

EECS 965 Exam I

Fall 2025 - 75 Points

Name _____

Instructions

- 1) Your solutions must be detailed, unambiguous, and organized. I require that you show **all** your mathematics (i.e., no Matlab unless explicitly allowed).
- 2) Mathematically reduce your solutions to their **simplest** and most fundamental form.
- 2) Please **underline or circle** all numeric answers (e.g., $|A| = 11.2$), or in some way make your final answer **clear**.
- 4) If you feel that a problem is unclear, contradictory, incomplete, or ambiguous, **ask for clarification**.
- 5) This is an exam; it must reflect **your** knowledge and effort—and yours only!

Please **sign** this statement: "As an honorable scholar and human being, I pledge that this exam is a reflection of my knowledge only. I hereby pledge that I committed no act that a reasonable person could construe as academic misconduct."

Signed: _____

Problem 1 - 25 points

Consider a **real-valued** random variable x .

Under hypothesis \mathcal{H}_0 , x is described by the pdf:

$$p(x|\mathcal{H}_0) = \begin{cases} (3/8)(2-x)^2 & \text{for } 0 < x < 2 \\ 0 & \text{for } x < 0, x > 2 \end{cases}$$

While under hypothesis \mathcal{H}_1 , x is described by the pdf:

$$p(x|\mathcal{H}_1) = \begin{cases} (3/8)x^2 & \text{for } 0 < x < 2 \\ 0 & \text{for } x < 0, x > 2 \end{cases}$$

The *a priori* probabilities of these two hypotheses are:

$$P(\mathcal{H}_0) = \frac{3}{5} \quad \text{and} \quad Pr(\mathcal{H}_1) = \frac{2}{5}$$

From a **single** observation x , we must (attempt to) **choose** the correct hypothesis (\mathcal{H}_0 or \mathcal{H}_1).

1. Determine the Likelihood Ratio Test (i.e., determine $L(x)$ and y) using the MAP detection criteria.
2. Simplify the LRT, such that the decision rule can be expressed in terms of this decision statistic:

$$T_d(x) = x$$

For this decision statistic, determine the value of threshold y' for MAP criteria.

3. Say you now instead desire a threshold y' that would result in a probability of detection of:

$$P_D = 0.90$$

Determine:

- a) the value of this threshold y' , and
- b) the resulting probability of false alarm.

Problem 2 - 25 points

Under hypothesis \mathcal{H}_a , an observation $\mathbf{x} = [x_1, x_2, x_3, x_4]^T$ is equal to a known signal \mathbf{s}_a with additive Gaussian noise \mathbf{w} :

$$\mathbf{x} = \mathbf{s}_a + \mathbf{w}$$

Under hypothesis \mathcal{H}_b , an observation \mathbf{x} is equal to a known signal \mathbf{s}_b with additive Gaussian noise \mathbf{w} :

$$\mathbf{x} = \mathbf{s}_b + \mathbf{w}$$

The two known signals are:

$$\mathbf{s}_a = [3, -1, 1, -3]^T \quad \text{and} \quad \mathbf{s}_b = [-3, 3, -5, 5]^T$$

while the Gaussian noise vector $\mathbf{w} = [w_1, w_2, w_3, w_4]^T$ is distributed as:

$$\mathbf{w} \sim \mathcal{N}(\mathbf{0}, \mathbf{C}_w)$$

where:

$$\mathbf{C}_w = E\{\mathbf{w}\mathbf{w}^T\} = \sum_{n=1}^4 \lambda_n \hat{\mathbf{v}}_n \hat{\mathbf{v}}_n^T$$

And also where:

$$\lambda_1 = 6.0 \quad \hat{\mathbf{v}}_1 = [+0.5, -0.5, +0.5, -0.5]^T$$

$$\lambda_2 = 4.0 \quad \hat{\mathbf{v}}_2 = [+0.5, -0.5, -0.5, +0.5]^T$$

$$\lambda_3 = 2.0 \quad \hat{\mathbf{v}}_3 = [+0.5, +0.5, -0.5, -0.5]^T$$

$$\lambda_4 = 1.0 \quad \hat{\mathbf{v}}_4 = [+0.5, +0.5, +0.5, +0.5]^T$$

1. To decorrelate the elements of the noise vector, apply the Karhunen-Loeve transform.

Specifically, determine

- a) the transformed signal vectors \mathbf{s}'_a and \mathbf{s}'_b , and
 - b) the covariance matrix of the transformed noise vector \mathbf{w}' .
2. Now, using a LRT threshold of $\mathbf{y} = e^2$, determine a LRT for this detection problem, expressed in terms of **transformed measurement** $\mathbf{x}' = [x'_1, x'_2, x'_3, x'_4]^T$ (i.e., in terms of variables x'_1, x'_2, x'_3, x'_4).
3. Simplify this LRT into a **decision rule** of the form:

$$T_d(\mathbf{x}') > \mathbf{y}'$$

I.E., provide explicitly—and in their **simplest possible form**—the statistic $T_d(\mathbf{x}')$ and threshold \mathbf{y}' .

Problem 3 - 25 points

Under hypothesis \mathcal{H}_a , a scalar measurement X is equal to random variable w_a :

$$X = w_a$$

Random variable w_a is described by the **Gaussian distribution**:

$$w_a \sim \mathcal{N}(\mu=0, \sigma^2=1)$$

i.e.:

$$p(w_a) = \frac{1}{\sqrt{2\pi}} \exp\left[\frac{-w_a^2}{2}\right] \quad \text{for } -\infty < w_a < \infty$$

Under hypothesis \mathcal{H}_b , the scalar measurement X is equal to random variable w_b :

$$X = w_b$$

Random variable w_b is described by a **uniform distribution**:

$$p(w_b) = \begin{cases} 0.2 & \text{for } -2.5 \leq w_b \leq 2.5 \\ 0 & \text{for } w_b \leq -2.5, w_b \geq 2.5 \end{cases}$$

The two hypotheses are **equally probable, a priori**.

1. Use the **MAP** criterion to determine a decision rule using the detection statistic:

$$T_d(x) = x$$

Describe carefully and completely the decision regions \mathcal{R}_a and \mathcal{R}_b for this decision rule.

2. Determine the probability of error for this decision rule (you may use MatLab or other cumulative probability solver for this calculation).