

Linear Subspace

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Subspace of $\mathbb{R}^n \Rightarrow$ if we say V is a subspace of \mathbb{R}^n
then V is a subset of \mathbb{R}^n

Conditions for V to be a subspace of \mathbb{R}^n , then this means 3 things

1) V contains the 0 vector ($\mathbf{0} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$)

2) if \vec{x} in V , then $c\vec{x}$ is also in V
• or if \vec{x} is a subspace of V
• closure under multiplication

3) if \vec{a} in V and \vec{b} in V , then $\vec{a} + \vec{b}$ in V
• closure under addition

EXAMPLES

$$V = \{\mathbf{0}\} = \left\{ \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} \right\}$$

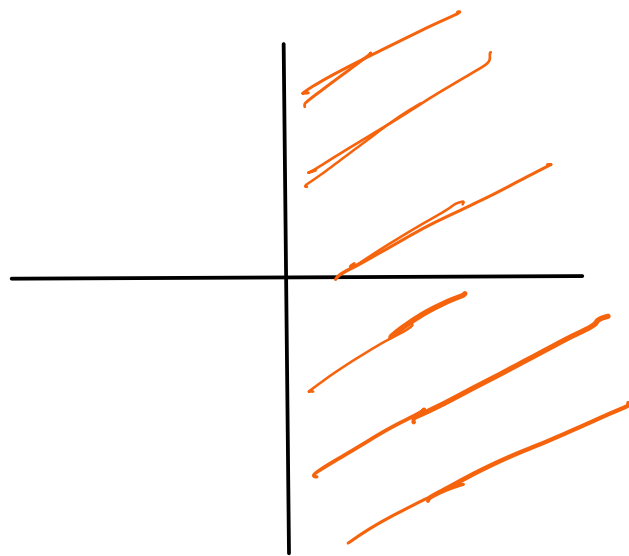
1) contains the zero vector

$$2) c \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$3) \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

So V is a subspace of \mathbb{R}^3

$$2. S = \left\{ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \in \mathbb{R}^2 \mid x_1 \geq 0 \right\}$$



1) contains the zero vector

2) $c \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ if c is +ve we are good

but if c is < 0 then we are outside $x_1 \geq 0$ so we are not in our subspace (S)

So, we are violating the condition of being a subspace

So it's not a subspace of \mathbb{R}^2

2) $V = \text{span}(v_1, v_2, v_3)$ is a valid subspace of \mathbb{R}^n

: linear combinations of (v_1, v_2, v_3)

$$\Rightarrow c_1 v_1 + c_2 v_2 + c_3 v_3$$

1) if $c_1 = c_2 = c_3 = 0$, then span contains the zero vector

$$2) a_1 c_1 v_1 + a_2 c_2 v_2 + a_3 c_3 v_3$$

$\Rightarrow a_{11} v_1 + a_{22} v_2 + a_{33} v_3$ } still a linear combination of v_1, v_2, v_3 with new arbitrary constants

$$3) c_1 v_1 + c_2 v_2 + c_3 v_3 + c_1 v_1 + c_2 v_2 + c_3 v_3 \Rightarrow c_{11} v_1 + c_{22} v_2 + c_{33} v_3 \quad \leftarrow$$

\Rightarrow so both 2), 3) are in U , so U is a subspace of \mathbb{R}^n

Basis of Subspace

If 1) $V = \text{span}(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n)$

2) All $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly independent

Then we can say: S is a basis of V

Basis = a "minimum" set of vectors that spans the subspace

So if you are able to remove a vector from a span and still able to create the subspace then it's not a basis

There can be many basis for a space (\mathbb{R}^2)

$$\text{Standard basis for } \mathbb{R}^2 \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} \\ \left\{ i, j \right\}$$

And you can represent any vector in \mathbb{R}^2 by a combination of i & j

$$\{v_1, v_2, \dots, v_n\} = \text{Basis for } U \\ = v_1, v_2, \dots \text{ are linearly independent} \\ = v_1, v_2, \dots \text{ span } U$$

Each vector in U is a unique combination of these vectors