H1
MOUNT-HOLE3.2

H2
MOUNT-HOLE3.2

H3
MOUNT-HOLE3.2

H4
MOUNT-HOLE3.2

H5
MOUNT-HOLE2.8

H6
MOUNT-HOLE2.8

H7
MOUNT-HOLE2.8

H8
MOUNT-HOLE2.8

	P00_COVER
	Moonwalker
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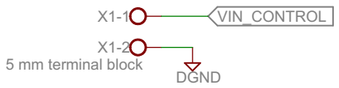
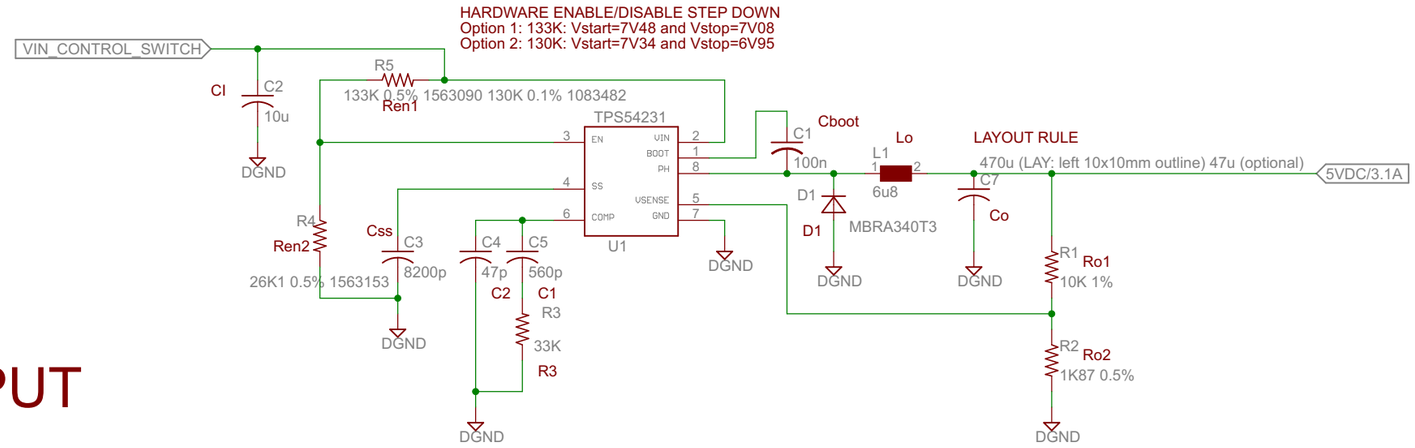
MAIN LIPO CONTROL INPUT

For round LIPO Holder 2.54 mm
connector with screws

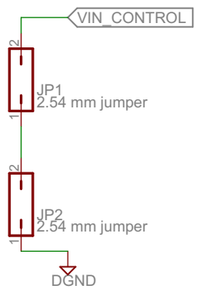


VIN_CONTROL_SWITCH to 5VDC (2A MAX)



SECUNDARY LIPO CONTROL INPUT

For helicopter LIPOs
Check 2.54mm pitch into layout

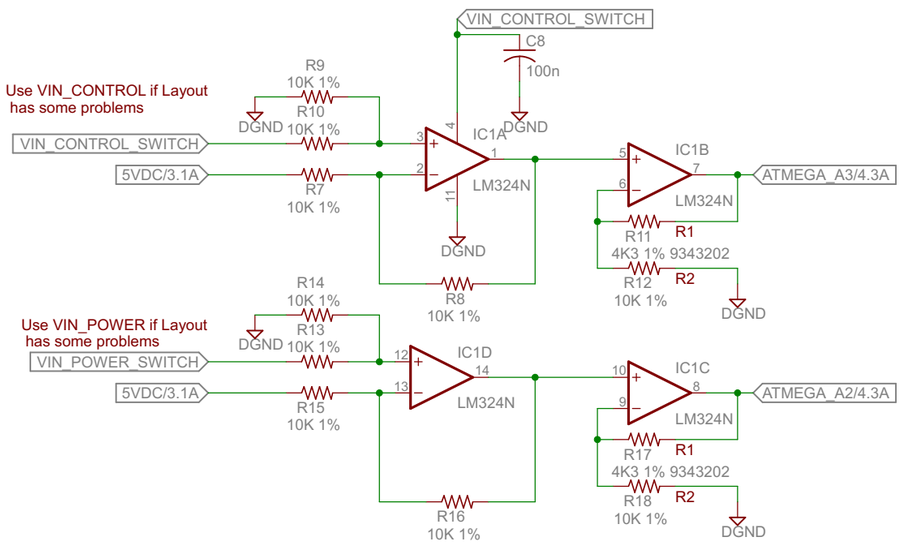


GNDs

Use R19 or little wire

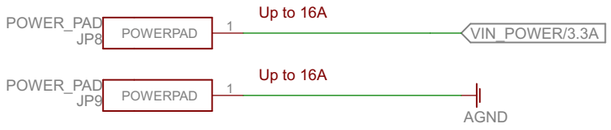
BATTERY VOLTAGE READER

(VIN_CONTROL_SWITCH-5VDC)*(1+R1/R2)=ICBoutput
(VIN_POWER_SWITCH-5VDC)*(1+R1/R2)=ICDoutput



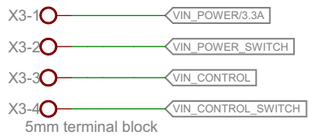
MAIN LIPO POWER INPUT

Two big PADS to connect two cables
Up to 10A

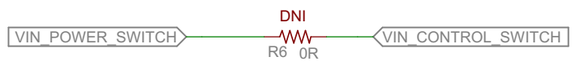


ON/OFF SWITCH

Switch is located at chassis car
1 and 3 are inputs; 2 and 4 are outputs



Use VIN_POWER_SWITCH as VIN_CONTROL_SWITCH
Configuration not used by default



	P01_POWER
	Moonwalker
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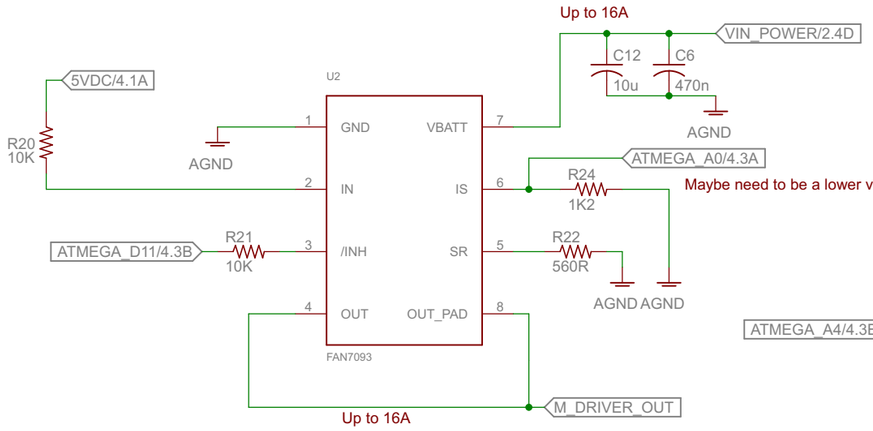
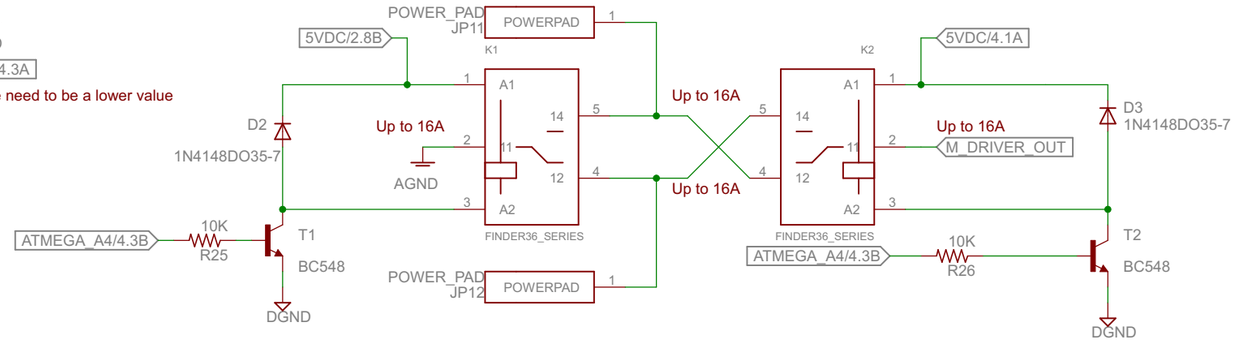
MOTORs DRIVER

Up to 16A



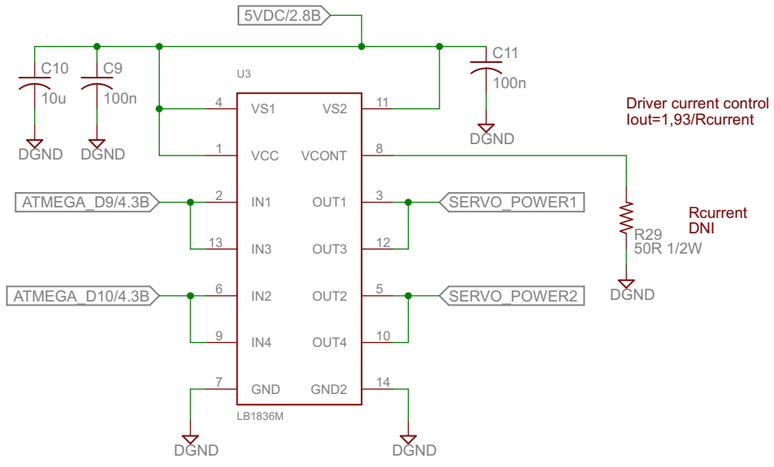
MOTORs FORWARD/REVERSE and OUTPUTs

Up to 16A
Relay coil doesn't have polarity

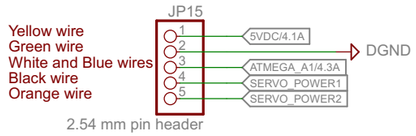


SERVO DRIVER

Control onboard chasis-servo



SERVO OUTPUTs



	P02_MOTORs
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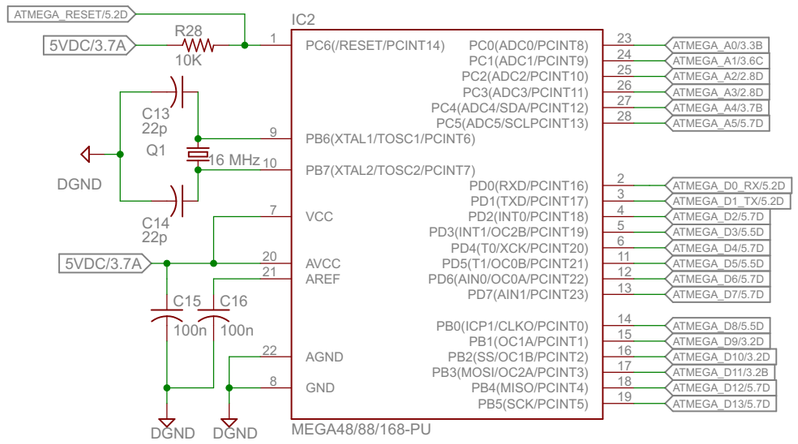
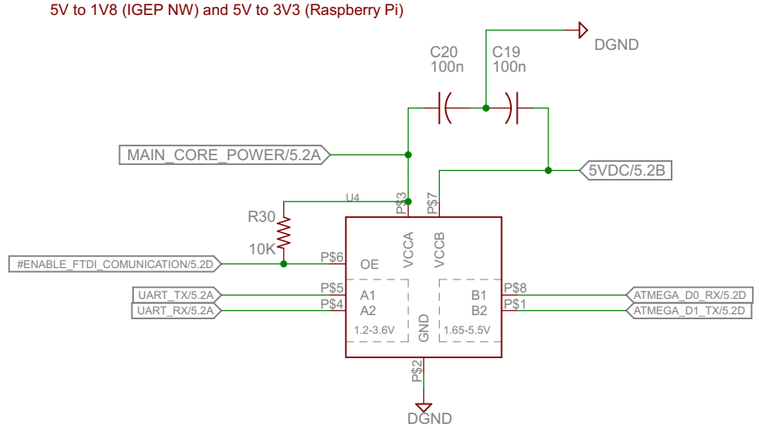
ATMEGA 8bits

Main core expansion board



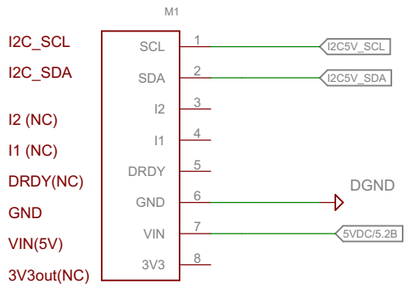
UART communication level translator

5V to 1V8 (IGEP NW) and 5V to 3V3 (Raspberry Pi)



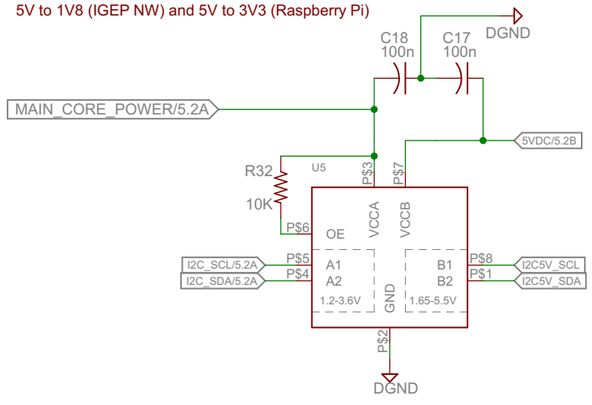
I2C accelerometer and compass

http://www.adafruit.com/products/1120
Dont connect highest devices near or under module sensor



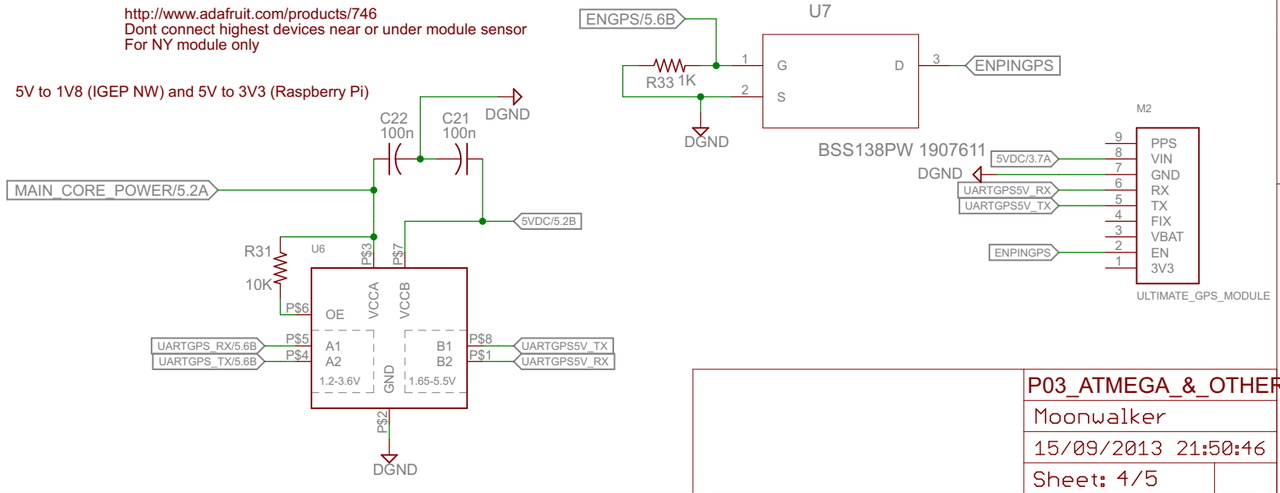
I2C communication level translator

5V to 1V8 (IGEP NW) and 5V to 3V3 (Raspberry Pi)



UART GPS translator and GPS module

http://www.adafruit.com/products/746
Dont connect highest devices near or under module sensor
For NY module only



	P03_ATMEGA_&_OTHERS
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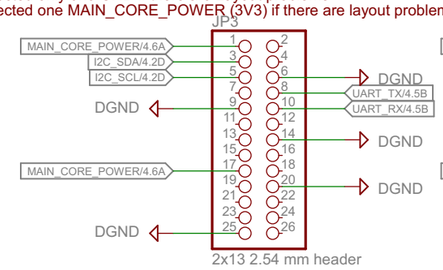
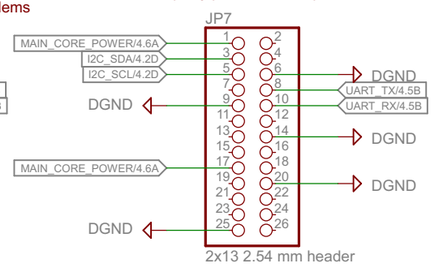
RASPERRY PI HEADERs

Comunication and power
Can be connected only one GND if there are Layout problems
Can be connected one MAIN_CORE_POWER (3V3) if there are layout problems



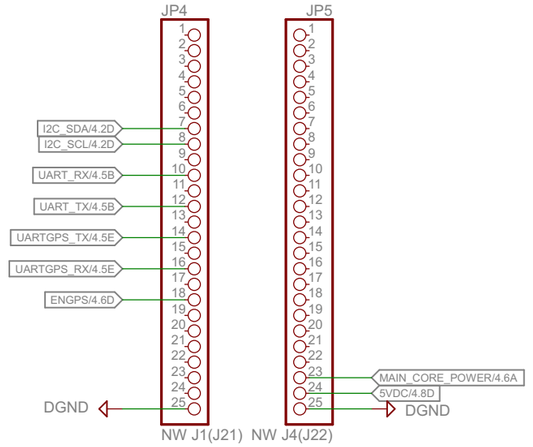
If there are rasperry pi stabilization problems



Main power board

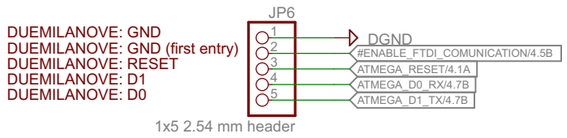
NEW YORK HEADERs

Comunication and power
Respect J1 and J2 distance: 22,8mm
First six pin can be remove if Layout problems ocurred



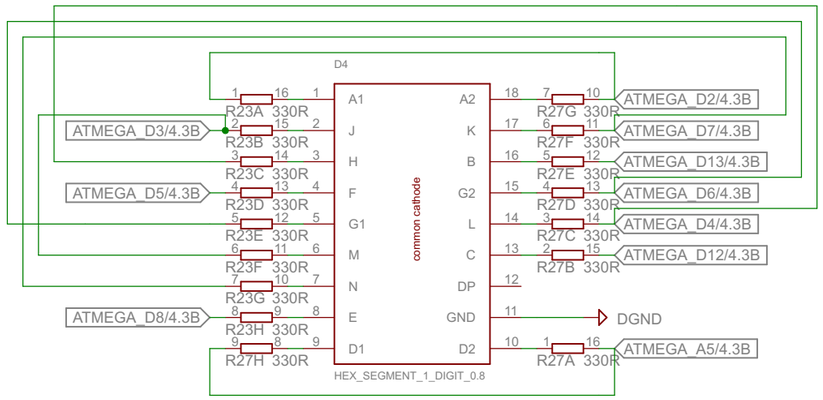
ATMEGA PROGRAMER HEADER

Use FT232RL (Duemilanove FTDI) and Arduino software
http://arduino.cc/en/Tutorial/ArduinoToBreadboard



ATMEGA HEX SEGMENT DEBUGGER

Use FT232RL (Duemilanove FTDI) and Arduino software
http://arduino.cc/en/Tutorial/ArduinoToBreadboard
Resistor array value not defined yet. Prove Hex segment before (330R by default)



	P04_COMUNICATIONS
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	Sheet: 5/5