



INTERNET OF THINGS
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Internet of Things

Lab 4

Video Streaming

Introduction

Introduction

- **In this lab, we will be connecting a USB webcam to the RPi!**
- We'll need to build a program to enable webcam streaming from source
- Then we'll configure the RPi to automatically start all the programs needed to survive a reboot, just like a real security camera!
- We need to install one new program, **libjpeg8-dev**
 - **libjpeg8-dev** is a set of libraries required for efficient manipulation of JPEG images
 - We will be using the camera to generate a continuous stream of JPEGs

Installing Programs

Installing Programs

In your terminal, run:

- `sudo apt-get update`
- `sudo apt-get upgrade -y`
- `sudo apt-get install -y cmake libjpeg8-dev`

- As explained in the previous lab, these commands:
 1. Update the RPi's list of available packages
 2. Upgrade the packages installed on the RPi to the latest version
 3. Install the new packages specified

Installing Programs

- Now reboot the Pi

➤ `sudo reboot`

- Normally, you don't need to reboot after installing new packages, but since we updated the entire system, it's very likely a kernel upgrade has occurred
- Whenever the Linux kernel gets upgraded, there are a few side effects that persist until the next reboot
 - For example, **udev**, the device monitoring **daemon** (a daemon is a background process) usually stops recognizing new USB devices
 - As we are using a USB webcam, we need to reboot to fix this issue

Building and Installing mjpg-streamer

Building and installing mjpg-streamer

- **mjpg-streamer** is a command line application that **copies JPEG frames from one or more input plugins to multiple output plugins**
- **It can be used to stream JPEG files over an IP-based network**
 - From a webcam to various types of viewers such as Chrome, Firefox, Cambozola, VLC, mplayer, and other software capable of receiving MJPG streams
- The project page is:
`https://github.com/jacksonliam/mjpg-streamer`

Building and installing mjpg-streamer

- Inside your home folder, please run the following:
 - `git clone https://github.com/jacksonliam/mjpg-streamer.git`
- This command tells **git** to download a copy of the project from github.com
 - Fun fact: git is a source control tool, but it's formal description is "the stupid content tracker"
- Next, change the current directory into the source folder:
 - `cd mjpg-streamer/mjpg-streamer-experimental`

Building and installing mjpg-streamer

- Next, we need to build the project into an executable:

➤ `sudo make`

➤ `sudo make install`

- Run `ls` and see the file listing as below:

```
pi@raspberrypi:~/mjpg-streamer/mjpg-streamer-experimental$ ls
_build          input_uvc.so      output_file.so    start.sh
cmake           LICENSE           output_http.so    TODO
CMakeLists.txt  makedeb.sh        output_rtsp.so    utils.c
Dockerfile      Makefile          output_udp.so     utils.h
docker-start.sh mjpg_streamer     plugins           www
input_file.so   mjpg_streamer.c   postinstall.sh
input_http.so   mjpg_streamer.h   README.md
input_raspicam.so mjpg_streamer@.service scripts
pi@raspberrypi:~/mjpg-streamer/mjpg-streamer-experimental$
```

Building and installing mjpg-streamer

- Take a look at the files that have been produced
- First, see there are several files ending in **.so**

What are .so files?

- A **file** with the **.SO file** extension is a **Shared Library file**
- They contain information that can be used by one or more programs to offload resources **so** that the application(s) calling the **SO file** doesn't have to actually provide the **SO file**
- For example, one SO file might contain information and functions on how to quickly search through the whole computer
- Several programs can then call upon that SO file to use that feature in their own respective programs.

Building and installing mjpg-streamer

- In order to use shared object files, we need to include them in our system's shared object library path
- This path is a collection of folders that Linux searches when trying to load library files
- On Linux, this includes the **/lib** and **/usr/lib** folders by default
- There are two options to include these .so files in our library path:
 1. Copy these files to a folder already in our path (such as `/lib` or `/usr/lib`)
 2. Use an **environment variable** (such as **LD_LIBRARY_PATH**) to temporarily add the object files to the path (must be done every time)

Building and installing mjpg-streamer

We pursue Option 1:

- **Let's copy the library files into the `/usr/lib/` folder:**
 - `sudo cp *.so /usr/lib/`
- The **make install** command already **placed the binary** into our **`/usr/bin`** folder, which is in our PATH
 - You can verify this with the following command:
 - `which mjpg_streamer`

- **Tip:**

- The **which** command looks for the **first executable inside your path** that matches the name you give it, and tells you the full file path
- To see a full, colon-separated list of the directories included in your path, run:
 - `echo $PATH`

Testing the Camera

Testing the Camera

- Now that we have the executable built, we should test to make sure everything is working as expected
- For this step, connect your phone or laptop to the RPi's access point (see the previous lab if you need a refresher on how to do this)
- The command to start the webcam server is below:
 - `mjpg_streamer -i "input_uvc.so" -o "output_http.so -n"`
- On the device you have connected to the RPi's hotspot, enter the following URLs to test the cameras:
 - `http://<ip>:8080/?action=stream`
 - `http://<ip>:8080/?action=snapshot`
- If everything is working, you should see the camera's output on your device
- **Note: the webserver built in to `mjpg_streamer` defaults to port 8080**

- **How it works?**

- This command calls your new executable, telling it to record the stream from the USB camera (handled by the **input_uvc.so** library)
- It tells the executable to output the stream to an unsecured micro webserver on port 8080 (handled by the **output_http.so** library)
- The **-n** flag tells mjpg_streamer to disable camera commands (such as powering it on, panning, tilting, zooming, etc.) on the web interface, as this is a security risk

Configuring Linux's systemd

Configuring systemd

- **Background:**
 - **systemd** is the modern **init** system used by most Linux Operating System Distributions (**distros**)
 - An init system is a collection of tightly integrated scripts that work together to manage system resources, spawn new processes, and automate the launching of other scripts
 - The init script is the first userspace process that launches on the system, and the last one to exit at shutdown
- **It's systemd's ability to automatically launch processes that we want to take advantage of now**
 - **Our goal is to automatically enable the camera when the RPi boots up**
 - **If the RPi gets updated or crashes and reboots, we don't have to manually run the stream program**

Configuring systemd

- The authors of the mjpeg-streamer repo made this easy for us by providing a sample **unit file**, named **mjpg_streamer@.service**
- This unit file is in your project folder where the shared libraries were
- The provided service file is not perfect, but it is close to what we need
- Edit the file, and replace the line starting with "ExecStart" with the following (the last flag is a lowercase "L" not a "1"):
 - `ExecStart=/usr/local/bin/mjpg_streamer -i input_uvc.so -o "output_http.so -n -l localhost"`
- Make sure the code is on one line!

- **How it works?**

- This command is very similar to the one in previous slides, but we've added the **-l** flag
- The **-l localhost** option tells mjpg_streamer to only expose the stream to localhost so other devices on the network cannot see the stream
- Later, we'll use **nginx** to re-expose the stream, but behind a username and password
- For now you won't be able to see any streams

Configuring systemd

- Additionally, we need to add three more lines directly under the `ExecStart` entry:
 - `RestartSec=3`
 - `Restart=always`
 - `Type=simple`
- These options tell systemd to keep trying to restart the service every 3 seconds if it fails, in case the camera gets unplugged temporarily
- **Remove the “user=...” line to enable root permissions on execution**

Configuring systemd

- Your completed unit file should look like the following, **with 'pi' replaced with your username:**

```
[Unit]
Description=A server for streaming Motion-JPEG from a video capture device
After=network.target

[Service]
User=pi
ExecStart=/usr/local/bin/mjpg_streamer -i input_uvc.so -o "output_http.so -n -l localhost"
RestartSec=3
Restart=always
Type=simple
[Install]
WantedBy=multi-user.target
```

- Now, we need to add this file to systemd's path to enable it

Configuring systemd

- Then we need to place it in **/lib/systemd/system**
 - `sudo cp mjpg-streamer-experimental/mjpg_streamer@.service /lib/systemd/system/mjpg-streamer.service`
- Now we need to enable the service:
 - `sudo systemctl enable mjpg-streamer`
- Now it's time to reboot
- If you did everything correctly, you won't be able to see the stream, but there's another way you can test

Configuring systemd

- After rebooting, run:

➤ `sudo systemctl status mjpg-streamer`

- If you did everything correctly, you should see the following, which indicates the camera service is running!

```
pi@raspberrypi:~$ sudo systemctl status mjpg-streamer.service
• mjpg-streamer.service - A server for streaming Motion-JPEG from a video captur
  Loaded: loaded (/lib/systemd/system/mjpg-streamer.service; enabled; vendor pr
  Active: active (running) since Mon 2019-02-25 18:54:57 PST; 1min 42s ago
  Main PID: 1079 (mjpg_streamer)
  CGroup: /system.slice/mjpg-streamer.service
          └─1079 /usr/local/bin/mjpg_streamer -i input_uvc.so -o output_http.so

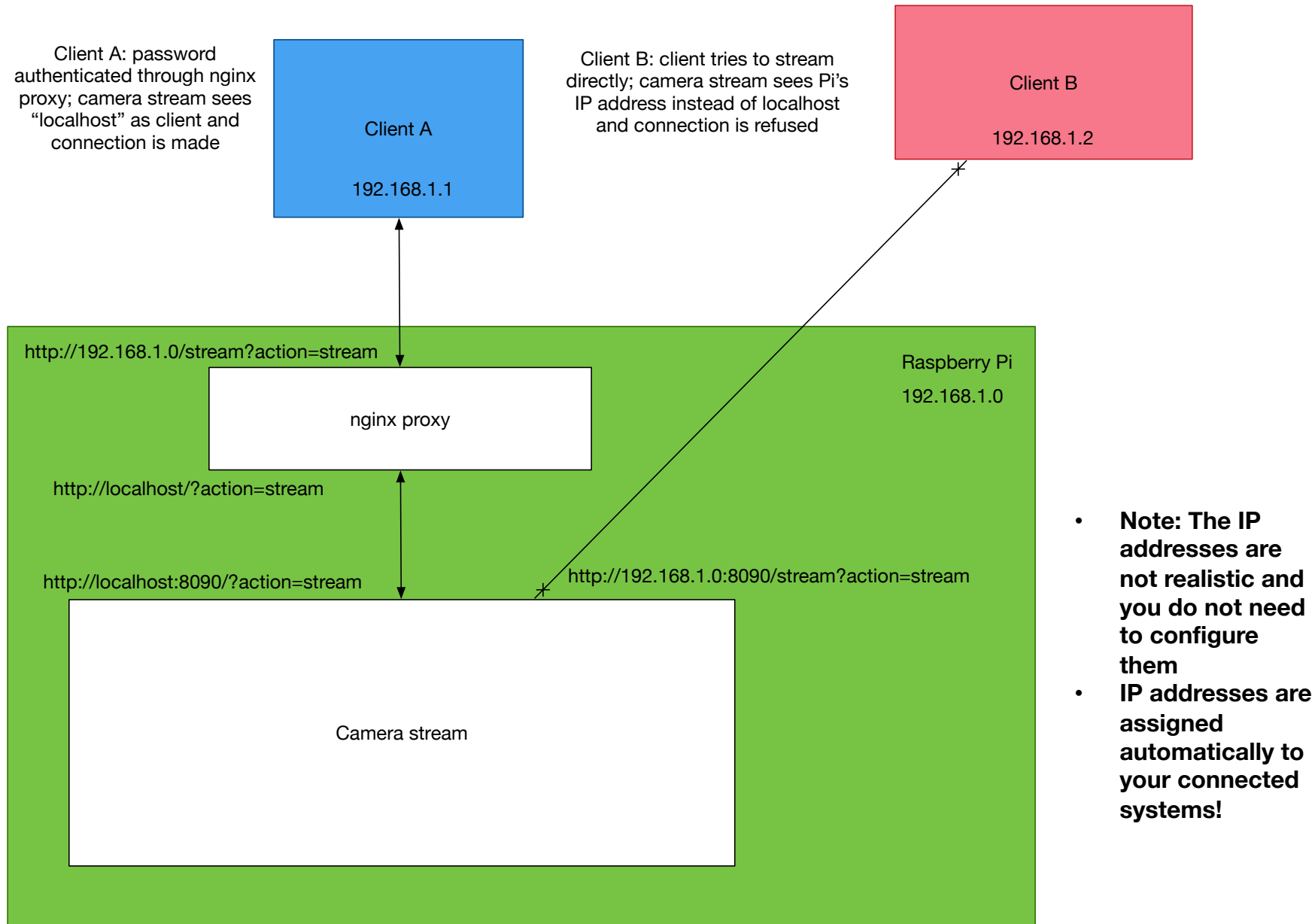
Feb 25 18:54:57 raspberrypi mjpg_streamer[1079]: o: HTTP Listen Address..: loca
Feb 25 18:54:57 raspberrypi mjpg_streamer[1079]: o: username:password....: disa
Feb 25 18:54:57 raspberrypi mjpg_streamer[1079]: o: commands.....: disa
Feb 25 18:54:57 raspberrypi mjpg_streamer[1079]: MJPG-streamer [1079]: www-folde
Feb 25 18:54:57 raspberrypi mjpg_streamer[1079]: MJPG-streamer [1079]: HTTP TCP
Feb 25 18:54:57 raspberrypi mjpg_streamer[1079]: MJPG-streamer [1079]: HTTP List
Feb 25 18:54:57 raspberrypi mjpg_streamer[1079]: MJPG-streamer [1079]: username:
Feb 25 18:54:57 raspberrypi mjpg_streamer[1079]: MJPG-streamer [1079]: commands.
Feb 25 18:54:57 raspberrypi mjpg_streamer[1079]: MJPG-streamer [1079]: starting
Feb 25 18:54:57 raspberrypi mjpg_streamer[1079]: MJPG-streamer [1079]: starting
lines 1-17/17 (END)
```

Proxying Video Through NGINX

Proxying Video through NGINX

- For security reasons, we disabled the video stream on all hosts other than "localhost"--that is to say only the RPi can see it's own stream, but any devices connected to it cannot
- That is very secure, but without a monitor or display attached to the Pi, it's not very useful
- **We want other devices to be able to see the stream, but only if they have the right credentials: your username and password**
- In an earlier lab, we set up Nginx to serve a website for the stream, without the video, and used an `.htaccess` file to configure logins
- Now, we can use that same login permission configuration with a **proxy_pass** directive to allow Nginx to serve the stream
- See the next diagram to understand what is happening

Proxying Video through NGINX



Proxying Video through NGINX

- As you can see in the diagram, **clients can view the stream only through the Nginx proxy, which requires password authentication**
- Let's add the necessary lines to the configuration file (located at `/etc/nginx/sites-enabled/default`), inside the server block but outside the location block:

```
location /stream/{  
    proxy_pass http://localhost:8080/;  
}
```

- Now we have to reload the Nginx configuration file:
 - `systemctl reload nginx`
 - Now, using your phone you can navigate to the following address to see the live stream:
`http://<IP_Address>/stream/?action=stream`

Proxying Ultrasonic Data Through NGINX

Proxying Ultrasonic Data through Nginx

- This step is very similar to the previous step, as we are achieving the same goal: password protecting our data through Nginx proxying
- Open the nginx configuration file just as before, and add the following location block:

```
location /measure/{  
    proxy_pass http://localhost:9000/measure/;  
}
```

- Now **reload** nginx as you did in the previous step, and run
➤ `python3 dashboard.py`

Proxying Ultrasonic Data through Nginx

- If you navigate to `http://<RPi's IP address>/measure/` you'll be able to see your sensor data with a password prompt
- The prompt may not appear if you've logged in recently in that browser
- To test it, use an Incognito tab or clear your cookies first
- However, you can still navigate to the old url (with the :9000) without a password, because Flask currently accepts connections from any host
- We want to limit the Flask server to localhost connections only, and use Nginx's proxy to open up the server to anyone with the correct password, just like the video stream
- Therefore, we need to change one line in `dashboard.py`
 - Replace `0.0.0.0` in the last line with `localhost`, and you've secured the server

Enabling Flask as a Service

Enabling Flask as a Service

- Nginx is enabled as a service, and we wrote a service file for mjpg-streamer, so both of those services will automatically start when the RPi is booted
 - The final step in the project is to enable Flask as a service so the Ultrasonic Sensor survives reboots
 - Without the ultrasonic data, only part of the system is operational after a reboot, so **let's write a unit file** and enable it
- `vim ultrasonic.service`

Enabling Flask as a Service

See the unit file below

```
[Unit]
Description=Ultrasonic Data Service
After=network.target

[Service]
ExecStart=/usr/bin/dashboard
TimeoutSec=3
Restart=always
Type=simple

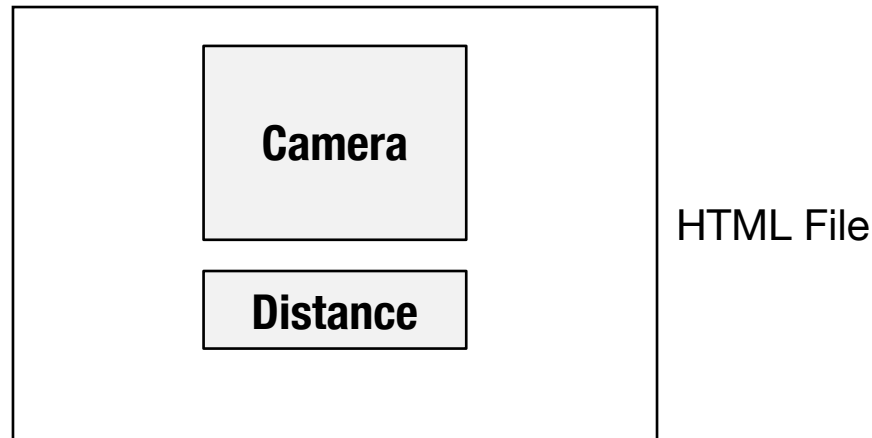
[Install]
WantedBy=multi-user.target
```

Enabling Flask as a Service

- Now, copy the service file into system's path and enable it:
 - `sudo cp ultrasonic.service /lib/systemd/system/ultrasonic.service`
 - `sudo systemctl enable ultrasonic.service`
- Finally, we need to make our **dashboard.py** executable and place it into our PATH:
 - `chmod +x dashboard.py`
 - `sudo cp dashboard.py /usr/bin/dashboard`

❖ Task 4-1.

- Write an HTML file to show the camera stream and ultrasound value as follows:



- Note: The next few slides provide sample codes for the HTML file!
- Demo the project to the TA

HTML File

Note: You do not have to use the provided code snippets
You can write your own simpler HTML file!

HTML File

- This is a sample HTML page we use to show the information:

```
<html>
  <head>
    <meta name="viewport" content="width=device-width, initial-scale=1">
    <!-- Ensure the page is zoomed out when first loaded -->
  </head>
  <body>
    <center>
      <img id="stream" src = "/stream/?action=stream"
        onerror="alert('Video stream disabled.')" />
      <!-- Include the video stream in the page, alert user if it's not working -->
      <br>
      Distance:
      <div id="reading">
        <!-- Create a placeholder for the measurement later -->
      </div>
      <br>
      <br>
      <a id="downloader" href="http://172.21.121.251/stream/?action=snapshot"
        download="">
        <!-- Create a download button for saving snapshots -->
        Save Snapshot
      </a>
    </center>
  </body>
  <script> ... </script>
  <style> ... </style>
</html>
```

Note:

- You do not have to use this file!
- You can write your own, simpler or fancier version of the HTML file!

- Below, find the JavaScript code embedded in the HTML page
- Blue code represents the success state, red implies an error has occurred

```
<script>
function showMeasurement(){
var date = new Date();
var reading = document.getElementById('reading');
var downloader = document.getElementById('downloader');
fetch('/measure/')
  .then(response => response.json())
  .then(function(response) {
    var filename = date.toDateString()+date.toLocaleTimeString() // Turn date into a string for the filename
    filename += "_cm_"+response.result+".jpeg" // Append the Sensor Distance measurement to the filename
    filename = filename.replace(/\s/g,"_"); // Replace spaces in the dates with underscores
    downloader.download=filename; // Apply this filename to the downloader's download attribute
    reading.innerHTML= response.result + " cm"; // Update the measurement placeholder on the site
    reading.className = 'success'; // Set the status to success (turn the text green)
  })
  .catch(function() {
    reading.innerHTML="Error Fetching Measurement"; // Error Handling
    reading.className = 'error'; // Show error message in placeholder
    var filename = date.toDateString()+date.toLocaleTimeString() // Turn date into a string for the filename
    filename += "_cm_unknown.jpeg" // Append measurement placeholder to the filename
    filename = filename.replace(/\s/g,"_"); // Replace spaces in the dates with underscores
    downloader.download=filename; // Set the status to success (turn the text green)
  });
}
window.setInterval(function(){ showMeasurement(); }, 500); // Tell the browser to call our function every 500ms
</script>
```


HTML File

- Below, find the CSS styling embedded in the html page to make the page fancier!

```
<style>
img#stream{
    /* Size the stream so it's no bigger
    than 90% of the screen, and no bigger
    than the camera resolution */
    width: 90%;
    max-width: max-content;
}
div#reading {
    /* Allows the placeholder and label
    to share a line in the html */
    display: inline-block;
}
.success {
    /* Turns text green */
    color: green;
}
.error {
    /* Turns text red */
    color: red;
}
</style>
```