



DAMA 50

Written Assignment II

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[DAMA 50] Written Assignment 2

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Problem 7

Consider the Euclidean vector space \mathbb{R}^5 with the Euclidean inner product. A subspace $U \subset \mathbb{R}^5$ is defined by

$$U = \text{span} \left\{ \begin{bmatrix} 0 \\ -1 \\ 2 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ -3 \\ 1 \\ -1 \\ 2 \end{bmatrix}, \begin{bmatrix} -3 \\ 4 \\ 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ -3 \\ 5 \\ 0 \\ 7 \end{bmatrix} \right\}.$$

Using **Sagemath**

- check if the vectors that span U are linearly independent;
 - find the projection matrix that maps \mathbb{R}^5 onto U ;
 - find the projection of the vector $x = [-1 \ 9 \ -1 \ 4 \ 1]^T$ onto U ;
 - compute the projection error in question (c) both analytically and numerically.
-
-

(a)

Define the vectors u_1, u_2, u_3 and u_4

In [1]: %display latex

In [2]:
u1=vector(QQ, [0,-1,2,0,2])
u2=vector(QQ, [1,-3,1,-1,2])
u3=vector(QQ, [-3,4,1,2,1])
u4=vector(QQ, [-1,-3,5,0,7])
show(u1,u2,u3,u4)

(0, -1, 2, 0, 2) (1, -3, 1, -1, 2) (-3, 4, 1, 2, 1) (-1, -3, 5, 0, 7)

Compute the matrix M

In [3]: `M=column_matrix([u1,u2,u3,u4]);M`

Out[3]:

$$\begin{pmatrix} 0 & 1 & -3 & -1 \\ -1 & -3 & 4 & -3 \\ 2 & 1 & 1 & 5 \\ 0 & -1 & 2 & 0 \\ 2 & 2 & 1 & 7 \end{pmatrix}$$

Check for linear dependence with Row Echelon Form

In [4]: `M.echelon_form()`

Out[4]:

$$\begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

The vectors that span U are not linearly dependent. Only u_1 , u_2 and u_3 are linearly independent because they are the only pivot columns.

(b)

Compute the matrix A of the basis vectors of U

In [5]: `A=column_matrix([u1,u2,u3]);A`

Out[5]:

$$\begin{pmatrix} 0 & 1 & -3 \\ -1 & -3 & 4 \\ 2 & 1 & 1 \\ 0 & -1 & 2 \\ 2 & 2 & 1 \end{pmatrix}$$

In [6]: `At=transpose(A);At`

Out[6]:

$$\begin{pmatrix} 0 & -1 & 2 & 0 & 2 \\ 1 & -3 & 1 & -1 & 2 \\ -3 & 4 & 1 & 2 & 1 \end{pmatrix}$$

Let \vec{x} be an arbitrary vector of \mathbb{R}_5 . Then the projection of \vec{x} onto U is $Proj_U \vec{x} = A(A^T A)^{-1} A^T \vec{x}$ and the projection matrix is $P_\pi = A(A^T A)^{-1} A^T$

```
In [7]: Pπ=A*((At*A).inverse())*At;Pπ
```

Out[7]:

$$\begin{pmatrix} \frac{10}{21} & -\frac{2}{7} & \frac{4}{21} & -\frac{1}{7} & -\frac{1}{3} \\ -\frac{2}{7} & \frac{43}{63} & \frac{4}{63} & \frac{2}{7} & -\frac{2}{9} \\ \frac{4}{21} & \frac{4}{63} & \frac{58}{63} & \frac{1}{7} & \frac{1}{9} \\ -\frac{1}{7} & \frac{2}{7} & \frac{1}{7} & \frac{1}{7} & 0 \\ -\frac{1}{3} & -\frac{2}{9} & \frac{1}{9} & 0 & \frac{7}{9} \end{pmatrix}$$

(c)

The simple and easy way

We can just multiply the projection matrix P_π with the vector \vec{x} to find $\pi_U(x)$

```
In [8]: x=vector(QQ,[-1,9,-1,4,1]);x
```

Out[8]: $(-1, 9, -1, 4, 1)$

```
In [9]: px=Pπ*x;px
```

Out[9]: $\left(-\frac{29}{7}, \frac{51}{7}, \frac{1}{7}, \frac{22}{7}, -1\right)$

The more analytical approach as shown in Example 3.11 of "Mathematics for Machine Learning"

We compute the matrix $A^T A$ and the vector $A^T x$

```
In [10]: x=matrix([-1,9,-1,4,1]).transpose();x
```

Out[10]:

$$\begin{pmatrix} -1 \\ 9 \\ -1 \\ 4 \\ 1 \end{pmatrix}$$

```
In [11]: AtA=At*A;AtA
```

Out[11]:

$$\begin{pmatrix} 9 & 9 & 0 \\ 9 & 16 & -14 \\ 0 & -14 & 31 \end{pmatrix}$$

```
In [12]: Atx=At*x;Atx
```

```
Out[12]: ⎛ -9 ⎞  
          ⎜ -31 ⎟  
          ⎝ 47 ⎠
```

We now solve the equation $A^T A \lambda = A^T x$ to find λ :

```
In [13]: var('λ1,λ2,λ3,λ')
```

```
Out[13]: (λ₁, λ₂, λ₃, λ)
```

```
In [14]: λ=matrix([λ1,λ2,λ3]).transpose();λ
```

```
Out[14]: ⎛ λ₁ ⎞  
          ⎜ λ₂ ⎟  
          ⎝ λ₃ ⎠
```

```
In [15]: B=AtA*λ;B
```

```
Out[15]: ⎛ 9 λ₁ + 9 λ₂ ⎞  
          ⎜ 9 λ₁ + 16 λ₂ - 14 λ₃ ⎟  
          ⎝ -14 λ₂ + 31 λ₃ ⎠
```

```
In [16]: equations = [B[0][0]==Atx[0][0], B[1][0]==Atx[1][0], B[2][0]==Atx[2][0]];equations
```

```
Out[16]: [9 λ₁ + 9 λ₂ = (-9), 9 λ₁ + 16 λ₂ - 14 λ₃ = (-31), -14 λ₂ + 31 λ₃ = 47]
```

```
In [17]: solutions = solve(equations, [λ1,λ2,λ3]);solutions
```

```
Out[17]: ⎡ ⎛ 1 ⎞ ⎛ -8 ⎞ ⎛ 1 ⎞ ⎤  
      ⎢ ⎜ - — ⎟ , ⎜ — ⎟ , ⎜ ⎟ ⎥  
      ⎣ ⎝ 7 ⎠ ⎝ 7 ⎠ ⎝ 1 ⎠ ⎦
```

```
In [18]: λt=matrix([solutions[0][0].rhs(),solutions[0][1].rhs(), solutions[0][2].rhs()]).transpose();λt
```

```
Out[18]: ⎛ 1 ⎞  
          ⎜ - — ⎟  
          ⎝ 7 ⎠  
          ⎛ -8 ⎞  
          ⎜ — ⎟  
          ⎝ 7 ⎠  
          ⎛ 1 ⎞
```

The projection of $\pi_U(x)$ of x onto U can be computed via $\pi_U(x) = A\lambda$

```
In [19]: ΠuX = A*λt; ΠuX
```

```
Out[19]: ⎛ - 29 ⎞  
          ⎜ ⎟  
          ⎜ 7 ⎟  
          ⎜ 51 ⎟  
          ⎜ 7 ⎟  
          ⎜ 1 ⎟  
          ⎜ 7 ⎟  
          ⎜ 22 ⎟  
          ⎜ 7 ⎟  
          ⎜ -1 ⎟
```

(d)

The projection error in question (c) is the norm of the difference vector between the original vector and its projection onto U . That is $\|x - \pi_U(x)\|$

```
In [20]: x=vector(QQ,[-1,9,-1,4,1]);x
```

```
Out[20]: (-1, 9, -1, 4, 1)
```

```
In [21]: px=Pπ*x;px
```

```
Out[21]: ⎛ - 29 ⎞ ⎛ 51 ⎞ ⎛ 1 ⎞ ⎛ 22 ⎞ ⎛ -1 ⎞  
          ⎜ 7 ⎟ ⎜ 7 ⎟ ⎜ 7 ⎟ ⎜ 7 ⎟ ⎜ ⎟
```

```
In [22]: analytical = norm(x-px);analytical
```

```
Out[22]: 2 √(33 / 7)
```

```
In [23]: numerical= n(analytical);numerical
```

```
Out[23]: 4.34248118673448
```

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Problem 8

Given a non-zero vector $v \in \mathbb{R}^m$ the Householder matrix P is defined as

$$P = \mathbf{1} - \beta vv^T, \quad \beta = \frac{2}{v^T v}$$

where $\mathbf{1}$ is the m -by- m identity matrix. If a vector $x \in \mathbb{R}^m$ is multiplied by P , then it is reflected in the hyperplane $\{\text{span}(v)\}^\perp$. Given $v = (1, -1, 1)^T$, use Sagemath to

- compute the associated Householder matrix P as well as P^2 ;
 - compute the vector $x' = Px$, where $x = (1, 1, 3)^T$;
 - compute and the lengths of both x and x' and comment on the result;
 - plot the vectors v, x, x' in a common 3-dimensional plot.
-
-

In [3]: `restore()`

In [4]: `%display latex`

(a)

Define vector $v = (1, -1, 1)^T$

In [5]: `v=vector([1,-1,1])`

In [6]: `id3=identity_matrix(3)`

Compute the Householder matrix P which is defined as $P = \mathbf{1} - \beta vv^T$

In [7]: `P=id3-2/(v.row()*v.column())[0][0]*v.column()*v.row();P`

Out[7]:

$$\begin{pmatrix} \frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} & \frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & \frac{1}{3} \end{pmatrix}$$

Verify that P is symmetrical

In [8]: `P==P.transpose()`

Out[8]: `True`

Compute P^2

```
In [9]: P**2
Out[9]: ⎛1 0 0
          ⎜0 1 0
          ⎝0 0 1
```

We notice that P is a square, symmetrical matrix which implies that P and P^T are equal. We also see that $P^2 = I_{3x3} \Rightarrow P \cdot P = I_{3x3} \Rightarrow P \cdot P^T = I_{3x3}$ which implies that P is orthogonal.

(b)

First we define vector $x = (1, 1, 3)^T$

```
In [10]: x=vector([1,1,3]);x
Out[10]: (1, 1, 3)
```

Compute vector $x' = Px$

```
In [11]: x2=P*x.column();vector(x2.list())
Out[11]: (-1, 3, 1)
```

(c)

Compute the length of x

```
In [12]: norm(x)
Out[12]: √11
```

Compute the length of x'

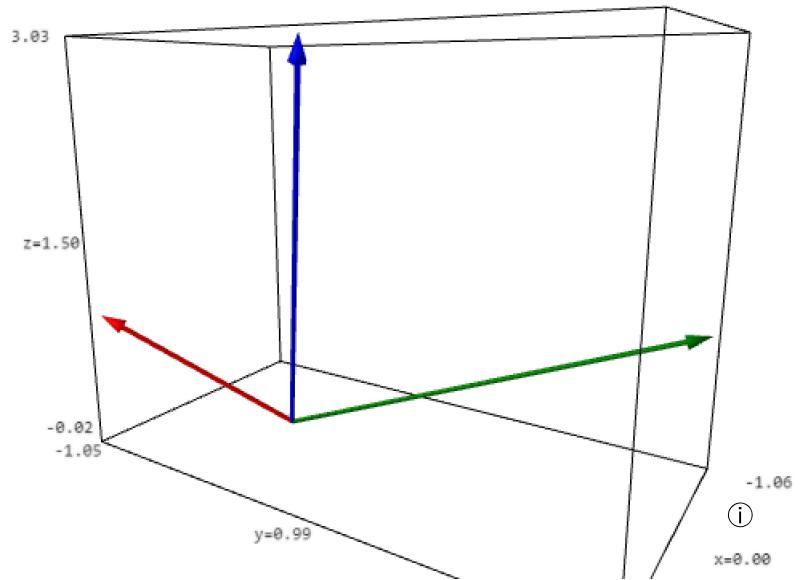
```
In [13]: norm(vector(x2.list()))
Out[13]: √11
```

The lengths of x and x' are equal, which is to be expected since the length of a vector x is not changed when transforming it using an orthogonal matrix such as P .

(d)

```
In [14]: arrows= arrow((0,0,0),(1,-1,1), color = "red")+\narrow((0,0,0),(1,1,3), color = "blue")+\narrow((0,0,0),(-1,3,1), color = "green");arrows
```

Out[14]:



[DAMA 50] Written Assignment 2

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Problem 9

Using by-hand calculation,

- (a) find the 3 by 3 real symmetric matrix S given that

$$x^T S x = 4(x_1 - x_2 + 2x_3)^2$$

given $x = (x_1, x_2, x_3)^T$.

- (b) Is S positive definite ? Is it positive semi-definite?
-

- (a) Let S be a 3 by 3 real symmetric matrix. Then for $a, b, c, d, e, f \in \mathbb{R}$ we are given that

$$x^T S x = 4(x_1 - x_2 + 2x_3)^2 \Leftrightarrow (x_1 \ x_2 \ x_3) \cdot \begin{pmatrix} a & d & e \\ d & b & f \\ e & f & c \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 4(x_1 - x_2 + 2x_3)^2 \Leftrightarrow$$

$$\Leftrightarrow (ax_1 + dx_2 + ex_3 \quad dx_1 + bx_2 + fx_3 \quad ex_1 + fx_2 + cx_3) \cdot \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} =$$

$$= 4(x_1^2 + x_2^2 + 4x_3^2 - 2x_1x_2 - 4x_2x_3 + 4x_1x_3) \Leftrightarrow$$

$$\Leftrightarrow ax_1^2 + dx_1x_2 + ex_1x_3 + dx_1x_2 + bx_2^2 + fx_2x_3 + ex_1x_3 + fx_2x_3 + cx_3^2 =$$

$$= 4x_1^2 + 4x_2^2 + 16x_3^2 - 8x_1x_2 - 16x_2x_3 + 16x_1x_3 \Leftrightarrow$$

$$\Leftrightarrow ax_1^2 + bx_2^2 + cx_3^2 + 2dx_1x_2 + 2ex_1x_3 + 2fx_2x_3 =$$

$$= 4x_1^2 + 4x_2^2 + 16x_3^2 - 8x_1x_2 - 16x_2x_3 + 16x_1x_3$$

The two polynomials are equal if and only if they have the same degree and corresponding terms have equal coefficients. Therefore

$$\begin{cases} a = 4 \\ b = 4 \\ c = 16 \\ 2d = -8 \Leftrightarrow d = -4 \\ 2e = 16 \Leftrightarrow e = 8 \\ 2f = -16 \Leftrightarrow f = -8 \end{cases}$$

So the 3 by 3 real symmetric matrix S is:

$$S = \begin{pmatrix} 4 & -4 & 8 \\ -4 & 4 & -8 \\ 8 & -8 & 16 \end{pmatrix}$$

(b)

If matrix S was positive definite then $\forall x \in \mathbb{R}^3 \setminus \{0\}$: $x^T S x > 0$.

We can see that for $x = (0, 2, 1)^T$ we get $x^T S x = 0$.

Therefore, matrix S is **not** positive definite.

However, since $x^T S x = 4(x_1 - x_2 + 2x_3)^2 \geq 0$, $\forall x_1, x_2, x_3 \in \mathbb{R}$,

Matrix S is positive semi-definite.

[DAMA 50] Written Assignment 2

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Problem 10

Consider the vector space \mathbb{R}^4 with a Euclidean inner product.

You are given three vectors $(1, 0, 1, 0)^T, (2, 2, 0, -3)^T, (0, 3, 6, 5)^T$. Using by-hand calculation

- verify that these vectors are linearly independent;
- apply the Gram–Schmidt procedure to transform the above basis vectors to obtain an orthonormal basis.

- (a)** We compute the column matrix A of the given vectors and we put A in reduced row echelon form. With elementary row operations we get:

$$A = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 2 & 3 \\ 1 & 0 & 6 \\ 0 & -3 & 5 \end{pmatrix} \xrightarrow{\substack{R3=R3-R1 \\ R2=R2-\frac{2}{3}R3 \\ R4=R4-R3}} \begin{pmatrix} 1 & 2 & 0 \\ 0 & 2 & 3 \\ 0 & -2 & 6 \\ 0 & -3 & 5 \end{pmatrix} \xrightarrow{\substack{R3=R3+R2 \\ R4=R4+\frac{3}{2}R2}} \begin{pmatrix} 1 & 2 & 0 \\ 0 & 2 & 3 \\ 0 & 0 & 9 \\ 0 & 0 & \frac{19}{2} \end{pmatrix} \xrightarrow{\substack{R2=\frac{1}{2}R2 \\ R3=\frac{1}{9}R3 \\ R4=\frac{2}{19}R4}} \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & \frac{3}{2} \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\xrightarrow{\substack{R2=R2-\frac{2}{3}R3 \\ R4=R4-R3}} \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \xrightarrow{R1=R1-2R2} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

Every column is a pivot column which implies that the given vectors are linearly

independent. So a basis for the column space of A is $\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 0 \\ -3 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \\ 6 \\ 5 \end{bmatrix} \right\}$

(b)

$$v_1 = (1, 0, 1, 0), \quad v_2 = (2, 2, 0, -3), \quad v_3 = (0, 3, 6, 5)$$

$$w_1 = v_1 = (1, 0, 1, 0) \quad \text{with } \|w_1\| = \sqrt{1^2 + 0 + 1^2 + 0} = \sqrt{2}$$

$$\begin{aligned} w_2 &= v_2 - \frac{v_2 \cdot w_1}{\|w_1\|^2} \cdot w_1 = (2, 2, 0, -3) - \frac{(2, 2, 0, -3) \cdot (1, 0, 1, 0)}{1^2 + 0 + 1^2 + 0} \cdot (1, 0, 1, 0) = \\ &= (2, 2, 0, -3) - \frac{2+0+0+0}{2} \cdot (1, 0, 1, 0) = (2, 2, 0, -3) - (1, 0, 1, 0) = \\ &= (1, 2, -1, -3) \end{aligned}$$

$$\text{where } \|w_2\| = \sqrt{1^2 + 2^2 + (-1)^2 + (-3)^2} = \sqrt{1+4+1+9} = \sqrt{15}$$

$$\begin{aligned} w_3 &= v_3 - \frac{v_3 \cdot w_1}{\|w_1\|^2} \cdot w_1 - \frac{v_3 \cdot w_2}{\|w_2\|^2} \cdot w_2 = (0, 3, 6, 5) - \frac{(0, 3, 6, 5) \cdot (1, 0, 1, 0)}{2} \cdot (1, 0, 1, 0) - \\ &\quad - \frac{(0, 3, 6, 5) \cdot (1, 2, -1, -3)}{1+4+1+9} \cdot (1, 2, -1, -3) = \\ &= (0, 3, 6, 5) - \frac{0+0+6+0}{2} \cdot (1, 0, 1, 0) - \frac{0+6-6-15}{15} \cdot (1, 2, -1, -3) = \\ &= (0, 3, 6, 5) - (3, 0, 3, 0) + (1, 2, -1, -3) = (-3, 3, 3, 5) + (1, 2, -1, -3) = \\ &= (-2, 5, 2, 2) \end{aligned}$$

$$\text{where } \|w_3\| = \sqrt{(-2)^2 + 5^2 + 2^2 + 2^2} = \sqrt{4+25+4+4} = \sqrt{37}$$

Verifying the orthogonality:

$$w_1 \cdot w_2 = (1, 0, 1, 0) \cdot (1, 2, -1, -3) = 1 + 0 - 1 + 0 = 0$$

which implies that $w_1 \perp w_2$

$$w_2 \cdot w_3 = (1, 2, -1, -3) \cdot (-2, 5, 2, 2) = -2 + 10 - 2 - 6 = -10 + 10 = 0$$

which implies that $w_2 \perp w_3$

$$w_1 \cdot w_3 = (1, 0, 1, 0) \cdot (-2, 5, 2, 2) = -2 + 0 + 2 + 0 = 0$$

which implies that $w_1 \perp w_3$.

Indeed w_1, w_2, w_3 is an orthogonal basis.

Now

$$u_1 = \frac{1}{\sqrt{2}}(1, 0, 1, 0) = \left(\frac{\sqrt{2}}{2}, 0, \frac{\sqrt{2}}{2}, 0 \right)$$

$$u_2 = \frac{1}{\sqrt{15}}(1, 2, -1, -3) = \left(\frac{\sqrt{15}}{15}, \frac{2\sqrt{15}}{15}, -\frac{\sqrt{15}}{15}, -\frac{\sqrt{15}}{5} \right)$$

$$u_3 = \frac{1}{\sqrt{37}}(-2, 5, 2, 2) = \left(-\frac{2\sqrt{37}}{37}, \frac{5\sqrt{37}}{37}, \frac{2\sqrt{37}}{37}, \frac{2\sqrt{37}}{37} \right)$$

is an orthonormal basis since $u_1 \perp u_2, u_2 \perp u_3, u_1 \perp u_3$ and $\|u_1\| = \|u_2\| = \|u_3\| = 1$.