text{and} \quad \tilde{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2$$

Note: <https://powcoder.com>

- This not the usual sample variance!

- $\tilde{\sigma}^2 = \frac{n-1}{n} S^2$

- This one is biased, $\mathbb{E}(\tilde{\sigma}^2) = \frac{n-1}{n} \sigma^2 \neq \sigma^2$

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Example: Gamma distribution

- Sampling from: $X \sim \text{Gamma}(\alpha, \theta)$

- The pdf is

$$f(x | \alpha, \theta) = \frac{1}{\Gamma(\alpha)\theta^\alpha} x^{\alpha-1} \exp\left(\frac{-x}{\theta}\right)$$

- Population moments: $\mathbb{E}(X) = \alpha\theta$ and $\text{var}(X) = \alpha\theta^2$
- Sample moments: $M = \bar{X}$ and $S^2 = \frac{1}{n-1} \sum (X_i - \bar{X})^2$

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Equating them:

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Solving these gives:

$$\hat{\theta} = \frac{S^2}{\bar{X}} \text{ and } \alpha = \frac{\bar{X}^2}{S^2}$$

Note:

- This is an example of using S^2 instead of M_2

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Outline

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Estimation & sampling distributions

Estimation <https://powcoder.com>

Method of moments

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Maximum likelihood estimation

Method of maximum likelihood (ML)

- Idea: find the 'most likely' explanation for the data
- More concretely: find parameter values that maximise the probability of the data

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Example: Bernoulli distribution

- Sampling from: $X \sim \text{Be}(p)$
- Data are 0's and 1's
- Then pmf is

$$f(x | p) = p^x(1-p)^{1-x} \quad x = 0, 1, \quad 0 < p < 1$$

- Observe values x_1, \dots, x_n of X_1, \dots, X_n (iid)
- The probability of the data (the random sample) is

$$\begin{aligned} \Pr(X_1 = x_1, \dots, X_n = x_n | p) &= \prod_{i=1}^n f(x_i | p) = \prod_{i=1}^n p^{x_i} (1-p)^{1-x_i} \\ &= p^{\sum x_i} (1-p)^{n-\sum x_i} \end{aligned}$$

- Regard the sample x_1, \dots, x_n as known (since we have observed it) and regard the probability of the data as a function of p .
- When written this way, this is called the **likelihood** of p :

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$$L(p) = L(p | x_1, \dots, x_n) \\ = \Pr(X_1 = x_1, \dots, X_n = x_n | p)$$

$$= p^{\sum x_i} (1-p)^{n-\sum x_i}$$

- Want to find the value of p that maximizes this likelihood.

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- It often helps to find the value of θ that maximizes the **log** of the likelihood rather than the likelihood
- This is called the **log-likelihood**

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$$\ln L(p) = \ln p^{\sum x_i} + \ln(1-p)^{n-\sum x_i}$$

- The final answer (the maximising value of p) is the same, since the log of non-negative numbers is a one-to-one function whose inverse is the exponential, so any value θ that maximises the log-likelihood also maximises the likelihood.

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- Putting $x = \sum_{i=1}^n x_i$ so that x is the number of 1's in the sample,

$$\ln L(p) = x \ln p + (n - x) \ln(1 - p)$$

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- Find the maximum of this log-likelihood with respect to p by differentiating and equating to zero,

$$\frac{\partial \ln L(p)}{\partial p} = x \frac{1}{p} + (n - x) \frac{-1}{1 - p} = 0$$

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- This gives $p = x/n$
- Therefore, the maximum likelihood estimator is $\hat{p} = X/n = \bar{X}$

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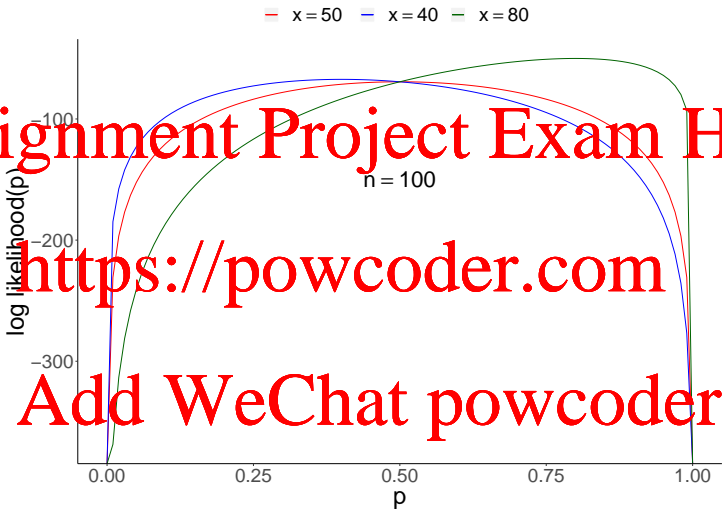


Figure : Log-likelihoods for Bernoulli trials with parameter p

Maximum likelihood: general procedure

- Random sample (iid): X_1, \dots, X_n
- Likelihood function with m parameters $\theta_1, \dots, \theta_m$ and data x_1, \dots, x_n is:

$$L(\theta_1, \dots, \theta_m) = \prod_{i=1}^n f(x_i | \theta_1, \dots, \theta_m)$$

- If X is discrete, for f use the pmf
- If X is continuous, for f use the pdf

- The **maximum likelihood estimates** (MLEs) or the **maximum likelihood estimators** (MLEs) $\hat{\theta}_1, \dots, \hat{\theta}_m$ are values that maximize $L(\theta_1, \dots, \theta_m)$.

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- Note: same abbreviation and notation for both the **estimators** (random variable) and the **estimates** (realised values).
- Often (but not always) useful to take logs and then differentiate and equate derivatives to zero to find MLE's.
- Sometimes this is too hard, but we can maximise numerically. No closed-form expression in this case.

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Example: Exponential distribution

Sampling (iid) from: $X \sim \text{Exp}(\theta)$

$$f(x | \theta) = \frac{1}{\theta} e^{-x/\theta}, \quad x > 0, \quad 0 < \theta < \infty$$

$$L(\theta) = \frac{1}{\theta^n} \exp\left(-\frac{\sum_{i=1}^n x_i}{\theta}\right)$$

$$\ln L(\theta) = -n \ln(\theta) - \frac{1}{\theta} \sum_{i=1}^n x_i$$
$$\frac{\partial \ln L(\theta)}{\partial \theta} = -\frac{n}{\theta} + \frac{\sum x_i}{\theta^2} = 0$$

This gives: $\hat{\theta} = \bar{X}$

Example: Exponential distribution (simulated)

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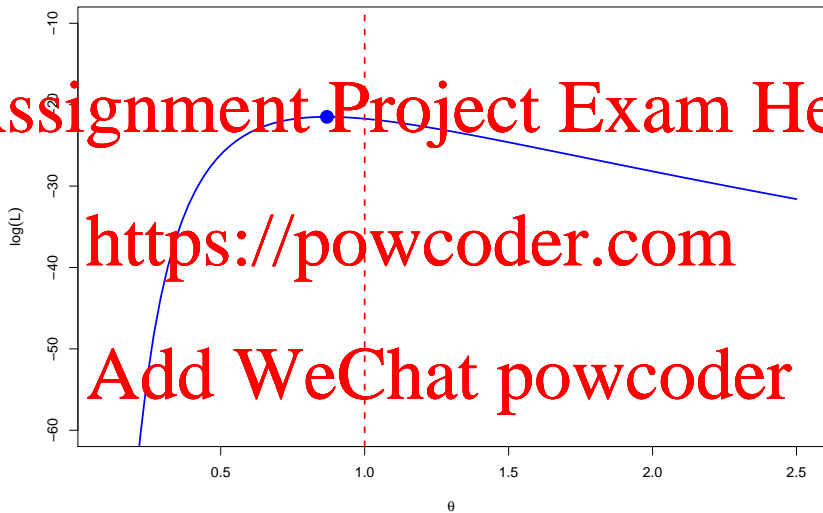
```
x <- rexp(25) # simulate 25 observations from  $\text{Exp}(1)$   
> x
```

```
[1] 0.009669867 3.842141708 0.394267770 0.098725403  
[5] 0.386704987 0.024086824 0.274132718 0.872771164  
[9] 0.950139235 0.022927991 1.538592014 0.337613769  
[13] 0.634363088 0.494441270 1.789416017 0.503498224  
[17] 0.000482703 1.617899321 0.336797648 0.312564298  
[21] 0.702562098 0.265119183 3.825238461 0.238687987  
[25] 1.752657238
```

```
> mean(x) # maximum likelihood estimate
```

```
[1] 0.8690201
```


Log-likelihood curve



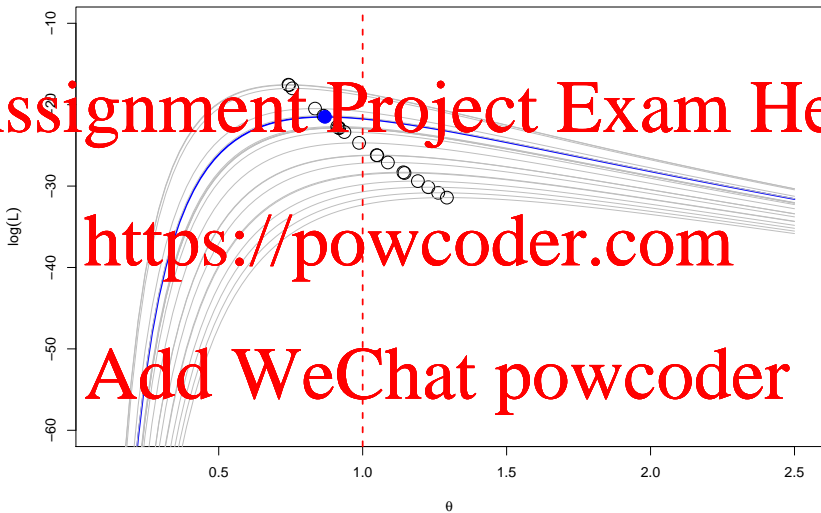
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What if we repeat the sampling process several times?

Log-likelihood curves



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What if we repeat the sampling process several times?

Example: Geometric distribution

Sampling (iid) from: $X \sim \text{Geom}(p)$

$$L(p) = \prod_{i=1}^n p(1-p)^{x_i-1} = p^n (1-p)^{\sum x_i - n}, \quad 0 \leq p \leq 1$$

$$\frac{\partial \ln L(p)}{\partial p} = \frac{n}{p} - \frac{\sum_{i=1}^n x_i - n}{1-p} = 0$$

This gives: $\hat{p} = 1/\bar{X}$

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Example: Normal distribution

Sampling (iid) from: $X \sim \mathcal{N}(\theta_1, \theta_2)$

$$L(\theta_1, \theta_2) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi\theta_2}} \exp \left[-\frac{(x_i - \theta_1)^2}{2\theta_2} \right]$$

$$\ln L(\theta_1, \theta_2) = -\frac{n}{2} \ln(2\pi\theta_2) - \frac{1}{2\theta_2} \sum_{i=1}^n (x_i - \theta_1)^2$$

Take partial derivatives with respect to θ_1 and θ_2 .

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$$\frac{\partial \ln L(\theta_1, \theta_2)}{\partial \theta_1} = \frac{1}{\theta_2} \sum_{i=1}^n (x_i - \theta_1)$$
$$\frac{\partial \ln L(\theta_1, \theta_2)}{\partial \theta_2} = -\frac{n}{2\theta_2} + \frac{1}{2\theta_2^2} \sum_{i=1}^n (x_i - \theta_1)^2$$

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Set both of these to zero and solve. This gives: $\hat{\theta}_1 = \bar{x}$ and $\hat{\theta}_2 = n^{-1} \sum_{i=1}^n (x_i - \bar{x})^2$. The maximum likelihood estimators are therefore:

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$$\hat{\theta}_1 = \bar{X}, \quad \hat{\theta}_2 = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2 = \frac{n-1}{n} S^2$$

Note: $\hat{\theta}_2$ is biased.

Stress and cancer: VEGFC

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```
x <- c(0.97, 0.82, 0.73, 0.96, 1.26)
```

```
> n <- length(x)
```

```
> mean(x) # MLE for population mean
```

```
[1] 0.888
```

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```
> sd(x) * sqrt((n - 1) / n) # MLE for the pop. st. dev.
```

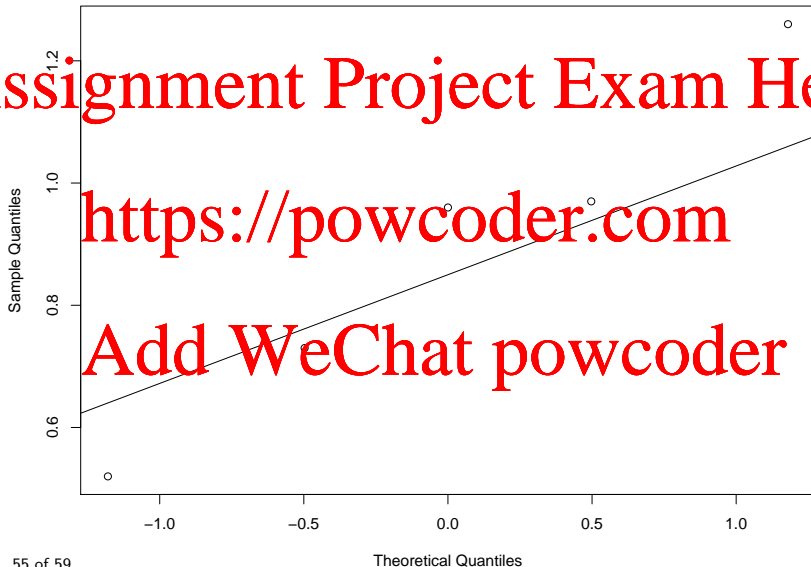
```
[1] 0.2492709
```

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```
> qqnorm(x) # Draw a QQ plot
```

```
> qqline(x) # Fit line to QQ plot
```

Normal Q-Q Plot



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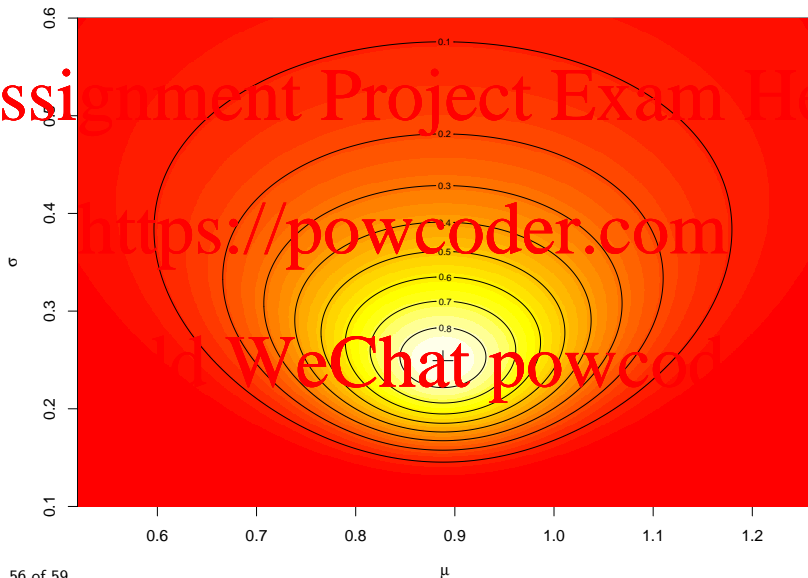
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Challenge problem (boundary problem)

Take a random sample of size n from the shifted exponential distribution with pdf:

$$f(x | \theta) = e^{-(x-\theta)} \quad (x \geq \theta)$$

Equivalently:

$$X_i \sim \theta + \text{Exp}(1)$$

Derive the MLE for θ .

Is it biased?

Can you create an unbiased estimator from it?

Invariance property

Suppose we know $\hat{\theta}$ but are actually interested in $\phi = g(\theta)$ rather than θ itself. Can we estimate ϕ ?

Yes! It is simply $\hat{\phi} = g(\hat{\theta})$.

This is known as the invariance property of the MLE. In other words, transformations don't affect the value of the MLE.

Consequence: MLEs are usually biased since expectations are **not** invariant under transformations.

Is the MLE a good estimator?

Some useful results:

- Asymptotically unbiased
- Asymptotically optimal variance ('efficient')
- Asymptotically normally distributed

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The proofs of these rely on the CLT. More details of the mathematical theory will be covered towards the end of the semester.

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