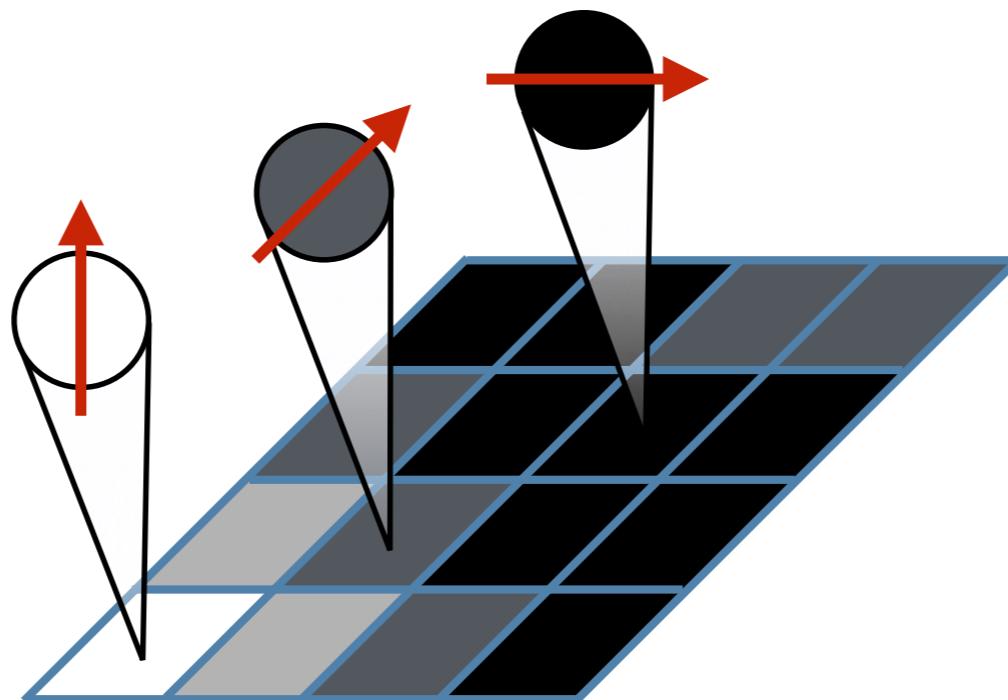


Tensor Networks and Applications



Machine learning galvanizing industry & science



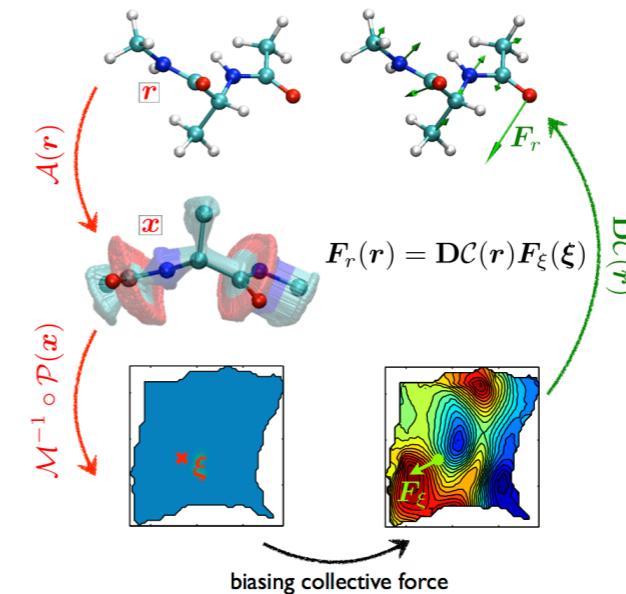
Language Processing



Self-driving cars



Medicine



Materials Science / Chemistry

Google rebranded a "machine learning first company"



Neural nets replace linguistic approach to Google Translate

arXiv.org > quant-ph > arXiv:1802.06002

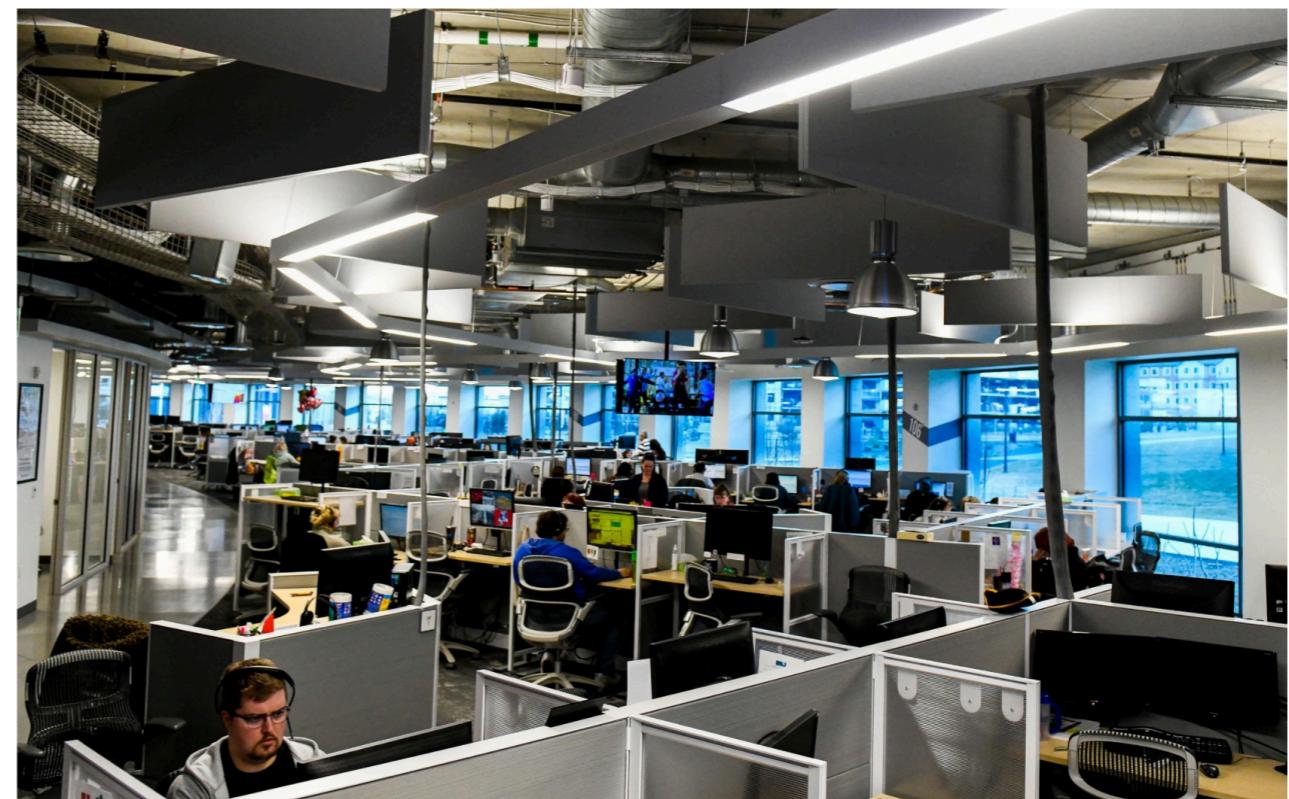
Quantum Physics

Classification with Quantum Neural Networks on Near Term Processors

Edward Farhi, Hartmut Neven

(Submitted on 16 Feb 2018)

Quantum machine learning



Examples of Machine Learning

Image recognition

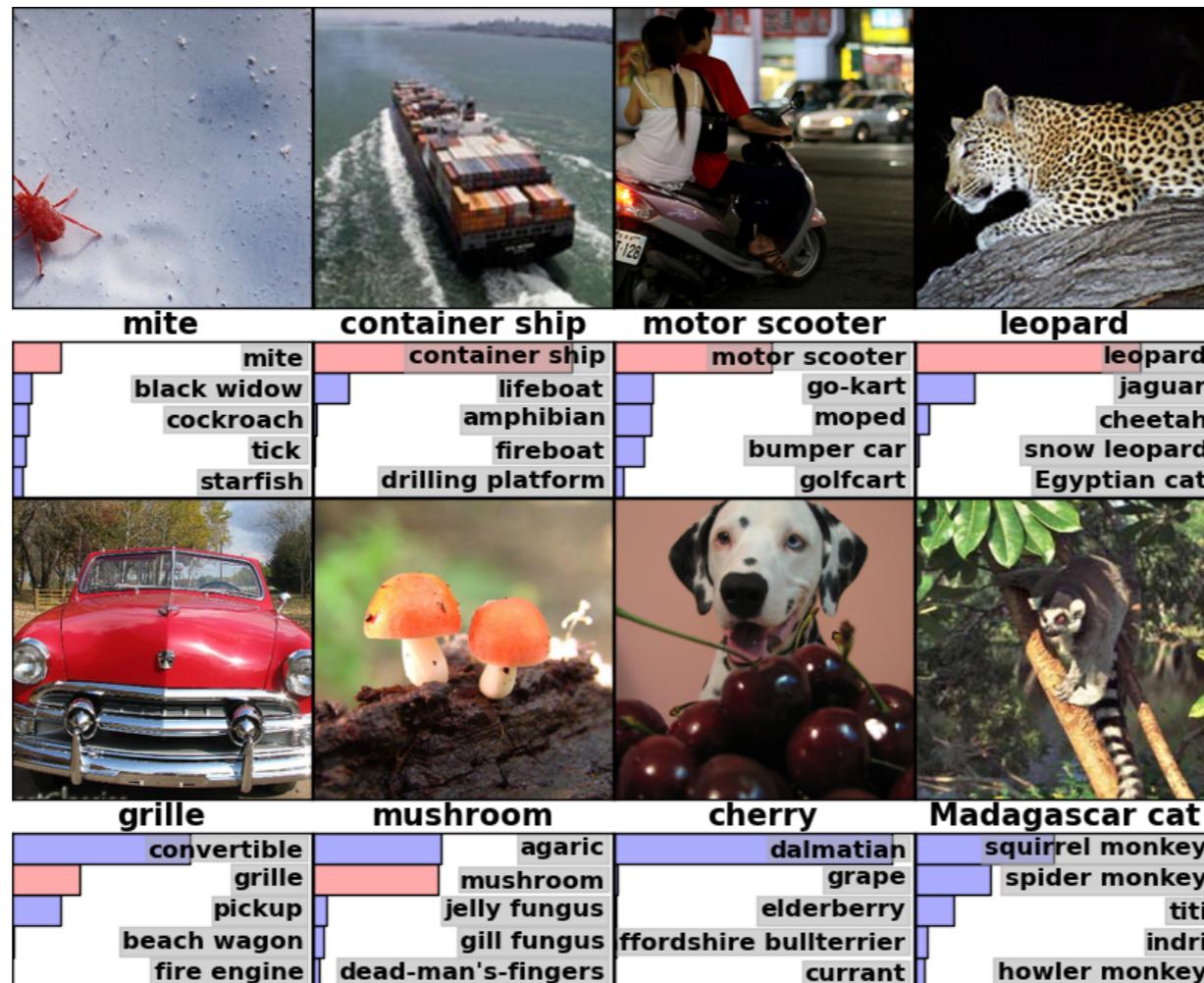
ImageNet Classification with Deep Convolutional Neural Networks

Alex Krizhevsky
University of Toronto
kriz@cs.utoronto.ca

Ilya Sutskever
University of Toronto
ilya@cs.utoronto.ca

Geoffrey E. Hinton
University of Toronto
hinton@cs.utoronto.ca

2012 paper that launched recent deep learning craze (20k citations)



ImageNet:

- 1.2 million training images (150k test)
- 1000 categories
- 15% neural net error
- 26% next best error

Sound prediction

Visually Indicated Sounds

Andrew Owens¹
Antonio Torralba¹
¹MIT

Phillip Isola^{2,1}
Edward H. Adelson¹
²U.C. Berkeley

Josh McDermott¹
William T. Freeman^{1,3}
³Google Research

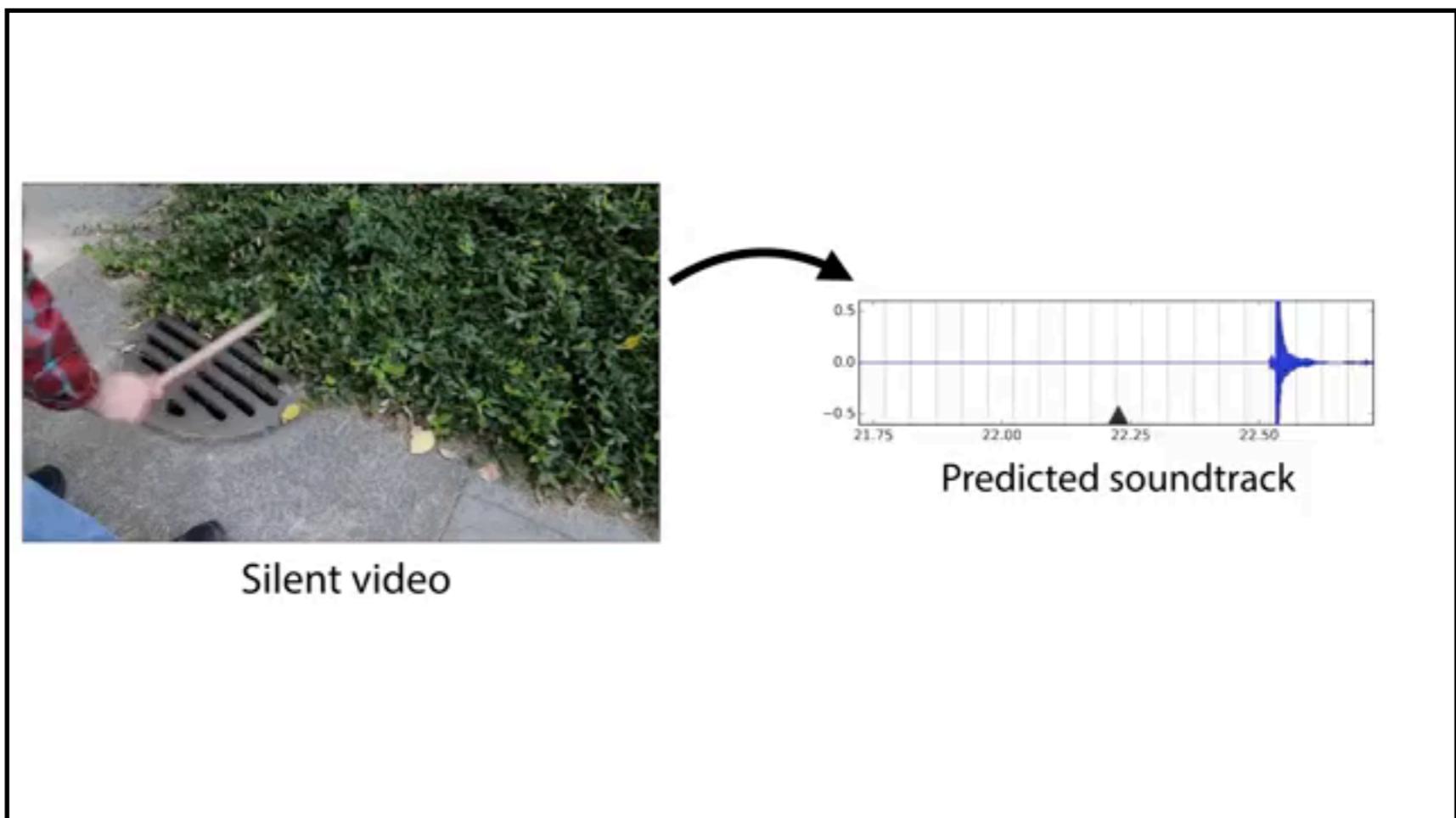
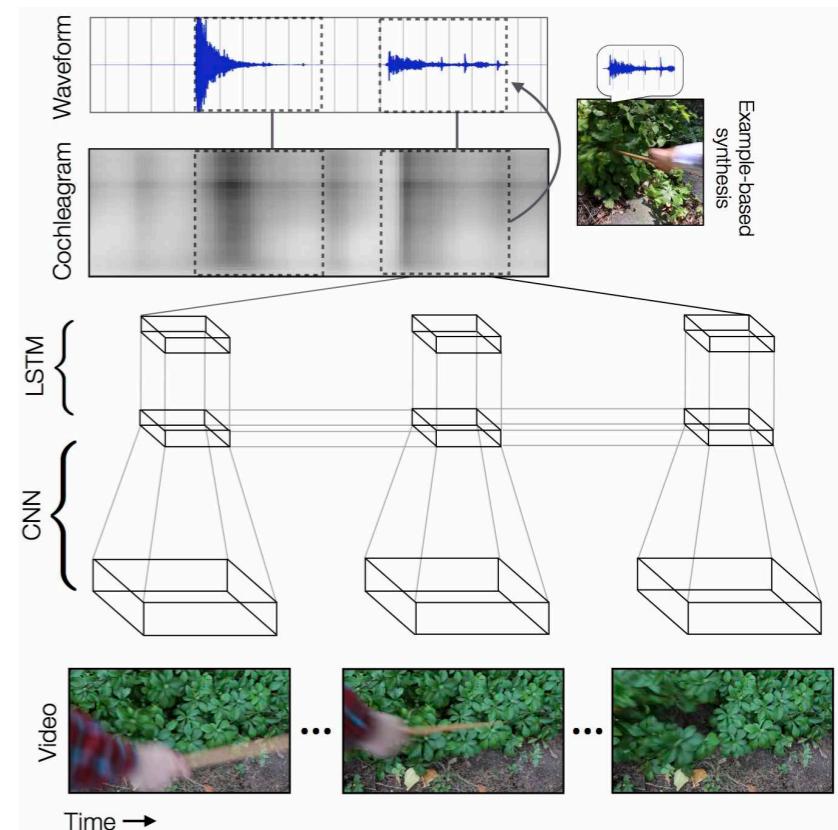
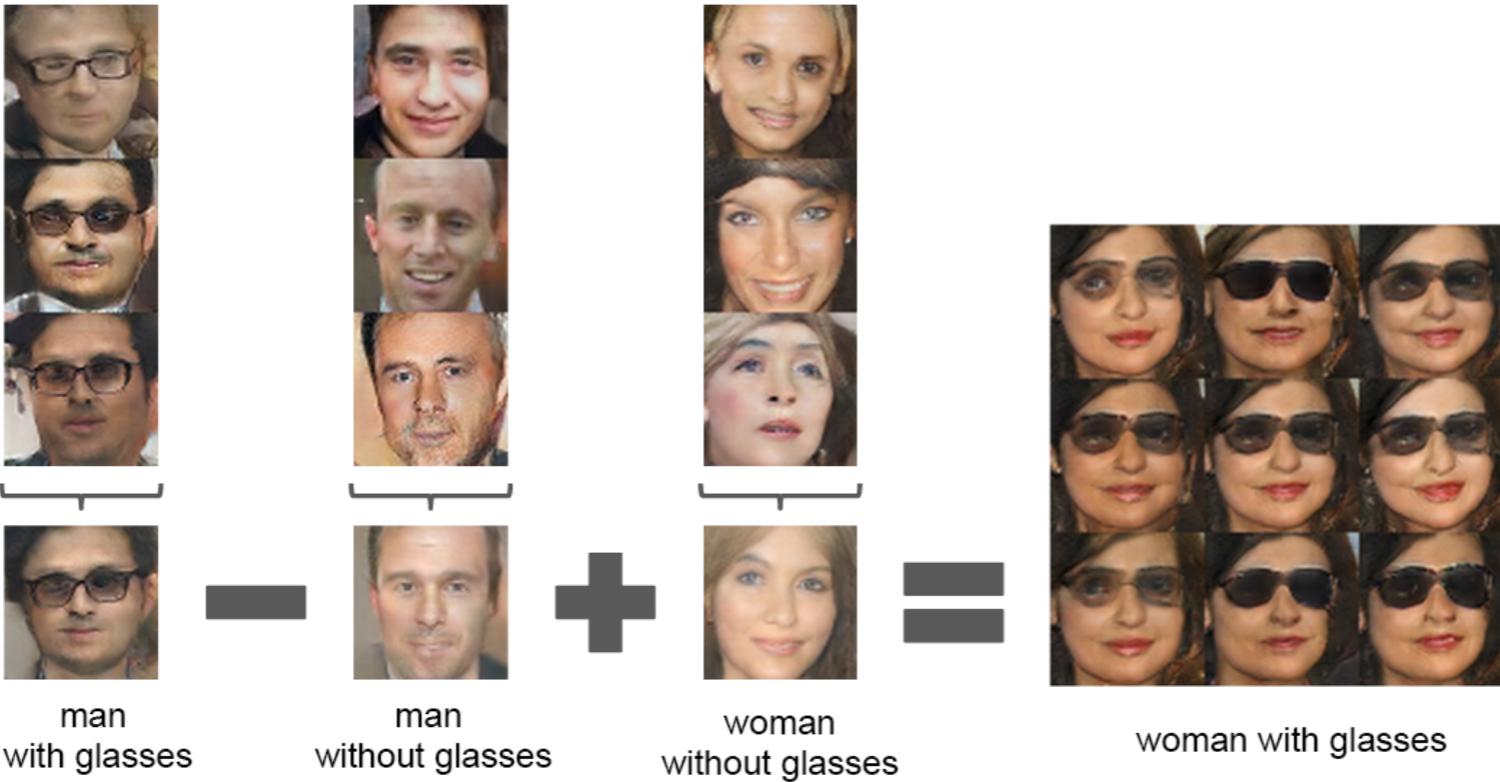


Image Generation



UNSUPERVISED REPRESENTATION LEARNING WITH DEEP CONVOLUTIONAL GENERATIVE ADVERSARIAL NETWORKS

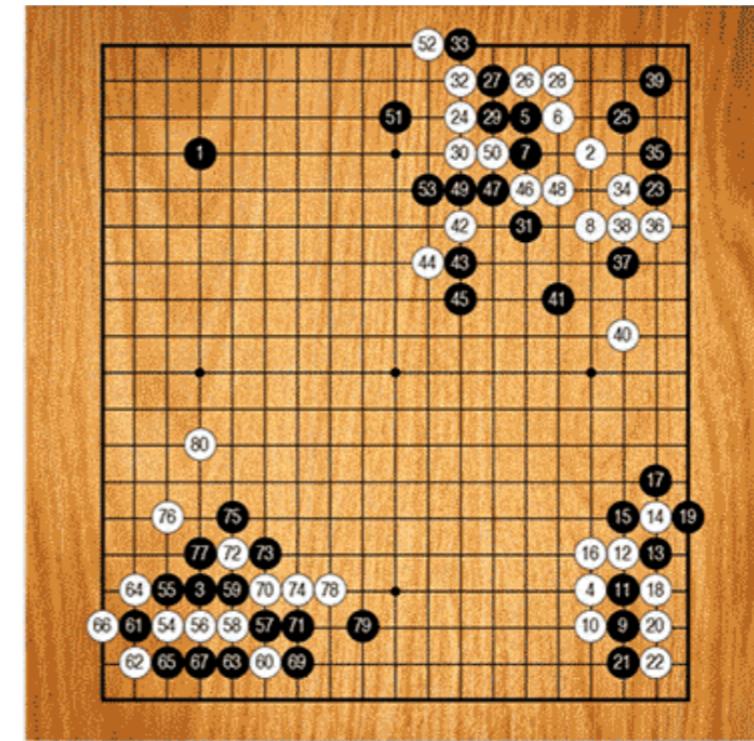
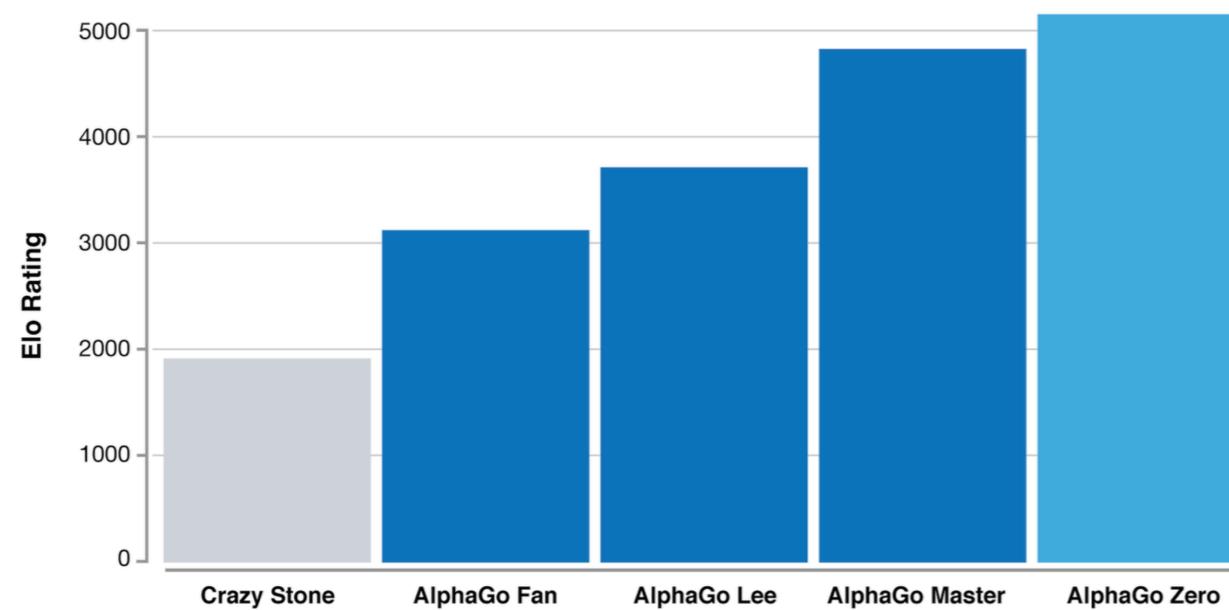
Alec Radford & Luke Metz
indico Research
Boston, MA
{alec,luke}@indico.io

Soumith Chintala
Facebook AI Research
New York, NY
soumith@fb.com

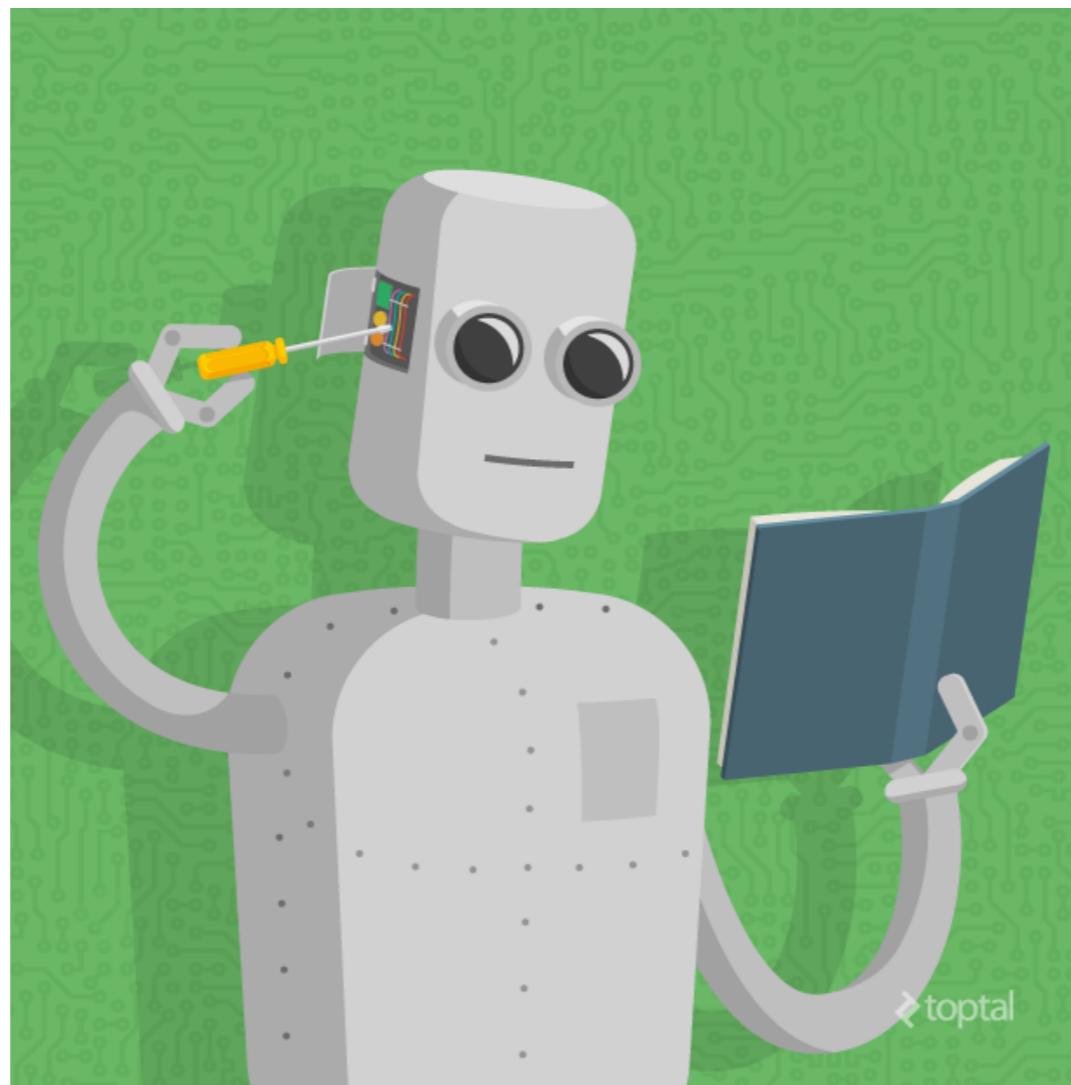
Success at tasks previously thought impossible



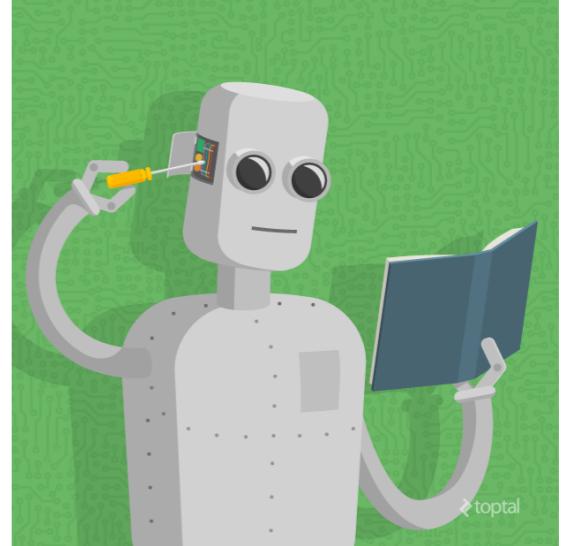
AlphaGo



What is machine learning?



What is machine learning?



Data driven problem solving

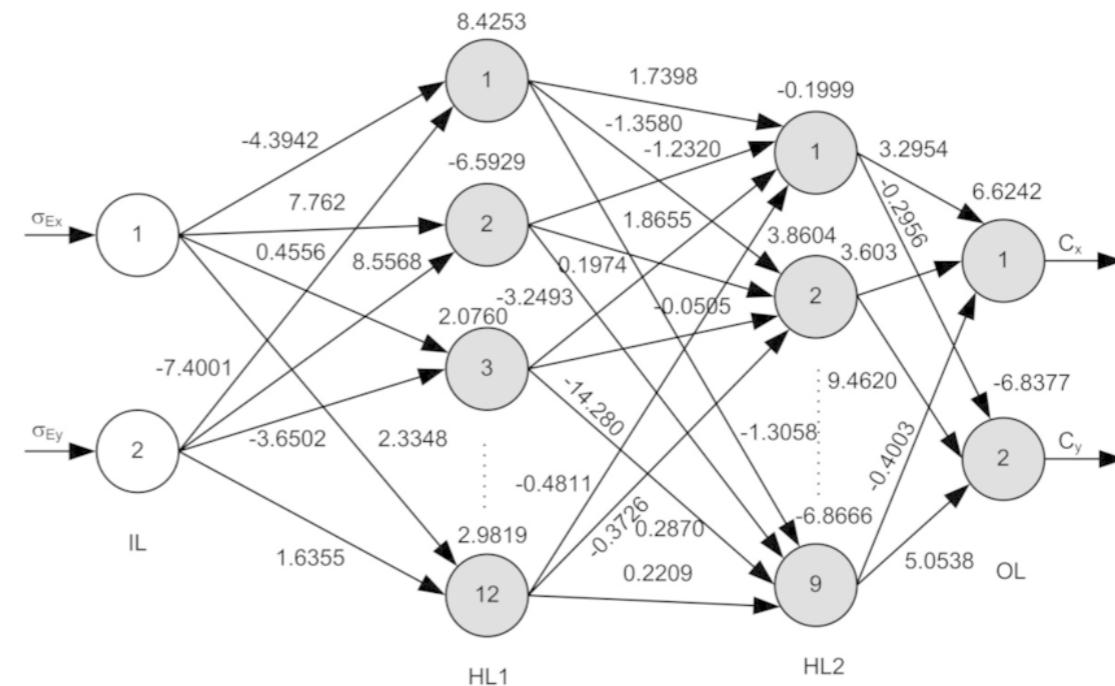
Any system that, given more data, performs
increasingly better at some task

Framework / philosophy, not single method

Software 1.0



Software 2.0



Andrej Karpathy [Follow](#)

Director of AI at Tesla. Previously Research Scientist at OpenAI and PhD student at Stanford. I like to train deep neural nets on large datasets.

Nov 11, 2017 · 7 min read

<https://medium.com/@karpathy/software-2-0-a64152b37c35>

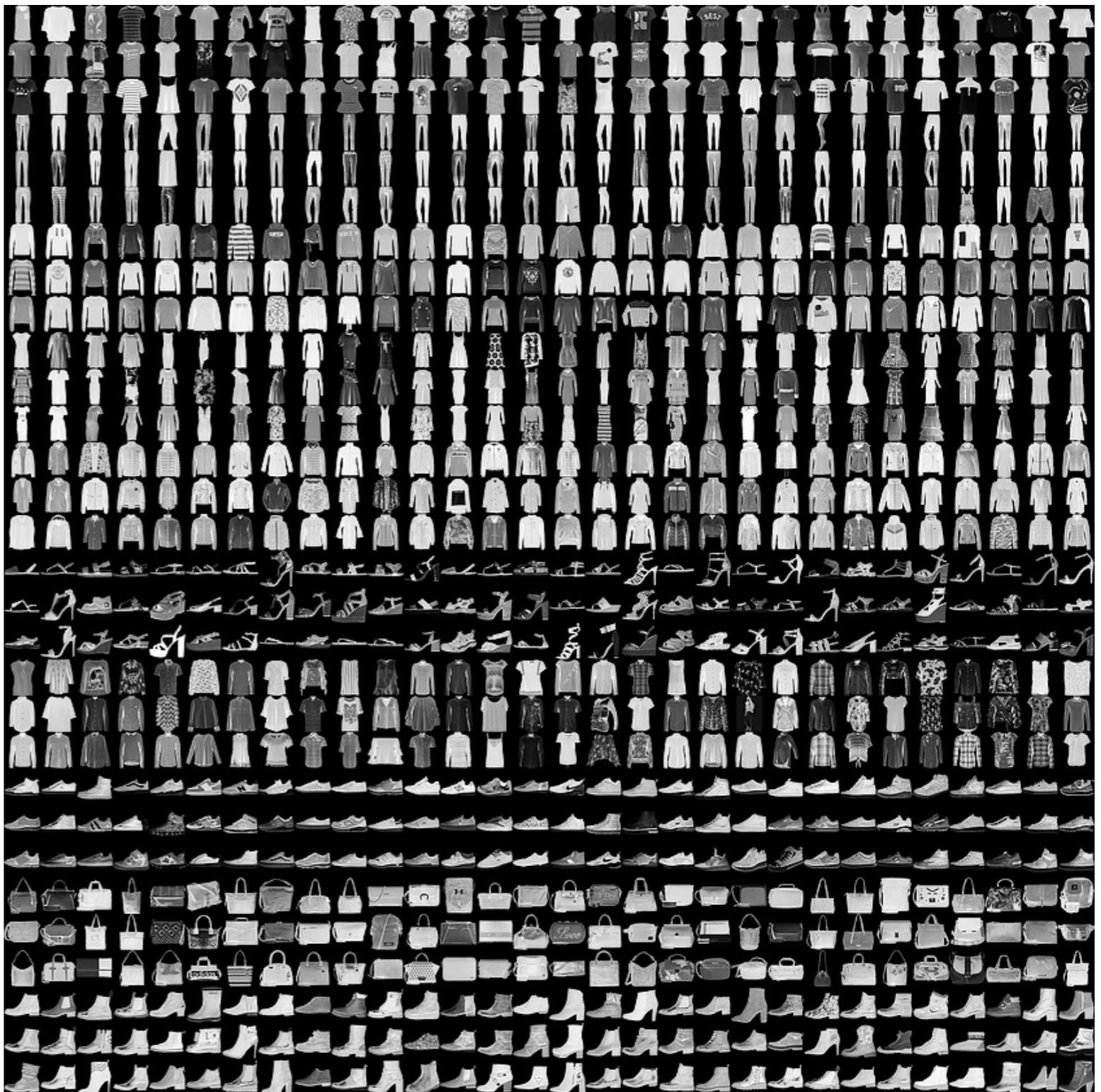
Basics of Machine Learning

Example of a Dataset – Fashion MNIST

10 categories (labels)

28x28 grayscale

70000 labeled images

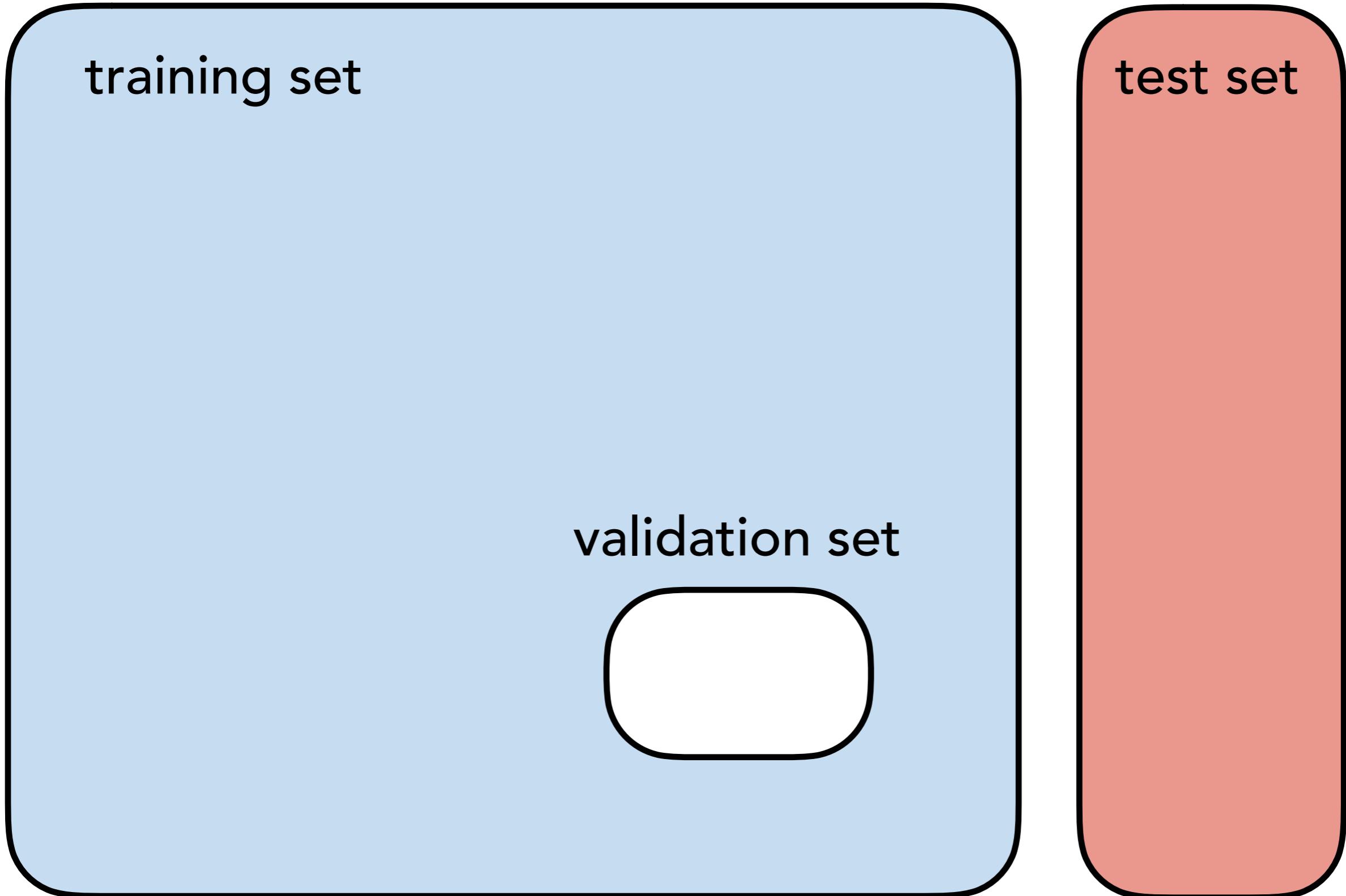


Anatomy of a Dataset

training set

test set

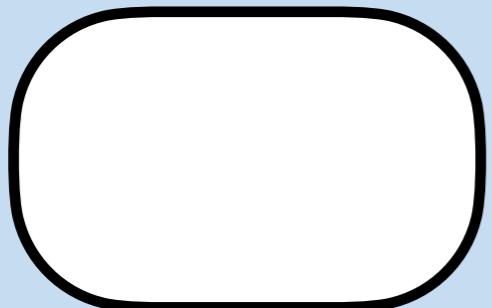
Anatomy of a Dataset



Anatomy of a Dataset

training set

validation set 1

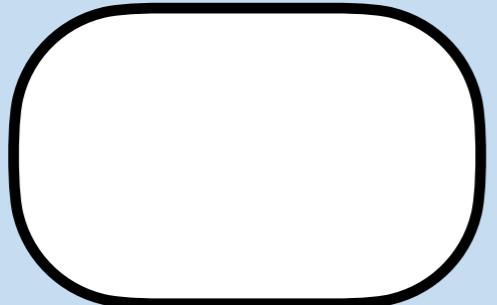


test set

Anatomy of a Dataset

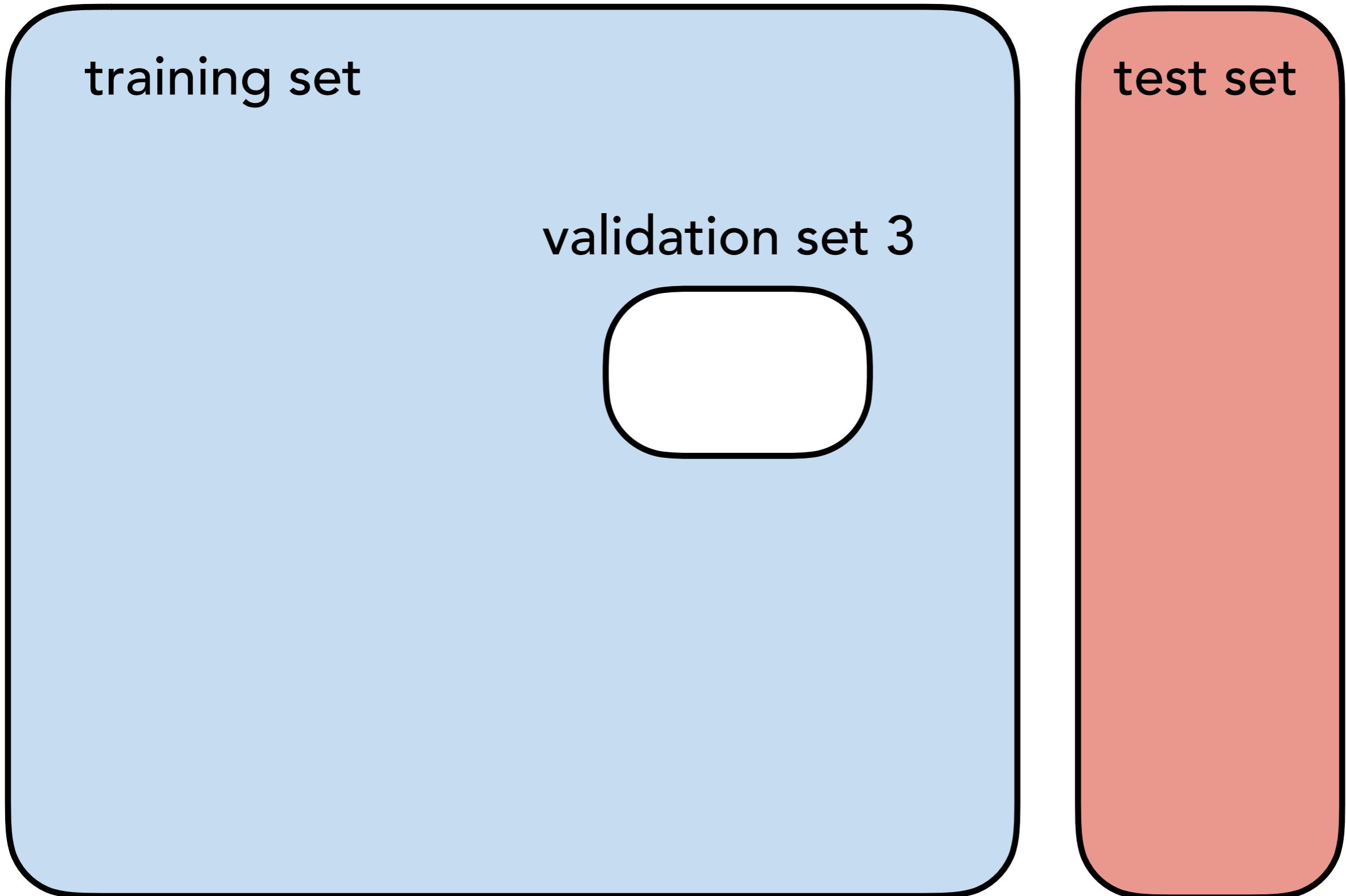
training set

validation set 2

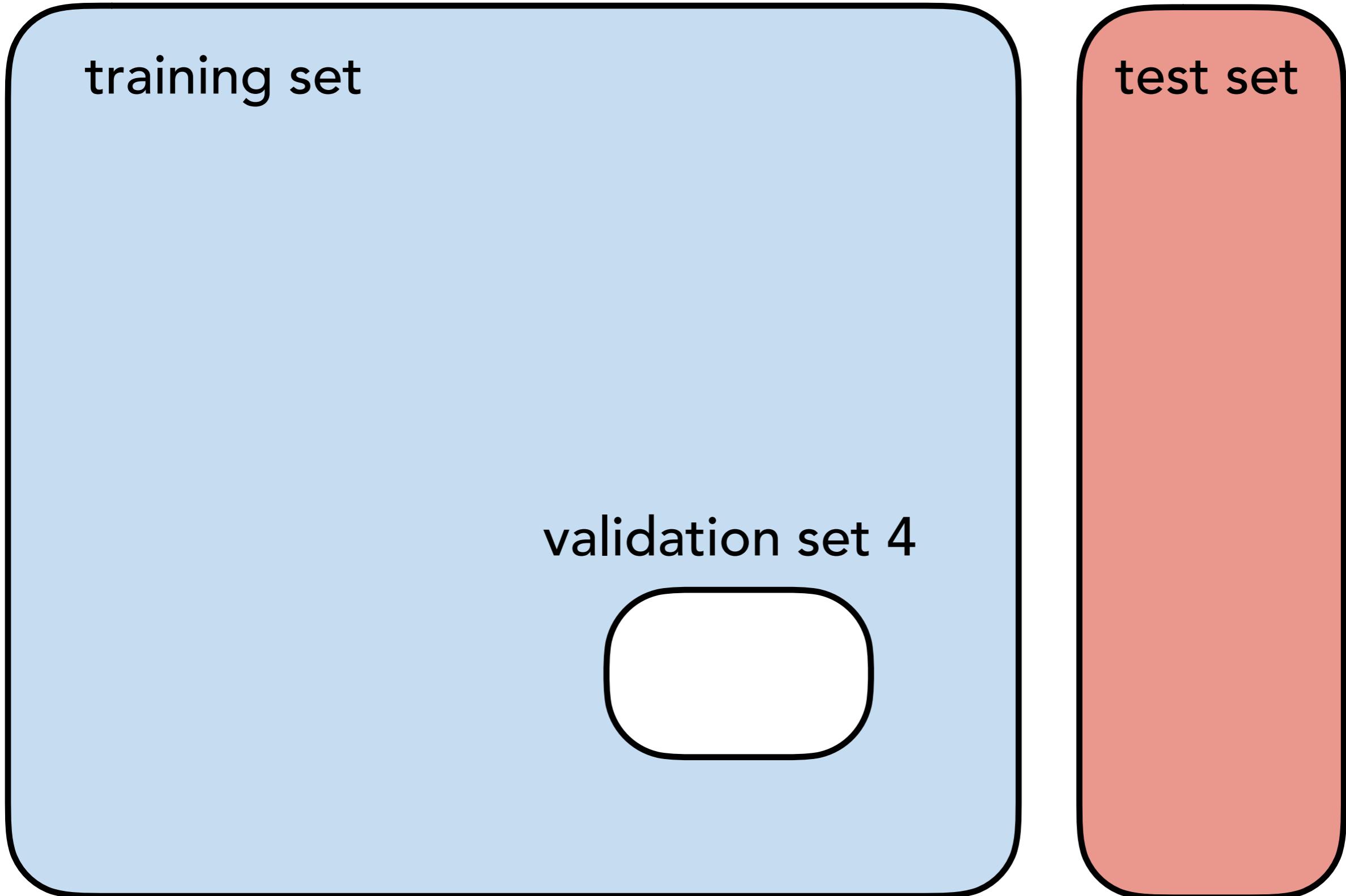


test set

Anatomy of a Dataset



Anatomy of a Dataset



Types of learning tasks:

		<i>a priori</i> knowledge
• Supervised learning	(labeled data)	<i>high</i>
• Unsupervised learning	(unlabeled data)	
• Reinforcement learning	('reward' data)	<i>low</i>

Supervised Learning

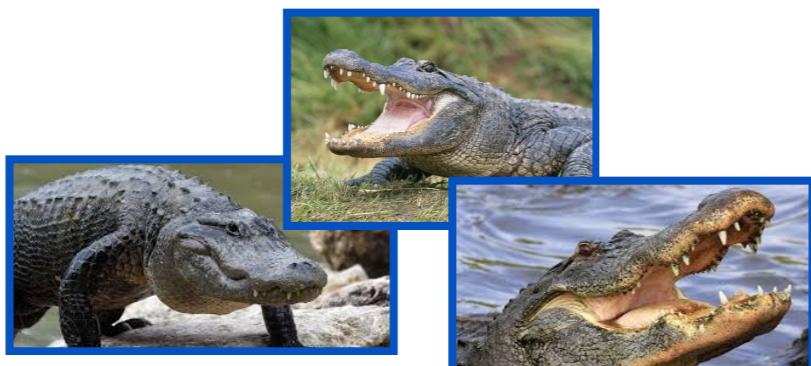
Given labeled training data (labels A and B)

Find *decision function* $f(\mathbf{x})$

$$f(\mathbf{x}) > 0 \quad \mathbf{x} \in A$$

$$f(\mathbf{x}) < 0 \quad \mathbf{x} \in B$$

Example: identify photos of **alligators** and **bears**



Supervised Learning

Typical strategy:

given training set $\{\mathbf{x}_j, y_j\}$, minimize cost function

$$C = \frac{1}{N_T} \sum_j (f(\mathbf{x}_j) - y_j)^2$$

$$y_j = \begin{cases} +1 & \mathbf{x}_j \in A \\ -1 & \mathbf{x}_j \in B \end{cases}$$

by varying adjustable params of f

Cost function measures distance of trial function $f(\mathbf{x}_j)$ from idealized "indicator" function y_j

Unsupervised Learning

Given unlabeled training data $\{\mathbf{x}_j\}$

- Find function $f(\mathbf{x})$ such that $f(\mathbf{x}_j) \simeq p(\mathbf{x}_j)$
- Find function $f(\mathbf{x})$ such that $|f(\mathbf{x}_j)|^2 \simeq p(\mathbf{x}_j)$
- Find data clusters and which data belongs to each cluster
- Discover reduced representations of data for other learning tasks (e.g. supervised)

Unsupervised Learning

Typical approach for inferring $p(\mathbf{x})$

Given data $\{\mathbf{x}_j\}$, maximize log likelihood

$$\mathcal{L} = \sum_j \log p(\mathbf{x}_j)$$

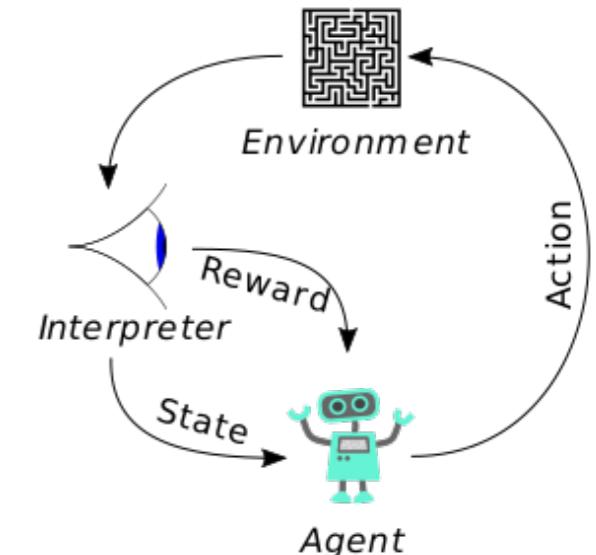
by varying p

Can view log likelihood as distance measure between
 $p(\mathbf{x})$ and $p_{\text{data}}(\mathbf{x}) = \sum \delta(\mathbf{x} - \mathbf{x}_j)$
("Kullback-Leibler divergence")

Reinforcement learning

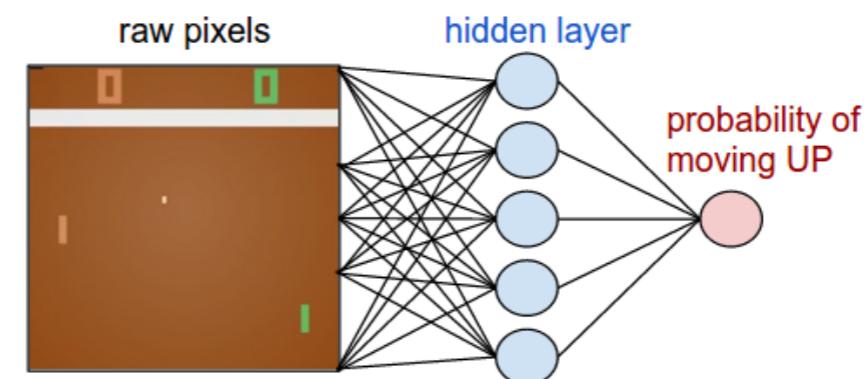
Many flavors, but have common features

- environment & agent with states s_n
- agent actions a_n
- reward $R(s_n)$ for being in state s_n



Goal: determine a policy $P(s_n) \rightarrow a_n$,
best actions to maximize reward in fewest steps

Example: learning "Pong"
by observing screen state



General Philosophy of Machine Learning

- Solution to problem just some function $y(\mathbf{x})$
- Parameterize very flexible functions $f(\mathbf{x})$
(prefer convenient over "correct")
- Of all f that come closest to y for training data,
prefer the simplest f

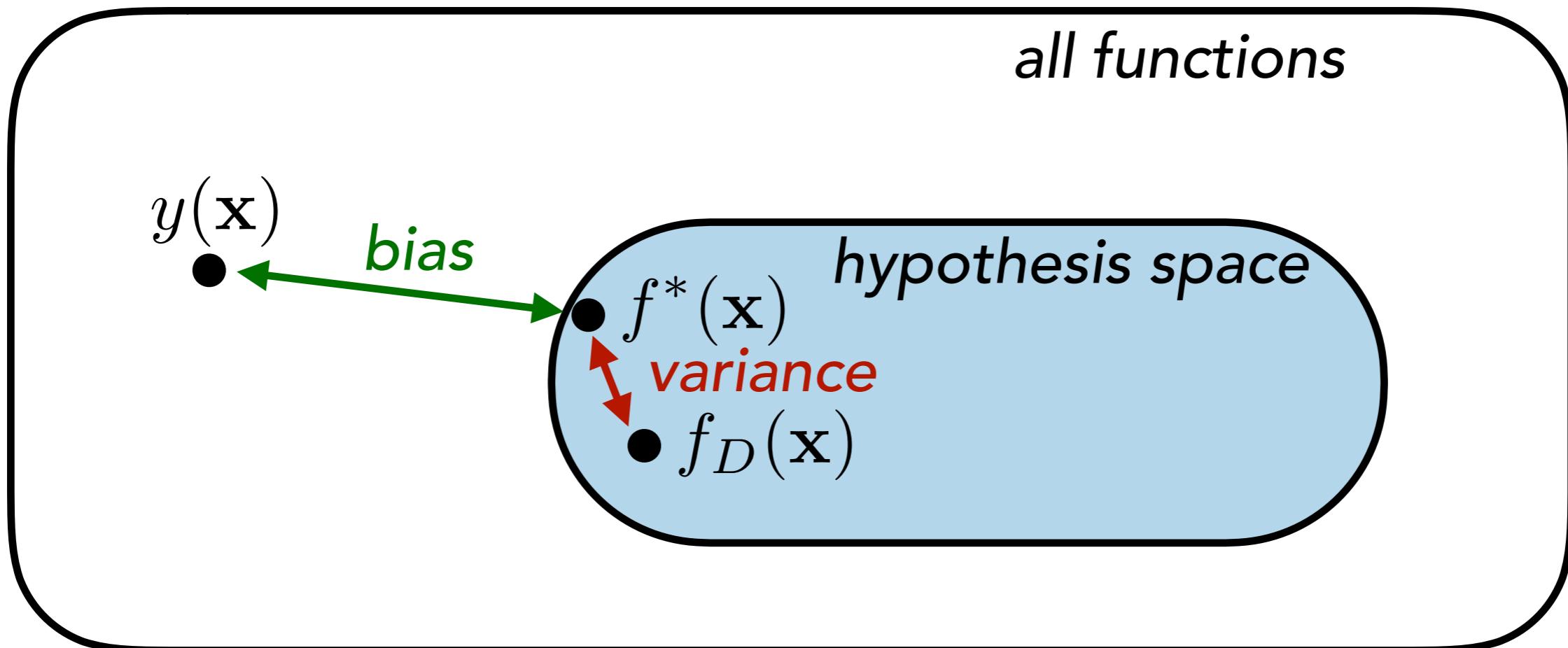


Bias-Variance Tradeoff

$y(\mathbf{x})$ – ideal solution function

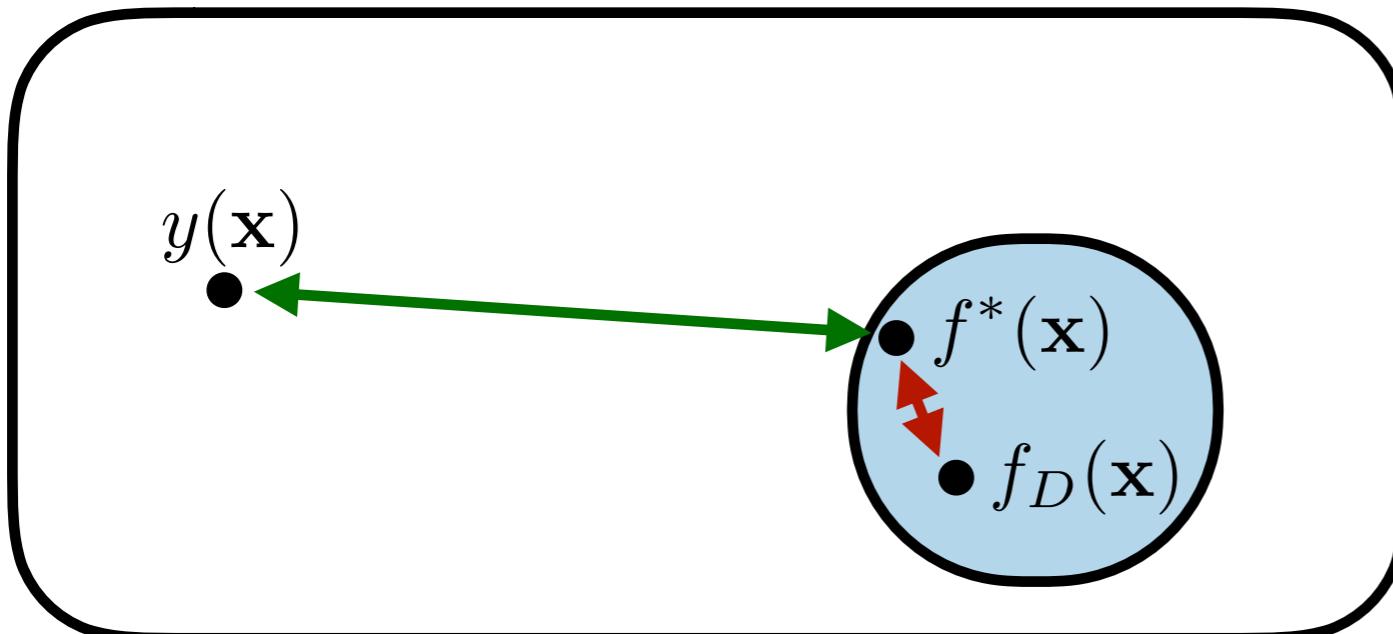
$f^*(\mathbf{x})$ – best possible hypothesis

$f_D(\mathbf{x})$ – best hypothesis given training data



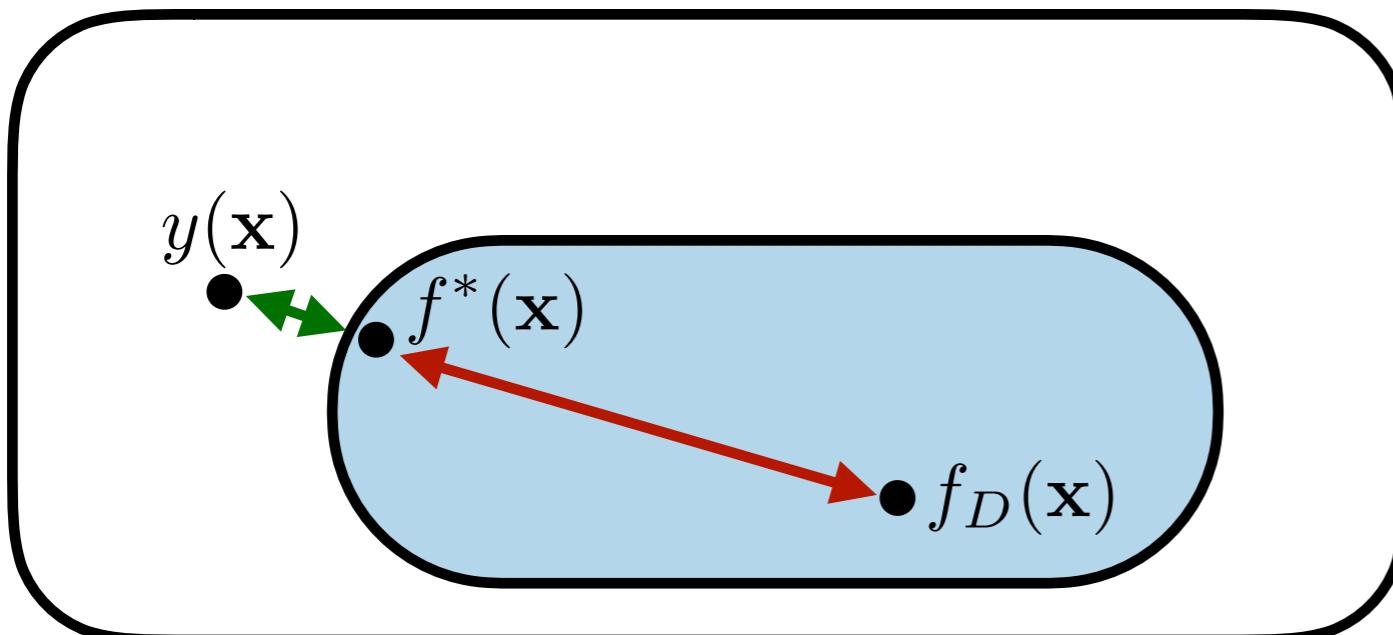
Bias-Variance Tradeoff

Two extreme situations



low variance: will generalize!

high bias: poor results



low bias: good result possible

high variance: might overfit

Model Architectures

Let's discuss the 3 most used types of models
(increasing complexity)

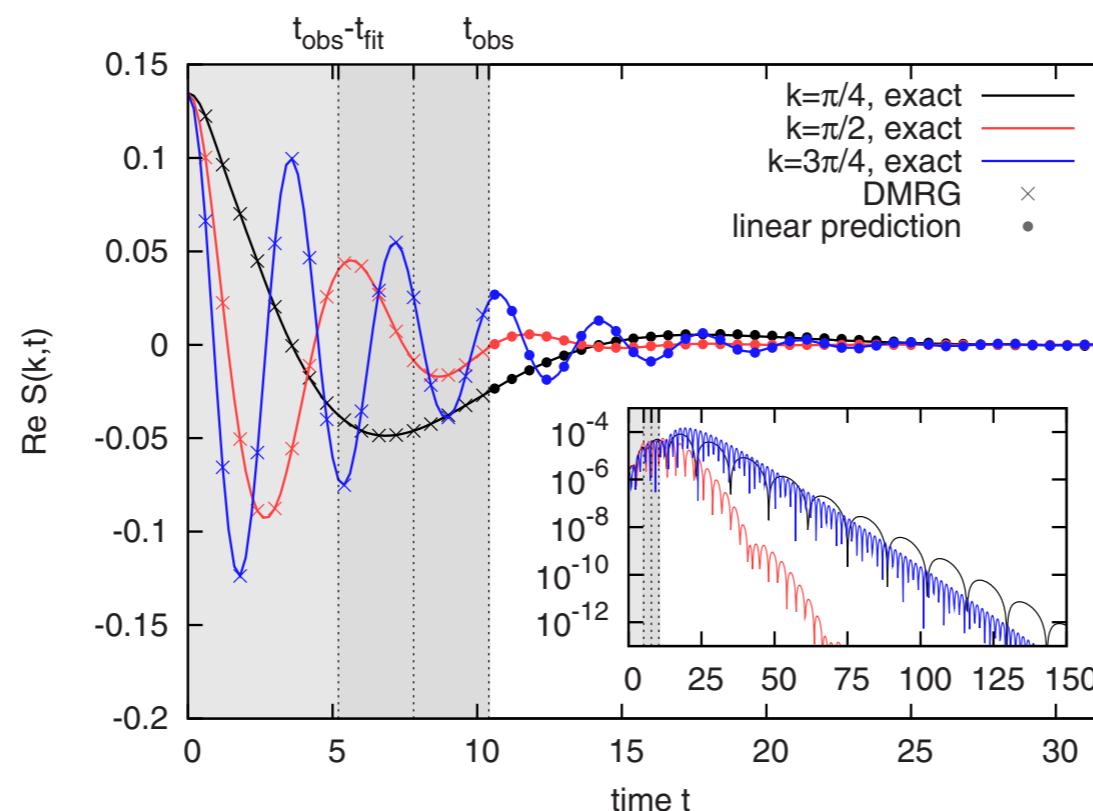
- The linear model
- Kernel learning / support vector machines
- Neural networks

The linear model

$$f(\mathbf{x}) = W \cdot \mathbf{x} + W_0$$

Where W and W_0 are the weights to be learned

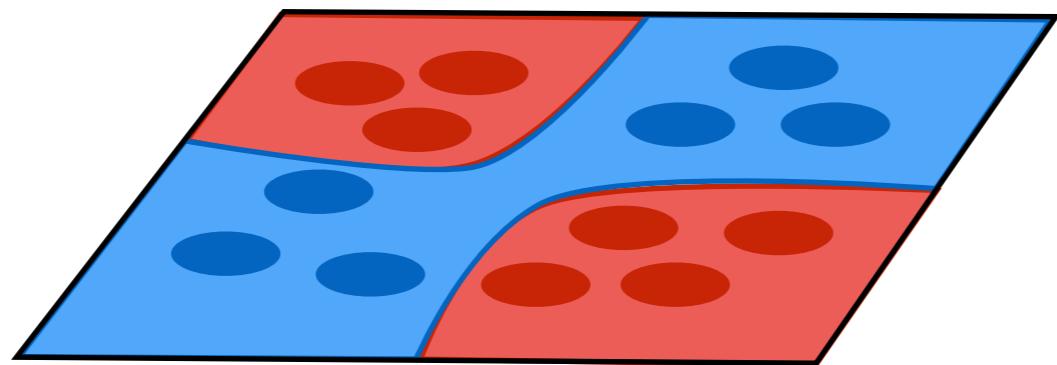
Can be surprisingly powerful, and a useful starting point



Barthel, Schollwöck, White, PRB 79, 245101

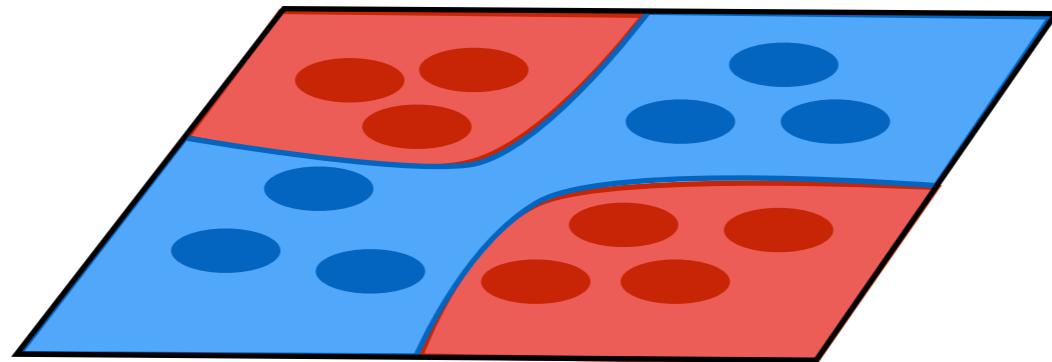
Kernel learning

Want $f(\mathbf{x})$ to separate classes, say



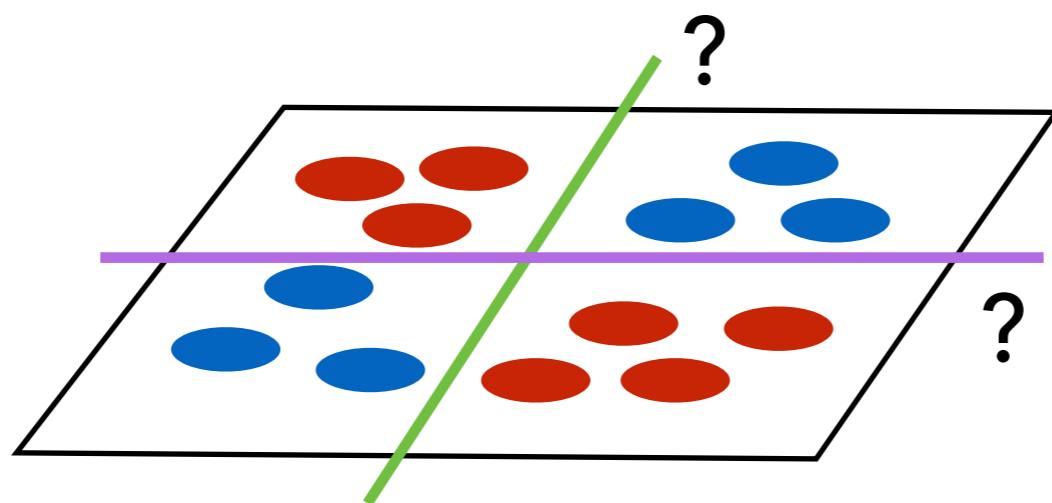
Kernel learning

Want $f(\mathbf{x})$ to separate classes, say



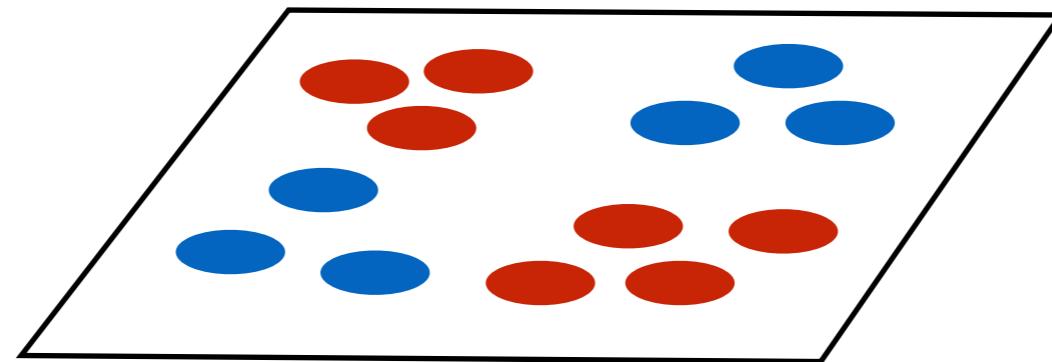
Linear classifier
may be insufficient

$$f(\mathbf{x}) = \mathbf{W} \cdot \mathbf{x}$$



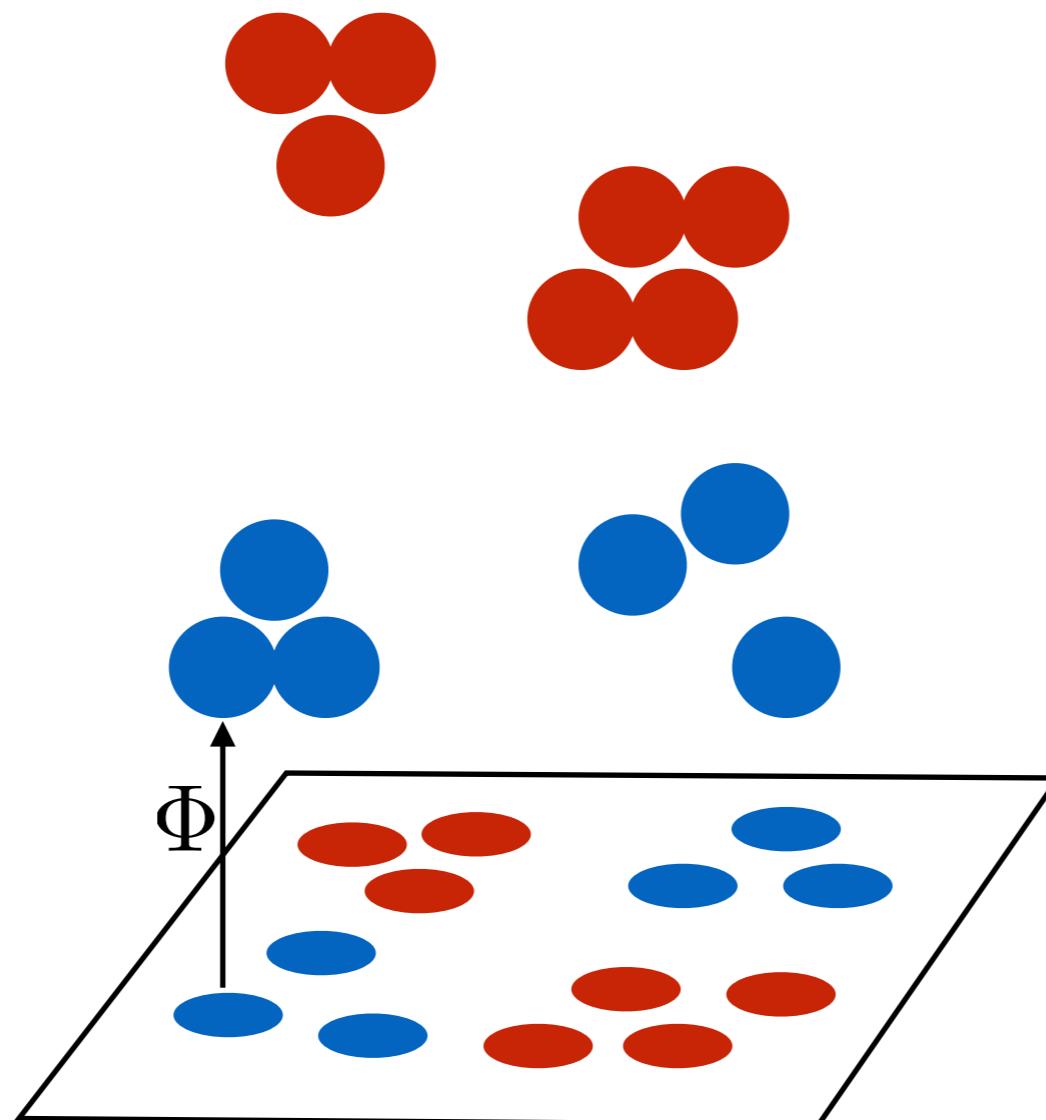
Kernel learning

Apply non-linear "feature map" $x \rightarrow \Phi(x)$



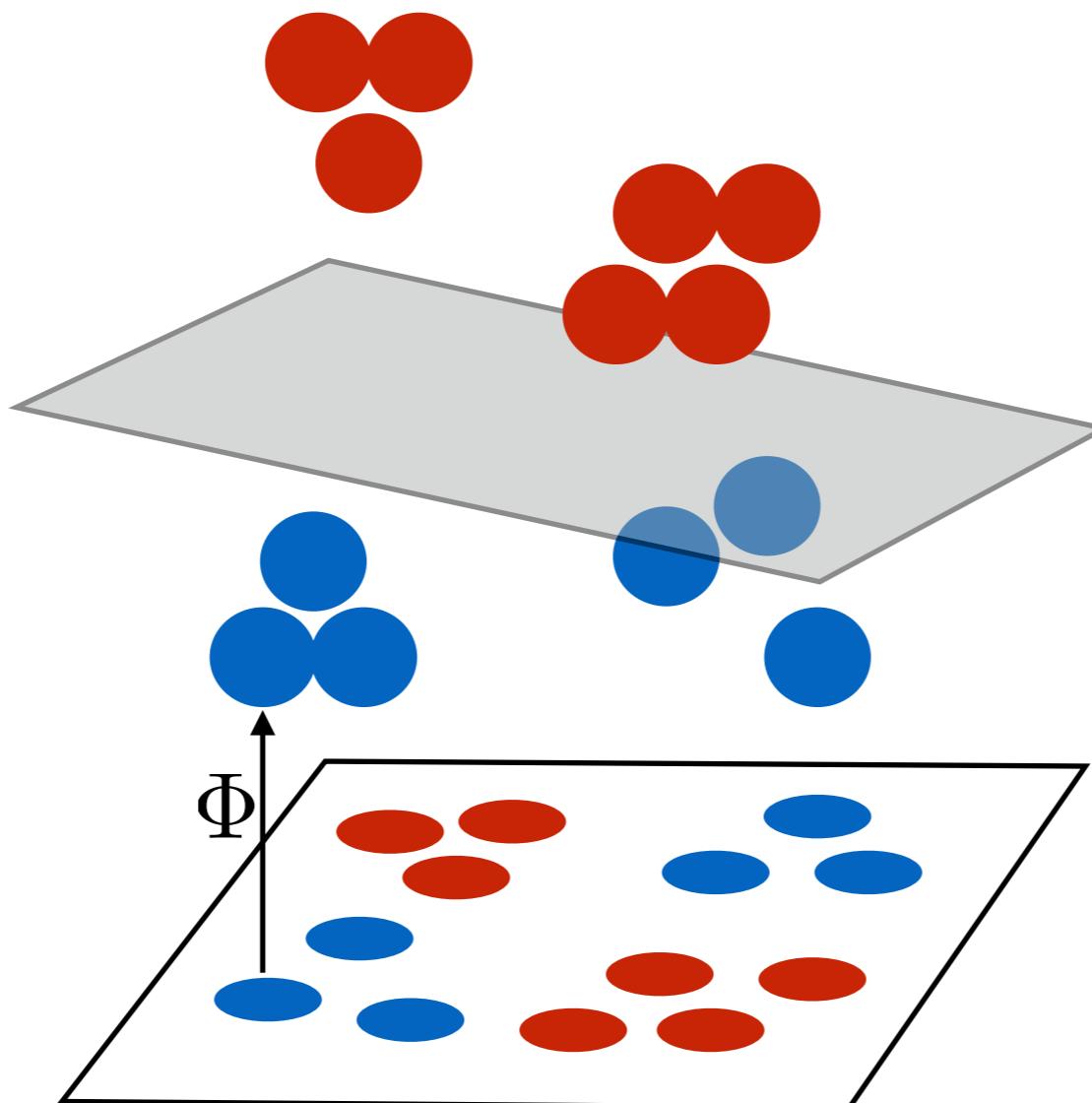
Kernel learning

Apply non-linear "feature map" $x \rightarrow \Phi(x)$



Kernel learning

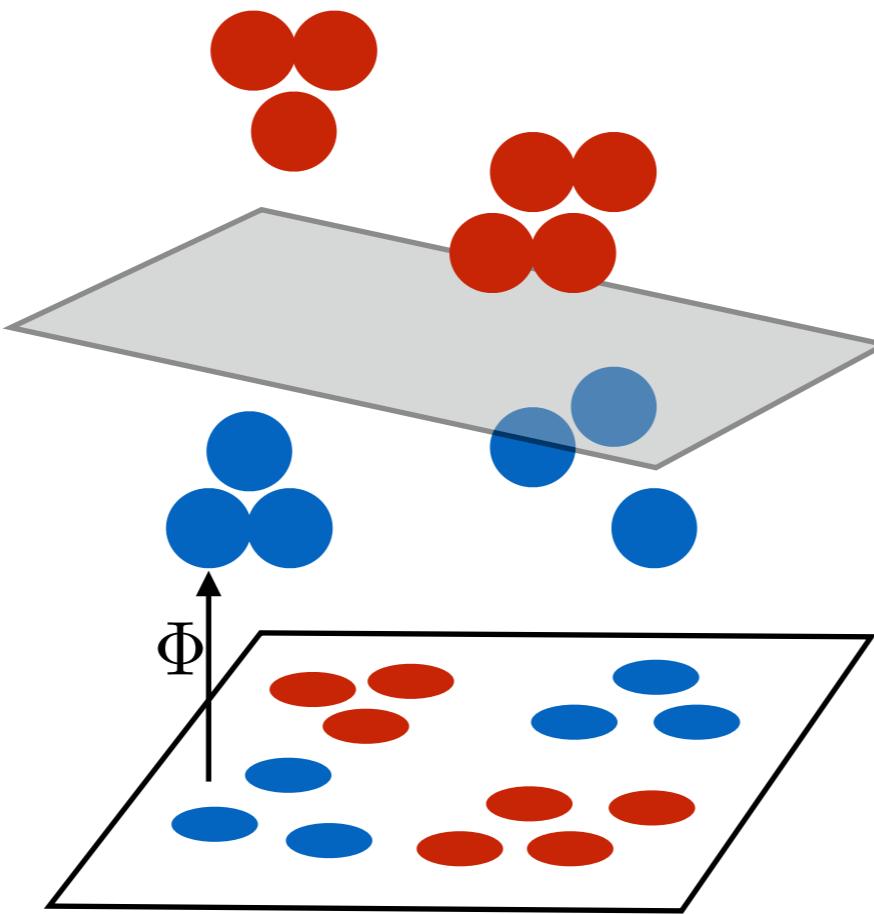
Apply non-linear "feature map" $x \rightarrow \Phi(x)$



Decision function

$$f(\mathbf{x}) = W \cdot \Phi(\mathbf{x})$$

Kernel learning



Decision function

$$f(\mathbf{x}) = \mathbf{W} \cdot \Phi(\mathbf{x})$$

Linear classifier in *feature space*

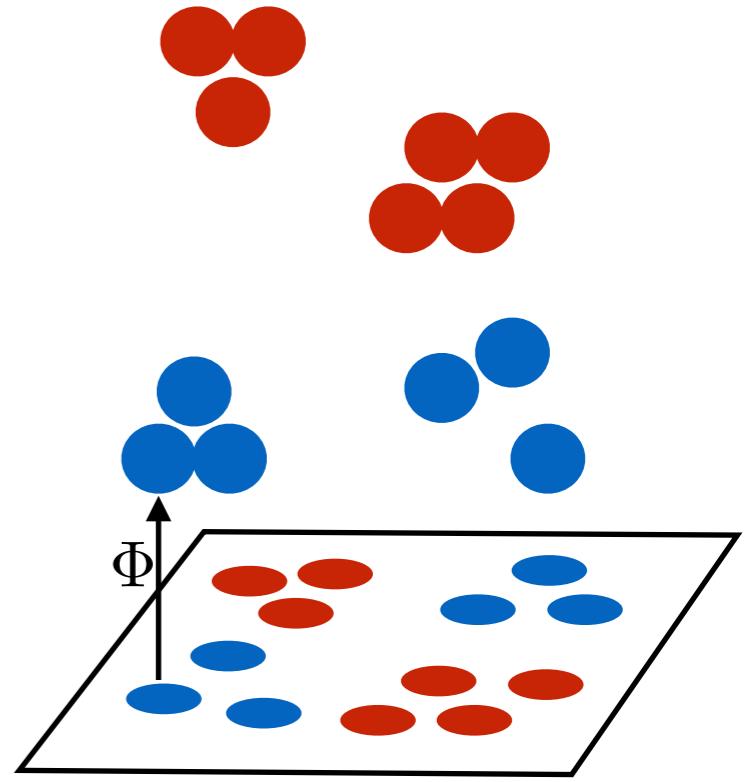
Kernel learning

Example of *feature map*

$$\mathbf{x} = (x_1, x_2, x_3)$$

$$\Phi(\mathbf{x}) = (1, x_1, x_2, x_3, x_1x_2, x_1x_3, x_2x_3)$$

\mathbf{x} is "lifted" to feature space



Kernel learning

Technical notes:

- Also called "support vector machine" when using a particular choice of cost function
- Name "kernel learning" comes from idea that $\Phi(\mathbf{x})$ may be too high dimensional, yet $K_{ij} = \Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{x}_j)$ may be efficiently computable, enough to optimize
- Very generally, optimal weights have the form

$$W = \sum_j \alpha_j \Phi(\mathbf{x}_j)$$

a result known as the "representer theorem"

Kernel learning

Kernel learning still popular among academics & for certain applications (e.g. life sciences)

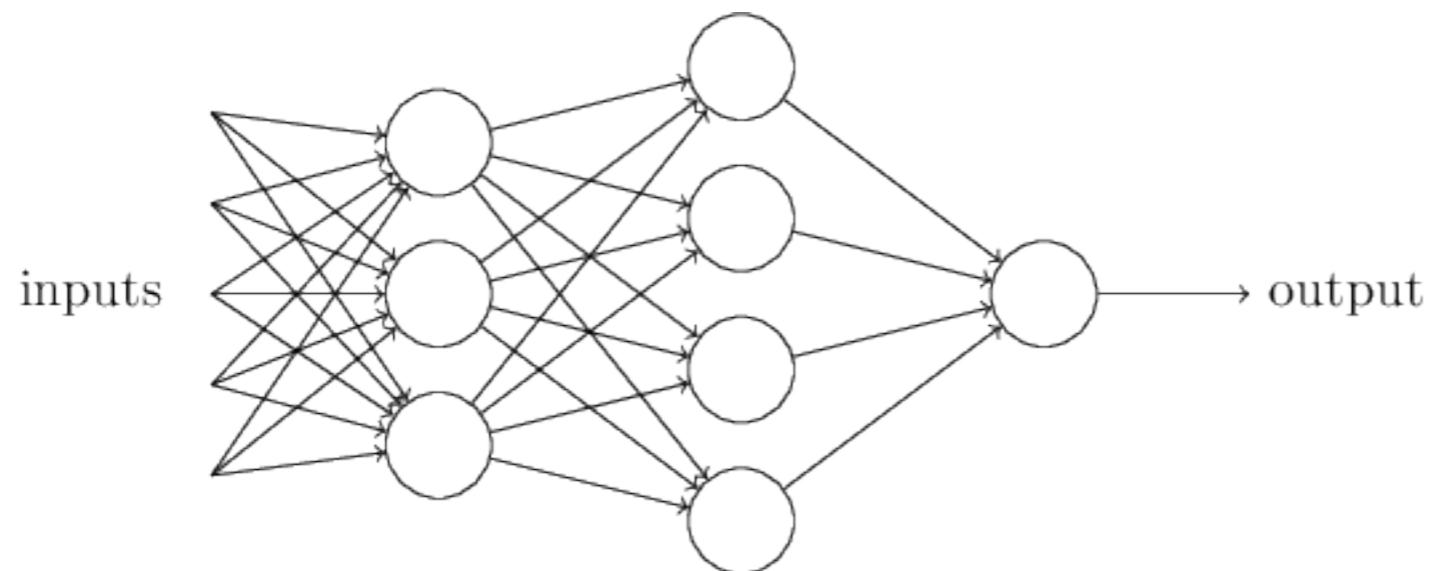
But "kernelization" approach scales as N^3 where N is size of training set – very costly!

Thus kernel methods not popular with engineers

Tomorrow: learning kernel models with tensor network weights

Neural networks

Current favorite of M.L. engineers



Often notated diagrammatically
(not a tensor diagram!)

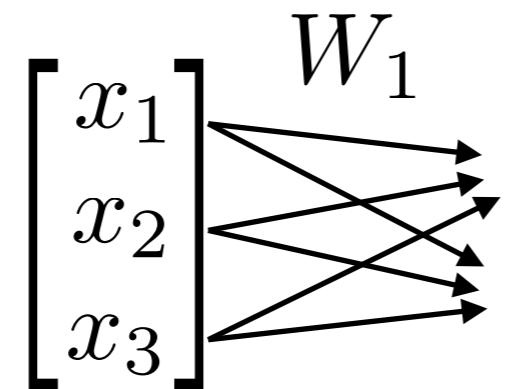
Neural networks

Actually very simple: compute a function $f(\mathbf{x})$ as

Neural networks

Actually very simple: compute a function $f(\mathbf{x})$ as

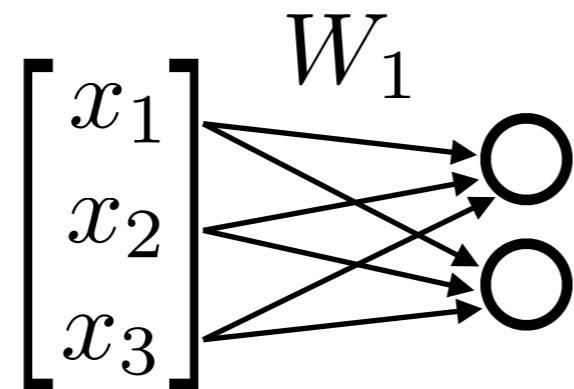
- Multiply input \mathbf{x} by rectangular "weight" matrix W_1



Neural networks

Actually very simple: compute a function $f(\mathbf{x})$ as

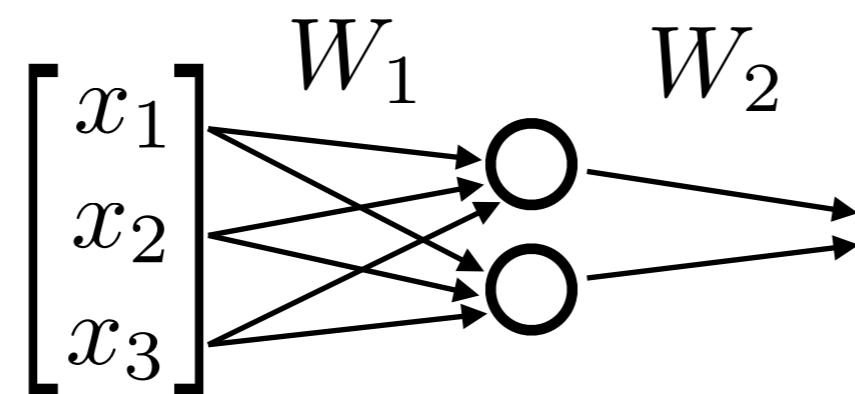
- Multiply input \mathbf{x} by rectangular "weight" matrix W_1
- Point-wise evaluate components of $\mathbf{x}' = W_1 \mathbf{x}$ by some non-linear function [e.g. $\sigma(x'_j) = 1/(1 - e^{x'_j - b})$]



Neural networks

Actually very simple: compute a function $f(\mathbf{x})$ as

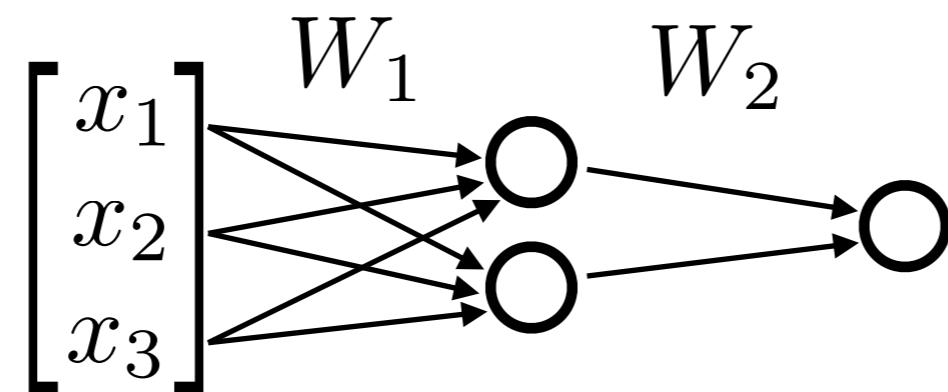
- Multiply input \mathbf{x} by rectangular "weight" matrix W_1
- Point-wise evaluate components of $\mathbf{x}' = W_1 \mathbf{x}$ by some non-linear function [e.g. $\sigma(x'_j) = 1/(1 - e^{x'_j - b})$]
- Multiply result by second weight matrix W_2



Neural networks

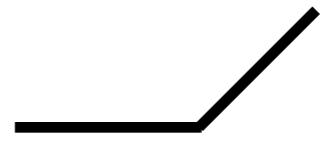
Actually very simple: compute a function $f(\mathbf{x})$ as

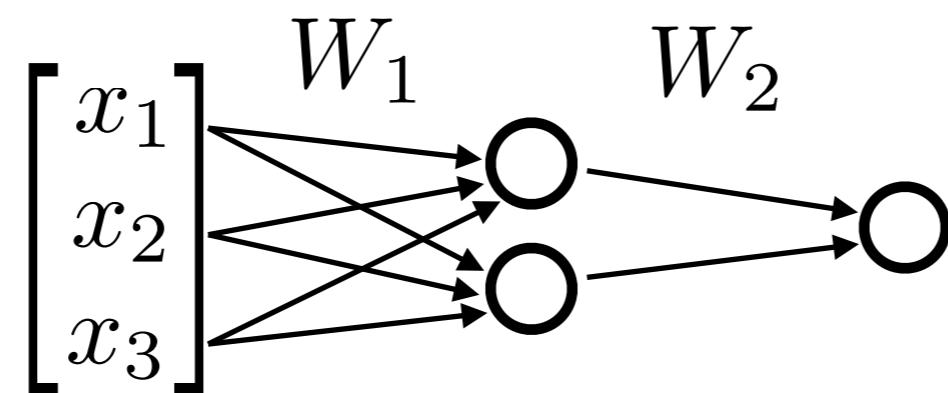
- Multiply input \mathbf{x} by rectangular "weight" matrix W_1
- Point-wise evaluate components of $\mathbf{x}' = W_1 \mathbf{x}$ by some non-linear function [e.g. $\sigma(x'_j) = 1/(1 - e^{x'_j - b})$]
- Multiply result by second weight matrix W_2
- Plug new components into nonlinearities, etc.



Neural networks

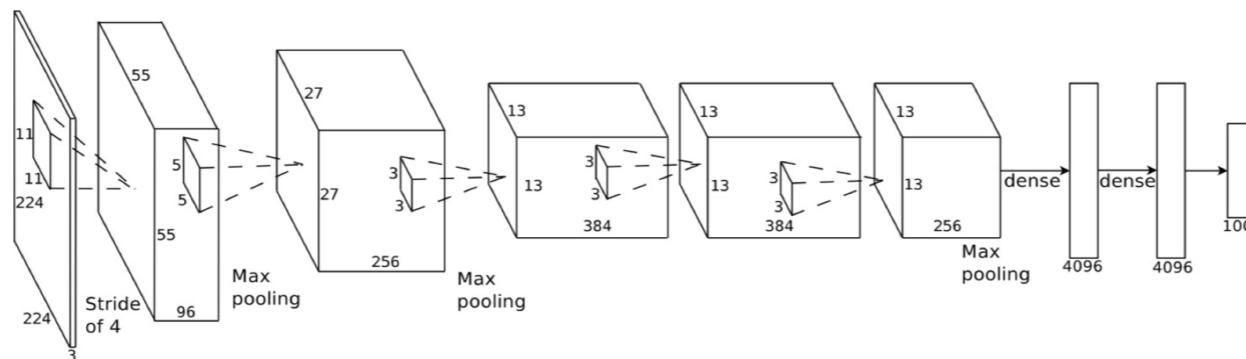
Additional facts:

- Non-linearities $\sigma(x)$ called "neurons"
- Other neurons include tanh and ReLU 
- Neural net with more than one weight matrix is "deep"
- Number of neurons is arbitrary, but with enough can represent any function



Neural networks

Many successful neural nets include "convolutional layers"
These have sparser weight layers with few parameters.

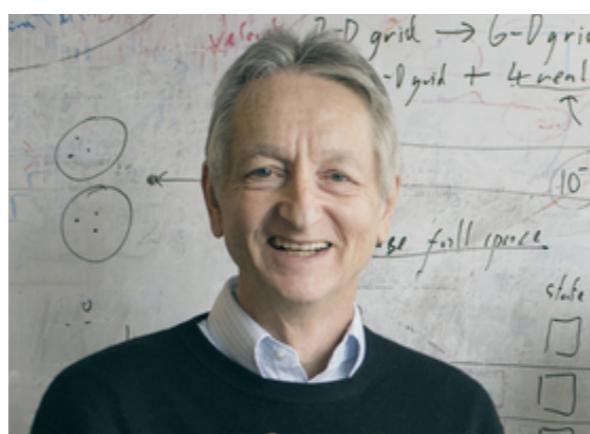


Recent upsurge of neural nets since 2012 (ImageNet paper)

"Deep learning" often associated with 3 researchers:



Yann LeCun (Facebook)



Geoff Hinton (Vector/Google)



Yoshua Bengio (Montreal)

Other model types

Graphical models

very similar to tensor networks, except

- always interpreted as probability
- non-negative parameters only

Boltzmann machines

identical to random-bond classical Ising ($T=1$)

J_{ij} values learnable parameters

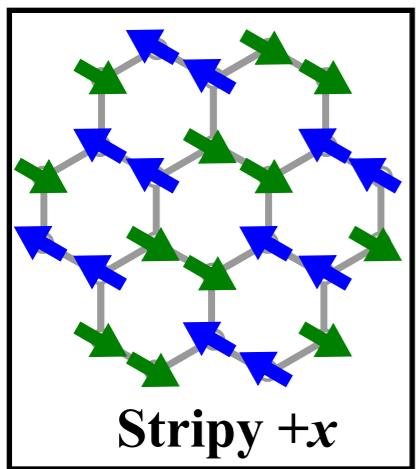
generate data by sampling subset of spins

Decision trees

make decisions about input by taking
forking paths

Selected Physics Applications

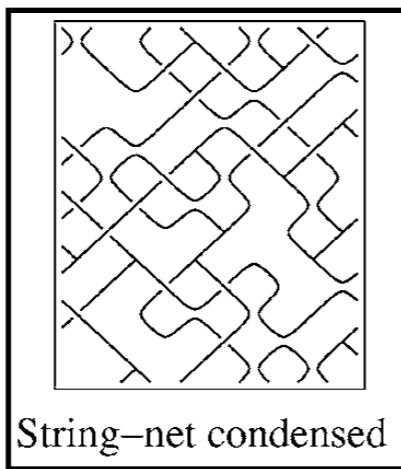
Phase recognition



Friends:

Lev Landau

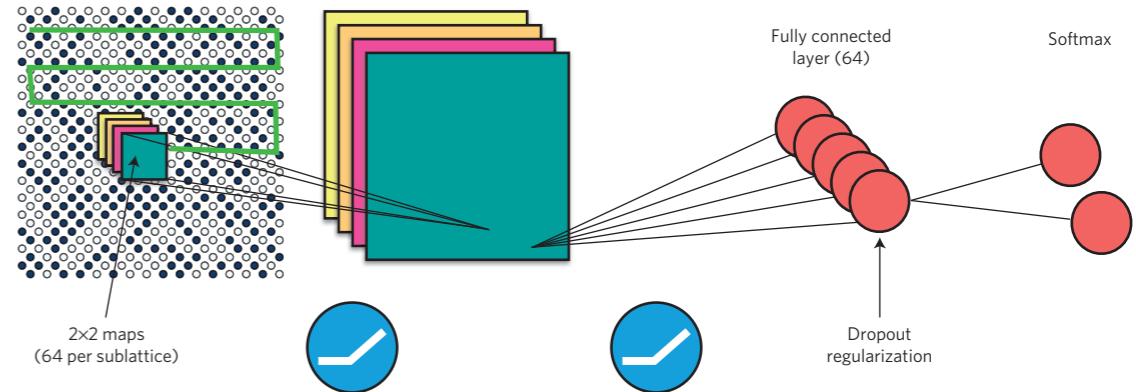
Werner Heisenberg



Friends:

Michael Levin

Xiao-Gang Wen



View Monte Carlo configurations as input data,
train model (supervised or unsupervised) to distinguish phases

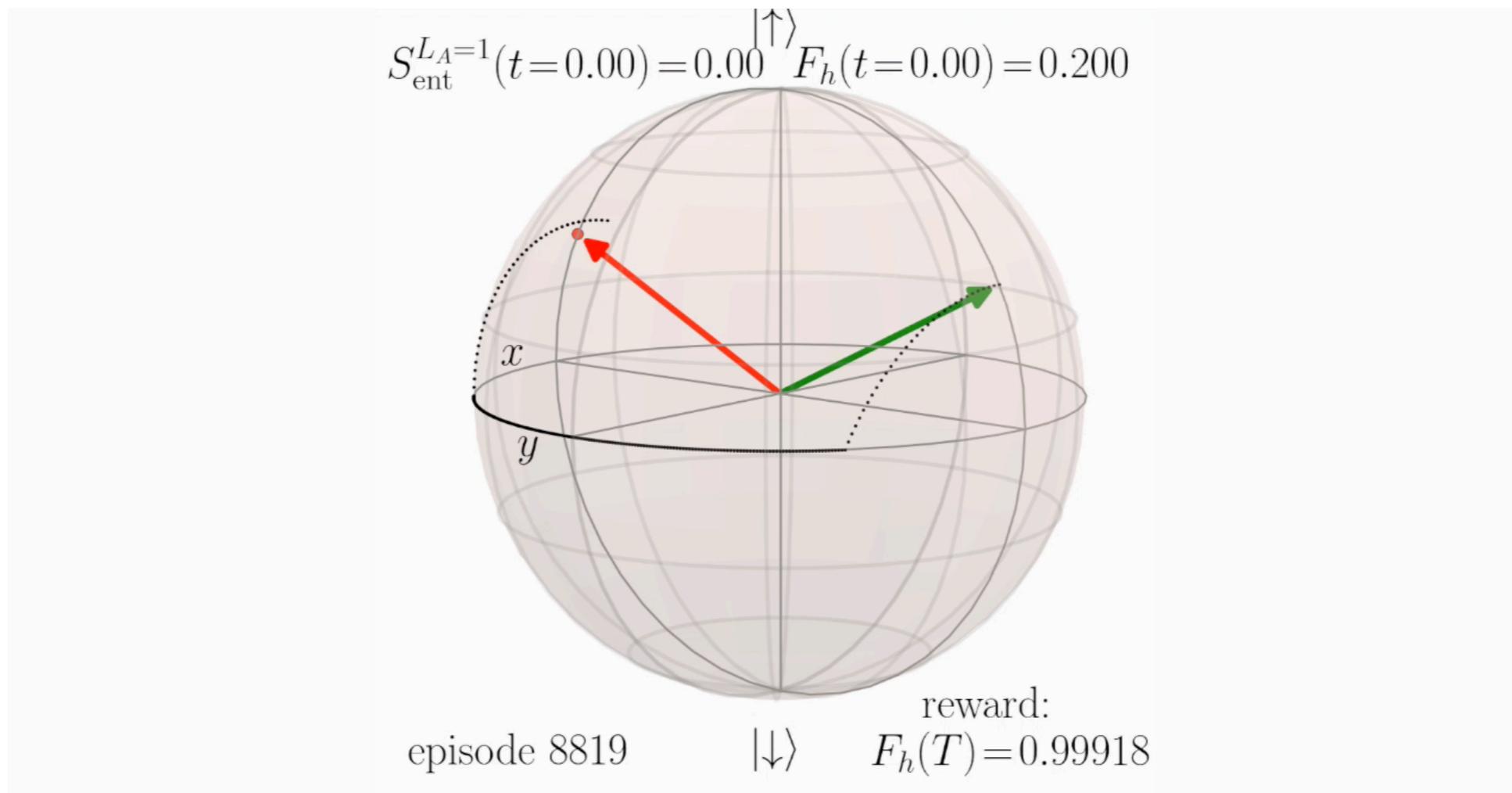
Some relevant papers:

- Carrasquilla, Melko, Nature Phys. (2017) [supervised]
- Wang, PRB 94, 195105 [unsupervised]
- Broecker, Carrasquilla, Melko, Trebst Scientific Reports 7, 8823 (2017) [from aux. field QMC]
- Broecker, Assaad, Trebst arxiv:1707.00663 [unsupervised]
- ... and quite a few others ...

Learning to Control Quantum Systems

How to apply time-dependent field to quantum system
and reach some target state?

Treat fidelity as "reward" and train reinforcement learning agent
to work out best protocol



Many Other Creative Ideas

Learning quantum Monte Carlo updates

J. Liu, Y. Qi, et al. arxiv:1610.03137

L. Huang, L. Wang, arxiv:1610.02746

L. Wang, arxiv:1702.08586

H. Shen, J. Liu, L. Fu, arxiv:1801.01127

Neural Net Representations of Wavefunctions

G. Carleo, M. Troyer, arxiv:1606.02318

D. Deng, X. Li, S. Das Sarma, arxiv:1609.09060, arxiv: 1701.04844

S. Clark, arxiv:1710.03545

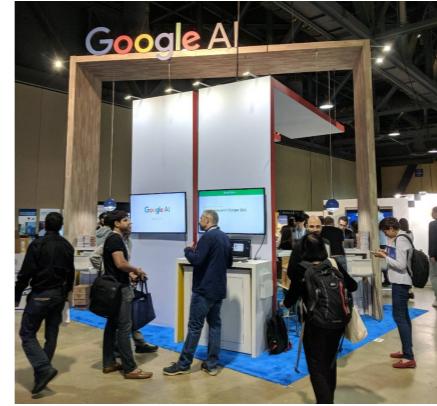
Learning Density Functionals

J. Snyder, et al., arxiv:1112.5441

F. Brockherde, et al., arxiv:1609.02815

L. Li, et al., arxiv:1609.03705

Machine Learning Research Culture



One sub-community is academic: papers often involve theorems

Another community is engineering-oriented: papers focus on results, developments are intuitive/faddish

Conference talks/posters valued above journal articles

Strong industry ties: Google, Microsoft, etc. have booths at conferences, grad students poached often

Recommended Resources

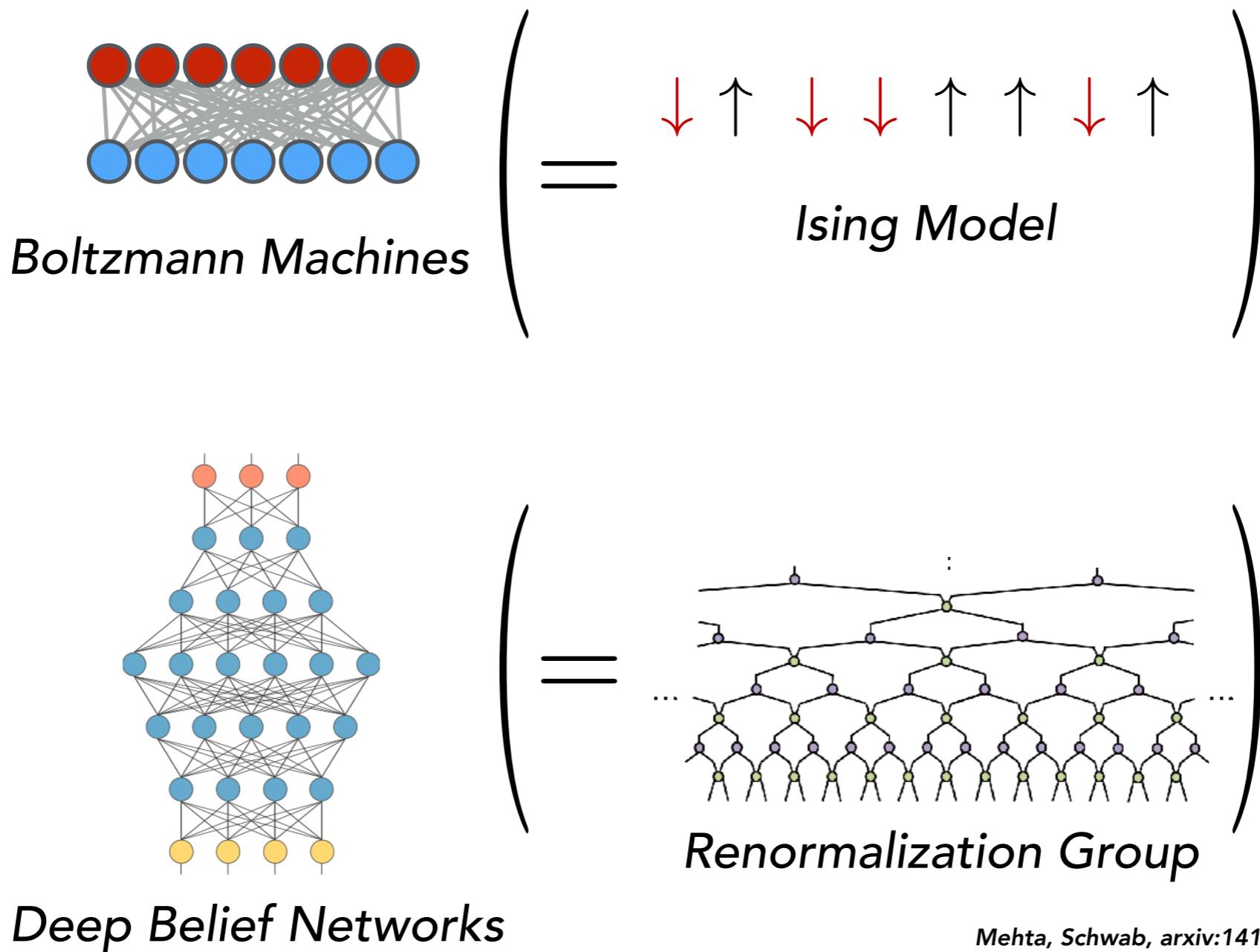
- Online book by Michael Nielsen (quant. computing author)
<http://neuralnetworksanddeeplearning.com>
- Caltech Lectures by Yaser Abu-Mostafa CS 156
Available on YouTube. Companion book "Learning from Data"
- M.L. review article by Pankaj Mehta, David Schwab
aimed at physicists
- TensorFlow examples (MNIST demo)
- Blogs of Chris Olah and Andrej Karpathy

Tensor Network Machine Learning

Stoudenmire, Schwab, *Advanced in Neural Information Processing Systems (NIPS)*, 29, 4799 [arxiv:1605.05775]



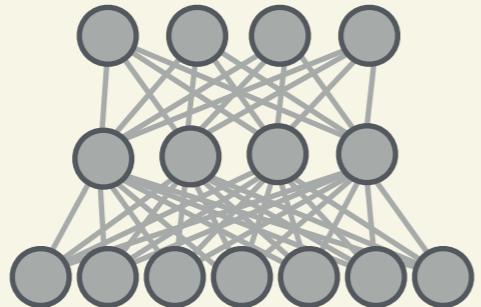
Many physics ideas in machine learning



Let's apply more ideas to M.L!

Analogy between wavefunctions & M.L. models

machine learning – model functions

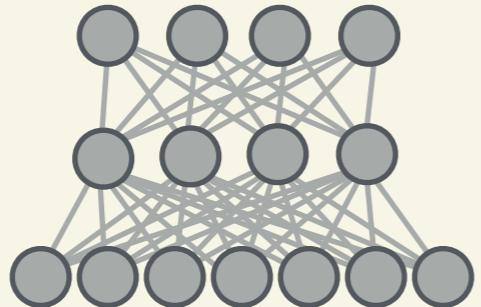


Neural Nets

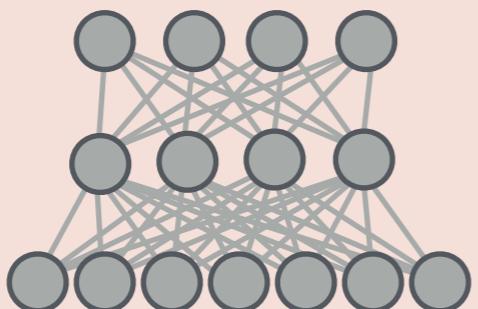
physics – wavefunctions

Analogy between wavefunctions & M.L. models

machine learning – model functions



Neural Nets

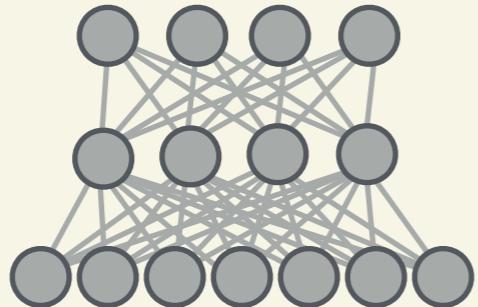


Neural Quantum States

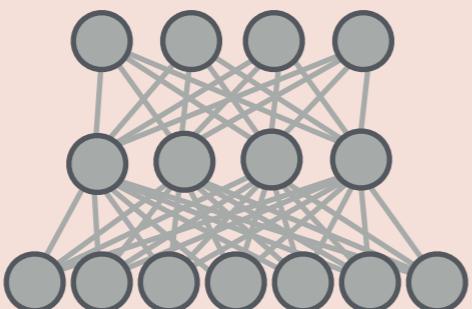
physics – wavefunctions

Analogy between wavefunctions & M.L. models

machine learning – model functions



Neural Nets



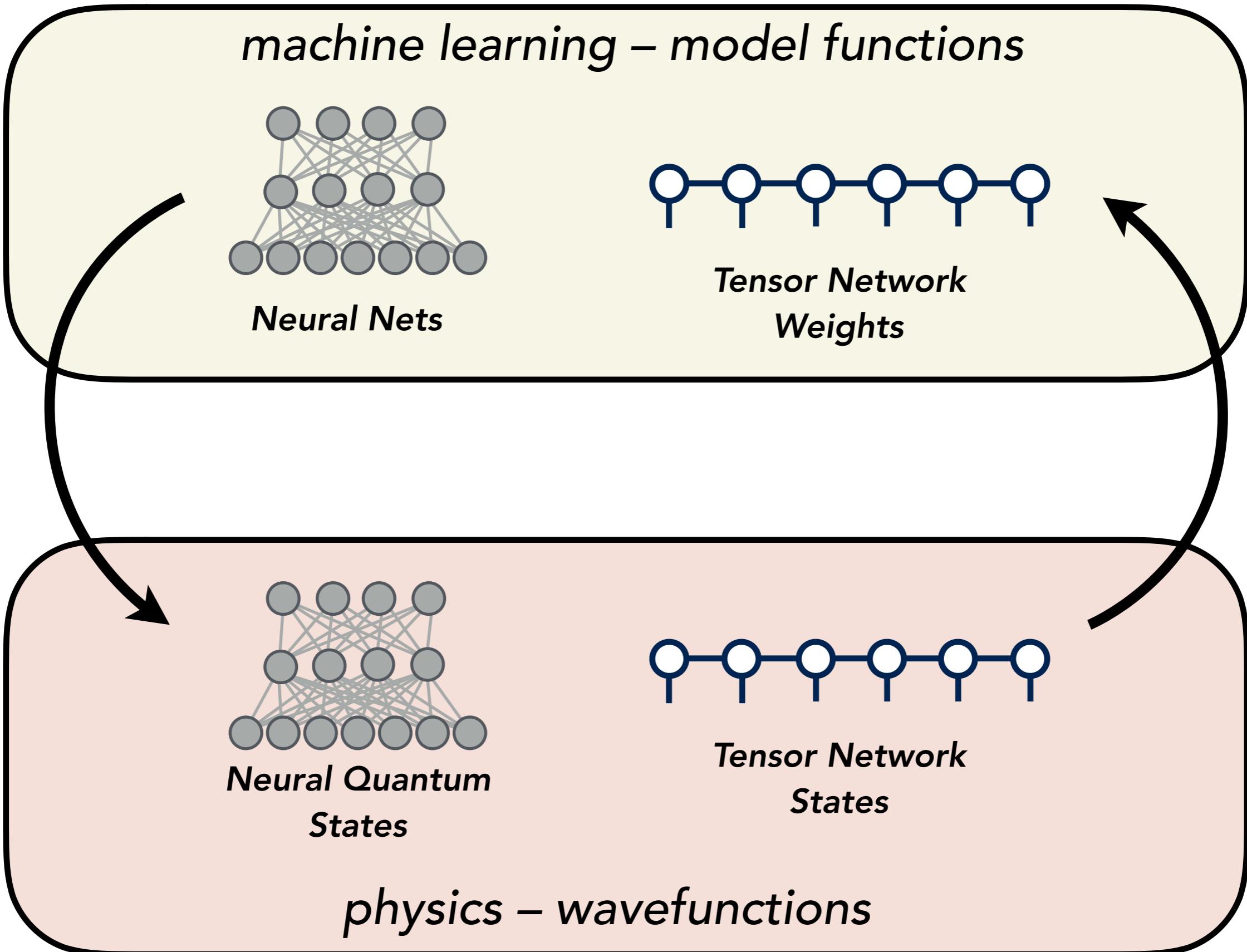
Neural Quantum States



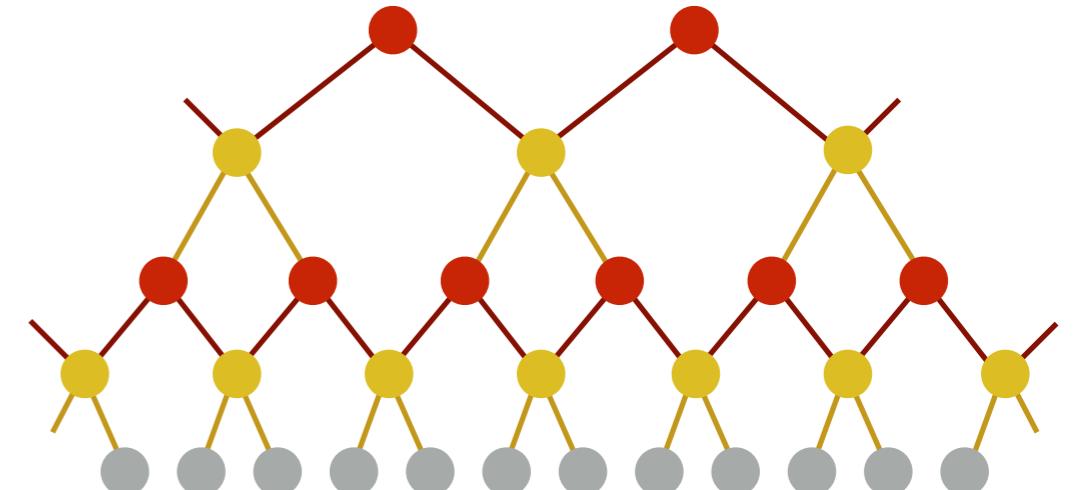
Tensor Network States

physics – wavefunctions

Analogy between wavefunctions & M.L. models



Are tensor networks useful for machine learning?



"MERA" tensor network

Tensor networks can represent weights of useful and interesting machine learning models

Realized benefits:

- Linear scaling
- Adaptive weights
- Learning data "features"

Future benefits?

- Interpretability / theory
- Better algorithms
- Quantum computing

Raw data vectors

$$\mathbf{x} = (x_1, x_2, x_3, \dots, x_N)$$

Example: grayscale images,
components of \mathbf{x} are pixels

$$x_j \in [0, 1]$$



A 10x10 grid of handwritten digits from 0 to 9, representing a 10x10 grayscale image. The digits are arranged in a single row, with each digit appearing 10 times. The digits are written in a cursive style.

0	0	0	0	0	0	0	0	0	0
1	1	1	1	1	1	1	1	1	1
2	2	2	2	2	2	2	2	2	2
3	3	3	3	3	3	3	3	3	3
4	4	4	4	4	4	4	4	4	4
5	5	5	5	5	5	5	5	5	5
6	6	6	6	6	6	6	6	6	6
7	7	7	7	7	7	7	7	7	7
8	8	8	8	8	8	8	8	8	8
9	9	9	9	9	9	9	9	9	9

Propose following model

$$f(\mathbf{x}) = W \cdot \Phi(\mathbf{x})$$

$$= \sum_{\mathbf{s}} W_{s_1 s_2 s_3 \dots s_N} x_1^{s_1} x_2^{s_2} x_3^{s_3} \dots x_N^{s_N} \quad s_j = 0, 1$$

Weights are N-index tensor
Like N-site wavefunction

Cohen et al. arxiv:1509.05009
Novikov, Trofimov, Oseledets, arxiv:1605.03795
Stoudenmire, Schwab, arxiv:1605.05775

N=3 example:

$$\begin{aligned} f(\mathbf{x}) &= W \cdot \Phi(\mathbf{x}) = \sum_{\mathbf{s}} W_{s_1 s_2 s_3} x_1^{s_1} x_2^{s_2} x_3^{s_3} \\ &= W_{000} + W_{100} x_1 + W_{010} x_2 + W_{001} x_3 \\ &\quad + W_{110} x_1 x_2 + W_{101} x_1 x_3 + W_{011} x_2 x_3 \\ &\quad + W_{111} x_1 x_2 x_3 \end{aligned}$$

Contains linear classifier, plus other "feature maps"

More generally, apply local "feature maps" $\phi^{s_j}(x_j)$

$$f(\mathbf{x}) = W \cdot \Phi(\mathbf{x})$$

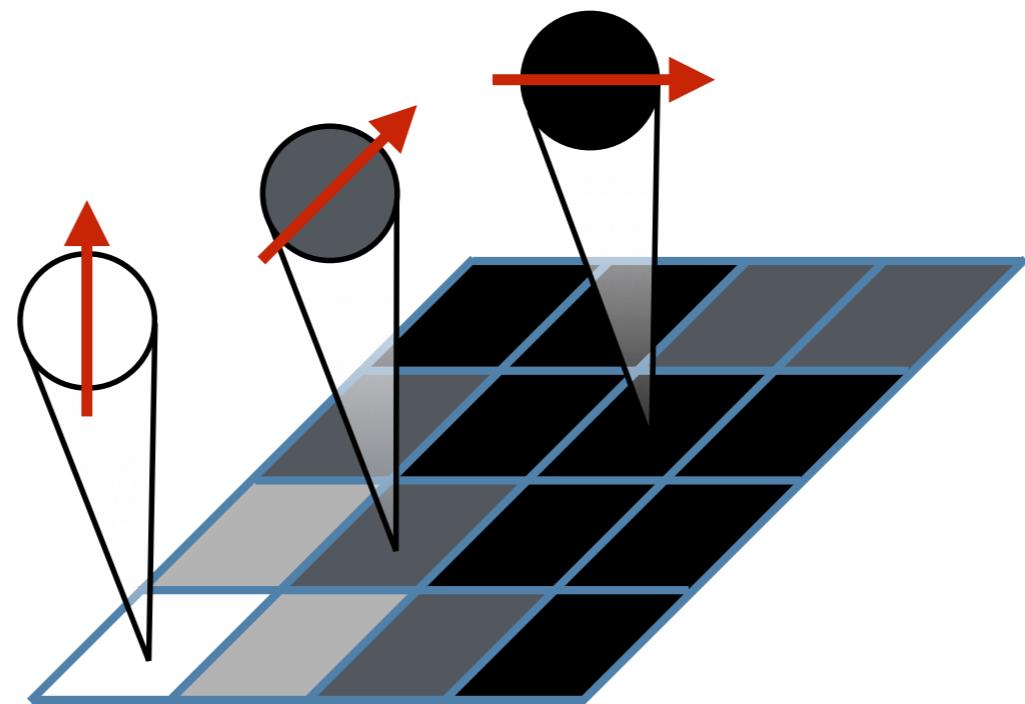
$$= \sum_{\mathbf{s}} W_{s_1 s_2 s_3 \dots s_N} \phi^{s_1}(x_1) \phi^{s_2}(x_2) \phi^{s_3}(x_3) \dots \phi^{s_N}(x_N)$$

Highly expressive!

For example, following local feature map

$$\phi(x_j) = \left[\cos\left(\frac{\pi}{2}x_j\right), \sin\left(\frac{\pi}{2}x_j\right) \right] \quad x_j \in [0, 1]$$

Picturesque idea of pixels as "spins"



\mathbf{x} = input

ϕ = local feature map

Total feature map $\Phi(\mathbf{x})$

$$\Phi^{s_1 s_2 \cdots s_N}(\mathbf{x}) = \phi^{s_1}(x_1) \otimes \phi^{s_2}(x_2) \otimes \cdots \otimes \phi^{s_N}(x_N)$$

- Tensor product of local feature maps / vectors
- Just like product state wavefunction of spins
- Vector in 2^N dimensional space

\mathbf{x} = input

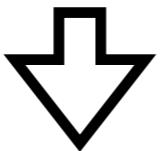
ϕ = local feature map

Total feature map $\Phi(\mathbf{x})$

More detailed notation

$$\mathbf{x} = [x_1, \ x_2, \ x_3, \ \dots, \ x_N]$$

raw inputs



$$\Phi(\mathbf{x}) = \begin{bmatrix} \phi_1(x_1) \\ \phi_2(x_1) \end{bmatrix} \otimes \begin{bmatrix} \phi_1(x_2) \\ \phi_2(x_2) \end{bmatrix} \otimes \begin{bmatrix} \phi_1(x_3) \\ \phi_2(x_3) \end{bmatrix} \otimes \dots \otimes \begin{bmatrix} \phi_1(x_N) \\ \phi_2(x_N) \end{bmatrix}$$

*feature
vector*

\mathbf{x} = input

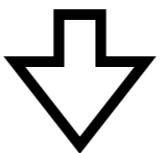
ϕ = local feature map

Total feature map $\Phi(\mathbf{x})$

Tensor diagram notation

$$\mathbf{x} = [x_1, \quad x_2, \quad x_3, \quad \dots, \quad x_N]$$

raw inputs

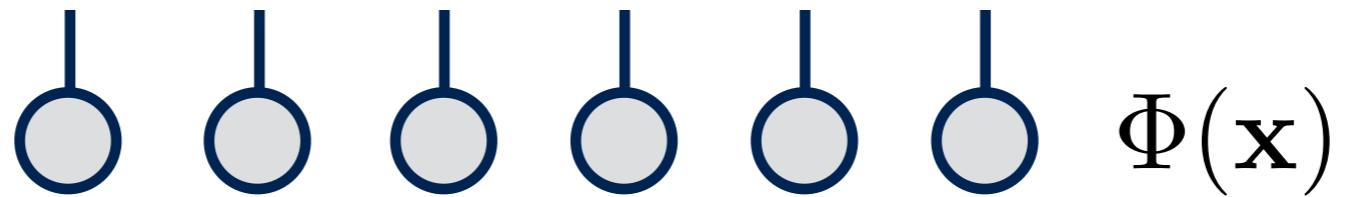


$$\Phi(\mathbf{x}) = \begin{array}{ccccccc} s_1 & s_2 & s_3 & s_4 & s_5 & s_6 & s_N \\ \phi^{s_1} & \phi^{s_2} & \phi^{s_3} & \phi^{s_4} & \phi^{s_5} & \phi^{s_6} & \dots \end{array}$$

*feature
vector*

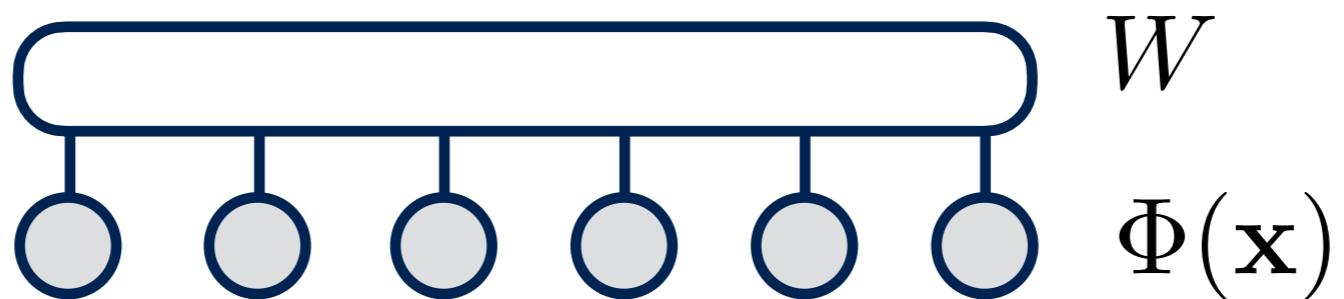
Construct decision function

$$f(\mathbf{x}) = W \cdot \Phi(\mathbf{x})$$



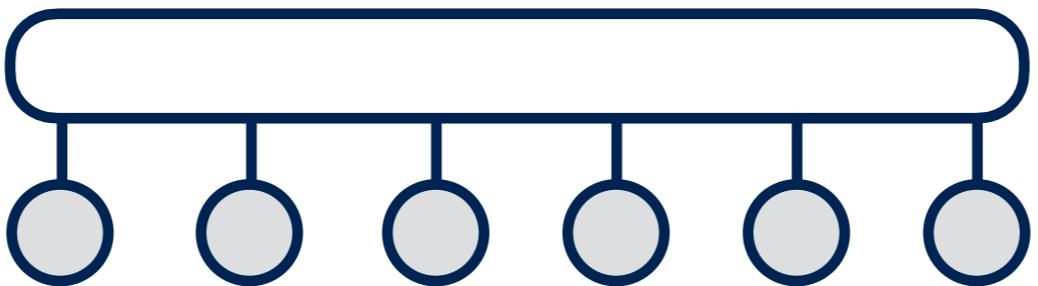
Construct decision function

$$f(\mathbf{x}) = W \cdot \Phi(\mathbf{x})$$



Construct decision function

$$f(\mathbf{x}) = W \cdot \Phi(\mathbf{x})$$

$$f(\mathbf{x}) = \begin{array}{c} \text{---} \\ | \\ \text{---} \end{array} \begin{array}{l} W \\ \Phi(\mathbf{x}) \end{array}$$


Construct decision function

$$f(\mathbf{x}) = W \cdot \Phi(\mathbf{x})$$

$$f(\mathbf{x}) = \begin{array}{c} \text{---} \\ | \\ \text{---} \end{array} \begin{array}{l} W \\ \Phi(\mathbf{x}) \end{array}$$

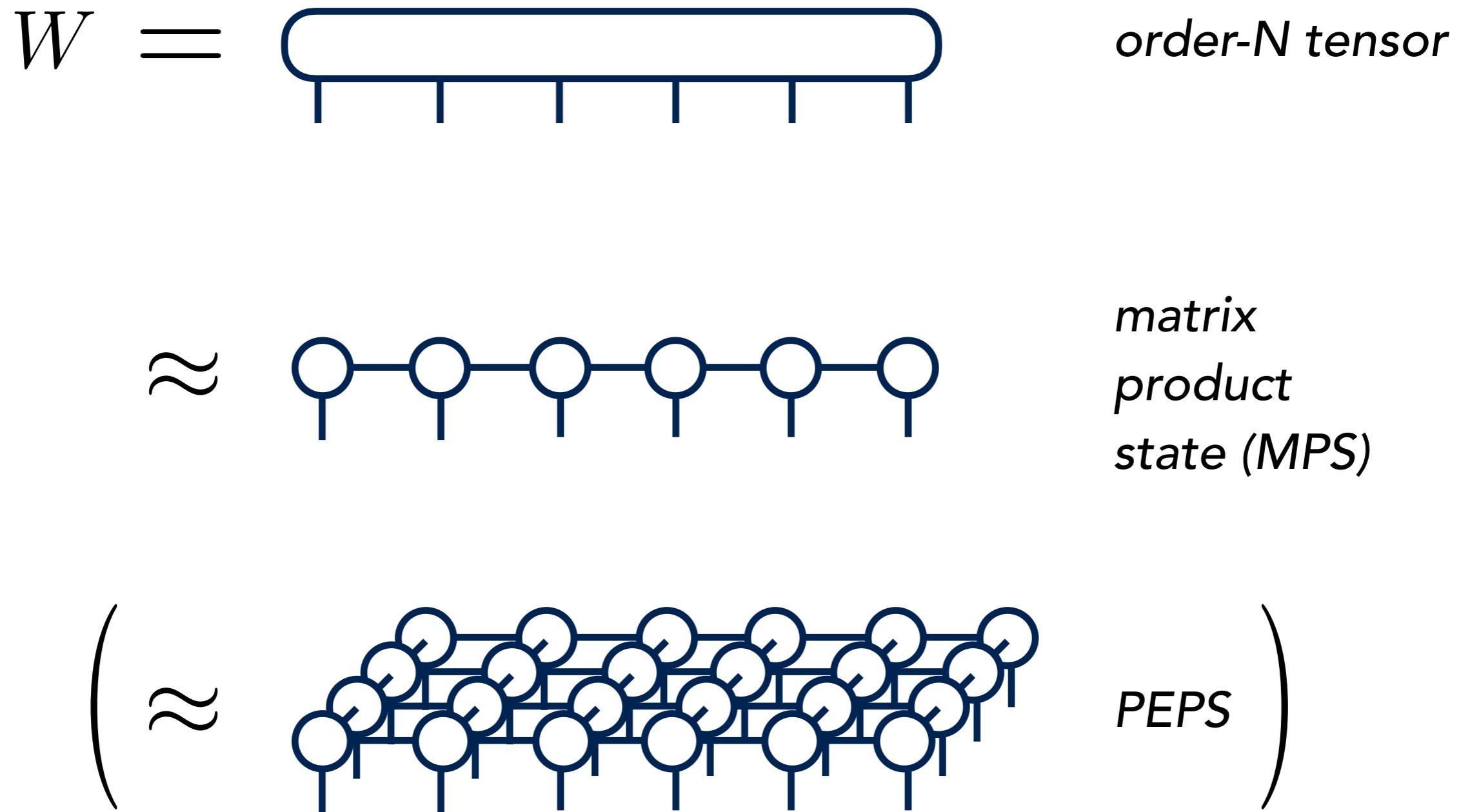
$$W = \text{---}$$

Main approximation

$$W = \text{---} \quad \text{order-}N \text{ tensor}$$
$$\approx \text{---} \quad \begin{matrix} \text{matrix} \\ \text{product} \\ \text{state (MPS)} \end{matrix}$$

The diagram illustrates the main approximation of a tensor W . On the left, a thick horizontal line with vertical tick marks at its ends is labeled "order- N tensor". On the right, a thin horizontal line with vertical tick marks at its ends is labeled "matrix product state (MPS)". A wavy line symbol between them indicates they are approximately equal.

Main approximation



Linear scaling

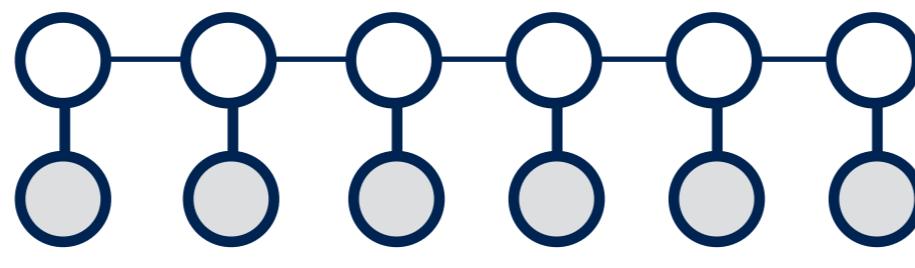
Can use algorithm similar to DMRG to optimize

Scaling is $N \cdot N_T \cdot m^3$

N = size of input

N_T = size of training set

m = MPS bond dimension

$$f(\mathbf{x}) = \begin{array}{c} \text{---} \\ | \\ \text{---} \end{array} W \Phi(\mathbf{x})$$


Linear scaling

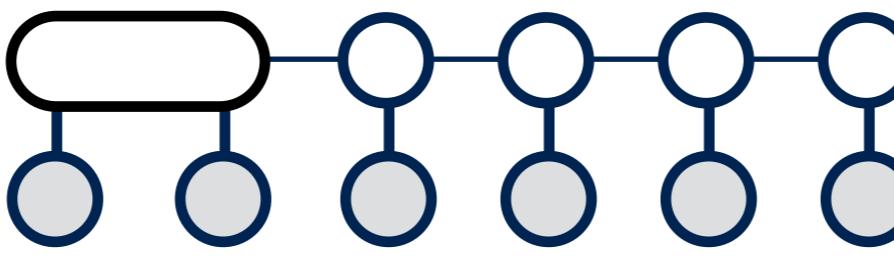
Can use algorithm similar to DMRG to optimize

Scaling is $N \cdot N_T \cdot m^3$

N = size of input

N_T = size of training set

m = MPS bond dimension

$$f(\mathbf{x}) = \Phi(\mathbf{x}) W$$


Linear scaling

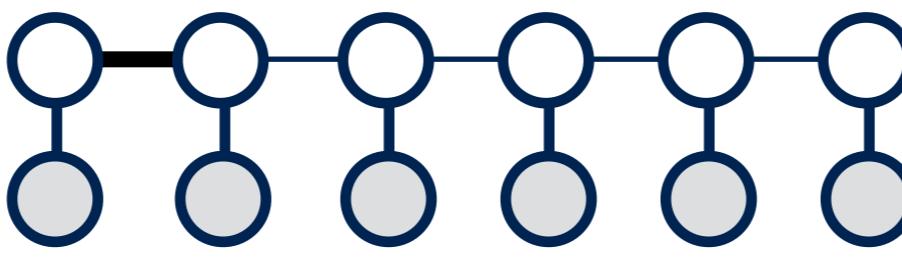
Can use algorithm similar to DMRG to optimize

Scaling is $N \cdot N_T \cdot m^3$

N = size of input

N_T = size of training set

m = MPS bond dimension

$$f(\mathbf{x}) = \Phi(\mathbf{x}) W$$


Linear scaling

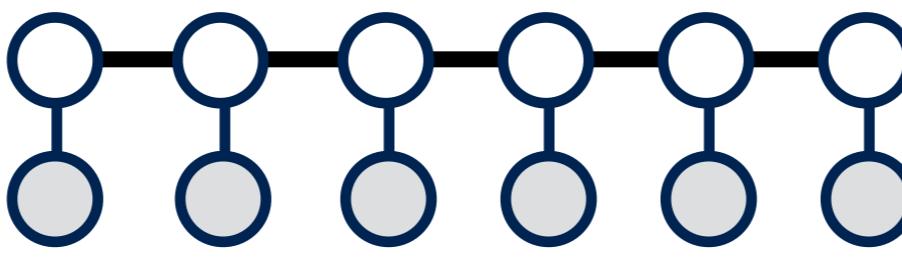
Can use algorithm similar to DMRG to optimize

Scaling is $N \cdot N_T \cdot m^3$

N = size of input

N_T = size of training set

m = MPS bond dimension

$$f(\mathbf{x}) = \Phi(\mathbf{x}) W$$


Why should this work at all?

Linear classifier $f(\mathbf{x}) = V \cdot \mathbf{x}$ exactly m=2 MPS

$$W =$$

$$\begin{bmatrix} V_0 & 1 \end{bmatrix} \begin{bmatrix} \hat{1} & 0 \\ \hat{V}_1 & \hat{1} \end{bmatrix} \begin{bmatrix} \hat{1} & 0 \\ \hat{V}_2 & \hat{1} \end{bmatrix} \begin{bmatrix} \hat{1} & 0 \\ \hat{V}_3 & \hat{1} \end{bmatrix} \cdots$$

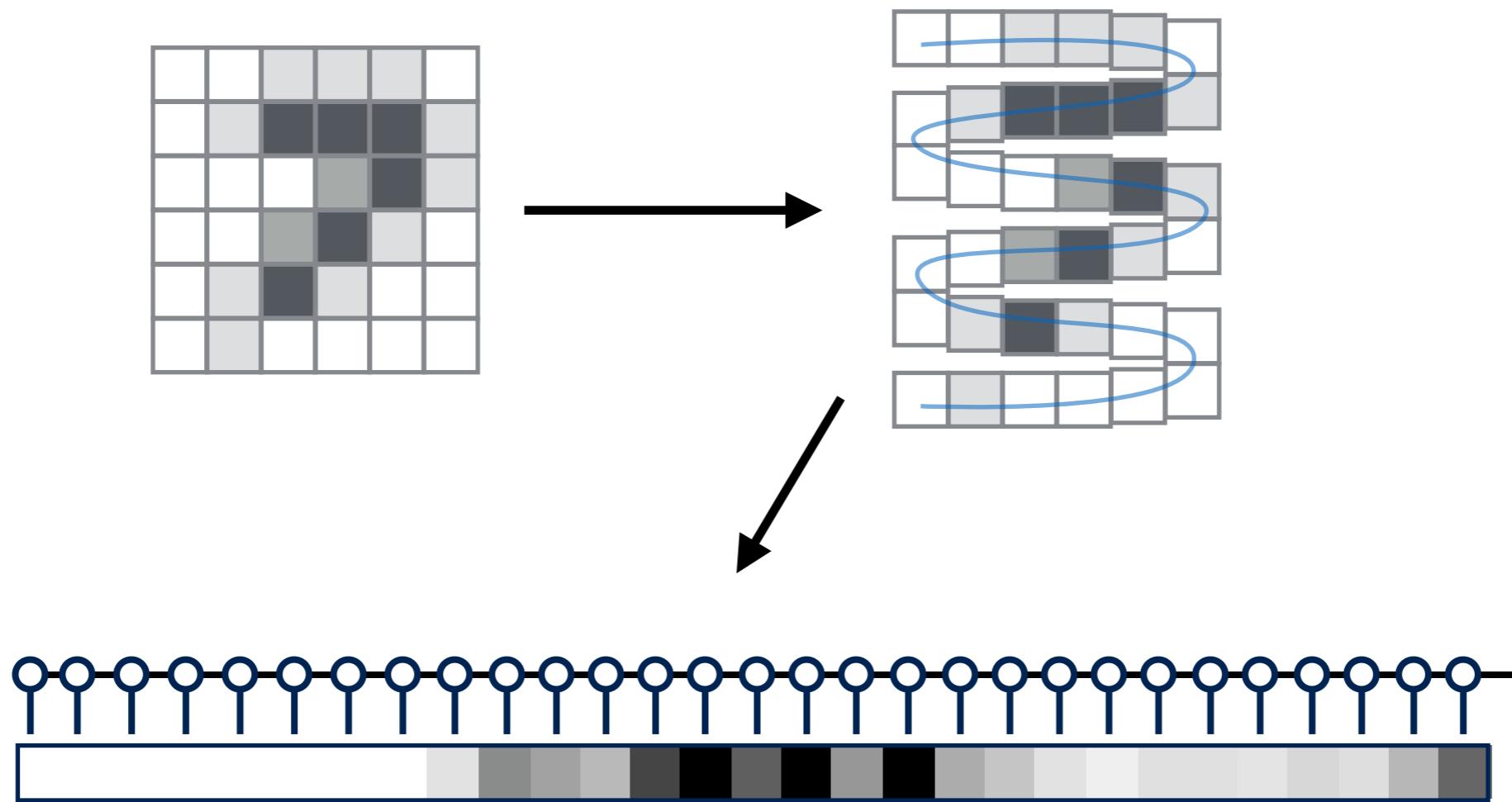
$$\hat{1} = [1 \ 0]$$

$$f(\mathbf{x}) = W \cdot \Phi(\mathbf{x})$$

$$\hat{V}_j = [0 \ V_j]$$

$$\phi^{s_j}(x_j) = [1, x_j]$$

Experiment: handwriting classification (MNIST)



Train to 99.95% accuracy on 60,000 training images

Obtain **99.03%** accuracy on 10,000 test images
(only 97 incorrect)

Papers using tensor network machine learning

Expressivity & priors of TN based models

- Levine et al., "Deep Learning and Quantum Entanglement: Fundamental Connections with Implications to Network Design" arxiv:1704.01552
- Cohen, Shashua, "Inductive Bias of Deep Convolutional Networks through Pooling Geometry" arxiv:1605.06743
- Cohen et al., "On the Expressive Power of Deep Learning: A Tensor Analysis" arxiv: 1509.05009

Generative Models

- Han et al., "Unsupervised Generative Modeling Using Matrix Product States" arxiv: 1709.01662
- Sharir et al., "Tractable Generative Convolutional Arithmetic Circuits" arxiv: 1610.04167

Supervised Learning

- Novikov et al., "Expressive power of recurrent neural networks", arxiv:1711.00811
- Liu et al., "Machine Learning by Two-Dimensional Hierarchical Tensor Networks: A Quantum Information Theoretic Perspective on Deep Architectures", arxiv: 1710.04833
- Stoudenmire, Schwab, "Supervised Learning with Quantum-Inspired Tensor Networks", arxiv:1605.05775
- Novikov et al., "Exponential Machines", arxiv: 1605.03795

Related uses of tensor networks

Compressing weights of neural nets (& other models)

Yu et al., *Advances in Neural Information Processing* (2017), arxiv:1711.00073

Izmailov et al., arxiv:1710.07324 (2017)

Yang et al., arxiv:1707.01786 (2017)

Garipov et al., arxiv:1611.03214 (2016)

Novikov et al., *Advances in Neural Information Processing* (2015) (arxiv:1509.06569)

Large scale linear algebra (PCA/SVD)

Lee, Cichocki, arxiv: 1410.6895 (2014)

Feature extraction & tensor completion

Bengua et al., arxiv:1606.01500, arxiv:1607.03967, arxiv:1609.04541 (2016)

Phien et al., arxiv:1601.01083 (2016)

Bengua et al., *IEEE Congress on Big Data* (2015)

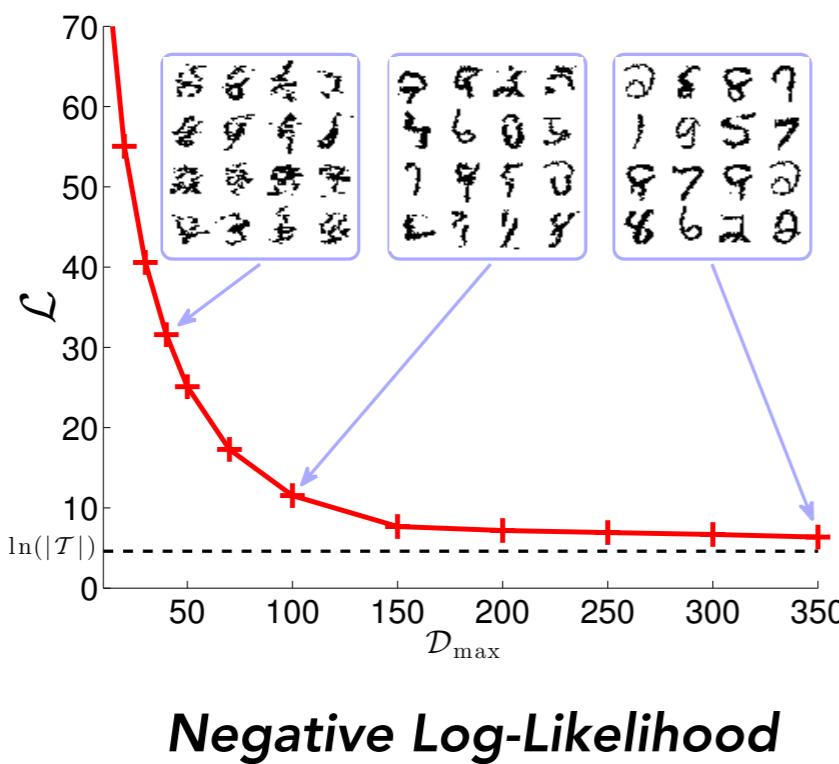
Tensor Network Machine Learning Studies

Unsupervised Generative Modeling Using MPS

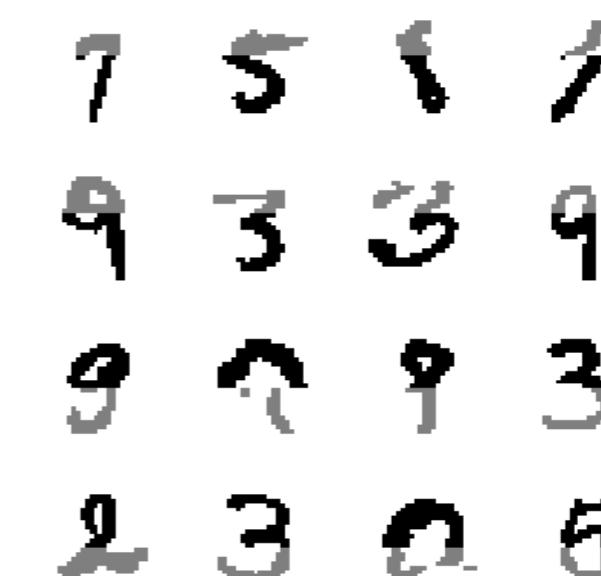
Zhao-Yu Han, Jun Wang, Heng Fan, Lei Wang, Pan Zhang

- Map data to product state, tensor network weights
- Squared output is probability – "Born machine"
- "Perfect" sampling (no autocorrelation)

$$p(\mathbf{x}) = \left| \begin{array}{cccccc} x_1 & x_2 & x_3 & x_4 & x_5 & x_6 \\ \text{---} & \text{---} & \text{---} & \text{---} & \text{---} & \text{---} \end{array} \right|^2$$



Negative Log-Likelihood

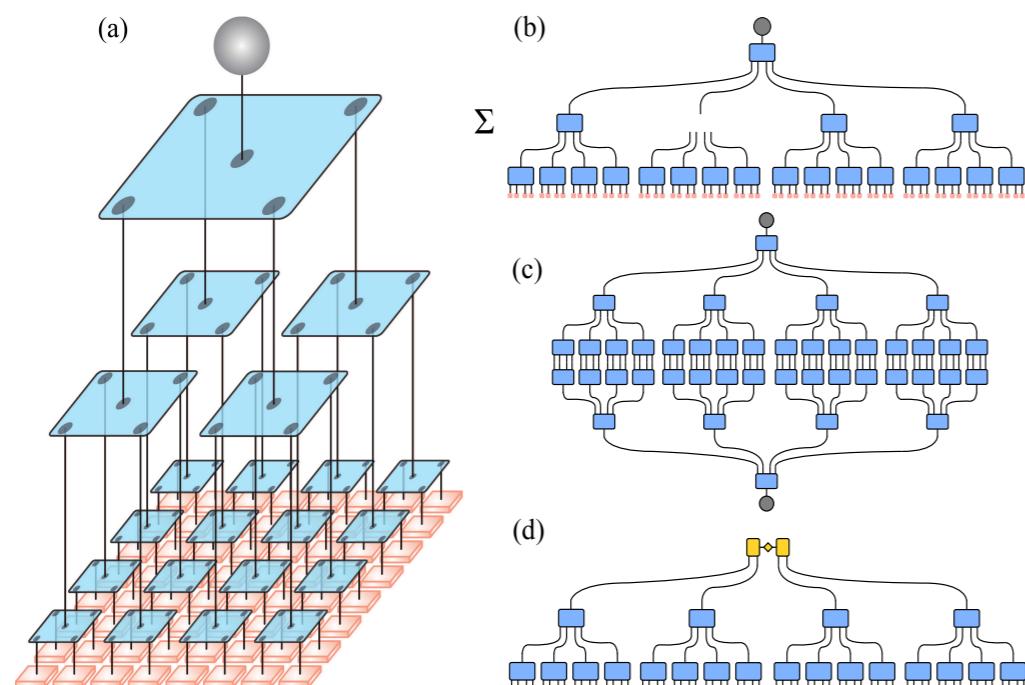


Reconstructing Testing Images

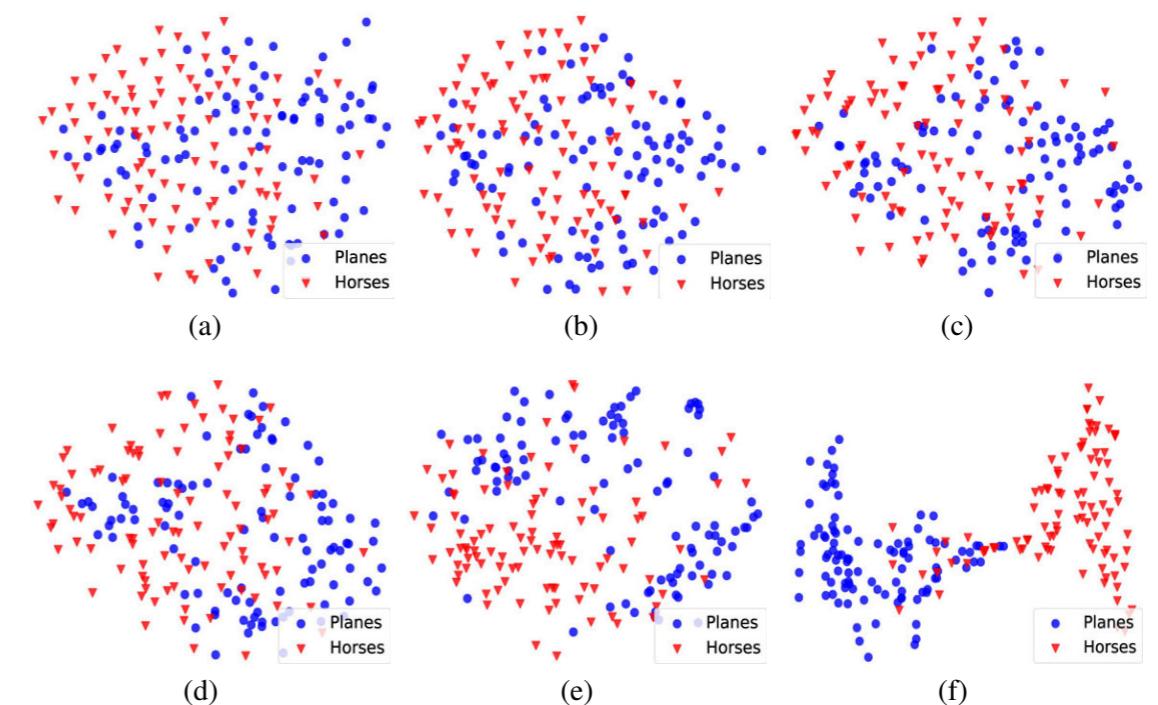
Machine Learning By Hierarchical Tensor Networks...

Ding Liu, Shi-Ju Ran, Peter Wittek, Cheng Peng, Raul Blazquez Garcia, Gang Su, Maciej Lewenstein

- Supervised learning with tree tensor networks
- Tests on MNIST, CIFAR-10
- Studied properties of the trained model (feature representations, entanglement)



Model Architecture

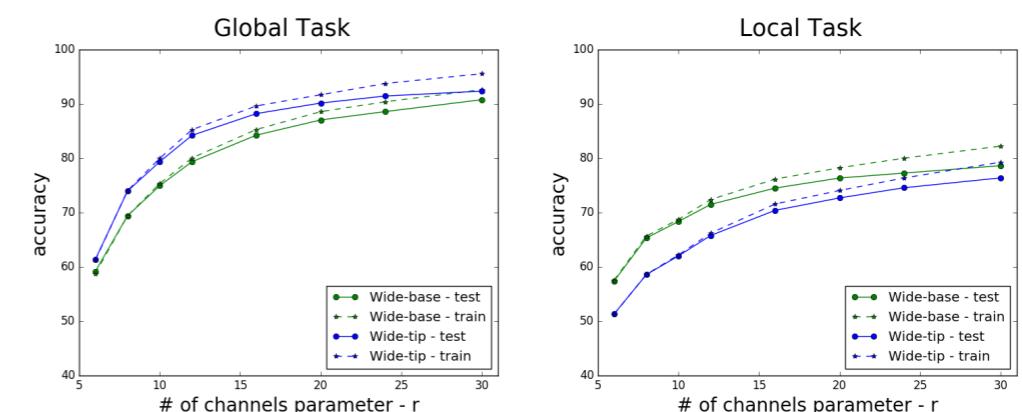
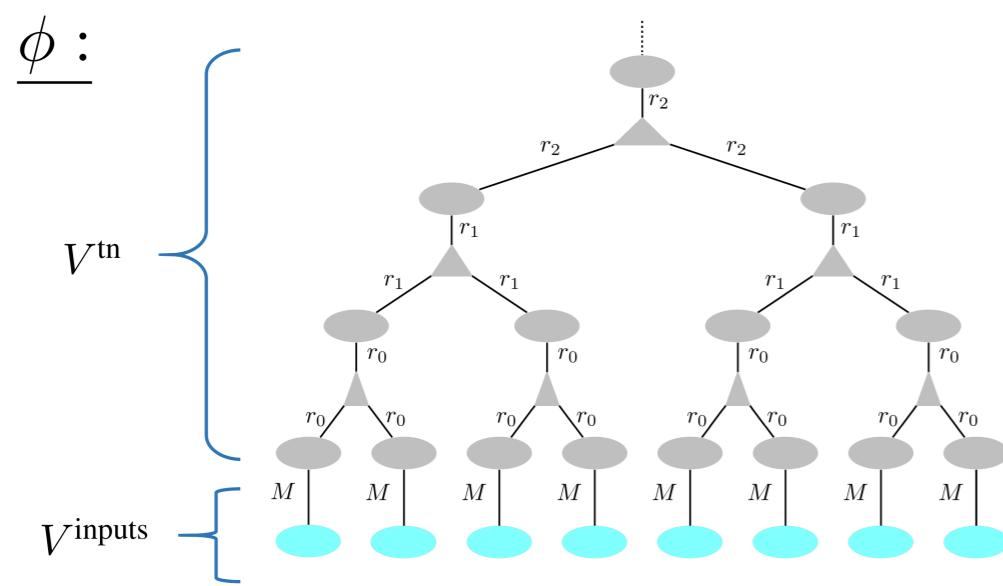


**Data Representation at
Different Scales**

Deep Learning and Quantum Entanglement...

Yoav Levine, David Yakira, Nadav Cohen, Amnon Shashua

- "ConvAC" deep neural net = tree tensor network
- Tensor network rank as capacity of model
- Experiment on "inductive bias" of model architecture



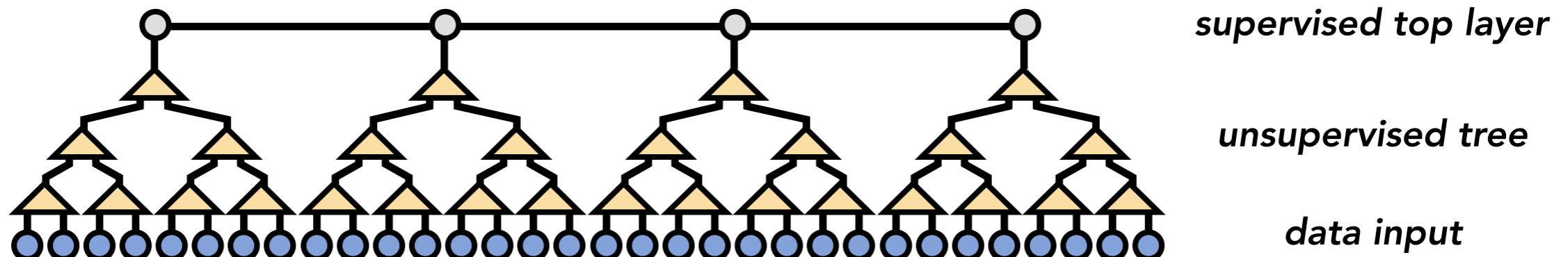
Tree Network as a Deep Neural Net

Inductive Bias Experiment

Learning Relevant Features of Data...

E.M. Stoudenmire

- Unsupervised determination of tree tensor network (compress data)
- Supervised training of top layer
- Excellent performance with "features" determined by tree tensors



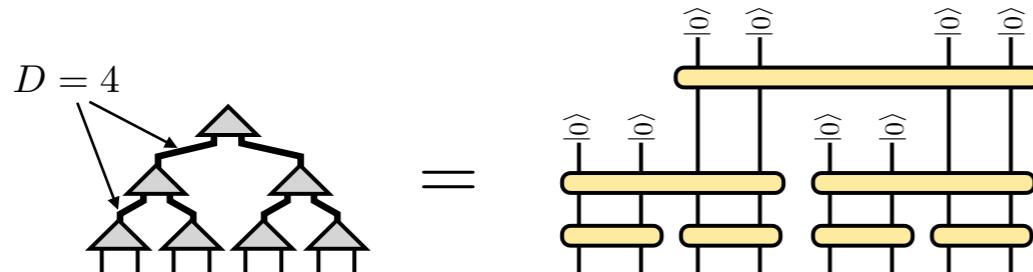
89% accuracy on
Fashion MNIST data set

$$\rho^\mu = (1 - \mu) \sum_j \begin{array}{c} \text{blue circle} \\ \text{blue circle} \\ \text{blue circle} \\ \text{blue circle} \\ \text{blue circle} \end{array} + \mu \begin{array}{c} \text{red circle} \\ \text{red circle} \\ \text{red circle} \\ \text{red circle} \\ \text{red circle} \end{array}$$

mixed training
supervised / unsupervised

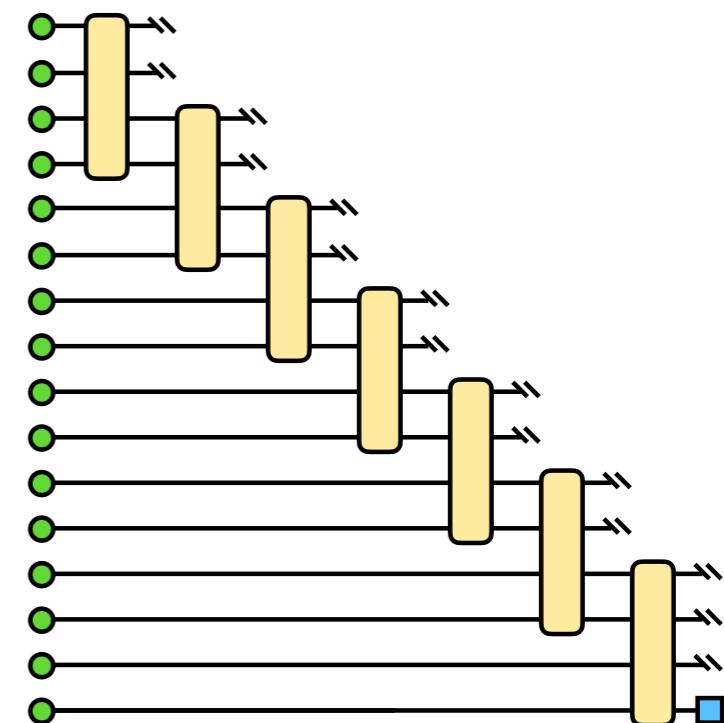
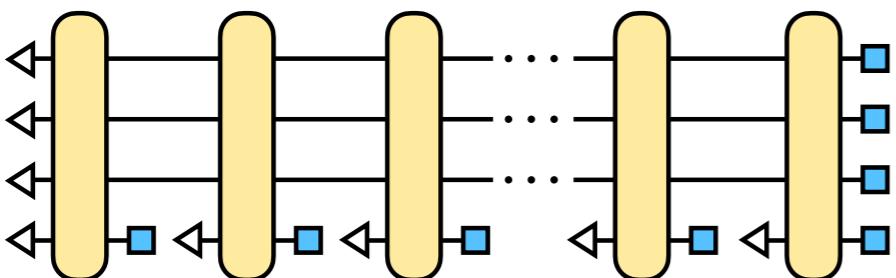
Tensor Network Learning on Quantum Computers

Tensor networks equivalent to quantum circuits



Proposal for learning based on MPS:

Qubit-efficient
generative model:



Huggins, Patil, Whaley, Stoudenmire, arxiv:1803.11537

Grant, Benedetti, et al., arxiv:1804.03680

Conclusions & Future Directions

- Quantum-inspired tensor networks an intriguing alternative to traditional machine learning models
- Better scaling, interesting algorithms, opportunities for theoretical insights
- Continue pushing interpretability, algorithms
- Promising as a framework for machine learning with quantum computing

Learning Relevant Features of Data

For a model $f(\mathbf{x}) = W \cdot \Phi(\mathbf{x})$

Given training data $\{\mathbf{x}_j\}$

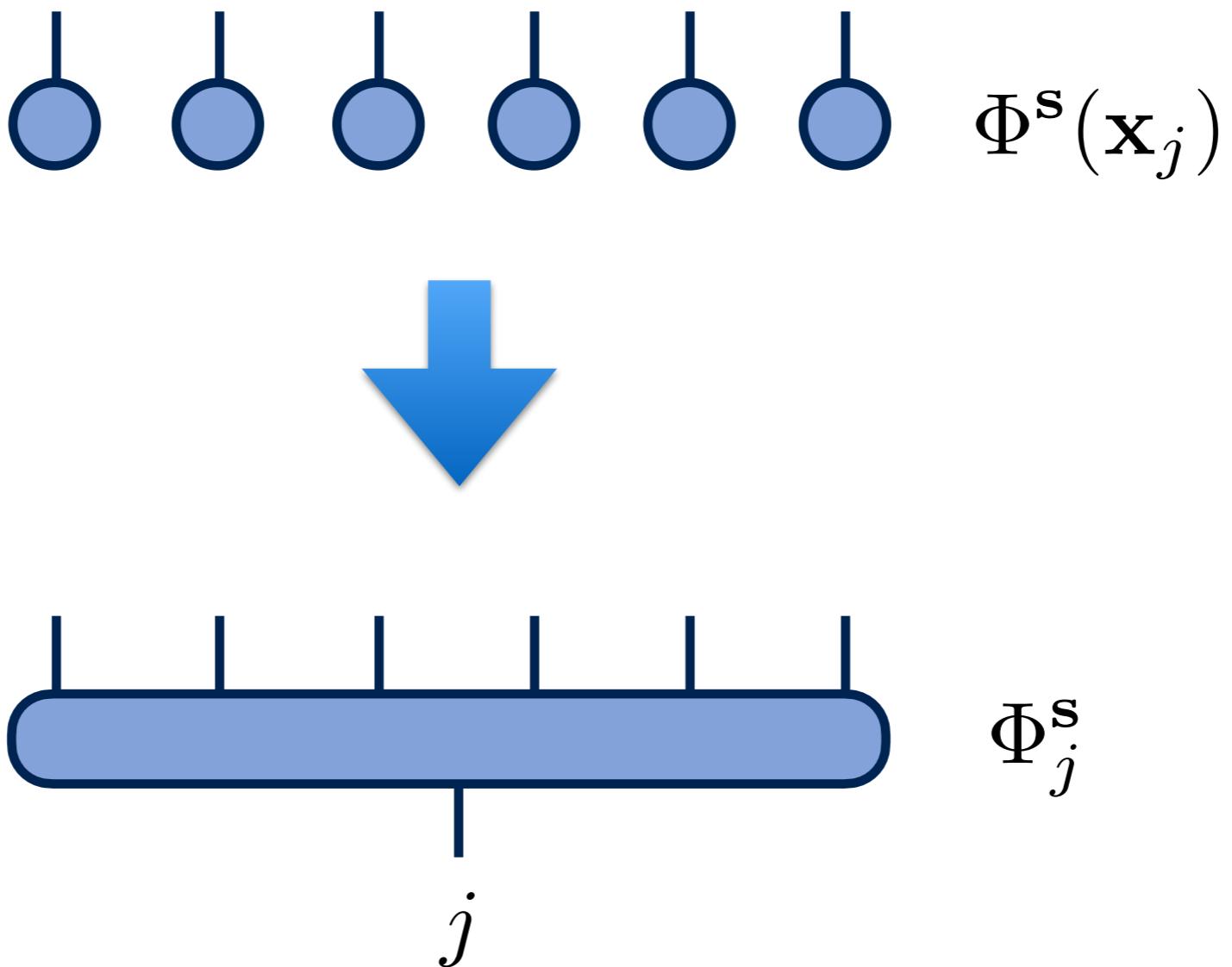
Can show optimal W is of the form

$$W = \sum_j \alpha_j \Phi(\mathbf{x}_j)$$

Holds for wide variety of cost functions / tasks

"representer theorem"

View $\Phi^S(\mathbf{x}_j) = \Phi_j^S$ as a tensor



Representer theorem says

$$W^s = \Phi_j^s \alpha_j$$

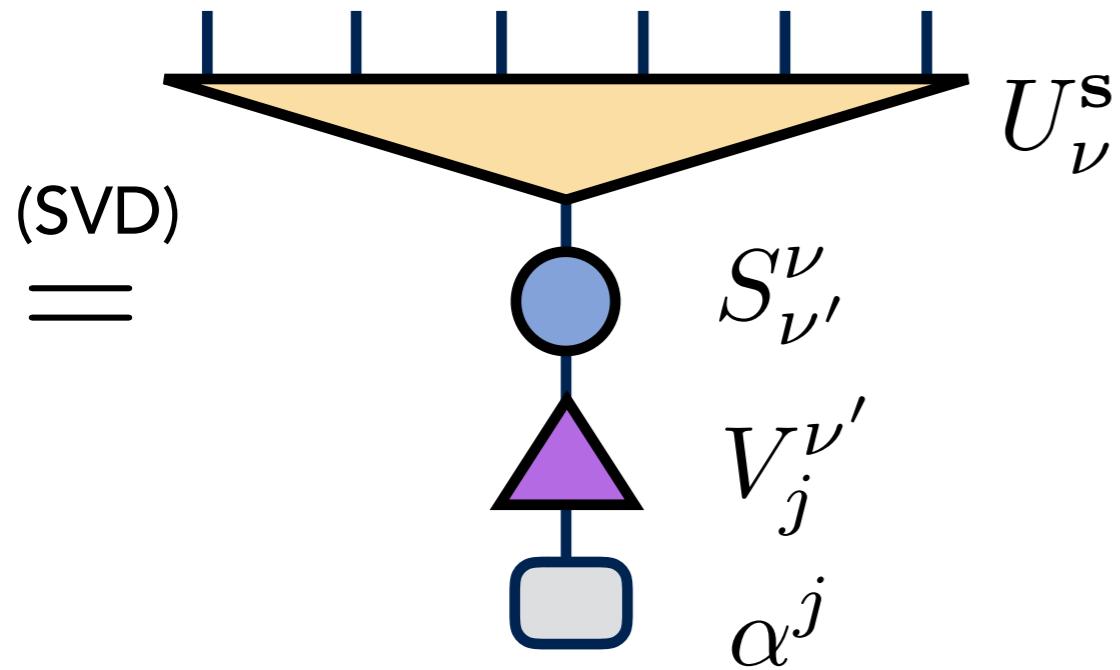
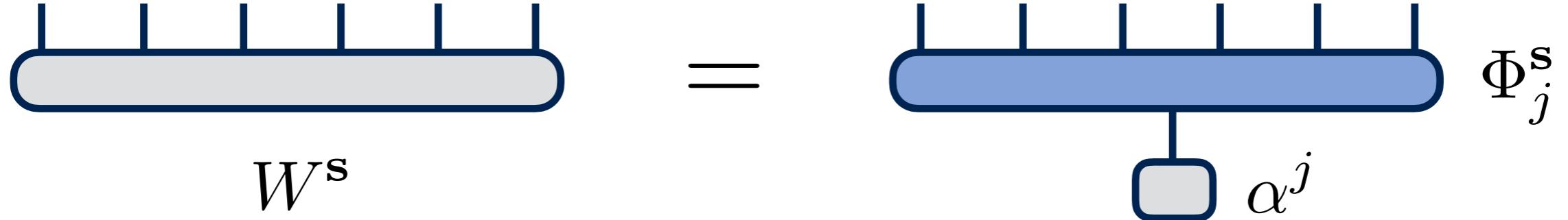
Really just says weights in the span of $\{\Phi_j^s\}$

Can choose any basis for span of $\{\Phi_j^s\}$

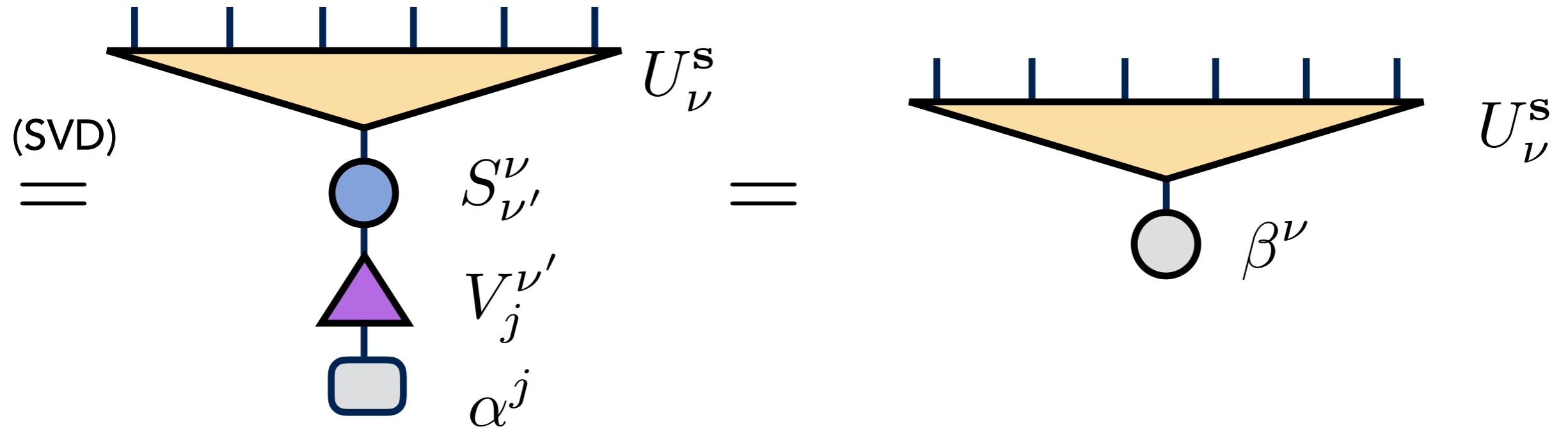
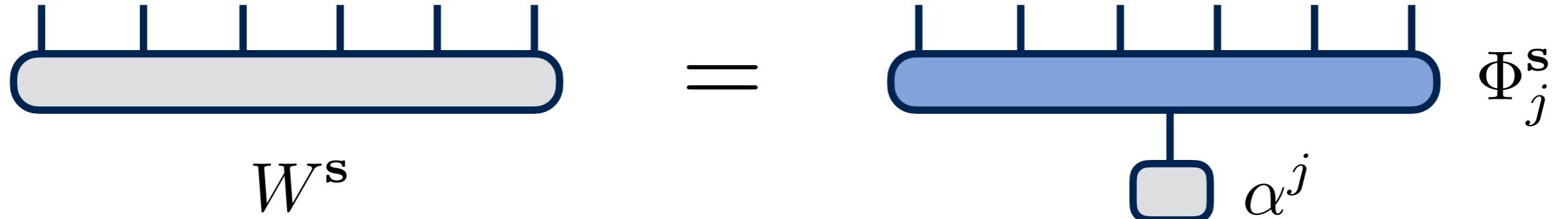
$$W^s = \Phi_j^s \alpha^j$$

The diagram illustrates the decomposition of a weight matrix W^s into a scalar multiple of a basis vector Φ_j^s and a residual vector α^j . On the left, a horizontal bar representing W^s is shown with vertical tick marks at its ends and along its length. This bar is divided into two parts: a light gray segment at the bottom and a dark blue segment at the top. An equals sign follows this bar. To the right of the equals sign is another horizontal bar. This bar has a dark blue segment at the top and a light gray segment at the bottom. A small square node is attached to the bottom segment by a vertical line, representing the scalar α^j . To the right of the bar is the expression Φ_j^s .

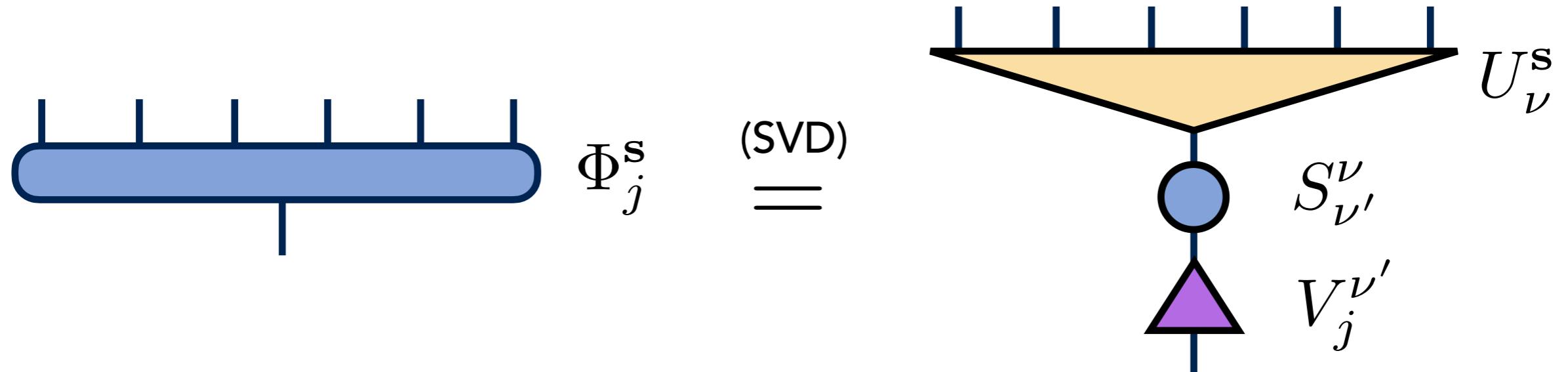
Can choose any basis for span of $\{\Phi_j^S\}$



Can choose any basis for span of $\{\Phi_j^S\}$



Why switch to U_ν^s basis?



Orthonormal basis

Can discard basis vectors corresponding to small s. vals.

Can compute U_ν^s fully or partially using tensor networks

Computing U_ν^s efficiently

Define *feature space covariance matrix*
(similar to density matrix)

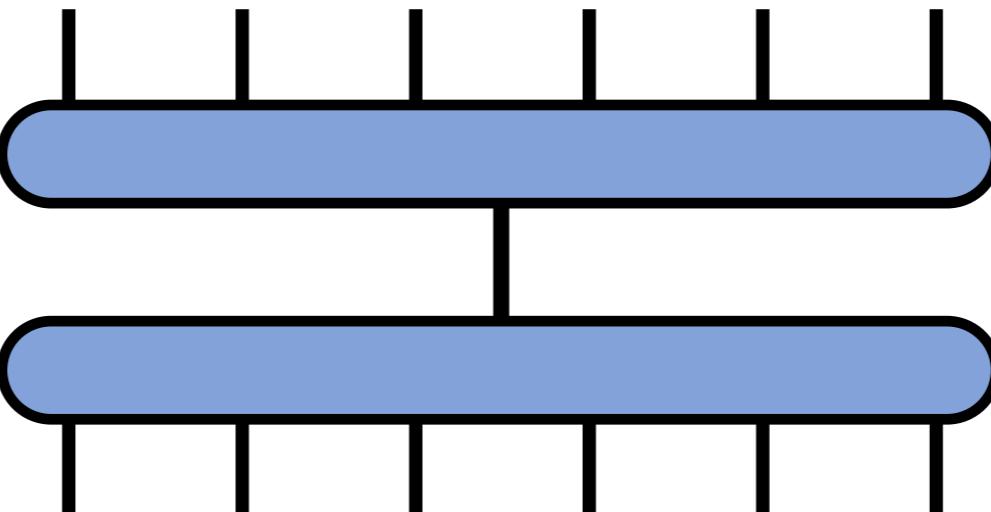
$$\rho = \frac{1}{N_T} \begin{array}{c} | \\ | \\ | \\ | \\ | \\ | \end{array} \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{array} \begin{array}{c} | \\ | \\ | \\ | \\ | \\ | \end{array}$$
$$\Phi_j^s \quad \Phi_s^{\dagger j} =$$

The diagram illustrates the decomposition of the feature space covariance matrix ρ into two components, Φ_j^s and $\Phi_s^{\dagger j}$. These components are shown as blue horizontal bars with vertical indices. The equation $\Phi_j^s \quad \Phi_s^{\dagger j} =$ is followed by three terms: U_ν^s , $(S_\nu)^2$, and $U_s^{\dagger \nu}$. To the right of these terms is a diagram of a tree tensor network. It consists of two yellow trapezoidal tensors at the top and bottom, connected by a central blue circle. Vertical indices connect the top and bottom tensors to the components Φ_j^s and $\Phi_s^{\dagger j}$.

Strategy: compute U_ν^s iteratively as a layered (tree) tensor network

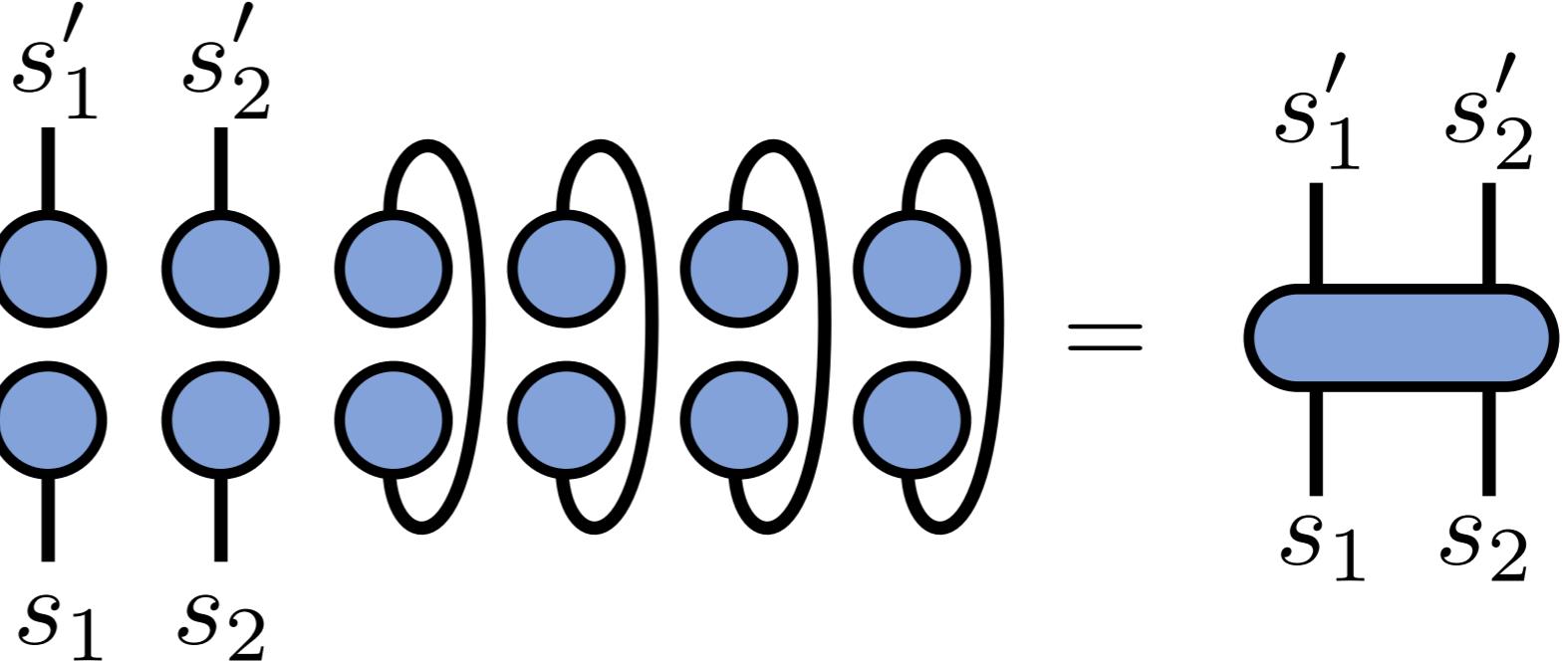
For efficiency, exploit product structure of Φ

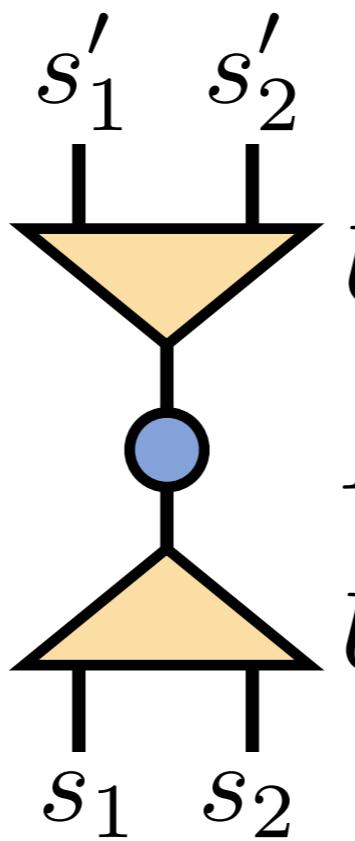
$$\rho = \Phi\Phi^\dagger = \frac{1}{N_T}$$



$$= \frac{1}{N_T} \sum_{j=1}^{N_T} \begin{array}{c} \text{blue circle} \\ \text{black outline} \\ \text{vertical line} \end{array} \quad \Phi(\mathbf{x}_j) \quad \Phi^\dagger(\mathbf{x}_j)$$

Compute tree tensors from reduced matrices

$$\rho_{12} = \sum_{j \in \text{training}} s_1' \quad s_2' \\ s_1 \quad s_2$$


$$\rho_{12} = s_1' \quad s_2' \\ s_1 \quad s_2 = \begin{array}{c} s_1' \quad s_2' \\ \backslash \quad / \\ \text{---} \\ \text{---} \end{array} U_{12} \\ P_{12} \\ U_{12}^\dagger$$


Truncate small
eigenvalues

Compute tree tensors from reduced matrices

$$\rho_{34} = \sum_{j \in \text{training}} \text{Diagram} = \text{Diagram}$$

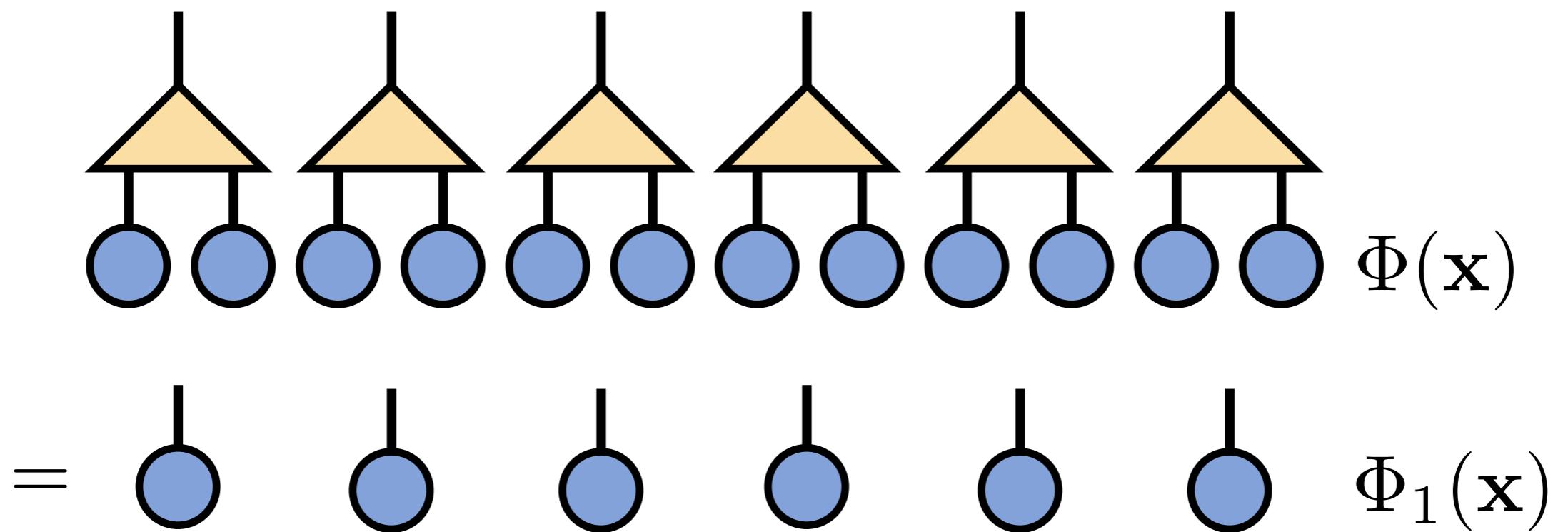
The diagram consists of two parts separated by an equals sign. On the left, a summation symbol (\sum) is followed by the text "j ∈ training". To its right is a sequence of six circular nodes connected by vertical lines. The first three nodes have self-loops; the first two are paired together by a larger loop, and the first three are paired together by an even larger loop. The next three nodes do not have loops. On the right side of the equals sign is another sequence of nodes: the first two are paired by a horizontal oval, and the last two are paired by another horizontal oval.

$$\rho_{34} = \text{Diagram} = \text{Diagram}$$

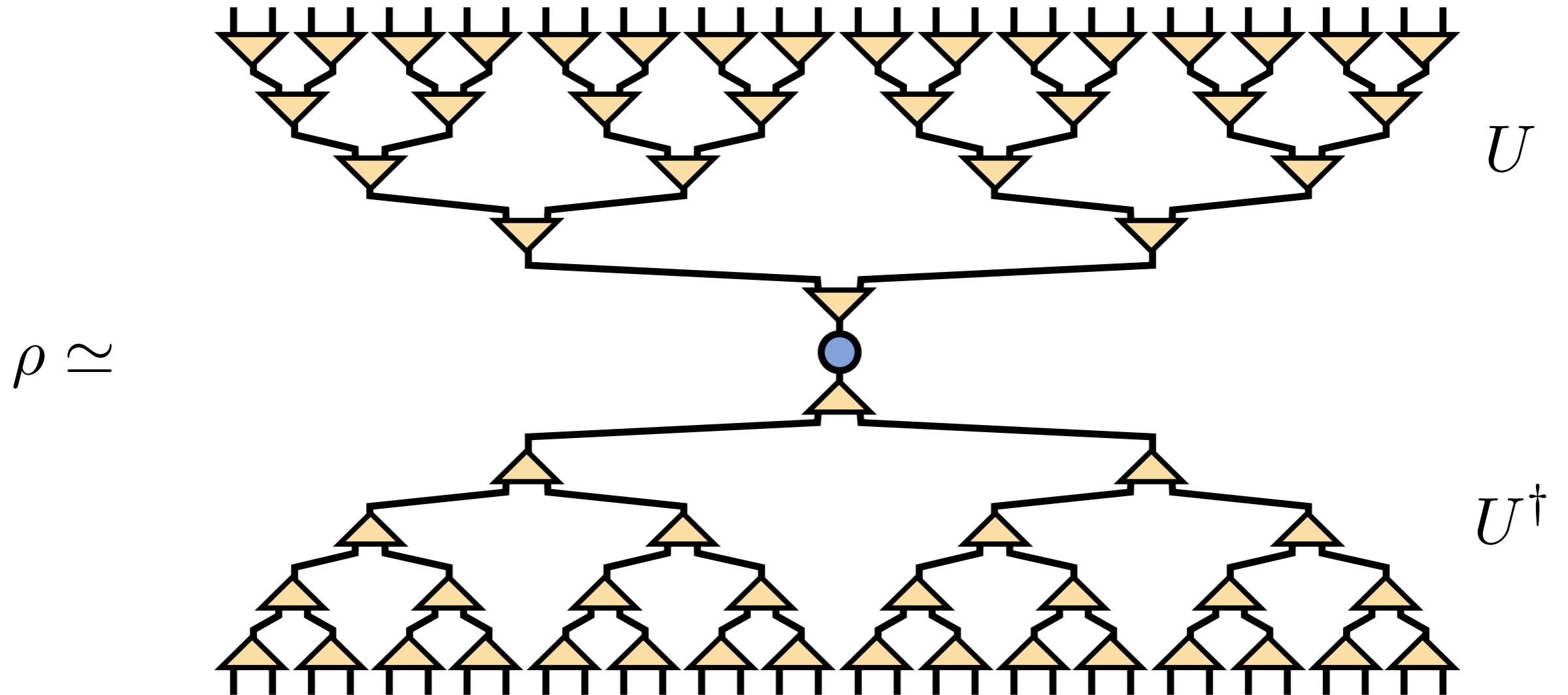
The diagram consists of two parts separated by an equals sign. On the left is a blue rounded rectangle with two vertical lines extending from its top and bottom edges. The top line is labeled s'_3 and the bottom line is labeled s_3 . The right line is labeled s'_4 and the left line is labeled s_4 . On the right is a diagram showing a central blue circle connected to two yellow triangles. The top triangle has two vertical lines extending from its top vertex, labeled s'_3 and s'_4 . The bottom triangle has two vertical lines extending from its bottom vertex, labeled s_3 and s_4 . To the right of the triangles are the labels U_{34} , P_{34} , and U_{34}^\dagger .

Truncate small eigenvalues

Having computed a tree layer, rescale data

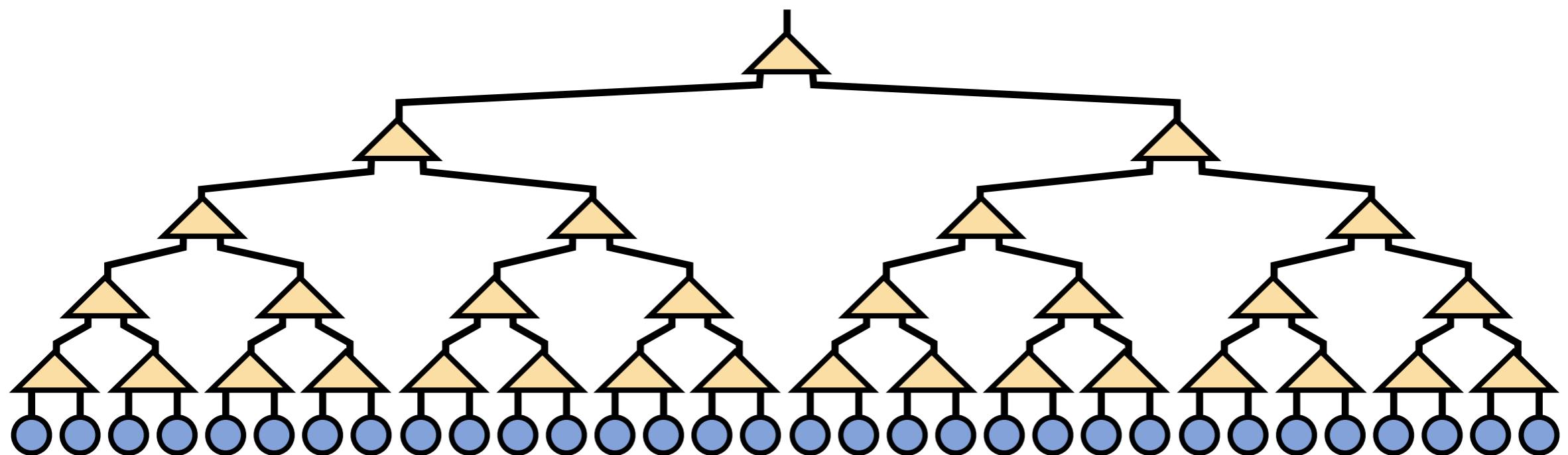


With all layers, have approximately diagonalized ρ



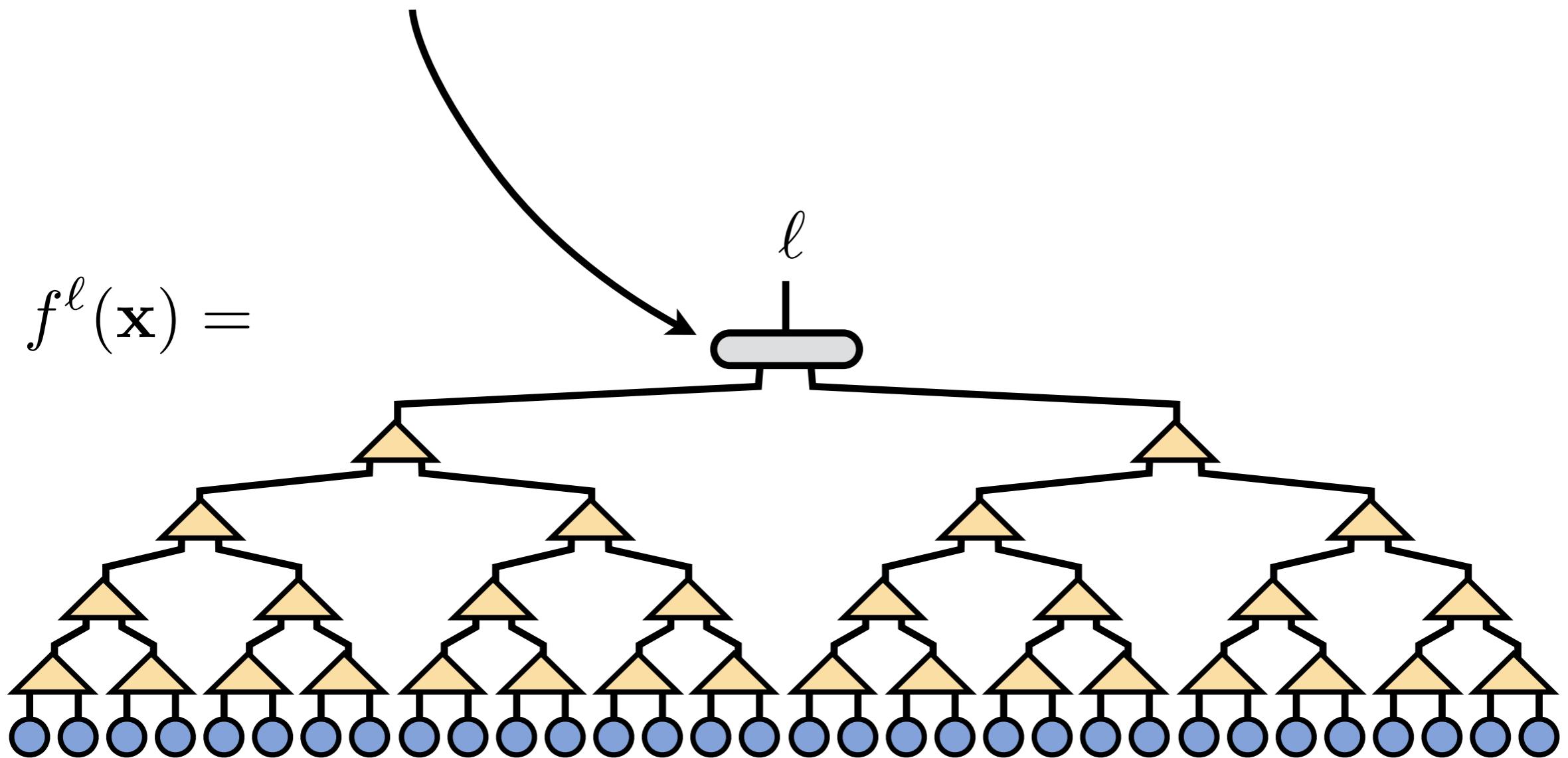
Equivalent to *kernel PCA*,
but linear scaling with size of data set

Can view as *unsupervised learning* of representation of training data

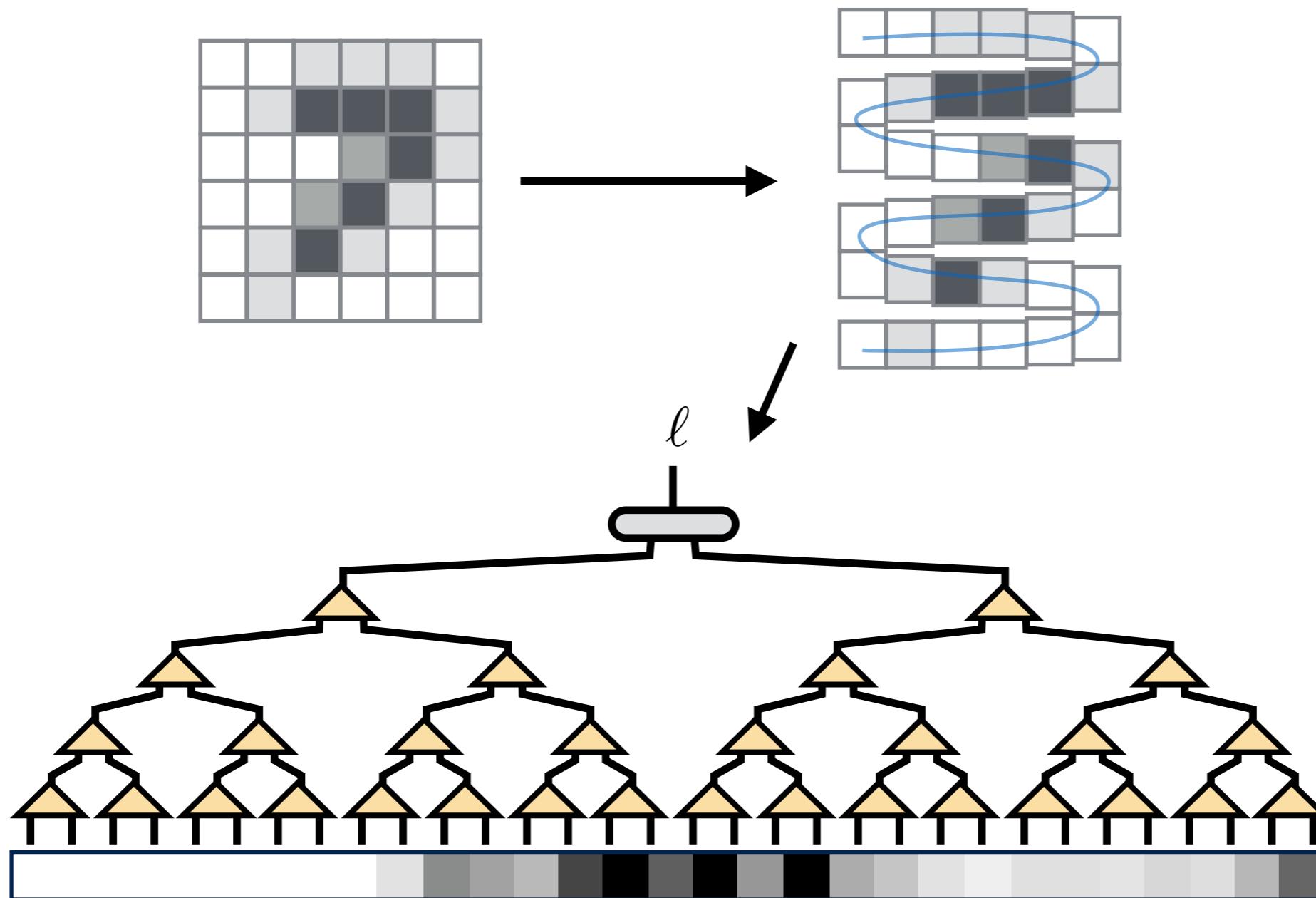


Use as starting point for supervised learning

Only train top tensor for supervised task



Experiment: handwriting classification (MNIST)

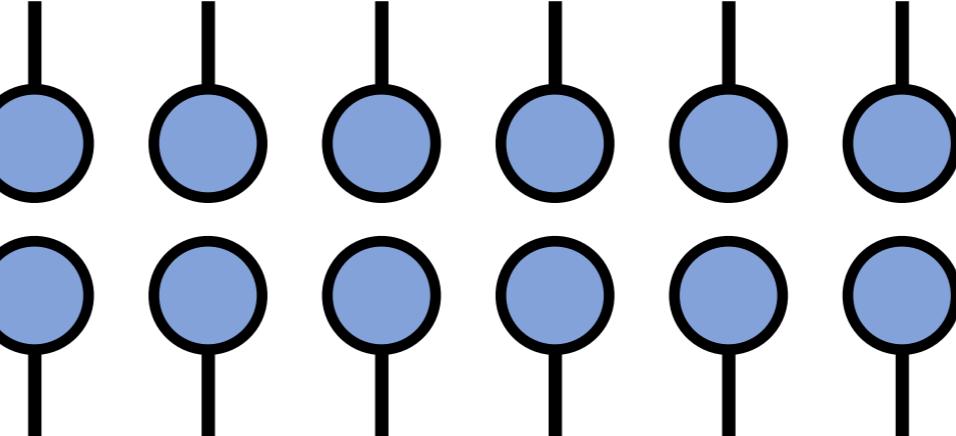


Cutoff 6×10^{-4} gave top indices sizes 328 and 444
Training acc: 99.68% Test acc: 98.08%

Refinements and Extensions

No reason we must base tree around ρ

Could reweight based on importance of samples

$$\tilde{\rho} = \frac{1}{N_T} \sum_{j=1}^{N_T} w_j \Phi(\mathbf{x}_j) \Phi^\dagger(\mathbf{x}_j)$$


Another idea is to mix in a "lower level" model trained on a given task (e.g. supervised learning)

$$\rho^\mu = (1 - \mu) \sum_j \begin{array}{c} \text{blue circle} \\ \text{---} \\ \text{blue circle} \end{array} + \mu \begin{array}{c} \text{red circle} \\ \text{---} \\ \text{red circle} \end{array}$$

If $\mu = 1$, tree provides basis for provided weights

If $0 < \mu < 1$, tree is "enriched" by data set

Experiment: mixed correlation matrix for MNIST

Using $\rho^\mu = (1 - \mu)\rho + \mu \sum_\ell |W^\ell\rangle\langle W^\ell|$

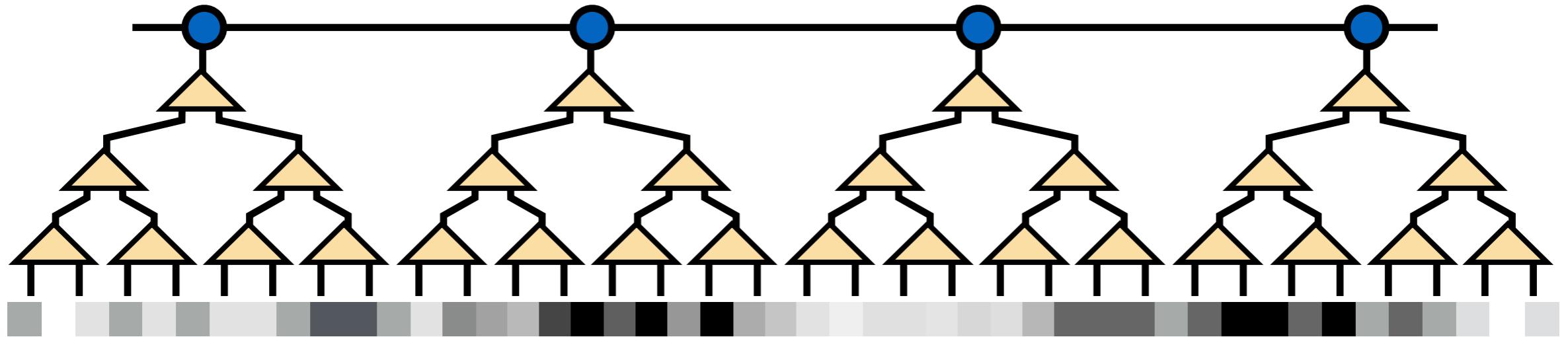
with trial weights trained from a linear classifier
and $\mu = 0.5$

Train acc: 99.798% Test acc: 98.110%

Top indices of size 279 and 393.

Comparable performance to unmixed case with
top index sizes 328 and 444

Also no reason to build entire tree



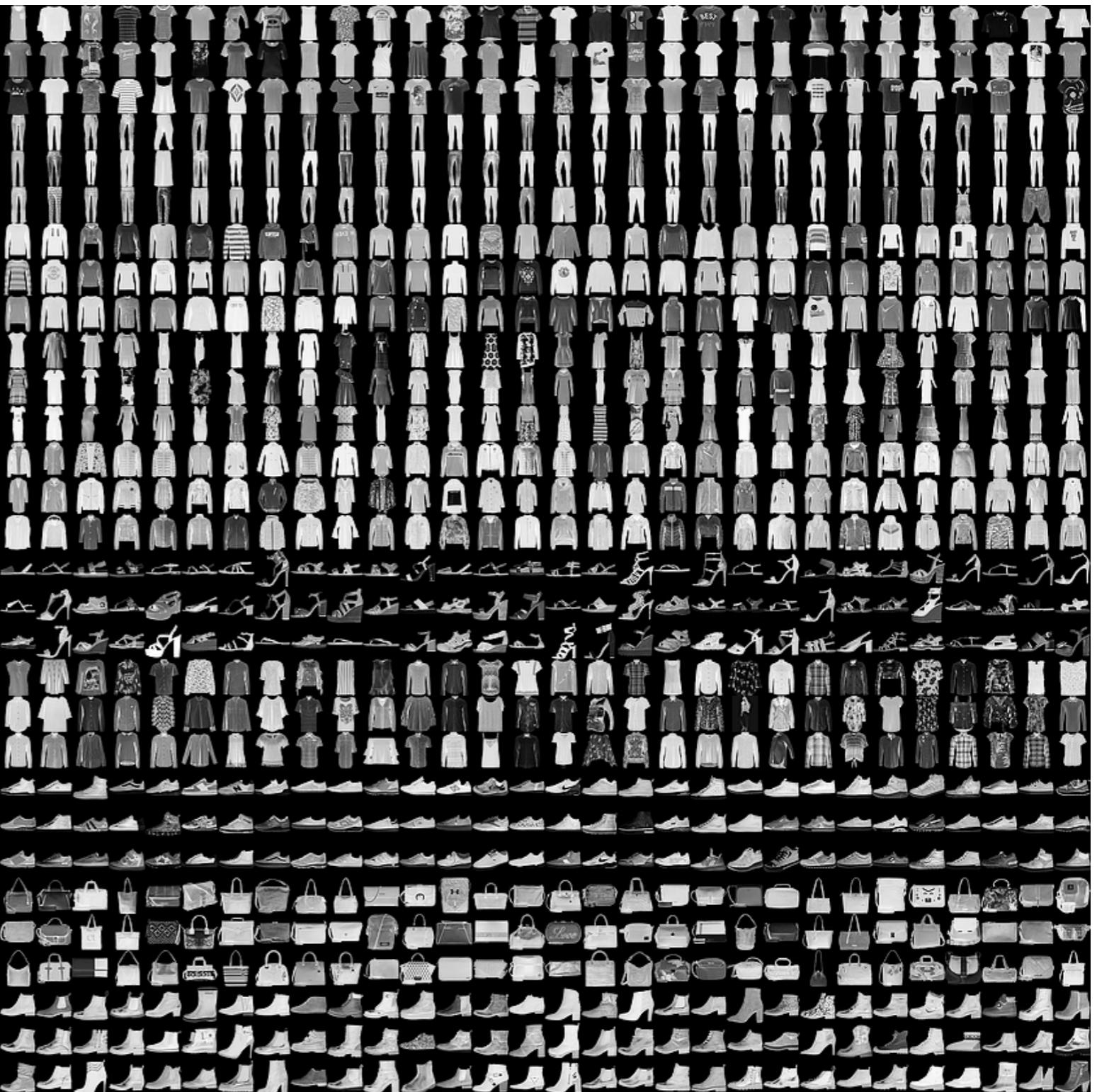
Approximate top tensor by MPS

Experiment: "fashion MNIST" dataset

28x28 grayscale

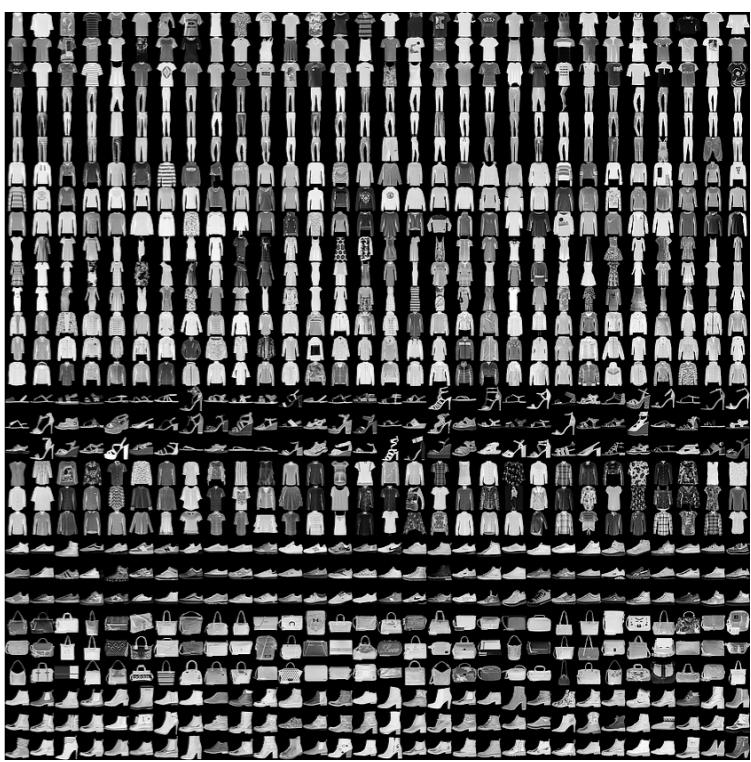
60,000 training images

10,000 testing images



Experiment: "fashion MNIST" dataset

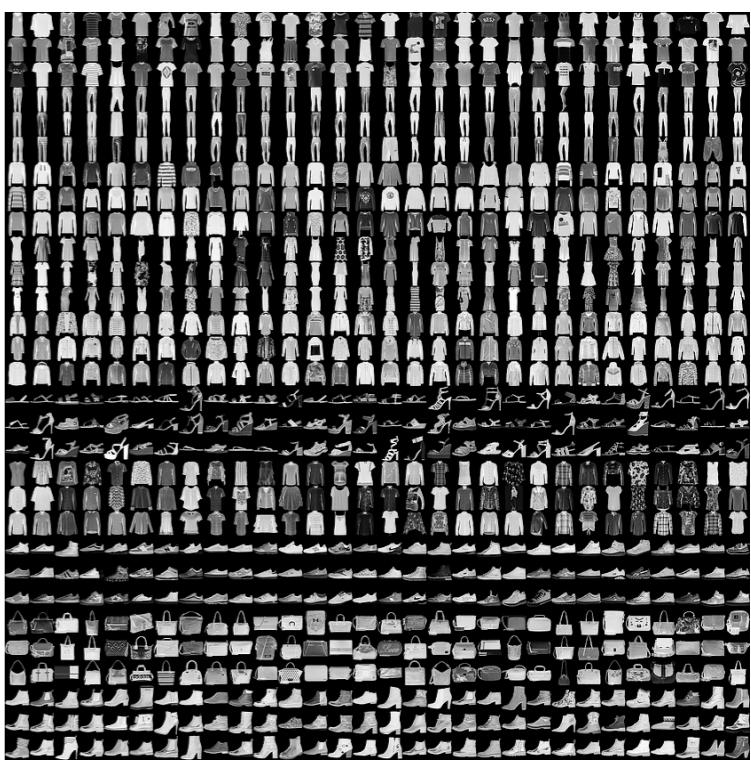
- Used 4 tree tensor layers
- Dimension of top "site" indices ranged from 11 to 30
- Top MPS bond dimension of 300 and 30 sweeps



Experiment: "fashion MNIST" dataset

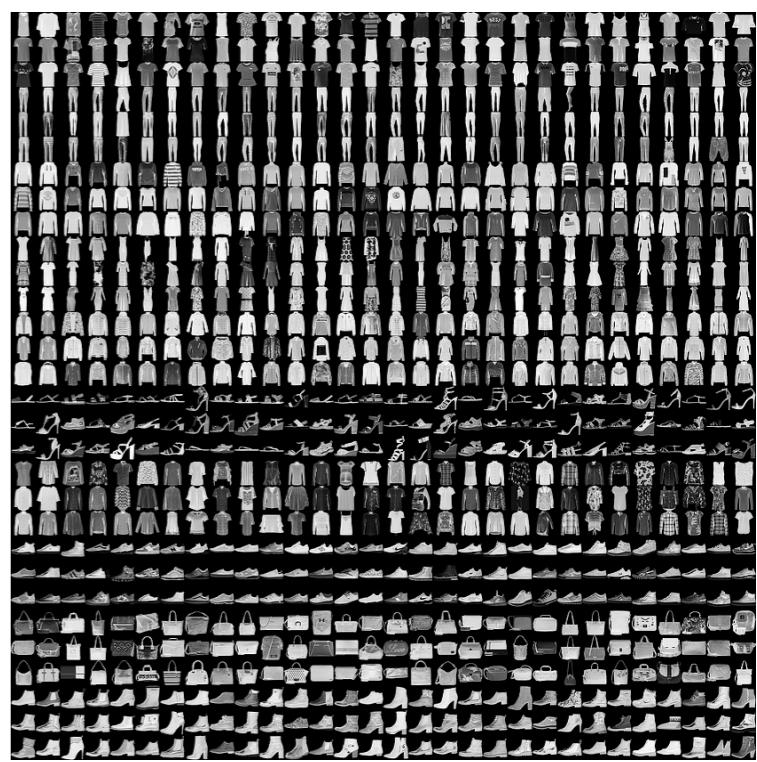
- Used 4 tree tensor layers
- Dimension of top "site" indices ranged from 11 to 30
- Top MPS bond dimension of 300 and 30 sweeps

Train acc: 95.38% Test acc: **88.97%**



Experiment: "fashion MNIST" dataset

- Used 4 tree tensor layers
- Dimension of top "site" indices ranged from 11 to 30
- Top MPS bond dimension of 300 and 30 sweeps



Train acc: 95.38% Test acc: **88.97%**

Comparable to XGBoost (**89.8%**), AlexNet (**89.9%**),
Keras Conv Net (**87.6%**)

Best (w/o preprocessing) is GoogLeNet at **93.7%**

Much Room for Improvement

- Use MERA instead of tree layers
- Optimize all layers, not just top, for specific task
- Iterate mixed approach: feed trained network into new covariance/density matrix
- Stochastic gradient based training

Recap & Future Directions

- Trained layered tensor network on real-world data in unsupervised fashion
- Specializing top layer gives very good results on challenging supervised image recognition tasks
- Linear tensor network approach gives enormous flexibility. Progress toward interpretability.

