

Practice2 Report 22320607 Xu Ziyang

Overview:

1. Calculation

2. Graph

3. Model and code

Part 1:

1. $sY(s) + kY(s) = kU(s)$
 $Y(s) = \frac{k}{s+k} U(s) = \frac{k}{s+k}$
 $Y(s) = \frac{1}{s} - \frac{1}{s+k}$
 $y(t) = 1 - e^{-kt}$

2. $s^2Y(s) + 2k s Y(s) + (k^2+1) Y(s) = ksU(s) + (k^2+1)U(s)$
 $Y(s) = W(s)U(s)$
 $= \frac{ks + (k^2+1)}{s^2 + 2ks + (k^2+1)} U(s)$
 $= \frac{1}{s} - \left(\frac{1}{s}\right)\left(\frac{1}{s+k}\right) + \frac{1}{s-(k+1)}$
 $y(t) = 1 - e^{-kt} \cdot \cos(t).$

3. $sY(s) + 2b Y(s) = sU(s) + bU(s)$
 $Y(s) = W(s)U(s)$
 $Y(s) = \frac{s+b}{s+k} U(s)$
 $Y(s) = \frac{1}{s+k}$
 $\ddot{y}(t) = \exp\left(-\frac{2bt}{s+k}\right) \frac{1}{s+k}$

4. $\ddot{y} + 5\dot{y} + 8y + 4y = 0 \quad (\lambda+1)(\lambda^2 + 5\lambda + 8\lambda + 4) = 0$
 $\lambda^3 + 15\lambda^2 + 8\lambda + 4 = 0$
 $\lambda_1 = -1 \quad \lambda_2 = \lambda_3 = -2$
 ~~$\therefore Y(s) = \frac{1}{s+1} + \frac{1}{s+2} + \frac{1}{s+2}$~~

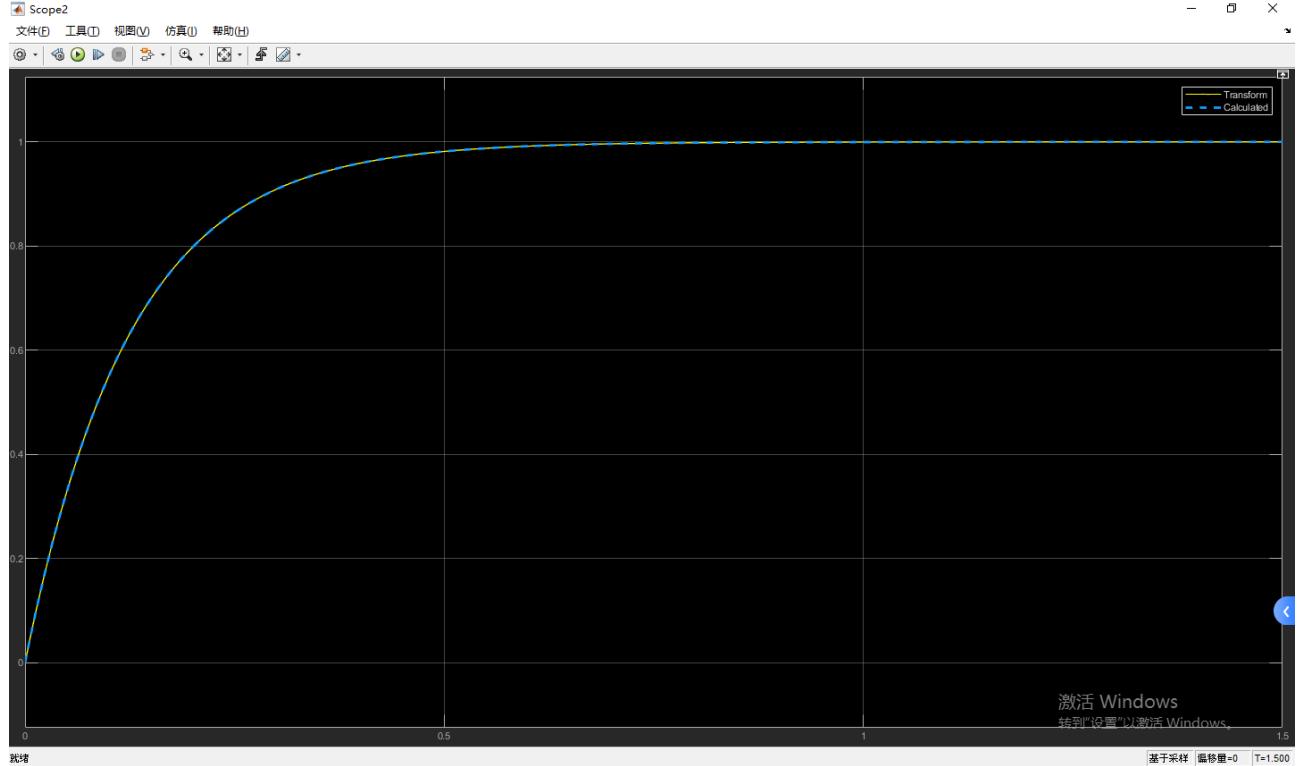
5. Assume $Y(s)_{s.r} = W(s)U(s)$, $U(s) = \frac{1}{s}$.
 $\frac{k}{s-1} + \frac{(k+3)s^2}{s^3} = \frac{1}{s} W(s)$
 $W(s) = \frac{s^2 + 2(k+3)s + k^2}{s^3 - 2s^2 + s^2}$

$Y(s) = U(s)W(s)$
 $(s^4 - 2s^3 + s^2)Y(s) = [12s^3 + 2(2k+3)s^2 - 4(k+3)s + 4(k+3)]U(s)$
 $\ddot{y}(t) + 2\dot{y}(t) + 4y(t) = 12\ddot{u}(t) + 2(2k+3)\dot{u}(t) - 4(k+3)u(t) + 4(k+3)u(t)$

Part 2:

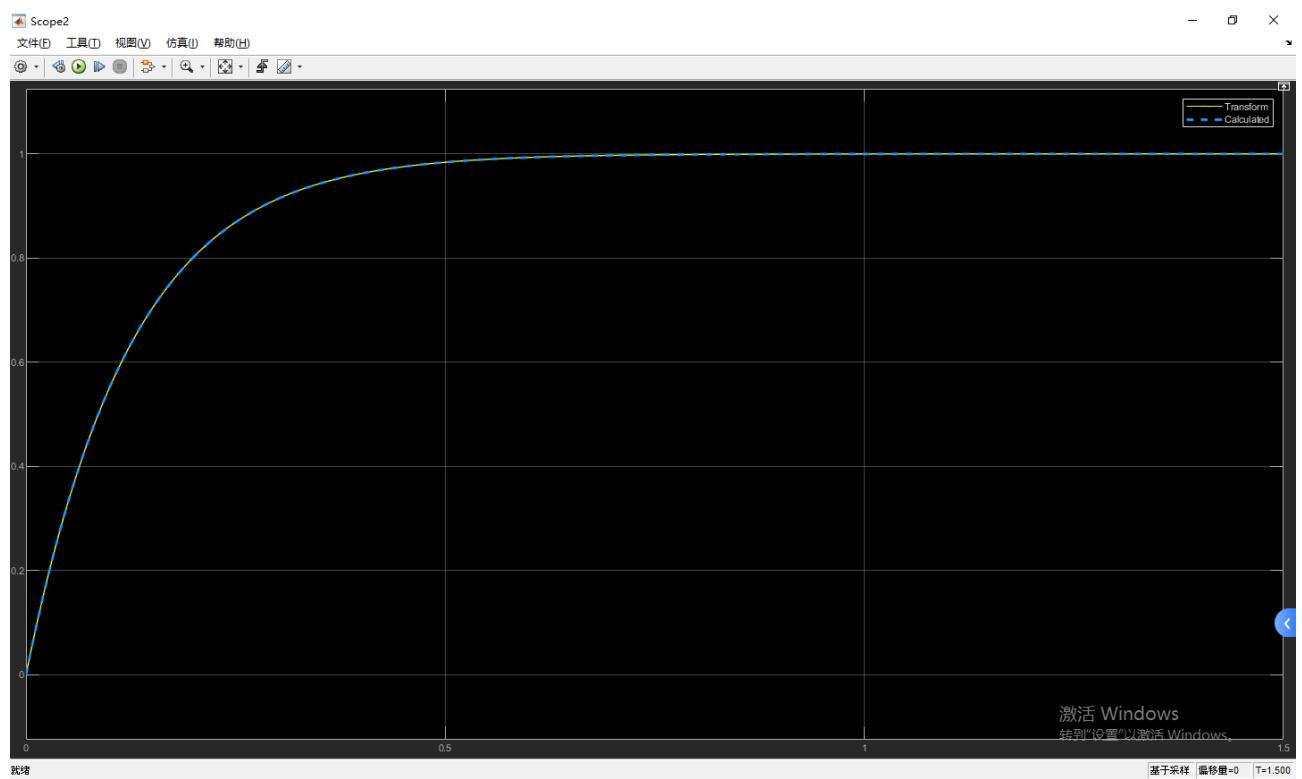
1. Step response of

$$\dot{y}(t) + ky(t) = ku(t).$$



2. Step response of

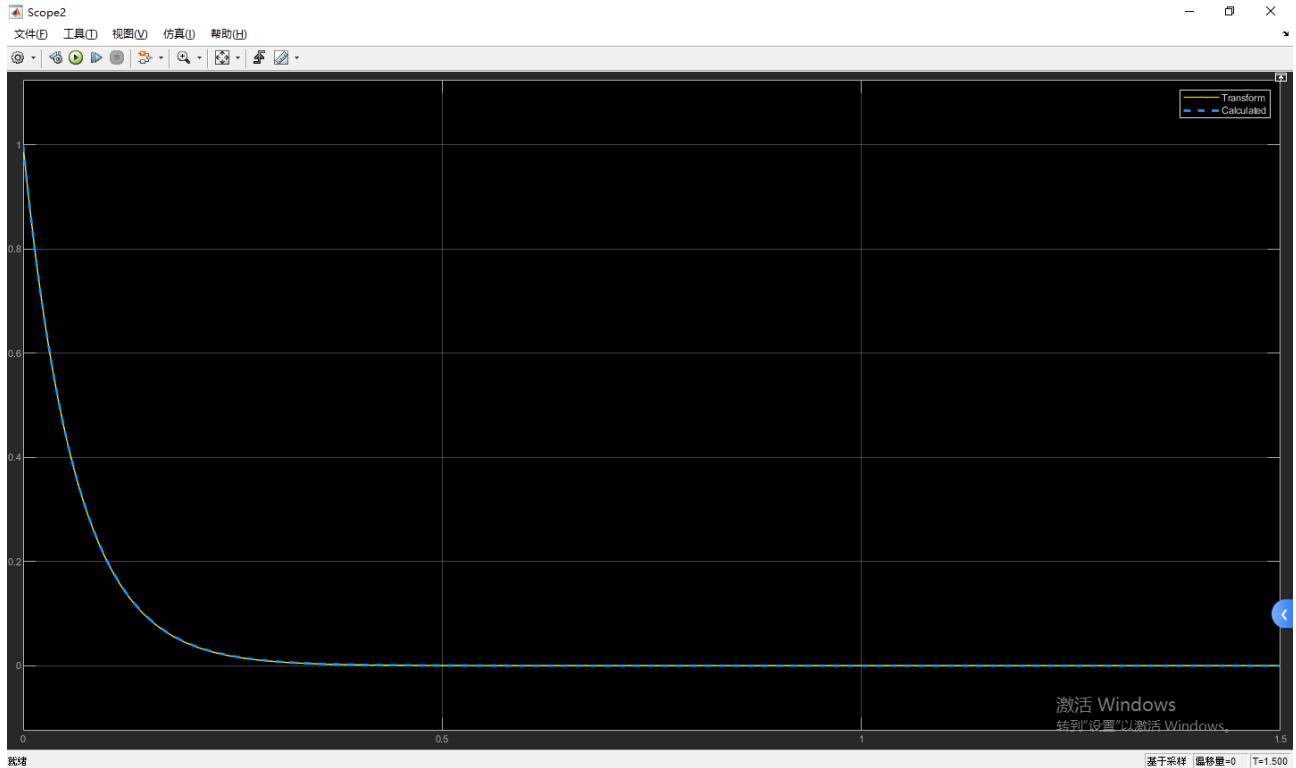
$$\ddot{y}(t) + 2k\dot{y}(t) + (k^2 + 1)y(t) = k\dot{u}(t) + (k^2 + 1)u(t).$$



3.

For $u(t) = e^{-kt}$ find the forced response of the system

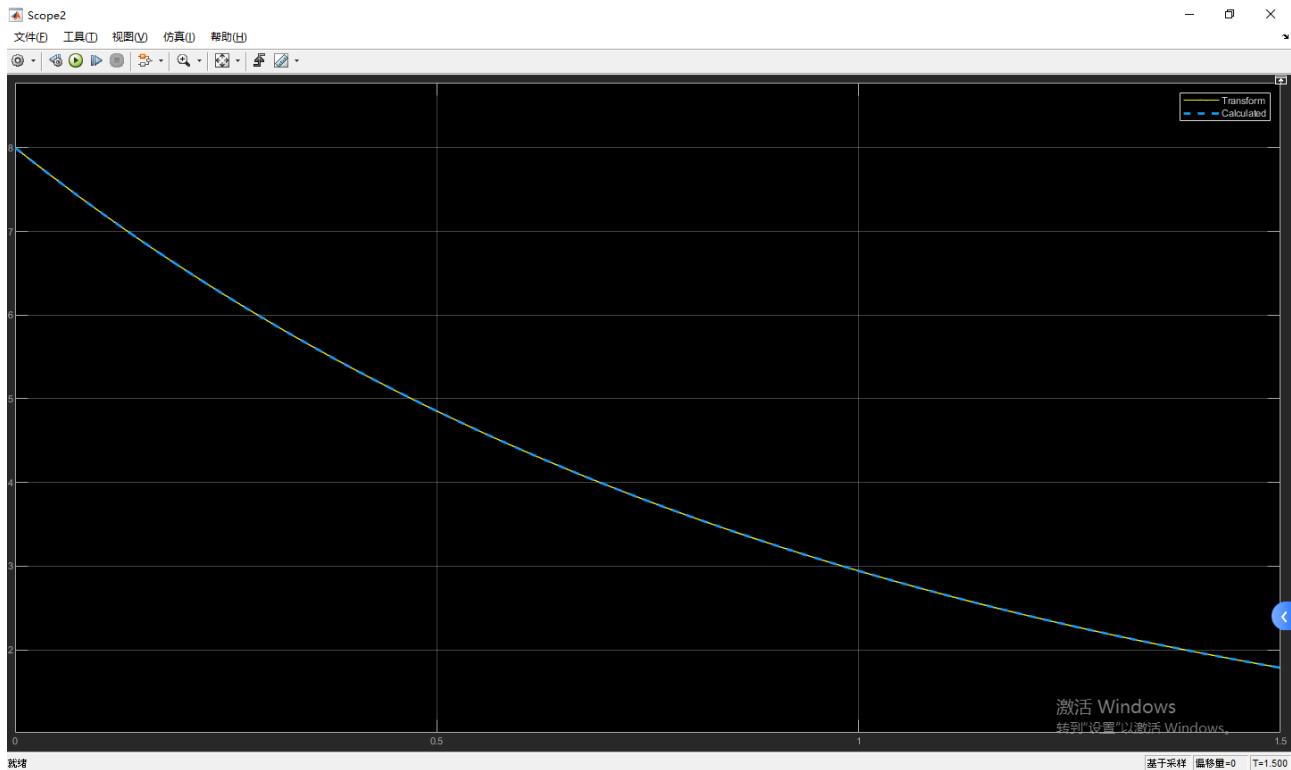
$$\dot{y}(t) + 2ky(t) = \dot{u}(t) + ku(t).$$



4. Find the output $y(t)$ of the system

$$\ddot{y} + 5\dot{y} + 8y = \ddot{u} + u,$$

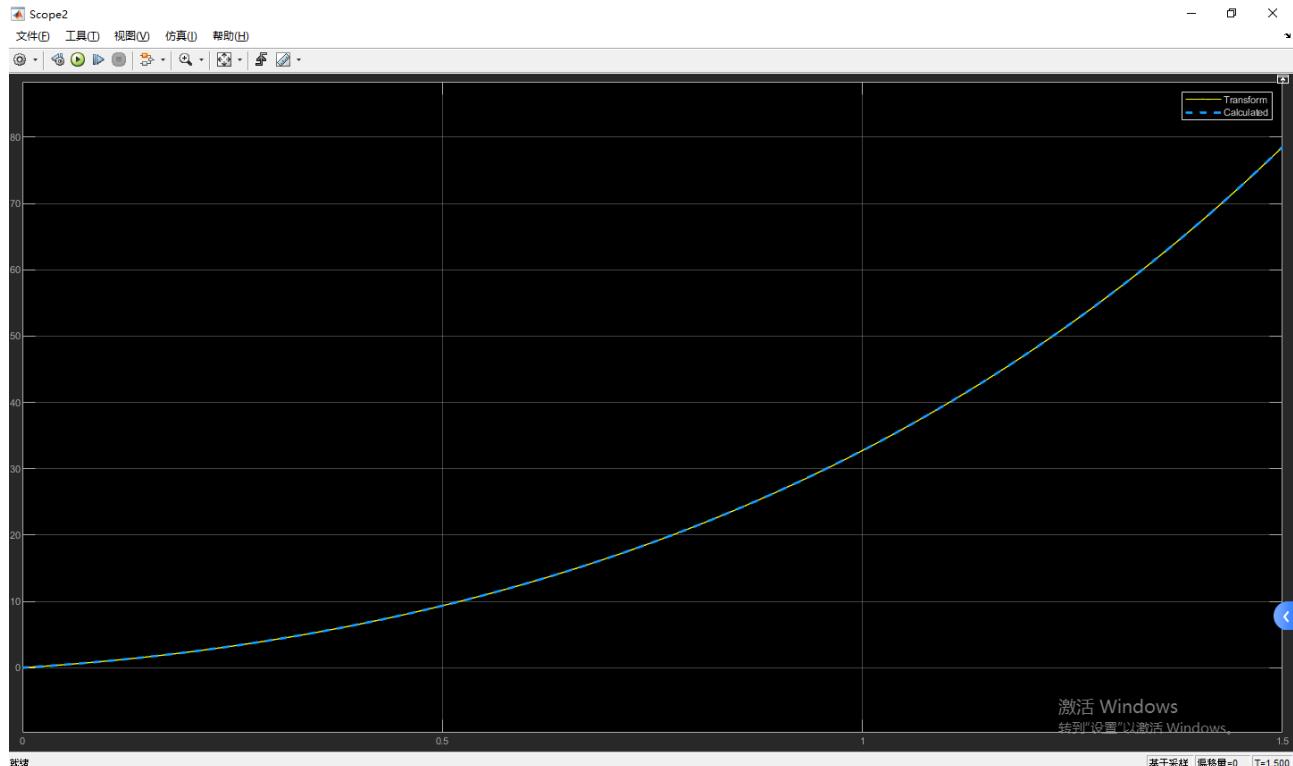
$$u(t) = 3k \cos(t) + 2k \sin(t), \quad y(0) = k, \quad \dot{y}(0) = -k, \quad \ddot{y}(0) = k.$$



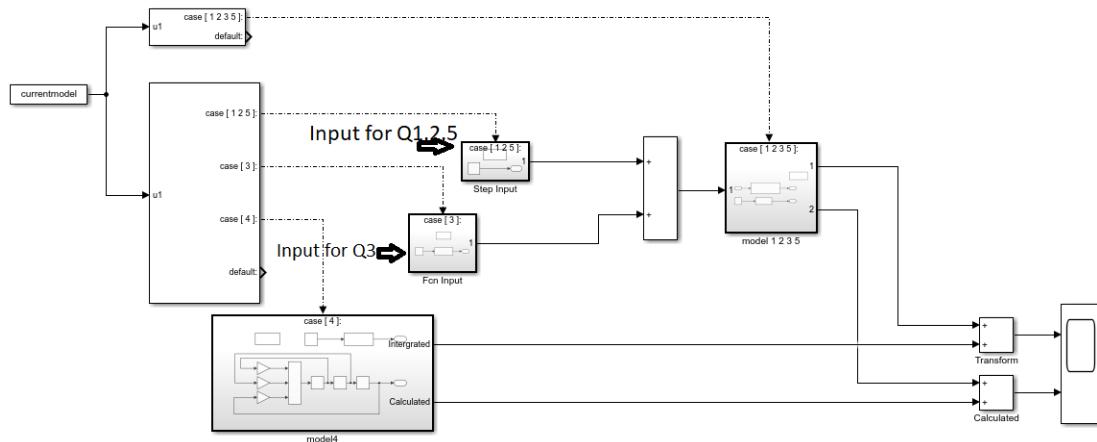
5. Assume that $u(s) = 1/s$.

5. Find a differential equation of the system with the following step response:

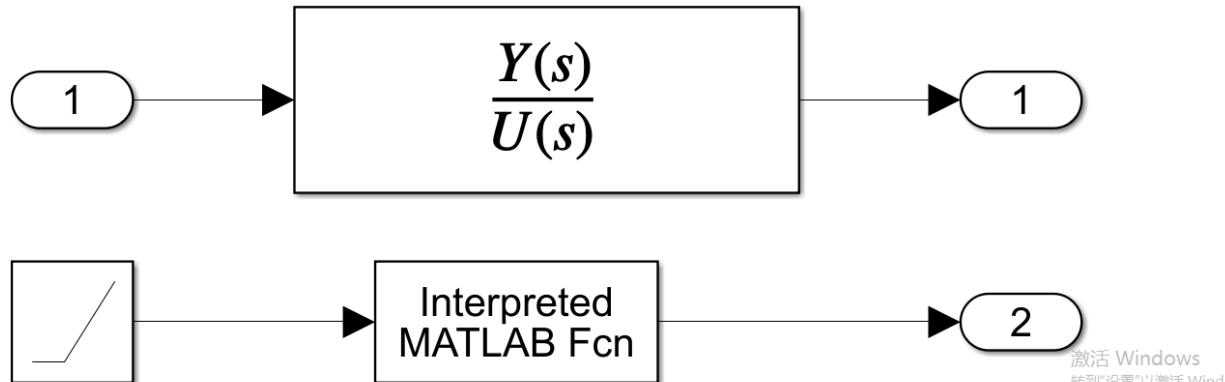
$$y_{\text{step response}} = kte^t + (k+3)t^2.$$



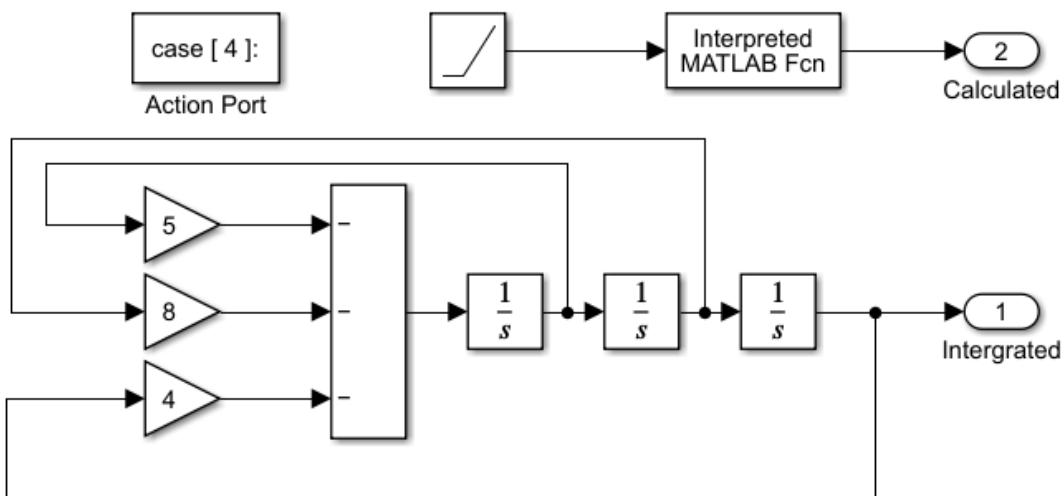
Part 3: Model:



Used For Q1.2.3.5



Used for Q4.



Code: **solves.m**

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k = 7 + 1;
eq1Solve = @(u)(1-exp(-k*u));
eq2Solve = @(u)(1-cos(u)*exp(-k*u));
eq3Solve = @(u)(exp(-2*k*u));
eq5Solve = @(u)(k*u*exp(u)+(k+3)*u^2);
currentmodel = 5;
switch currentmodel
    case 1
        eqSolve = eq1Solve;
        argU = [k];
        argD = [1,k];
        InputGt2 = 0;
    case 2
        eqSolve = eq2Solve;
        argU = [k];
        argD = [1,k];
        InputGt2 = 0;
    case 3
        eqSolve = eq3Solve;
        argU = [k];
        argD = [1,k];
        InputGt2 = 0;
    case 5
        eqSolve = eq5Solve;
        argU = [k];
        argD = [1,k];
        InputGt2 = 0;
end

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case 2
    eqSolve = eq2Solve;
    argU = [k (k^2+1)];
    argD = [1 2*k k^2+1];
    InputGt2 = 0;
case 3
    eqSolve = eq3Solve;
    argU = [1 k];
    argD = [1 2*k];
    InputGt2 = @(u)exp(-k*u);
case 5
    eqSolve = eq5Solve;
    InputGt2 = 0;
    argU = [k 2*(k+3) -4*(k+3) 2*(k+3)];
    argD = [1 -2 1 0 0];
end
```