

CMPSC 311 - Introduction to Systems Programming

Signals

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(Slides are mostly by Professor Patrick McDaniel and Professor Abutalib Aghayev)

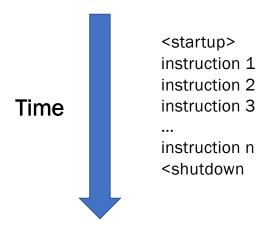


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Control Flow



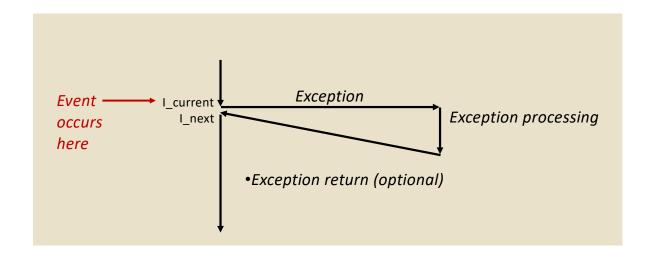
- Processors do only one thing:
 - from startup to shutdown, a CPU simply reads and executes a sequence of instructions, one at a time
 - This sequence is the CPU's control flow (or flow of control)



Exceptional Control Flow



• Exceptional control flow enables a system to react to an event



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Exceptional Control Flow

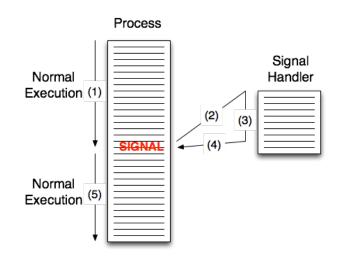


- Mechanisms exists at all levels of a computer system for exceptional control
- Low-level mechanisms
 - Exceptions
 - Examples: interrupts, traps, faults, and aborts
 - Implemented using combination of hardware and OS software
- High-level mechanisms
 - Process context switch (implemented by OS software and hardware timer).
 - Signals (implemented by OS software)
 - Nonlocal jumps: setjmp() and longjmp() (implemented by C runtime library)

UNIX Signals



- A signal is a special message sent through the OS to tell a process (or thread) of some command or event
- The process execution stops and special "signal handler" code runs.
- The process can resume operation after the signal handling is complete.



Signal types (abbreviated)



```
/* Signals */
                               /* Hangup (POSIX). */
#define SIGHUP
                       1
                               /* Interrupt (ANSI). */
#define SIGINT
#define SIGQUIT
                               /* Quit (POSIX). */
                               /* Abort (ANSI).
#define SIGABRT
                                                 */
#define SIGFPE
                               /* Floating-point exception (ANSI). */
#define SIGKILL
                               /* Kill, unblockable (POSIX). */
#define SIGSEGV
                               /* Segmentation violation (ANSI). */
                               /* Termination (ANSI). */
#define SIGTERM
                       15
#define SIGSTKFLT
                       16
                               /* Stack fault. */
                               /* Child status has changed (POSIX). */
#define SIGCHLD
                        17
                               /* Continue (POSIX). */
#define SIGCONT
                        18
                               /* Bad system call. */
#define SIGSYS
                        31
```

Signals as process control



- The operating system use signals to control process behavior
 - Signals are sent on errors

```
#define SIGILL 4 /* Illegal instruction (ANSI). */
#define SIGTRAP 5 /* Trace trap (POSIX). */
#define SIGIOT 6 /* IOT trap (4.2 BSD). */
#define SIGBUS 7 /* BUS error (4.2 BSD). */
#define SIGFPE 8 /* Floating-point exception (ANSI). */
#define SIGSEGV 11 /* Segmentation violation (ANSI). */
```

Signals can be used by other applications too

```
#define SIGUSR1 10 /* User-defined signal 1 (POSIX). */
#define SIGUSR2 12 /* User-defined signal 2 (POSIX). */
```

Control the process execution

```
#define SIGKILL 9 /* Kill, unblockable (POSIX). */
#define SIGCONT 18 /* Continue (POSIX). */
#define SIGSTOP 19 /* Stop, unblockable (POSIX). */
```

Process IDs



- Every process running on the OS is given a unique process ID (PID)
 - This is what is used in the OS and for process control to reference that specific running program instance.
- To find a process ID for a program, use the ps utility
 - The ps stands for "process status"

```
ps -U mcdaniel
  PID TTY
                   TIME CMD
30908 ?
               00:00:00 gnome-keyring-d
30919 ?
               00:00:00 gnome-session
30964 ?
               00:00:00 ssh-agent
30967 ?
               00:00:00 dbus-launch
30968 ?
               00:00:01 dbus-daemon
30978 ?
               00:00:00 at-spi-bus-laun
30982 ?
               00:00:00 dbus-daemon
30985 ?
               00:00:00 at-spi2-registr
30999 ?
               00:00:02 gnome-settings-
31009 ?
               00:00:00 pulseaudio
31011 ?
               00:00:00 gvfsd
31017 ?
               00:00:00 gvfsd-fuse
31031 ?
               00:02:43 compiz
31041 ?
               00:00:00 dconf-service
31044 ?
               00:00:00 gnome-fallback-
31045 ?
               00:00:06 nautilus
31047 ?
               00:00:01 nm-applet
31048 ?
               00:00:41 vmtoolsd
31049 ?
               00:00:00 polkit-gnome-au
31064 ?
               00:00:00 gvfs-udisks2-vo
31079 ?
               00:00:00 gvfs-gphoto2-vo
31083 ?
               00:00:00 gvfs-afc-volume
31090 ?
               00:00:00 gvfs-mtp-volume
```

kill



Kill is a program than sends signals to processes.

- Where <sig> is the signal number and <pid> is the process ID of the running program you want to send the signal.
 - If no SIGNUM is given, then SIGTERM is used by default.

```
$ ps -U mcdaniel
                                                                     $ ./signals
                                                                     Sleeping ...zzzzz ....
                      57613 pts/4
                                      00:00:00 signals
                                                                     Signal handler got a SIGHUP!
                      $ kill -1 57613
                                                                     Signals received: 1
                      $ kill -2 57613
                                                                     Woken up!!
                      $ kill -9 57613
                                                                     Sleeping ...zzzzz ....
                                                                     Signal handler got a SIGNINT!
                                                                     Signals received: 2
                                                                     Woken up!!
                                                                     Sleeping ...zzzzz ....
                                                                     Killed
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```

SIGTERM vs. SIGKILL



- SIGTERM interrupts the program and asks it to shut down, which it should.
 - Sometimes this does not work (for instance when the process is in a locked state)
 - It is often desirable to add a signal handler to handle the SIGTERM, so that it can gracefully shut down the process, cleanup memory, close files, etc.
- SIGKILL kills the process
 - Can lead to inconsistent state, because there is no opportunity to gracefully shutdown the process.

Definition: the term *graceful shutdown* refers to the proper and complete sync with secondary storage, disposal of resources, and normal termination.

send signals to all instances of a patricular program

killall



Killall is a program than sends signals to all instances of a particular progam.

```
killall [-<sig>] <name>
```

- Where <sig> is the signal number and <name> is the name of running program you want to send the signal.
 - If no SIGNUM is given, then SIGTERM is used by default.

```
$ ./signals
$ killall -1 signals
$ killall -2 signals
$ killall -SIGKILL signals

Signal handler got a SIGHUP!
Signals received: 1
Woken up!!
Sleeping ...zzzzz ....
Signal handler got a SIGNINT!
Signals received: 2
Woken up!!
Sleeping ...zzzzz ....
Killed
```

raise()



raise allows a process to send signals to itself.

```
int raise(int sig);
```

- There are a range of reasons why a process might want to do this.
 - Suspend itself (SIGSTOP)
 - Kill itself (SIGKILL)
 - Reset its configuation (SIGHUP)
 - User defined signals (SIGUSR1..)

```
void suicide_signal(void) {
   raise(SIGKILL);
   return; // This will never be reached
}
```



User-defined signal handlers



You can create your own signal handlers simply by creating a function

```
void <fname>( int <var name> )
```

and passing a function pointer to the function

```
sighandler_t signal(int signum, sighandler_t handler);
```

• Thereafter, whenever a signal of the type signo is raised. your program is called instead of the default handler.

```
void signal_handler(int no) {
    printf("Sig handler got a [%d]\n", no);
    return;
}
signal(SIGHUP, signal_handler);
signal(SIGINT, signal_handler);
```

Function pointers



 A function pointer is a pointer to a function that can be assigned, passed as parameters, and called

```
<return> (*<var>)(<params>);
```

- <return> is the return type of the function
- <var> is the variable names
- <params
 > are the parameters
 , separated by commas

```
int myfunc(int i) {
  printf("Got into function with %d\n", i);
  return 0;
}
int main( void ) {
  int (*func)(int);
  func = myfunc; // set variable ware to function
  func(7);
  return 0;
}
```

```
$ ./signals
Got into function with 7
$
```

An alternate approach



 The sigaction() system call changes the action taken by a process on receipt of a specific signal.

```
int sigaction(int signum, const struct sigaction *act, struct sigaction *oldact);
```

- Where:
 - signnum is the signal number to be handled
 - act is a structure containing information about the new handler, NULL means ignore the signal
 - oldact is a pointer to the previously assigned handler, as assigned in call to function

```
struct sigaction new_action, old_action;
new_action.sa_handler = signal_handler;
new_action.sa_flags = SA_NODEFER | SA_ONSTACK;
sigaction(SIGINT, &new_action, &old_action);
```

```
signalhondler-t sighal (int signum, signalhandler-t handler);
int signation (int signum, conet struct signation & new-act,
struct signation & old-act);
```

Why another API?



- Many argue that the sigaction function is better:
 - The signal() function does not block other signals from arriving while the current handler is executing; sigaction() can block other signals until the current handler returns.
 - The signal() function resets the signal action back to SIG_DFL (default) for almost all signals.
 - Better tuning of signals/controls of process through flags
 - SA_NODEFER don't suspend signals while in handler
 - SA_ONSTACK provide alternate stack for signal handler
 - SA_RESETHAND Restore the signal action to the default upon entry to the signal handler.

Note: In general, sigaction is preferred over signal.

Putting it all together ...



```
void signal handler(int no) {
                                                             $ ./signals
   printf("Signal received : %d\n", no);
                                                             Sleeping ...zzzzz ....
    if (no == SIGHUP) {
        printf("Signal handler got a SIGHUP!\n");
                                                             Signal received: 1
    } else if (no == SIGINT) {
                                                             Signal handler got a SIGHUP!
        printf("Signal handler got a SIGNINT!\n");
                                                             Woken up!!
                                                             Sleeping ...zzzzz ....
    return;
                                                             Signal received: 2
                                                             Signal handler got a SIGNINT!
void cleanup handler(int no) {
                                                             Woken up!!
   printf("Killed");
                                                             Sleeping ...zzzzz ....
    exit(0);
                                                             Killed
int main(void) {
    struct sigaction new action, old action; // Setup the signal actions
    new action.sa handler = signal handler;
    new action.sa flags = SA NODEFER | SA ONSTACK;
    sigaction( SIGINT, &new action, &old action );
    signal( SIGHUP, signal handler );
                                         // Setup the signal handlers
    signal( SIGTERM, cleanup handler );
    while (1) {
        printf( "Sleeping ...zzzzz ....\n" );
        select( 0, NULL, NULL, NULL, NULL );
        printf( "Woken up!!\n" );
    // Return successfully
    return 0;
```