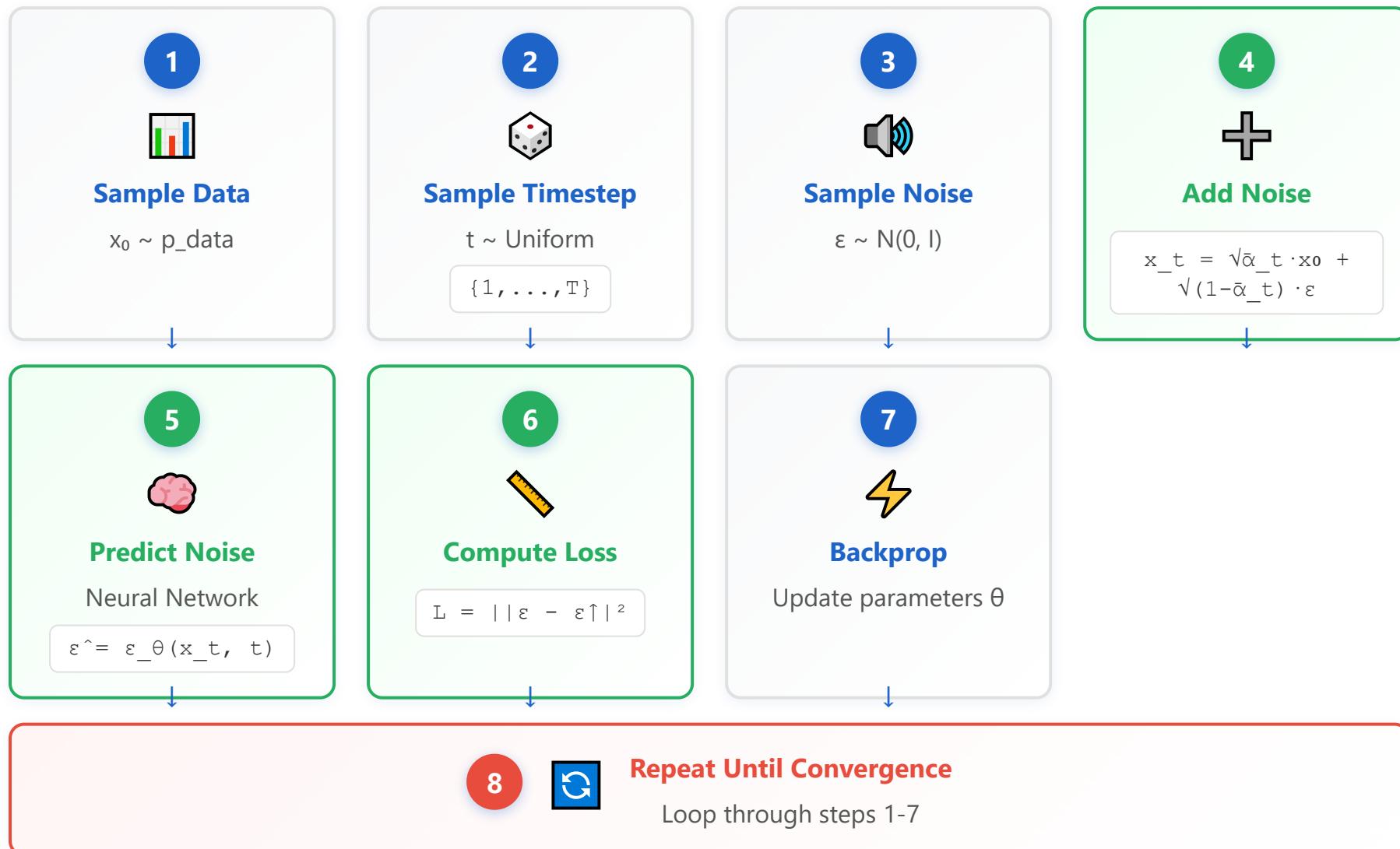


Training Algorithm

Part 3/7: Reverse Process



Core Training Loop: Sample → Add Noise → Predict → Optimize → Repeat

Concrete Calculation Example

2D Case with Actual Numbers

📝 Step-by-Step Calculation

Step 1: Sample Data Point

$x_0 = [3.0, 2.0]$

Original data point from training set

Step 2: Sample Timestep

$t = 500$ (out of $T=1000$)

Random timestep, halfway through diffusion

Step 3: Sample Noise

$\varepsilon \sim N(0, I) = [0.8, -1.2]$

Random Gaussian noise vector

Step 4: Add Noise (Forward Process)

$\bar{\alpha}_{500} = 0.5$ (example)

$$x_t = \sqrt{\bar{\alpha}_t} \cdot x_0 + \sqrt{1-\bar{\alpha}_t} \cdot \varepsilon$$

$$x_{500} = \sqrt{0.5} \cdot [3.0, 2.0] + \sqrt{0.5} \cdot [0.8, -1.2]$$

$$x_{500} = [2.12, 1.41] + [0.57, -0.85]$$

$$\text{x500} = [2.69, 0.56]$$

Step 5: Predict Noise

$$\hat{\varepsilon} = \varepsilon_\theta(x_{500}, 500) = [0.75, -1.15]$$

Neural network prediction

Step 6: Compute Loss

$$L = ||\varepsilon - \varepsilon \uparrow||^2$$

$$L = ||[0.8, -1.2] - [0.75, -1.15]||^2$$

$$L = ||[0.05, -0.05]||^2$$

$$L = 0.0025 + 0.0025 = 0.005$$

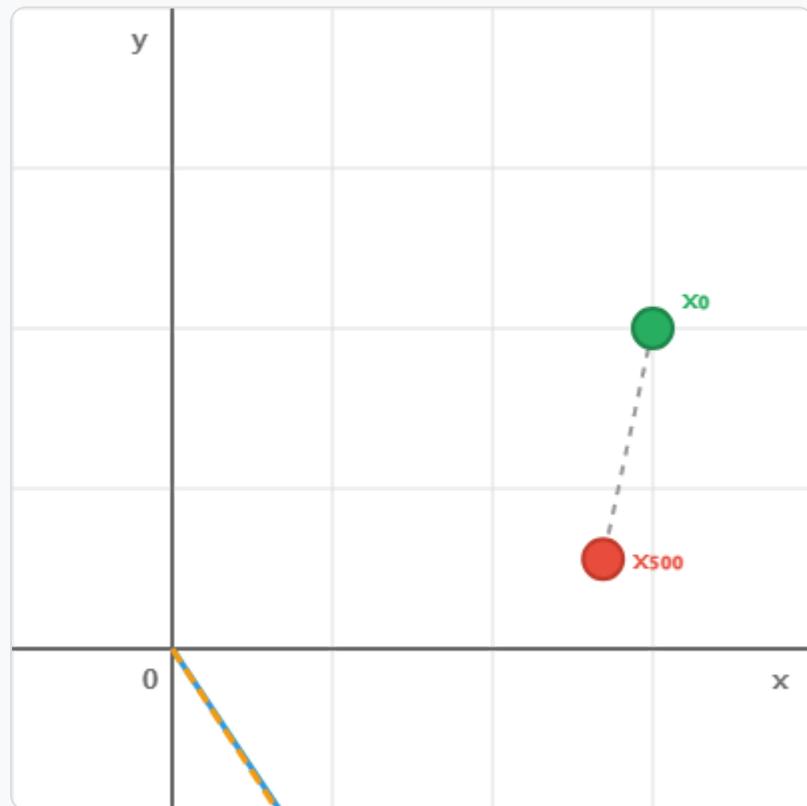
Step 7: Update Parameters

$$\theta \leftarrow \theta - \alpha \cdot \nabla_{\theta} L$$

Gradient descent to minimize loss



Visual Representation



Legend

- $x_0 = [3.0, 2.0]$ - Original data
- $x_{500} = [2.69, 0.56]$ - Noisy data
- $\varepsilon = [0.8, -1.2]$ - True noise
- $\hat{\varepsilon} = [0.75, -1.15]$ - Predicted noise

Goal: Make $\hat{\varepsilon}$ closer to ε by updating θ