

AMENDMENT HISTORY

RA83P/84P/85P/93P/94P/95P Series OPERATION MANUAL
Doc No: 93142115

| No. | Document No & Rev No. | Date (D/M/Y) | Amendments |
|-----|-----------------------|-----------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 0 | 93142115-00 | 10/12/03 | First issue |
| 1 | 93142115-01 | 23/01/04 | Chapter 5, para 5.2: Deleted "MAP" from the key switch, which was mistakenly printed. |
| 2 | 93142115-02 | 29/03/04 | Preface: Added "Operation of AIS." Chapter 1, 2, 4: Amended the power cable type name. Chapter 3: Added AIS spec. Chapter 6: Added the descriptions for AIS display, operation, etc. Chapter 4: Reedited 4.6.4 by adding 4.6.4.1 and 4.6.4.2 for Display installation methods. Reedited Para. 4.7.3 to add more details for GAIN/STC settings. Chapter 10: Added the AIS sentence. |
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Amendment policy

When any change is applied in the document, only the document number of the relevant sheet(s) and cover sheet are modified and the rest of the sheets are not changed. The document number is shown in the footer area, right or left bottom of each sheet.

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Preface

Safety Notices

OPERATOR SAFETY

Watch for the rotating antenna:

The radar antenna will start to rotate without notice. For your safety, keep away from the area in the vicinity of the radar antenna.

Be aware of RF Radiation Hazard:

The active radar antenna radiates powerful RF energy. Continuous exposure to RF energy may cause harmful effects to the human body. It also causes Cardiac Pacemaker to malfunction. A person who uses a Cardiac Pacemaker should under no circumstances be exposed to RF radiation.

Most countries accept that RF power density levels below 100 W/m^2 cause no significant RF hazard.

Distance vs. specified RF Power Density Level

| Power / antenna length | 100 W/m^2 | 10 W/m^2 |
|------------------------|---------------------|--------------------|
| 6 KW / 4 ft Aerial | 1.09 m | 3.46 m |
| 6 KW / 6 ft Aerial | 1.3 m | 4.10 m |
| 12 KW / 4 ft Aerial | 1.55 m | 4.89 m |
| 12 KW / 6 ft Aerial | 1.84 m | 5.81 m |
| 25 KW / 4 ft Aerial | 2.45 m | 7.73 m |
| 25 KW / 6 ft Aerial | 2.82 m | 8.91 m |

Dangerous HIGH voltage inside:

Life threatening high voltage is present in the antenna and display units. This high voltage may be present even after the power switch has been turned off. The high voltage circuits are provided with protection covers and warning labels to avoid unintentional contact with these sections. For safety reasons, switch the power off before accessing the internal circuitry and discharge any residual voltages in capacitors by an appropriate method. Only qualified personnel should attempt these maintenance procedures.

MAINTENANCE SAFETY

Beware of residual high voltages:

High voltages may remain in the capacitors and the anode cap on the Cathode Ray Tube several minutes after you have turned the power switch off. Wait at least five minutes or discharge them to ground before starting your inspection.

Make sure the main power supply is OFF:

To prevent an electrical injury due to erroneous power switching, make sure that the main power supply and the system power switch are both OFF. Also attach a safety label showing that service is in progress.

Avoid inhaling dust:

The dust could be a temporary health hazard. When cleaning inside of the equipment, avoid inhaling the dust.

Avoid static electricity:

Take care not to damage the ESDs (Electrostatic Sensitive Devices) due to static electricity from carpet and cloths.

Various symbols used in this manual

The following symbols are used in this manual. You are requested to be fully aware of the meaning of each symbol before carrying out inspection and maintenance on this radar system

Warning mark



To handle the equipment ignoring this sign may lead to fatal damage or injury to human body.

Alarm mark



To handle the equipment ignoring this sign may lead to injury to human body or damage to the equipment.

Caution mark



To handle the equipment ignoring this sign may lead to a malfunction of the equipment.

Warning High Voltage mark



To handle the equipment ignoring this sign may lead to electrical shock to human body.

Prohibition mark



This sign indicates that a specified action is prohibited. The prohibited action will be shown in the vicinity of the mark.

HOW TO USE THIS MANUAL

Scope of this manual

This manual provides necessary information for installation, operation and maintenance of RA83P/84P/85P/93P/94P/95P Series radar systems.

Organization of this manual

This manual is divided into chapters for quick and easy finding of the information you require. The titles and contents of each chapter are as follows:

Chapter 1: GENERAL DESCRIPTIONS

- Outline of the equipment
- Equipment category
- EMC compliance statement
- System configuration
- Software type name used

Chapter 2: EQUIPMENT SUPPLIED

- Standard equipment list
- Spare parts list
- Installation material list
- Optional items

Chapter 3: TECHNICAL SPECIFICATIONS

- Antenna specification
- Processor specification
- ATA Specification
- Serial data and sentence used
- Power supply
- Compass Safe Distance
- Environmental specification
- Mechanical specification

Chapter 4: INSTALLATION

- Installation considerations
- Unpacking each component of the system
- Inspection of each component unit and accessories
- Setting the units
- Cable routing and connections
- Installation procedure
- Setting up after installation
- Setting up option

Chapter 5: BASIC OPERATION

- Introduction
- Control panel layout
- Operating controls
- Getting started
- Basic radar operations

Chapter 6: USING THE MENU

- RADAR MENU
- DISP MENU
- ADJUST MENU
- SYSTEM MENU
- MAINTENANCE MENU
- Operation of EPA
- Operation of ATA
- Operation of AIS

Chapter 7: GRAPHIC DISPLAYS

- Entering Graphic Mode
- Selecting the Graphic Display/DISPLAY ITEM SELECT MENU
- Registering or modifying the NAVLINE data / NAVLINE DATA INPUT MENU

Chapter 8: TROUBLE SHOOTING AND ON BOARD SERVICING

- Information required for service
- Self diagnosis functions provided
- Trouble shooting
- On board servicing

Chapter 9: MAINTENANCE

- Periodic inspection and cleaning

Chapter 10: TECHNICAL REFERENCES

- Serial input data sentence detail
- Tracking data output sentence detail
- Radar output sentence detail
- Interface requirements

Chapter 1 General Descriptions

1.1 Outline of the equipment

The RA83P/84P/85P/93P/94P/95P Series of radar is designed and manufactured to meet the carriage requirement of the latest IMO/SOLAS regulations and its harmonized IEC technical standards, shown below.

- IEC 60945 4th Edition 2002, General
- IEC 60936-1: Ship borne Radar
- IEC 60872-2 and 3: EPA and ATA
- IEC 61162-1: Digital Interface

The equipment is composed of two units, the antenna and the processor. The antenna unit comprises a 4 ft or 6 ft aerial, which is mounted on the transceiver unit of either 6kW (For RA83P/93P) or 12 kW (For RA84P/94P), 25 kW (For RA85P/95P) type. The 4 foot and 6 foot aerials are encapsulated in a water-sealed, durable plastic case. The transceiver unit is contained in a waterproof aluminum case.

1.2 Equipment category

The RA83P/84P/85P/93P/94P/95P series of radar is composed of the component units in the following categories, specified in the IEC 60945 4th edition, Para 4.4.

Antenna Unit (Type RW701A-04/06 + RB717AP/RB718AP/RB719AP):

Exposed to the weather (formerly Class X)

Processor Unit (Type RP100AP):

Protected from the weather (formerly Class B)

Operation Unit (Type RO100A):

Protected from the weather (formerly Class B)

1.3 EMC compliance statement

This series of equipment has been tested and verified by the CETCOM Germany, according to the IEC 60945 4th Edition, in terms of Electro Magnetic Compatibility and atmospheric durability against the maritime environment.

1.4 System configuration

The RA83P/84P/85P/93P/94P/95P radar sets are configured as follows:

Refer to Figure 1 for the system configuration of this series.

RA83P

| Component Unit | Sub-unit | Type name |
|----------------|----------------|-------------------|
| Antenna Unit | | Not assigned |
| | Aerial, 4-foot | RW701A-04 |
| | Aerial, 6-foot | RW701A-06 |
| | Transceiver | RB717AP (6 kW) |
| Processor Unit | | RP100AP |
| Operation Unit | | RO100A |
| Display Unit | | CF 17T01 SIM-A1/2 |

RA84P

| Component Unit | Sub-unit | Type name |
|----------------|----------------|-------------------|
| Antenna Unit | | Not assigned |
| | Aerial, 4-foot | RW701A-04 |
| | Aerial, 6-foot | RW701A-06 |
| | Transceiver | RB718AP (12 kW) |
| Processor Unit | | RP100AP |
| Operation Unit | | RO100A |
| Display Unit | | CF 17T01 SIM-A1/2 |

RA85P

| Component Unit | Sub-unit | Type name |
|----------------|----------------|-------------------|
| Antenna Unit | | Not assigned |
| | Aerial, 4-foot | RW701A-04 |
| | Aerial, 6-foot | RW701A-06 |
| | Transceiver | RB719AP (25 kW) |
| Processor Unit | | RP100AP |
| Operation Unit | | RO100A |
| Display Unit | | CF 17T01 SIM-A1/2 |

RA93P

| Component Unit | Sub-unit | Type name |
|----------------|----------------|-------------------|
| Antenna Unit | | Not assigned |
| | Aerial, 4-foot | RW701A-04 |
| | Aerial, 6-foot | RW701A-06 |
| | Transceiver | RB717AP (6 kW) |
| Processor Unit | | RP100AP |
| Operation Unit | | RO100A |
| Display Unit | | CF 19T01 SIM-A1/2 |

RA94P

| Component Unit | Sub-unit | Type name |
|----------------|----------------|-------------------|
| Antenna Unit | | Not assigned |
| | Aerial, 4-foot | RW701A-04 |
| | Aerial, 6-foot | RW701A-06 |
| | Transceiver | RB718AP (12 kW) |
| Processor Unit | | RP100AP |
| Operation Unit | | RO100A |
| Display Unit | | CF 19T01 SIM-A1/2 |

RA95P

| Component Unit | Sub-unit | Type name |
|----------------|----------------|-------------------|
| Antenna Unit | | Not assigned |
| | Aerial, 4-foot | RW701A-04 |
| | Aerial, 6-foot | RW701A-06 |
| | Transceiver | RB719AP (25 kW) |
| Processor Unit | | RP100AP |
| Operation Unit | | RO100A |
| Display Unit | | CF 19T01 SIM-A1/2 |

1.5 Software type name used

The RA83P/84P/85P/93P/94P/95P series of radar uses the following type of software:

NOTE: The asterisk (*) shows revision code, varied from A to Z.

| Software Type | Application |
|---------------|---------------------------------|
| KM-D56* | Radar logic board |
| KM-D62* | Gyro/Log Interface (KSA-08A) |
| KM-D07* | ATA (Option: MRE-300) |
| KM-D63* | AIS Interface (Option: AIS-100) |

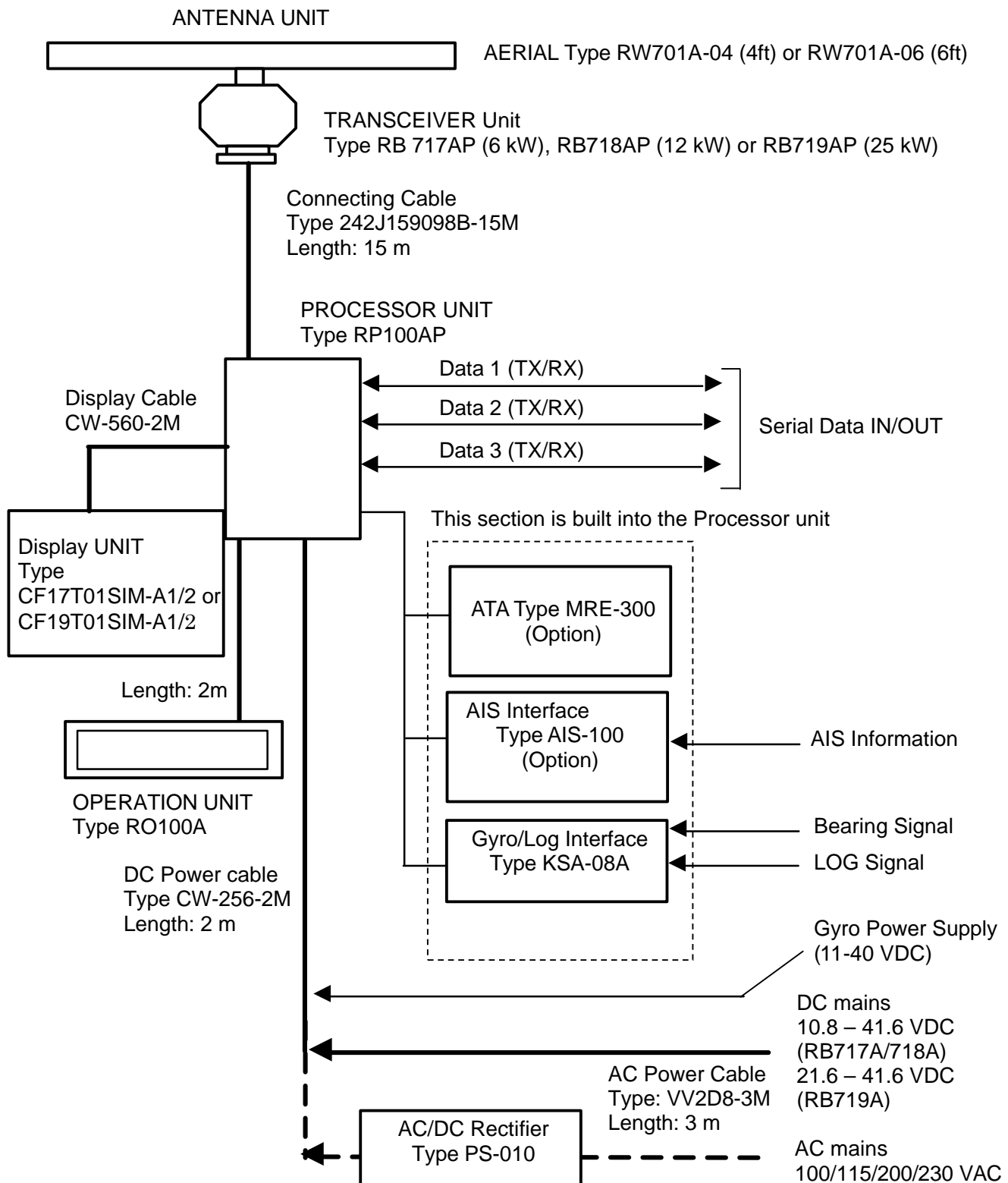


Figure 1.1 System configuration of RA83P/84P/85P/93P/94P/95P series of radar

Chapter 2 Equipment Supplied

2.1 Standard equipment list

RA83P

| No. | Item name | Type name | Remark | Weight/length | Q'ty |
|-----|------------------------|--------------------|-----------------------------------------------------------------------------------|---------------|-------|
| 1 | Aerial | RW701A-04/06 | 4 ft / 6 ft | 6 kg / 8 kg | 1 |
| 2 | Transceiver unit | RB717AP | 6 kW | 17 kg | 1 |
| 3 | Processor unit | RP100AP | | 5.5 kg | 1 |
| 4 | Operation unit | RO100A | | 2 kg | 1 |
| 5 | Display Unit | CF 17T01 SIM-A1/2 | | 9 kg | 1 |
| 6 | Gyro/Log Interface | KSA-08A | Built into the processor unit | Not specified | 1 |
| 7 | Connecting cable | 242J159098B | With connectors attached on both ends | 15 m | 1 |
| 8 | Power cable | CW-256-2M | Cable with 5-pin connector on one end and fly leads on the other end | 2 m | 1 |
| 9 | Display cable | CW-560-2M | Cable with D-SUB connector on both ends | 2 m | 1 |
| 10 | Connecting cable | CW-388-5M | For Gyro/Log I/F. One end with 10-pin connector and flying leads on the other end | 5 m | 1 |
| 11 | Spare parts | SP-100 | See spare parts list | Not specified | 1 set |
| 12 | Installation materials | M12-BOLT.KIT | See installation material list | Not specified | 1 set |
| 13 | Documents | RA80P/90P SER.OM.E | Operation manual | Not specified | 1 |

RA84P

| No. | Item name | Type name | Remark | Weight/length | Q'ty |
|-----|------------------------|-------------------|-----------------------------------------------------------------------------------|---------------|-------|
| 1 | Aerial | RW701A-04/06 | 4 ft / 6 ft | 6 kg / 8 kg | 1 |
| 2 | Transceiver unit | RB718AP | 12 kW | 17 kg | 1 |
| 3 | Processor unit | RP100AP | | 5.5 kg | 1 |
| 4 | Operation unit | RO100A | | 2 kg | 1 |
| 5 | Display Unit | CF 17T01 SIM-A1/2 | | 9 kg | 1 |
| 6 | Gyro/Log Interface | KSA-08A | Built into the processor unit | Not specified | 1 |
| 7 | Connecting cable | 242J159098B | With connectors attached on both ends | 15 m | 1 |
| 8 | Power cable | CW-256-2M | Cable with 5-pin connector on one end and fly leads on the other end | 2 m | 1 |
| 9 | Display cable | CW-560-2M | Cable with D-SUB connector on both ends | 2 m | 1 |
| 10 | Connecting cable | CW-388-5M | For Gyro/Log I/F. One end with 10-pin connector and flying leads on the other end | 5 m | 1 |
| 11 | Spare parts | SP-100 | See spare parts list | Not specified | 1 set |
| 12 | Installation materials | M12-BOLT.KIT | See installation material list | Not specified | 1 set |
| 13 | Documents | RA80P/90PSER.OM.E | Operation manual | Not specified | 1 |

RA85P

| No. | Item name | Type name | Remark | Weight/length | Q'ty |
|-----|------------------------|-------------------|-----------------------------------------------------------------------------------|---------------|-------|
| 1 | Aerial | RW701A-04/06 | 4 ft / 6 ft | 6 kg / 8 kg | 1 |
| 2 | Transceiver unit | RB719AP | 25 kW | 21 kg | 1 |
| 3 | Processor unit | RP100AP | | 5.5 kg | 1 |
| 4 | Operation unit | RO100A | | 2 kg | 1 |
| 5 | Display Unit | CF 17T01 SIM-A1/2 | | 9 kg | 1 |
| 6 | Gyro/Log Interface | KSA-08A | Built into the processor unit | Not specified | 1 |
| 7 | Connecting cable | 242J159098B | With connectors attached on both ends | 15 m | 1 |
| 8 | Power cable | CW-256-2M | Cable with 5-pin connector on one end and fly leads on the other end | 2 m | 1 |
| 9 | Display cable | CW-560-2M | Cable with D-SUB connector on both ends | 2 m | 1 |
| 10 | Connecting cable | CW-388-5M | For Gyro/Log I/F. One end with 10-pin connector and flying leads on the other end | 5 m | 1 |
| 11 | Spare parts | SP-100 | See spare parts list | Not specified | 1 set |
| 12 | Installation materials | M12-BOLT.KIT | See installation material list | Not specified | 1 set |
| 13 | Documents | RA80P/90PSER.OM.E | Operation manual | Not specified | 1 |

RA93P

| No. | Item name | Type name | Remark | Weight/length | Q'ty |
|-----|------------------------|-------------------|-----------------------------------------------------------------------------------|---------------|-------|
| 1 | Aerial | RW701A-04/06 | 4 ft / 6 ft | 6 kg / 8 kg | 1 |
| 2 | Transceiver unit | RB717AP | 6 kW | 17 kg | 1 |
| 3 | Processor unit | RP100AP | | 5.5 kg | 1 |
| 4 | Operation unit | RO100A | | 2 kg | 1 |
| 5 | Display Unit | CF 19T01 SIM-A1/2 | | 9 kg | 1 |
| 6 | Gyro/Log Interface | KSA-08A | Built into the processor unit | Not specified | 1 |
| 7 | Connecting cable | 242J159098B | With connectors attached on both ends | 15 m | 1 |
| 8 | Power cable | CW-256-2M | Cable with 5-pin connector on one end and fly leads on the other end | 2 m | 1 |
| 9 | Display cable | CW-560-2M | Cable with D-SUB connector on both ends | 2 m | 1 |
| 10 | Connecting cable | CW-388-5M | For Gyro/Log I/F. One end with 10-pin connector and flying leads on the other end | 5 m | 1 |
| 11 | Spare parts | SP-100 | See spare parts list | Not specified | 1 set |
| 12 | Installation materials | M12-BOLT.KIT | See installation material list | Not specified | 1 set |
| 13 | Documents | RA80P/90PSER.OM.E | Operation manual | Not specified | 1 |

RA94P

| No. | Item name | Type name | Remark | Weight/length | Q'ty |
|-----|------------------------|-------------------|-----------------------------------------------------------------------------------|---------------|-------|
| 1 | Aerial | RW701A-04/06 | 4 ft / 6 ft | 6 kg / 8 kg | 1 |
| 2 | Transceiver unit | RB718AP | 12 kW | 17 kg | 1 |
| 3 | Processor unit | RP100AP | | 5.5 kg | 1 |
| 4 | Operation unit | RO100A | | 2 kg | 1 |
| 5 | Display Unit | CF 19T01 SIM-A1/2 | | 9 kg | 1 |
| 6 | Gyro/Log Interface | KSA-08A | Built into the processor unit | Not specified | 1 |
| 7 | Connecting cable | 242J159098B | With connectors attached on both ends | 15 m | 1 |
| 8 | Power cable | CW-256-2M | Cable with 5-pin connector on one end and fly leads on the other end | 2 m | 1 |
| 9 | Display cable | CW-560-2M | Cable with D-SUB connector on both ends | 2 m | 1 |
| 10 | Connecting cable | CW-388-5M | For Gyro/Log I/F. One end with 10-pin connector and flying leads on the other end | 5 m | 1 |
| 11 | Spare parts | SP-100 | See spare parts list | Not specified | 1 set |
| 12 | Installation materials | M12-BOLT.KIT | See installation material list | Not specified | 1 set |
| 13 | Documents | RA80P/90PSER.OM.E | Operation manual | Not specified | 1 |

RA95P

| No. | Item name | Type name | Remark | Weight/length | Q'ty |
|-----|------------------------|-------------------|-----------------------------------------------------------------------------------|---------------|-------|
| 1 | Aerial | RW701A-04/06 | 4 ft / 6 ft | 6 kg / 8 kg | 1 |
| 2 | Transceiver unit | RB719AP | 25 kW | 21 kg | 1 |
| 3 | Processor unit | RP100AP | | 5.5 kg | 1 |
| 4 | Operation unit | RO100A | | 2 kg | 1 |
| 5 | Display Unit | CF 19T01 SIM-A1/2 | | 9 kg | 1 |
| 6 | Gyro/Log Interface | KSA-08A | Built into the processor unit | Not specified | 1 |
| 7 | Connecting cable | 242J159098B | With connectors attached on both ends | 15 m | 1 |
| 8 | Power cable | CW-256-2M | Cable with 5-pin connector on one end and fly leads on the other end | 2 m | 1 |
| 9 | Display cable | CW-560-2M | Cable with D-SUB connector on both ends | 2 m | 1 |
| 10 | Connecting cable | CW-388-5M | For Gyro/Log I/F. One end with 10-pin connector and flying leads on the other end | 5 m | 1 |
| 11 | Spare parts | SP-100 | See spare parts list | Not specified | 1 set |
| 12 | Installation materials | M12-BOLT.KIT | See installation material list | Not specified | 1 set |
| 13 | Documents | RA80P/90PSER.OM.E | Operation manual | Not specified | 1 |

2.2 Spare parts list**RA83P/84P/85P/93P/94P/95P (Common use)**

| No | Description | Rating | Remark | Shape (Dimensions) | Q'ty | Use |
|----|-------------|------------|---------------|---------------------|-------|---------------------------|
| 1 | Fuse | 15A | Normal blow | Tubular (φ6.3 x 32) | 1 | Main power supply |
| 2 | Fuse | 5A | Normal blow | Tubular (φ 5 x 25) | 1 | Motor power supply |
| 3 | Fuse | 0.3A | Normal blow | Tubular (φ 5 x 25) | 1 | High voltage power supply |
| 4 | Motor brush | 24Z125209B | Not specified | Not specified | 1 set | Antenna motor |

2.3 Installation material list**RA83P/84P/85P/93P/94P/95P (Common use)**

| No | Description | Rating | Q'ty | Use |
|----|----------------|----------------|------|----------------|
| 1 | Hexagonal bolt | B12X55U | 4 | Antenna unit |
| 2 | Nut | N12U | 8 | Antenna unit |
| 3 | Plain washer | 2W12U | 8 | Antenna unit |
| 4 | Spring washer | SW12U | 4 | Antenna unit |
| 5 | Ferrite core | E04RA400270150 | 1 | Processor unit |

2.4 Optional items

RA83P/84P/85P/93P/94P/95P (Common use)

| No. | Description | Rating | Remark | Weight/length/Q'ty |
|-----|----------------------------------|------------------------------|---------------------------------------------------------------------------------|--------------------|
| 1 | ATA | MRE-300 | Built into the processor unit | Not specified |
| 2 | AIS Interface | AIS-100 | Built into the processor unit | Not specified |
| 3 | Connecting cable | CW-387-5M | For AIS I/F. One end with 8-pin connector and flying leads on the other end | 5 m |
| | | CW-376-5M | For Navigator. One end with a 6-pin connector and flying leads on the other end | 5 m |
| | | CW-561-10M | For Remote Display. With 12-pin connector on both ends | 10 m |
| 4 | Display Cable | CW-560-2M | With D-sub connector on both ends | 2 m |
| 5 | Rectifier | PS-010 | With two 5 A fuses | 3.5 kg |
| 6 | AC power cable | VV-2D8-3M | Flying leads on both ends | 3 m |
| 7 | Connecting cable in extra length | 242J159098C-20M | Connectors attached on both ends | 20 m |
| | | 242J159098D-30M | | 30 m |
| | | 242J159098E-XM (See NOTE) | | 100 m max |

NOTE: The length of the cable is specified by the customer within 100 meters.

Chapter 3 Technical Specifications

3.1 Antenna specification

| | | | |
|---------------------------|--------------------------------|-----------|------------------------------|
| Model name | RA83P/93P | RA84P/94P | RA85P/95P |
| Aerial length | 4 feet / 6 feet | | |
| Peak power output | 6 kW | 12 kW | 25 kW |
| Frequency | 9410 +/- 30 MHz | | |
| Beam width Horizontal | 1.8° / 1.2° | | |
| Vertical | 22° | | |
| Side lobes Within +/- 10° | Better than -23 dB | | |
| Outside +/- 10° | Better than -30 dB | | |
| Rotation | 24 r.p.m. | | |
| Transmission pulse width | 6 kW | 12 kW | 25 kW |
| S (Short pulse) | 0.08 μs / 4000 Hz | | 0.08 μs/2000 Hz |
| M1 (Medium 1 pulse) | 0.25 μs / 2000 Hz | | 0.3 μs / 1300 Hz |
| M2 (Medium 2 pulse) | 0.5 μs / 1000 Hz | | 0.6 μs / 800 Hz |
| L (Long pulse) | 1.0 μs / 500 Hz | | 1.2 μs / 500 Hz, 400Hz(96NM) |
| IF center frequency | 60 MHz | | |
| IF bandwidth | 15 MHz (S, M1) / 3 MHz (M2, L) | | |
| Noise figure | Better than 6 dB | | |
| Operation in wind | 100 knots as relative | | |
| Water proofing grade | IPX6 (IEC 60529) | | |

3.2 Processor specification

| | |
|------------------------|-----------------------------------------------------------------------------|
| Display | 17.4 inch high resolution color LCD / 19 inch high resolution color LCD |
| Effective diameter | 259 mm (RA83P/84P/85P) / 282 mm (RA93P/94P/95P) |
| Resolution | 1280 x 1024 pixels |
| Video level | 8 levels |
| Presentation mode | Head-up, north-up, course-up and true motion |
| Range scale (NM) | 1/8 1/4 1/2 3/4 1.5 3 6 12 24 48 64 (6 kW) 72 (12 kW) 96 (25 kW) |
| Rings interval (NM) | 1/16 1/8 1/4 1/2 1 2 4 8 16 (6 kW) 12 (12 kW) 16 (25 kW) |
| Off-centering | Sweep origin can be moved to any point within 2/3 of the screen radius. |
| Trail display interval | Every scan, 15 sec, 30 sec, 1 min, 3 min, 6 min, 12 min and OFF |
| Alarm | Entry alarm [alarm range (Minimum 0.5 NM), depth and bearing can be varied] |
| EPA | Up to 10 targets can be plotted, 5 points for one target each |

(Processor specification)

| | |
|--------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| ATA (Option) | Display of acquire/track data of up to 10 targets and Guard Zone are available. Display of guard zone is also available (any alarm range, width and bearing can be set). |
| AIS data display | Symbols and data, up to 20 targets, |
| Data available for EPA and ATA | Speed, course, CPA, TCPA, distance, bearing and age (time elapsed since the first plot, applicable to EPA only). |
| Minimum detectable range | 20 meters at 1/8 nm range |
| Range resolution | 20 meters at 1/8 nm range |
| Range data accuracy | 70 meters or 1% of the range scale selected, whichever is the greater. |
| Bearing data accuracy | +/-1° maximum |
| Navigation data display | Data of own ship's position (latitude/longitude) |

3.3 ATA Specification (Option)

| | |
|---------------------------|---------------------------------------------------------------------------------------------------------------------|
| Acquisition | Manual |
| Tracking | Automatic |
| Number of targets tracked | Up to 10 targets |
| Numerical data output | Distance, bearing, speed, course, CPA and TCPA |
| Alarm | Collision alarm and lost alarm |
| On screen display | Symbols (acquired target, tracked target, target with data display and lost target), target number and vectors. |
| Display mode | Relative and True |
| Tracking distance range | Up to 40.0 nm |
| ATA data output | To be taken via the DATA 1 connector on the processor rear panel. Signal level: RS422 Data format: IEC 1162-1 |

3.4 AIS specification (Option)

| | |
|-----------------------------|----------------------------------------------------------------------------------------------------------------------------------------------|
| Number of targets displayed | Up to 20 activated targets and 20 sleeping targets |
| Numerical data indication | MMSI, CPA, TCPA, CSE/COG, STW/SOG |
| On screen display | Symbols, target number and vectors. |
| Indication limit range | 1.0 to 6.5 nm |
| AIS data input | To be taken via the AIS connector on the processor rear panel. Signal level: RS422 Data format: IEC61162-2 Formatter: ALR, VDO, VDM |

3.5 Serial data and sentence used

Serial data: IEC 61162-1 or NMEA 0183 ver 2.0

Sentence: BWC, GGA, GLC, GLL, HDT, RMB, RTE, VBW, VDR, VHW, VTG, WPL

3.6 Power Supply

Mains Input Voltage: 24 VDC / 32 VDC

Input Voltage Tolerance: 10.8 VDC – 41.6 VDC (for RA83P/84P/93P/94P)
21.6 VDC – 41.6 VDC (for RA85P/95P)

Input Power: 170 W nominal at 24 VDC

Transient Protection:

Specified to the requirements of IEC 60945 4th Edition.

Reversed polarity protection: Protected by the Main Fuse.

AC Operation

Rectifier Unit Type PS-010 is required.

Input voltage range: 115/230 VAC

Input voltage tolerance: +/- 10%

Input voltage frequency range: 47 to 63 Hz

Input Power: 220 W

3.7 Compass Safe Distance

| Component Unit | Type Name | Standard | Steering |
|----------------|-------------------|----------|----------|
| Antenna | RB717AP/RW701A-04 | 1.4 m | 0.95 m |
| | RB717AP/RW701A-06 | 1.4 m | 0.95 m |
| | RB718AP/RW701A-04 | 1.4 m | 0.95 m |
| | RB718AP/RW701A-06 | 1.4 m | 0.95 m |
| | RB719AP/RW701A-04 | 1.2 m | 0.65 m |
| | RB719AP/RW701A-06 | 1.2 m | 0.65 m |
| Processor | RP100AP | 0.6 m | 0.4 m |
| Operation | RO100A | 0.6 m | 0.4 m |

3.8 Environmental specification

To the requirements of IEC 60945 4th Edition. The measure environmental specifications are as follows:

(1) Temperature and humidity

| | Operating temperature | Storage temperature | Humidity |
|---------|-----------------------|---------------------|-------------------|
| Antenna | -25°C - +55°C | +70°C | 93%+/-3% at +40°C |
| Display | -15°C - +55°C | +55°C | 93%+/-3% at +40°C |

(2) Vibration

2-5Hz up to 13.2 Hz: Amplitude +/-1mm +/-10% (Maximum acceleration 7m/s² at 13.2Hz)

13.2 Hz up to 100Hz: Maximum acceleration 7 m/s² constant

3.9 Mechanical specification

Dimensions: W (Width) x Depth x Height, Unit in mm

Weight: Unit in kg

Antenna:

RB717AP/718AP: 325 x 390 x 450, 23 kg (for 4ft system), 25 kg (for 6ft system)

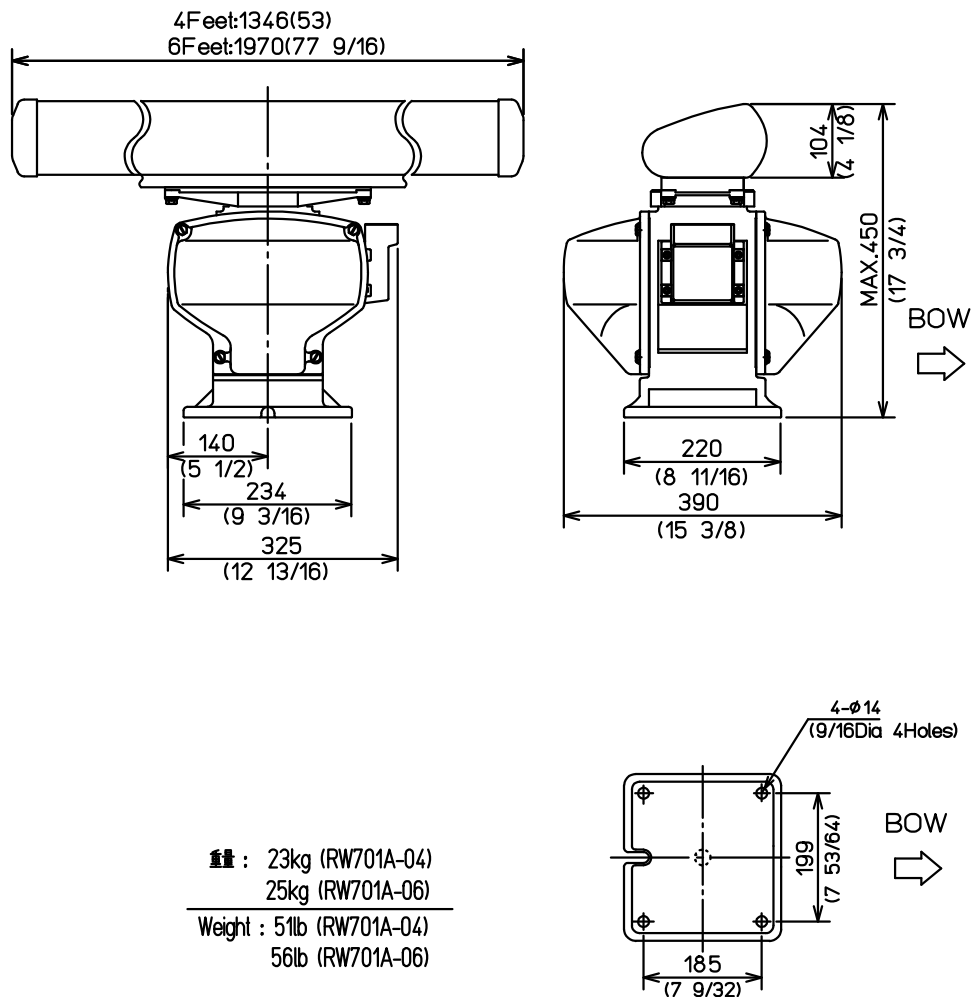
RB719AP: 325 x 470 x 450, 27 kg (for 4ft system), 29 kg (for 6ft system)

Aerial Swing circle: 1346 for 4 ft, 1970 for 6 ft

Processor: 320 x 122 x 320, 5.5 kg

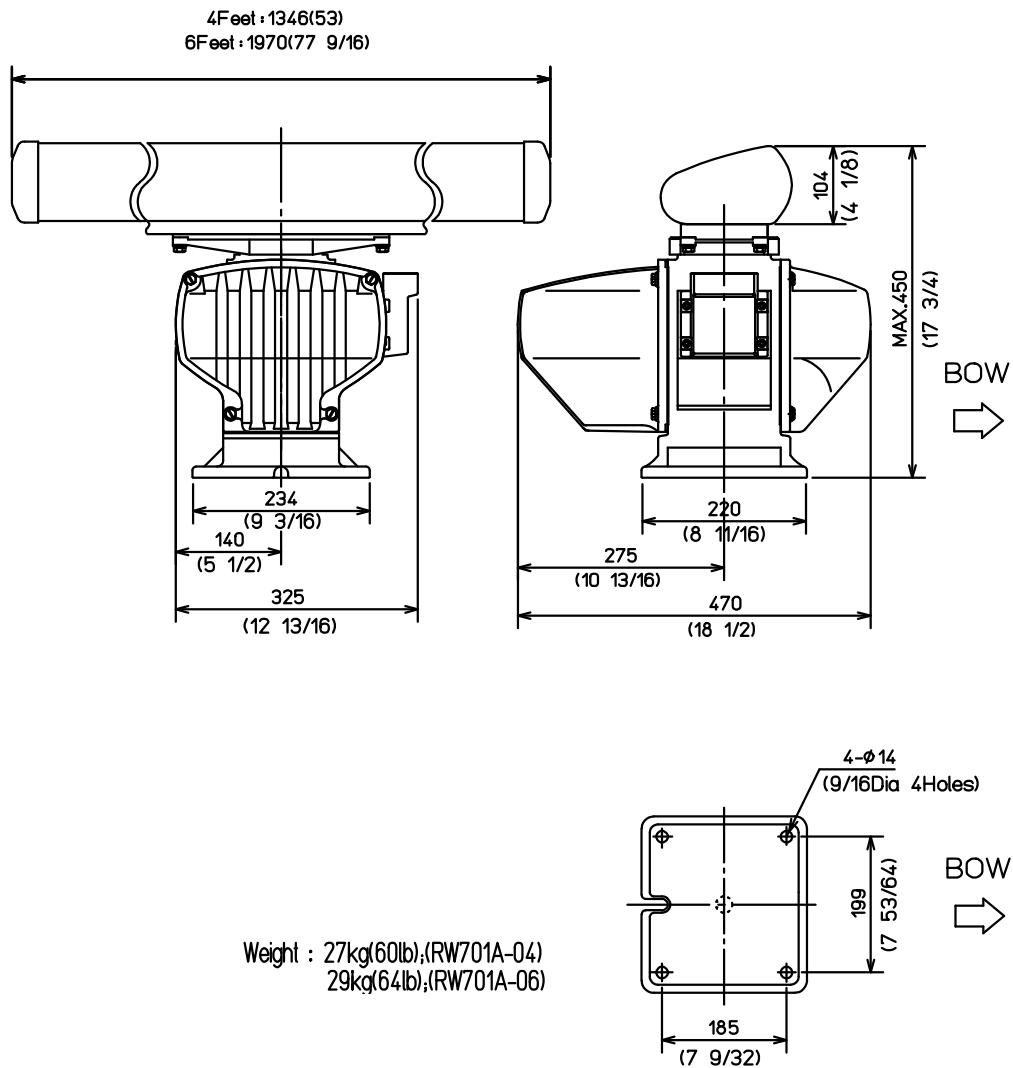
Operation: 354 x 130 x 49, 2 kg

[Antenna unit]



UNIT : mm(inch)

Figure 3.1 External dimensions of the Antenna unit, RB717AP/718AP



UNIT : mm(inch)

Figure 3.2 External dimensions of the Antenna unit, RB719AP

[Processor unit]

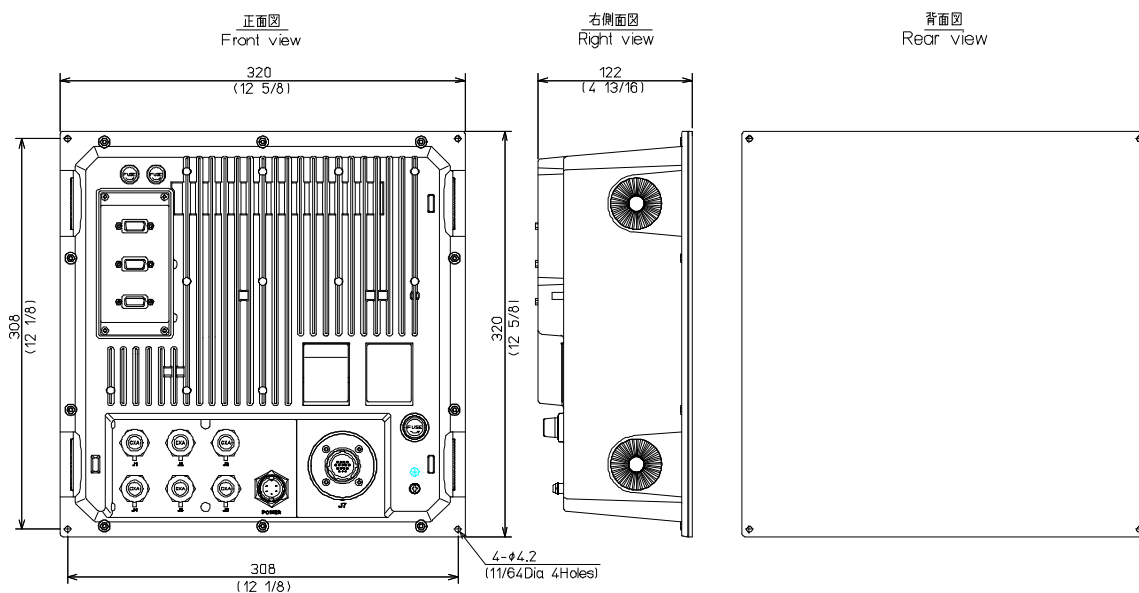


Figure 3.3 External dimensions of the Processor unit, RP100AP

[Operation unit]

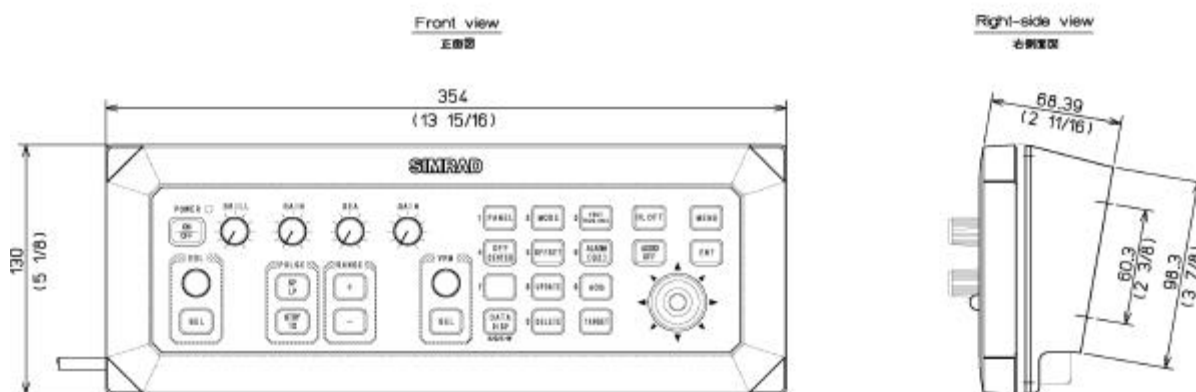


Figure 3.4 External dimensions of Operation Unit, RO100A

Chapter 4 Installation

4.1 Installation considerations

Qualified service personnel should perform the installation of the RA83P/84P/85P/93P/94P/95P series. The installation comprises the following operations.

- (1) Unpacking each component of the system.
- (2) Inspection of the exterior of each component unit and accessory.
- (3) Checking the ship's mains voltage and current capacity.
- (4) Determining the site of installation
- (5) Installing the Antenna Unit.
- (6) Installing the Processor Unit
- (7) Installing the accessory items
- (8) Planning the cable routing and connections
- (9) Commissioning

4.2 Unpacking each component of the system

Unpack your package and check if all of the items stated in the packing list are contained in the package. If not, report this to the insurance agent for tracing missing goods or refund.

4.3 Inspection of each component unit and accessories

Carefully check the exterior of each component unit for dents, damage, etc. Also check the inside of component units for electrical and mechanical damage. The LCD module is a fragile item, which is easily broken if the display unit is accidentally dropped.

4.4 Setting the units

To achieve the best operational performance, the following factors must be considered.

4.4.1 Antenna Unit

- (1) The radar antenna should be mounted on the centerline of your ship where no large obstacles interfere with the path of the radar beam.
- (2) Location should be as high as possible, however, keep in mind that nearby objects may be overlooked if mounted too high. Also note that the higher the antenna, the higher the level of sea clutter.
- (3) The mounting surface should be as flat as possible and approximately parallel

with the vessel's water line.

- (4) The antenna unit should be positioned forward of large structure and exhaust stacks, to avoid causing blind sectors on the radar screen as well as contamination from engine exhaust on the radar antenna aperture.
- (5) Provide sufficient servicing space.

4.4.2 Processor and Operation Unit

- (1) Select a location that provides good observation to radar screen and outside environment.
- (2) Locate the display so that it provides easy viewing from all likely operator's positions.
- (3) Select a position safe and free of dampness, water spray, rain and direct sunlight.
- (4) Provide enough space for servicing. Consider access to the rear panel for connecting various cables.
- (5) Position the processor unit as far as possible away from other radio equipment.
- (6) Keep a safe distance from the magnetic compass: standard: 0.60 m, steering: 0.40 m.

4.5 Cable routing and connections

4.5.1 Antenna

- (1) The cable connecting the antenna and display should be run separately away from other cables such as, radio antenna feeders, power cables, etc. Under no circumstances should it be in parallel arrangement with other cables. These precautions are essential to avoid radio interference to/from other equipment installed on the ship. If this is not possible, either cable set should be screened with metal conduit or another form of shielding.
- (2) Cable should be run as short as possible but be kept within the standard length to achieve best radar performance.
- (3) The copper braids of the cable must be grounded via a grounding stud in the transceiver unit.

4.5.2 Processor Unit

- (1) The Processor Unit must be grounded to the hull via a grounding stud at the rear of the processor unit.

4.6 Installation procedure

Observe the following procedure for installing the Antenna unit and Processor unit.

4.6.1 Installing the Transceiver Unit

When mounting the unit, position the transceiver unit as shown, so that a notched part of the transceiver base is directed towards the aft. This arrangement simplifies cable fitting and servicing. Also take note of the precautions detailed in paragraph 4.4.1 when you attempt to install the antenna unit.

- (1) Drill four fixing holes of 14 mm diameter on the fitting surface of a radar platform, as shown in Figure 4.1.
- (2) Fit the transceiver unit on the position and fix it using the 12 mm stainless bolts prepared as installation materials.

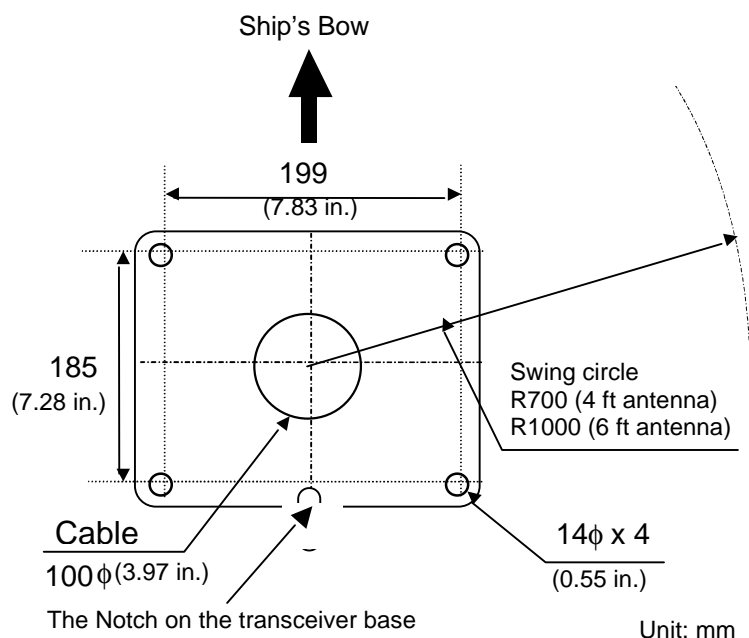


Figure 4.1 Plan view of fixing holes

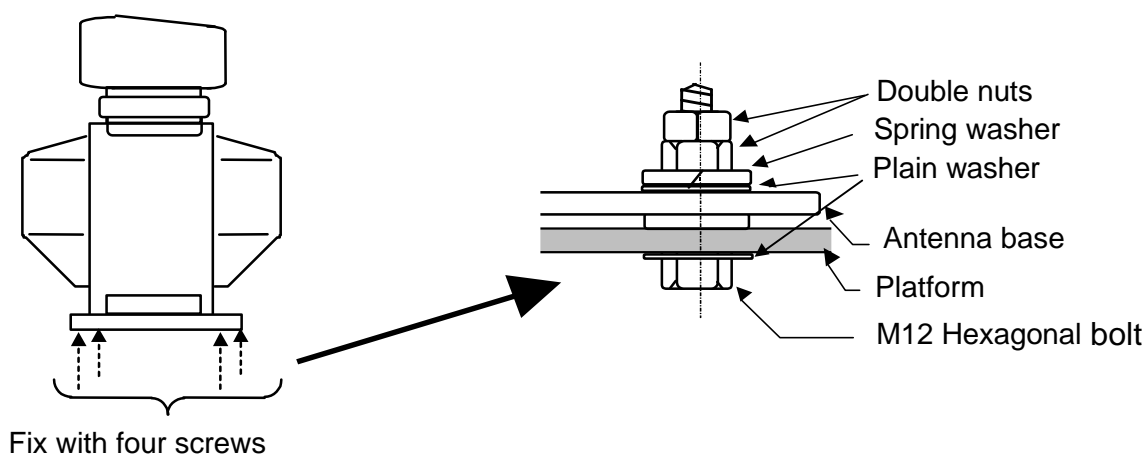


Figure 4.2 Details of the base fixing

4.6.2 Fitting the Aerial

- (1) Remove the protection cap on the outlet of the rotating base.
- (2) Fit the aerial on to the rotating base. Orient the aerial front face (the company logo printed on it) to the direction to which two arrow-marks on the rotating base point.
- (3) Fix the aerial with four bolts attached to the aerial base.

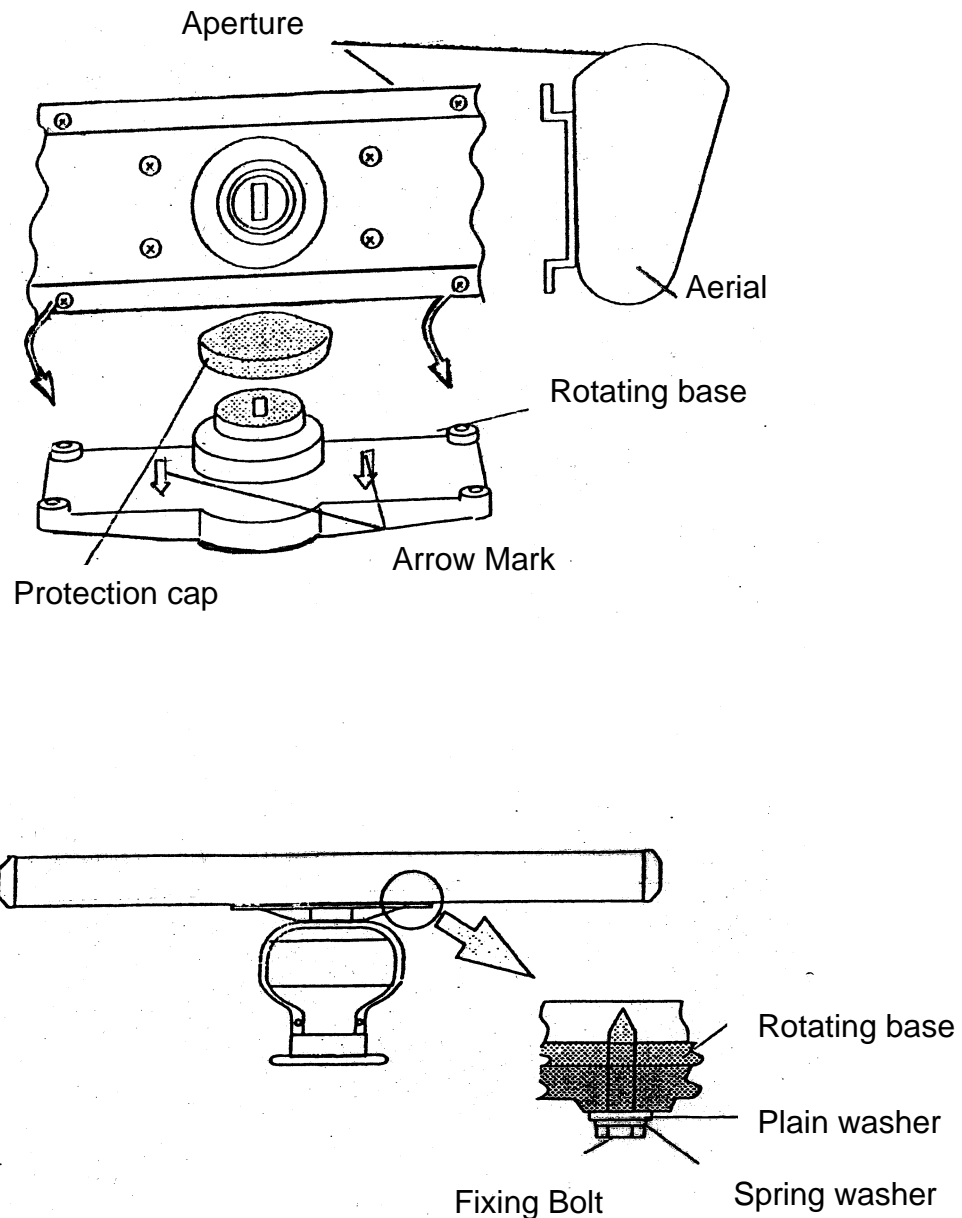


Figure 4.3 Fitting the aerial onto the rotating base

4.6.3 Connecting the cable

- (1) Remove the front and rear covers by loosening fixing bolts (4 bolts each).
- (2) Remove the TR (transceiver) unit by removing two fixing bolts. Make sure the magnetron fitted on the transceiver does not attract any magnetizing material.
- (3) Remove the rubber sealing, washer, and retainer plate from the antenna cable.
- (4) Feed the cable through the access hole through to the inside of the antenna unit.
- (5) Slide the rubber sealing, washer and retainer plate onto the cable.
- (6) Fix the cable retainer plate over the dressed braid using three fixing bolts.
- (7) Fix the antenna cable with the cable clamp.
- (8) Connect the antenna cable to the Modulator PCB. (Refer to the interconnection diagram for detail)

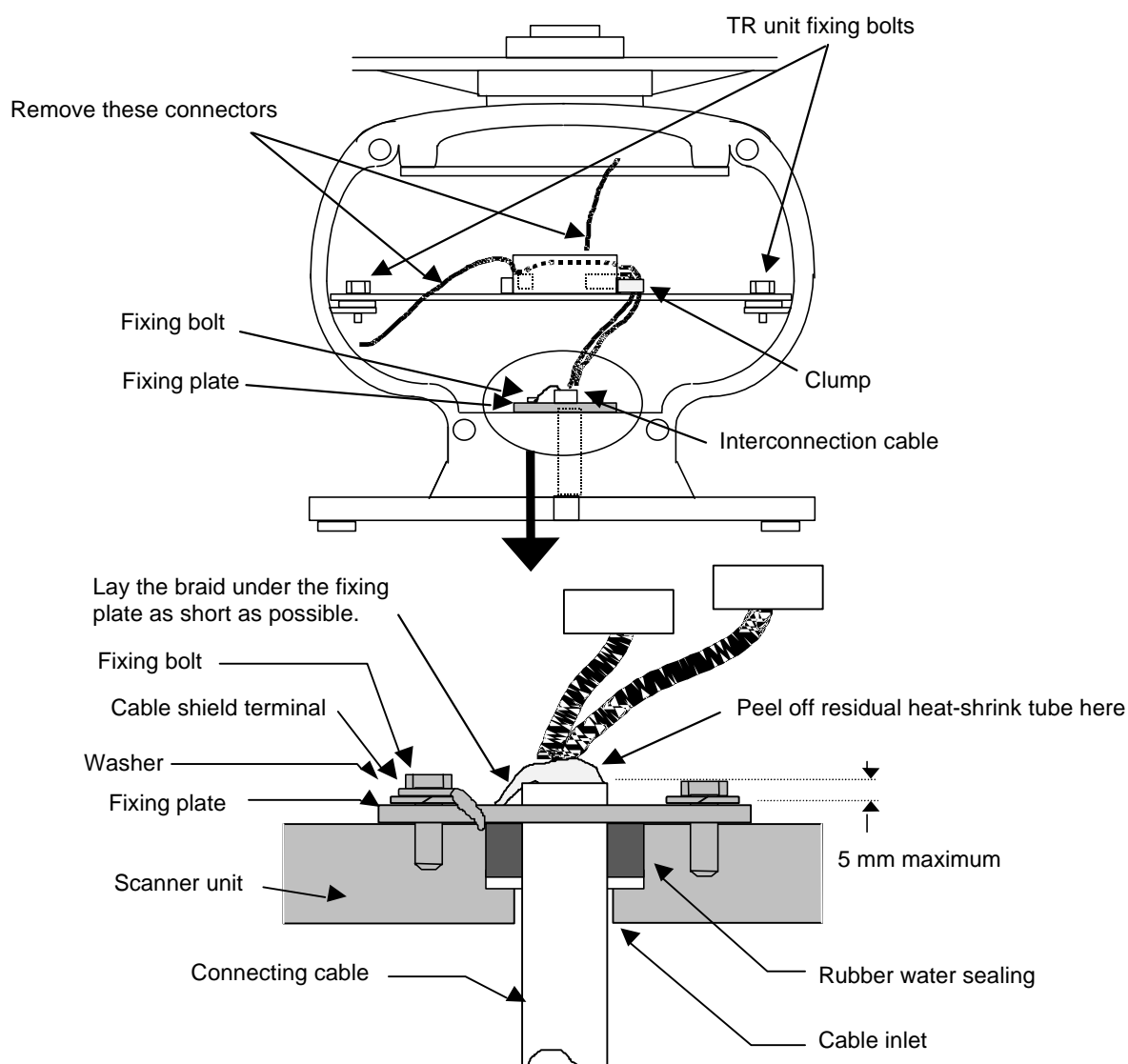
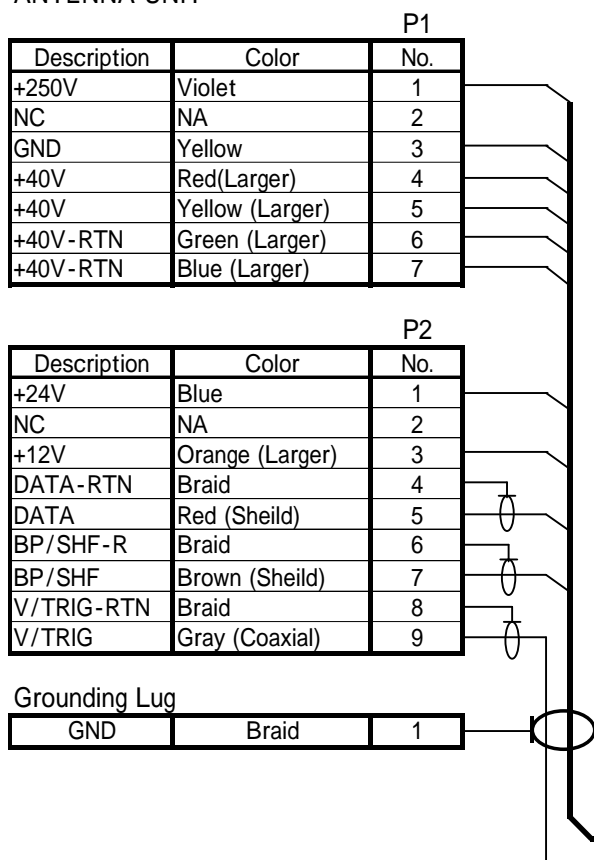


Figure 4.4 Connecting the cable to the antenna

ANTENNA UNIT



PROCESSOR UNIT

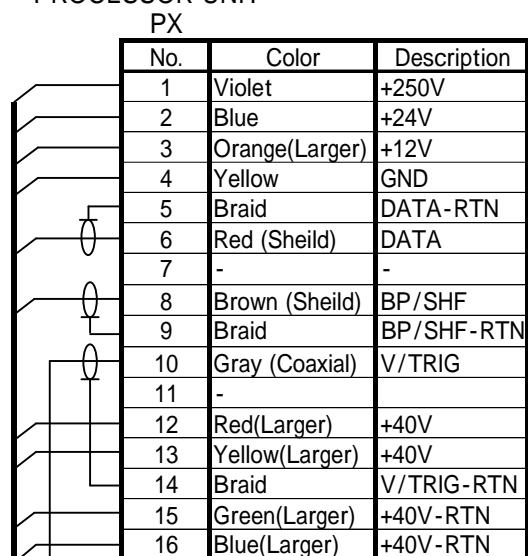


Figure 4.5 Interconnections between Antenna Unit and Processor Unit

4.6.4 Installing the Processor and Operation unit

The Processor Unit can be installed on tabletop or bulkhead. Use the following procedure for installation.

The Operation Unit can be installed in table mount or flush mount mode.

4.6.4.1 Table mounting:

Processor unit

- (1) Determine the location observing the precaution given in Para 4.4.2.
- (2) Place the Processor Unit onto the position where the unit is installed and fix it using the truss tapping screws prepared in the installation material kit. (4 positions)

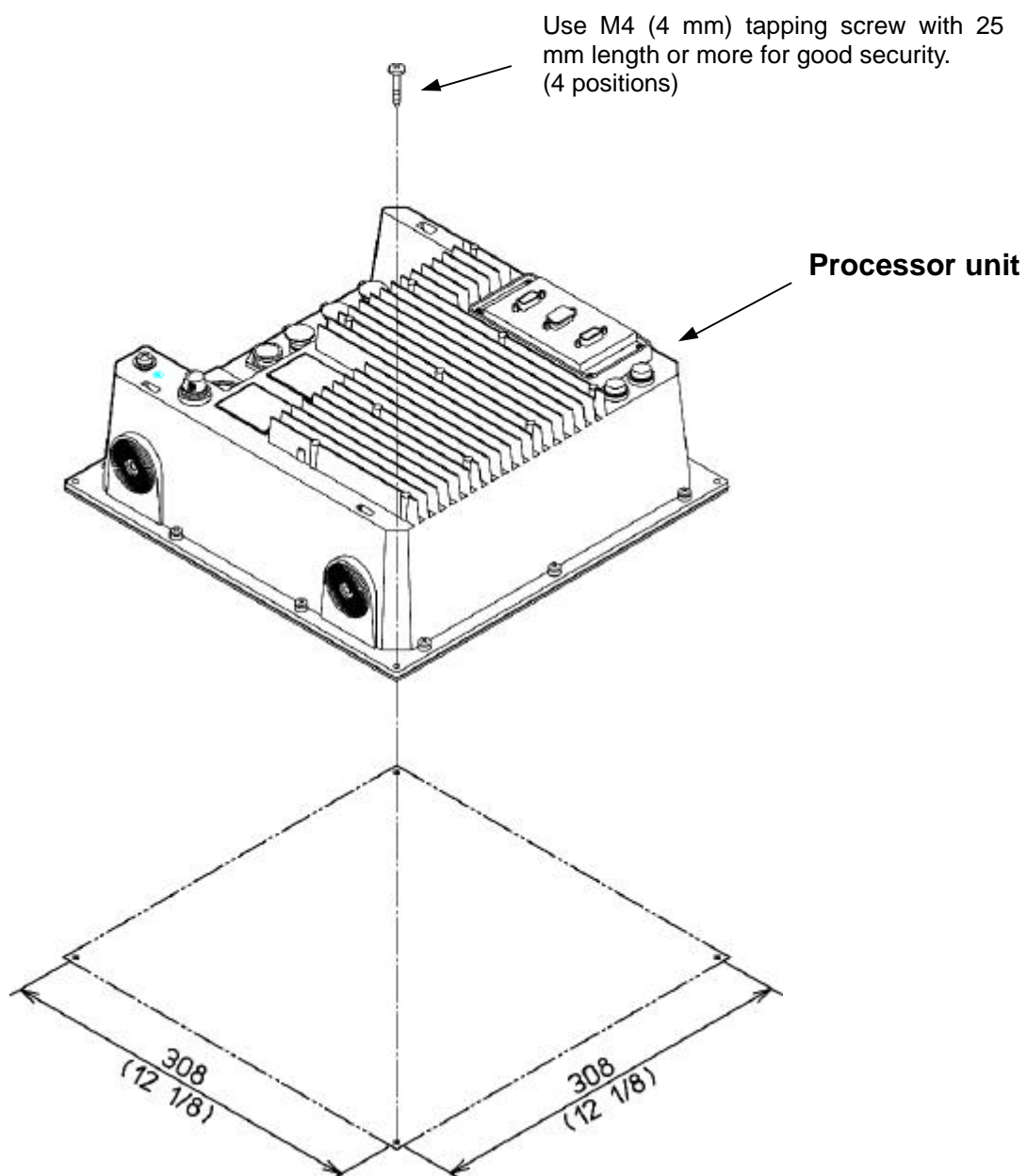


Figure 4.6 Installing the Processor Unit

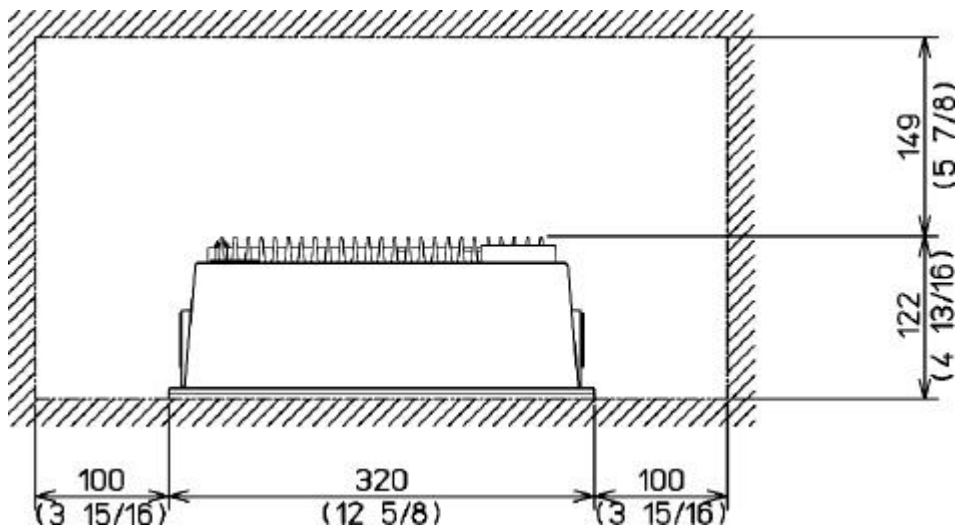


Figure 4.7 Service space required for the Processor Unit

Operation unit

- (1) Remove the screw cover (4 positions) at the corner of the operation unit. To do so, insert a thin, flat screwdriver into a gap between the cover and the operation unit. Apply gentle pressure to gradually pry the cover off the unit.
- (2) Remove the mounting bracket from the operation unit by loosening the M5 screw (4 positions).
- (3) Determine the place to install the bracket and mark the point of screw. (4 positions)
- (4) Put the bracket in place and fix with 5M (5 mm) tapping screw. (4 positions)

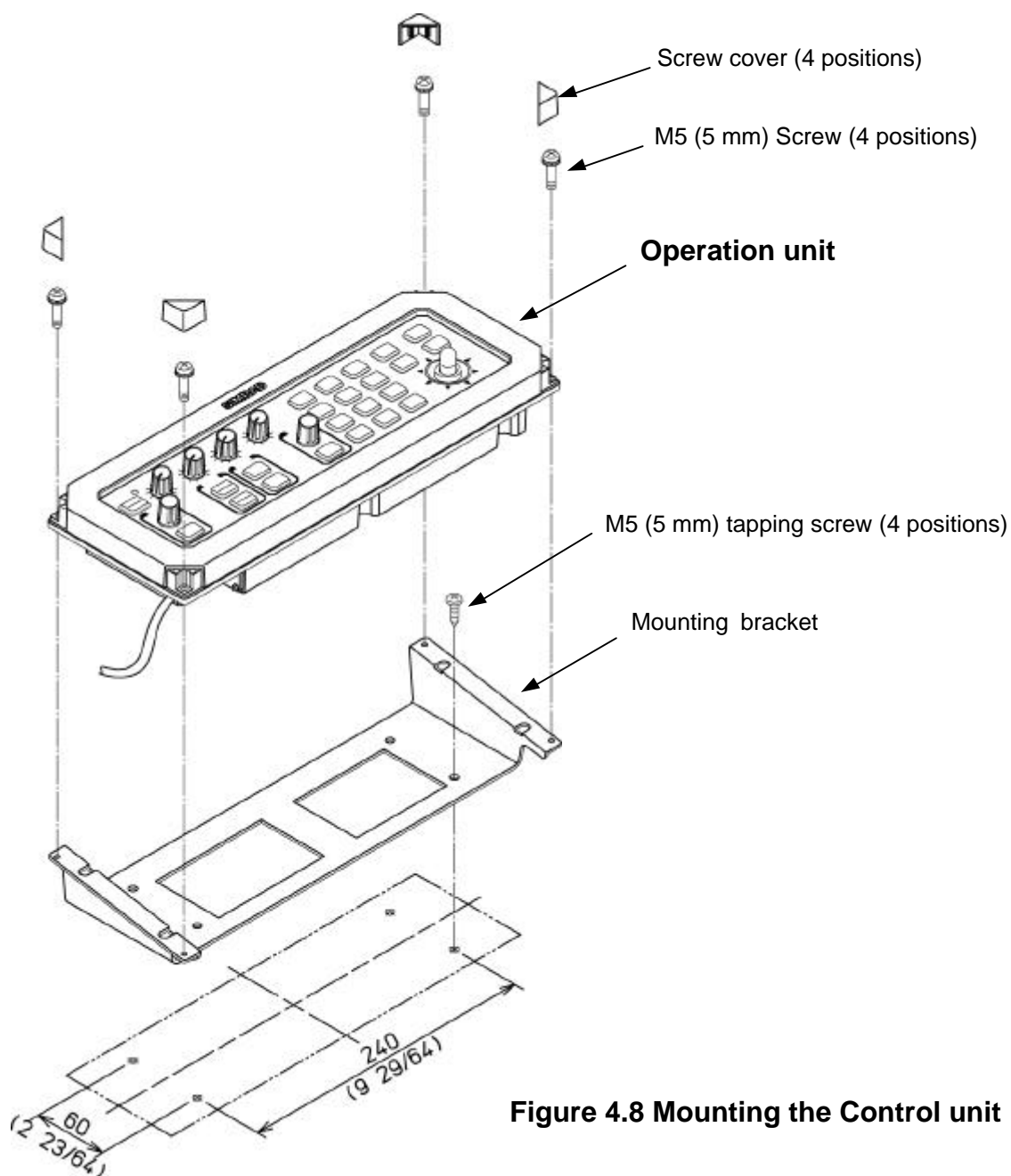


Figure 4.8 Mounting the Control unit

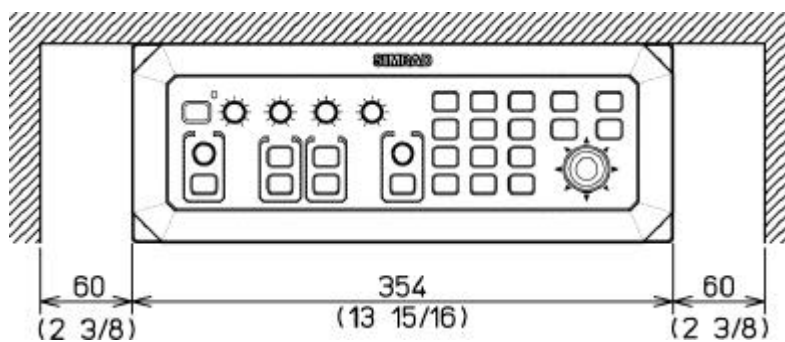


Figure 4.9 Service space required for the Operation unit

4.6.4.2 Flush mounting

Operation Unit

Preparation:

- (1) Cut aperture in surface to the dimensions shown below
- (2) Mark screwing points with a sharp-edged tool.

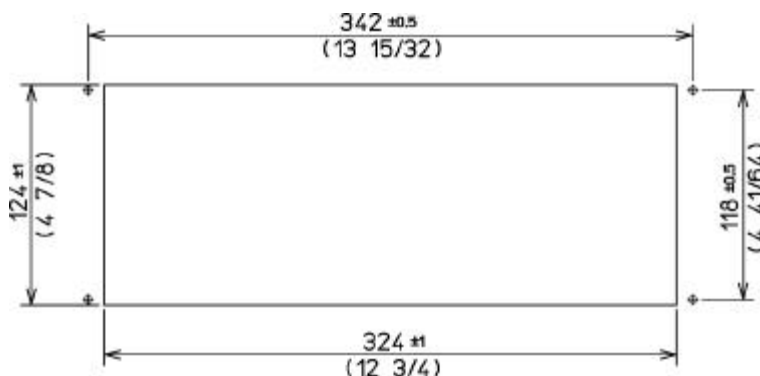


Figure 4.10 Dimensions of the Operation unit mounting aperture

Installation:

- (1) Remove the mounting bracket from the Operation unit.
- (2) Remove a screw cover, which is fitted on each corner of the Operation unit front face. (Refer to Figure 4.13)
- (3) Put the Operation unit and connecting cable into the aperture flush with the panel surface. Connect the cable to the Processor unit at the specified receptacle. (Refer to Figure 4.14)
- (4) Fasten the Operation unit to the panel using a 4 mm tapping-screw. (4 positions)
In case you use M4 screws select an appropriate length that best suits fixing the unit to the panel.
- (5) Refit the screw covers removed in step (2).

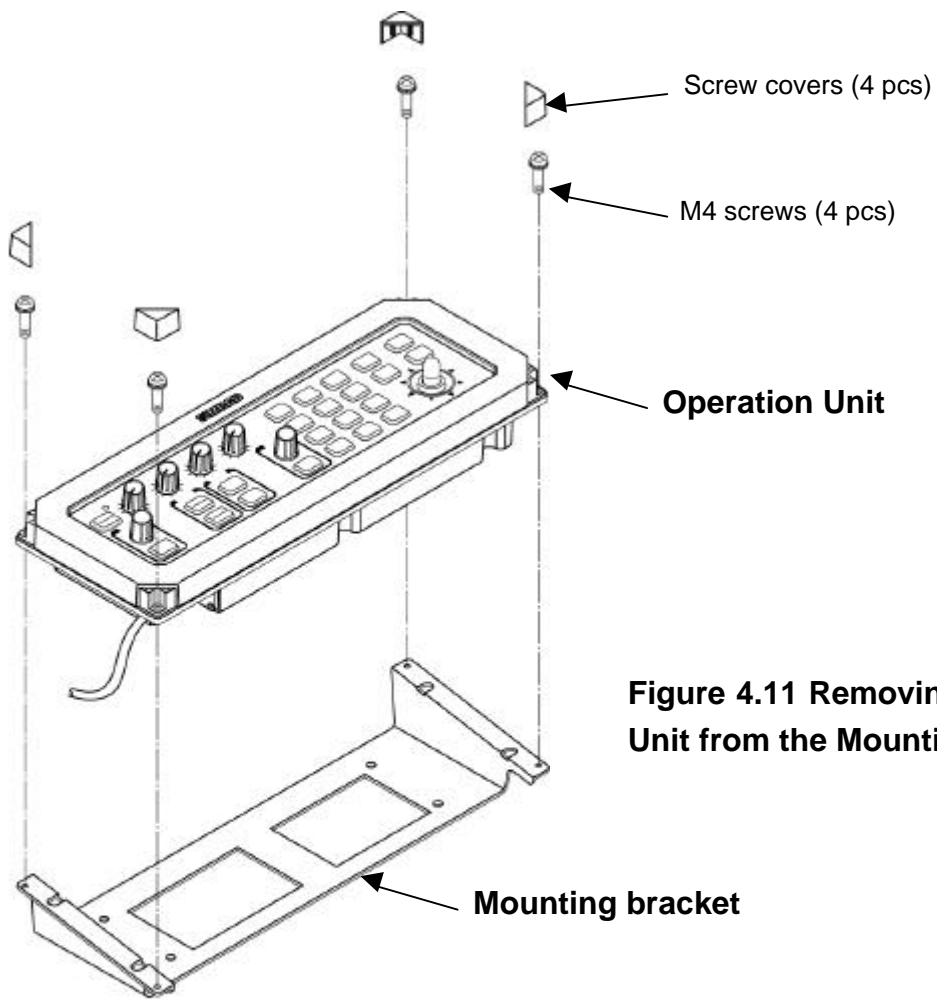


Figure 4.11 Removing the Operation Unit from the Mounting Bracket

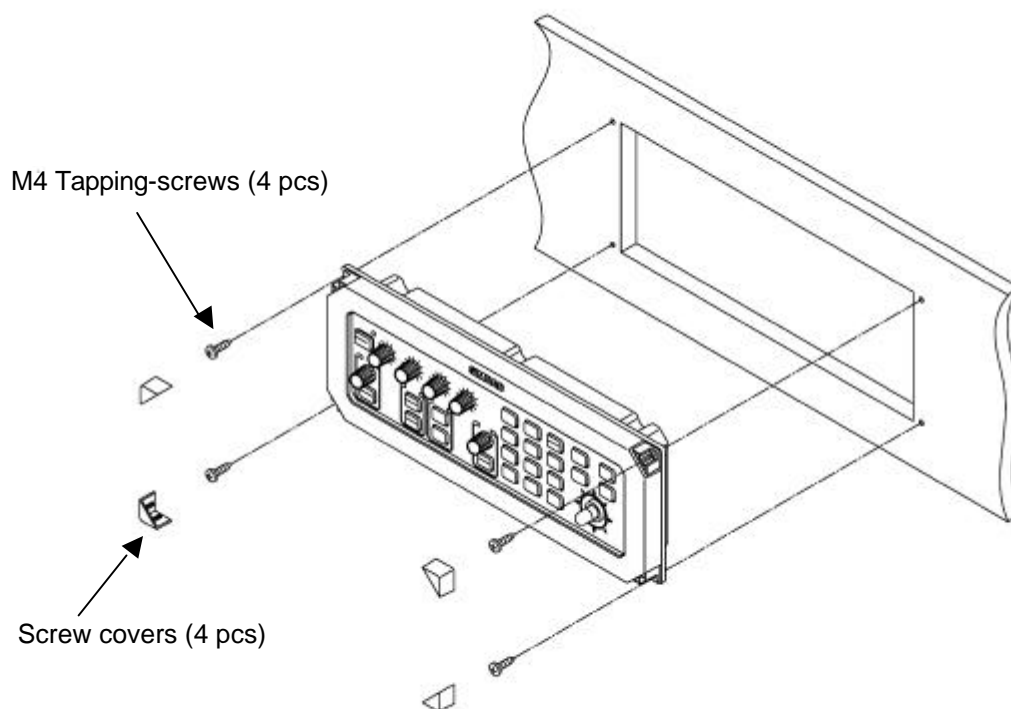


Figure 4.12 Installing the Operation Unit onto the panel

4.6.5 Connecting the cable to the Processor Unit

Connect the antenna cable, power cable and the data cable to the designated sockets as shown in Figure 4.13.

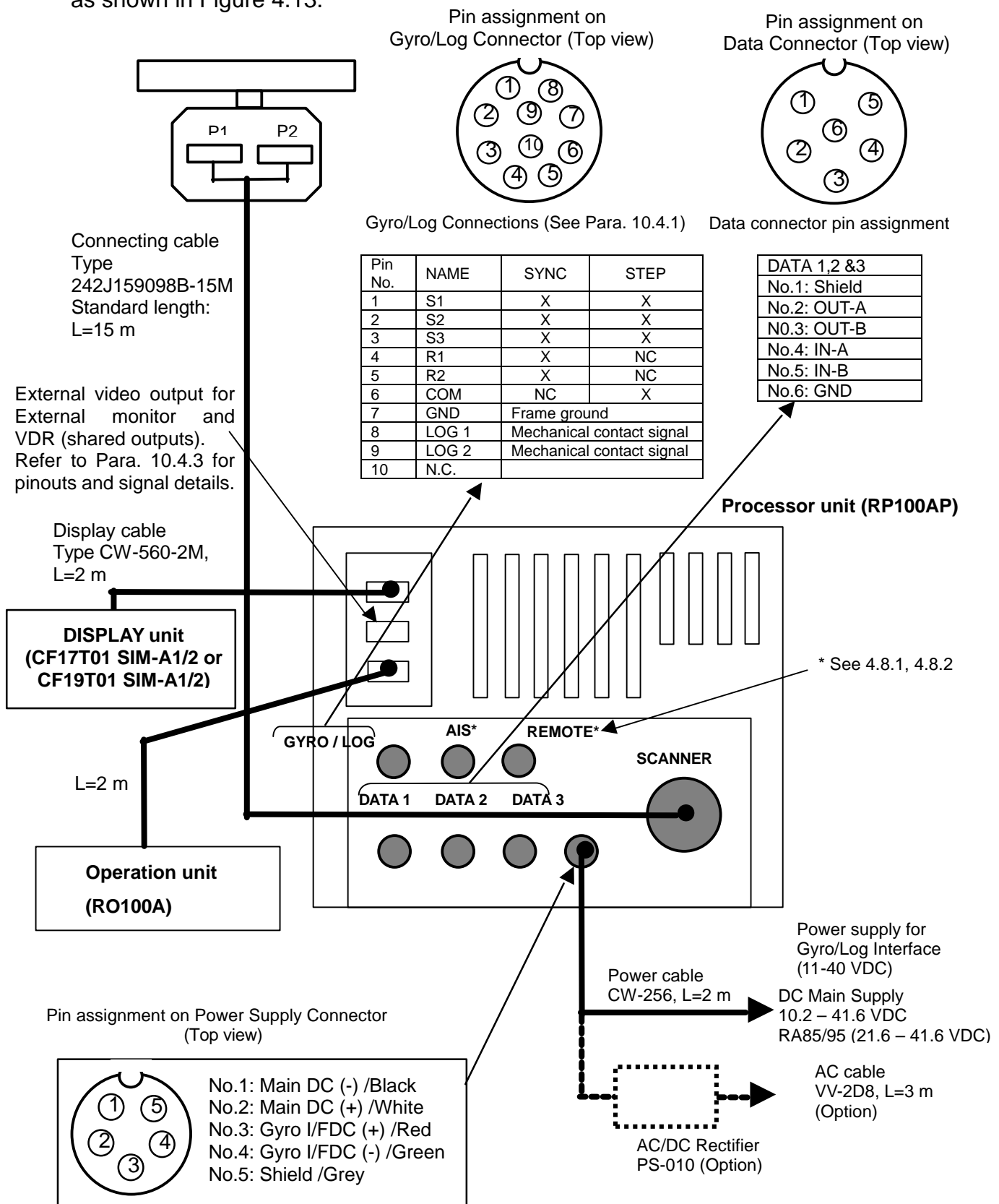


Figure 4.13 Cable connections to the Processor Unit

4.6.6 Link setting for the gyrocompass

When the Gyro signal voltage is lower than 50V, change the link positions for J721 to J725 from “2-3” to “1-2” on the Main Logic PCB (E47-700*) as shown below.

Change setting from “2-3” to “1-2”,
applicable for J721 to J725

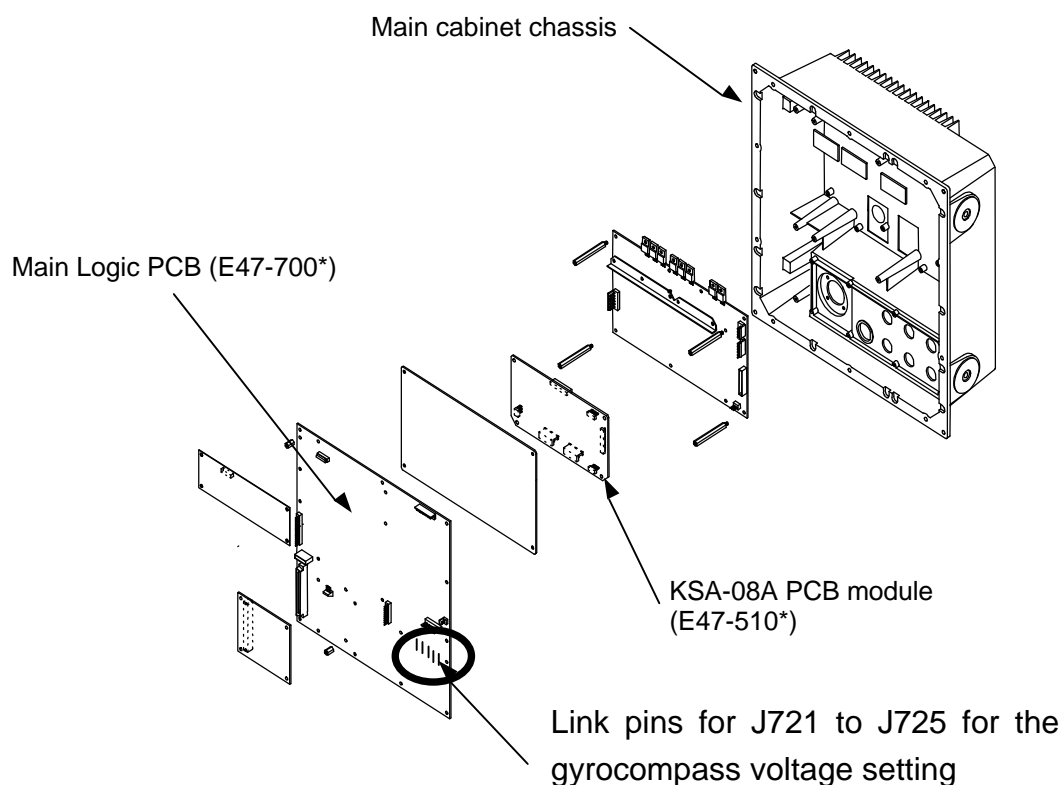
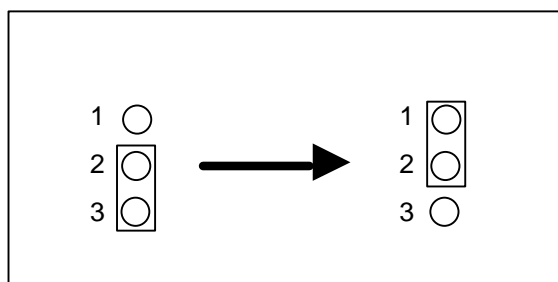


Figure 4.14 Locations of the gyrocompass links on the Main Logic PCB

4.6.7 Ferrite core assembling for Power cable

Loop the power cable around the ferrite core three turns at position of 40 cm from the connector as shown in figure 4.15.

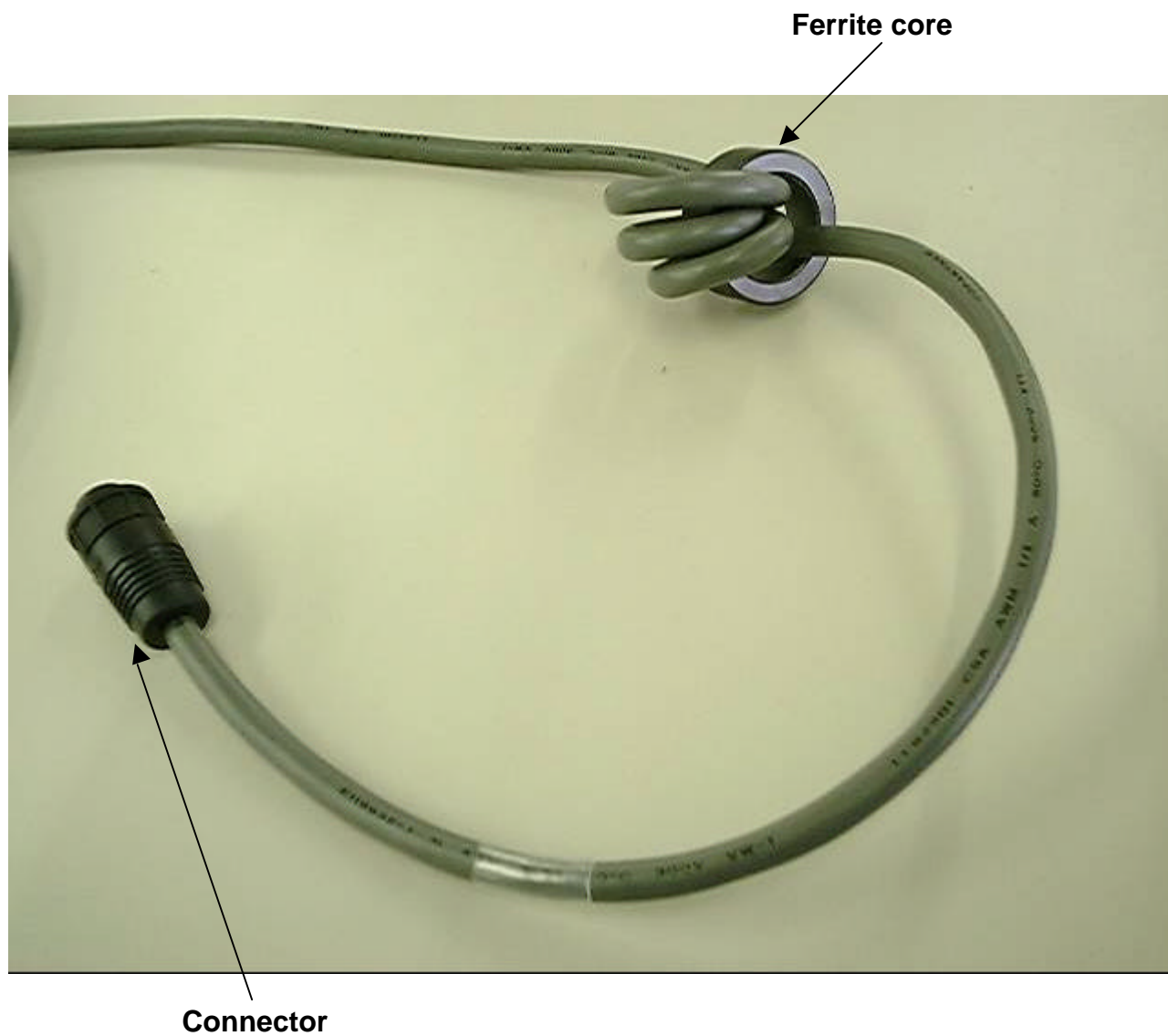


Figure 4.15 Ferrite core assembling for Power cable

4.7 Setting up after installation

A few set ups are required after installation. Before carrying out the setting up procedures, check the following items in order to make sure the equipment operates in normal manner:

- (1) Check that the ship's power supply is properly rated to operate the radar system.
- (2) No person is present near the platform or on the mast where the radar antenna is to be operated. Put a warning tag on the display unit that reads, "**RADAR ADJUSTMENT IN PROCESS. DO NOT TOUCH ANY CONTROLS**".

NOTE: The following setup menus are protected from ordinary key operations. To use this function, first turn off the radar set. Second, press and hold the MODE key and turn the radar on. When the standby condition is established, turn the radar on to enter the following menu functions.

4.7.1 Transmission timing

SYSTEM MENU: SYSTEM SETUP/DELAY

Adjusts the transmission delay time in order to match the timing of radar transmission and the start of the radar sweep. In practice, refer to the following figures that illustrate the result of the setting, whether it is properly adjusted or not. To effectively perform this setting, find an appropriate nearby object that is straight across from your radar. Carry out the following procedure to set up the proper transmission delay time.

- (1) Highlight the DELAY item and press the ENT key to set up the selection-ready status.
- (2) Press the Joystick towards the up or down until a straight video line is shown on the screen.
- (3) Press the ENT key to fix the settings.

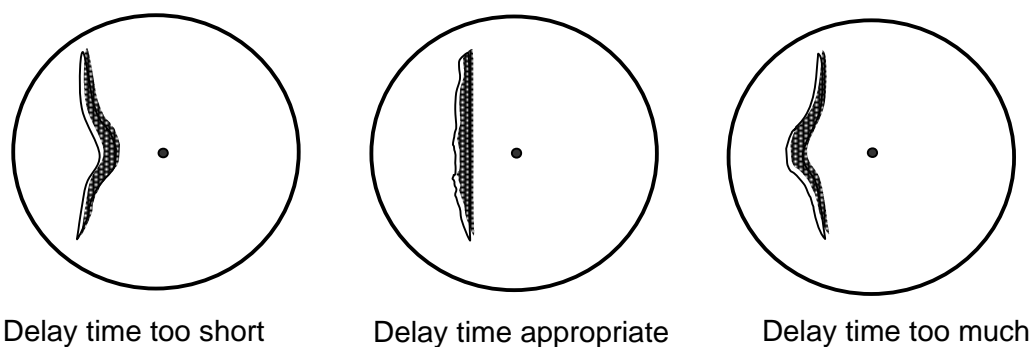


Figure 4.16 Echo presentation depending on the transmission delay timing

4.7.2 Ship's heading set up

SYSTEM MENU: SYSTEM SETUP/HDG

Adjusts the bearing of the radar picture shown on the screen. First, take an optical bearing of a stationary target located within a viewable range using a standard magnetic compass on the ship. Then measure the target bearing on the radar. If the deviation is found more than +/- 1 degree on the screen, carry out the following procedure for correction.

- (1) Move the Joystick up or down to highlight the HDG sign and press the ENT key.
- (2) Press the Joystick up or down to change the bearing, in order to set the radar echo bearing to coincide with the compass bearing.
- (4) Press the ENT key to fix the bearing.

4.7.3 Resetting Manual GAIN/STC (Height)/Manual STC

Gain and Sea settings have been properly set at the factory, however, when a need is arisen to change these settings use the following procedures. Resetting must be carried out in the following order.

1. Manual GAIN setting
2. STC (Height) setting
3. Manual STC setting

When completed, be sure to record respective setting values in the GAIN/SEA/HEIGHT sheet prepared in this paragraph.

4.7.3.1 Manual GAIN setting

- (1) Press and hold the MODE key and turn the power on. When a beep is heard, release the key.
- (2) Transmit the radar when STBY is displayed on the screen.
- (3) Set the RAIN and SEA control to 0, GAIN to 8 and BRILL to 10 (Max), respectively.
- (4) Confirm the following settings. If not set so.
IR level: IR2
SEA, GAIN, RAIN: MANUAL
- (5) Set the range scale to maximum. (RA83P/93P: 64 NM, RA84P/94P: 72 NM, RA85P/95P: 96 NM)
- (5) Select the GAIN MANUAL menu per ADJUST>PRESET>GAIN MANUAL and display the GAIN MANUAL index entry window.
- (6) Move the Joystick up or down until a desired noise level (density of the noise speckle) is obtained and press the ENT key to fix the setting.
- (7) Record the new GAIN setting value in the GAIN/SEA/HEIGHT Setting Record

sheet (GAIN/SEA/HEIGHT sheet, hereafter).

- (8) Repeat the above procedure for all range scales, if required.

4.7.3.2 STC (Height) setting

The STC characteristic is more less subject to vary depending on the height of the antenna from the sea surface. Resetting the STC may be needed according to the circumstances of the respective vessels. To achieve the best result, this setting should be carried out off shore. Use the following procedure to do.

- (1) Set SEA, GAIN and RAIN control to manual mode.
- (2) Set GAIN to 8, SEA to 0 and RAIN to 0, respectively. Make sure that the sea clutter speckle is appropriately shown on the screen. If the speckle is too much or too short on the display, adjust the GAIN control as appropriate.
- (3) Select an appropriate range scale to permit the clutter speckle is shown within the screen.
- (4) Adjust the SEA control to reduce the sea clutter until some residual clutter speckle is shown.
- (5) Turn the SEA control either clockwise or counterclockwise to see the effect of the STC. If the effect is uniform in both long and short ranges, the STC Height selection is considered appropriate. In such a case when the short range sea return is suppressed earlier than that of the long range or vice versa, use the following procedure to correct.
- (6) Go SYSTEM>SYSTEM SETUP>HEIGHT and display the HEIGHT index entry window.
- (7) Adjust the SEA control to see the tendency of the control. If the short-range clutter return is suppressed in advance to the long range one, reduce the HEIGHT value by pressing the Joystick downwards, and vice versa.
- (8) Adjust the SEA control to confirm the effect. If the result is not satisfactory, repeat the above procedure.
- (9) Press the ENT key to fix the setting.
- (10) The HEIGHT index is irrelevant to the range. If this setting cannot be performed offshore, the HEIGHT index should be selected with reference to the actual antenna height from the sea surface. Use the following criteria as reference.

| Antenna height | Recommended HEIGHT index |
|----------------|--------------------------|
| 3 m | 8 |
| 5 m | 5 |
| 10 m | 2 |

4.7.3.3 Manual STC setting

This setting allows the maximum STC range to be effective up to 6 NM. Use the following procedure to set up.

- (1) Set radar controls as follows:
Range scale: 12 NM, RAIN/SEA: 0, GAIN: 8, BRILL: 10 (Max)
- (2) Activate VRM 1 per: DISP>MARK>VRM 1>ON and press the ENT key.
- (3) Set VRM 1 to 6.0 NM.
- (4) Turn off IR 2 per: DISP>ECHO>IR>OFF and press the ENT key.
- (5) Set SEA, GAIN and RAIN to MANUAL mode.
- (6) Set SEA to 10 notch (Maximum).
- (7) Go ADJUST>PRESET>SEA MANUAL and display the numeral entry window.
- (8) Press the Joystick up or down to allow the background noise speckle is reduced to about 6 NM. Press the ENT key to fix the setting. Record the value.
- (9) Repeat the above procedure to the rest of the range scales using the same value.
- (10) Change range scale from one to the other with the SEA control set to maximum. If the STC effect is not uniform on some ranges, reset the setting repeating the above procedure.
- (11) Reset IR2 to be activated.

GAIN/SEA/HEIGHT Setting Record sheet

| Range scale | Pulse length | GAIN setting | | SEA | |
|----------------|--------------|--------------|-----|---------|-----|
| | | Initial | New | Initial | New |
| 96NM(72or64NM) | LP | | | | |
| 48NM | LP | | | | |
| 24NM | LP | | | | |
| 12NM | LP | | | | |
| 12NM | M2 | | | | |
| 6NM | M2 | | | | |
| 6NM | M1 | | | | |
| 3NM | M2 | | | | |
| 3NM | M1 | | | | |
| 1.5NM | M1 | | | | |
| 1.5NM | SP | | | | |
| 0.75NM | M1 | | | | |
| 0.75NM | SP | | | | |
| 0.5NM | SP | | | | |
| 0.25NM | SP | | | | |
| 0.125NM | SP | | | | |

STC HEIGHT: Initial setting: New setting:

4.7.4 Performance Monitor initial setup

SYSTEM MENU: BITE/PM TUNE

A calibration of the performance monitor must be made when the radar set is installed or the magnetron or the Receiver Front End module (MIC, or Microwave Integrated Circuit) is replaced during repair. To carry out the calibration:

- (1) Highlight the PM TUNE and press the ENT key to set the ready-to-select status.
- (2) Press the Joystick to the up or down to make the performance monitor video image become the largest.
- (3) Press the ENT key to fix the tuning for the Performance Monitor.
- (4) Highlight the word CALIBRATION GO shown below the PM TUNE sign.
- (5) Press the ENT key to complete the calibration. The RX, TX, and SYSTEM Bar graphs will be fully displayed, as a result.

Example of Performance Monitor Bar Graph is shown below, which is applicable to the RX, TX and SYSTEM bar graphs.



Figure 4.17 Bar graph display shown for Performance Monitor

4.8 Setting up Option

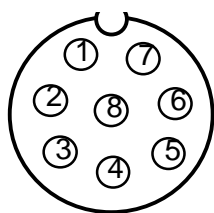
4.8.1 AIS Interface (Option)

DISP MENU: NAV/AIS

Activate AIS function from DISP/NAV/AIS menu.

Automatic Identification System (AIS) will automatically display ships symbol and data around your ship. The range of the data display ships can be set from RADAR/AIS menu.

Pin assignment on
Data Connector (Top view)



| Pin No. | NAME |
|---------|------------|
| 1 | Shield |
| 2 | IN-B |
| 3 | IN-A |
| 4 | OUT-B |
| 5 | OUT-A |
| 6 | GND |
| 7 | AIS ALARM+ |
| 8 | AIS ALARM- |

4.8.2 Remote Display operation

A Processor Unit type RP100AP can be used as a remote display. To use the display in this configuration, use the following procedure.

4.8.2.1 Connecting the Remote Display

Connect the Master display (RP100AP) and a Remote display (RP100AP) with the connecting cable CW-561 (10m) as shown in Figure 4.17.

4.8.2.2 Required set up

In the Slave display, set the status switch S1-6 on the Logic PCB (E47-700*) to ON.



CAUTION:

Do not connect the Antenna unit to the remote display. If do so, the remote display may malfunction.

4.8.2.3 Possible operation on Remote Display

The remote display is configured to be slave to the master display in terms of transmission control, transmit and standby. Except this function, the remote display has all controls that the master does, such as, gain, STC, FTC, range scale change, off-centering, changing mode of operation, VRM, EBL, fixed rings, etc.

In the following circumstances, the display presentation becomes abnormal but is not fault.

- (1) When the transmission is turned off, the slave screen is displayed with plural coaxial video caused by non-updated video data.
- (2) When the master display is set to short range and the remote display to long range, the remote screen will be shown with coaxial radar picture caused by higher transmission rate video being supplied from the master display.
- (1) On the contrary, when the master display is set to long range and remote display to short range, the remote display screen will be shown with stretched video towards range. In a particular case, the radar video display will be shown halfway due to slower transmission rate.

NOTE: To utilize the nav data, true bearing mode, true motion mode and EPA/ATA functions in remote display, relevant sensor units such as, gyro compass, speed log and GPS receiver must be connected.

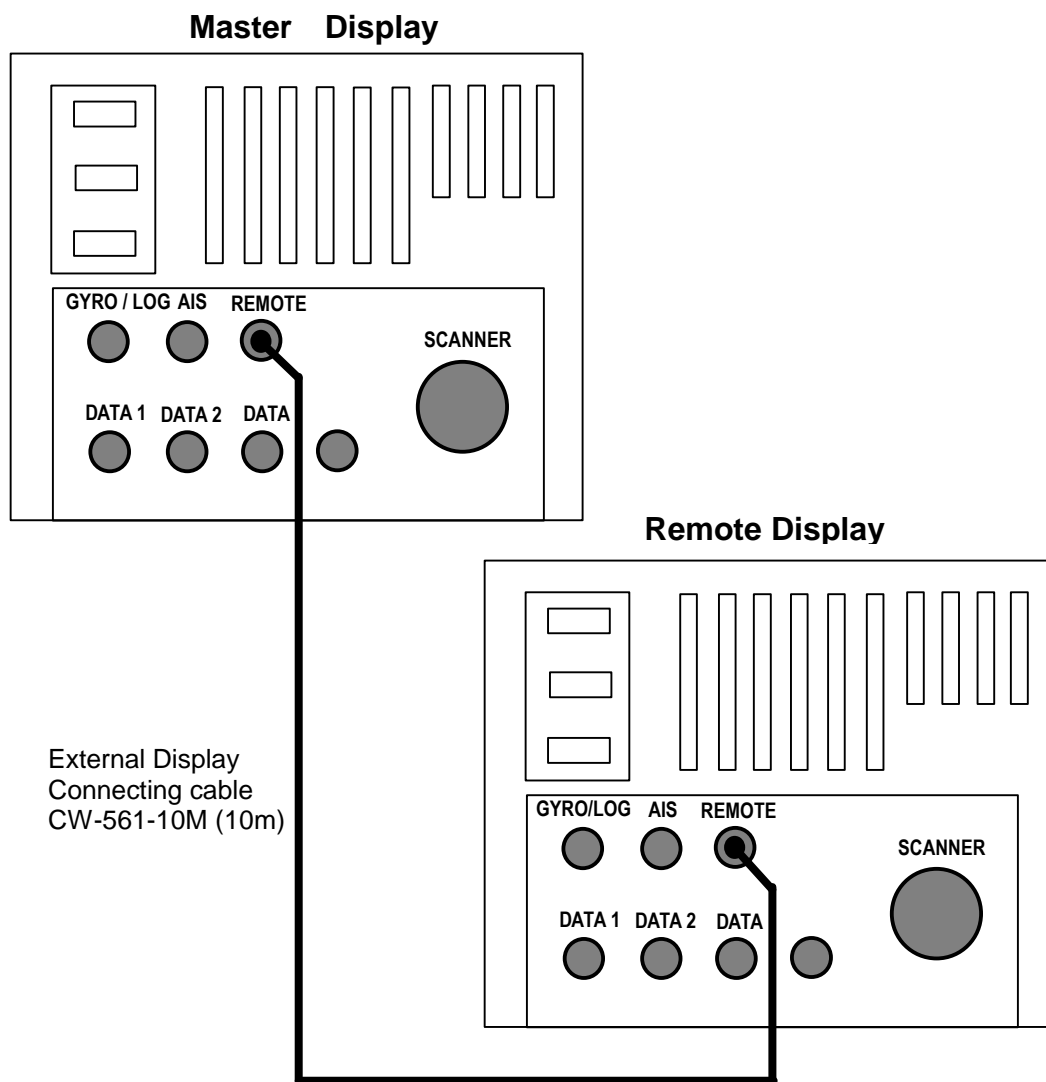
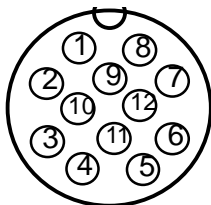


Figure 4.18 Remote display connection

Pin assignment on
REMOTE Connector
(Top view)



| Pin No. | NAME |
|---------|------------------|
| 1 | VIDEO OUT |
| 2 | TRIG OUT |
| 3 | GND |
| 4 | AZIP OUT |
| 5 | SHF OUT |
| 6 | GND |
| 7 | VIDEO IN |
| 8 | TRIG IN |
| 9 | GND |
| 10 | AZIP IN |
| 11 | SHF IN |
| 12 | +12Vdc(Not used) |

APPENDIX 1

Installation of the ATA module, MRE-300

The ATA module MRE-300 is installed inside the processor unit. Use following the instructions for installation.

- (1) Locate the position of the four fixing studs on the Main Logic PCB (E47-700*) prepared for the ATA module. (Refer to the figure below)
- (2) Put the ATA module (MRE-300) on the studs and press the module gently downwards in order that the connector installed on the module properly plugs into the receptacle J705 on the Main Logic PCB.
- (3) Fix the module using the four 3 mm fixing screws, prepared in the ATA module kit.

Installation of the AIS module, AIS-100

The AIS module (AIS-100) is installed inside the processor unit. Use the following instructions for installation.

- (1) Locate the position of the four fixing studs on the Main Logic PCB (E47-700*) prepared for the AIS module. (Refer to the figure below)
- (2) Put the AIS module (AIS-100) on the studs and press the module gently downwards in order that the connector installed on the module properly plugs into the receptacle J716 on the Main Logic PCB.
- (3) Fix the module using the four 3 mm fixing screws, prepared in the AIS-100 kit.

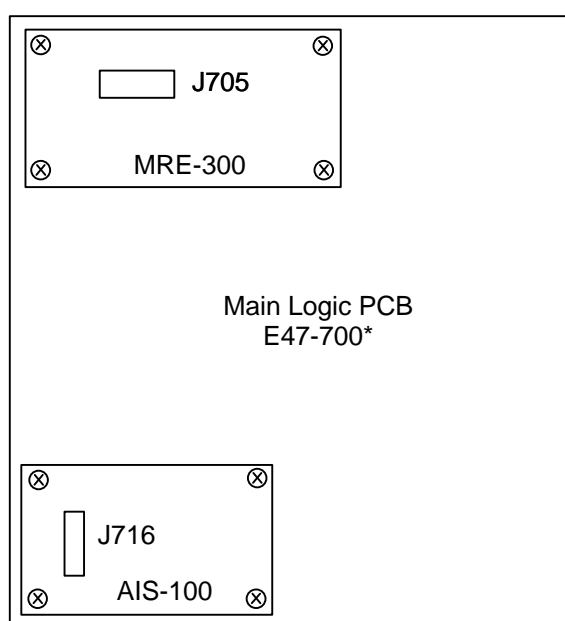


Figure A.1 Position of the ATA and AIS modules to be installed

AIS connector pinouts and cable color coding designation:

| Cable type name | Port name | Pin number | Signal name | Color code |
|-----------------|-----------|------------|-------------|------------------|
| CW-387-5M | AIS | 1 | Shield | Braid |
| | | 2 | IN-B | Red dot/Orange |
| | | 3 | IN-A | Black dot/Orange |
| | | 4 | OUT-B | Red dot/White |
| | | 5 | OUT-A | Black dot/White |
| | | 6 | GND | Black dot/Grey |
| | | 7 | AIS ALARM+ | Red dot/Pink |
| | | 8 | AIS ALARM- | Black dot/Pink |

About AIS malfunction alarm

If the AIS transponder gets failed in operation, the AIS ABNORMAL status is supplied from the transponder to the display causing the error message to appear on the screen.

NOTE: *In case no alarm signal lines are available in the AIS transponder, link the AIS ALARM+ (Red dot/Pink wire) and AIS ALARM- (Black dot/Pink) signal lines at the cable end at the transponder side. This processing is necessary to prevent the AIS alarm message from being shown mistakenly on the display.*

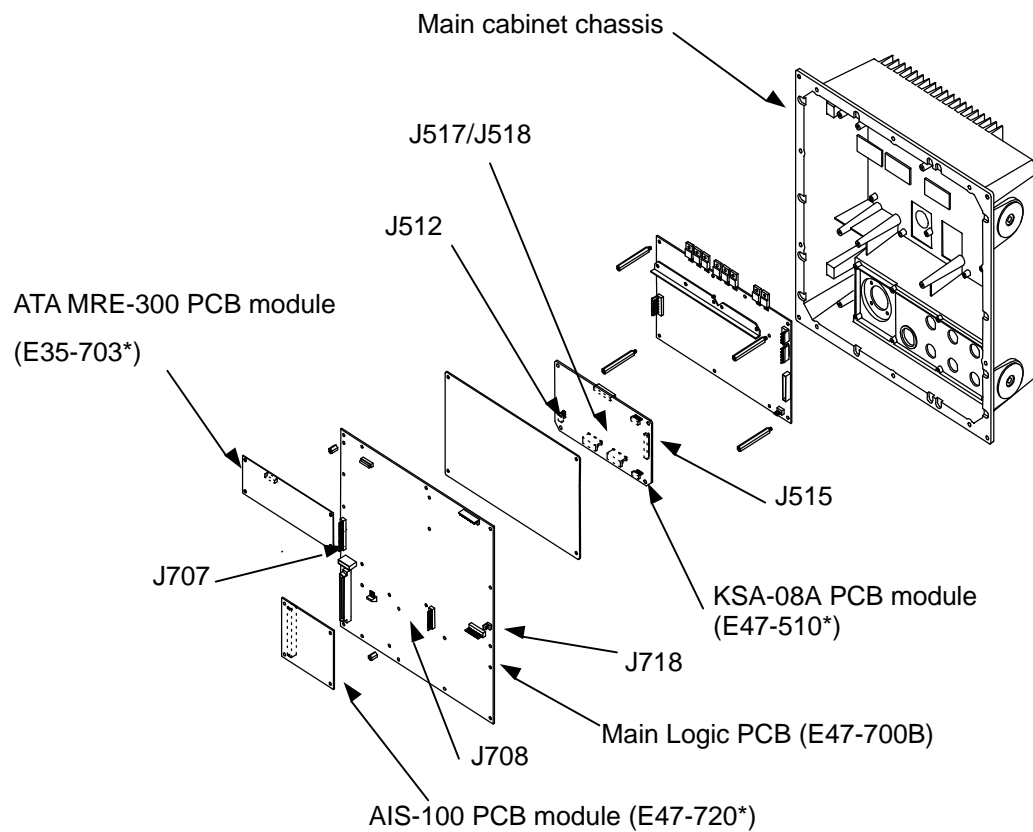


Figure A.2 Fitting ATA, AIS and Gyro Interface modules into Main Logic PCB

APPENDIX 2

Cables pinouts and cable color-coding designation

GYRO connector pinouts and cable color coding designation:

| Cable type name | Port name | Pin No. | Signal name | Color code |
|-----------------|-----------|---------|-------------|------------------|
| CW-388-5M | GYRO | 1 | S1 | Red dot/Orange |
| | | 2 | S2 | Black dot/Orange |
| | | 3 | S3 | Red dot/Grey |
| | | 4 | R1 | Red dot/White |
| | | 5 | R2 | Black dot/White |
| | | 6 | COM | Red dot/Yellow |
| | | 7 | GND | Shield |
| | | 8 | LOG1 | Red dot/Pink |
| | | 9 | LOG2 | Black dot/Pink |
| | | 10 | NC | |

DATA connector pinouts and cable color coding designation:

| Cable type name | Port name | Pin No. | Signal name | Color code |
|-----------------|-----------|---------|-------------|--------------|
| CW-376-5M | DATA | 1 | Shield | Shield, Blue |
| | | 2 | OUT-A | White |
| | | 3 | OUT-B | Red |
| | | 4 | IN-A | Orange |
| | | 5 | IN-B | Black |
| | | 6 | GND | Green |

REMOTE connector pinouts and cable color coding designation:

| Cable type name | Port name | Pin No. A | Pin No. B | Signal name | Color code |
|-----------------|-----------|-----------|-----------|-------------|-------------------------|
| CW-561-10M | REMOTE | 1 | 7 | VIDEO OUT | Coax. Black 1D(*)/White |
| | | 2 | 8 | TRIG OUT | Coax. Black 2D(*)/White |
| | | 3 | 9 | GND | Coax. Shield |
| | | 4 | 10 | AZIP OUT | White |
| | | 5 | 11 | SHF OUT | Yellow |
| | | 6 | 6 | GND | Coax. Shield |
| | | 7 | 1 | VIDEO IN | Coax. Black 3D(*)/White |
| | | 8 | 2 | TRIG IN | Coax. Black 4D(*)/White |
| | | 9 | 3 | GND | Coax. Shield |
| | | 10 | 4 | AZIP IN | Green |
| | | 11 | 5 | SHF IN | Blue |
| | | 12 | 12 | +12V DC | NC |

NOTE for (*):

1D – 4D: This notation indicates the number of dots printed on the cable jacket.

Chapter 5 Basic Operation

5.1 Introduction

In this chapter, all necessary operating instructions are given from getting started to turning off the system. The following panel layout illustration will give you an idea what sort of key switches and controls are available as well as their brief functional descriptions.

5.2 Control Panel Layout

The following illustration shows the layout of the control panel. All controls and key switches are grouped for respective functions.

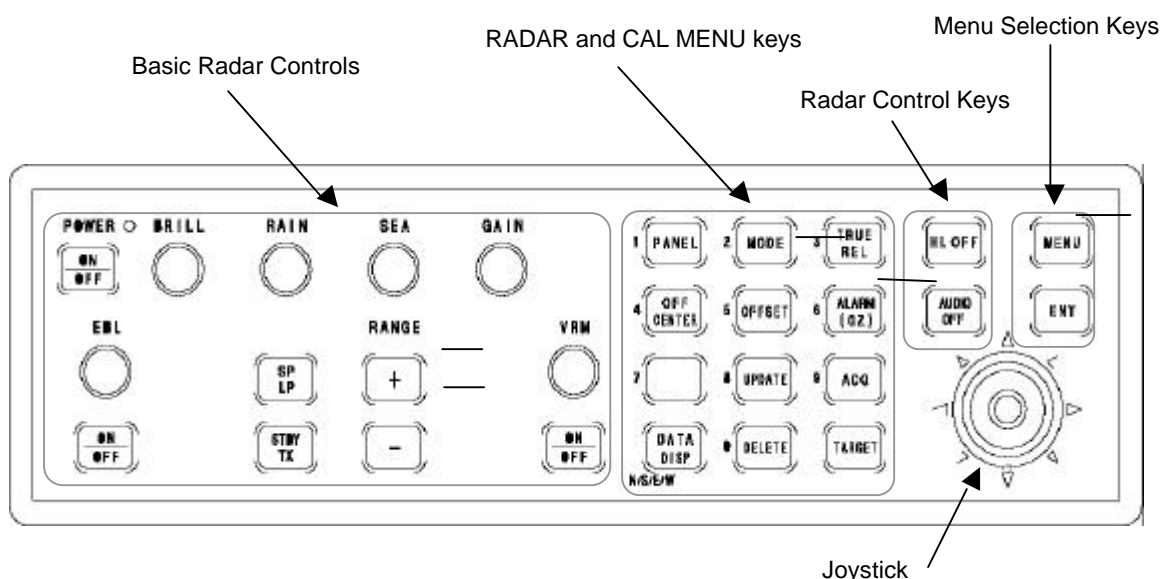


Figure 5.1 Control panel layout

5.3 Operating Controls

All necessary radar controls and functional settings can be made on the display control panel. For fundamental radar operations, such as turning on and off the radar, transmit, range change, gain control, anti-clutter rain and sea controls, the respective dedicated controls and key switches are provided, which are grouped on the left side of the control panel. For setting up various functions and ATA operations, relevant key switches and the Joystick are provided on the right side of the control panel.

SWITCHES AND CONTROLS

POWER switch

POWER



The POWER key switch turns on and off the mains supply to the radar system.

STBY/TX switch

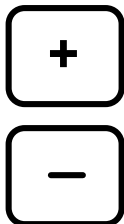
PULSE



When the system goes into standby mode after 3 minutes preheating period, the STBY/TX key switch functions as a transmission switch. To temporarily stop the transmission, press the STBY/TX key again. The system returns to standby mode.

RANGE +/- switches

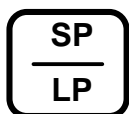
RANGE



The RANGE key changes the range scale. A press of the + key or – key increases or decreases the range scale, respectively.

SP/LP switch

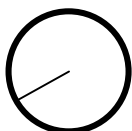
PULSE



The SP/LP key is used to change the transmission pulse length to either long or short. Default is a standard pulse length. Subsequent pressing of the key toggles the pulse length between standard and long pulses.

BRILL control

BRILL



The BRILL control is used to set the brilliance of the display tube. Turning the control CW increases the picture brilliance and CCW decreases the brilliance.

GAIN control



The GAIN control is used to vary the receiver gain. Turning the GAIN control CW increases the receiver gain, and CCW decreases the gain. Select AUTO1, AUTO2, or HARBOR by ADJUST/ADJUST MENU, the automatic gain control will come into effect. The GAIN MANUAL sign will change to GAIN AUTO on the screen. In this mode, no manual control is available.

SEA control



The SEA control is used to reduce the clutter echo returned from the sea surface. Turning the control CW reduces the clutter and its effect becomes the largest at a full CW position and minimum at a full CCW position. Select AUTO1, AUTO2, or HARBOR by ADJUST/ADJUST MENU, Harbor STC and the Automatic STC functions will come into effect. The HARBOR STC that provides a preset Anti-clutter sea effect, optimized for narrow areas. The AUTO1 and AUTO2 STC provides a hands-free Anti-clutter sea effect. The mode will display as AUTO1, AUTO2, HARBOR and SEA MANUAL in sequence. In the HARBOR and Auto Anti-clutter Sea modes, the manual control is disabled.

RAIN control



The RAIN control is used to reduce the clutter echo from rain or snow. Turning the control CW reduces the clutter echo with maximum effect at a full CW position and minimum at a full CCW position. Select AUTO1 or AUTO2 by ADJUST/ADJUST MENU, the automatic anti-rain clutter control will come into effect. The RAIN MANUAL sign will change from RAIN to RAIN AUTO on the screen. In this mode, the manual control is disabled.

EBL ON/OFF key



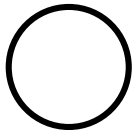
The EBL SEL key is used to switch EBL control at every press of the key. When the second EBL and Parallel Index Line (PI) feature are selected, this key is used to select these markers in the following cyclic order.

- First press: First EBL
- Second press: Second EBL
- Third press: Parallel Cursor
- Subsequent press of the key repeats the above steps.

To select the second EBL, press MENU key and select 2nd EBL item from the DISP/MARK menu. Then press ENT key and select ON. To erase the second EBL, select OFF from the menu. To select the Parallel Index line, select PI from the same menu and select ON.

EBL control

EBL



The EBL control is a rotary type control used to move the EBL position and parallel Index line.

VRM SEL key



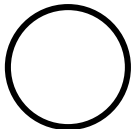
The VRM SEL key is used to switch VRM control at every press of the key. When the second VRM and Parallel Index Line (PI) feature are ON, this key is used to select these markers in the following cyclic order.

- First press: 1st VRM
- Second press: 2nd VRM
- Third press: Parallel Cursor
- Subsequent press of the key repeats the above steps.

To select the second VRM, press MENU key and select 2nd VRM from the DISP/MARK menu. Then press ENT key and select ON. To erase the second VRM, select OFF from the menu. To select the Parallel Index line, select PI from the same menu and select ON.

VRM control

VRM



The VRM control is a rotary type used to move the VRM position.

PANEL key



The PANEL key is used to change the brilliance of the panel illumination. Every press of the key will increase or decrease the brilliance in sequential order. The illumination level will be set to an appropriate level when the radar is first turned on.

OFFCENTER key



The OFFCENTER key is used to offset the picture to an assigned point determined by the cross cursor. First, move the cross cursor with Joystick to the point where the picture is to be offset. Second, press the OFF CENTER key. A further press of the key will reset the picture to the screen center.

DATA DISP .key



The DATA DISP key is used to show navigational information on the upper right of the screen. Every press of the key displays the following information in sequence.

First press: Own ship's course and speed data
 Second press: Own ship's position obtained from LORAN Receiver.
 Third press: Own ship's position obtained from (D) GPS in lat/long coordinate.
 Fourth press: Own ship's position and the distance/bearing to a waypoint en route.



Caution: The navigation data shown in this step is directly received from external navigator equipment. Note that the COG (Course Over Ground) and the SOG (Speed Over Ground) data supplied from the navigator device may slightly differ from what is shown in the top right corner of the screen as own ship's bearing and speed data.

MODE key



The MODE key is used to change the picture mode. Every press of the key will change the mode in the following sequence.

First press: H UP RM (Head Up, Relative Motion)
 Second press: N UP RM (North Up, Relative Motion)
 Third press: C UP RM (Course Up, Relative Motion)
 Fourth press: N UP TM (North Up, True Motion)
 Further press of the key returns the picture mode to the H UP RM mode.

OFFSET key



The OFFSET key is used to set the EBL 1 and VRM 1 off-centered on the screen. Every press of the key toggles the EBL 1 and VRM 1 off-centered and centered.

UPDATE key



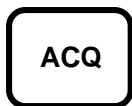
The UPDATE key is used in the EPA function, in conjunction with the TARGET key and Joystick, to correct a plotted target position. For detail, refer to Para 6.6.11 "Correcting the latest plotting position".

DELETE key



The DELETE key is used in the EPA/ATA function, in conjunction with the TARGET key, to cancel a plotted target. For detail, refer to Para 6.6 Operation of EPA or Para 6.7.4 Using ATA.

ACQ key



The ACQ key is used in the EPA/ATA function, in conjunction with the TARGET key, to acquire a target for tracking. For detail, refer to Para. 6.6 Operation of EPA or Para. 6.7.4 Using ATA.

TARGET key



The TARGET key is used in the EPA/ATA function, to assign the target number to acquire, delete or display the ATA/EPA information of each tracked target. For detail, refer to Para 6.6 Operation of EPA or Para 6.7.4 Using ATA.

TRUE/REL key



The TRUE/REL key is used to change EPA or ATA target vectors to Relative or True.

ALARM (GZ) key



The ALARM key is used to turn on and off the Guard Zone Alarm.

HL OFF Key



The HL OFF key is used to momentarily remove the Heading Line from the screen. When the key is pressed and held, the Heading Line will be removed and, when released it appears again.

AUDIO OFF



The AUDIO OFF key is used to temporarily turn off the audio alarm. A press of the key will silence the alarm.

MENU key



The MENU key is used to display the MENU on the screen. Every press of the key will change the contents of the menu as follows:

First press: RADAR MENU. This menu contains all the preset items for radar functions, sensor data display and EPA/ATA operational settings.

Second press: CAL MENU. This menu contains all technical settings for the radar operation and Performance Monitor.

ENT key



The ENT key is used to activate and fix the selected menu items by the joystick.

5.4 Getting Started

- (1) Press the POWER ON/OFF key switch. The red LED lamp lights accordingly and a 3-minute timer starts to count down. At the same time, the following information will be shown on the screen.
 - Application software name
 - Range scale
 - Range ring interval
- (2) When the countdown timer finishes, the STANDBY sign will appear on the screen.

- (3) Press the STBY/TX key to transmit. The radar starts transmission and the radar video, alphanumeric and graphic information will be shown on the screen at a preset brilliance level. Refer to Figure 5.2 for possible screen presentation.

5.5 Basic Radar Operations

Basic radar controls can be set up using dedicated keys and controls on the control panel. These include:

- Range scale selection
- Pulse selection
- Gain control
- Anti-clutter SEA
- Anti-clutter RAIN
- Bearing measurement with EBL and two EBLs
- Range measurement with VRM and two VRMs
- Picture off-centering
- Selection of presentation mode
- Guard Zone Alarm
- Control panel brilliance

All available screen presentations are shown in Figure 5.2 and respective meanings are given under the illustration.

5.5.1 Range scale selection

A press of the RANGE + or RANGE – key will increase or decrease the range scale by step.

5.5.2 Transmission Pulse selection

Press the SP/LP key if required, to change the pulse length according to your requirement. The pulse change function is available on specific range scales, ranging from 3/4 NM to 12 NM. Available pulse lengths vs range scales are shown in Table 5.1 “Range vs Transmission Pulse Length”.

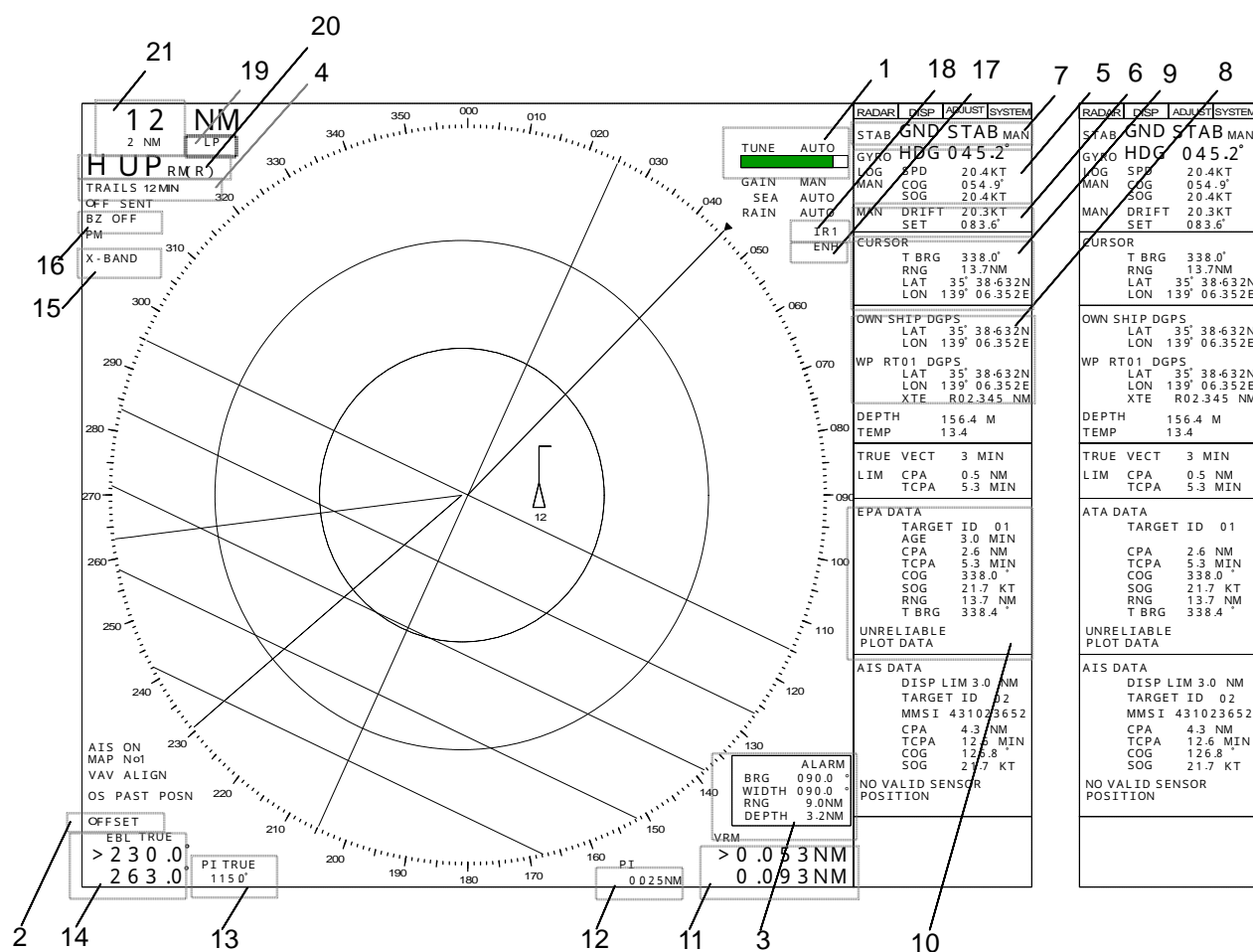


Figure 5.2 RA83P/84P/85P/93P/94P/95P On-screen information

No. Descriptions

- 1 Tuning bar graph & tuning mode display
- 2 Screen & EBL/VRM offsets display
- 3 Guard zone position (Range/Bearing)
- 4 Trail length in time
- 5 Bearing/Speed Data & signal source names
- 6 Tidal data & track mode
- 7 Own ship's data & sensor name
- 8 Ship's and Waypoint position data with position sensor name
- 9 Cross cursor position data (lat/long or Range/Bearing)
- 10 EPA (ATA) data

No. Descriptions

- 11 VRM (No.1/No.2) distance data
- 12 Parallel Index Line interval
- 13 Parallel Index Line bearing
- 14 EBL (No.1/No.2) bearing data
- 15 TX Frequency Band display
- 16 Electronic Buzzer status
- 17 Picture Enhancement status (ON)
- 18 Interference Rejection status
- 19 TX Pulse length status
- 20 Picture mode status
- 21 Range scale and Rings interval display

Table 5.1 Range vs Transmission Pulse Length

| RANGE (NM) | Pulse code | Pulse length (6/12kW) | Pulse length (25kW) |
|------------|------------|-----------------------|---------------------|
| 0.125 | SP | 0.08 us | 0.08 us |
| 0.25 | SP | 0.08 us | 0.08 us |
| 0.5 | SP | 0.08 us | 0.08 us |
| 0.75 | SP | 0.08 us | 0.08 us |
| | M1P | 0.25 us | 0.3 us |
| 1.5 | SP | 0.08 us | 0.08 us |
| | M1P | 0.25 us | 0.3 us |
| 3 | M1P | 0.25 us | 0.3 us |
| | M2P | 0.5 us | 0.6 us |
| 6 | M1P | 0.25 us | 0.3 us |
| | M2P | 0.5 us | 0.6 us |
| 12 | M2P | 0.5 us | 0.6 us |
| | LP | 1.0 us | 1.2 us |
| 24 | LP | 1.0 us | 1.2 us |
| 48 | LP | 1.0 us | 1.2 us |
| 64 (6KW) | LP | 1.0 us | — |
| 72 (12KW) | LP | 1.0 us | — |
| 96 (25KW) | LP | — | 1.2 us |

5.5.3 Gain control

The GAIN control is used to change the receiver gain. The gain control can be switched to manual or auto mode by ADJUST/ADJUST MENU. When the equipment is turned on at first, the gain control will be defaulted to manual mode.

Set the gain control as appropriate to your operational needs. As a standard setting, turn the GAIN control clockwise to 3/4 of the full excursion. This provides slight noise speckles on the mid ranges and adequate speckles on the long ranges.

To set the auto gain mode, select AUTO1, AUTO2, or HARBOR by ADJUST/ADJUST MENU. The receiver gain will be automatically set and the manual gain control will accordingly become inactive.

5.5.4 Anti-clutter SEA control

The Anti-clutter SEA control is used to reduce the clutter echo appearing around the center of the screen, which is caused by the echo return from the sea surface. The effect of the control is highest at the center of the screen and reduces with distance. The Anti-clutter SEA control is effective up to approximately 6 NM, which can be switched to either manual or auto mode by ADJUST/ADJUST MENU. When first

turned on, the anti-clutter sea control is defaulted to manual mode. To set the auto Anti-clutter mode, select AUTO1, AUTO2, or HARBOR by ADJUST/ADJUST MENU. The receiver gain will be automatically set and the manual SEA clutter control will accordingly become inactive. The HARBOR STC provides a preset Anti-clutter sea effect, optimized for narrow areas. The AUTO1 and AUTO2 STC provides a hands-free Anti-clutter sea effect. The mode will display as AUTO1, AUTO2, HARBOR, and MANUAL. In HARBOR and Auto Anti-clutter Sea modes, the manual control is set ineffective.

5.5.5 Anti-clutter RAIN control

The RAIN control is used to reduce the clutter echo appearing on the screen caused by the rain or snow. The effect of the anti-clutter rain control increases as you turn the control clockwise and is the greatest at a fully clockwise position. The anti-clutter RAIN control can be switched to either a manual or auto mode by ADJUST/ADJUST MENU.

When first turned on, the anti-clutter RAIN function is defaulted to manual mode. To set the auto RAIN-clutter control, select AUTO1 or AUTO2 by ADJUST/ADJUST MENU. The clutter echo from rain or snow will be reduced automatically and the manual rain clutter control will become inactive.

5.5.6 Bearing measurement using a single EBL

- (1) Activate the 1st EBL from the DISP/MARK menu with select ON. The EBL will be displayed in a dashed line with the bearing display in the bottom left of the screen. An arrow mark will be shown on the front of the digital display to indicate the EBL is active.
- (2) Select the bearing mode if necessary, either RELATIVE or TRUE by DISP/[BRG TRUE/REL] MENU.
- (3) Rotate the EBL control to measure the bearing of a target. To measure a single target, always set the EBL on the center of the target. To measure the bearing of the edge of a landmass, move EBL towards the inside of the landmass by half of the aerial horizontal beam width.
- (4) To erase the EBL, select OFF from the DISP/MARK/1st EBL menu item.

5.5.7 Bearing measurement using two EBLs

- (1) Activate the 2nd EBL from the DISP/MARK menu with select ON. The 2nd EBL will be shown with the 1st EBL in a dotted line with the bearing display underneath the 1st EBL bearing display. An arrow mark will be shown on the front of the digital display to indicate the selected EBL is active.

- (2) Use the same step as step (2) and (3) in the 1st EBL operation.
- (3) To switch the active EBL to another, press the EBL SEL key.
- (4) To erase the second EBL, select OFF from the DISP/MARK/2nd EBL menu item.

5.5.8 Range measurement using Range Rings

Display the RANGE RINGS on the screen from the DISP/MARK menu with select ON. The range ring's interval is indicated on the top left corner of the screen under the range indication. Approximate target range can be estimate with range rings.

5.5.9 Range measurement using VRM

- (1) Activate the 1st VRM from the DISP/MARK menu with select ON to show VRM on the screen. The VRM will be shown in a dashed line with the distance displayed in the bottom right of the screen. An arrow mark will be shown in front of the digital display indicating that VRM is active.
- (2) Rotate the VRM control to measure the distance to a target. Always place the VRM on the right front of the target.
- (3) To erase the VRM, select OFF from the DISP/MARK/1st VRM menu item.

5.5.10 Range measurement with two VRMs

- (1) Activate the 2nd VRM from the DISP/MARK menu with select ON. The 2nd VRM will be shown with 1st VRM, in a dotted line with the distance displayed shown underneath the 1st VRM display. An arrow mark will be shown on the front of the digital display to indicate which VRM is active to control.
- (2) Rotate the VRM control to measure the distance to a target. Always place the VRM on the right front of the target.
- (3) To switch the active VRM to another, press the VRM SEL key.
- (4) To erase the second VRM, select OFF from the DISP/MARK/2nd VRM menu item.

5.5.11 Measuring the distance and bearing between any two points by offset 1st EBL / 1st VRM

- (1) Activate the 1st EBL and 1st VRM from the DISP/MARK menu with select ON to display 1st EBL and 1st VRM.
- (2) Place the cross cursor on the first target.
- (3) Press the OFFSET key. The origin of 1st EBL / 1st VRM is now set on the first target.
- (4) Move 1st EBL to fall in the center of the second target.

- (5) Move 1st VRM to touch the right front of the second target. The distance between the two targets will be shown on the bottom right center of the screen.

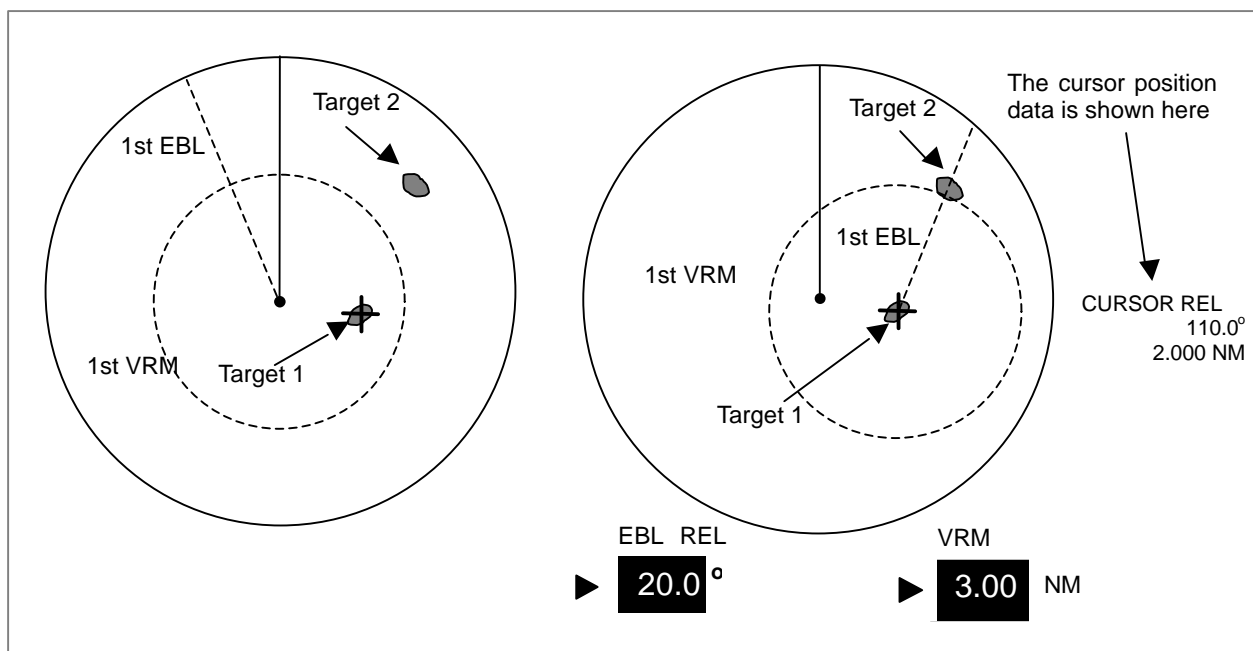


Figure 5.3 Measuring the distance between two points

5.5.12 Picture off-centering

The radar picture can be offset to any position within 2/3 of the screen radius. Use the following procedure.

- (1) Move the cross cursor to a desired point to be offset.
- (2) Press the OFF CENTER key. The entire radar picture will be moved to the specified point.
- (3) A further press of the key will reset the picture to the center position.

5.5.13 Selection of presentation mode

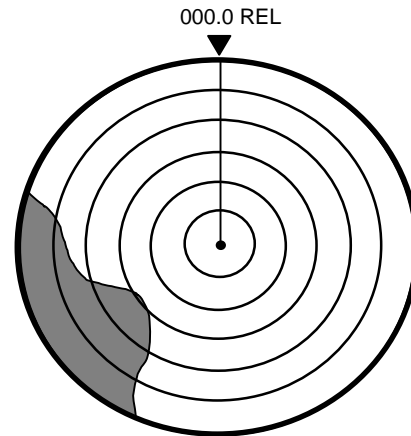
The following four kinds of presentation modes are available.

- (1) Head Up, Relative Motion
- (2) North Up, Relative Motion (Note: Bearing information must be provided)
- (3) Course Up, Relative Motion (Note: Bearing information must be provided)
- (4) True Motion (Note: The bearing and speed information must be provided)

To select the presentation mode, press the MODE key. Every press of the key will change the presentation mode in the above sequence.

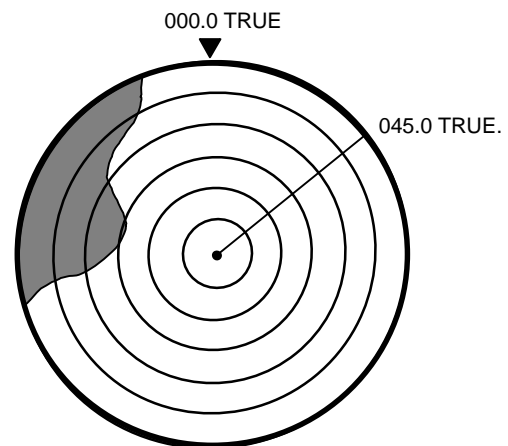
Head Up, Relative Motion (H UP RM)

Ship's position and heading line are always fixed to the screen center and 0 degree of the bearing scale, respectively. Bearings of the objects displayed on the screen are relative to ship's heading. When own ship changes her course, all displayed objects will move in azimuth, accordingly. (Bearing Un-stabilized)



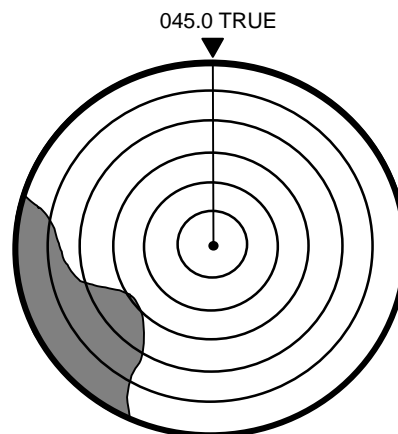
North Up, Relative Motion (N UP RM)

Own ship's position is fixed to the center of the screen, meanwhile, the azimuth bearing scale is stabilized in which true north refers to the cursor scale of 000.0 degree. When own ship changes her course, all displayed objects will stay stationary in azimuth, accordingly. (Bearing stabilized) To allow the bearing to be stabilized, the true bearing data must be provided from a bearing sensor such as a gyrocompass.



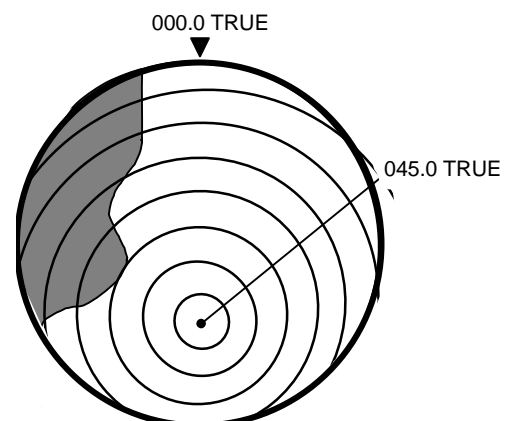
Course Up, Relative Motion (C UP RM)

The picture mode is the same as the North Up, Relative Motion mode except, the ship's intended course pointed by the ship's heading line is brought to top of the display.



True Motion (N UP TM)

Own ship and each target moves with its true motion on the radar screen. When own ship reaches 2/3 of the screen radius, it is reset backwards to a specified point to repeat the display. To achieve the True Motion display, a bearing sensor and a speed sensor must be connected to the radar system to provide true bearing and true speed information.



5.5.14 Setting the Guard Zone

The Guard Zone Alarm warns the operator a target has entered the preset alarm zone. When the target stays in the zone for more than 8 seconds, the ALARM sign will flicker and an audio alarm sounds. Press the AUDIO OFF key to silence the alarm.

To set up the position of the Guard Zone

- (1) Press the ALARM (GZ) key. This allows the EBL and VRM controls to be used for moving the Alarm Zone in azimuth and range, respectively.
- (2) Move the EBL control to set the position of the Guard Zone in azimuth. The center bearing of the Guard Zone will be displayed in the lower right corner of the screen.
- (3) Move the VRM control to set the position of the Guard Zone in range. The distance of the outer edge of the Guard Zone will be displayed in the same place as the bearing display. The minimum distance is limited to 0.6 NM.

To set up the depth and width of the Guard Zone

(Reference drawing: Figure 5.4 The outline of the Guard Zone Alarm)

- (1) Press the EBL SEL key and rotate the EBL control to set up the width of the alarm zone. An arrow mark will be shown on the front of the WIDTH to indicate width is active to control. A further press of the key will return to control the Guard Zone in azimuth.
- (2) Press and hold the VRM SEL key and rotate the VRM control to set up the depth of the alarm zone. An arrow mark will be shown on the front of the DEPTH to indicate depth is active to control. A further press of the key will return to control the Guard Zone in range. The minimum distance of the inner zone to own ship is limited to 0.5 NM.
- (3) Press the ENT key to fix the settings. The Guard Zone will be shown on the screen.



CAUTION: In the following case, the alarm function will become inoperative. The ALARM range and bearing displays accordingly flicker to notify that the function is inoperative.

- When the alarm zone is set beyond the viewable screen area caused by improper range scale setting such as, the range scale is too short, off-centering is too much, etc.

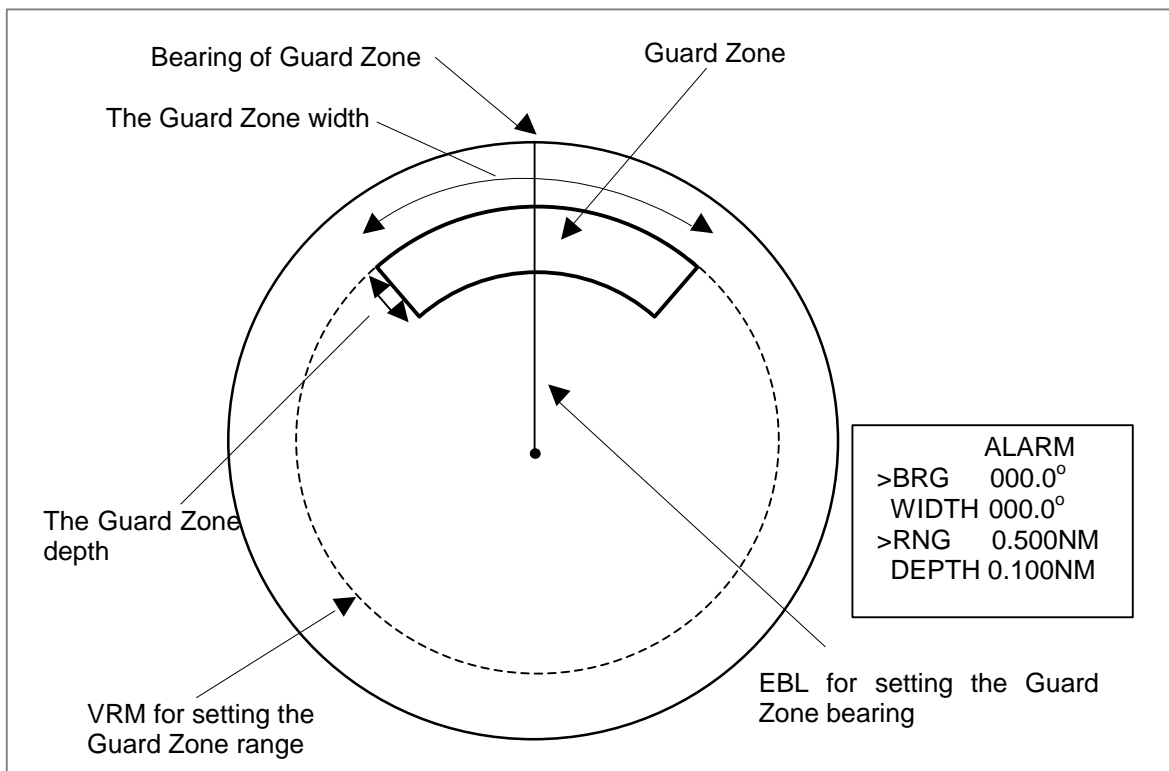


Figure 5.4 The outline of the Guard Zone Alarm

5.5.15 Control panel brilliance

The control panel illumination is set by default. To change the brilliance, use either the following procedure.

- (1) Keep pressing the PANEL key to change the panel illumination in 10 cyclic steps, starting from OFF, increasing, decreasing and finally to OFF again.

5.5.16 Displaying the navigational data

Navigational data such as own ship's position, waypoint position and the distance and bearing to a waypoint can be shown on the screen. Press the DATA DISP key to display this data on the screen.

NOTE:

1. A navigator unit must be connected to the processor unit.
2. The serial data format must be selected. Refer to Para 6.3 "SYSTEM: I/O SETUP MENU" for detail.

Each press of the DATA DISP key changes the contents of the navigation display in the following sequence.

OFF: The navigation display is turned off.

OWN SHIP (COG/SOG): Own ship's bearing and speed.

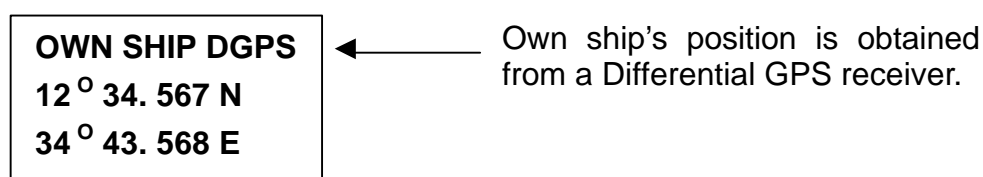
OWN SHIP (TD): Own ship's position in the LOP (Lane of Position) coordinate.

OWN SHIP (L/L): Own ship's position is expressed in latitude and longitude.

OWN SHIP (L/L) / WP (Bearing/Distance): Own ship's position in latitude/longitude and waypoint position in bearing and distance.

OWN SHIP (L/L) / WP (L/L): Own ship's position and waypoint position in latitude/longitude grid.

OWN SHIP'S POSITION DISPLAY



WAYPOINT POSITION DISPLAY

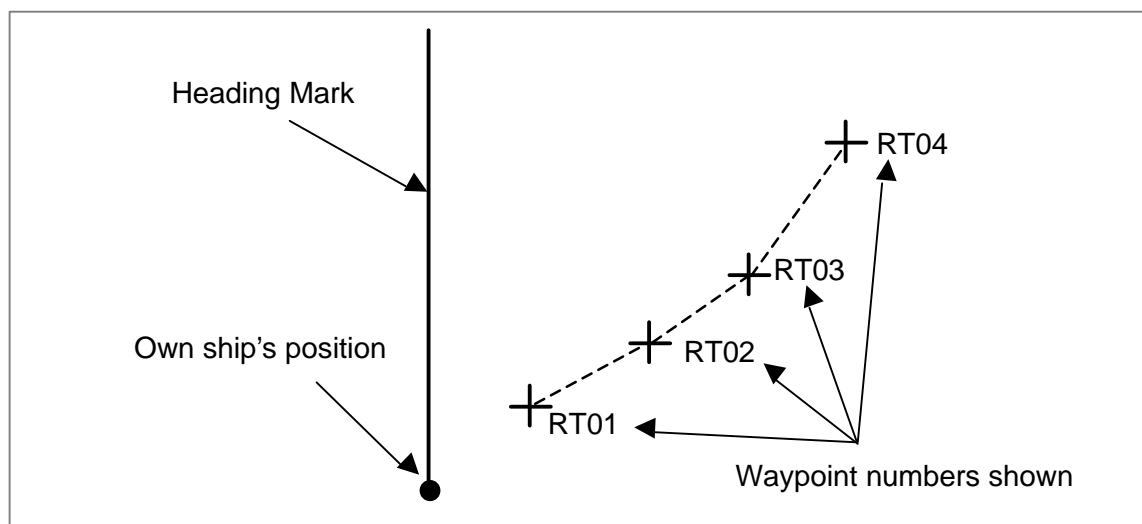
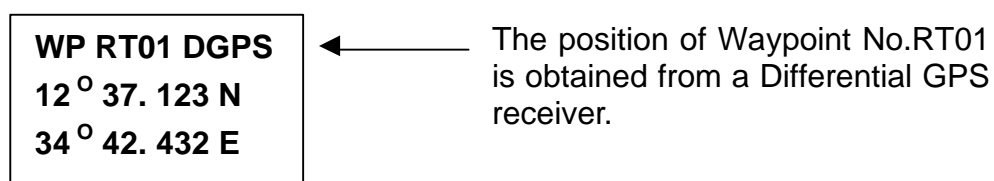


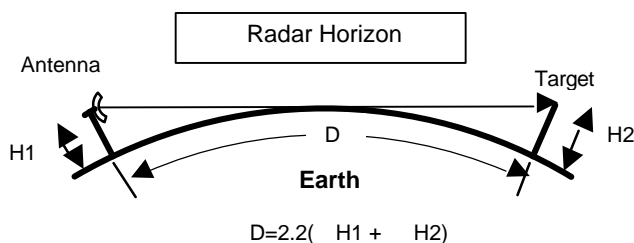
Figure 5.5 The waypoint number display on the screen

APPENDIX 1: Interpretation of Radar Images

Factors that affect the radar detection range

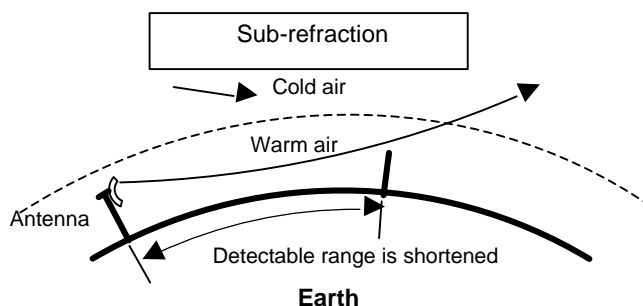
Radar Horizon

The radar uses microwave energy that travels in a straight line like light. Light is reflected towards the surface of the earth due to the temperature, humidity, and the atmospheric pressure changes in the air. This causes the visual range to extend beyond the physical horizon. This is called the optical horizon. Microwave has the same effect and this is called the radar horizon. Meanwhile, its wavelength is longer than that of light. The radar visual range is therefore longer than light by approximately 6%.



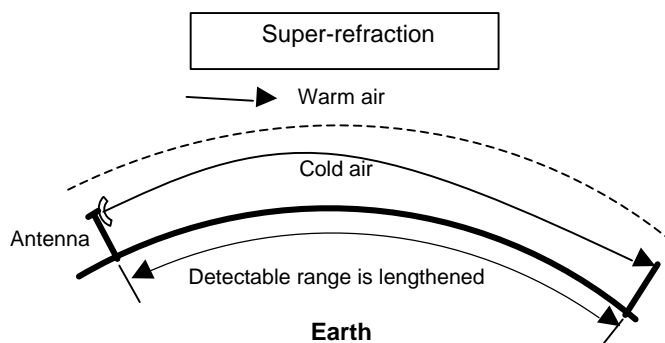
Sub-refraction

When cold air flows over a warm surface, the microwave is bent upwards as shown in the figure. This phenomenon is called sub-refraction. As a result, the detectable range may be reduced. This situation is likely to occur in the Polar Regions, or in warm current waters where cold air from the Polar Regions flow over the sea surface.



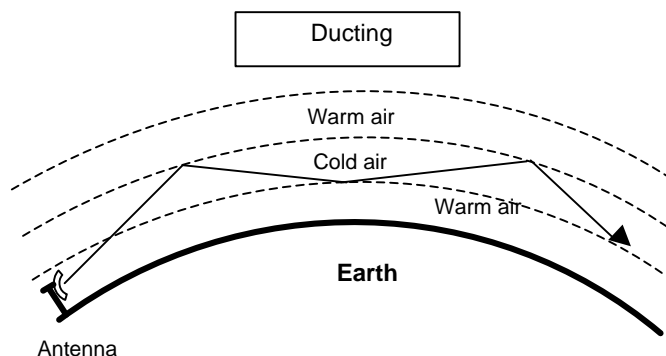
Super-refraction

When the air being warmed up in an inland area flows over the cold sea, the microwave is bent downwards. In this case, a detectable radar range may increase. This situation may occur produced in warm coastal regions, and it becomes noticeable as the temperature difference becomes larger.



Ducting

When two or more layers of different temperature come into contact with one another, the radar wave may be reflected from the boundary surface where different refraction indices exist. As a result, the microwave propagates along the curvature of the earth while being reflected on the wave passage situated between the interface and the surface of the earth. This passage is called "Duct", and an abnormal propagation of the radio wave caused by the duct is called "Ducting". If the air layers with mutually different temperature or atmospheric pressures are alternately present along the different altitudes, radar may be able to detect a target far beyond its maximum detectable range.



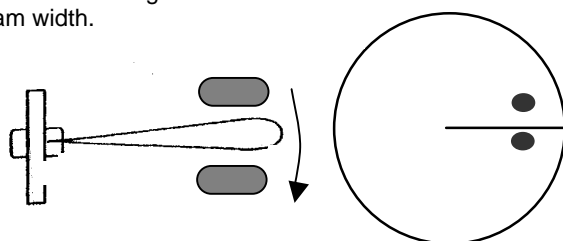
Picture resolution

The picture resolution depends on the bearing and range discriminations that are solely determined by the antenna horizontal beam width and the transmission pulse length. These factors are defined in the following explanations and illustrations.

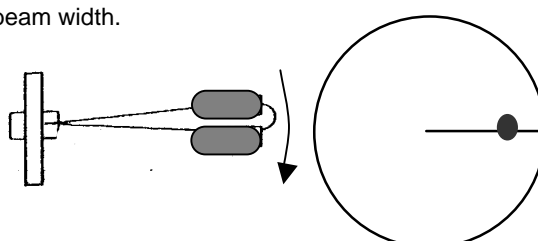
(1) Bearing discrimination

The bearing discrimination is defined as the minimum bearing where two targets of the same distance are displayed as two independent images on the screen. The bearing discrimination is determined by the aerial horizontal beam width.

The distance between two targets in azimuth is longer than the radar beam width.



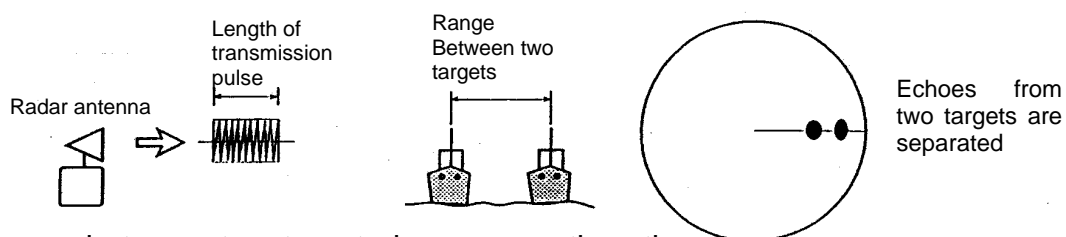
The distance between two targets in azimuth is shorter than the radar beam width.



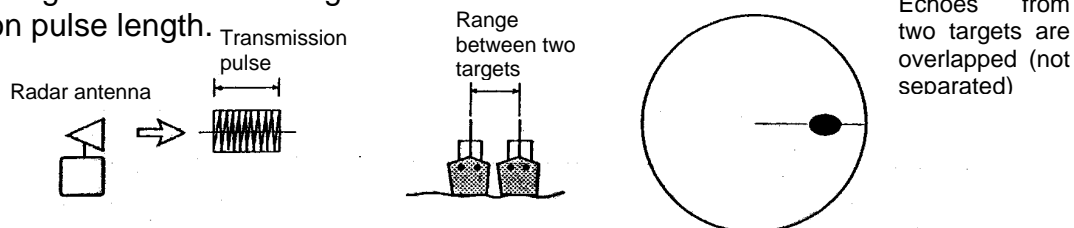
(2) Range discrimination

The range discrimination is defined as the minimum distance where two different targets situated in line on the same bearing are shown separated. The range discrimination is dependent on the transmission pulse length.

When the range between two targets is wider than the transmission pulse length.

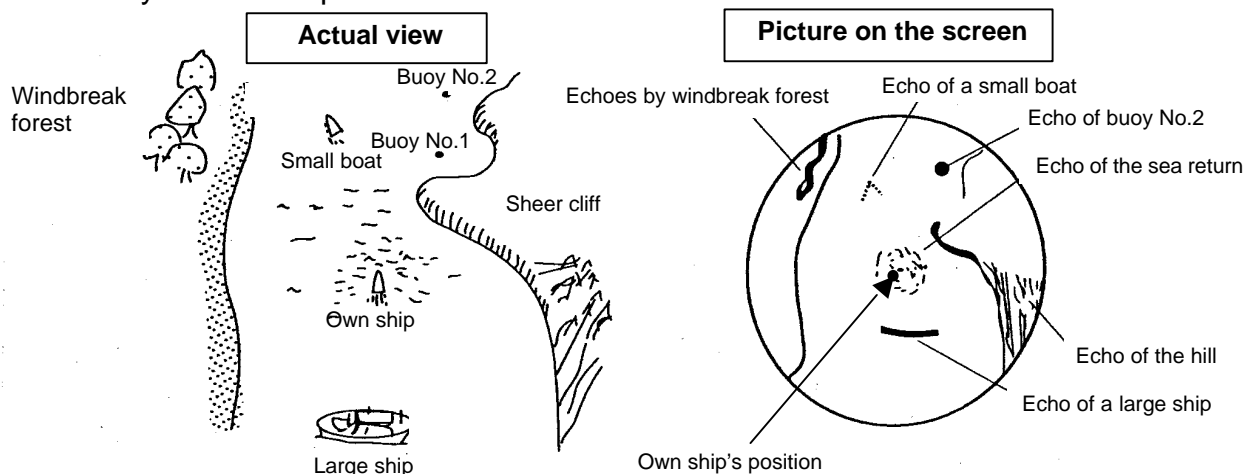


When the range between two targets is narrower than the transmission pulse length.



Reading the radar images

The following pictures illustrate how the radar picture is constituted from an actual situation around your own ship.

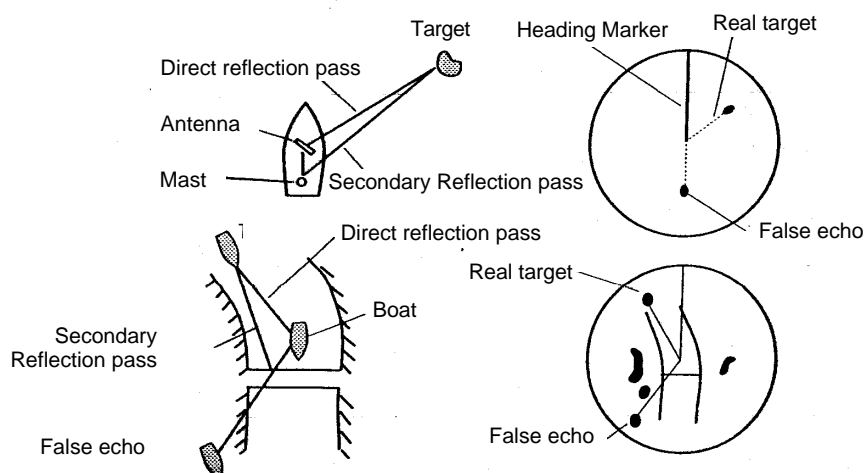


- The buoy No.1 is not detected because the cape blocks it.
- The echo of the large boat is painted similar to its actual profile because of short distance.
- The echo of a small boat is shown as a spot because it has a small echoing area.
- The hill located on the starboard (in the bearings of 90 deg to 130 deg) has a deep forest zone, and its echoing area is large. It is represented as wide spreading echoes on the screen.
- Since the sand beach on the port side is deep, but is not topographic. The echoes are shown weak.
- The windbreak forest produces strong echoes, and it is shown as massive echoes in high contrast.
- The echoes reflected from the sea surface change from time to time, depending on the wind speed and direction. These echoes are shown as a group of spots.

False echoes

The operator should be fully aware of various false echoes caused by the radar performance, terrain and structures on the land, as mentioned below.

(1) False echo caused by secondary reflection

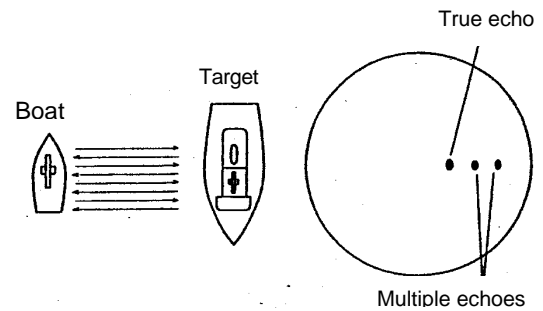


An example of false echo caused by the radar beam reflected by an aft mast.

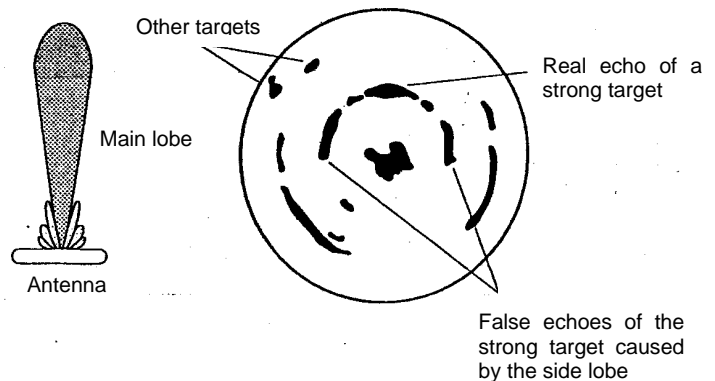
An example of a temporarily produced false echo caused by the radar beam reflected by a large bridge.

(2) False echo caused by multiple echoes

When a boat passes near a large boat, radio waves are repeatedly reflected between own boat and the nearby boat, causing several echoes at regular intervals to appear in the same bearing but at multiple distances. These false echoes produced by multiple reflections are called multiple echoes. In this case, the real target is easily detected. When the reflection case disappears when the boat moves, the reflection echoes on the display have changed, even if these multiple echoes are produced, the true image is easily detected. The boat has changed her course. For this reason, the true image can easily be identified.

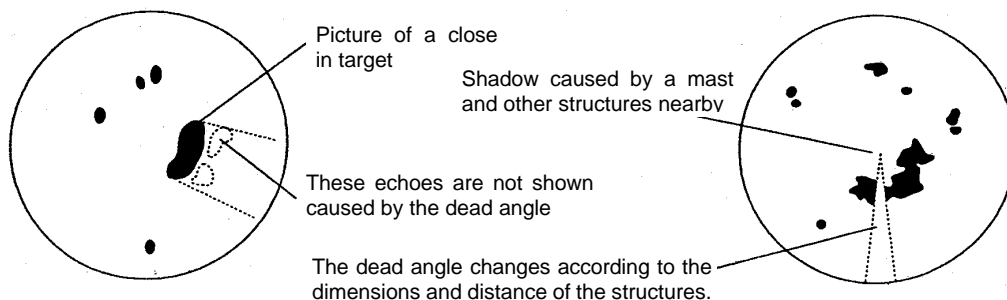


The radio beam emitted from a radar antenna contains some residual smaller beams on both sides of the main beam. These components are called the side lobes. A closely located target with high reflectivity can be displayed as an arc caused by the side lobes. To reduce these false echoes, reduce the gain slightly or apply A/C sea control.

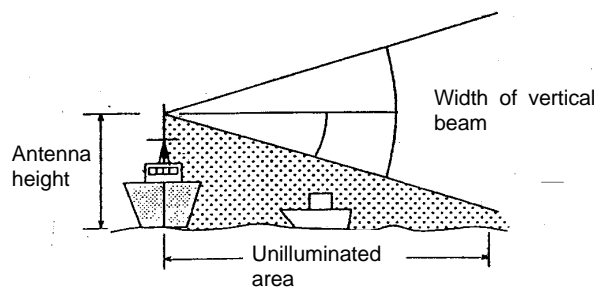


(4) Shadow and dead angle

If the funnel, mast or other structures are located near a radar antenna, the radar beam will be blocked, causing a shadow area where no object will be detected by the radar. The angle of the shadow is called the dead angle. To avoid the shadow, the radar antenna position should be changed to a better place to minimize this effect. If this is not possible, the operator should be aware this dead angle exists while operating the radar.



Height of antenna affects the short range target detection. If the antenna is mounted too high, the radar beam may skip the target, causing no echo detection. The vertical beam width of the radar antenna also affects the close range detection.



APPENDIX 2: Receiving the Radar Beacons and SART

The X-band radar system is required to be capable of receiving signals emitted from a Radar Beacon and a SART (Search and Rescue Transponder). To receive those signals by the radar system, use the following procedures.

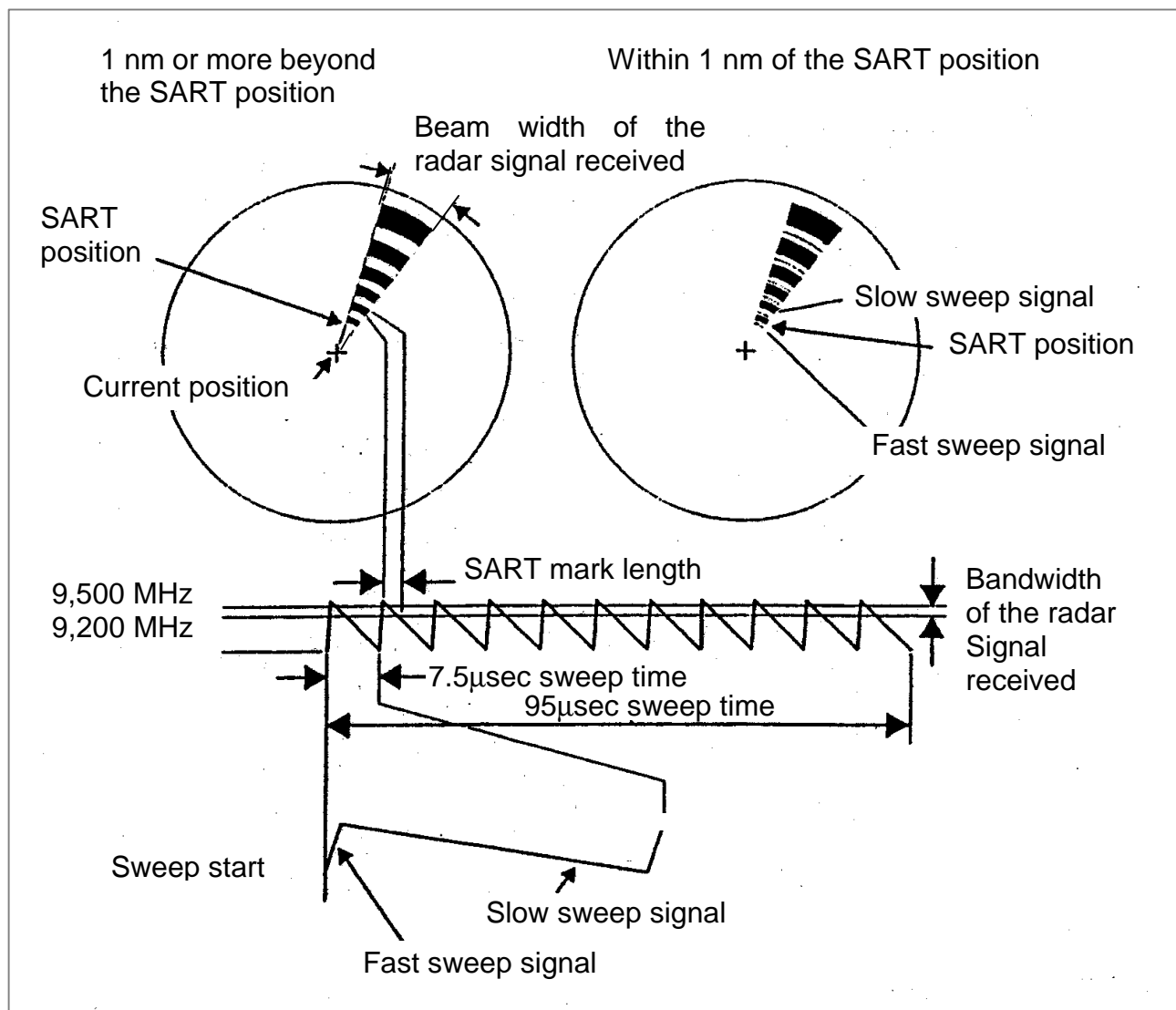
- (1) Set the range scale to 6 or 12 NM.
- (2) Turn off the Interference Rejection function from DISP/ECHO/IR menu item. Refer to Para. 6.1.2 "IR (Interference Rejection).
- (3) In case the radar picture is obscured with too many echo signals, detune the receiver a little for better observation.
- (4) When your vessel approaches the transmitting Radar Beacon or the SART, the echoes will become blurred in an arc. For better observation of those signals, adjust the Gain, Anti-clutter Sea and RAIN controls, as appropriate.

About SART

According to the GMDSS (Global Maritime Distress and Safety Systems) requirement, the IMO/SOLAS class ships must be equipped with a SART. When a ship is in distress, a signal will be automatically emitted from the SART so that other ships and/or aircrafts can identify its location. When your ship carrying the X-band radar comes within 8 miles of a ship in distress, the SART picks up the radar signal and responds to it. The signal consists of 12 sweeps and is emitted in the frequency range of 9.2 GHz through to 9.5 GHz. The SART has two sweep times that switch from slow sweep (7.5 us) to fast sweep (0.4 us) and vice versa, according to the distance. When the radar receives this signal, a line of 12 dots, which is equally spaced at about 0.64 NM, appears on the screen. The nearest blip of the SART indicates the location of the ship in distress. When your vessel comes within 1 NM to the SART, a fast sweep signal is displayed on the radar and a thin line connects the 12 blips.

Actual location of the ship carrying the SART

If your vessel is located at 1 NM or more away from the SART, the position at which the first echo is displayed is 0.64 NM behind the actual SART position when the 12 SART echoes are identified. If your vessel comes within 1 NM from the SART, the fast sweep signal is indicated. The position of this echo is displayed 150 meter beyond the actual SART position.



The SART signal presentation and its signal timing

Chapter 6 Using The Menu



[Common key operation]

All menu-driven functions can be selected by the same key sequence. In the menu, there are four main menus available such as RADAR, DISP (Display), ADJUST, and SYSTEM.

The RADAR menu provides operational sub menus, used in setting up parameters for picture stabilizing mode and EPA/ATA functions.

The DISP menu provides sub menus that set on-screen marks, cursor, echo trails, plotting mode selection, etc. all used for screen display.

The ADJUST menu is protected from ordinary operations. This menu provides operational sub menus for adjustments and presets for the screen display, including video contrast controls for radar, markers, alpha-numeric characters, presetting manual/auto tuning functions, manual/auto GAIN, SEA, RAIN functions, etc.

The SYSTEM menu is also protected. The menu provides technical sub menus used for setting up various technical parameters of the radar system during installation or post repair adjustments.

To select the menu items, use the following procedures.

(1) Press the MENU key and use the Joystick to select an item. The selected item is highlighted. Subsequent pressing of the MENU key brings back to the normal operation.

- 1) Press the MENU key.
- 2) Highlight a desired menu by pressing the Joystick.
- 3) Highlight a desired sub menu or item by pressing the Joystick up or down.
- 4) Press the ENT key to activate the selection sequence or select the sub menu.
- 5) Press the Joystick up or down to select a status or parameter of the item selected. When the parameters are identified with numbers (1:PANEL, 2:MODE, 3:TRUE/REL, etc.) the numerical keypad can also be used for the selection.
- 6) Press the ENT key to fix the selection. The highlighted part is removed and its function becomes effective.
- 7) Press the Joystick up or down to select the item.
- 8) Press the ENT key to activate the selection sequence.
- 9) Press the Joystick up or down to select a status or parameter of the item selected. When the parameter is numerical, the numerical keypad can be used for the selection.
- 10) Press the ENT key to fix the selection.

NOTE: When you have finished setting the relevant menu functions, exit the menu by pressing the MENU key to make sure the settings become active.

6.1 RADAR Menu

The RADAR menu includes the setting and display items used for the ordinary radar operations.

6.1.1 Picture Stabilization

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|--------------------------|-----------------------------|-----------------------|
| SEA STAB/GND STAB | Stabilizing mode indication | <u>SEA</u> GND (Note) |

NOTE 1: The under lined is a default value.

NOTE 2: To change the selection, go to DISP=>SEA STAB/GND STAB.

SEA (Sea Stabilized mode): The radar picture is stabilized with respect to the water with signals supplied from a bearing sensor and a water speed sensor. The current direction (Set) and speed (Drift) are combined in the motion of targets on the screen.

GND (Ground Stabilized mode): The radar picture is stabilized with respect to the ground with the signals supplied from a bearing sensor and a speed sensor (either a water speed sensor or a ground speed sensor). When a water speed sensor is used, a tidal effect causes the deviation in picture stabilization. In such a case, the Set and Drift correction must be made by manual means or NMEA signal. Refer to Para 6.4.1.3 and 6.4.1.4 for details.

6.1.2 Ship's Heading

GYRO HDG

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|-------------------------|------------------|
| GYRO HDG | Gyro heading indication | None |

NOTE: *This item is for display only.*

6.1.3 Ship's Speed

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|----------------------|-------------------------|------------------|
| LOG/DOLOG SPD | Ship's Speed indication | LOG or DOLOG |

LOG: Magnetic Log or Mechanical Log.

DOLOG: Doppler Log.

NOTE: *This item is for display only. To change the selection, go to SYSTEM => I/O SETUP => SEA STAB SPD or GND STAB SPD.*

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------|------------------|
| MAN SPD | Manual Speed | 0 to 99.9 (KT) |

NOTE: *To set the speed, go to SYSTEM => IO SETUP => SEA STAB SPD.*

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|-------------------------------|------------------|
| MAN COG | Course Over Ground indication | N.A. |
| SOG | Speed Over Ground indication | N.A. |

NOTE: *This item is for display only.*

6.1.4 Set and Drift

When the GND STAB (Ground Stabilized) mode is selected via SYSTEM/IO SETUP/GND STAB SPD, the Set and Drift data is displayed.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|--------------------------|-------------------|
| MAN SET | Direction of the current | 0 to 359.9 (Deg.) |
| DRIFT | Speed of the current | 0 to 99.9 (KT) |

To set or change setting, go to SYSTEM/IO SETUP/GND STAB SPD.

6.1.5 Cursor Position

| <u>Indication</u> | <u>Meaning</u> |
|---------------------|-----------------------------------------------|
| CURSOR T BRG | Cursor True or Relative(R) Bearing indication |
| RNG | Cursor Range |
| LAT | Cursor Latitude |
| LON | Cursor Longitude |

NOTE: To use this function the heading and latitude/longitude data must be supplied from the gyro/log interface unit KSA-08A and a GPS or Loran-C navigator unit.



CAUTION:

- When no bearing data is entered from the gyrocompass, the latitude and longitude display will turn to "XXX.XX.XXX".
- The position data may deviate when a navigator unit is used in latitude above 70 degrees.

[Data Indication]

| | |
|----------------------|-------------------------------------------------------------------------|
| OWN SHIP DGPS | Own Ship Information (Input Device Name) (Select with DATA DISP key) |
| LAT | Latitude/ COG/LOP1 |
| LON | Longitude/ SOG/LOP2 |
| WP RT01 DGPS | Waypoint Information/Route Name/Input Device |
| LAT | Latitude/Bearing |
| LON | Longitude/Range |
| XTE | Cross Track Error |
| DEPTH K (W) | Depth |

NOTE: K means the depth from the Keel, W means the depth from Water surface.

| | |
|-------------------|-------------------|
| WATER TEMP | Water Temperature |
|-------------------|-------------------|

6.1.6 Vector Time

The vector indication mode can be set with the TRUE/REL key. A vector time can be set from the following menu.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|------------------------|------------------------|-----------------------------------------------------------|
| TRUE (REL) VECT | Vector Indication Time | <u>OFF</u> , 30SEC, 1MIN, 3MIN, 6MIN, 12MIN, 30MIN, 60MIN |

6.1.7 CPA Alarm Limit

This function is used to set up the warning limit at which the CPA and TCPA alarms are activated. Use the following procedure to set up.

- (1) Highlight the item and press the ENT key.
- (2) Move the Joystick up or down to select the value and press the ENT key.
- (3) Setting ranges for CPA and TCPA are as follows:

ATA CPA: 0.00 NM to 19.9 NM.

ATA TCPA: 1 Minute to 63 min.

AIS LIM CPA: 0 NM to 19.9 NM

AIS TCPA: 1 to 63 min.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|------------------------------|------------------|
| LIM CPA | Limit for CPA (NM) | 0 to 19.9 (NM) |
| TCPA | Limit for Time to CPA (Min.) | 1 to 63 (Min.) |

6.1.8 Data indication

The following data are shown in the data window.

| | |
|---------------------|-----------------------------------------------------------------|
| EPA/ATA DATA | Plot Mode (Select with DISP/NAV/PLOT MODE menu. ATA: option) |
| TARGET ID | ID for Operating Target |
| AGE | EPA Life |
| CPA | Closest Point of Approach |
| TCPA | Time to CPA |
| CSE/COG | Course/Course Over Ground |
| STW/SOG | Speed Through Water/Speed Over Ground |
| RNG | Range |
| T/R BRG | True or Relative(R) Bearing |

| | |
|------------------|-------------------------------------------------------------------------------------------------------------------------------|
| AIS DATA | (ON/OFF with DISP/NAV/AIS menu) |
| LIM | Indicating Range ----- 1.0 to 6.5 (NM) AIS data will be displayed inside the range of LIM setting. |
| TARGET ID | Target ID for Data Indication ----- 1 to 20 Set the ship's ID to data display. |
| MMSI | Ship's ID |
| CPA | Closest Point of Approach |
| TCPA | Time to CPA |
| CSE/COG | Course/Course Over Ground |
| STW/SOG | Speed Through Water/Speed Over Ground |

6.2 DISP Menu

The DISP menu has three sub menus; MARK, ECHO, and NAV. Each menu has the following sub menus.

6.2.1 MARK

The MARK menu has various markers such as VRM (Variable Range Marker), EBL (Electronic Bearing Line), Stern Marker and Cursor L/L (Position Cursor) that can be turned on or off. This menu also has the bearing mode control that affects the bearing indication of the EBL and vectors.

6.2.1.1 VRMs and EBLs

VRM 1 and 2, EBL 1 and 2, and PI (Parallel Index Line) can be set with the menu.

| | | |
|----------------|------------------------------|-----------------|
| 1st VRM | Variable Range Marker No.1 | <u>OFF</u> , ON |
| 2nd VRM | Variable Range Marker No.2 | <u>OFF</u> , ON |
| 1st EBL | Electronic Bearing Line No.1 | <u>OFF</u> , ON |
| 2nd EBL | Electronic Bearing Line No.2 | <u>OFF</u> , ON |
| PI | Parallel Index Line Cursor | <u>OFF</u> , ON |

NOTE: *The underlined items are default values.*

To change the bearing and interval of the parallel index line, use the following procedure:

- 1) Set the screen to normal display mode.
- 2) Keep pressing the EBL SEL key until the wedge symbol points to the letters PI, shown in the left bottom of the screen. In the same manner, press the VRM SEL key until the wedge symbol points to the letters PI in the right bottom of the screen.
- 3) Rotate the EBL control to move the PI in azimuth and the VRM control to change the interval of the index lines.

6.2.1.2 VRM Unit

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------|--------------------|
| VRM UNIT | Unit for VRM | <u>NM</u> , KM, SM |

6.2.1.3 RANGE RINGS

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|--------------------|----------------|------------------|
| RANGE RINGS | Range Rings | <u>OFF</u> , ON |

6.2.1.4 BRG TRUE/REL (Bearing True or Relative)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|---------------------|----------------|-----------------------------------------|
| BRG TRUE/REL | Bearing Mode | <u>REL</u> , TRUE (True or Relative) |

6.2.1.5 STERN MKR (Stern Marker)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------|------------------|
| STERN MKR | Stern Marker | <u>OFF</u> , ON |

6.2.1.6 CURSOR L/L (Cursor Position Indication)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|-----------------------------------------|------------------|
| CURSOR L/L | Cursor Position (Latitude/Longitude) | <u>OFF</u> , ON |

6.2.2 ECHO (Echo Menu)

The ECHO menu has various functions associated with radar echo presentations and signal processing as described below.

6.2.2.1 TRAILS (Echo Trail Setting)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|-------------------|--------------------------------------------------------------|
| TRAILS | Radar Echo Trails | <u>OFF</u> , EVERY, 15SEC, 30SEC, 1MIN, 3MIN, 6MIN, 12MIN |

OFF: The TRAILS function is turned off.

EVERY scan: All ship's echoes are plotted on every picture scan.

15SEC, 30SEC, 1MIN, 3MIN, 6MIN and 12MIN: All ships' tracks are plotted every specified time, 15 sec, 30 sec, 1 min, 3 min, 6 min or 12 min.

6.2.2.2 IR (Interference Rejection)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|------------------------|-------------------------|
| IR | Interference Rejection | <u>OFF</u> , 1, 2, 3, 4 |

OFF: The IR function is turned off.

1, 2, 3 and 4: The effect of interference rejection increases as the number increases.

6.2.2.3 ENH (Echo Enhancement)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|--------------------|------------------|
| ENH | Radar Echo Enhance | <u>OFF</u> , ON |

When the ENH is set to ON, the target echo, which signal level exceeds a predetermined level, are stretched towards range for better recognition.

6.2.2.4 TUNE (Receiver Tuning Mode)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------|----------------------|
| TUNE | Tuning Mode | <u>AUTO</u> , MANUAL |

6.2.2.5 MAN TUNE (Manual Tuning Set)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------|------------------|
| MAN TUNE | Manual Tuning | 0 to 99 |

This function becomes effective when the manual-tuning mode is selected.

6.2.2.6 DAY/NIGHT (Day or Night Screen)

The screen color can be changed according to the lighting conditions as required.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|------------------------|--------------------|
| DAY/NIGHT | Day/Night screen color | <u>NIGHT</u> , DAY |

NIGHT: Echoes in green with red characters and black background.

DAY: Echoes in yellow with white characters and dark blue background.

6.2.2.7 RADAR VIDEO (Radar picture color)

The radar picture can be changed to your requirements as follows:

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------------|------------------------------------------------------------------------------------|
| MONO | Mono color picture | Picture color changes automatically to yellow in DAY mode and green in NIGHT mode. |
| YELLOW | Yellow picture color | Fixed to yellow irrelevant to DAY or NIGHT. |
| GREEN | Green picture color | Fixed to green irrelevant to DAY or NIGHT. |
| MULTI | Multi picture color | Radar picture changes in 7 different colors according to its signal strength. |

6.2.3 NAV (NAV Menu)

The NAV menu includes various navigational items such as the screen stabilization, potting function setting, AIS data indication, etc.

6.2.3.1 STAB (Screen stabilizing Mode)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|------------------|------------------|
| STAB | Stabilizing Mode | <u>SEA</u> , GND |

6.2.3.2 PLOT MODE (Plotting Mode)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------|------------------|
| PLOT MODE | Plot Mode | <u>EPA</u> , ATA |

In the RA83P/84P/85P/93P/94P/95P radar series, the Electronic Plotting Aid (EPA) function is installed as standard, while the Automatic Tracking Aid (ATA) unit is an optional item. To use the ATA function, the ATA module (PCB based) must be installed inside the processor unit.



CAUTION: To use the EPA and ATA functions, the bearing and speed information must be applied from an external bearing/speed sensor.

6.2.3.3 TARGET ALL CLEAR (Plotting Target All Clear)

Using this function, all target plots can be cleared. To do so, highlight the "TARGET ALL CLEAR" sign and press the ENT key.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-----------------------|-----------------------------|------------------|
| TARGET ALL CLR | All plotted targets cleared | None |

6.2.3.4 ID DISP (ID Number Display)

When this item is set to ON, the target number is indicated beside the target symbol mark.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|-------------------|------------------|
| ID DISP | Target ID Display | <u>OFF</u> , ON |

6.2.3.5 AIS (Automatic Identification Systems) Data Display

This function is available on option basis. For operating details, refer to Para. 6.8 "Operating the AIS."

6.2.3.6 Navigation Display, Map function

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|----------------------------------|-------------------------------|-----------------------------------------|
| NAV ALIGN MODE | Navigation Display Align Mode | <u>OFF</u> , MANUAL, SERIAL |
| MAP | Map Display | <u>OFF</u> , ON |
| MAP DATUM | Map Display Datum | <u>NONE</u> , WGS84, WGS72, SGS85, PE90 |
| GPS DATUM REFERENCE LOCAL | GPS Datum | See NOTE |

NOTE: The GPS DATUM (REFERENCE or LOCAL) is shown only when SERIAL is selected as NAV ALIGN MODE.

6.2.3.7 TM RESET (True Motion Center Reset)

When this function is activated, the picture center position is reset to the position designated by the SYSTEM/SYS SETUP/TM RESET menu.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|--------------------------|------------------|
| TM RESET | True Motion Center Reset | No choice |

6.2.3.8 OS PAST CRS (Own Ship's Past Course)

When this function is selected, the course own ship has traveled past is displayed in a line form plotted at a predetermined interval.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|--------------------|------------------------|-----------------------------------------------------------|
| OS PAST CRS | Own Ship's Past Course | <u>OFF</u> , EVERY, 15SEC, 30SEC, 1MIN, 3MIN, 6MIN, 12MIN |

6.3 ADJUST MENU

The ADJUST menu has two sub menus; ADJUST and PRESET.

Details of each sub menu are as follows:

6.3.1 ADJUST

6.3.1.1 Screen Contrast Settings

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|--------------------|----------------------|------------------|
| VIDEO CONTR | Radar Video Contrast | 0 to <u>99</u> |

Changes the brilliance of the radar echo presentation.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|---------------------|-----------------|------------------|
| MARKER CONTR | Marker Contrast | 0 to <u>99</u> |

Changes the brilliance of various markers, Parallel Cursor, Heading Line, Alarm Zone, and Cross Cursor.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------|------------------|
| PLOT CONTR | Plot Contrast | 0 to <u>99</u> |

Changes the brilliance of plotting symbols and ID number used for the EPA and ATA functions.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------|------------------|
| DATA CONTR | Data Contrast | 0 to <u>99</u> |

Changes the brilliance of texts and graphics outside the PPI screen.

6.3.1.2 Navigation Position Alignment

This function is used to move a user defined Navigation Line(s) or map to a desired position on the screen. To do so, perform the following procedure.

- (1) Set the NAV ALIGN MODE to MANUAL in the DISP/NAV menu. Highlight the prompt NAV ALIGN d-LAT or d-LON.
- (2) Press the ENT key to set the NAV ALIGN.
- (3) Press the Joystick up or down to set the align value and press the ENT key.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|------------------------|-----------------------------|------------------|
| NAV ALIGN d-LAT | Manual Navigation Alignment | -1.000 to 1.000 |
| d-LON | | -1.000 to 1.000 |

6.3.1.3 RADAR SENSITIVITY (Selecting Auto/Man Receiver Functions)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|--------------------|----------------------|------------------------------|
| AUTO SELECT | Auto Function Select | <u>AUTO1</u> , AUTO2, HARBOR |

NOTE:

The AUTO function provides automated Gain, STC and FTC functions without the need of operator's control, giving an optimized radar picture while it is activated.

The **AUTO 1** is suited for coastal navigation. In this mode the picture is optimized for short and mid ranges with reduced noise and weather clutters.

The **AUTO 2** is used for open sea navigation. In this mode the sea and weather clutters are effectively reduced while the long-range performance is maintained.

The **HARBOR** mode is used for the navigation in a confined area such as a harbor, inland waterway, canal, etc. where hard and tall objects give strong radar reflections causing the picture to be saturated. Using this mode the Gain, STC and FTC are effectively introduced to minimize such strong echoes while the picture definition is maintained.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|----------------------|------------------|----------------------|
| MANUAL SELECT | | |
| GAIN | Auto/Manual Gain | <u>AUTO</u> , MANUAL |
| SEA | Auto/Manual STC | <u>AUTO</u> , MANUAL |
| RAIN | Auto/Manual FTC | <u>AUTO</u> , MANUAL |

6.3.2 PRESET

This menu is protected from ordinary operations. To use this function, first turn off the radar set. Second, press and hold the MODE key and turn the equipment on. When

the standby condition is established, turn the radar on. This allows you to enter the PRESET menu and select the following menu functions.

6.3.2.1 AUTO TUNE (Auto Tune Preset)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|------------------|------------------|
| AUTO TUNE | Auto Tune Preset | 0 to 99 |

This function is used to correct the deviated automatic tuning function. Use the following procedure to do:

- (1) Prior to presetting the AUTO TUNE, open the DISP/ECHO menu and set TUNE to AUTO.
- (2) Highlight AUTO TUNE in the ADJUST/PRESET menu, and press the ENT key.
- (3) Press the Joystick either up or down until the radar picture becomes the largest.
- (4) Press the ENT key to fix the setting.

6.3.2.2 MANUAL TUNE (Tuning Meter Center Preset)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|--------------------|----------------------------|------------------|
| MANUAL TUNE | Tuning Meter Center Preset | 0 to 99 |

To make tuning meter preset, carry out the following procedure.

- (1) Open the DISP/ECHO menu and set TUNE to MANUAL and press the Joystick up or down to obtain the largest radar video presentation.
- (2) Press the ENT key to fix the setting.
- (3) Highlight MANUAL TUNE in the ADJUST/PRESET menu and press the ENT key.
- (4) Perform the manual tuning by pressing the Joystick up or down to let the tuning meter bar graph becomes the longest.
- (5) Press the ENT key to fix the setting.

6.3.2.3 GAIN AUTO/MANUAL (Gain Preset)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------------|----------------|------------------|
| GAIN AUTO/MANUAL | Gain preset | 1 to 30 |

GAIN AUTO: This function is used to preset the reference receiver gain in AUTO mode. Once set, the receiver gain will be automatically controlled to a preset level, providing a constant optimized receiver gain even if the amount of video presentation and climatic condition change. Select a desired level by the Joystick and press the ENT key to fix the entry.

GAIN MANUAL: This function is used to preset the reference receiver gain in MANUAL mode. Once set, the receiver gain will be controlled with reference to the preset level. Select a desired level by the Joystick and press the ENT key to fix the entry.

6.3.2.4 SEA AUTO/MANUAL/HARBOR (STC Preset)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------|------------------|
| SEA AUTO/MANUAL | STC Preset | 1 to 16 |

SEA AUTO: This function is used to preset the effect of AUTO STC (Anti-Sea Clutter). Once set, the sea clutter echo will be reduced to a predetermined level, providing constant effect of Anti-Sea Clutter even if the sea state varies. Select a desired level with the Joystick and press the ENT key to fix the entry.

SEA MANUAL: This function is used to preset the Anti- Sea Clutter effect in manual mode. Before setting up the level, turn the SEA control to an appropriate position at which the Anti- Sea Clutter needs to be preset. Select a desired level by the Joystick and press the ENT key to fix the entry.

HARBOR: This function is used to preset the Anti-Sea Clutter effect used in a confined area such as a harbor, waterway, etc. Run your radar in a harbor for instance, and select the most suited level with the Joystick and press the ENT key.

6.3.2.5 RAIN AUTO/MANUAL (FTC Preset)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------|------------------|
| RAIN AUTO/MANUAL | FTC Preset | 1 to 16 |

RAIN AUTO: This function is used to preset the effect of AUTO RAIN. Once set, the clutter echo caused by the rain or snow will be reduced to a predetermined level, providing the constant Anti-Rain Clutter effect even if the weather conditions vary. Select a desired level by the Joystick and press the ENT key to fix the entry.

RAIN MANUAL: This function is used to preset the reference receiver Anti-Clutter Rain in MANUAL mode. Once set, the Anti-Clutter Rain will be controlled with reference to the preset level. Select a desired level by the Joystick and press the ENT key to fix the entry.

6.3.2.6 MBS (Main Bang Suppression)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|-----------------------|------------------|
| MBS | Main Bang Suppression | 0 to 99 |

This function is used to minimize the center sun shown on the radar screen caused by

the split of the transmitting energy generated by the magnetron (transmitting tube).

6.3.2.7 TARGET LEVEL (Target Detection Level)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|---------------------|------------------------|------------------|
| TARGET LEVEL | Target Detection Level | 1 to 8 |

This function is used to set the signal level to be supplied to the ATA system. Use the following procedure to select a signal level.

(1) Highlight the TARGET LEVEL. The signal level increases in ascending order.

(2) Press the ENT key to set the ready to select status.

Press the Joystick up or down to select an appropriate level and press the ENT key to set up the level.

6.4 SYSTEM MENU

The SYSTEM menu has I/O SETUP, SYS SETUP, and BITE functions. Details of each function is as follows:

6.4.1 I/O SETUP

This function is used to select the data source supplied from a speed sensor and a bearing sensor.

NOTE: This menu is protected from ordinary operations. To use this function, turn off the radar first. Press and hold the MODE key and turn the radar on again. When the standby condition is established, turn the radar on to enter the following menu functions.

6.4.1.1 HDG INPUT (Heading Input)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------|-------------------|
| HDG INPUT | Heading Input | <u>GYRO</u> , HDT |

GYRO: The compass data is taken from a gyrocompass via the gyro interface unit KSA-08A. Use the GYRO SET to set up the bearing.

HDT: The true bearing data will be automatically set in the incoming data sentence.

6.4.1.2 GYRO SET (Gyro Initial Setting)

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------------|------------------|
| GYRO SET | Gyro Initial Setting | 0.0 to 359.9 |

NOTE: The GYRO HDG bearing data becomes “XXX.X” and the buzzer sounds in the following circumstances:

1. When no gyro signal is input.
2. When no power is applied to KSA-08A. Check the power supply line to KSA-08A for power failure, disconnection, etc.
3. When initial setting of the gyro bearing is not completed.

In case at least one condition has been met, the bearing stabilized picture in relative or true motion mode such as N UP RM (North Up Relative Motion), C UP (Course Up Relative Motion) or N UP TM (North Up True Motion) will be reset to H UP RM (Head Up Relative Motion) mode.

6.4.1.3 SEA STAB SPD (Water Speed Input)

This function is used to select the signal source of the water speed input. The available selections include; MAN (Manual setting), PULSE (Pulse signal supplied from a speed log) and the NMEA sentences (VHW and VBW).

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|---------------------|-------------------|------------------------------|
| SEA STAB SPD | Water Speed Input | MAN, <u>PULSE</u> , VHW, VBW |

NOTE for NMEA sentences, VHW and VBW:

When the VHW sentence is selected, the Doppler Log or a speed log (Magnetic or Mechanical) can be selected according to the talker device name included in the sentence. When the VBW sentence is selected, only the Doppler LOG is selected.

The relation of the sentences and available device names is shown in the following table.

Table 6.1 Available NMEA sentences and talker devices

| Sentence | Talker identifier | On-screen display | Device name |
|----------|-------------------|-------------------|-----------------------|
| VHW | VD | DO LOG | Doppler LOG |
| | VM | LOG | Speed LOG, magnetic |
| | VW | LOG | Speed LOG, mechanical |
| VBW | VD | DO LOG | Doppler LOG |

6.4.1.4 GND STAB SPD (Ground Stabilized Speed)

This function is used to select the signal source of the ground speed and set/drift inputs. The available selections include; MAN (Manual setting), PULSE (Pulse signal supplied from a speed log) and the NMEA sentences.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|---------------------|----------------------------------------------------------------------------------|--------------------------|
| GND STAB SPD | Speed stabilized over ground | See the following table. |
| SET / DRIFT | Set: The direction towards which current flows. Drift: The speed of a current | See the following table. |

Table 6.2 Combinations of GND STAB SPD and SET/DRIFT

| GND STAB SPD | SET/DRIFT | Notes |
|--------------|------------|-----------------------------------------|
| MAN | MAN | |
| PULSE | MAN | |
| VHW | MAN | |
| VHW | VDR | |
| VBW | Not needed | Set/Drift data included in the sentence |
| VTG | Not needed | Course and speed measured over ground |

NOTE for NMEA sentences, VHW, VBW, VTG and VDR:

When the VHW sentence is selected, the Doppler Log or a speed log (Magnetic or Mechanical) can be selected according to the talker device name included in the sentence.

When the VBW sentence is selected, only the Doppler LOG is selected.

When the VDR sentence is selected, only the Doppler LOG is selected.

When the VTG sentence is selected, the Doppler LOG or the GPS receiver is selected.

Table 6.3 The relation of the sentences and available device names

| Sentence | Talker identifier available | On-screen display | Device name |
|----------|-----------------------------|-------------------|-----------------------|
| VHW | VD | DO LOG | Doppler LOG |
| | VM | LOG | Speed LOG, magnetic |
| | VW | LOG | Speed LOG, mechanical |
| VBW | VD | DO LOG | Doppler LOG |
| VDR | VD | DO LOG | Doppler LOG |
| VTG | GP | GP | GPS receiver |
| | VD | DO LOG | Doppler LOG |

6.4.1.5 LOG PULSE (Log Pulse Rate)

This menu is used to set up the incoming log pulse ratio, which is fed to the Gyro Interface unit, type KSA-08A built into the processor unit.

The following pulse ratios can be selected: 100, 200, 400 and 500 pulses/nm.

Indication**LOG PULSE**Meaning

Log pulse count for 1 NM

Selection100, 200, 400, 500

6.4.1.6 GYRO (Gyro Gear Ratio)

This menu is used to set up the gyro gear ratio used, which is fed to the Gyro Interface unit, type KSA-08A. The following pulse ratios can be selected: 36X, 90X, 180X and 360X.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|------------------------------|-------------------------|
| GYRO | Gear Ratio for Gyro repeater | 36, 90, 180, <u>360</u> |

6.4.1.7 Serial Input Format

This menu is used to select the type of incoming serial signal sent from external equipment for each data input connector from DATA1 to DATA3. The following signal formats can be selected:

SERIAL GPS (DATA1: J4) IEC61162-1, NMEA-0183, NMEA-0182, KODEN-717
SERIAL COMPASS (DATA2: J5) IEC61162-1, NMEA-0183, NMEA-0182, KODEN-717
SERIAL LOG (DATA3: J6) IEC61162-1, NMEA-0183, NMEA-0182, KODEN-717

6.4.1.8 SERIAL TRANSMIT (Serial Output Interval)

This menu is used to select the interval of transmission of outgoing signals.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|------------------------|------------------------|------------------|
| SERIAL TRANSMIT | Serial Output Interval | 0.1 to 9.9 SEC |

6.4.2 SYSTEM SETUP

This menu is used to select various functional parameters, which are specific to respective users and their operating conventions.

NOTE: *This menu is protected from ordinary operations. To use this function, turn off the radar se first. Press and hold the MODE key and turn the equipment on. When the standby condition is established, turn the radar on to enter the following menu functions.*

6.4.2.1 RANGE DISP (Range Scale Display)

This function is used to select the range scale notation system; decimal or fraction.

Example: DECIMAL: 0.125, 0.25... FRACTION: 1/8, 1/4....

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|--------------------|---------------------------|
| RANGE DISP | Range Display Mode | <u>DECIMAL</u> , FRACTION |

6.4.2.2 BUZZER

This function is used to turn on or off the electronic buzzer.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------|------------------|
| BUZZER | Alarm Buzzer | OFF, <u>ON</u> |

NOTE: *To momentary silence the audio alarm, press the AUDIO OFF key.*

6.4.2.3 DELAY (Transmission Timing Adjustment)

This function is used to adjust the transmission delay time in order to coincide the radar transmission timing with the start of the radar sweep. In practice, the Figure 4.7 in Chapter 4 illustrates the result of the setting, whether it is properly adjusted or not. To effectively perform this setting, find an appropriate object that is straight across from your radar.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|-------------------|------------------|
| DELAY | Radar Echo Timing | <u>0</u> to 99 |

Carry out the following procedure to set up the proper transmission delay time.

- (1) Highlight DELAY and press the ENT key to set up the selection ready status.
- (2) Press the Joystick up or the down until a straight picture is shown on the screen.
- (3) Press the ENT key to exit.

6.4.2.4 HDG (Ship's Heading Adjustment)

This function is used to correct the ship's heading bearing to allow the entire radar picture to be set to correct bearings.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|------------------------|---------------------|
| HDG | Radar Echo Bearing Set | <u>0.0</u> to 359.9 |

Use the following procedure for correction.

First, take an optical bearing of a stationary target located within viewable range using a standard magnetic compass. Second, measure the target bearing on the radar. If the deviation is found more than +/- 1 degree on the screen, carry out the following procedure for correction.

- (1) Highlight HDG and press the ENT key.
- (2) Press the Joystick up or down to change the bearing, in order to set the radar echo bearing to coincide with the compass bearing within a specified accuracy.
- (3) Press the ENT key to fix the bearing.

6.4.2.5 HEIGHT (STC Law Selection)

This function is used to set the most suited Anti-Clutter Sea control law that corresponds to the height of a radar antenna from the sea level. The variable range of the figure is 1 to 9, which does not represent an actual height but an index of the law. Select the most suited figure while the radar is operated.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------------------|------------------|
| HEIGHT | Antenna Height (STC curve) | <u>1</u> to 9 |

6.4.2.6 TM RESET (True Motion Reset Position)

This function is used to set the resetting point of the radar picture in the True Motion mode when the center of a radar picture reaches the predetermined boundary of the screen.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|----------------------------|--------------------------|
| TM RESET | True Motion Reset Position | <u>OPPOSITE</u> , CENTER |

There are two resetting modes available as, CENTER and OPPOSITE.

CENTER: The picture is brought back to the center of the radar screen.

OPPOSITE: The picture is brought back in parallel to the course taken to a point on the circle of 66 % of the screen radius. Refer to Figure 6.1 for detail.

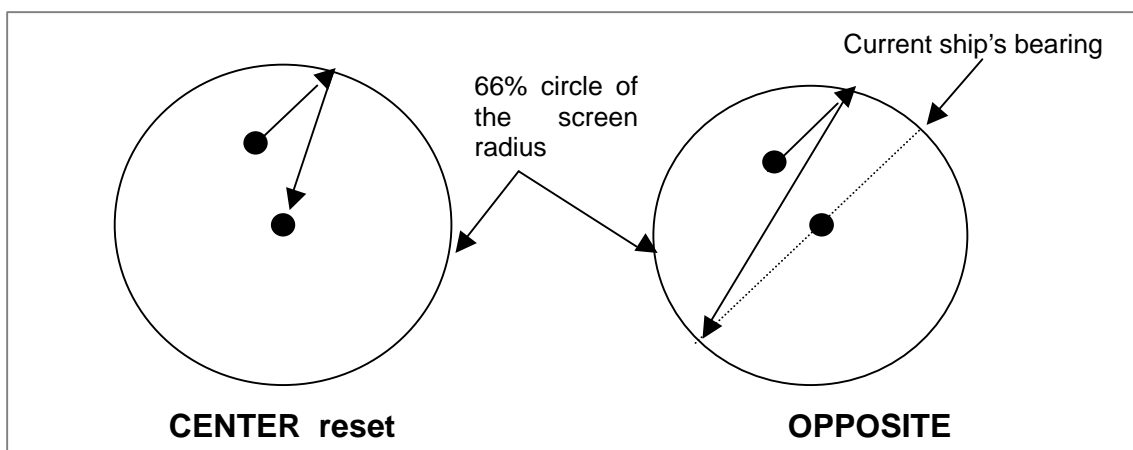


Figure 6.1 Resetting point in the True Motion mode

6.4.2.7 KEY SOUND (Key Click Sound)

This menu is used to turn on or off the key click.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|-----------------|------------------|
| KEY SOUND | Key Click Sound | OFF, <u>ON</u> |

6.4.2.8 BUZZER FREQ (Buzzer Sound Frequency)

This menu is used to set up the audio frequency of a key click. The frequency can be selected among the frequencies ranging from 100 Hz to 9999 Hz.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|--------------------|----------------------------|------------------|
| BUZZER FREQ | Buzzer Sound Frequency[Hz] | 100 to 9999 |

6.4.2.9 ALARM MODE (Alarm Zone Set Mode)

This menu is used to set up the alarm zone shape.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|---------------------|-------------------------|
| ALARM MODE | Alarm Zone Set Mode | <u>VARIABLE</u> , FIXED |

Selectable alarm zones are as follows:

VARIABLE: The alarm zone shape can be changed from a full circle to any form of semi-circles. The depth and angle of the alarm zone can be set using the EBL and VRM.

FIXED: The alarm zone can be selected from three different shapes, the 90 degree, 180 degree and full circle.

6.4.2.10 TRAIL MODE (Echo Trail Mode)

This menu is used to select the type of trail presentations.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|-----------------|---------------------|
| TRAIL MODE | Echo Trail Mode | <u>PAINT</u> , PLOT |

PAINT: The ship's trail is displayed for the time specified by the operator. Once selected, the trail is displayed every picture scan for a specified time. After fully displayed within the time, the entire trail length is first shortened to 2/3 of a total length and then it continues to stretch to its full length. The PAINT is a default setting.

PLOT: The trail is plotted every specified time, leaving the ship's trail in a dot form.

6.4.2.11 OFF CENTER (Off-center Mode)

This menu is used to select the point of offset to which the center of the radar picture is shifted.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|-----------------|--------------------------|
| OFF CENTER | Off-Center Mode | <u>CURSOR</u> , OPPOSITE |

The available off center modes are as follows:

CURSOR: An entire radar screen can be shifted to any point within 66% of the screen radius.

OPPOSITE: An entire radar screen can be shifted downwards by 66% of the screen radius.

6.4.3 BITE (Built In Test Equipment)

NOTE: This menu is protected from ordinary operations. To use this function, turn off the radar first. Press and hold the MODE key and turn the radar on. When the standby condition is established, turn the radar on to enter the following menu functions.

6.4.3.1 ALARM TEST (Alarm System Test)

This function is used to verify that the alarm function is in normal order.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|-------------------|------------------|
| ALARM TEST | Alarm System Test | <u>OFF</u> , ON |

Carry out the following operation to perform this function.

- (1) Highlight the words ALARM TEST.
- (2) Press the ENT key to set the selection ready status.
- (3) Press the joystick down to select the ON sign.
- (4) Press the ENT key to fix the selection. The alarm test will start.
- (5) In approximately 10 seconds, various alarm messages will be shown and an audio alarm will be activated. (NOTE: NO audio alarm sounds if the BUZZER OFF status is activated)
- (6) To cancel the ALARM TEST function, set the ALARM TEST to OFF, or set the radar to standby mode once, and then transmit again.

6.4.3.2 ATA TEST (ATA Tracking Test Mode)

This function is used to test the ATA function.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|------------------------|------------------|
| ATA TEST | ATA Tracking Test Mode | <u>OFF</u> , ON |

When the ATA Test mode is selected, the following test conditions and display will be available on the screen.

- (1) Range scale: 6 NM
- (2) Ship's heading: 90 degrees
- (3) Test target speed: 12 knots
- (4) Test target bearing: 90 degrees
- (5) A small letter "x" will be shown near the test target as an identifier and a large letter "X" at the bottom of the screen, showing that the display is in the TEST mode.

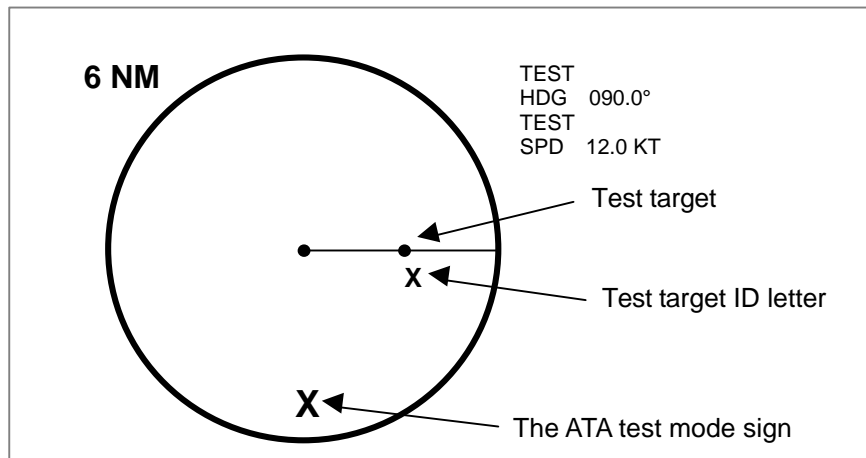


Figure 6.2 The ATA test mode display

(6) To perform the ATA test function, use the SYSTEM/BITE/ATA TEST menu.

6.5 MAINTENANCE MENU

This menu is protected from ordinary operation. To activate this function, press and hold the Mode Key and turn the unit on.

6.5.1 ANTENNA

The following maintenance test items will be shown:

| <u>Items shown</u> | <u>Meaning</u> | <u>Normal indication (range)</u> |
|--------------------|---------------------------------------|----------------------------------|
| TUNING LEVEL | Tuning Level Indicator | 10 to 20 |
| TUNING VOLTAGE | Tuning Voltage Level Monitor | 50 to 240 |
| 250V(HT) | 250V monitor | 100 to 180 |
| MAG. CURRENT | Magnetron Current Monitor | 5 to 240 |
| P.M. RX | Performance Monitor Receiver Level | 10 to 240 |
| P.M. TX | Performance Monitor Transmitter Level | 10 to 240 |
| ANTENNA TYPE | | 1 |
| ANTENNA MODE | Scanner Unit ID2 | ID No. (See NOTE) |

NOTE: ID number varies according to the transmission power level as follows:

7: 6 kW, 0: 12 kW, 5: 25 kW

6.6 Operation of the EPA

The EPA (Electronic Plotting Aid) provides the information for collision avoidance by manually plotting the first and second positions of each target. These include:

CPA (Closest Point of Approach), TCPA (Time to Closest Point of Approach), Ship's speed, Ship's course and Ship's vector

6.6.1 Using the EPA

Perform the following procedure to use the EPA function:

- (1) Move the Joystick to move the cross cursor to a target for plotting.
- (2) Press the ACQ key to acquire the target. The assigned target is braced with a dashed acquire mark with the figure 1 shown nearby.
- (3) After 30 seconds or more since the target has been acquired, plot the target again as a second plot by placing the cross cursor on it and pressing the ACQ key. A vector will be developed and the relevant data will be shown on the right side of the screen. (Refer to Figure 6.2)
- (4) Press the DELETE key to cancel the target tracking. The symbol of the target and data will be cleared.

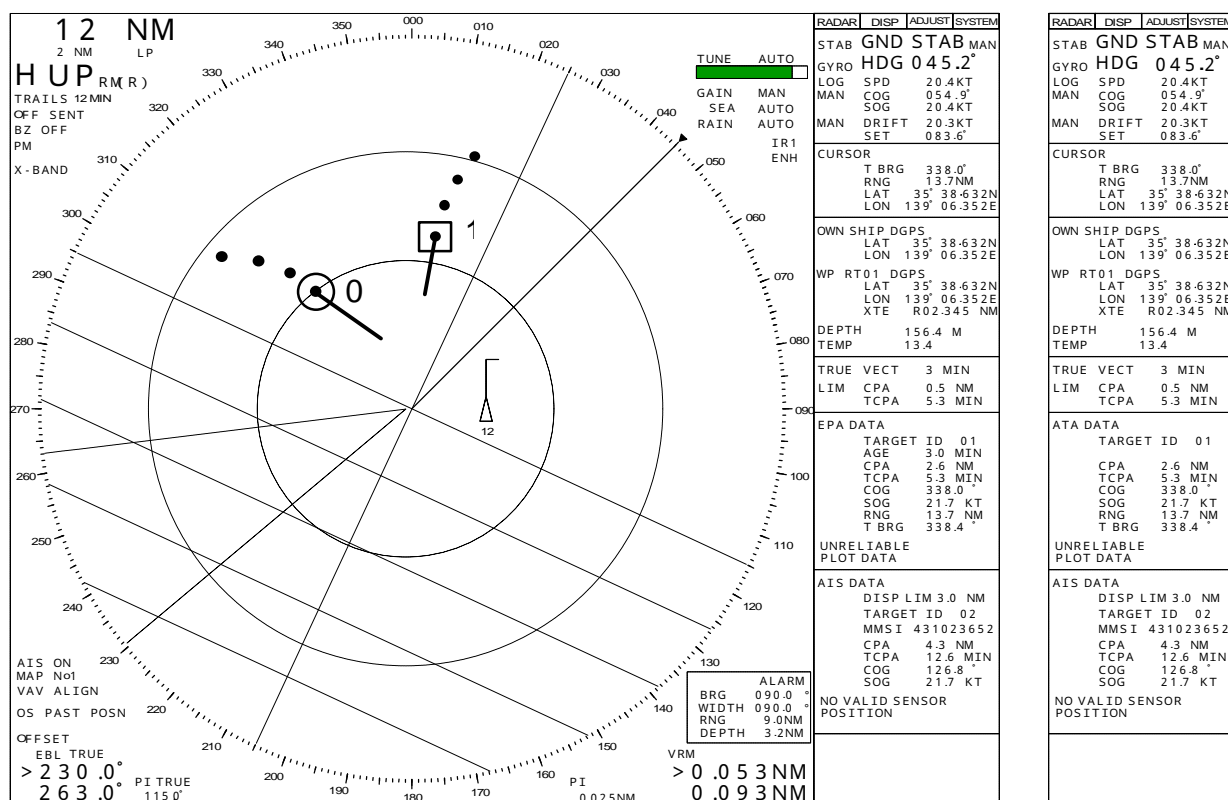


Figure 6.3 The EPA data shown on the screen

6.6.2 CPA and TCPA

The definition of CPA and TCPA is shown in the Figure 6.3.

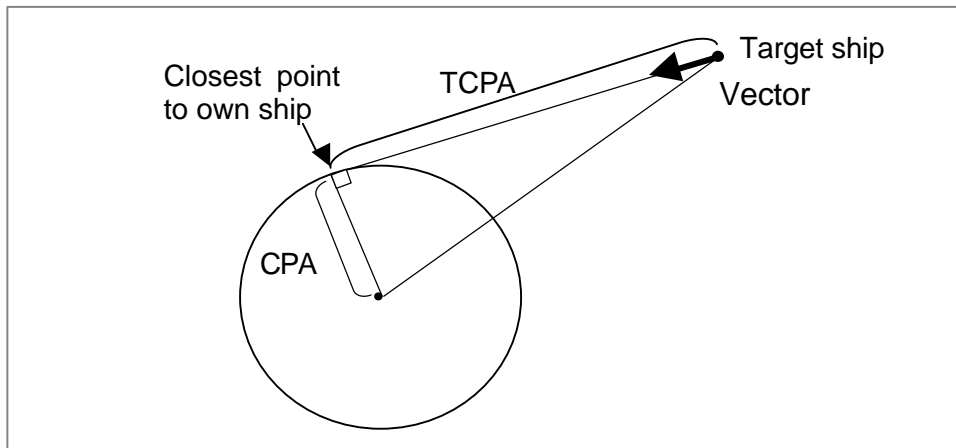


Figure 6.4 Definition of CPA and TCPA

6.6.3 EPA plotting on the screen

The EPA data is displayed for 10 minutes on the screen. Up to 5 plots are available. When the 6th plot is entered, plot 1 will be deleted automatically.

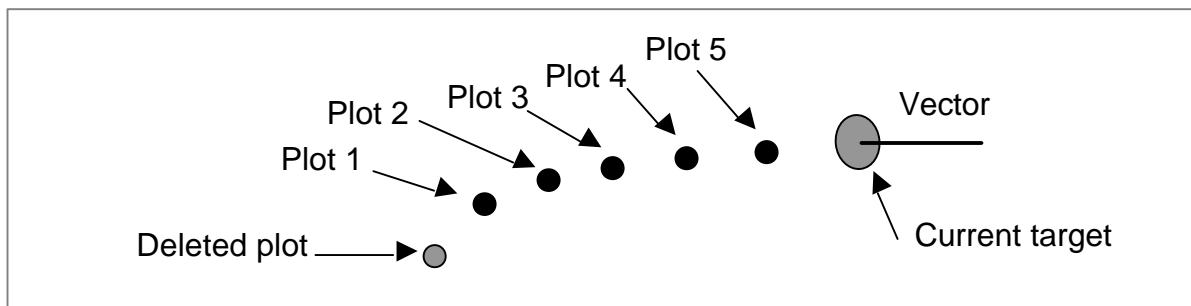



Figure 6.5 Plotting sequence

6.6.4 Alarm display

When 10 minutes has elapsed since a target has been plotted on the screen, the system judges that the reliability of the plot data is lost, and accordingly turns the audio alarm on together with the screen message "UNRELIABLE PLOT DATA" and the blinking symbol  shown. Responding to the audible alarm and the screen message, you must update the plot. If you leave the plotted data without updating for 15 minutes, all symbols and the data currently plotted on the screen will be automatically deleted.

6.6.5 Explanation of the EPA terms

TARGET ID:

The target ID number can be tagged on each displayed target from 1 to 10.

AGE:

The time elapsed from when a target is plotted. The unit is in minute(s).

CPA (Closest Point of Approach):

The closest distance of a plotted target to own ship. The unit is in nautical mile(s).

TCPA (Time to CPA):

The time required for a target reaching CPA.

CRS/COG (Course/Course Over Ground):

The course of a target plotted is shown. The course can be switched to true or relative by pressing the TRUE/REL key.

STW/SOG (Speed):

The true speed of a plotted target, can be switched to true or relative by pressing the TRUE/REL key.

VECT (Vector):

The vector time of a plotted target.

BRG (Bearing):

The bearing of a target, plotted in true or relative mode. The bearing display is referenced to own ship.

DIST (Distance):

The distance of a target plotted from own ship.

UNRELIABLE PLOT DATA:

A warning that means the assigned target plot is old and not reliable, suggesting you to update the plotting. When this display is shown, an audio alarm is activated. If you leave the plot not updated for 15 minutes after the last update, all symbols and data currently plotted will be deleted.

LIMIT CPA TCPA

This is a warning limit of CPA and TCPA. If the CPA and TCPA figures exceed the set up limit the assigned warning symbols flash and the audio alarm sounds. Set the warning limit with the RADAR/LIM CPA or TCPA menu.

6.6.6 VECT TIME (Selecting the Vector Time)

This function is used to set up the length of a vector that predicts the position of a target after preset time. Set with the RADAR/TRUE (REL) VECT menu.

6.6.7 EPA symbols

Acquisition symbols

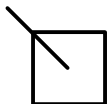
The symbol for the plotted target changes as follows according to the plotting status:



This symbol appears when a target is plotted for the first time.



This symbol appears when a target is plotted for more than two points. A vector develops and the target data can be displayed when its target number is assigned (highlighted).



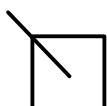
This symbol appears when a target is plotted for more than two points with its target number assigned. The target data is shown in the right side of the screen.

Warning symbols

The following symbols are used in the EPA functions to notify the operator of a high-risk target or invalid plotting. These symbols will blink when they are shown.



This is a CPA alarm symbol that appears when a plotted target is predicted to infringe a predetermined CPA and/or TCPA range. The symbol blinks at an interval of 0.5 seconds. The data can be displayed by assigning the target number.



This is a CPA alarm symbol that appears when the relevant target number is assigned. The rest of the features are the same as above.



This is an Unreliable Plot symbol that appears when a target is not plotted over 10 minutes. The on-screen error message "UNRELIABLE PLOT DATA" will also appear on the screen. In approximately 15

minutes from when the symbol is shown and no further plotting is made, the symbol mark and audio-visual alarm will be turned off automatically.

6.6.8 WARNING LIMIT (Setting the Warning Limit of CPA and TCPA)

This function is used to set up the limit at which the warning alarm for CPA and TCPA is activated. Use the RADAR/LIM CPA and LIM TCPA menu. Setting ranges for CPA and TCPA are as follows:

CPA: 0.00 NM to 19.9 NM.

TCPA: 1 Minute to 63 Minutes

6.6.9 TARGET ALL CLEAR (Clearing all target plots)

Use the DISP/NAV/TARGET ALL CLR menu.

6.6.10 ID DISP (Displaying Target ID Number)

Using this function, the target ID number can be tagged on each displayed target. Use the DISP/NAV/ID DISP menu.

6.6.11 Correcting the latest plotting position

In case you find a wrong plotting and need to correct it, carry out the following steps:

- (1) Move the Joystick to move the cross cursor on to the new plot point.
- (2) Press the UPDATE key. Wrong plot will be corrected as shown below.

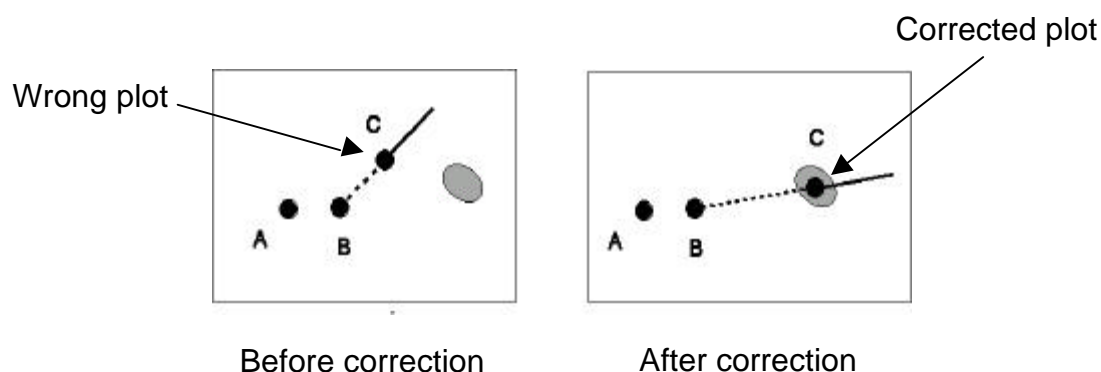


Figure 6.6 Correcting the plotting position

6.7 Operating the ATA

6.7.1 Using the ATA

The ATA (Automatic Tracking Aid) unit is an optional PC Board that can be installed into the processor unit. Using this function, up to ten targets can be manually acquired and tracked automatically. All tracked target data is the same type as the EPA data, and is shown on the right of the screen.

All operating procedures are also the same as that of the EPA function with one exception i.e. no second plotting is needed in the ATA system.

Note: If the ATA system gets malfunctioned, the plotting system will switch to EPA mode automatically.

6.7.2 Outline of the ATA system

To use the ATA function the MRE-300 ATA module must be installed. (Refer to APPENDIX 1 in Chapter 4 for installation instruction) To run the ATA function, the bearing signal and the speed signal must be supplied to the Processor unit.

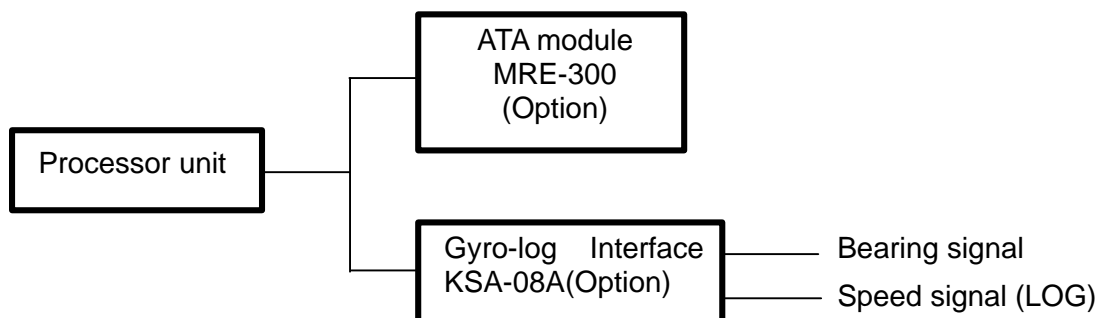


Figure 6.7 Configuration of ATA



WARNING: The accuracy of the auto tracking function provided by the ATA could be affected by the following factors:

- (1) Sea clutter and weather clutter such as rain and snow may degrade the ATA tracking capability. These clutter components should be appropriately reduced.
- (2) Poor receiver sensitivity may also degrade the tracking capability.
- (3) Faulty azimuth synchronization could be the cause of erratic vectors.
- (4) Degraded bearing and speed data fed from external sensor devices also cause erratic vectors.

If any of the errors stated above are detected, the following data provided by the ATA will be erratic.

- (1) The CPA and TCPA value.
- (2) The target ship's course and speed.
- (3) The target ship's bearing and distance.

6.7.3 ATA functions

The ATA system provides the following functions and display on the screen.

(1) Symbols:

- Acquisition symbols
- Warning symbols

(2) Target acquisition

(3) Target data display

(4) Changing the vector length

(5) Cancellation of an acquisition and tracking of target

(6) Warning limit setting

(7) Clearing all plotted targets

(8) Target number display

(9) Selecting the TRUE or RELATIVE tracking

6.7.4 Operating procedures

Perform the following procedure to use the ATA function:

(1) Move the Joystick to let the cross cursor fall on a target.

(2) Press the ACQ key to acquire the target. At the same time, the assigned target will be braced with a dashed acquire mark with an ID number shown nearby.

(3) To acquire a next target, press the TARGET key to set the next target ID.

(4) Repeat step (1) and (2) for other targets up to ID number 9.

(5) Press the DELETE key to cancel the target tracking. The symbol of the target and data will be cleared.

NOTE: The target detection echo level can be set with the menu "ADJUST/PRESET/TARGET LEVEL".

6.7.5 ATA symbols

Acquisition symbols

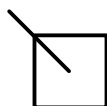
The symbol mark for the plotted target changes as follows according to the plotting status:



This symbol appears when a target is acquired for the first time.



This symbol appears when the target tracking becomes stable. A vector develops and the target data can be displayed when its target number is assigned (highlighted).



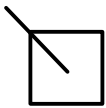
This symbol appears when a target tracking becomes stable with its target number assigned. The target data is shown in the right side of the screen.

Warning symbols

The following symbols are used in the EPA functions to notify the operator of a high-risk target or invalid plotting. These symbols will blink when they are shown.



This is a CPA alarm symbol that appears when a displayed target is predicted to infringe a predetermined CPA and/or TCPA range. It blinks at an interval of 0.5 seconds. The data can be displayed by assigning the target number.



This is a CPA alarm symbol that appears when the relevant target number is assigned. The rest of the features are the same as above.



This symbol appears with audio alarm when the target is lost during tracking. The on-screen error message "UNRELIABLE PLOT DATA" will also appear on the screen. The symbol mark and audio-visual alarm will be turned off automatically 15 seconds after first appearance of the symbol.



This symbol appears when the target enters the Guard Zone. The symbol is shown overlaid on the target and is automatically deleted as the target leaves the zone.

6.7.6 Setting the Guard Zone

The Guard Zone Alarm warns the operator an entry of a target to a preset alarm zone. When the target enters the zone, a flashing equilateral triangle with its apex down is shown to mark the target. (Refer to Figure 6.7) At the same time, the GZ sign flickers and an audio alarm sounds. To stop the audio alarm, press the AUDIO OFF key.

6.7.6.1 To set up the position of the Guard Zone

- (1) Press the ALARM (GZ) key. This allows the EBL and VRM controls to be used for moving the Alarm Zone in azimuth and range, respectively.
- (2) Move the EBL control to set the position of the Guard Zone in azimuth. The center bearing of the Guard Zone will be displayed in the lower right corner of the screen.
- (3) Move the VRM control to set the position of the Guard Zone in range. The distance of the outer edge of the Guard Zone will be displayed in the same place as the bearing display.

6.7.6.2 To set up the depth and width of the Guard Zone

(Reference drawing: Figure 6.7 The outline of the Guard Zone Alarm)

- (4) Press the EBL SEL key and rotate the EBL control to set up the width of the alarm zone. An arrow mark will be shown on the front of the WIDTH to indicate width is active to control. A further press of the key will return to control the Guard Zone in azimuth.
- (5) Press and hold the VRM SEL key and rotate the VRM control to set up the depth of the alarm zone. An arrow mark will be shown on the front of the DEPTH to indicate depth is active to control. A further press of the key will return to control the Guard Zone in range.
- (6) Press the ENT key to fix the settings. The Guard Zone will be shown on the screen.



Caution: In the following circumstances, the alarm function will become inoperative. The ALARM range and bearing displays accordingly flicker to notify that the function is inoperative.

- (1) When the alarm zone is set lower than 0.5 NM.
- (2) When the alarm zone is set beyond the viewable screen area caused by an improper range scale setting such as, the range scale is too short, off-centering is too much, etc.

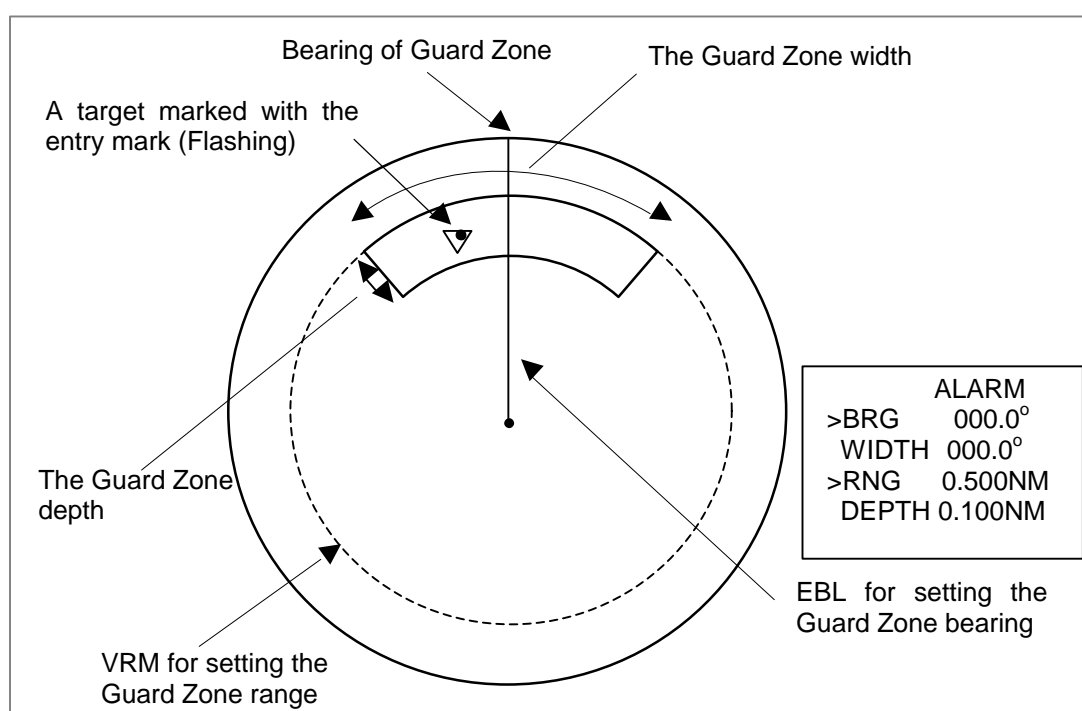


Figure 6.8 The outline of the Guard Zone Alarm

6.8 Operating the AIS

NOTE: To use this function, the optional AIS interface module (PCB based) must be installed inside the processor unit and connected to an external AIS transponder. The installation of the module must be performed by an authorized KODEN service personnel.

Reference description: APPENDIX 1 Installation of AIS module, AIS-100, Chapter 4 Installation.

6.8.1 Outline of the AIS

The AIS interface module receives the other ship's information sent from an external AIS transponder and displays the AIS symbols and data. (NOTE: The AIS transponder transmits own ship's information at certain interval and also receives the navigational information broadcast from ships located within the AIS reception coverage.

6.8.2 Setting the AIS to work

(1) In the DISP menu select AIS and select ON.

| <u>Indication</u> | <u>Meaning</u> | <u>Selection</u> |
|-------------------|------------------|-----------------------------|
| AIS | AIS data display | <u>OFF</u> , SYMBOL OFF, ON |

(2) In the RADAR menu select LIM (AIS range). Selecting the LIM range causes the AIS symbols to be displayed within the LIM range.

(3) The AIS symbols are displayed on the target echoes, which are termed "activated target." The AIS interface can handle up to 20 targets for AIS processing. The targets of 21 up to 40 are deemed to be "sleeping targets" or unprocessed targets, causing the alarm message "Number of targets have exceeded the limit" to be shown on the screen.

(4) To prevent potential dangerous targets from being unprocessed, always keep the LIM range to allow a total number of activated targets to be within 20. To view the AIS data of a specific activated target, set a target ID number in the RADAR menu to an associated TARGET ID shown on the screen.

6.8.3 AIS data display

| | |
|----------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MMSI | An acronym of "Maritime Mobile Service Identity", which means the identification number of each ship that carries the AIS transponder. The number is assigned by the IMO. |
| CPA | Closest Point of Approach |
| TCPA | Time to CPA |
| CSE/COG | Course/Course Over Ground |

STW/SOG Speed through Water/Speed Over Ground

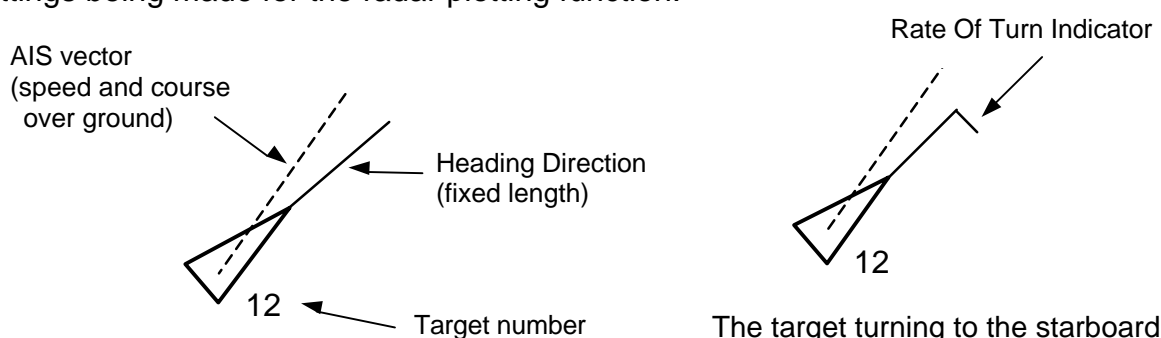
The TARGET ID is applied from 0 to 19 automatically. When a target has moved out of LIM range or been lost, the ID number being used will be applied to other newly entered target automatically.

6.8.4 AIS target symbols

According to the AIS operational status, the following target symbols are used.

Activated Target

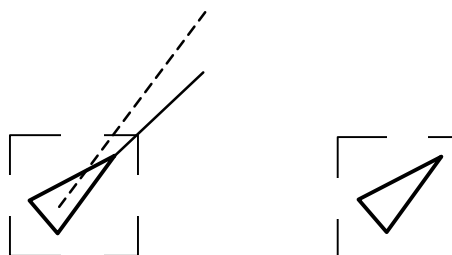
A target, which the AIS user has activated is termed "Activated Target" and is supplied with an ID number (0 to 20). The vector time and mode are determined with the settings being made for the radar plotting function.

**Figure 6.9 Activated Target Symbol**Sleeping Target

A target, which is not activated by the AIS user is termed "Sleeping Target." The target has no ID, vectors or ROT information, only showing the presence of a vessel with AIS equipped.

**Figure 6.10 Sleeping Target Symbol**Selected Target

A target selected by the AIS user is termed "Selected Target." A target to be selected can be Activated or Sleeping, whatever. Once selected, a dashed square is drawn around the target and AIS data (MMSI, CPA, TCPA, COG and SOG) will be displayed in the AIS data window.

**Figure 6.11 Selected Target Symbol**

Dangerous Target

If predicted CPA and TCPA values of an Activated Target are smaller than the one being set up, the AIS target symbol will turn to a flashing bold symbol as shown below.

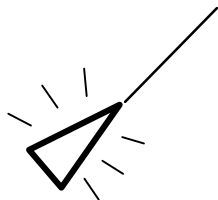


Figure 6.12 Alarm Target Symbol

Lost Target

A target that strays out of tracking is termed “Lost Target.” The lost symbol is displayed flashing with a line drawn across. When an activated target changes to a lost target, the buzzer sounds. When a sleeping target changes to a lost target, the buzzer does not sound and the symbol will disappear automatically approx. 1 minute later.

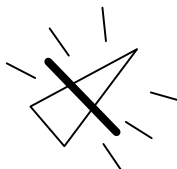


Figure 6.13 Lost Target Symbol

NOTE:

The radar vector (generated by EPA or ATA) and the AIS vector may differ in terms of the vector length and its direction. This is not a fault. The radar vector is developed based on the past target positions stored either by manual plotting (EPA) or automatic tracking (ATA). Meanwhile, the AIS vector is generated from the navigation data sent from the AIS transponder. The radar vectors take a certain time until they are fully displayed, while the AIS vector is displayed as soon as the AIS data is received from the AIS transponder.

Chapter 7 Graphic Displays

The RA83P/84P/85P/93P/94P/95P series has a graphic mode in addition to the normal radar display to assist in navigation. The available graphics are NAVLINE (Navigation Line), MAP (Map) and 10 kinds of marks. The map is constituted by a set of Coastlines.

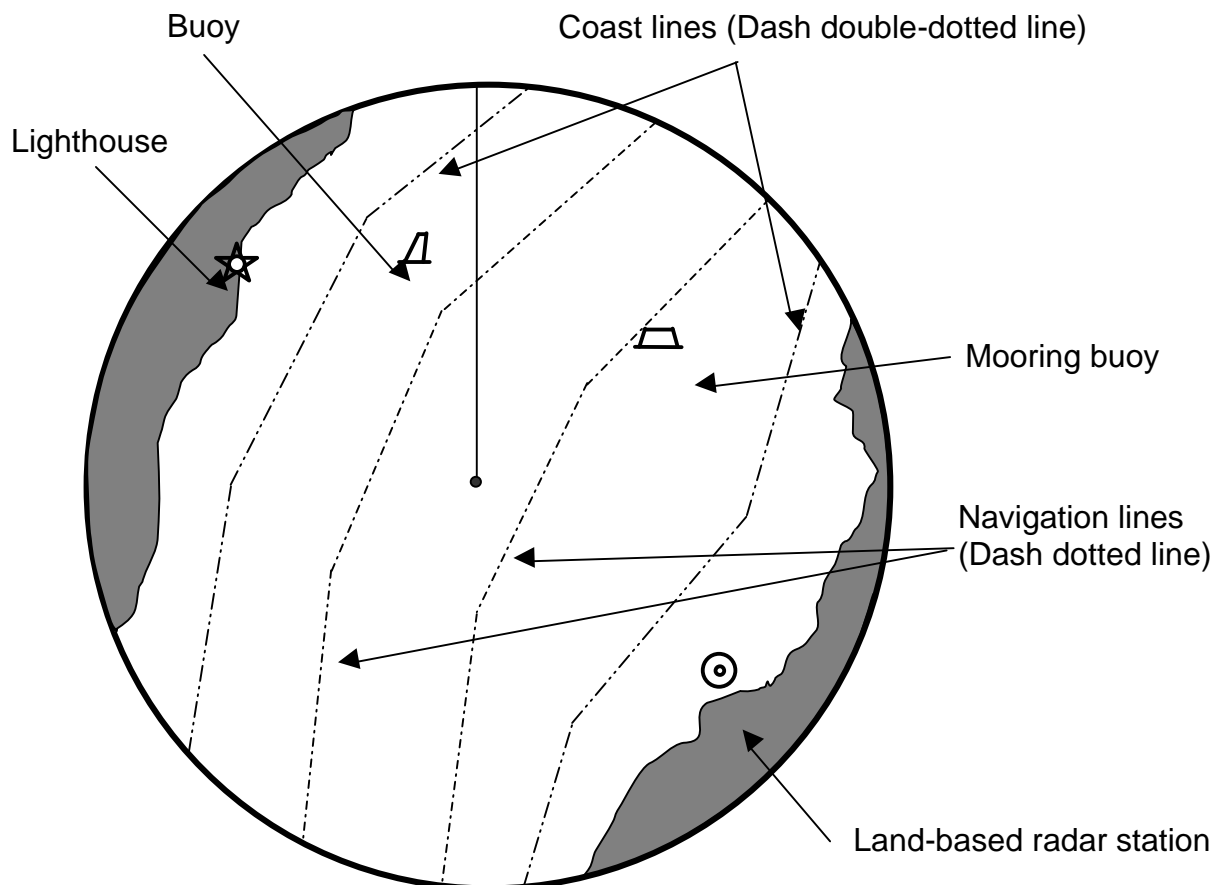


Figure 7.1 An example of the graphic display

Specifying nodes on each graphic in the latitude and longitude creates both navigations lines and coastlines.

7.1 Entering the Graphic Mode

Put the radar to standby mode and press the MENU key. Pressing the MENU key toggles the graphic mode of display in the following order.

First press: DISPLAY ITEM SELECT MENU

Second press: NAVLINE DATA INPUT MENU

Third press: COASTLINE DATA INPUT MENU

Fourth press: MARK INPUT MENU

NOTE: To use the graphic function, you need to enter the position data from external Electronic Position Fix System (EPFS).

7.2 Selecting the Graphic Display / DISPLAY ITEM SELECT MENU

This menu shows the status of the current settings on all available graphic display items.

Table 7.1 DISPLAY ITEM SELECT MENU

| | | | |
|--------------|-------------------|---|-----|
| DISPLAY ITEM | NAVLINER NUMBER | 0 | OFF |
| | | 1 | OFF |
| | | 2 | OFF |
| | | 3 | OFF |
| | | 4 | OFF |
| | | 5 | OFF |
| | | 6 | OFF |
| | | 7 | OFF |
| | | 8 | OFF |
| | | 9 | OFF |
| | MAP NUMBER | 0 | OFF |
| | | 1 | OFF |
| | COAST LINE NUMBER | 0 | OFF |
| | | 1 | OFF |
| | | 2 | OFF |
| | | 3 | OFF |
| | MARK | | OFF |

7.2.1 Selecting each item

To select a specific graphic display, carry out the following procedures:

- (1) Move the Joystick to the right highlighting the OFF sign and press the ENT key.
The OFF sign will blink accordingly.
- (2) Move the Joystick further to the right to show the blinking ON sign.
- (3) Press the ENT key to fix the selection of the graphic display. The ON sign will become stationary and the selected graphic display will be shown overlaid with a normal radar picture.

The above procedure applies to all DISPLAY ITEMS in the table.



WARNING: In case no positional data is entered in the selected graphic display item, a beep sounds to alarm the operator that the item is not valid.

7.2.2 NAVLINE

- The NAVLINE is a graphic display that shows a course or course separation zone on the radar screen. Up to 10 pairs of data can be registered (Registration number: 0 to 9) For registration of NAVLINE, refer to “7.3.1 Registering or modifying the NAVLINE data”
- One NAVLINE consists of a pair of continuous polygonal lines.
- You can register up to 10 points on each polygonal line (Registration number: A0 to A9 and B0 to B9).
- One NAVLINE alone can be displayed on the screen.
- If your ship contacts or crosses a NAVLINE, the warning display on the screen will appear with highlighted “NAVLINE” sign, which is shown in the lower right corner of the screen.
- Before displaying the NAVLINE, you must enter the position signal from the NAVIGATOR (EPFS)

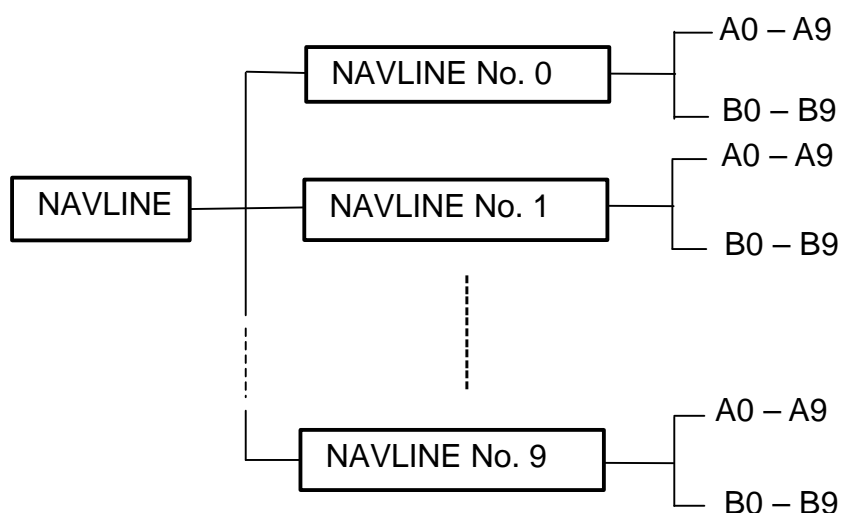


Figure 7.2 Structure of NAVLINE

7.2.3 MAP

- The MAP function is used to make artificial warning zones, warning spots or landmarks for fixed targets including coastlines, buoys, reefs, sunken ships and lighthouses on the radar screen. You can register up to 2 pairs of the maps (Registration number: 0 to 1).
- Up to 4 coastlines (Registration number: 0 to 3) and 20 marks (Registration number: 0 to 19) can be registered to a single map.
- Up to 20 points (Registration number: 0 to 19) can be registered to a single coastline. Polygonal lines connecting the registered points constitute a coastline.
- One map alone can be displayed at a time.

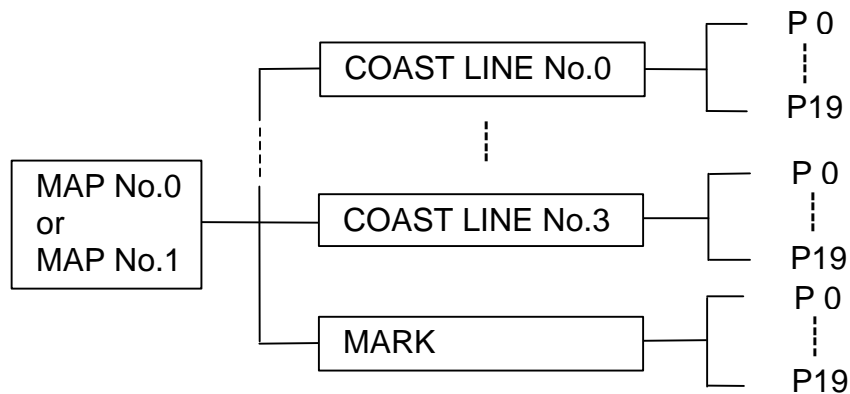


Figure 7.3 Structure of the Map

7.3 Registering or modifying the NAVLINE data/NAV LINE DATA INPUT MENU

To use this function, carry out the following procedures:

- (1) Select the NAVLINE INPUT MENU. The following list will accordingly be shown on the screen.

Table 7.2 NAV LINE INPUT MENU

| NAVLINE NUMBER | | | 0 | |
|-----------------|-----------|-------|------------|-------|
| POSITION NUMBER | LATITUDE | N / S | LONGITUDE | E / W |
| | 12°34.567 | N | 123°45.678 | E |
| A1 | | | | |
| A2 | | | | |
| A3 | | | | |
| A4 | | | | |
| A5 | | | | |
| A6 | | | | |
| A7 | | | | |
| A8 | | | | |
| A9 | | | | |
| B0 | | | | |
| B1 | | | | |
| B2 | | | | |
| B3 | | | | |
| B4 | | | | |
| B5 | | | | |
| B6 | | | | |
| B7 | | | | |
| B8 | | | | |
| B9 | | | | |

- (2) Move the Joystick up or down to highlight the number shown right to the words NAVELINE NUMBER and press the ENT key. The number will blink.
- (3) Move the Joystick left or right to select the desired number out of 0 through to 9.

- (4) Press the ENT key to fix the selection. The blinking number will become stationary.
- (5) Move the Joystick up or down to highlight an alphanumeric display (A0 – B9) under the POSITION NUMBER column.
- (6) Press the ENT key to let the selected alphanumeric display blink.
- (7) Use the N/S/E/W and numeric keys (0 - 9) to enter the latitude and longitude coordinates. If a correction is needed, move the Joystick left or right to highlight the part for correction and repeat step (7) and after.
- (8) Press the ENT key to fix the entry. The blinking alphanumeric data will become stationary.
- (9) To continue the registration, repeat the step (5) and after.

7.3.1 Registering or modifying the MAP data/COAST LINE INPUT MENU

- (1) Select the COASTLINE input menu. The following table will be accordingly shown.

Table 7.3 COASTLINE INPUT MENU

| | | | | |
|------------------|-----------|-------|------------|-------|
| MAP NUMBER | | | 0 | |
| COASTLINE NUMBER | | | 0 | |
| POSITION NUMBER | LATITUDE | N / S | LONGITUDE | E / W |
| | 12°34.567 | N | 123°45.678 | E |
| 1 | | | | |
| 2 | | | | |
| 3 | | | | |
| 4 | | | | |
| 5 | | | | |
| 6 | | | | |
| 7 | | | | |
| 8 | | | | |
| 9 | | | | |
| 10 | | | | |
| 11 | | | | |
| 12 | | | | |
| 13 | | | | |
| 14 | | | | |
| 15 | | | | |
| 16 | | | | |
| 17 | | | | |
| 18 | | | | |
| 19 | | | | |

- (2) Move the Joystick up or down to highlight the number shown right to the words MAP NUMBER and press the ENT key. The number will blink.
- (3) Move the Joystick left or right to select the MAP NUMBER, 0 or 1.

- (4) Press the ENT key to fix the selection. The blinking number will become stationary.
- (5) Move the Joystick down to highlight the number shown right to the words COASTLINE NUMBER and press the ENT key.
- (6) Press the Joystick left or right to select the COASTLINE NUMBER from 0 through to 3.
- (7) Press the ENT key to fix the selection. The number display will become stationary.
- (8) Move the Joystick up or down to highlight the number (0 - 19) under the POSITION NUMBER column and press the ENT key to fix the selection.
- (9) Use the N/S/E/W and numeric keys (0 - 9) to enter the latitude and longitude coordinates. If a correction is needed, move the Joystick left or right to highlight the part for correction and enter new data.
- (10) Press the ENT key to fix the entry. The blinking alphanumeric data will become stationary.
- (11) To continue the entry of position data for other position numbers or change the data, repeat the step (8) and after.

7.3.2 Registering or modifying the MARK data/MARK INPUT MENU

- (1) Select the MARK INPUT menu. The following list will be shown, accordingly.







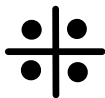

Table 7.4 MARK INPUT MENU



| MAP NUMBER | | | | 0 | |
|-----------------|-------------|-----------|-------|------------|-------|
| POSITION NUMBER | MARK SELECT | LATITUDE | N / S | LONGITUDE | E / W |
| | ○ | 12°34.567 | N | 123°45.678 | E |
| 1 | | | | | |
| 2 | | | | | |
| 3 | | | | | |
| 4 | | | | | |
| 5 | | | | | |
| 6 | | | | | |
| 7 | | | | | |
| 8 | | | | | |
| 9 | | | | | |

- (2) Move the Joystick up or down to highlight the number shown right to the words MAP NUMBER and press the ENT key. The number will blink.
- (3) Move the Joystick left or right to select the MAP NUMBER, 0 or 1.
- (4) Press the ENT key to fix the selection. The blinking MAP number will become stationary.

- (5) Move the Joystick up or down to highlight the number shown right to the words POSITION NUMBER and press the ENT key. The number will blink.
- (6) Select a desired mark by pressing a numeric key (0 - 9)
- (7) Use the N/S/E/W and numeric keys (0 - 9) to enter the latitude and longitude coordinates. If a correction is needed, move the Joystick left or right to highlight the part for correction and enter new data.
- (8) Press the ENT key to fix the entry. The blinking alphanumeric data will become stationary.
- (9) To continue the entry of position data for other position numbers or change the data, repeat the step (5) and after.

Table 7.5 MARKS USED IN THE MAP

| No. | Mark shape | Applicable objects |
|-----|-------------------------------------------------------------------------------------|----------------------------------------------------|
| 0 |  | Light |
| 1 |  | Lighthouse, Aeronautical light, Light beacon, etc. |
| 2 |  | Buoy |
| 3 |  | Large mooring buoy |
| 4 |  | Radio and/or radar station |
| 5 |  | Dry rock |
| 6 |  | Awash rock |
| 7 |  | Reef, submerged rock, etc. |

| | | |
|---|-----------------------------------------------------------------------------------|------------------------------------------------|
| 8 |  | Surface object, wreck, Hazardous point, etc |
| 9 |  | Rush tidal current, eddy, etc. |

Chapter 8 Trouble Shooting And On Board Servicing

This chapter covers simplified fault locating procedures to enable faulty areas to be identified on your vessel.

8.1 Information required for service

Please advise the following details:

- (1) Name of vessel, Satcom number if available.
- (2) Equipment type name
- (3) Equipment serial number
- (4) Software type name, shown on the standby screen and stated in this manual.
- (5) Next port of call, ETA and ship's agent
- (6) Faulty conditions and the result of on board check

8.2 Self diagnosis functions provided

The equipment provides on-screen alarm messages and the status indicator inside the display unit.

8.2.1 Alarm messages

The following alarm messages will be shown as a result of diagnosis by the built-in self-check function if the equipment becomes faulty. Details are as follows:

Table 8.1 Alarm messages shown on the screen

| Alarm messages | Faults detected |
|--------------------------------------|-------------------------------------------------------------------------------------------------|
| ANTENNA ABNORMAL (NO RESPONSE) | Communication between Antenna and Processor is faulty. Suspect no Antenna connection. |
| AZIMUTH ABNORMAL | The azimuth pulse signal is erratic in timing or frequency or no signal input to the processor. |
| HEADING LINE ABNORMAL | The Heading Line signal is erratic or no signal input to the processor. |
| TRIGGER ABNORMAL | Master trigger pulse is erratic in timing and level or, not present at all. |
| MAGNETRON CURRENT ABNORMAL | Magnetron current is not within specified range. |
| 250V ABNORMAL | High voltage supply for Modulator Unit is not within specified range. |
| MAGNETRON HEATER CURRENT ABNORMAL | Magnetron heater current is not within specified range. |

(Alarm messages)

| Alarm messages | Faults detected |
|----------------------|-------------------------------------------------------------------------------|
| RADAR VIDEO ABNORMAL | Video signal sent from the transceiver unit is erratic or not present at all. |
| GYRO HDG XXX | No bearing data is applied to the display unit. |
| LOG SPD XXX | No speed data is applied to the display unit. |

8.2.2 Status indicators

Two LEDs (Light Emitting Diodes) are provided on the Logic board fitted inside the processor unit. These LEDs indicate the operational status of the software and hardware used in this system. Details of the indications are as follows:

Table 8.2 Status indications

| LED No. | Usage | Operational status | LED status |
|---------|----------------|--------------------|------------|
| DS1 | Software check | Normal | ON |
| | | Failure | OFF |
| DS2 | Hardware check | Normal | ON |
| | | Failure | OFF |

Location of the status indicators

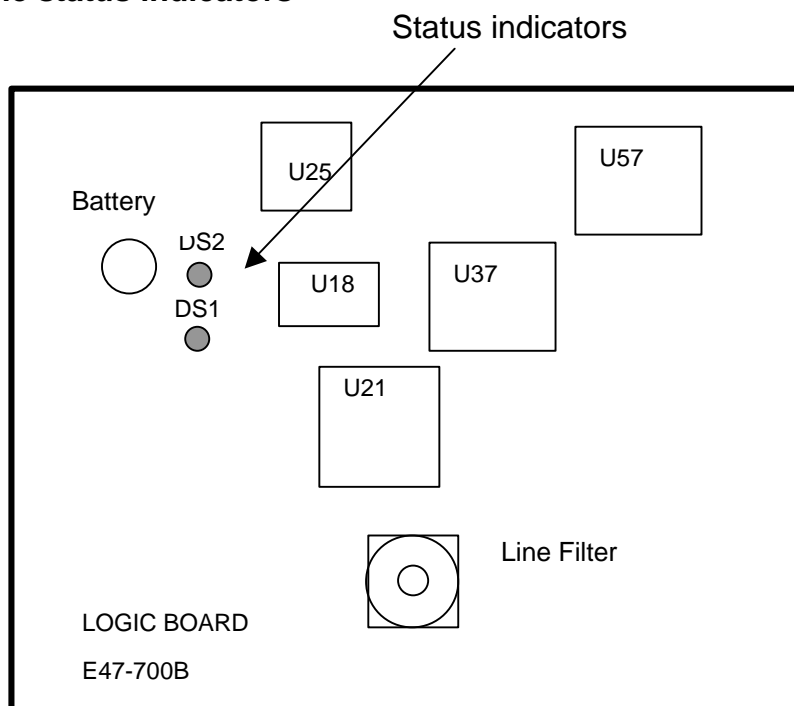


Figure 8.1 Location of status indicators

8.3 Trouble shooting

This section provides information required to fix or diagnose the faulty part in RA83P/84P/85P/93P/94P/95P radar systems.

8.3.1 First-line faultfinding

Use the following tables that show brief diagnosis schedule to assist first-line servicing on board the ship.

Table 8.3 Primary faults

| Description of fault | Possible cause of failure | Corrective measures |
|----------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Radar does not turn on | <ol style="list-style-type: none"> 1. Power cable is disconnected. 2. Power supply voltage is outside of the specified value. 3. Main fuse is blown. | <ol style="list-style-type: none"> 1. Connect the power cable and secure the cable plug connection. 2. Use properly rated power supply. 3. Replace the fuse with new one. |
| Radar turns on but nothing displayed on the screen | <ol style="list-style-type: none"> 1. Brilliance control is set at minimum position. 2. LCD is defective. 3. LCD driving circuits are defective. | <ol style="list-style-type: none"> 1. Turn the brilliance control CW to set proper brilliance. 2. Call for service. 3. Call for service. |

Table 8.4 Possible faults

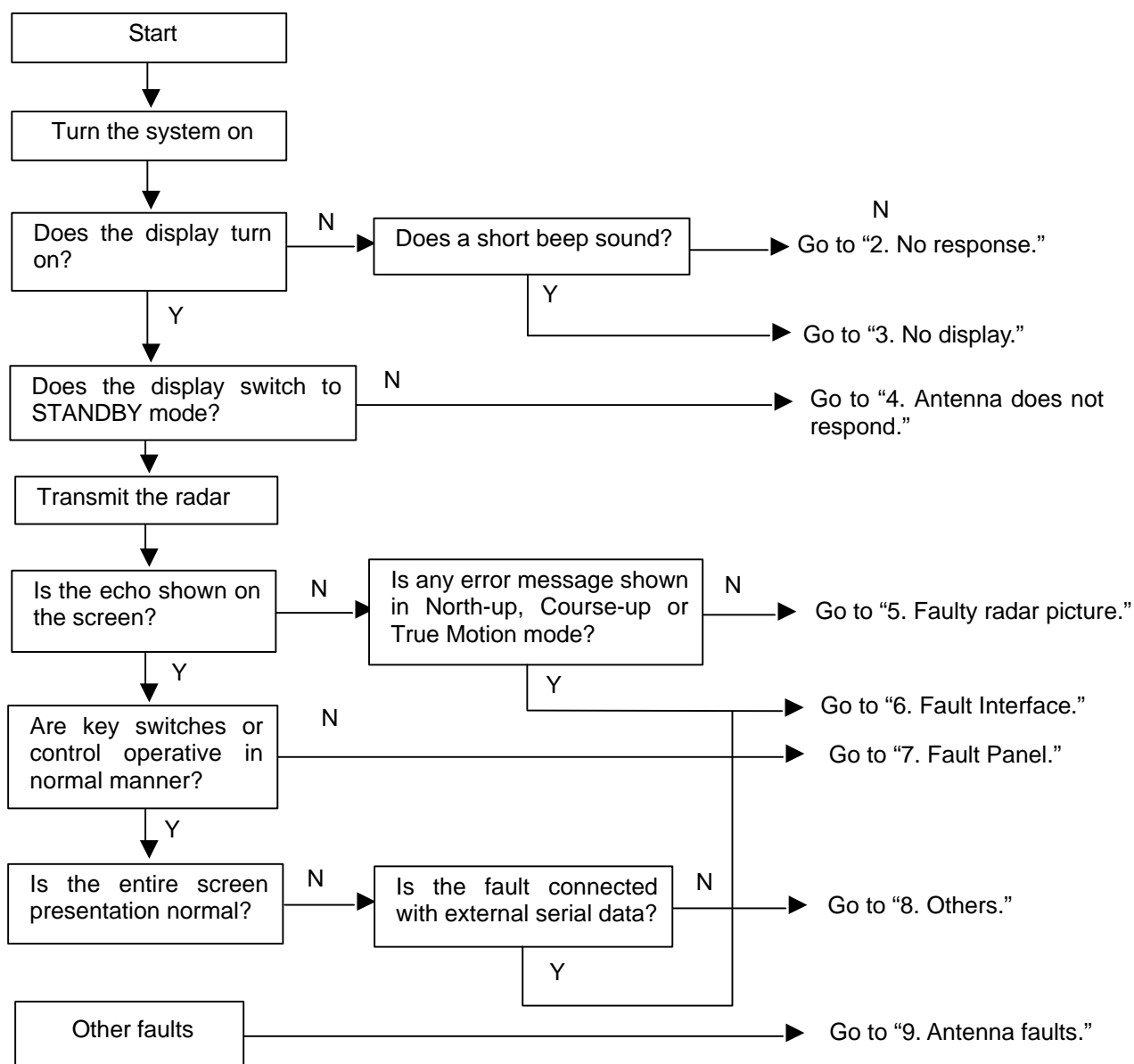
| Description of faults | Possible cause of failures | Corrective measures |
|-------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Screen is dark | <ol style="list-style-type: none"> 1. Brilliance of the screen is not properly set. 2. LCD driving circuits are defective. | <ol style="list-style-type: none"> 1. Turn the brilliance control CW to set proper brilliance. 2. Call for service. |
| No targets shown | <ol style="list-style-type: none"> 1. Tuning is deviated. 2. Video contrast is poor. 3. Transceiver is defective. | <ol style="list-style-type: none"> 1. Re-adjust tuning referring to para 6.2.14 and 6.2.15 in this manual. 2. Re-adjust contrast referring to para 6.2.1 3. Turn on Performance Monitor to isolate the faulty section. 4. Call for service. |
| Targets are weak | <ol style="list-style-type: none"> 1. Tuning has drifted. 2. Magnetron or MIC is faulty. | <ol style="list-style-type: none"> 1. Re-adjust tuning referring to para 6.2.14 and 6.2.15 in this manual. 2. Call for service. |
| No markers (HL, EBL, VRM, Range Rings, Parallel Index Line, Alarm Zone) | <ol style="list-style-type: none"> 1. Marker video contrast is not properly set. 2. Logic board is defective. | <ol style="list-style-type: none"> 1. Re-adjust Marker contrast referring to para 6.2.2. 2. Call for service. |
| Heading Line is missing | <ol style="list-style-type: none"> 1. Heading Line signal is not applied to the display. | <ol style="list-style-type: none"> 1. Check for cable connections for HL signal at antenna and display units. |

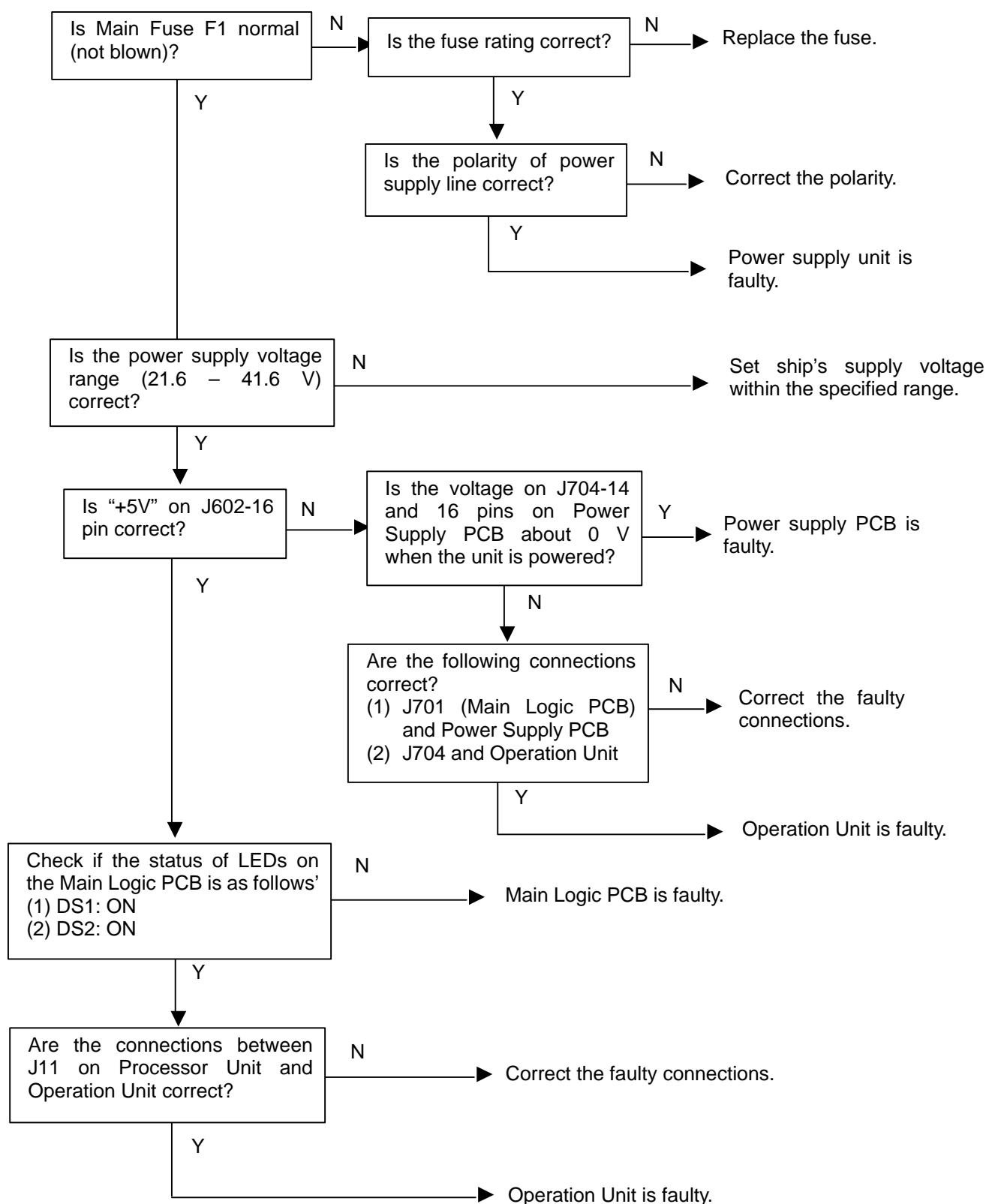
| Description of faults | Possible cause of failures | Corrective measures |
|------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Aerial does not rotate | <ol style="list-style-type: none"> 1. Motor fuse is blown. 2. Turning motor is not powered. 3. Turning motor brushes are worn out. | <ol style="list-style-type: none"> 1. Replace the motor fuse with new one. 2. Check the connections for motor power supply line. 3. Replace the motor brushes. |

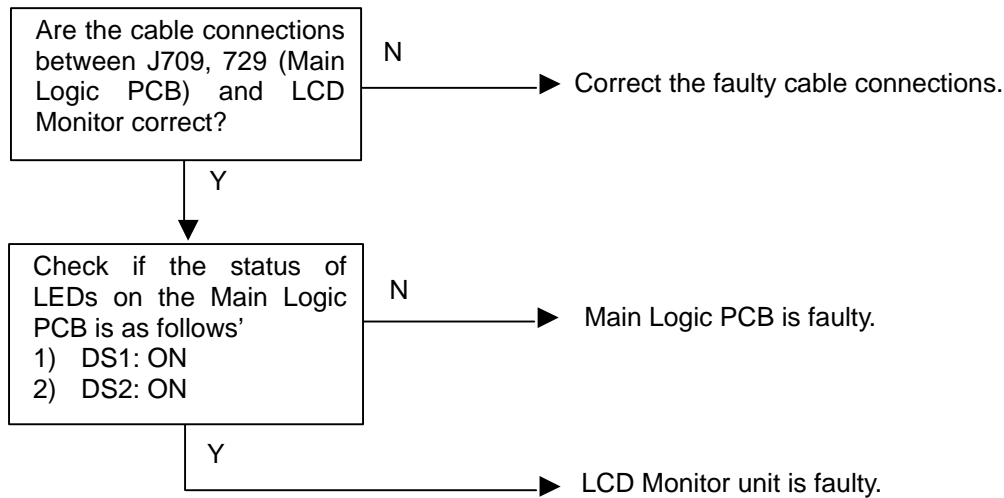
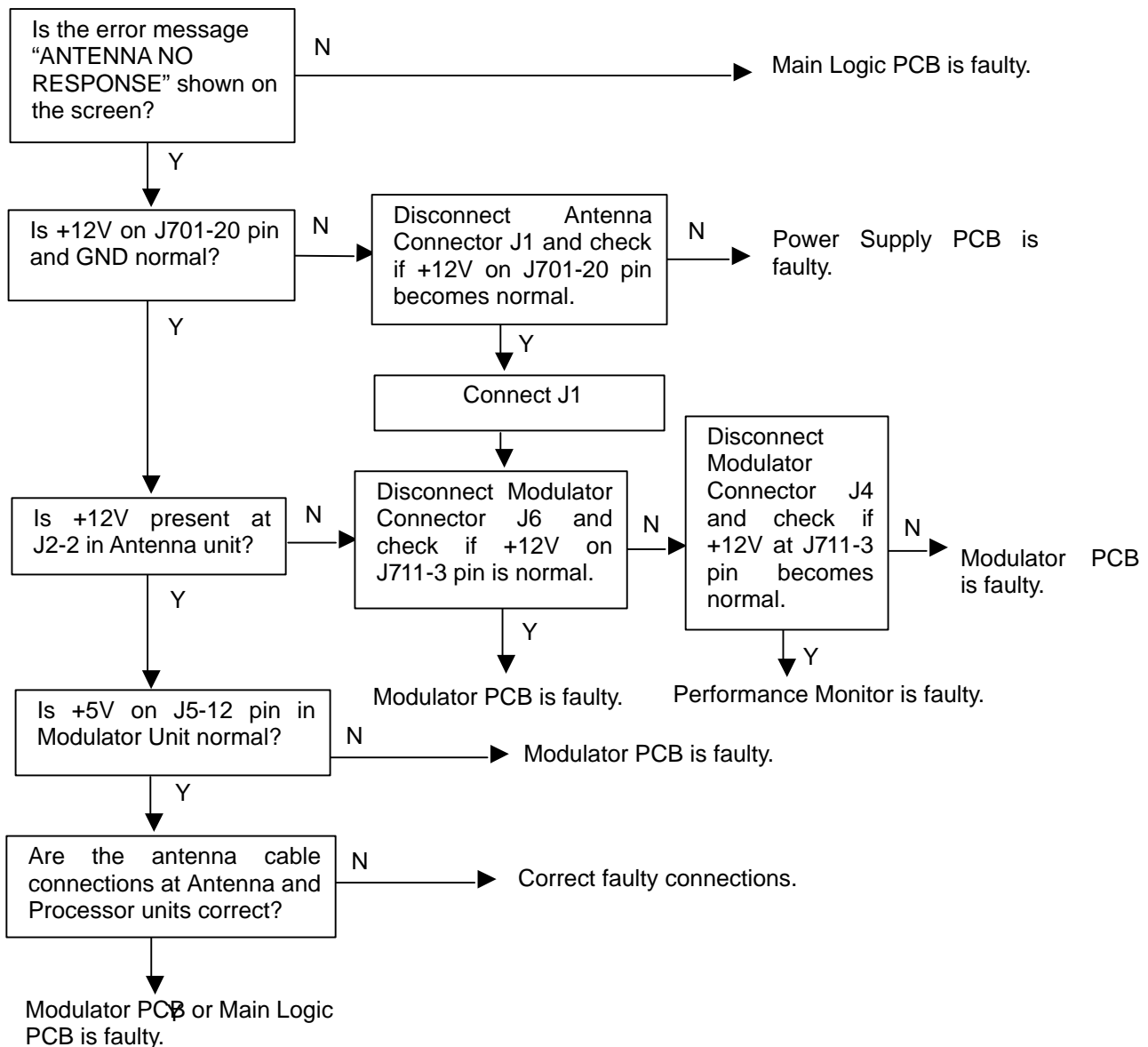
8.3.2 Faultfinding chart

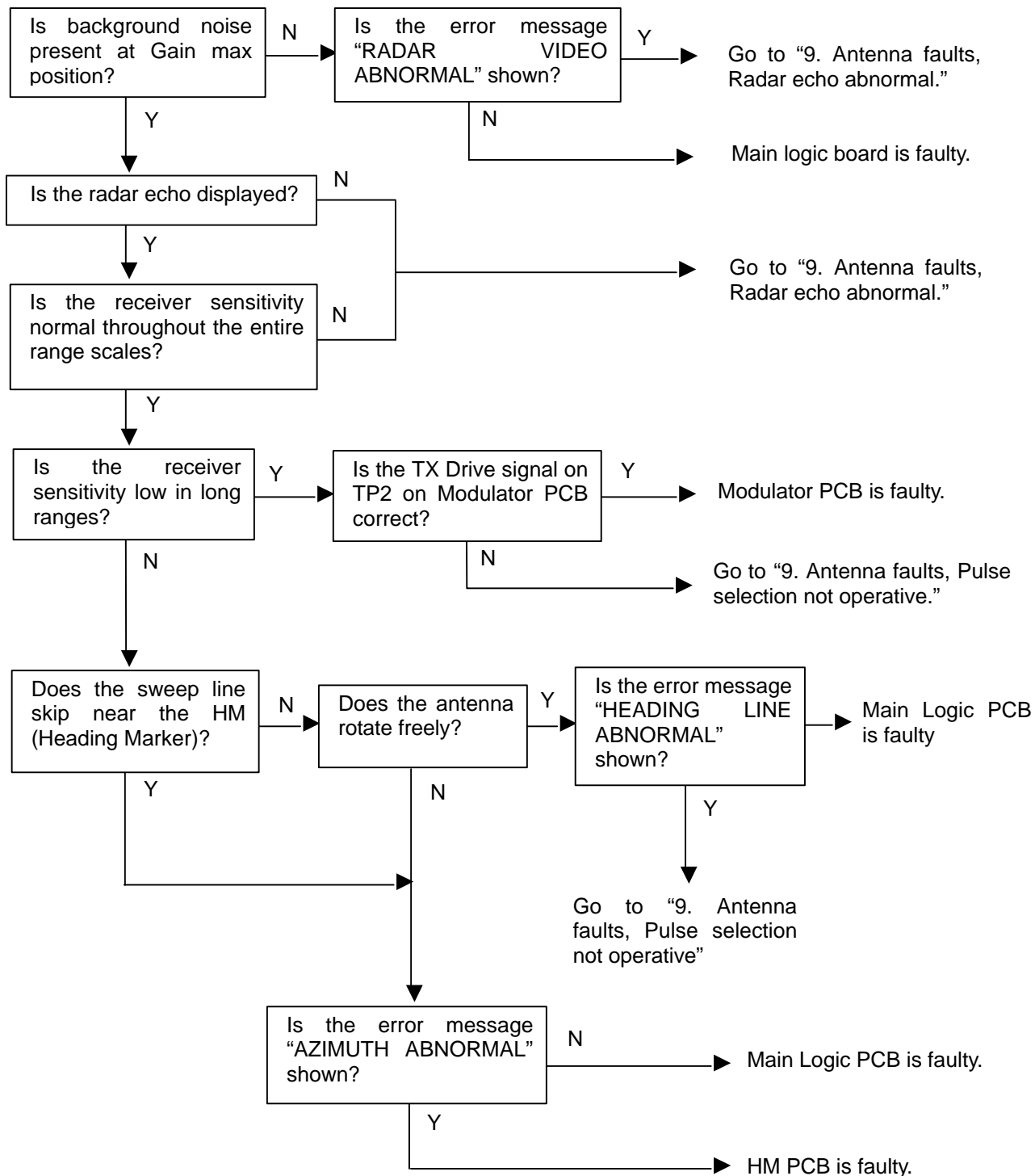
The following faultfinding charts are prepared for a service engineer to allow him to diagnose and locate a faulty part on a module basis. The charts are systematically arranged from primary fault analysis to finding a path to a detailed flow chart that follows.

1. Fault analysis



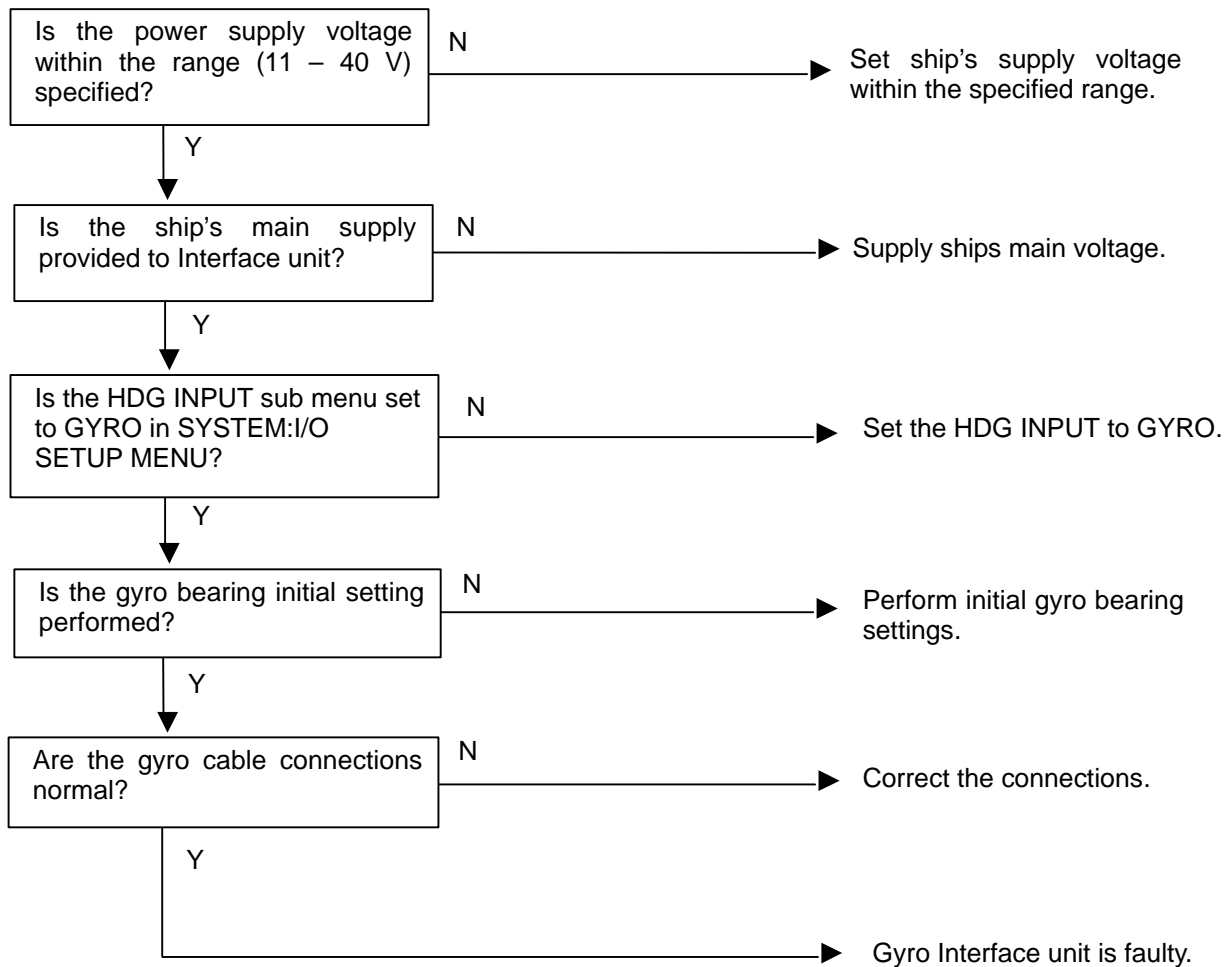
2. No response

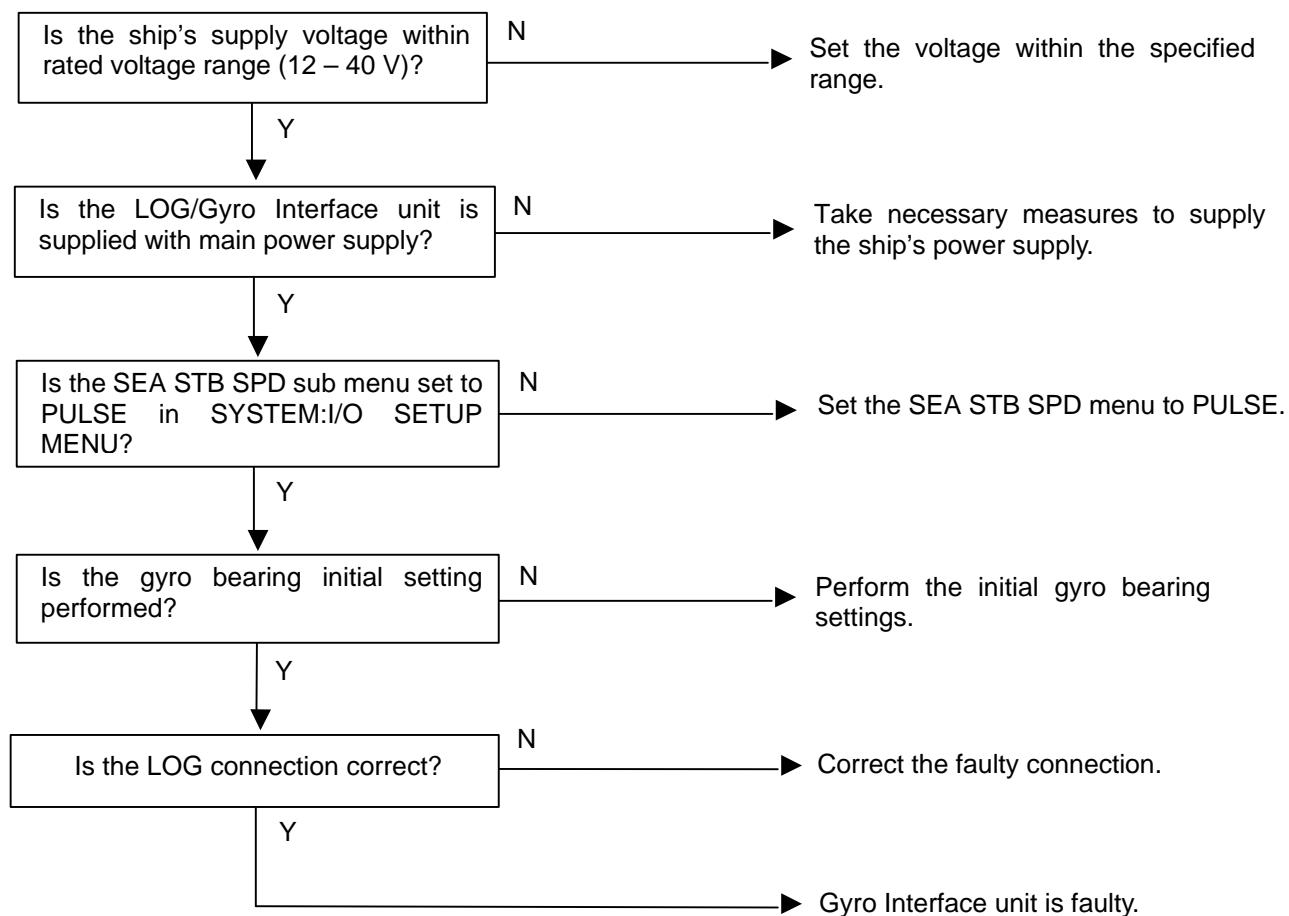
3. No display**4. Antenna does not respond**

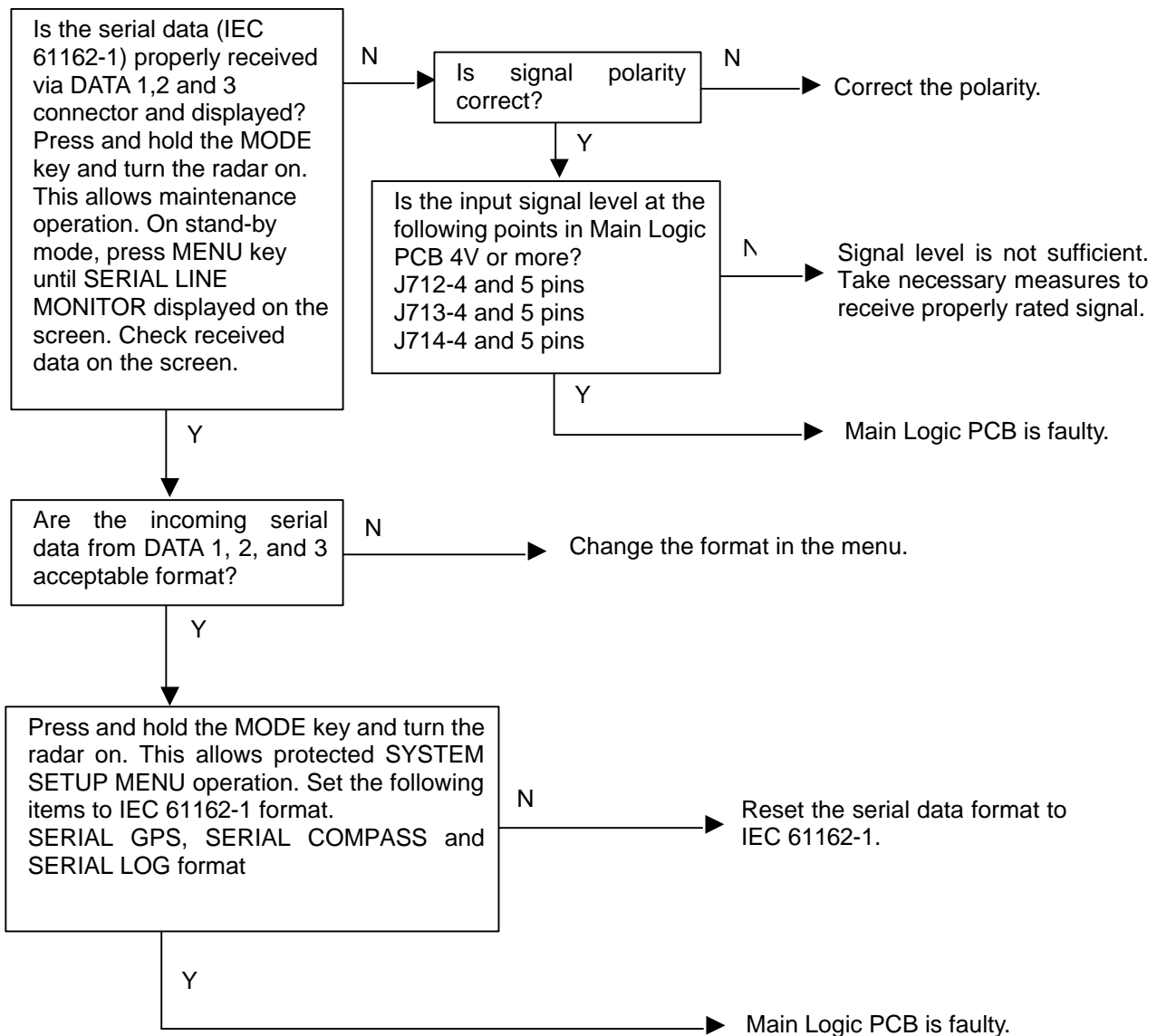
5. Faulty radar picture

6. Interface

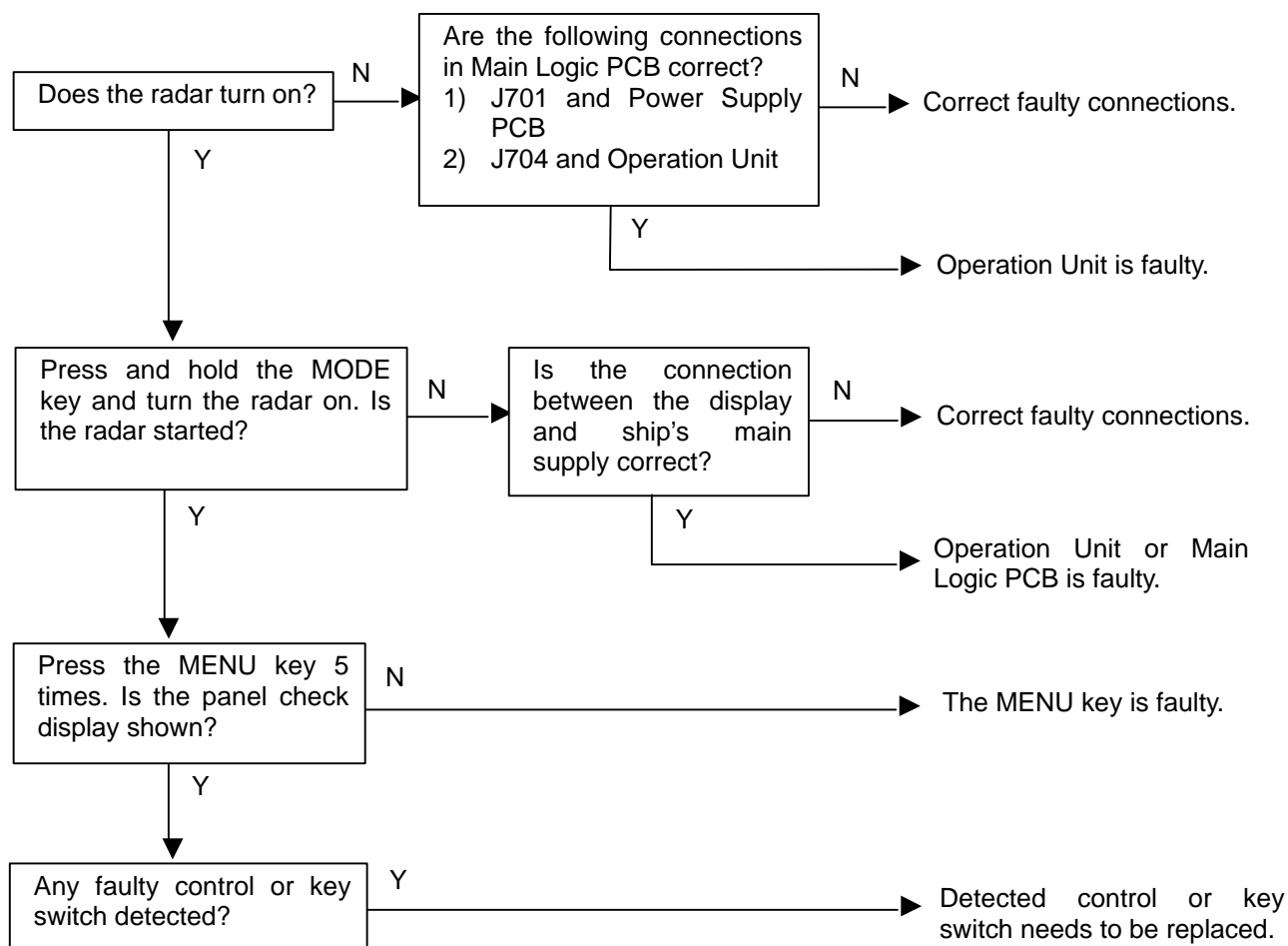
(1) Gyro Interface



(2) LOG Interface

(3) IEC 61162-1 Interface

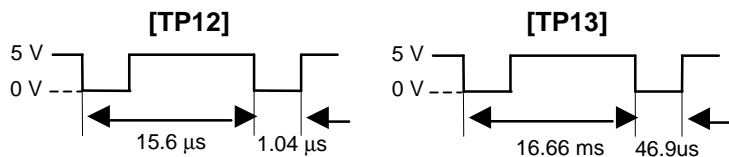
7. Operation Unit



8. Others

The display synchronization is unstable.

Are the following sync signals present at TP12 and TP13 in Main Logic PCB.



N → Main Logic PCB is faulty.

Y

Is the RGB signal presented at the J218 and J219 connector?

Y

→ LCD monitor unit is faulty.

N

→ Main Logic PCB is faulty.

Texts and graphics displays are erratic.

→ Main Logic PCB is faulty.

9. Antenna unit

+12V line is shorted.

Disconnect P6 (J6) from the Modulator PCB. Is the fault removed?

Y

→ IF PCB is faulty.

N

Disconnect P5 (J5) from the Modulator PCB. Is the fault removed?

N

→ Performance Monitor is faulty.

Y

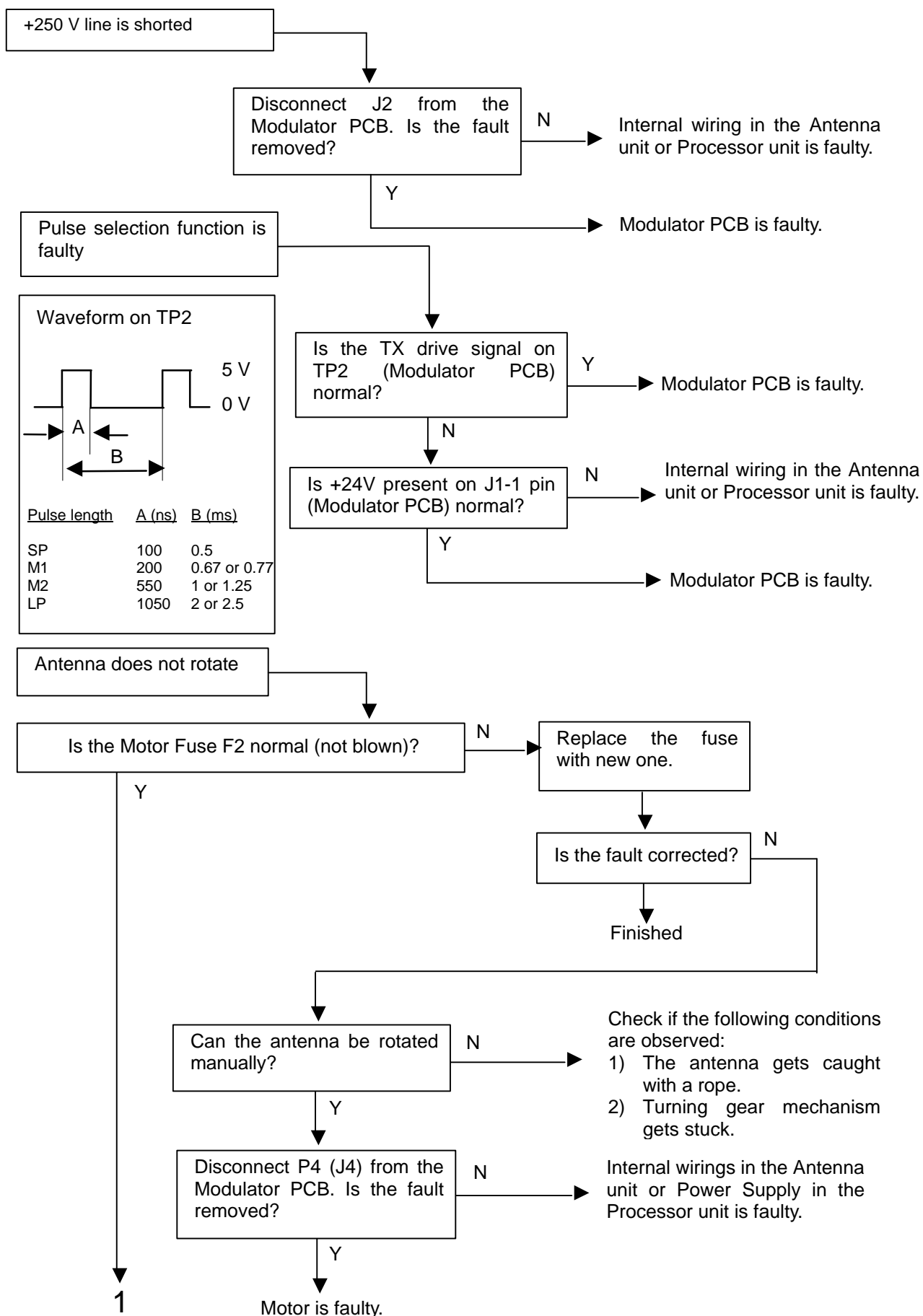
Disconnect P1 (J1) from the Modulator PCB. Is the fault removed?

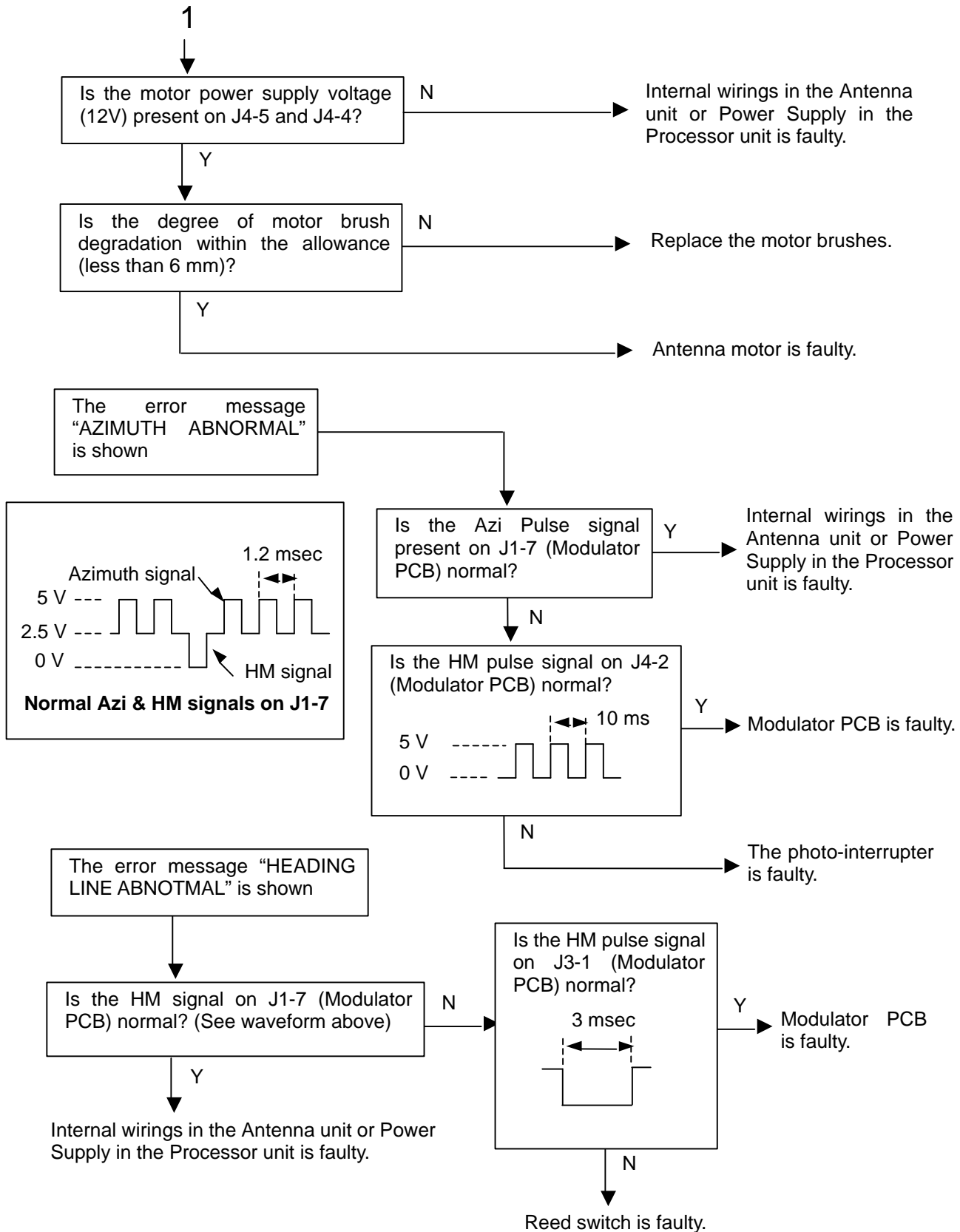
N

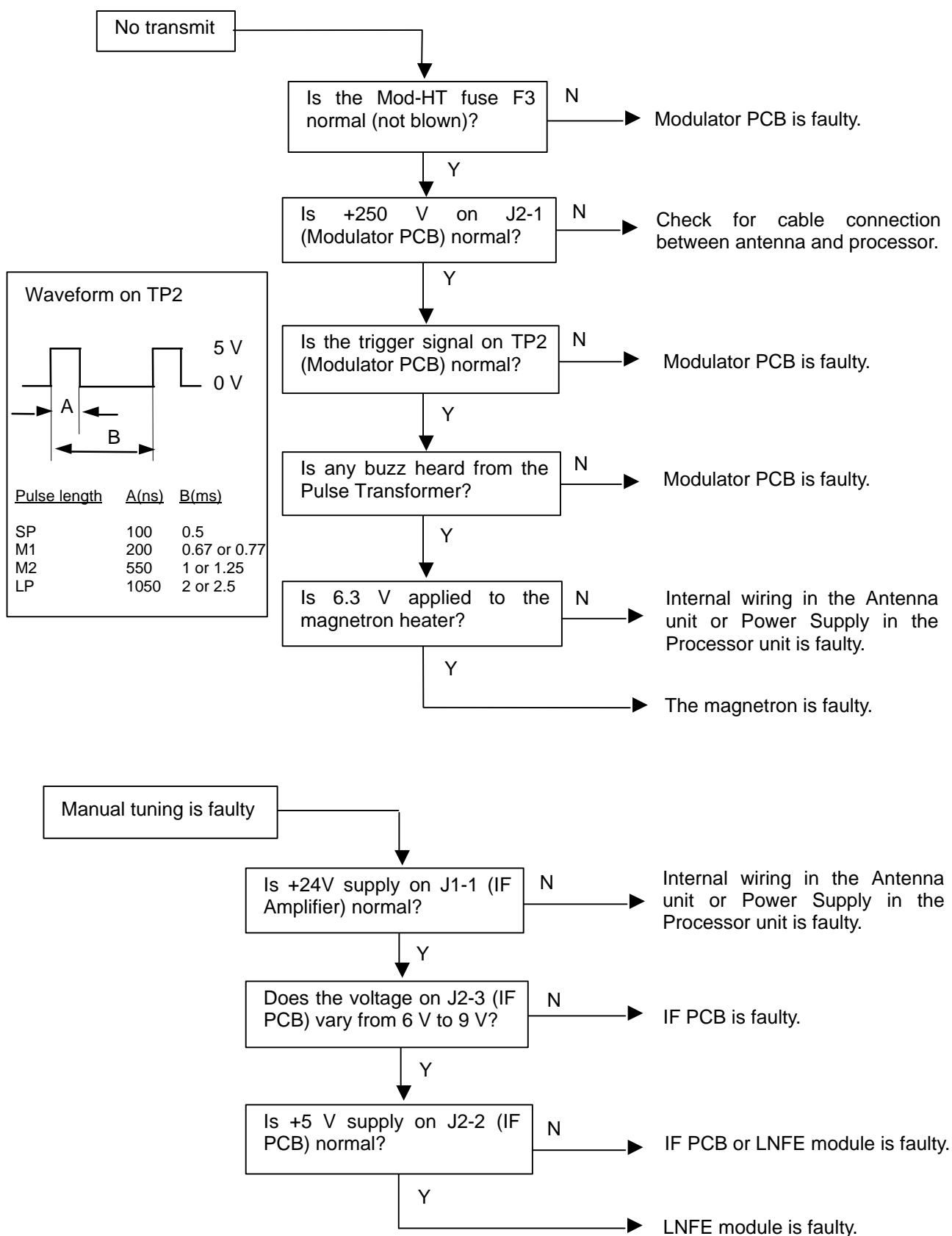
→ Internal wirings in the Antenna unit or Processor unit is faulty.

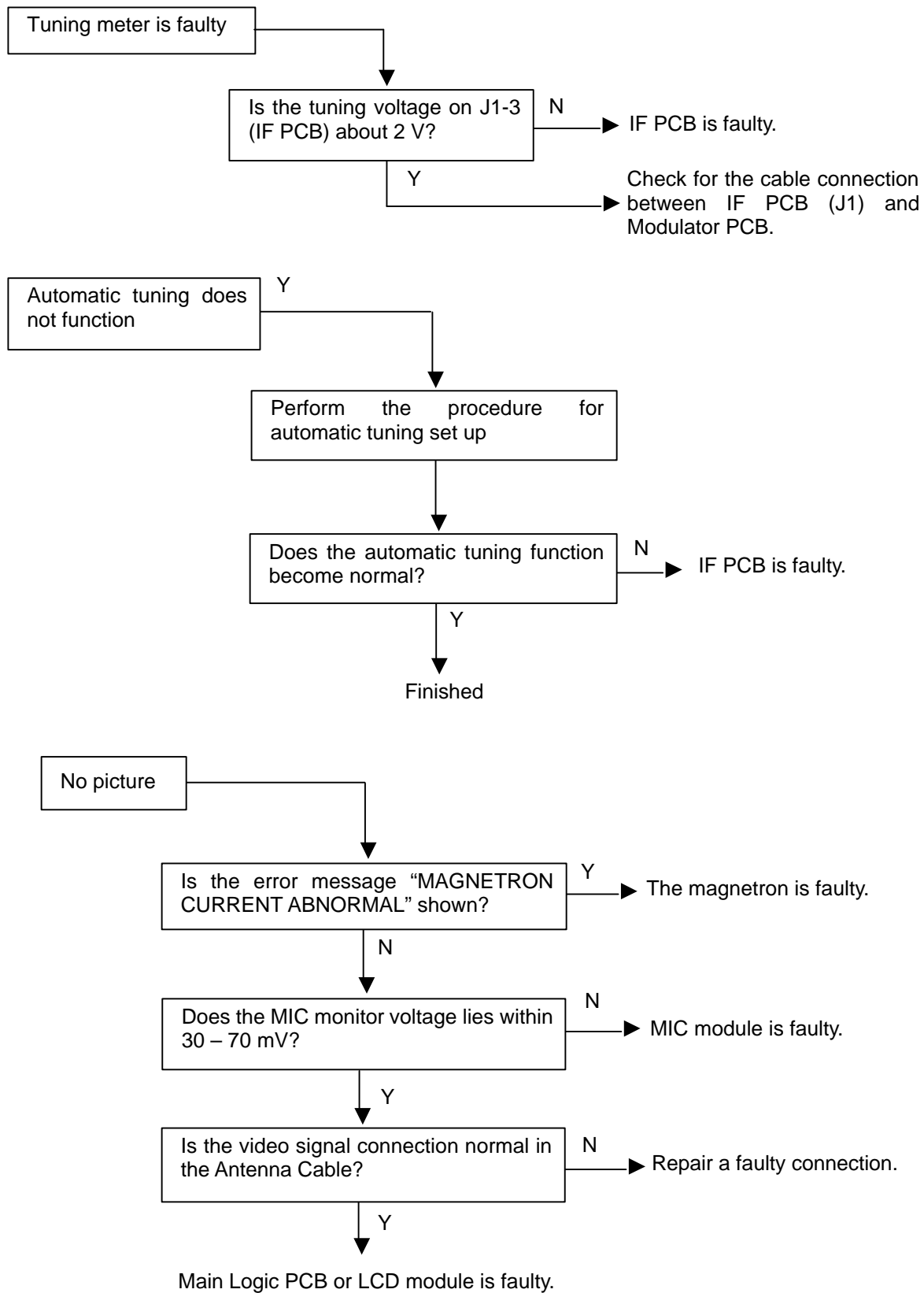
Y

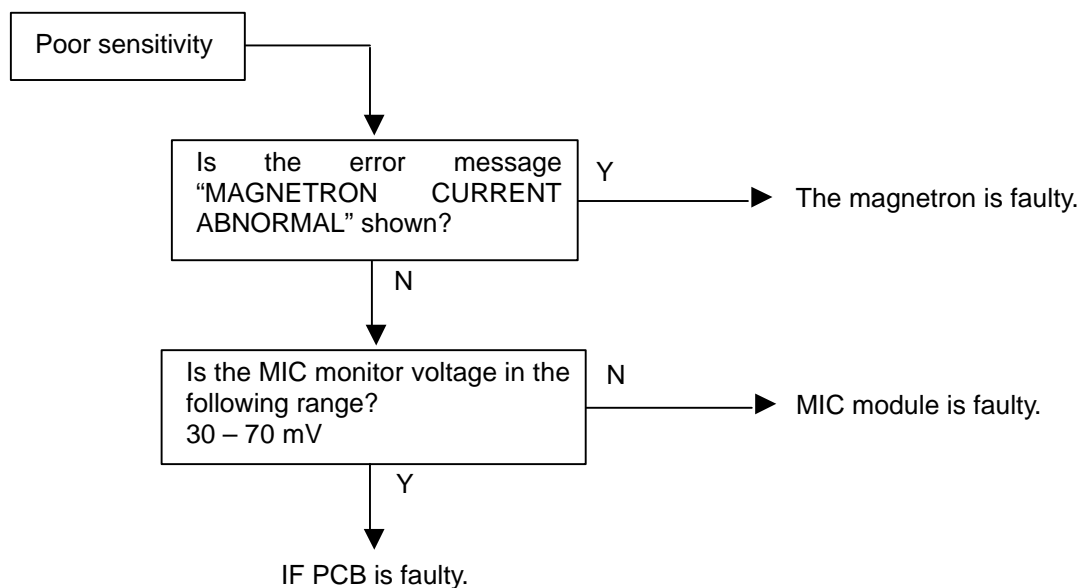
→ Modulator PCB is faulty











8.4 On board servicing

8.4.1 Replacing the fuses

There are three fuses provided on the rear panel of the processor unit. Details are as follows

- Fuse type and ratings

| Fuse name | Shape (Dimensions in mm) | Fuse Type | Ratings |
|------------------|---------------------------------------|-------------|---------|
| Main fuse | Tubular type ($\phi 6.3 \times 32$) | Normal Blow | 15 A |
| Modulator fuse | Tubular type ($\phi 5 \times 20$) | Normal Blow | 0.3 A |
| Drive Motor fuse | Tubular type ($\phi 5 \times 20$) | Normal Blow | 5 A |

- Location of the fuses

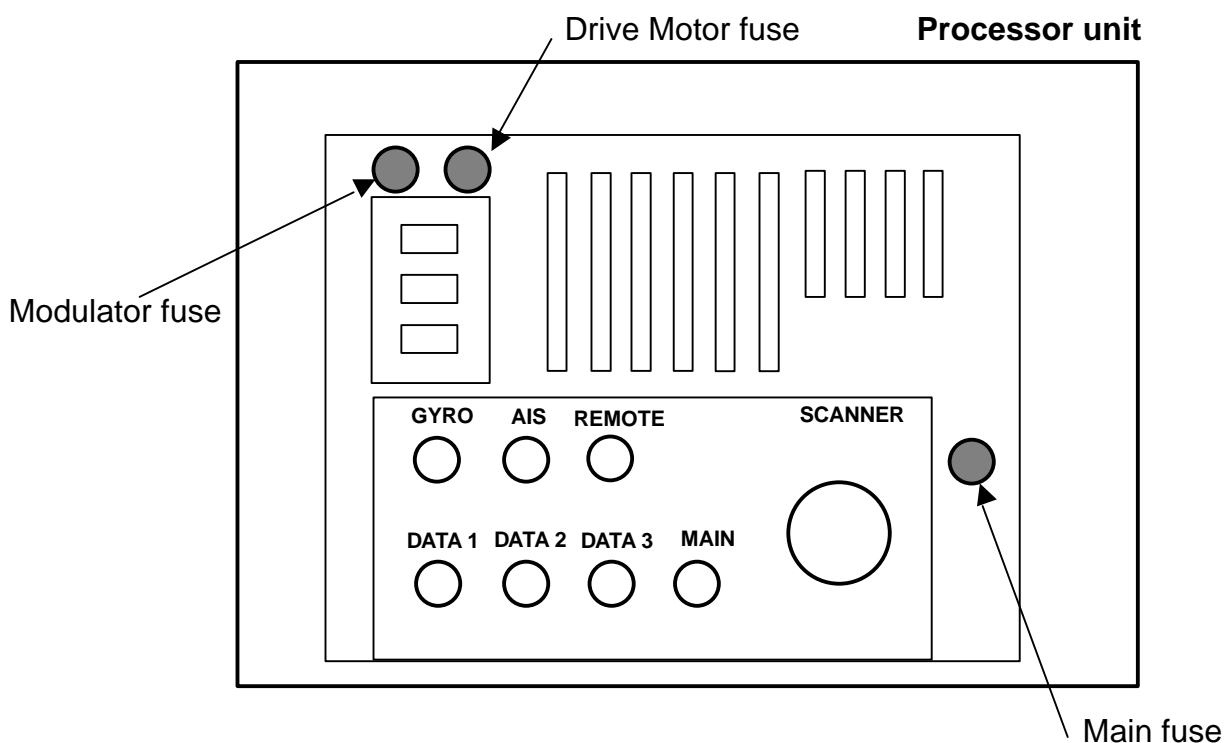


Figure 8.2 Fuses provided on the processor rear panel

Chapter 9 Maintenance

9.1 Periodic inspections and cleaning

Periodic inspection and cleaning is essential to allow the radar set to work in good order for a long period of time.

9.1.1 Monthly Check

(1) Check the antenna radiation surface for stains due to dirt soot. Wipe off the surface using a soft cloth soaked with fresh water or soapsuds. Also make sure the radiating surface of the aerial is free from residual paint or scratches.



Never turn the radar on while maintenance work is in process.

(2) If the display screen is dirty, clean the screen with a cloth soaked with anti-static agent. Do not use a dry cloth as it causes static charging, which accumulates dust.

9.1.2 Yearly check

Check the motor brushes of the antenna unit every 2,000 working hours. Replace them if the brushes are less than 6 mm in length.

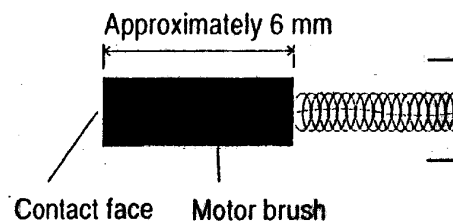


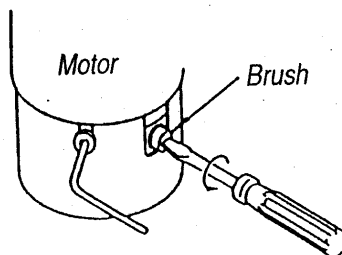
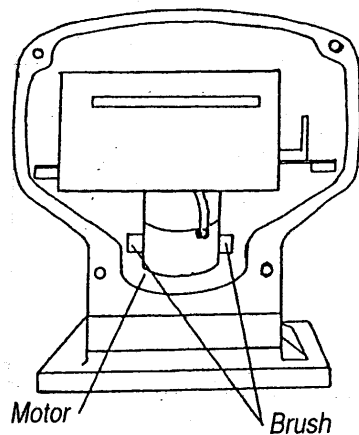
Figure 9.1 Criteria of the Motor Brush replacement

- (1) Loosen the four fixing screws that fasten the front side cover and remove the cover. The antenna motor will be found in the lower part in the antenna housing.
- (2) Use a flat-blade screwdriver to loosen the motor brushes as shown in Figure 9.2..
- (3) Insert a screwdriver into the groove provided on top of the brush and gently turn the screwdriver counter clockwise. Make sure to remove both brushes.
- (4) Install a new pair of brushes and reverse the procedure from step (3) to fix the brushes.



Alarm: Make sure to turn off the equipment before attempting to reach inside of the antenna unit. Failure to do so may lead to electrical shock.

Antenna housing unit



Gently turn the screwdriver counter clockwise to remove the motor brush.

Figure 9.2 Replacing the motor brushes

Chapter 10 Technical References

10.1 Serial input data sentence detail

Sentence name: IEC61162-1

Descriptions

(1) Data priority

Data such as waypoint display, own ship's position and the speed against water are available from two different sentences in IEC61162-1. These data are prioritized as follows:

| Data name | Available sentences | Priority |
|--------------------------------|---------------------|----------|
| Waypoint | RMB and BWC | RMB>BWC |
| Own ship's position | GGA and GGL | GGA>GGL |
| Own ship's speed against water | VBW and VHW | VBW>VHW |

(2) Route display

In case the RMB/BWC and RTE/WPL sentences are all input, only routes are displayed while the waypoint without route is not displayed.

(3) Checksum

Checksum is the total of all the EX-ORed data between the \$ and asterisk (*) signs.

| BWC | Bearing & Distance to Waypoint |
|-----|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| | <p>\$ -- BWC, , xxxx.xxx, N/S, xxxxx.xxx, E/W, xxx.x, T, , , xxx.x, N, xxx, a *hh <CR><LF></p> <p>Start of sentence</p> <p>These fields are used.</p> <p>Distance to go (nm) xx.xx: 00.00 to 09.99 nm xxx.x 010.0 to 999.9 nm</p> |
| GGA | Global Positioning System Fix Data |
| | <p>\$ -- GGA, , xxxx.xxx, N/S, xxxxx.xxx, E/W, x, , , , , , , , *hh <CR><LF></p> <p>Start of sentence</p> <p>These fields are not used</p> <p>GPS quality indicator 0: fix not available 1: GPS fix 2: DGPS fix 3 - 8: Not accepted in this sentence.</p> <p>Note for Talker device identifier: Only GP (GPS) is accepted.</p> |

| | |
|------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| GLC | Geographic Position, Loran C \$ - - GLC, , , , a *hh <CR><LF> <p>Start of sentence</p> <p>Sentence format</p> <p>Talker device</p> <p>Checksum</p> <p>Mode indicator</p> <p>This field is not used</p> <p>These fields are valid as far as the data are entered in 2 out of 5 TD fields; Otherwise the fields will be void</p> |
| GLL | Geographic Position, Latitude/Longitude \$ - - GGL, xxxx.xxx, N/S, xxxxx.xxx, E/W, , A, a *hh <CR><LF> <p>Start of sentence</p> <p>Sentence format</p> <p>Talker device</p> <p>latitude</p> <p>N: North S: South</p> <p>longitude</p> <p>E: East W: West</p> <p>A: Valid</p> <p>Checksum</p> <p>Mode indicator</p> <p>This field is not used</p> |
| HDT | Heading, True \$ - - HDT, xxx.x, T *hh <CR><LF> <p>Start of sentence</p> <p>Sentence format</p> <p>Talker device</p> <p>Heading (True)</p> <p>Checksum</p> <p>Note for Talker Device: Only HE (North Seeking Gyro) and HN (Non-north Seeking Gyro) are accepted.</p> |
| RMB | Recommended Minimum navigation Information \$ - - RMB, A, , , c-c, xxxx.xxx, N/S, xxxxx.xxx, E/W, xxx.x, xxx.x, , , a, *hh <CR><LF> <p>Start of sentence</p> <p>Sentence format</p> <p>Talker device</p> <p>A: Valid</p> <p>Waypoint ID</p> <p>Waypoint latitude</p> <p>N: North S: South</p> <p>Waypoint longitude</p> <p>E: East W: West</p> <p>Waypoint distance (nm) xx.xx: 00.00 to 09.99 nm xxx.x: 010.0 to 999.9 nm</p> <p>Waypoint Bearing (true)</p> <p>Checksum</p> <p>Mode indicator</p> <p>These fields are not used</p> |
| RTE | Routes \$ - - RTE, , x, W, , c-c, c-c, c-c, c-c *hh <CR><LF> <p>Start of sentence</p> <p>Sentence format</p> <p>Talker device</p> <p>Message mode</p> <p>Message number. Only one message is selectable</p> <p>Current waypoint</p> <p>Checksum</p> <p>Waypoint ID: <ul style="list-style-type: none"> The first 4 digits are valid to designate Waypoint ID, which can be assigned up to 8 kinds as maximum. Only a working route is displayed. </p> <p>This field is not used</p> |

| | |
|------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| VBW | Dual Ground/Water Speed <p>\$ - - VBW, xx.x, , A, xx.x, xx.x, A, , , , *hh <CR><LF></p> <p>Note for Talker device identifier: Only VD (Doppler Speed Log) is accepted.</p> |
| VDR | Set and Drift <p>\$ - - VDR, xxx.x, T, , , xx.x, N, *hh <CR><LF></p> <p>• The radar only accepts VD as a talker.</p> |
| VHW | Water Speed and Heading <p>\$ - - VHW, , , , xx.x, N, , , *hh <CR><LF></p> <p>Note 1: In case the speed data in knots is not available, then the metric speed data field will be recovered and used for alternative metric data.</p> <p>Note 2: Talker Device: Only VD (Doppler Speed Log), VM (Magnetic Water Speed Log) and VW (Mechanical Water Speed Log) are accepted.</p> |
| VTG | Course and Ground Speed <p>\$ - - VTG, xxx.x, T, , , xx.x, N, xx.x, K, a *hh <CR><LF></p> |
| WPL | Waypoint Location <p>\$ - - WPL, xxxx.xxx, N/S, xxxxx.xxx, E/W, c-c *hh <CR><LF></p> <p>Waypoint ID: The first 4 digits are valid to designate Waypoint ID, which can be assigned up to 8 kinds as maximum.</p> |

| | |
|------------|--------------------------------------------------------------------------------------------------------------|
| VDM | AIS Other Ship Data ! AI VDM, x, x, x, x, xxxxx· xxxx, N *hh <CR><LF> |
| VDO | AIS Own Ship Data ! AI VDO, x, x, x, x, xxxxx· xxxx, N *hh <CR><LF> |
| ALR | Set Alarm State \$ - - ALR, xxxxxx.xx, xxx, A, A, c- -c*hh <CR><LF> |

10.2 Tracking data output sentence detail

Sentence name: IEC61162-1

The ATA data can be output to an external unit via the data connector labeled “DATA 1,2 & 3” on the display rear panel.

| TTM | Tracked Target Message |
|-----|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| | <p>\$ RA TTM, x, x.x, xxx, T, xx.x, xxx.x, T, x.x, x.x, N, xxxx, a, , M, *hh <CR><LF></p> <p>Start of sentence</p> <p>Sentence format</p> <p>Talker device</p> <p>Target number (0 to 9)</p> <p>Bearing from own ship</p> <p>Target distance from own ship</p> <p>Target speed</p> <p>Target course</p> <p>Target (true) course</p> <p>Distance of Closest Point of Approach</p> <p>Time to CPA (min)</p> <p>Speed/distance units (nm)</p> <p>User data</p> <p>Checksum</p> <p>Type of acquisition</p> <p>These fields are not used</p> <p>Target status (See Note)</p> <p>Note for Target status: L: Lost, tracked target has been lost Q: Query, target in process of acquisition T: Tracking, target in process of tracking</p> |

10.3 Radar data output sentence detail

Sentence name: IEC61162-1

The Radar data can be output to an external unit via the data connector labeled “DATA 1,2 & 3” on the display rear panel.

10.3.1 Own Ship Data

| OSD | Own Ship Data |
|-----|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| | <p>\$ RA OSD, xxx.x, A, xxx.x, a, xx.x, a, x.x, x.x, N *hh <CR><LF></p> <p>Start of sentence</p> <p>Sentence format</p> <p>Talker device</p> <p>Own ship's Heading(True)</p> <p>Ship's True Heading Status: A=Valid</p> <p>Own ship's course</p> <p>Course reference</p> <p>Own ship's speed</p> <p>Speed reference</p> <p>Drift</p> <p>Set</p> <p>Speed units (K: km/h, N: Knot, S: SM/h)</p> <p>Checksum</p> <p>Note for Course/Speed reference: B: Log M: Manual W: Water R: Radar Tracking P: Positioning System</p> |

10.3.2 Radar System Data

| RSD | Radar System Data |
|-----|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| | <p>\$ RA RSD, x.x, x.x, x.x, x.x, x.x, x.x, x.x, x.x, x.x, x.x, a, a *hh <CR><LF></p> <p>Start of sentence</p> <p>Sentence format</p> <p>Talker device</p> <p>Origin 1 Range</p> <p>Origin 1 Bearing</p> <p>VRM 1 Range</p> <p>Origin 2 Range</p> <p>Origin 2 Bearing</p> <p>VRM 2 Range</p> <p>EBL 2 Bearing</p> <p>Cursor Range</p> <p>Cursor Bearing</p> <p>Display Range</p> <p>Range Unit (K/N/S)</p> <p>Display Mode C: Course Up H: Head Up N: North Up</p> <p>Checksum</p> |

10.4 Interface requirements

10.4.1 Input requirements

| Feature | Characteristics | |
|------------------|------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Power | Voltage Consumption | 24/32VDC, -10%, +30% 170 W |
| Gyro compass | Synchro Stepper Gear ratio Serial | Voltage value: 50VAC or 100VAC+/-10%, 50/60 Hz+/-10% Gear ratio: 1:360, 1:180, 1:90 Voltage value: 21.6 to 38.5 V (See NOTE) or 63 to 77 V (Standard) 1:360, 1:180, 1:90 To IEC61162-1 via opto-isolator |
| LOG | Mechanical input Electronic input Serial input | PRR: 100, 200, 400 pulse/nm Input type: opto-isolator (5V/5mA) Pulse width: 100 ms (min) Same as above To IEC61162-1 via opto-isolator |
| Serial interface | Signal standard | To IEC 61162-1 via opto-isolator |
| AIS interface | Signal standard | To IEC 61162-2 via floated RS422 |

NOTE: Changing Link settings are required on the Main Logic PCB for J721 to J725. Refer to Para. 4.6.6 for detail.

10.4.2 Data input/output serial line

Port name: DATA 1,2 & 3

The connector used:

Type LTWD-06PMMP-LC

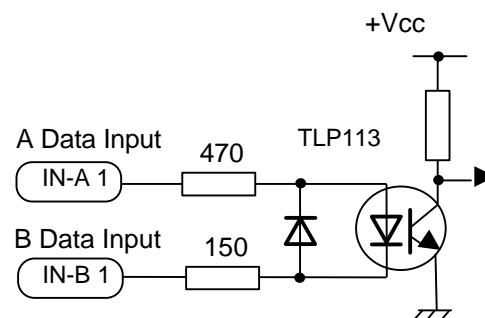
Serial Data input (listener side):

The IEC61162-1 standard signal can be received.

Input load: 470 + 150 ohms

Device: Opto-isolator

Type TLP113 (Toshiba)



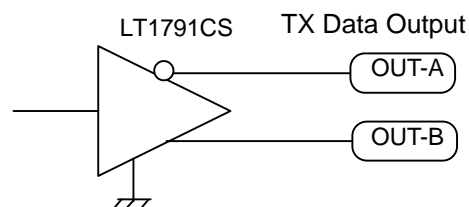
Serial data input circuit

Serial Data output (talker side):

The IEC61162-1 standard signal can be transmitted.

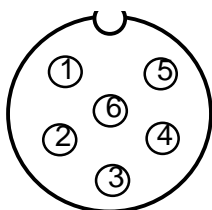
Device: RS422 Driver IC

Type LT1791CS (Linear Technology)



Serial data output circuit

Pin assignment on
Data Connector (Top view)



Data connector pin assignment

| DATA 1,2 & 3 | |
|--------------|--------|
| Pin No. | Name |
| 1 | Shield |
| 2 | OUT-A |
| 3 | OUT-B |
| 4 | IN-A |
| 5 | IN-B |
| 6 | GND |

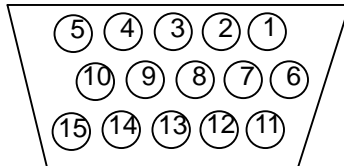
10.4.3 External monitor signal interface

Port name: VDR

The connector used: Small D-sub 15 pin

Pin assignment of the connector is as follows:

External CRT connector
(Top View)

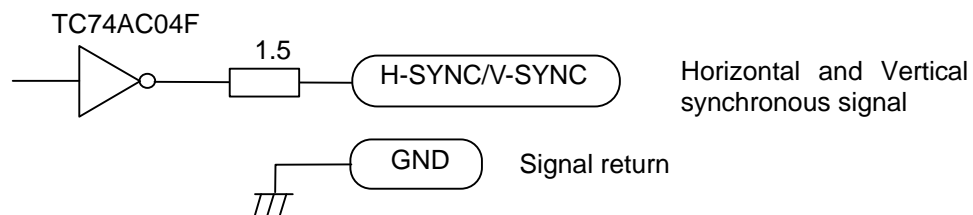


| Pin No. | Signal name |
|--------------|-------------|
| 1 | RVD |
| 2 | GVD |
| 3 | BVD |
| 6 | R-GND |
| 7 | G-GND |
| 8 | B-GND |
| 13 | H-SYNC |
| 14 | V-SYNC |
| 5,10 | GND |
| 4,9,11,12,15 | NC |

The signal specifications are as follows:

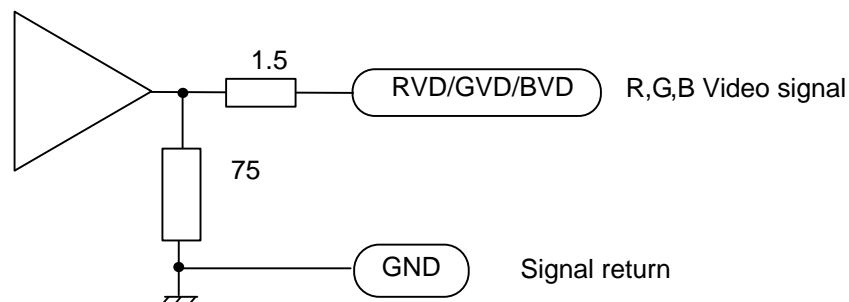
| Name | Frequency | Polarity | Pulse width | Level | Impedance |
|-----------------------------|-----------|----------|--------------|----------|--------------|
| Horizontal sync signal | 64.0kHz | Negative | 1.04 μ s | TTL | 200 Ω |
| Vertical synchronous signal | 60.0Hz | Negative | 46.9 us | TTL | 200 Ω |
| R,G,B Video signal | - | Positive | - | 0.7 Vp-p | 75 Ω |

Horizontal and Vertical synchronous signal output circuit



R,G,B Video signal output circuit

Video D/A Converter (FMS3818KRC)



10.4.4 Data input/output serial line (AIS)

Port name: AIS

The connector used:

Type LTWD-08PMMP-LC

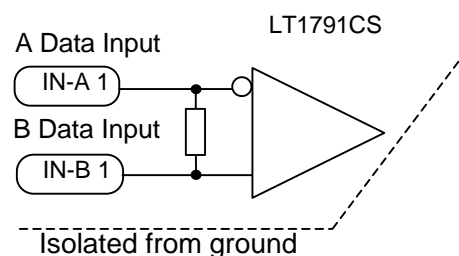
Serial Data input (listener side):

The IEC61162-1 standard signal can be received.

Input load: 94 ohms

Device: RS422 Driver/Receiver IC

Type LT1791CS (Linear Technology)



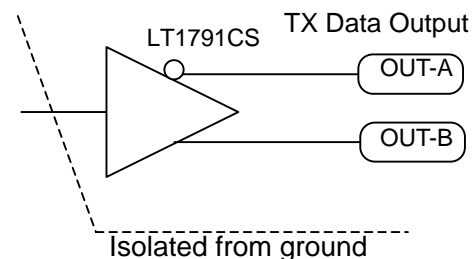
Serial data input circuit

Serial Data output (talker side):

The IEC61162-1 standard signal can be transmitted.

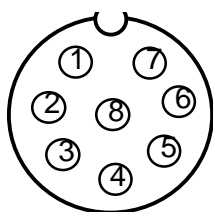
Device: RS422 Driver/Receiver IC

Type LT1791CS (Linear Technology)



Serial data output circuit

Pin assignment on
Data Connector (Top view)



Data connector pin assignment

| DATA 1,2 & 3 | |
|--------------|--------|
| Pin No. | Name |
| 1 | Shield |
| 2 | IN-B |
| 3 | IN-A |
| 4 | OUT-B |
| 5 | OUT-A |
| 6 | GND |
| 7 | ALARM+ |
| 8 | ALARM- |

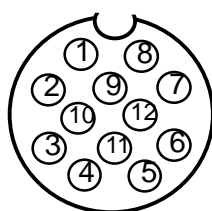
10.4.5 Radar Signal input/output

Port name: REMOTE

The connector used:

Type LTWU-12PMMP-LC

Pin assignment on
Data Connector
(Top view)



Data connector pin assignment

| Pin No. | NAME |
|---------|-----------|
| 1 | VIDEO OUT |
| 2 | TRIG OUT |
| 3 | GND |
| 4 | AZIP OUT |
| 5 | SHF OUT |
| 6 | GND |
| 7 | VIDEO IN |
| 8 | TRIG IN |
| 9 | GND |
| 10 | AZIP IN |
| 11 | SHF IN |
| 12 | +12Vdc |

DIP Switch S1-6 on the Logic PCB (E47-700B) in the Processor Unit (RP100AP)

The Processor Unit can be used as a radar remote display. When the status switch S1-#6 is set to ON, the display unit is operated with the radar signal supplied from external main display. When the status switch is set to the REMOTE position, never connect the scanner unit to the SCANNER connector.

10.4.6 Talker identifier accepted

The RA83P/84P/85P/93P/94P/95P series of radar accepts the following talker identifiers applied from external equipment.

| Talker device | Talker identifier | Display |
|------------------------------------|-------------------|---------------------------|
| Decca navigator | DE | DEC |
| Global positioning system GPS) | GP | GPS (See NOTE) |
| Differential GPS receiver (DGPS) | GP | DGPS (See NOTE) |
| GLONASS receiver | GL | GLO |
| Global navigation satellite system | GN | GNSS |
| Integrated navigation | IN | INS |
| Loran C | LC | LOR |
| Electronic positioning system | SN | EPFS |
| Gyro, north seeking | HE | GYRO |
| Gyro, non-north seeking | HN | GYRO |
| Compass, magnetic | HC | MAG |
| Doppler, other/general | VD | DOLOG |
| Speed LOG, water, magnetic | VM | LOG |
| Speed LOG, water, mechanical | VW | LOG |
| Other device | | display talker identifier |

NOTE

The on-screen device name, GPS or DGPS, is selected according to the GPS quality indicator in the GGA sentence. (Refer to Para 10.1 "Serial input data sentence detail")



Bundesrepublik Deutschland

Federal Republic of Germany

Bundesamt für Seeschifffahrt und Hydrographie

Federal Maritime and Hydrographic Agency



EC TYPE EXAMINATION (MODULE B) CERTIFICATE

This is to certify that:

Bundesamt für Seeschifffahrt und Hydrographie, specified as a "notified body" under the terms of „Schiffssicherheitsgesetz“ of 9. September 1998 (BGBl. I, p. 2860) modified last 27. February 2004 (BGBl. I, p. 307), did undertake the relevant type approval procedures for the equipment identified below which was found to be in compliance with the Navigation requirements of Marine Equipment Directive (MED) 96/98/EC as modified by Directive 2002/75/EC.

Applicant **Simrad AS**
Address **Nyaaskaien, N-4379 Egersund, Norway**

Manufacturer **Koden Electronics Co., Japan**
Address **Uenohara, Uenohara Machi, Kitatsuru-Gun, Yamanashi-Ken, Japan**

Annex A.1 Item **A.1 / 4.35 Radar Equipment with ATA**
(No & item designation) **A.1 / 4.36 Radar Equipment with EPA**

Product Name **MDC-17XXP / MDC-19XXP**

Trade Name(s) **RA83P / RA84P / RA85P / RA93P / RA94P / RA95P**

Specified Standard(s)

| | | |
|------------------------------------|-------------------------|-----------------------|
| IMO-Resolution A.694 (17) | IEC 60936-1 : 2002 | IEC 60872-2 : 1999 |
| IMO-Resolution A.813 (19) | IEC 61162-1 Ed.2 : 2000 | IEC 60872-3 : 2000 |
| IMO-Resolution MSC.64 (67) Annex 4 | | IEC 60945 Ed.3 : 1997 |

This certificate remains valid unless cancelled, expired or revoked.

Date of issue: 24.03.2004

Issued by: **Bundesamt für Seeschifffahrt und Hydrographie**
Bernhard-Nocht-Str. 78, 20359 Hamburg, Germany
Notified body 0735


Expiry date: 23.03.2009

Certificate No.: **6522 / 1131 / 2004**

This certificate consists of 2 pages.



by order


v. Arnim



Components necessary for operation:

See schedules 1

Approval Documentation:

Testreport No. BSH 6522 / 1113 / 2004

Testreport No. CETECOM 4-1003-01-01b/03

Testreport No. CETECOM 4-1003-01-02/03

Testreport No. CETECOM 2-2942-01-01/02

Testreport No. Delta K221784-1 Monitor J. Hatteland JH17T01MMD 17'

Testreport No. Delta E500053 Monitor J. Hatteland JH19T01MMD 19'

Documentation:

| | |
|--------------------|---------------------------------------------------|
| | RA83P / RA 84P / RA 85P / RA 93P / RA 94P / RA95P |
| Instruction Manual | 93142115_01 |

Tested software:

| | | | |
|-----------------------------------|-------------------|------------------------------|---------------|
| MDC-17XXP / MDC-18XXP / MDC-19XXP | Radar Logic Board | Gyro/Log Interface (KSA-08A) | ATA (MRE-300) |
| Software No. | KM-D56C | KM-D62A | KM-D07C |

Limitations on the acceptance or use of the product:

none

Places of production:

5278 Uenohara, Uenohara Machi

Kitatsuru-Gun, Yamanashi-Ken

409-0122 Japan

Notes:

The manufacturer shall inform Bundesamt für Seeschifffahrt und Hydrographie, as the notified body, of any modifications to the type-tested product(s) that may affect compliance with the requirements or conditions laid down for use of the product(s).

In case the specified regulations or standards are amended during the validity of this certificate, the product(s) must be re-certified before being placed on board vessels to which such amended regulations or standards apply.

The Mark of Conformity (wheelmark) may only be affixed to the type approved equipment, and a Manufacturer's Declaration of Conformity may only be issued, if the product quality system fully complies with the Marine Equipment Directive and is certified by a notified body against ANNEX B module D, E, or F of the Directive.

Example for the Application of the "Mark of Conformity":

xxxx number of the Notified Body responsible for quality surveillance module
yy Last two digits of the year in which the mark is affixed.

Notice on legal remedies available:

Objection to this document may be filed within one month after notification. The objection must be filed in writing to, or put on record at, Federal Maritime and Hydrographic Agency, Bernhard-Nocht-Str. 78, 20359 Hamburg, Germany

SCHEDULE 1 TO EC TYPE EXAMINATION (MODULE B) CERTIFICATE

No.: 6522 / 1131 / 2004

List of approved Equipment

| No. | Designation | Type Designation |
|-----|--------------------------------------|------------------------------------------------------------------------------------------------------|
| 1. | X-Band Scanner | a) 4 ft, Type RW701A-04 b) 6 ft, Type RW701A-06 |
| 2. | X-Band Transceiver with Turning Unit | a) 6 kW, Up Mast, Type RB717AP b) 12 kW, Up Mast, Type RB718AP c) 25 kW, Up Mast, Type RB719AP |
| 3. | Operation Unit | RO-100A |
| 4. | Display and Processor Units | |
| 4.1 | Processor Unit | a) RP-100P |
| 4.2 | Display Unit | a) 250 mm, colour, JH17T01MMD-A2 |
| | Display Unit | b) 250 mm, colour, JH19T01MMD-A2 |
| 5. | Electronic Units (ATA) | a) ATA function, Type MRE-300 |
| 6. | Other mandatory equipment | a) Gyro stabilisation/Log Interface, Type KSA-08A b) Performance Monitor X-Band, Type KPM-20 |

A Radar System is in minimum an assembly of one part out of each of the following component sections, see Table of Combinations for details.

- Scanner
- Transceiver with Turning unit
- Display Unit
- Operation Unit
- Performance Monitor
- Gyro stabilisation/Log interface

Depending on the configuration the radar will be capable to serve

1. As **Radar with ATA** compliant with **A.1/4.35**
2. As **Radar with EPA** compliant with **A.1/4.36**

Notice on legal remedies available:

Objection to this document may be filed within one month after notification. The objection must be filed in writing to, or put on record at, Federal Maritime and Hydrographic Agency, Bernhard-Nocht-Str. 78, 20359 Hamburg, Germany

SCHEDULE 2 TO EC TYPE EXAMINATION (MODULE B) CERTIFICATE

No.: 6522 / 1131 / 2004

Table of Combinations

| <div style="display: flex; justify-content: space-between; align-items: center;"> <div style="width: 60%; text-align: center;">Designation</div> <div style="width: 40%; text-align: center;">Type of RADAR</div> </div> | | | | | | | |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------|-----------------|---------------------------------------|----------------|------------------------------------------------|-----------------------|---------------------------|
| | | 1. | 2. | 3. | 4.1 | 5. | 6. |
| | | X-Band Scanners | X-Band Transceivers with tuning units | Operation Unit | Processor Unit with external 250mm PPI Display | Electronic Unit (ATA) | Other mandatory Equipment |
| 1.1 | X-Band RADAR RA-8XP / RA-9XP with EPA | X | X | X | X | | X |
| 1.2 | X-Band RADAR RA-8XP / RA-9XP with ATA | X | X | X | X | X | X |

Note: X = Mandatory equipment.

O = Optional for additional display systems, e.g. radar display in the wings.

D = One out of two possibilities is mandatory.

Notice on legal remedies available:

Objection to this document may be filed within one month after notification. The objection must be filed in writing to, or put on record at, Federal Maritime and Hydrographic Agency, Bernhard-Nocht-Str. 78, 20359 Hamburg, Germany

SUPPLEMENT TO SCHEDULE 1

EC TYPE EXAMINATION (MODULE B) CERTIFICATE

No.: 6522 / 1131 / 2004

Statement concerning Spurious Emissions, Out of Band Emissions and the Boundary between both

The following Radar Transceivers, which form part of the systems noted in this certificate, have been subject to a measurement procedure as detailed in IEC 60936-1, Ed. 1.1 (2002), Annex D, as contained in Amendment 1 and the guidelines contained in ITU-R Recommendation RM.1177. This standard defines the test method and requirements that ship-borne radar have to meet in order to comply with Appendix 3 of the Radio Regulations and ITU-R Recommendations SM.1539 and SM.1541.

The results of the measurement procedure were satisfactory and provide sufficient evidence that these Radar Transceivers are compliant with the criteria contained in the standards mentioned above and fulfil the requirements of Maritime Equipment Directive 96/98/EC as amended by 2001/53/EC and 2002/75/EC.

Table of measured Transceivers:

| Type | Model No. | Magnetron |
|----------------|------------------|------------------|
| X-Band Up Mast | RB717AP / 6KW | MSF 1422B |
| X-Band Up Mast | RB718AP / 12KW | MSF1425B |
| X-Band Up Mast | RB819AP / 25KW | M1458A |

The test reports detailing the tests and test results provided by the applicant are:

CETECOM 2-2942-01-01/02
CETECOM 4-1003-01-02/03

Notice on legal remedies available:

Objection to this document may be filed within one month after notification. The objection must be filed in writing to, or put on record at, Federal Maritime and Hydrographic Agency, Bernhard-Nocht-Str. 78, 20359 Hamburg, Germany