



# Dataset Summary

# 1. Gaze\_Dataset 개요

No.	Dataset Name	Official URL	IP / DIR Path
1	<a href="#">MpiiGaze</a>	<a href="https://www.mpi-inf.mpg.de/departments/computer-vision-and-machine-learning/research/gaze-based-human-computer-interaction/appearance-based-gaze-estimation-in-the-wild">https://www.mpi-inf.mpg.de/departments/computer-vision-and-machine-learning/research/gaze-based-human-computer-interaction/appearance-based-gaze-estimation-in-the-wild</a>	192.168.0.128:5002(Synology) /DataBase/mpiigaze
2	<a href="#">Gaze360</a>	<a href="http://gaze360.csail.mit.edu">http://gaze360.csail.mit.edu</a>	192.168.0.128:5002(Synology) /DataBase/gaze360-normalized
3	<a href="#">GazeCapture</a>	<a href="https://gazecapture.csail.mit.edu/">https://gazecapture.csail.mit.edu/</a>	192.168.0.128:5002(Synology) /DataBase/GazeCapture
4	<a href="#">RT-GENE</a>	<a href="https://zenodo.org/records/2529036">https://zenodo.org/records/2529036</a>	192.168.0.128:5002(Synology) /DataBase/RT_GENE
5	ETH-Xgaze	<a href="https://ait.ethz.ch/xgaze">https://ait.ethz.ch/xgaze</a>	192.168.0.128:5002(Synology) /DataBase/ETH-Xgaze
6	<a href="#">ETH-gaze</a>	404 error	
7	<a href="#">GI4E</a>	<a href="https://www.unavarra.es/gi4e/databases/gi4e/?languageld=1">https://www.unavarra.es/gi4e/databases/gi4e/?languageld=1</a>	192.168.0.128:5002(Synology) /DataBase/GI4E
8	<a href="#">U2eyes</a>	<a href="https://www.unavarra.es/gi4e/databases/u2eyes">https://www.unavarra.es/gi4e/databases/u2eyes</a>	192.168.0.128:5002(Synology) /DataBase/U2Eyes
9	TeyeD_Dikablis	<a href="https://www.v7labs.com/open-datasets/teyed">https://www.v7labs.com/open-datasets/teyed</a>	192.168.0.128:5002(Synology) /DataBase/TeyeD_Dikablis
10	TeyeD_GazeinTheWild	<a href="https://www.v7labs.com/open-datasets/teyed">https://www.v7labs.com/open-datasets/teyed</a>	192.168.0.128:5002(Synology) /DataBase//TEyeD_GazeinTheWild
11	Eye Gaze(Kaggle)	<a href="https://www.kaggle.com/datasets/4quant/eye-gaze">https://www.kaggle.com/datasets/4quant/eye-gaze</a>	192.168.0.128:5002(Synology) /DataBase/Kaggle_Eye_Gaze
12	Synthetic Human Eyes(Kaggle)	<a href="https://www.kaggle.com/datasets/allexmendes/synthetic-human-eyes">https://www.kaggle.com/datasets/allexmendes/synthetic-human-eyes</a>	192.168.0.128:5002(Synology) /DataBase/Synthetic_Human_Eyes
13	RIT-Eyes	<a href="https://cs.rit.edu/~cgaplab/RIT-Eyes/">https://cs.rit.edu/~cgaplab/RIT-Eyes/</a>	192.168.0.128:5002(Synology) /DataBase/RIT_Eyes
14	NVGaze	<a href="https://sites.google.com/nvidia.com/nvgaze">https://sites.google.com/nvidia.com/nvgaze</a>	192.168.0.128:5002(Synology) /DataBase/NVGaze
15	SYNTHESEYES	<a href="https://www.cl.cam.ac.uk/research/rainbow/projects/syntheseyes/">https://www.cl.cam.ac.uk/research/rainbow/projects/syntheseyes/</a>	192.168.0.128:5002(Synology) /DataBase/SynthesEyes

# 1. Gaze\_Dataset 개요

No.	Dataset Name	Official URL	IP / DIR Path
16	UNITYEYES	<a href="https://www.cl.cam.ac.uk/research/rainbow/projects/unityeyes/">https://www.cl.cam.ac.uk/research/rainbow/projects/unityeyes/</a>	192.168.0.128:5002(Synology) /DataBase/UnityEyes
17	UTMULTIVIEW	<a href="https://www.ut-vision.org/datasets/">https://www.ut-vision.org/datasets/</a>	192.168.0.128:5002(Synology) /DataBase/UTMULTIVIEW
18	EYEDIAP	<a href="https://www.idiap.ch/en/dataset/eyediap">https://www.idiap.ch/en/dataset/eyediap</a>	대학소속 연구목적으로 요청 중
19	OpenEDS : Open Eye Dataset	<a href="https://fort.fb.com/researcher-datasets">https://fort.fb.com/researcher-datasets</a>	대학소속 연구목적으로 요청 중
20	<a href="#">ShanghaiTechGaze</a>	<a href="https://github.com/dongzelian/multi-view-gaze">https://github.com/dongzelian/multi-view-gaze</a>	192.168.0.128:5002(Synology) /DataBase//shanghaiTechGaze



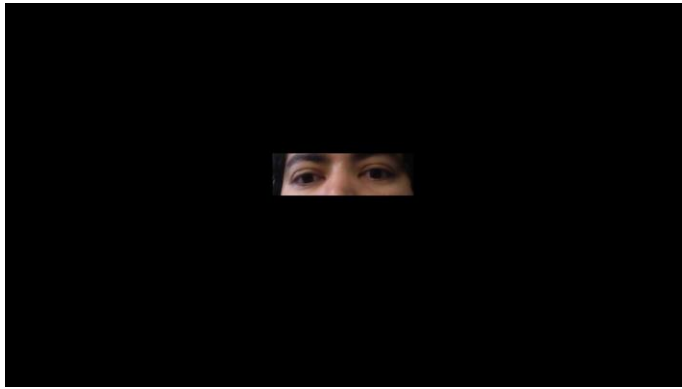
## Annotation 분류

No.	Annotation
1	<a href="#">Gaze_Dataset</a>
2	<a href="#">FaceLandmark_Dataset</a>
3	BoundingBox_Dataset
4	

# 1) Gaze\_Data EDA

- 1. MpiiGaze

## Original



## Crop



## Annotation



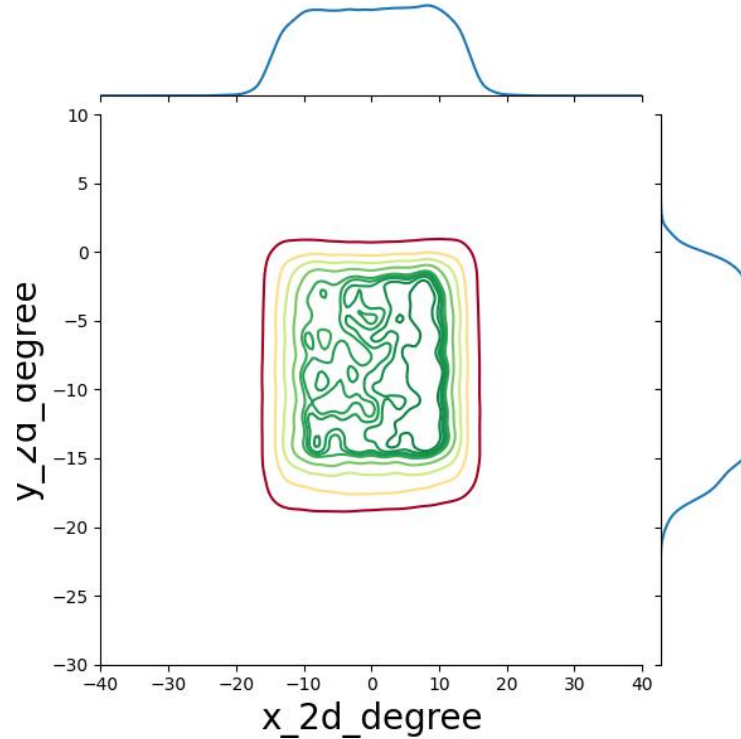
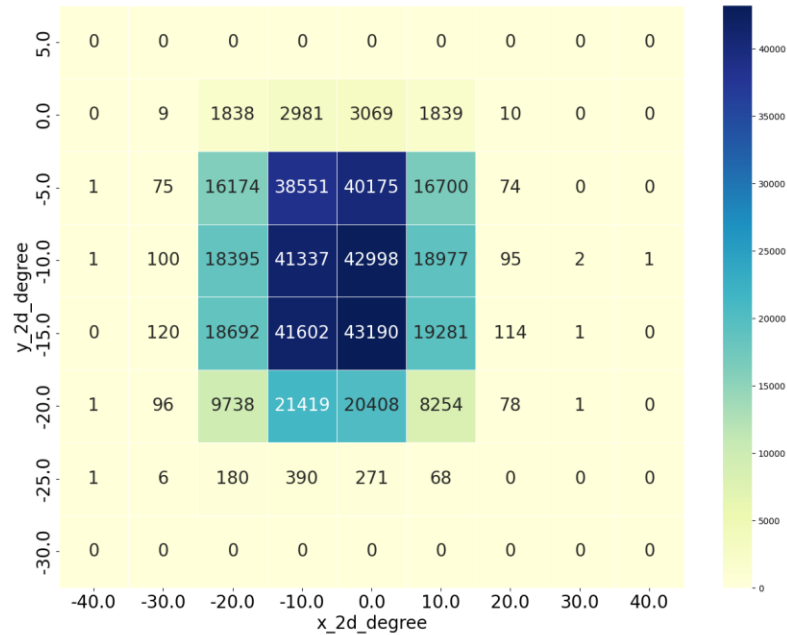
<b>Name</b>	MpiiGaze
<b>Official URL</b>	<a href="https://www.mpi-inf.mpg.de/departments/computer-vision-and-machine-learning/research/gaze-based-human-computer-interaction/appearance-based-gaze-estimation-in-the-wild">https://www.mpi-inf.mpg.de/departments/computer-vision-and-machine-learning/research/gaze-based-human-computer-interaction/appearance-based-gaze-estimation-in-the-wild</a>
<b>IP / DIR Path</b>	192.168.0.128:5002(Synology) /DataBase/mpiigaze
<b>Volume</b>	213,658 (Original) 427,316 (Crop)
<b>Type</b>	RGB real images (Original) Gray Scale images (Crop)
<b>Relevant URL</b>	1. <a href="https://phi-ai.buaa.edu.cn/Gazehub/3D-dataset/#mpiifacegaze">https://phi-ai.buaa.edu.cn/Gazehub/3D-dataset/#mpiifacegaze</a> 2. <a href="https://phi-ai.buaa.edu.cn/Gazehub/Guideline/EyeBased/MPIIGaze.pdf">https://phi-ai.buaa.edu.cn/Gazehub/Guideline/EyeBased/MPIIGaze.pdf</a>
<b>Annotation</b>	<b>3D_Gaze(rad)</b> - Ground truth of normalized 3D gaze direction vector <b>3D_Head</b> - Ground truth of normalized 3D head orientation vector. <b>2D_Gaze(rad)</b> - Ground truth of normalized 2D gaze direction vector <b>2D_Head</b> - Ground truth of normalized 2D head orientation vector <b>Rmat</b> - Rotation vector from original Camera Coordinate System (CCS) to the normalized CCS <b>Smat</b> - The diagonal elements of the scale matrix used in the normalization procedure <b>Gaze_Origin</b> - Origin of 3D gaze vector in the normalized CCS
<b>Image format</b>	JPG
<b>Label format</b>	Mat (Original) Label (Crop)
<b>Resolution</b>	1280 X 720 (Original) 60 X 36 (Crop)



## 1) Gaze\_Data EDA

- 1. MpiiGaze

- 분석(1) 양안(Eye\_gaze)



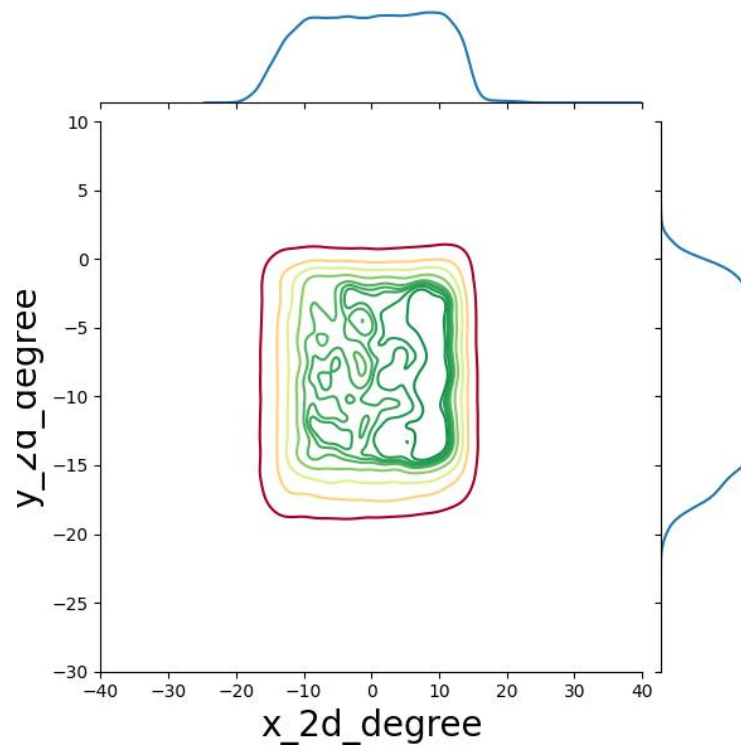
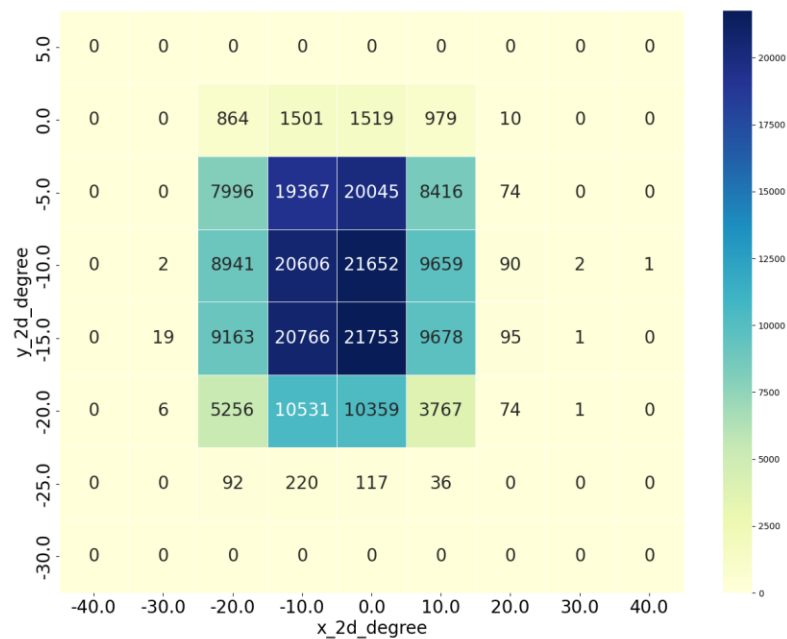
- 2D\_vector = degree
- 정면을 기준으로 아래쪽을 바라보는 데이터 위주로 구성됨



## 1) Gaze\_Data EDA

- 1. MpiiGaze

- 분석(2) 좌안(Eye\_gaze)



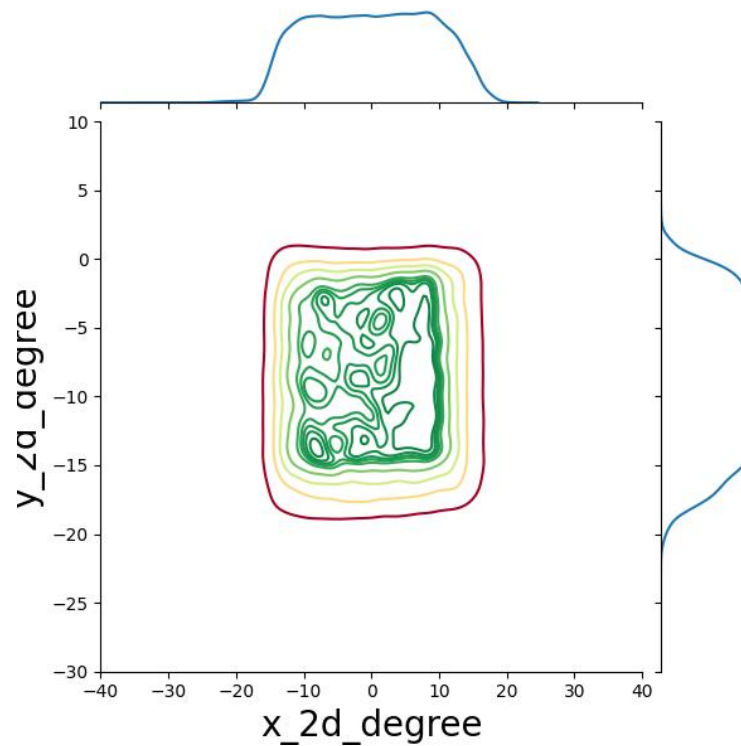
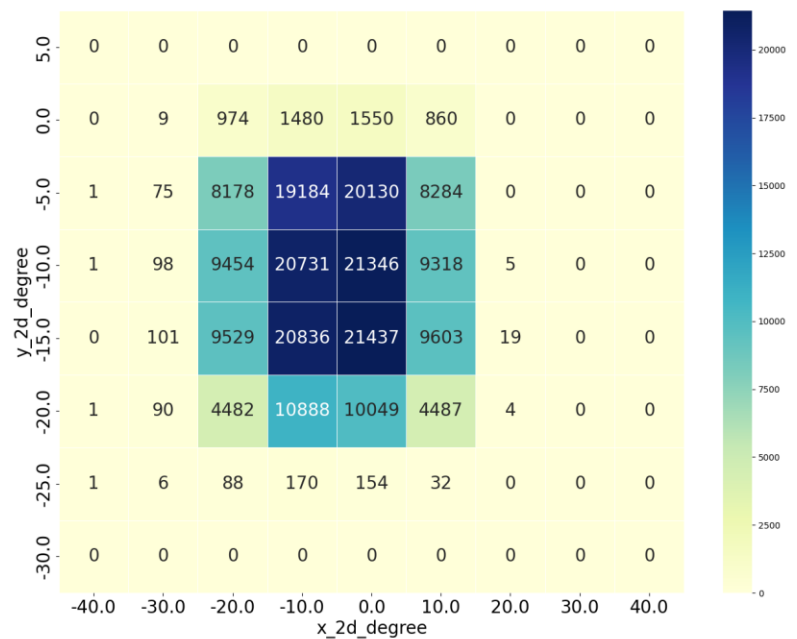
- 2D\_vector = degree
- 정면을 기준으로 아래쪽을 바라보는 데이터 위주로 구성됨



# 1) Gaze\_Data EDA

- 1. MpiiGaze

## • 분석(3) 우안(Eye\_gaze)



- 2D\_vector = degree
- 정면을 기준으로 아래쪽을 바라보는 데이터 위주로 구성됨





## 1) Gaze\_Data EDA

- 1. MpiiGaze

- 분석(4) headpose
- 2D\_vector = degree
- 정면을 기준으로 아래쪽을 바라보는 데이터 위주로 구성됨



## 1) Gaze\_Data EDA

- 1. MpiiGaze

- 특이사항

```
if which_eye == "left":  
    pass  
else:  
    im_eye = cv2.flip(im_eye, 1)  
    gaze = dpc.GazeFlip(gaze)  
    head = dpc.HeadFlip(head)  
    origin[0] = -origin[0]  
gaze_2d = dpc.GazeTo2d(gaze)  
head_2d = dpc.HeadTo2d(head)  
  
rvec, svec = norm.GetParams()
```



우측 눈 이미지와 우측 눈의 각 수치들이 좌우 반전



# 1) Gaze\_Data EDA

- 2. Gaze360

Original



<b>Name</b>	Gaze360
<b>Official URL</b>	<a href="http://gaze360.csail.mit.edu">http://gaze360.csail.mit.edu</a>
<b>IP / DIR Path</b>	192.168.0.128:5002(Synology) /DataBase/gaze360-normalized
<b>Volume</b>	124,831 images (Face cropped)
<b>Type</b>	RGB real images (Face cropped)
<b>Relavant URL</b>	1. <a href="https://openaccess.thecvf.com/content_ICCV_2019/papers/Kellnhofer_Gaze360_Physically_Unconstrained_Gaze_Estimation_in_the_Wild_ICCV_2019_paper.pdf">https://openaccess.thecvf.com/content_ICCV_2019/papers/Kellnhofer_Gaze360_Physically_Unconstrained_Gaze_Estimation_in_the_Wild_ICCV_2019_paper.pdf</a> 2. <a href="https://phi-ai.buaa.edu.cn/Gazehub/3D-dataset/#gaze360">https://phi-ai.buaa.edu.cn/Gazehub/3D-dataset/#gaze360</a>
<b>Annotation</b>	<b>3DGaze</b> - Ground truth of 3D gaze direction vector. <b>2DGaze</b> - Ground truth of 2D gaze direction vector i.e. yaw and pitch.
<b>Image format</b>	JPG
<b>Label format</b>	Label
<b>Resolution</b>	224 X 224



## 1) Gaze\_Data EDA

- 2. Gaze360

- 분석



# 1) Gaze\_Data EDA

- 3. GazeCapture

## Original



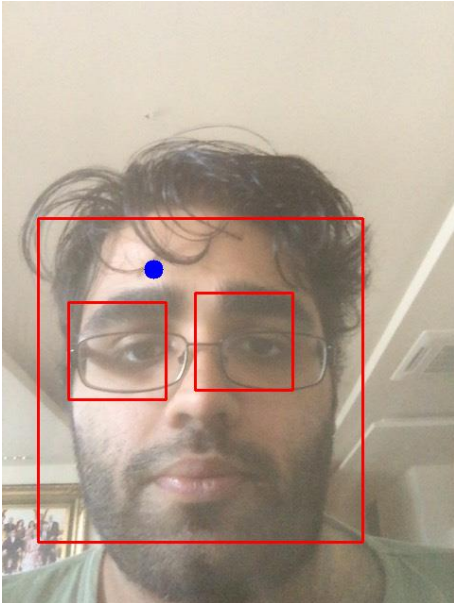
<b>Name</b>	GazeCapture
<b>Official URL</b>	<a href="https://gazecapture.csail.mit.edu/">https://gazecapture.csail.mit.edu/</a>
<b>IP / DIR Path</b>	192.168.0.128:5002(Synology) /DataBase/GaceCapture
<b>Volume</b>	2,445,504 images 1,474 ids
<b>Type</b>	RGB real images
<b>Relavant URL</b>	1. <a href="https://gazecapture.csail.mit.edu/cvpr2016_gazecapture.pdf">https://gazecapture.csail.mit.edu/cvpr2016_gazecapture.pdf</a> 2. <a href="https://github.com/CSAILVision/GazeCapture">https://github.com/CSAILVision/GazeCapture</a>
<b>Image format</b>	JPG
<b>Label format</b>	JSON
<b>Resolution</b>	Various Standards



# 1) Gaze\_Data EDA

- 3. GazeCapture

## Annotation



Annotation		
*Face.json	Face bbox (x, y, w, h)	It is relative to the top-left corner of the full frame (red box)
*Eye.json	eye bbox (x, y, w, h)	It is relative to the top-left corner of the face crop (red box)
dotInfo.json	Dot pts (x, y)	Position of the center of the dot (blue point)
	Dot cam (x, y)	Position of the center of the dot in prediction space. (unit: cm)
faceGrid.json	Face grid (x, y, w, h)	Position of the top-left corner of the face box (25 x 25)
Motion.json		A stream of motion data (accelerometer, gyroscope, and magnetometer)
Screen.json	Screen area (h, w)	Height and width of the active screen area of the app (in points)
	Orientation	1: portrait 2: portrait, upside down (iPad only) 3: landscape, with home button on the right 4: landscape, with home button on the left

## • 특이사항

- bounding box와 앱 상에서 나타나는 포인트를 바라보는 방식으로 Gaze Angle을 계산해야 하는 Dataset으로 확인



# 1) Gaze\_Data EDA

- 4. RT-GENE

Face



Left Eye



Right Eye

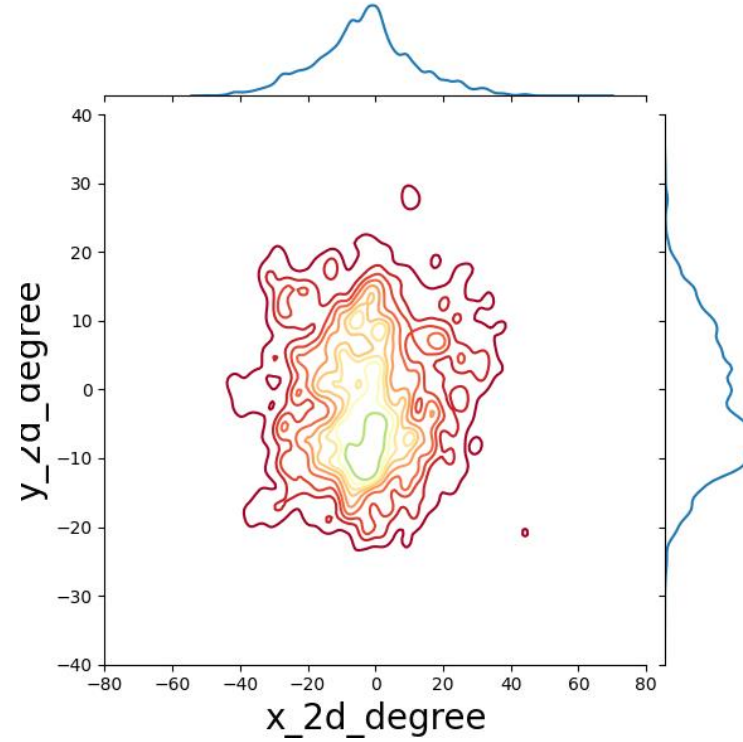
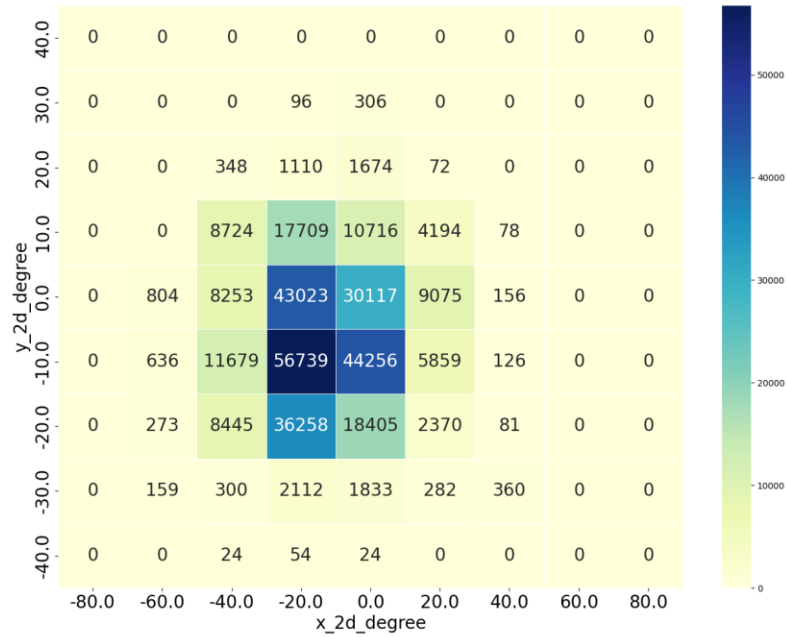


<b>Name</b>	RT-GENE
<b>Official URL</b>	<a href="https://zenodo.org/records/2529036">https://zenodo.org/records/2529036</a>
<b>IP / DIR Path</b>	192.168.0.128:5002(Synology) /DataBase/RT_GENE
<b>Volume</b>	326,895 (Face) 326,895 (Left eye) 326,895 (Right eye)
<b>Type</b>	Real RGB Images
<b>Relavant URL</b>	<a href="https://github.com/Tobias-Fischer/rt_gene">1. https://github.com/Tobias-Fischer/rt_gene</a> <a href="https://openaccess.thecvf.com/content_ECCV_2018/papers/Tobias_Fischer_RT-GENE_Real-Time_Eye_ECCV_2018_paper.pdf">2. https://openaccess.thecvf.com/content_ECCV_2018/papers/Tobias_Fischer_RT-GENE_Real-Time_Eye_ECCV_2018_paper.pdf</a> <a href="https://openaccess.thecvf.com/content_ICCVW_2019/papers/GAZE/Cortacero_RT-BENE_A_Dataset_and_Baselines_for_Real-Time_Blink_Estimation_in_ICCVW_2019_paper.pdf">3. https://openaccess.thecvf.com/content_ICCVW_2019/papers/GAZE/Cortacero_RT-BENE_A_Dataset_and_Baselines_for_Real-Time_Blink_Estimation_in_ICCVW_2019_paper.pdf</a>
<b>Annotation</b>	<b>3D_Gaze(rad)</b> - Ground truth of normalized 3D gaze direction vector <b>3D_Head</b> - Ground truth of normalized 3D head orientation vector. <b>2D_Gaze(rad)</b> - Ground truth of normalized 2D gaze direction vector <b>2D_Head</b> - Ground truth of normalized 2D head orientation vector
<b>Image format</b>	png
<b>Label format</b>	label
<b>Resolution</b>	224 X 224



# 1) Gaze\_Data EDA

- 4. RT-GENE



- 2D\_vector = degree





## 1) Gaze\_Data EDA

- 4. RT-GENE

- 특이사항

-



## 1) Gaze\_Data EDA

- 5. ETH-Xgaze  
original



### Annotation - Gaze

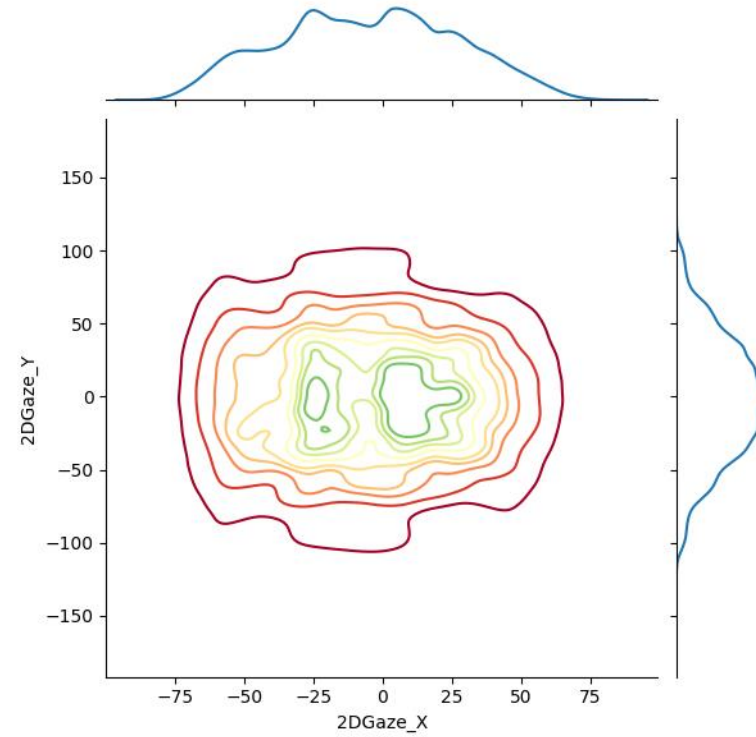
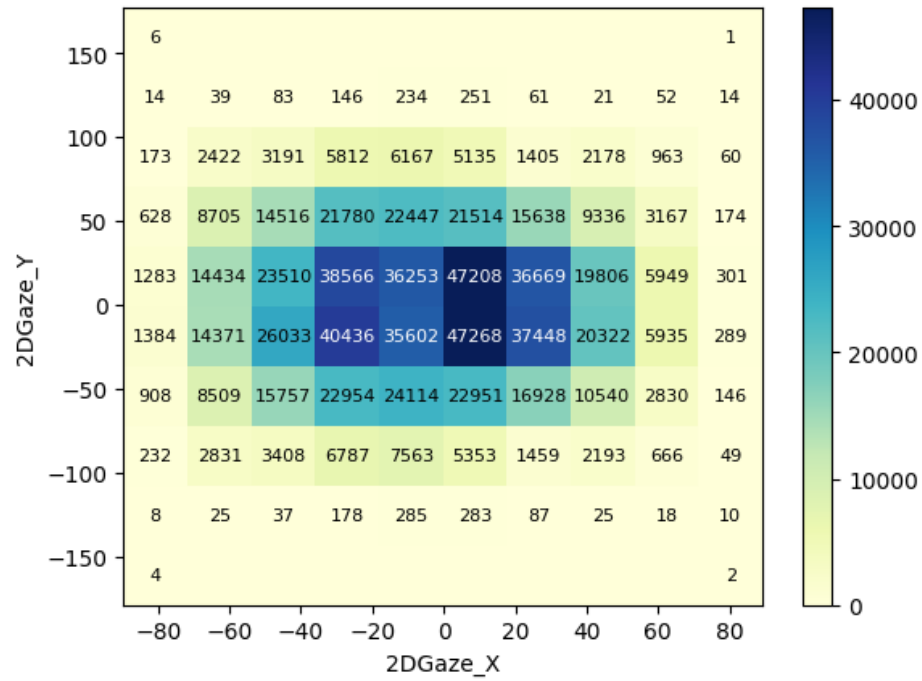


<b>Name</b>	ETH-Xgaze
<b>Official URL</b>	<a href="https://ait.ethz.ch/xgaze">https://ait.ethz.ch/xgaze</a>
<b>IP / DIR Path</b>	192.168.0.128:5002(Synology) /DataBase/ETH-Xgaze
<b>Volume</b>	Total 1083492 Id – 110
<b>Type</b>	RGB real image
<b>Relavant URL</b>	<a href="https://files.ait.ethz.ch/projects/xgaze/xucongzhang2020eccv.pdf">https://files.ait.ethz.ch/projects/xgaze/xucongzhang2020eccv.pdf</a>
<b>Annotation</b>	<ul style="list-style-type: none"> <li>- frame_index: the frame index of the image</li> <li>- cam_index: the camera index of the image range from 0 to 17</li> <li>- face_patch: the face patch image with size of number of samples * 448 * 448 * 3</li> <li>- face_mat_norm: the rotation matrix during data normalization</li> <li>- face_head_pose: the normalized head pose with size of 2 dimensions horizontal and vertical head rotations.</li> <li>- face_gaze: the normalized gaze direction with size of 2 dimensions a s horizontal and vertical gaze directions.</li> </ul>
<b>Image format</b>	jpg
<b>Label format</b>	h5, label
<b>Resolution</b>	448X448



# 1) Gaze\_Data EDA

- 5. ETH-Xgaze



- 2D\_vector = degree



## 1) Gaze\_Data EDA

- 5. ETH-Xgaze

- 테스트 데이터셋에는 gaze 라벨값이 들어있지 않아 train 데이터셋만 라벨링 진행



## 1) Gaze\_Data EDA

- 6. ETH-gaze

- 특이사항

[Publications](#)[People](#)[Data & Code](#)[Teaching](#)[Thesis](#)[Jobs](#)[Contact](#)[🔍 Search Publications, Teaching, etc](#)

# 404

Page not found :(

The requested page could not be found.

관련 페이지 탐색 불가 - 다른 경로로 탐색 필요



# 1) Gaze\_Data EDA

- 7. GI4E



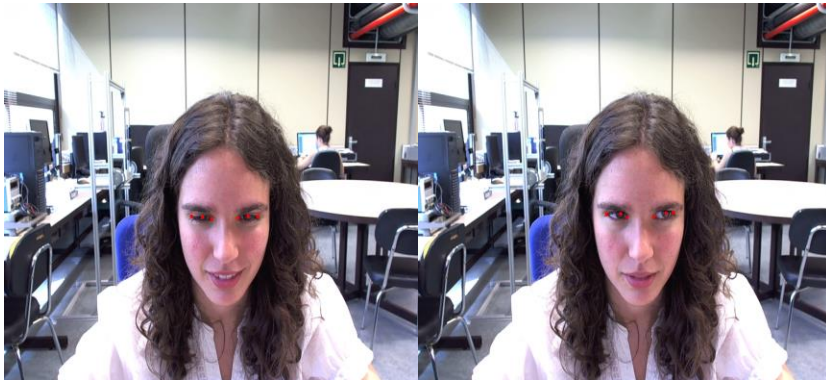
<b>Name</b>	GI4E
<b>Official URL</b>	<a href="https://www.unavarra.es/gi4e/databases/gi4e/?languageId=1">https://www.unavarra.es/gi4e/databases/gi4e/?languageId=1</a>
<b>IP / DIR Path</b>	192.168.0.180(A6000) /home/disk2/gaze/GI4E
<b>Volume</b>	1,236 images
<b>Type</b>	RGB real images
<b>Relavant URL</b>	None
<b>Annotation</b>	Eye Landmark_3 points
<b>Image format</b>	PNG
<b>Label format</b>	TXT
<b>Resolution</b>	800 X 600



## 1) Gaze\_Data EDA

- 7. GI4E

- 특이사항



1. Gaze Angle 분석에 필요한 Annotation(\*) 및 Information 부족으로 Gaze Angle 학습용 데이터로는 부적합(\*\*)

(\*) : head pose data or gaze angle data

(\*\*) : Only 3 Landmarks for each eyes

001_01.png	490.63	338.28	471.22	338.41	452.86	341.93	401.95	342.45	383.33	339.84	362.63	338.41
001_02.png	493.49	332.94	479.30	333.33	455.86	340.23	404.69	340.11	391.02	334.50	364.58	335.81
001_03.png	495.05	333.86	477.47	332.94	458.07	339.32	407.29	339.71	389.45	333.33	368.88	334.89
001_04.png	493.62	334.25	472.66	332.42	456.38	338.80	405.08	340.11	385.03	334.11	367.84	336.46
001_05.png	495.83	333.33	470.57	331.64	457.68	338.02	406.77	339.45	382.81	333.33	369.92	334.38
001_06.png	496.22	336.20	474.48	335.29	458.46	339.45	407.81	340.89	386.46	336.72	369.79	336.20
001_07.png	495.31	336.46	474.87	335.81	458.07	340.89	407.55	342.19	386.98	337.76	370.18	337.24
001_08.png	496.22	337.11	479.43	336.98	459.64	341.54	408.98	342.32	390.89	337.89	370.96	337.89
001_09.png	496.88	337.37	484.11	337.63	460.68	342.45	410.29	342.58	396.22	338.80	371.22	338.41
001_10.png	497.79	340.23	483.20	341.02	461.07	343.75	410.55	343.36	395.44	341.93	371.75	341.41
001_11.png	495.96	343.88	476.04	343.88	458.46	346.36	407.94	347.53	387.63	345.83	369.27	344.14
001_12.png	498.70	343.88	474.87	342.97	460.29	346.09	409.77	347.27	386.98	344.92	371.61	342.71



# 1) Gaze\_Data EDA

- 8. U2Eyes



<b>Name</b>	U2Eyes
<b>Official URL</b>	<a href="https://www.unavarra.es/gi4e/databases/u2eyes">https://www.unavarra.es/gi4e/databases/u2eyes</a>
<b>IP / DIR Path</b>	192.168.0.128:5002(Synology) /DataBase/U2Eyes
<b>Volume</b>	117,500 images
<b>Type</b>	RGB Synthetic images
<b>Relavant URL</b>	<a href="https://openaccess.thecvf.com/content_ICCVW_2019/papers/OpenEDS/Porta_U2Eyes_A_Binocular_Dataset_for_Eye_Tracking_and_Gaze_Estimation_ICCVW_2019_paper.pdf">https://openaccess.thecvf.com/content_ICCVW_2019/papers/OpenEDS/Porta_U2Eyes_A_Binocular_Dataset_for_Eye_Tracking_and_Gaze_Estimation_ICCVW_2019_paper.pdf</a>
<b>Annotation</b>	Head Pose <ul style="list-style-type: none"> <li>• Rotation – x, y, z (roll, pitch, yaw)</li> <li>• Position – x, y, z (coordinate)</li> <li>• LookAtPoint – x, y, z (coordinate)</li> </ul> POI (landmark) <ul style="list-style-type: none"> <li>• 2D vector - Caruncle, InteriorMargin, Iris, Pupil, IrisCenter, PupilCenter, CorneaCenter, GlobeCenter</li> <li>• 3D vector - Caruncle, InteriorMargin, Iris, Pupil, IrisCenter, PupilCenter, CorneaCenter, GlobeCenter</li> </ul>
<b>Image format</b>	PNG
<b>Label format</b>	XML
<b>Resolution</b>	3840 X 2160





## 1) Gaze\_Data EDA

- 8. U2Eyes

- 특이사항



# 1) Gaze\_Data EDA

- 9. TeyeD\_Dikablis

Name	
Official URL	
IP / DIR Path	
Volume	
Type	
Relavant URL	
Annotation	
Image format	
Label format	
Resolution	



## 1) Gaze\_Data EDA

- 9. TeyeD\_Dikablis

- 특이사항

1. 데이터 확인 결과 mp4 포맷, 프레임별 라벨링이 되어 있어서 1 프레임 당 이미지를 저장하는 전처리 진행 예정



# 1) Gaze\_Data EDA

- 10. TeyeD\_GazeinTheWild

<b>Name</b>	TeyeD_GazeinTheWild
<b>Official URL</b>	<a href="https://www.v7labs.com/open-datasets/teyed">https://www.v7labs.com/open-datasets/teyed</a>
<b>IP / DIR Path</b>	192.168.0.128:5002(Synology) /DataBase//TEyeD_GazeinTheWild
<b>Volume</b>	
<b>Type</b>	IR
<b>Relavant URL</b>	<a href="https://arxiv.org/pdf/2102.02115.pdf">https://arxiv.org/pdf/2102.02115.pdf</a>
<b>Annotation</b>	
<b>Image format</b>	mp4
<b>Label format</b>	txt
<b>Resolution</b>	



## 1) Gaze\_Data EDA

- 10. TeyeD\_GazeinTheWild

- 특이사항

1. 데이터 확인 결과 mp4 포맷, 프레임별 라벨링이 되어 있어서 1 프레임 당 이미지를 저장하는 전처리 진행 예정



# 1) Gaze\_Data EDA

- 11. Eye\_Gaze

Name	
Official URL	
IP / DIR Path	
Volume	
Type	
Relavant URL	
Annotation	
Image format	
Label format	
Resolution	



## 1) Gaze\_Data EDA

- 11. Eye\_Gaze

- 특이사항

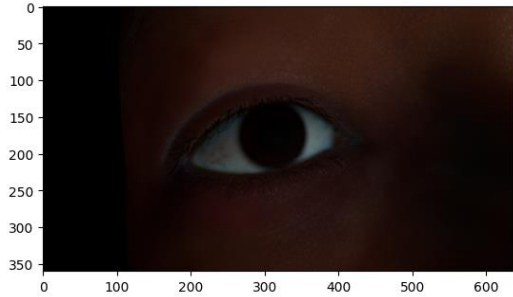
1. 데이터 분석결과 MPIIGaze와 동일한 Dataset으로 확인 됨  
[MPIIGaze](#)



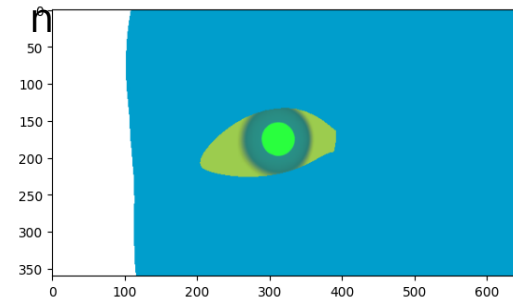
# 1) Gaze\_Data EDA

## - 12. Synthetic Human Eyes

Lit



segmentatio



<b>Name</b>	Sysnthetic Human Eyes(Kaggle)
<b>Official URL</b>	<a href="https://www.kaggle.com/datasets/allexmendes/synthetic-human-eyes">https://www.kaggle.com/datasets/allexmendes/synthetic-human-eyes</a>
<b>IP / DIR Path</b>	192.168.0.128:5002(Synology) /DataBase/Sysnthetic_Human_Eyes
<b>Volume</b>	Lit – 49999 Segmentation - 49999
<b>Type</b>	RGB
<b>Relavant URL</b>	<a href="https://arxiv.org/pdf/2102.02115.pdf">https://arxiv.org/pdf/2102.02115.pdf</a> <a href="https://www.kaggle.com/code/allexmendes/draw-projected-keypoints/notebook?scriptVersionId=59006081&amp;cellId=3">https://www.kaggle.com/code/allexmendes/draw-projected-keypoints/notebook?scriptVersionId=59006081&amp;cellId=3</a>
<b>Image format</b>	png
<b>Label format</b>	json
<b>Resolution</b>	640X360





# 1) Gaze\_Data EDA

## - 12. Synthetic Human Eyes

### Annotation - Landmark

Frame: 00007



### Annotation - Gaze



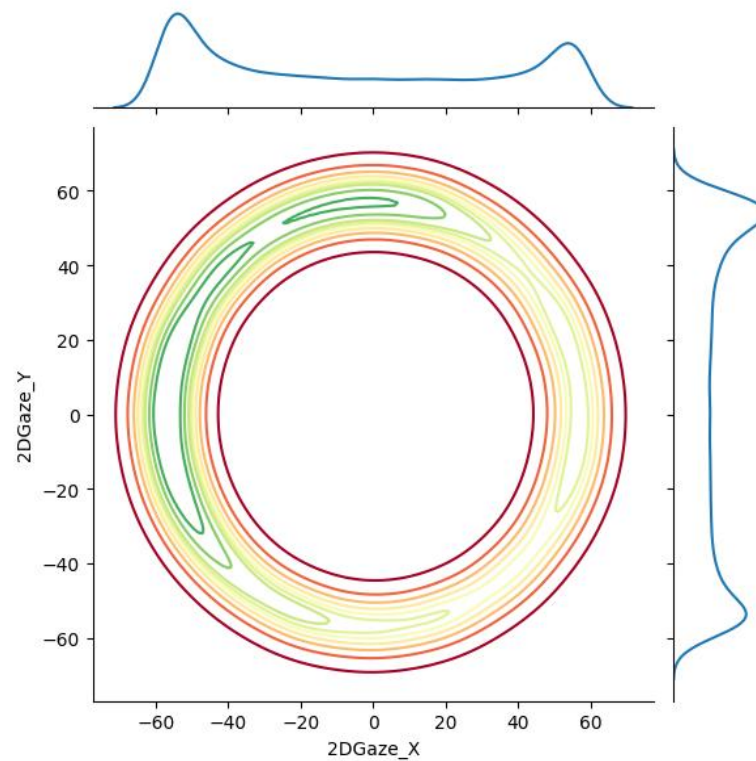
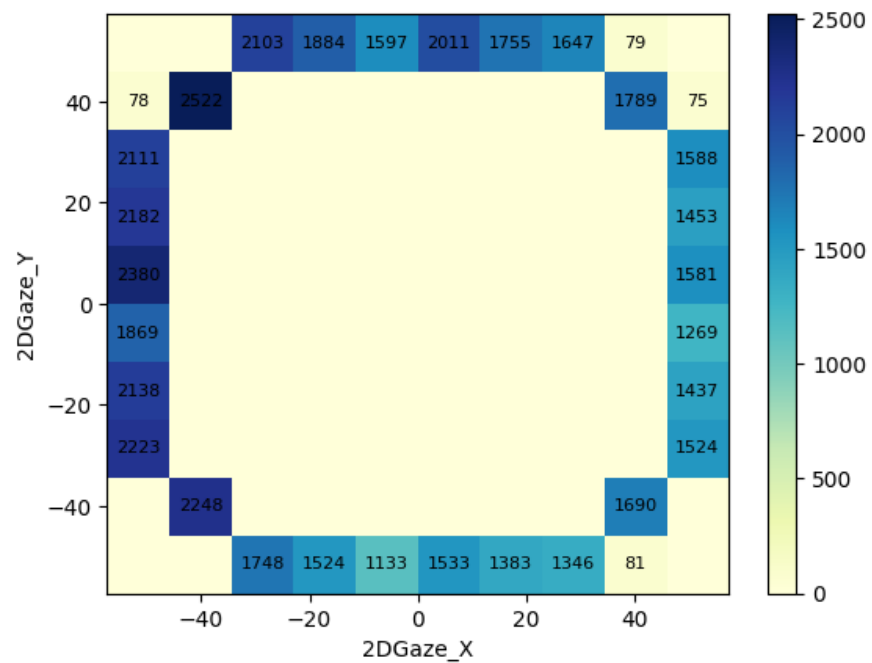
Annotation	Camera	ViewProjection - 4x4 matrix It's known as the ViewProjection matrix, often used in the transformation of 3D points into 2D space for rendering
	Overall	Side - indicates which eye is being shown in matching images ("Left" or "Right")
		GazeWorld - Ground truth of normalized 3D gaze direction vector
		GazeImage - Ground truth of normalized 2D gaze direction vector
	Parameters	EyeBlink - The amount of eye blinking.
		EyeLookDown - Eye rotation towards the downside of the face.
		EyeLookIn - Eye rotation towards the inside of the face.
		EyeLookOut - Eye rotation towards the outside of the face.
		EyeLookUp - Eye rotation towards the upside of the face.
		EyeSquint - A measure of how much you squint your eyes.
	Keypoints	EyeWide - A value equivalent to having your eyes wide open. Note: Cancels the effect of "EyeBlink" if both have similar values.
		PupilOffset - how much the pupils have moved or shifted from that reference
		EyelidLower1 - positions of the lower eyelid
		EyelidLower2 - positions of the lower eyelid
		EyelidLower3 - positions of the lower eyelid
		EyeCornerOuter - positions of the outer corner of the eye.
		EyeCornerOuter1 - positions of the outer corner of the eye.
		EyeCornerOuter2 - positions of the outer corner of the eye.
		EyeCornerInner - positions of the inner corner of the eye
		EyeCornerInner1 - positions of the inner corner of the eye
		EyeCornerInner2 - positions of the inner corner of the eye
		EyePupil - positions of the pupil
		EyelidUpper1 - positions of the upper eyelid
		EyelidUpper2 - positions of the upper eyelid
		EyelidUpper3 - positions of the upper eyelid



# 1) Gaze\_Data EDA

- 12. Synthetic Human Eyes

- 분석



- 2D\_vector = degree



## 1) Gaze\_Data EDA

### - 12. Synthetic Human Eyes

- 특이사항

```
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/01662.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/06092.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/11106.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/11920.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/17640.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/21852.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/21930.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/22185.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/23277.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/25141.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/25550.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/26888.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/28074.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/33963.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/42486.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/42955.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/46999.json
Key 'Overall' not found in nsmount/Sysnthetic Human Eyes/data/RGB/labeldata/47022.json
```

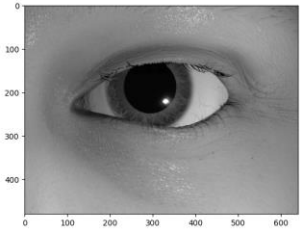
다음 해당하는 18개의 데이터 라벨이 존재하지 않았다.



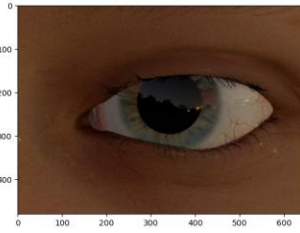
# 1) Gaze\_Data EDA

- 13. RIT-Eyes

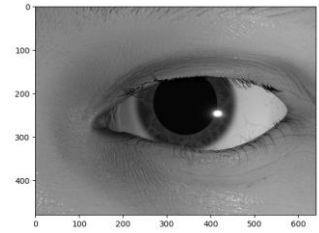
S-general



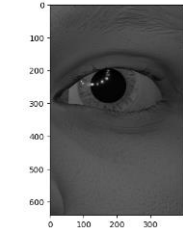
S-natural



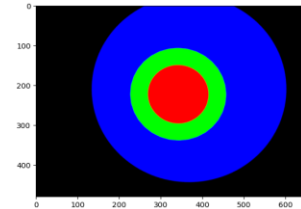
S-nvgaze



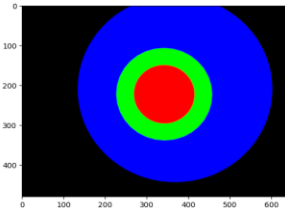
S-openeds



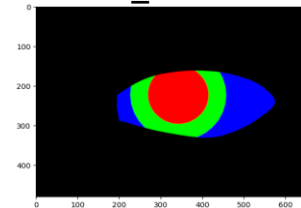
Without\_skin



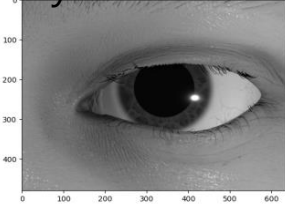
No glasses



With\_skin



synthetic



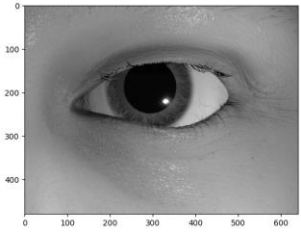
<b>Name</b>	RIT-Eyes
<b>Official URL</b>	<a href="https://cs.rit.edu/~cgaplab/RIT-Eyes/">https://cs.rit.edu/~cgaplab/RIT-Eyes/</a>
<b>IP / DIR Path</b>	192.168.0.128:5002(Synology) /DataBase/RIT_Eyes
<b>Volume</b>	S_general(synthetic) - 48000 (id-24) S_natural(synthetic) - 48000 (id-24) S_nvgaze(synthetic) - 51600 (id-24) S_openeds(synthetic) - 51600 (id-24))
<b>Type</b>	IR (S_general,S _nvgaze,S_openeds) RGB (S_natural)
<b>Relavant URL</b>	<a href="https://arxiv.org/pdf/2006.03642v1.pdf">https://arxiv.org/pdf/2006.03642v1.pdf</a>
<b>Image format</b>	tif
<b>Label format</b>	p
<b>Resolution</b>	S_general 640X480 S_natural 640X480 S_nvgaze 640X480 S_openeds 400X640



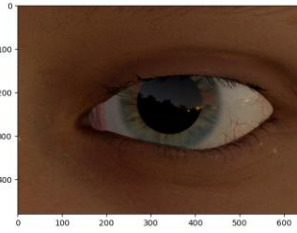
# 1) Gaze\_Data EDA

- 13. RIT-Eyes

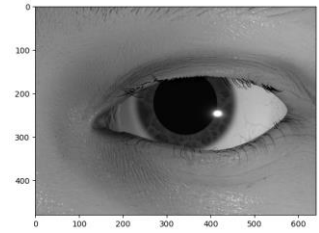
S-general



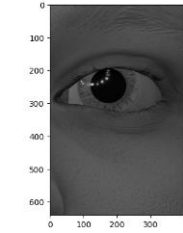
S-natural



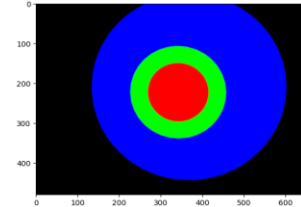
S-nvgaze



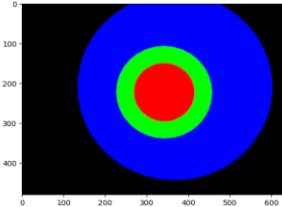
S-openeds



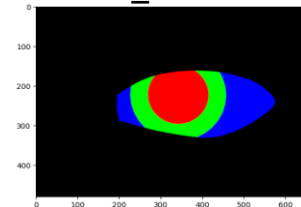
Without\_skin



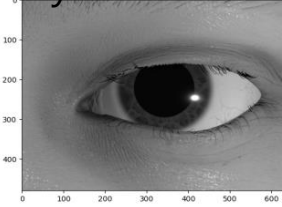
No glasses



With\_skin



synthetic



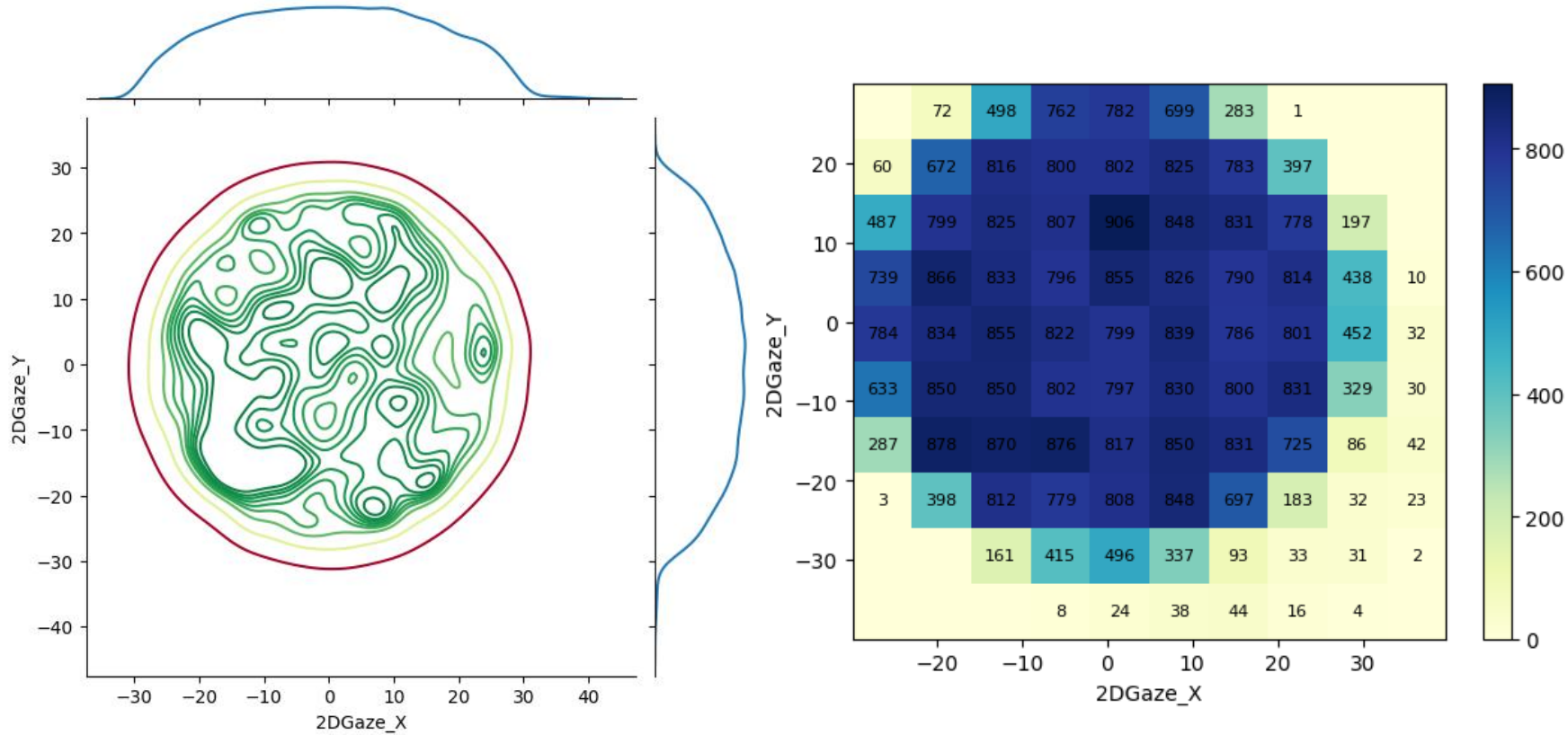
Annotation		
Camera_info	camera_3d_center	3D coordinates of the camera center.
	camera_distance	Distance from the camera to the eye.
	cam_az	Camera azimuth (horizontal angle of the camera).
	cam_el	Camera elevation angle (vertical angle of the camera).
	ortho_scale	The relevant orthoscale if it is an orthogonal projection.
	ortho_scale	The relevant orthoscale if it is an orthogonal projection.
Gaze	gaze_angle_az	Gaze angle in azimuth (horizontal direction).
	gaze_angle_el	Gaze angle (vertical) in elevation.
Eye_info	glasses	Information related to glasses, their possible presence, or characteristics.
	sclera	Information, possible characteristics, related to cells in the white part of the eye.
Landmark	iris_loc	3D coordinates of the iris center.
	eye_loc	3D coordinates of the eye center.
	pupil	Information related to the pupil, its possible size, or shape.
	eye_lid	Information related to the eyelid, possible location, or condition.
	iris_rot	Iris rotation information, possible directions.
	left_corner	3D coordinates of the left corner of the eye.
	right_corner	3D coordinates of the right corner of the eye.



# 1) Gaze\_Data EDA

- 13. RIT-Eyes

- 분석 s - natural



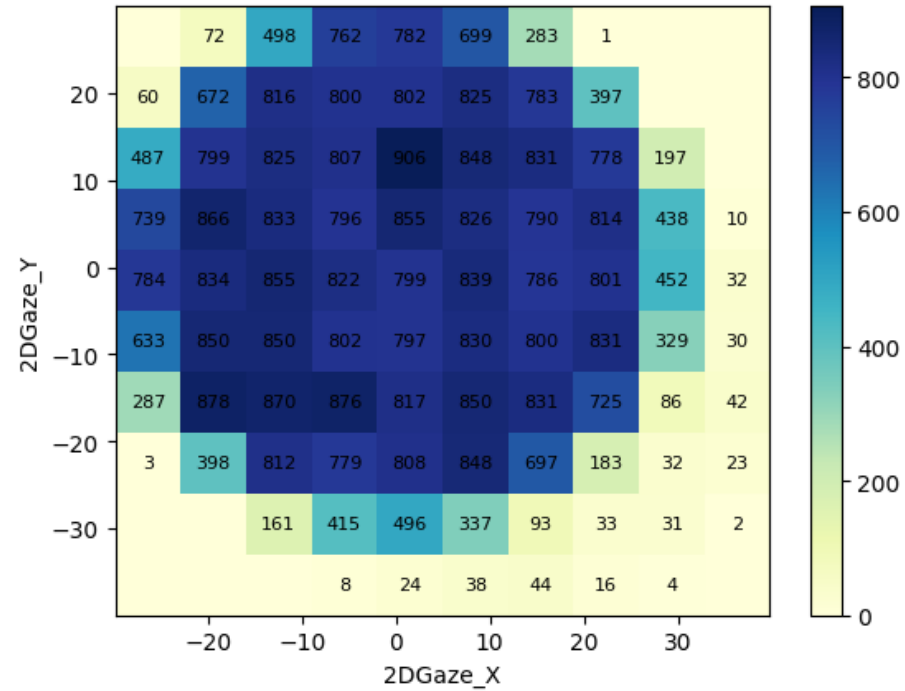
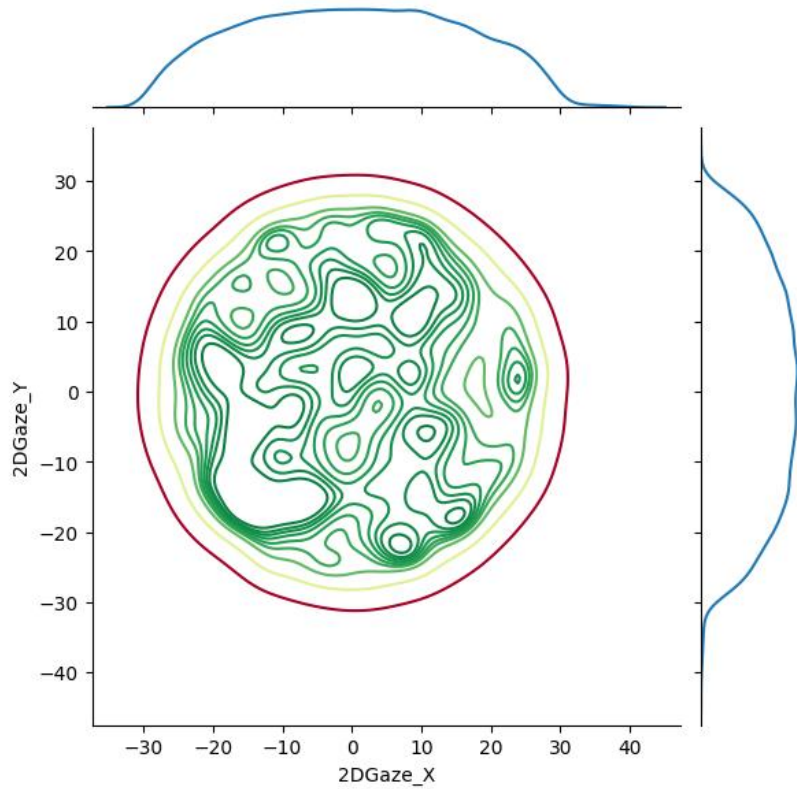
- degree



# 1) Gaze\_Data EDA

- 13. RIT-Eyes

- 분석 s - general



- degree

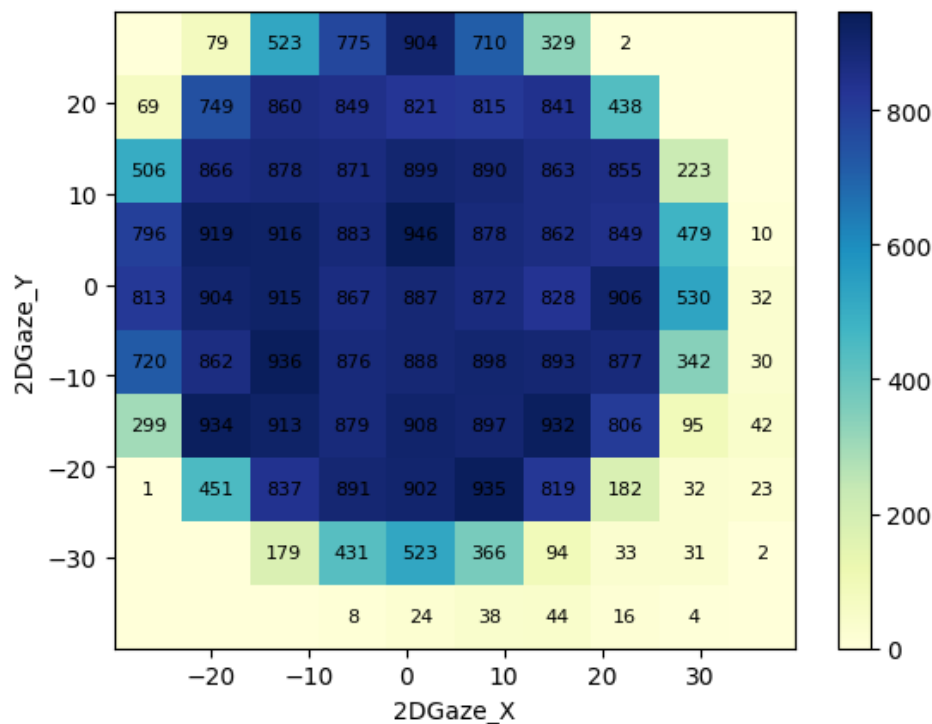
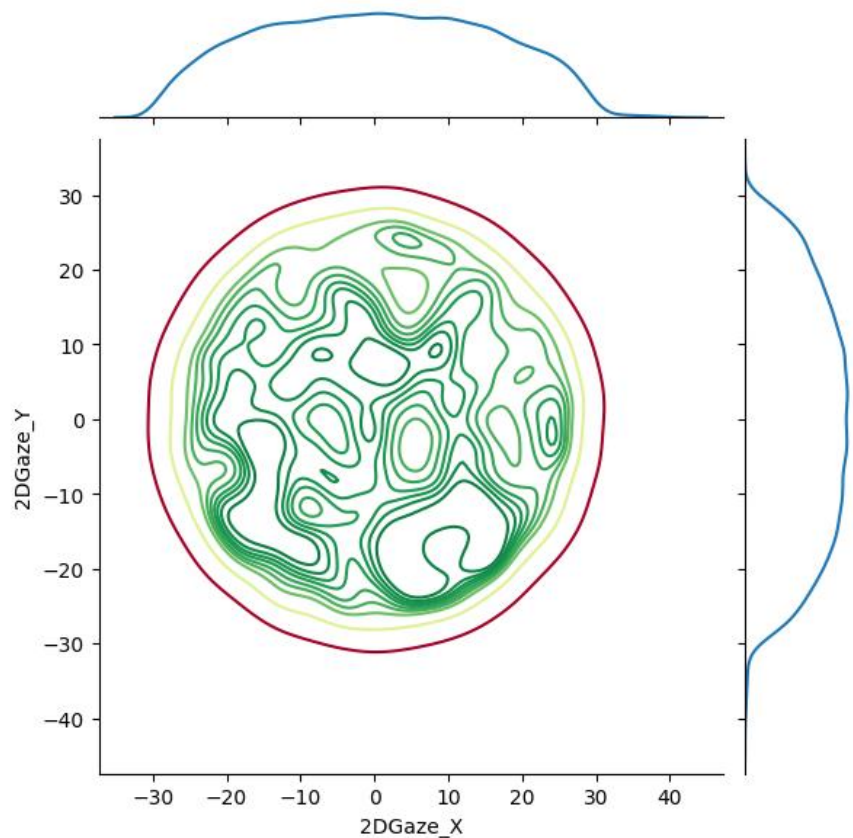




# 1) Gaze\_Data EDA

- 13. RIT-Eyes

- 분석 s - opens



- degree





- 13. RIT-Eyes

- 특이사항

ORIGINAL DATA는 존재하지않고 추출된 정보로 합성된 데이터만 존재

## 정규화된 좌표값들만 존재

S- nvgaze dataset에서 gaze\_x 와 gaze\_y값의 수가 맞지 않음

```
p_path = "nsmount/Rit_Eyes/data/IR/labeldata/s-nvgaze"

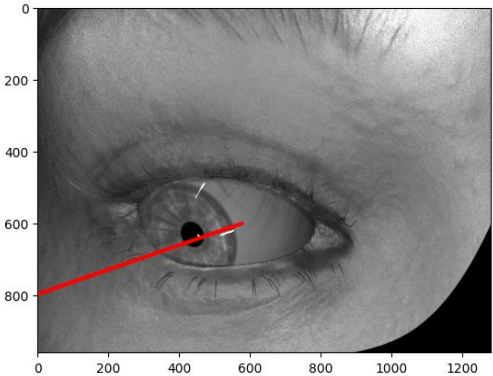
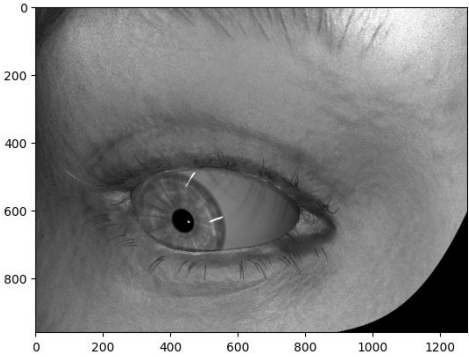
#for file name in tqdm(os.listdir(p_path), desc="processing Image files"):
for folder_name in os.listdir(p_path):
    folder_path = os.path.join(p_path, folder_name)

    for file_name in os.listdir(folder_path):
        file_path = os.path.join(folder_path, file_name)
        # Check if the file is a .label file
        if file_name.endswith(".p"):
            # Load data from the pickle file
            with open(file_path, 'rb') as file:
                data1 = pickle.load(file)
                print(len(data1["gaze_angle_az"]),len(data1["gaze_angle_el"]))
```



# 1) Gaze\_Data EDA

- 14. NVGaze



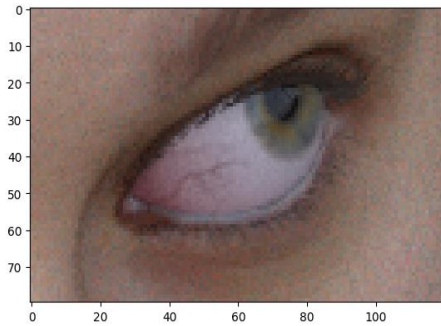
<b>Name</b>	NVGaze
<b>Official URL</b>	<a href="https://www.cl.cam.ac.uk/research/rainbow/projects/syntheseyes/">https://www.cl.cam.ac.uk/research/rainbow/projects/syntheseyes/</a>
<b>IP / DIR Path</b>	192.168.0.128:5002(Synology) /DataBase/SynthesEyes
<b>Volume</b>	Real Id - 42 2264127(crop) synthe Id – 10 (male – 5, female – 5)
<b>Type</b>	IR
<b>Relavant URL</b>	<a href="https://drive.google.com/file/d/10_qiwrIAM3Kk7eXW4moGE8ib4Ut3q050/view">https://drive.google.com/file/d/10_qiwrIAM3Kk7eXW4moGE8ib4Ut3q050/view</a> <a href="https://drive.google.com/file/d/1aGg2_Lm6KG4q5WztHWc6MkTtO4OXjtoo/view">https://drive.google.com/file/d/1aGg2_Lm6KG4q5WztHWc6MkTtO4OXjtoo/view</a>
<b>Annotation</b>	
<b>Image format</b>	png
<b>Label format</b>	csv
<b>Resolution</b>	1280X960



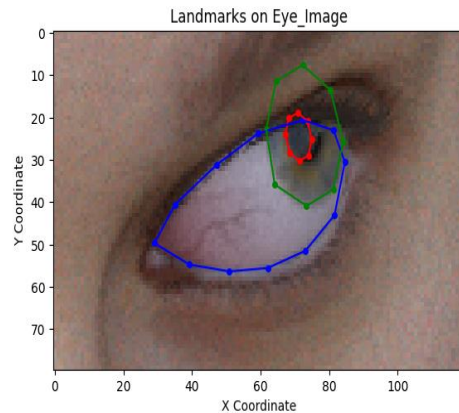
# 1) Gaze\_Data EDA

- 15. SYNTHSEYES

## Crop



## Annotation(Gaze, Landmark)



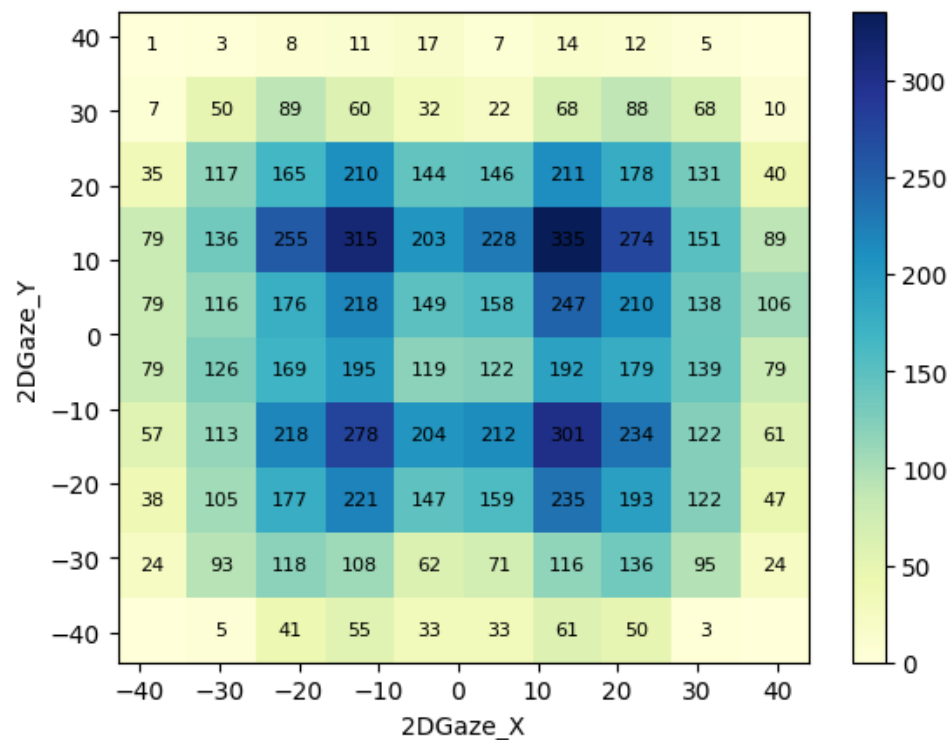
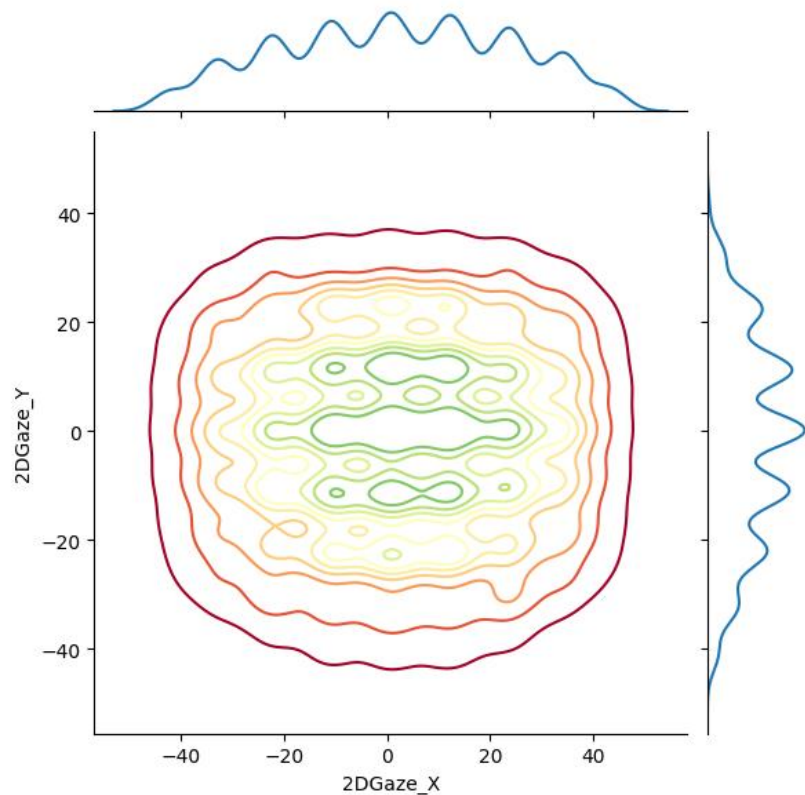
<b>Name</b>	SYNTHESEYES
<b>Official URL</b>	<a href="https://www.cl.cam.ac.uk/research/rainbow/projects/syntheseeyes/">https://www.cl.cam.ac.uk/research/rainbow/projects/syntheseeyes/</a>
<b>IP / DIR Path</b>	192.168.0.128:5002(Synology) /DataBase/SynthesEyes
<b>Volume</b>	11382 (Crop) Id – 10 (male – 5, female – 5)
<b>Type</b>	RGB real images (Crop)
<b>Relavant URL</b>	None
<b>Annotation</b>	look_vec – the 3D gaze direction in camera space. head_pose – a 3x3 matrix rotation from world space to camera space. ldmks – a dict containing the following 2D and 3D landmarks: 1. ldmks_lids_2d, ldmks_iris_2d, ldmks_pupil_2d in screen space. 2. dmks_lids_3d, ldmks_iris_3d, ldmks_pupil_3d in camera space
<b>Image format</b>	png
<b>Label format</b>	pkl
<b>Resolution</b>	120X80(Crop)



## 1) Gaze\_Data EDA

- 15. SYNTHSEYES

- 분석 - Total  
(Eye\_gaze)



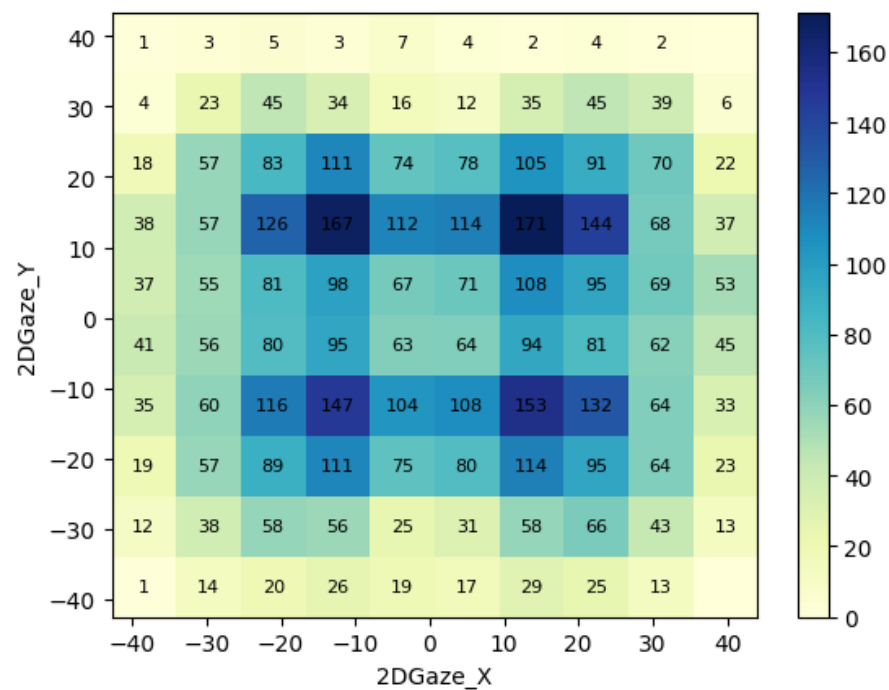
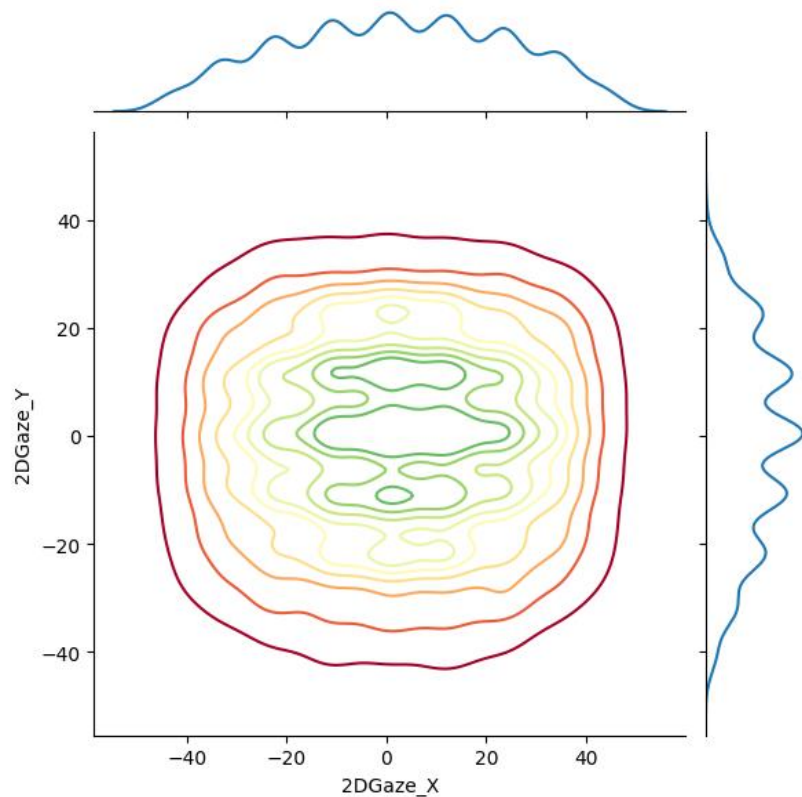
- 2D\_vector = degree



## 1) Gaze\_Data EDA

- 15. SYNTHSEYES

- 분석 - Male  
(Eye\_gaze)



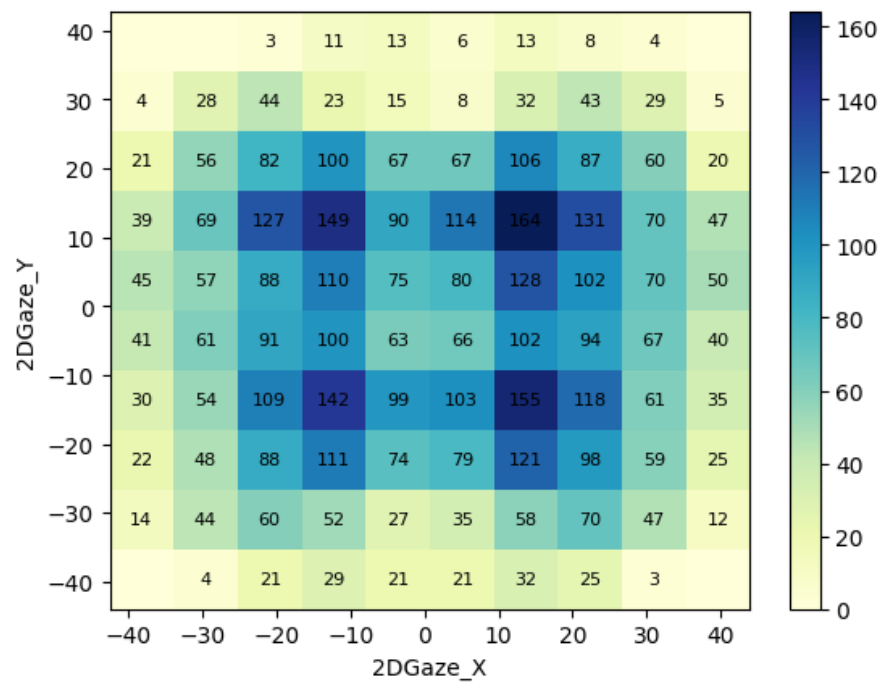
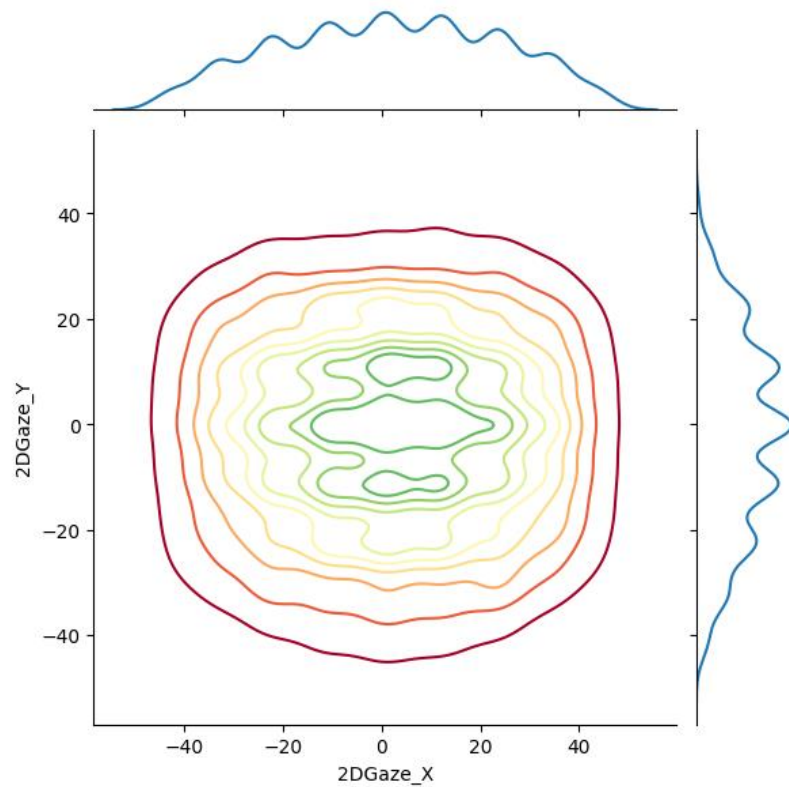
- 2D\_vector = degree



## 1) Gaze\_Data EDA

- 15. SYNTHSEYES

- 분석 - Female  
(Eye\_gaze)



- 2D\_vector = degree



## 1) Gaze\_Data EDA

- 15. SYNTHESSEYES

- 특이사항

1. 3D\_GAZE 데이터만 존재하여 2D\_GAZE 데이터를 추출(X,Y값) 하여 분석을 진행

look\_vec – the 3D gaze direction in camera space.

2. Left\_Eye 정보만 훈련데이터로 사용

**Official URL**

<https://www.cl.cam.ac.uk/research/rainbow/projects/syntheseyes/>

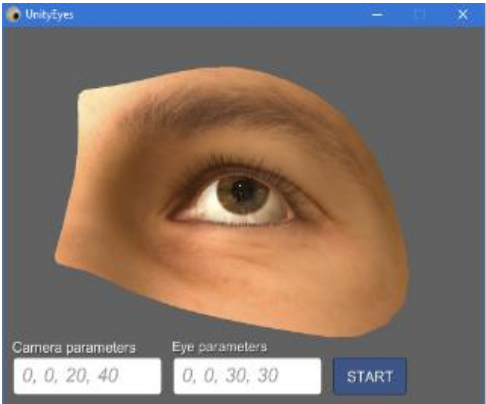
We render photorealistic images of eyes for use as training data. We prepare our dynamic eye region models by retopologizing high-quality 3D head scans (left) and annotating them with landmark and gaze information (green).



# 1) Gaze\_Data EDA

- 16. UNITYEYES

## Sample Image



Name	UNITYEYES
Official URL	<a href="https://www.cl.cam.ac.uk/research/rainbow/projects/unityeyes/">https://www.cl.cam.ac.uk/research/rainbow/projects/unityeyes/</a>
IP / DIR Path	192.168.0.128:5002(Synology) /DataBase/UnityEyes
Volume	None
Type	None
Relavant URL	<a href="https://www.cl.cam.ac.uk/research/rainbow/projects/unityeyes/tutorial.html">https://www.cl.cam.ac.uk/research/rainbow/projects/unityeyes/tutorial.html</a>
Annotation	None
Image format	None
Label format	None
Resolution	None



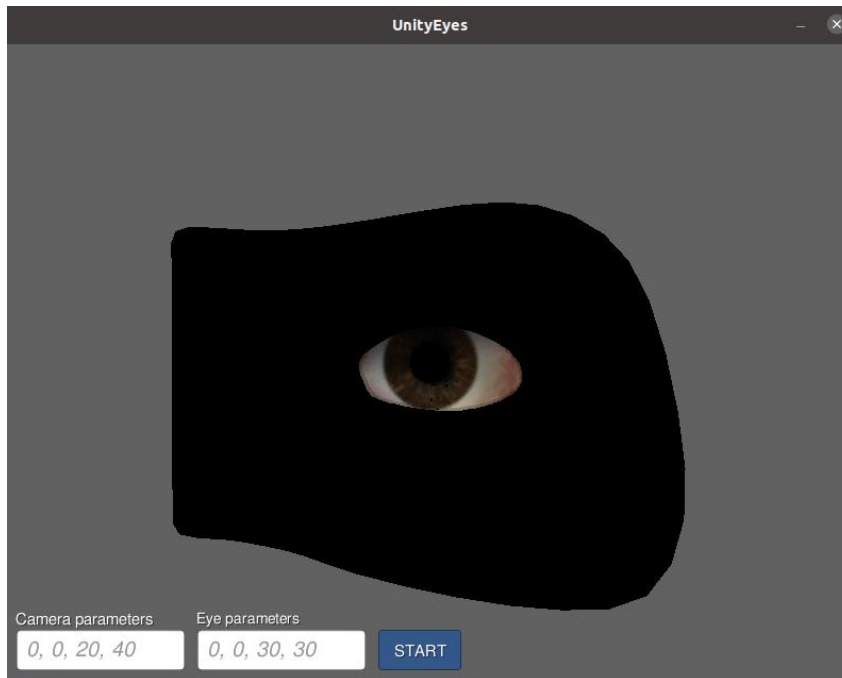


## 1) Gaze\_Data EDA

- 16. UNITYEYES

- 특이사항

 **unityeyes.x86**



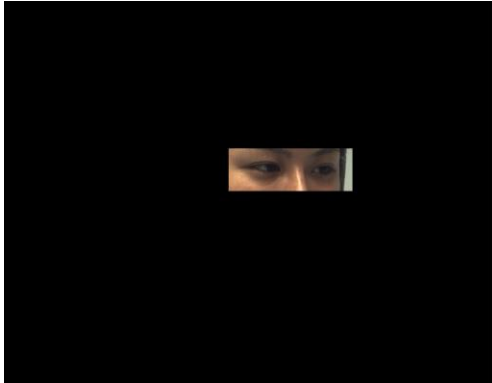
- 이미지 데이터와 라벨 데이터는 존재하지 않음
- 실행 파일을 실행시키면 아래와 같은 창이 나오며  
Camera params, Eye params를 조절하여  
데이터 생성 프로그램이 나오게 된다



# 1) Gaze\_Data EDA

- 17. UTMULTIVIEW

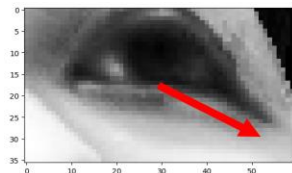
## Original



## Crop



## Annotation



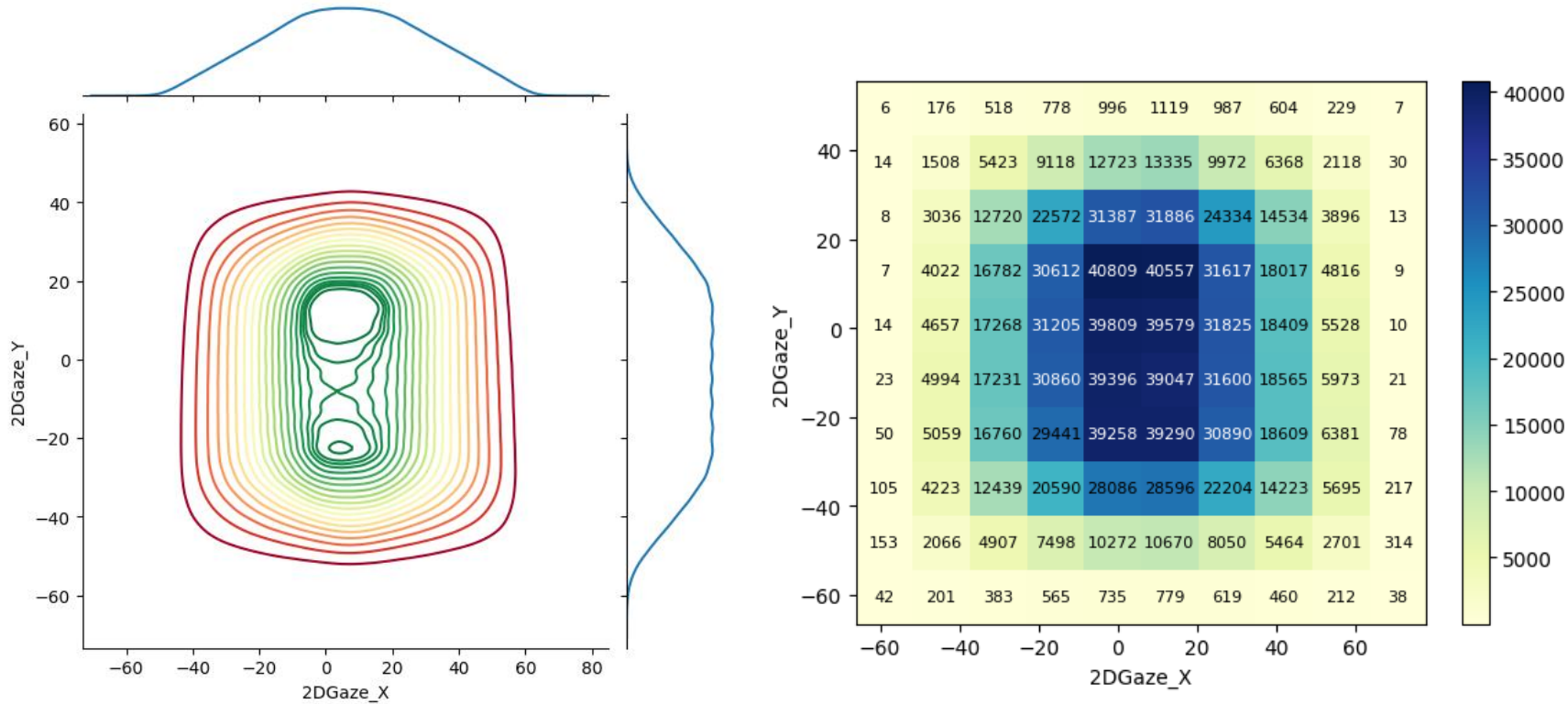
<b>Name</b>	UTMULTIVIEW
<b>Official URL</b>	<a href="https://www.ut-vision.org/datasets/">https://www.ut-vision.org/datasets/</a>
<b>IP / DIR Path</b>	192.168.0.128:5002(Synology) /DataBase/UTMULTIVIEW
<b>Volume</b>	Synth – 1,152,000(Crop) Test – 64,000(Crop) Original – 1,280 Id - 50
<b>Type</b>	RGB real images (Original) Gray Scale images (Crop)
<b>Relavant URL</b>	<a href="https://www.cv-foundation.org/openaccess/content_cvpr_2014/html/Sugano_Learning-by-Synthesis_for_Appearance-based_2014_CVPR_paper.html">https://www.cv-foundation.org/openaccess/content_cvpr_2014/html/Sugano_Learning-by-Synthesis_for_Appearance-based_2014_CVPR_paper.html</a>
<b>Annotation</b>	<b>3D_Gaze(rad)</b> - Ground truth of normalized 3D gaze direction vector <b>3D_Head</b> - Ground truth of normalized 3D head orientation vector. <b>2D_Gaze(rad)</b> - Ground truth of normalized 2D gaze direction vector <b>2D_Head</b> - Ground truth of normalized 2D head orientation vector
<b>Image format</b>	jpg
<b>Label format</b>	csv (Original) label (Crop)
<b>Resolution</b>	1280 X 1024 (Original) 60 X 36 (Crop)



## 1) Gaze\_Data EDA

- 17. UTMULTIVIEW

- 분석 우안  
(Eye\_gaze)



- 2D\_vector = degree
- 정면을 기준으로 시선이 중심부분에 분포 되어 있는 데이터 위주로 구성됨



## 1) Gaze\_Data EDA

- 17. UTMULTIVIEW

- 특이사항

```
if which_eye == "right":  
    img = cv2.flip(img, 1)  
    gaze = dpc.GazeFlip(gaze)  
    head = dpc.HeadFlip(head)
```

Original 이미지에서 오른쪽눈 정보만 사용후  
Flip하여 왼쪽 눈 정보로 사용하여 훈련 진행  
Crop된 데이터와 라벨도 오른쪽 눈에 대해서만 존재



# 1) Gaze\_Data EDA

- 18. EYEDIAP

Name	
Official URL	
IP / DIR Path	
Volume	
Type	
Relavant URL	
Annotation	
Image format	
Label format	
Resolution	



# 1) Gaze\_Data EDA

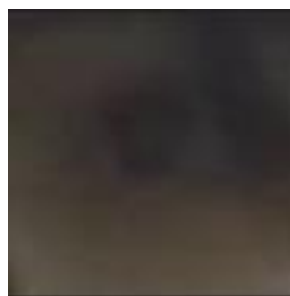
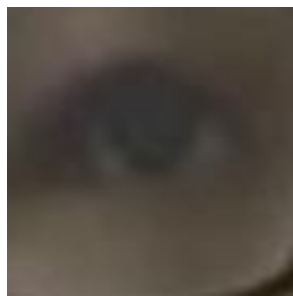
- 19. OpenEDS : Open Eye Dataset

Name	
Official URL	
IP / DIR Path	
Volume	
Type	
Relavant URL	
Annotation	
Image format	
Label format	
Resolution	



# 1) Gaze\_Data EDA

- 20. ShanghaiTechGaze



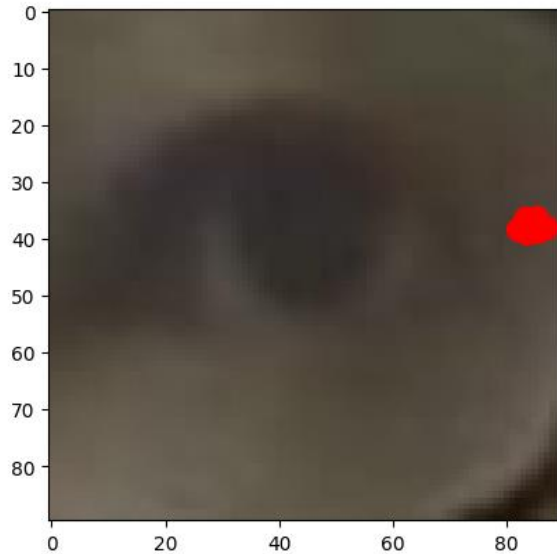
<b>Name</b>	ShanghaiTechGaze
<b>Official URL</b>	<a href="https://github.com/dongzelian/multi-view-gaze">https://github.com/dongzelian/multi-view-gaze</a>
<b>IP / DIR Path</b>	192.168.0.128:5002(Synology) /DataBase/ShanghaiTechGaze
<b>Volume</b>	155,864(leftcamera,crop) 155,864(middlecamera,crop) 155,864(rightcamera,crop) 467,592(total) 137 ids
<b>Type</b>	RGB real image (eye cropped)
<b>Relavant URL</b>	<a href="https://sci-hub.se/10.1109/TNNLS.2018.2865525">https://sci-hub.se/10.1109/TNNLS.2018.2865525</a>
<b>Annotation</b>	<b>2D_Gaze</b> - Ground truth of normalized 2D gaze direction vector <b>Eye Landmark_6 points</b> - normalized value
<b>Image format</b>	jpg
<b>Label format</b>	mat
<b>Resolution</b>	90 X 90



## 1) Gaze\_Data EDA

- 20. ShanghaiTechGaze

- 특이사항



- 모델 학습에 랜드마크를 사용하지 않음
- 정규화된 랜드마크값에 대한 정보가 부족<sup>(\*)</sup>
- 랜드마크 정보는 사용 불가
- 크롭된 눈 이미지 자체 학습용으로는 활용 가능
- 이미지와 GT값만 정리
- GT = 위치정보

<sup>(\*)</sup>only 6 landmarks of each eyes





# 1) FaceLandmark\_Data EDA

- 1. DIS\_300VW

Original

Landmark

Name	DIS_300VW
Official URL	<a href="https://ibug.doc.ic.ac.uk/resources/300-VW/">https://ibug.doc.ic.ac.uk/resources/300-VW/</a>
IP / DIR Path	192.168.0.128:5002(Synology) /DataBase/DIS_300VW
Volume	218,597 images 114 ids
Type	RGB real images
Relavant URL	
Annotation	FaceLandmark – 68points
Image format	Png
Label format	Pts
Resolution	Various Standards



# 1) FaceLandmark\_Data EDA

- 1. DIS\_300W

Original



Landmark



Name	DIS_300W
Official URL	<a href="https://ibug.doc.ic.ac.uk/resources/300-W/">https://ibug.doc.ic.ac.uk/resources/300-W/</a>
IP / DIR Path	192.168.0.128:5002(Synology) /DataBase/DIS_300W
Volume	300 (Indoor) 300 (outdoor)
Type	RGB real images
Relavant URL	
Annotation	Face Landmark – 68 points
Image format	png
Label format	Pts
Resolution	Various Standards



# 1. FaceLandmark\_Dataset 개요

No.	Dataset Name	Official URL	IP / DIR Path
1	<a href="#">DIS_300W</a>	<a href="https://ibug.doc.ic.ac.uk/resources/300-W/">https://ibug.doc.ic.ac.uk/resources/300-W/</a>	192.168.0.128(Synology) /DataBase/DIS_300W
2	<a href="#">DIS_300VW</a>		
3			
4			
5			
6			
7			
8			
9			
10			
11			
12			
13			
14			
15			



# 1. BoundingBox\_Dataset 개요

No.	Dataset Name	Official URL	IP / DIR Path
1			
2			
3			
4			
5			
6			
7			
8			
9			
10			
11			
12			
13			
14			
15			

