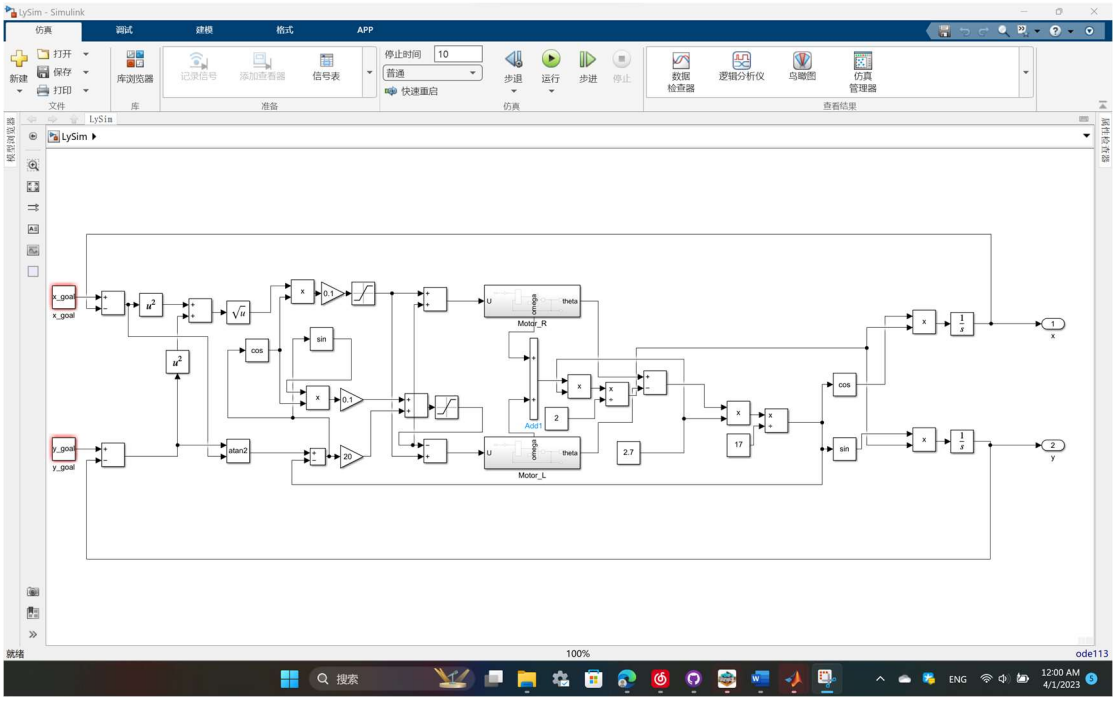
This task is on GitHub.

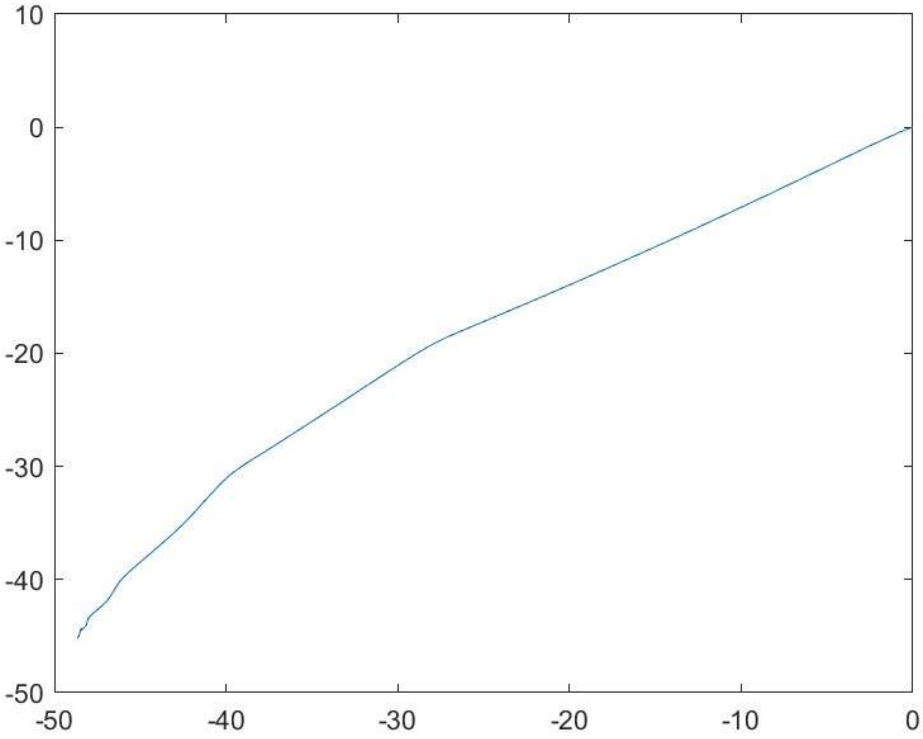
Disaster

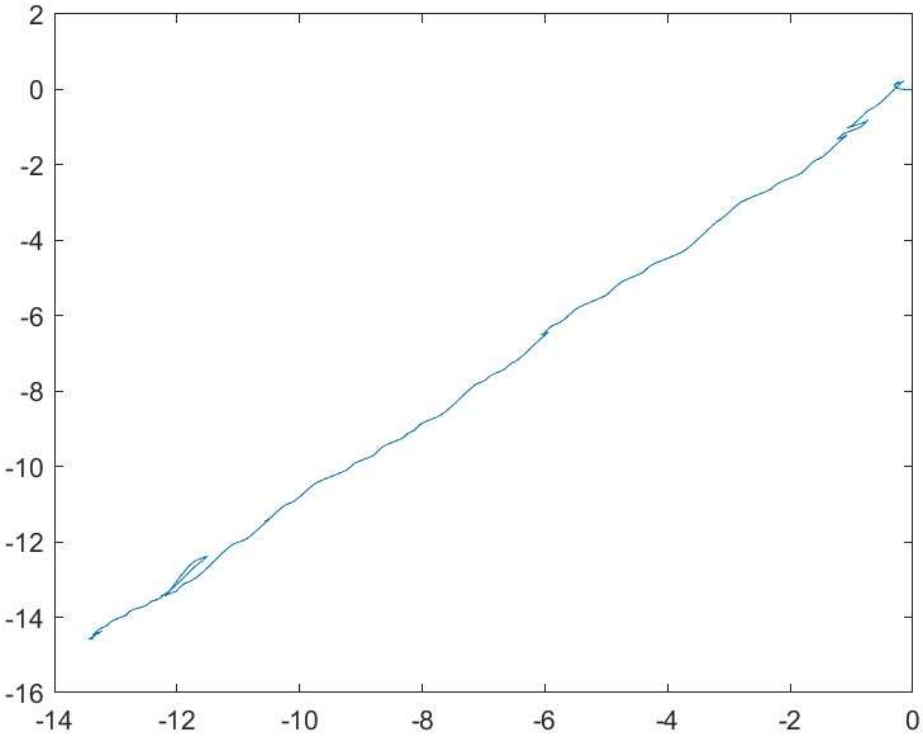
Simulink Model (by my own)



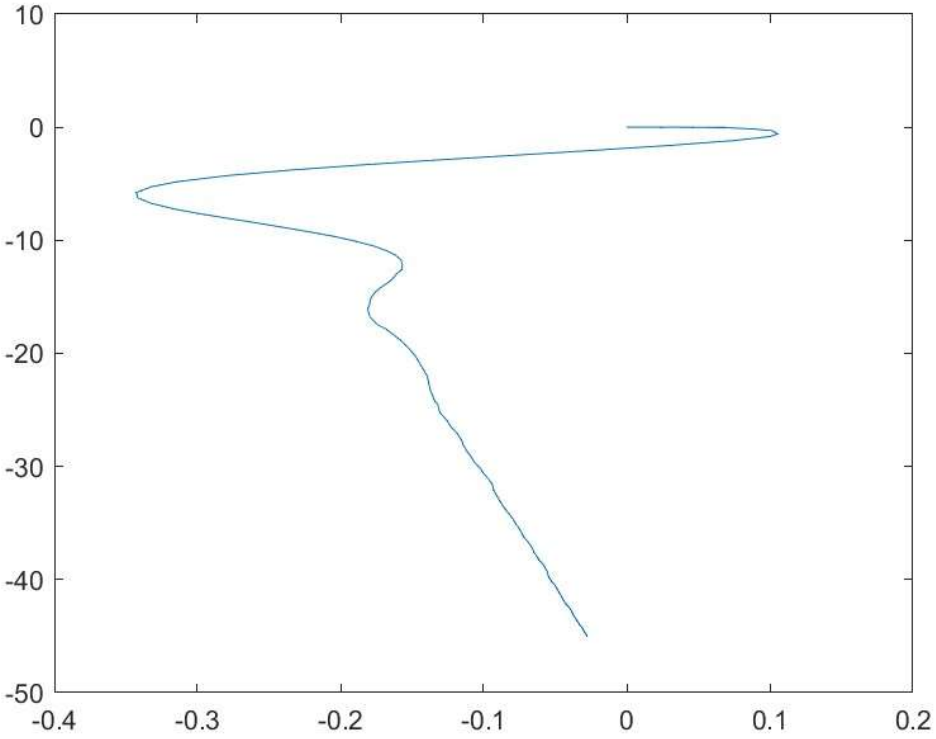
K changed non-linear controller

(First Bigger k1,Second Bigger k2)





Linear controller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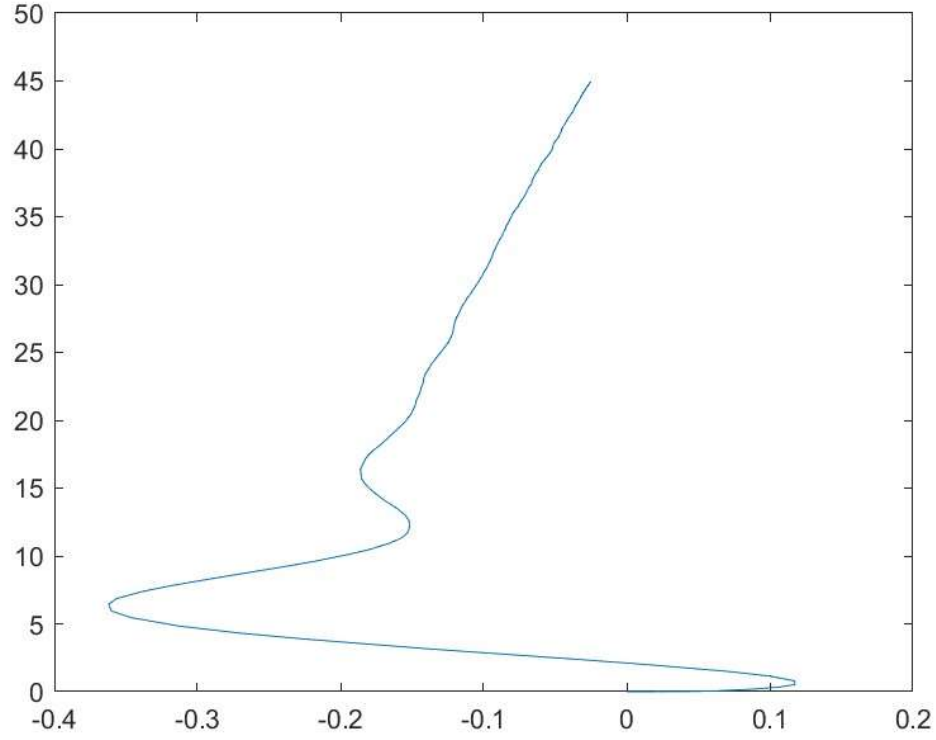
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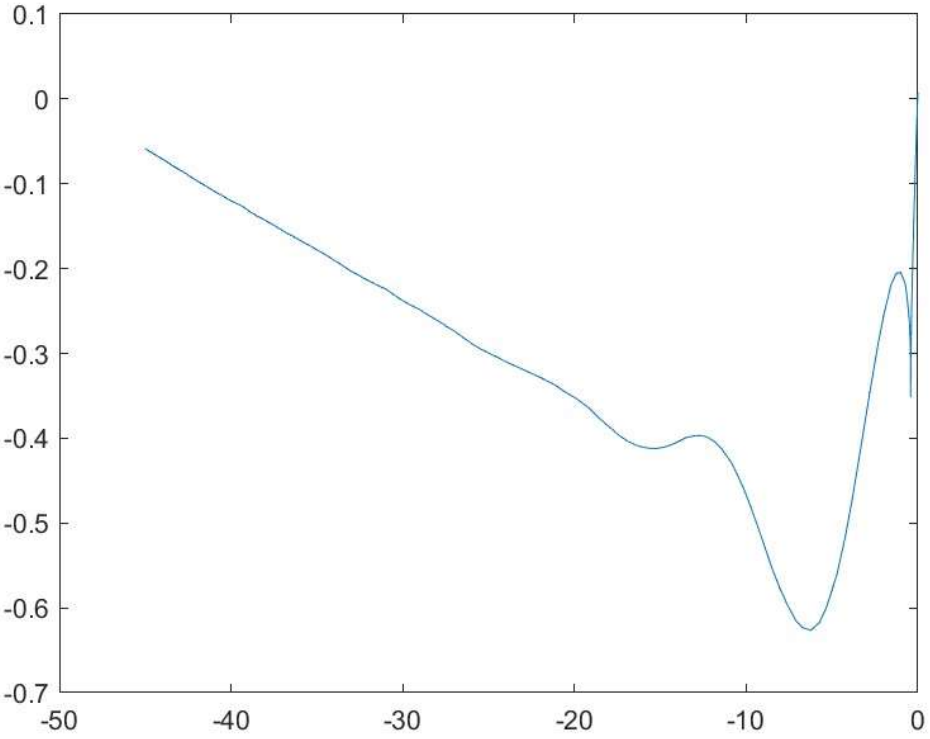
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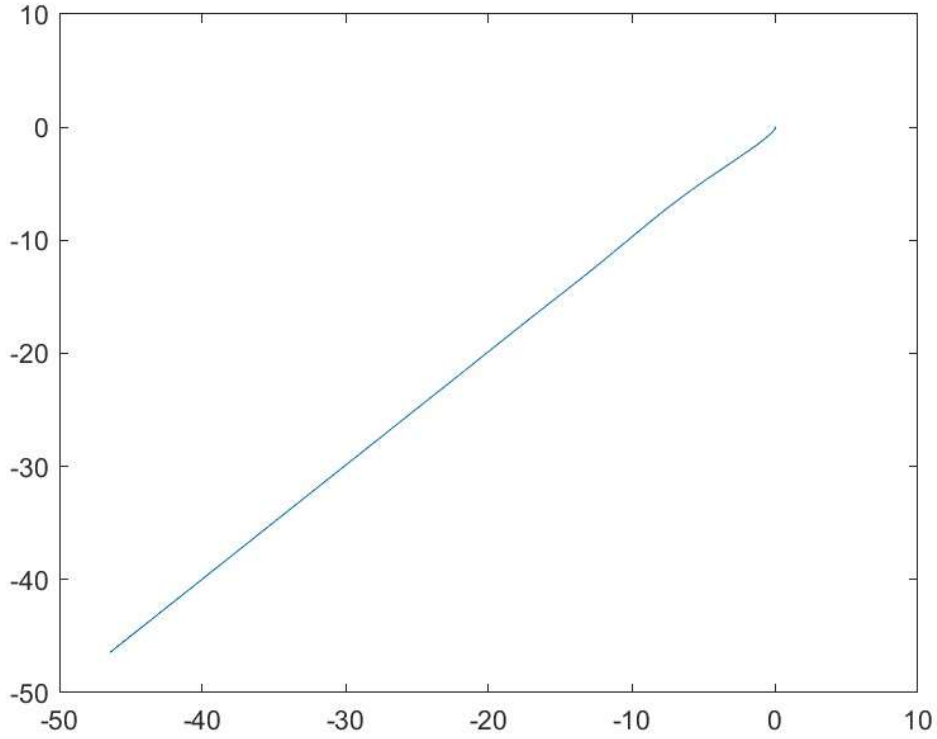
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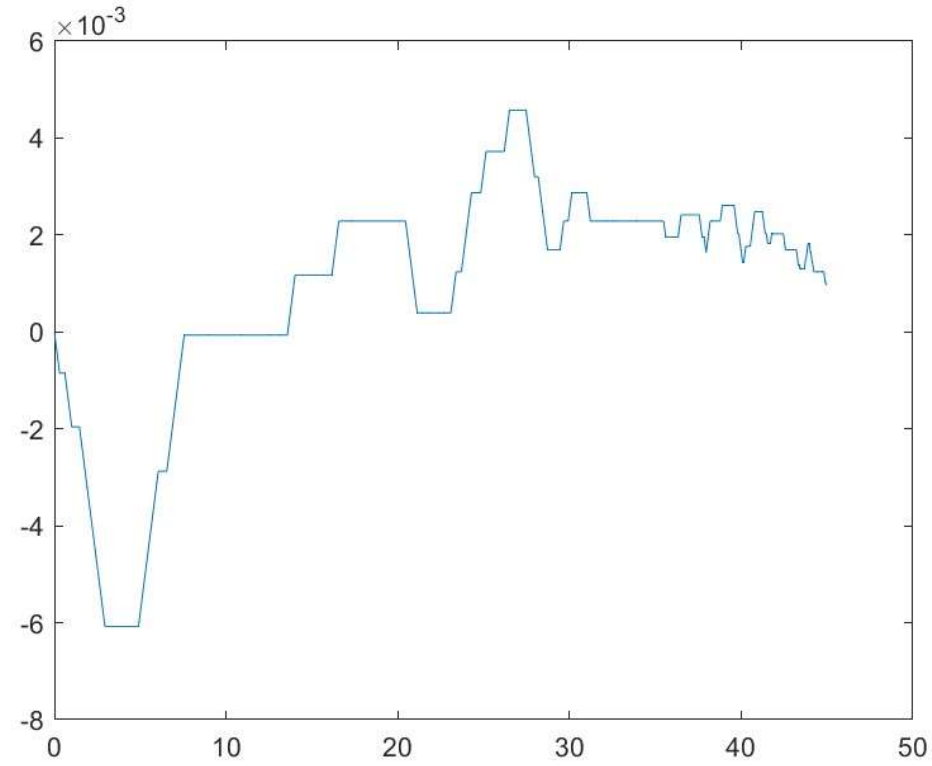
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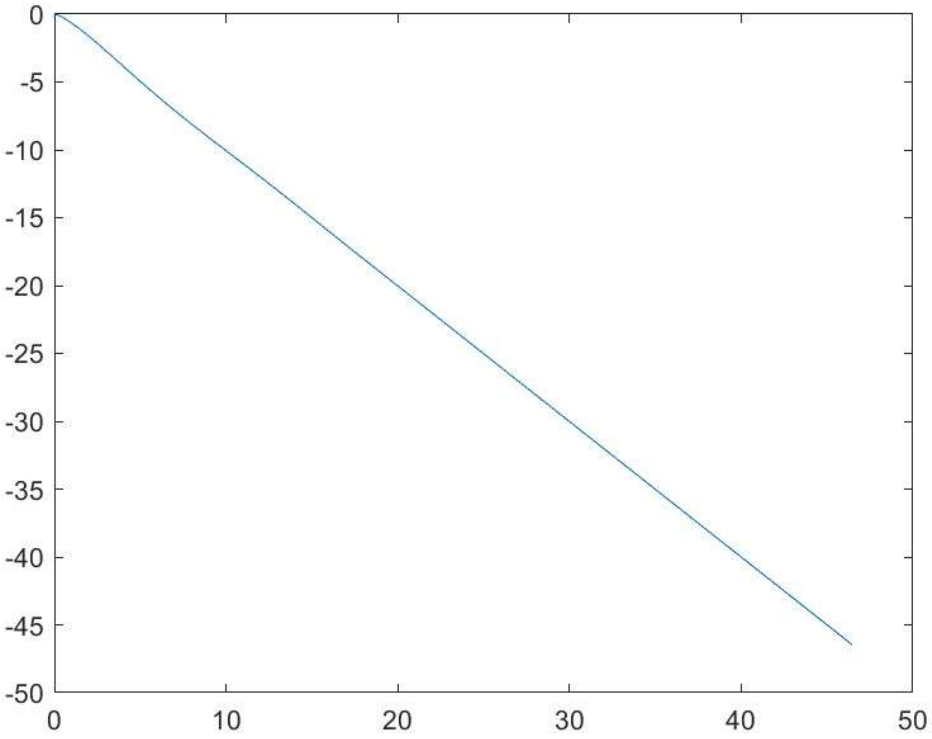
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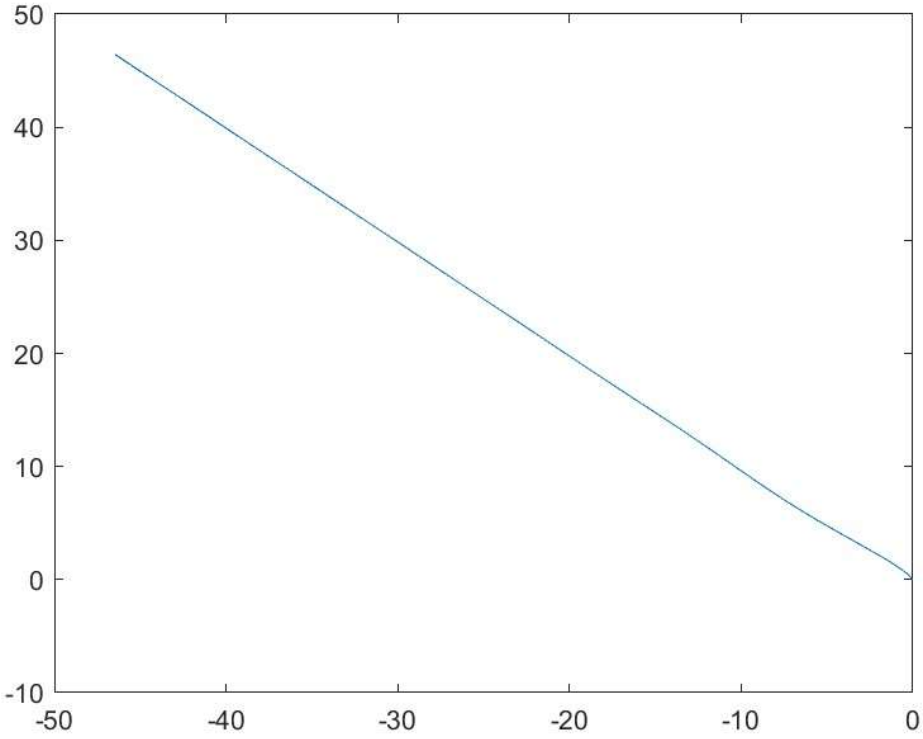
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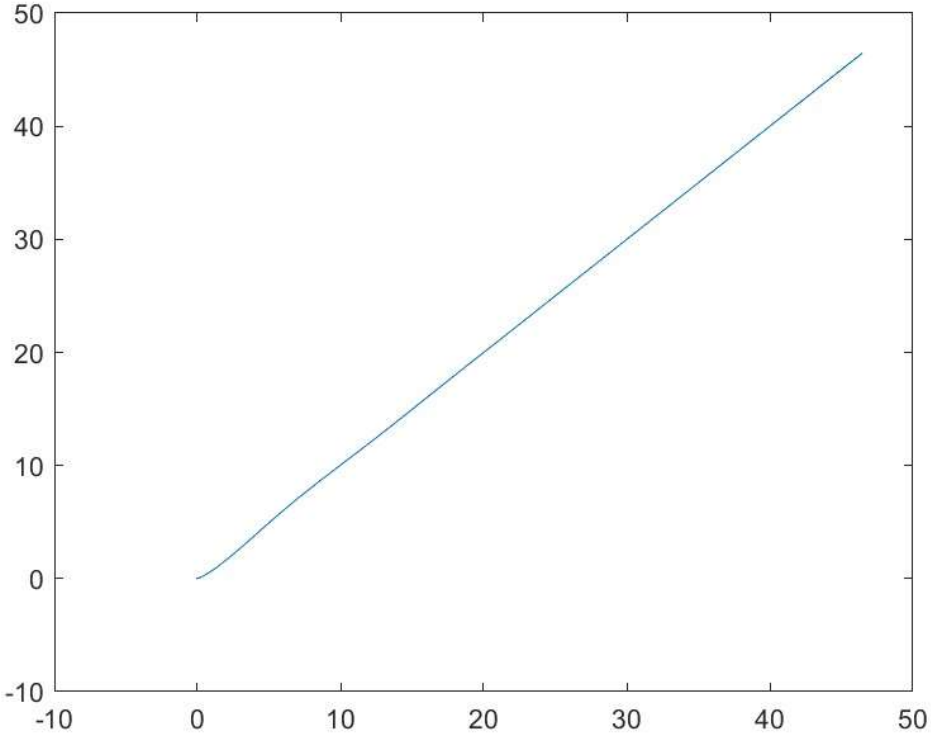
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30
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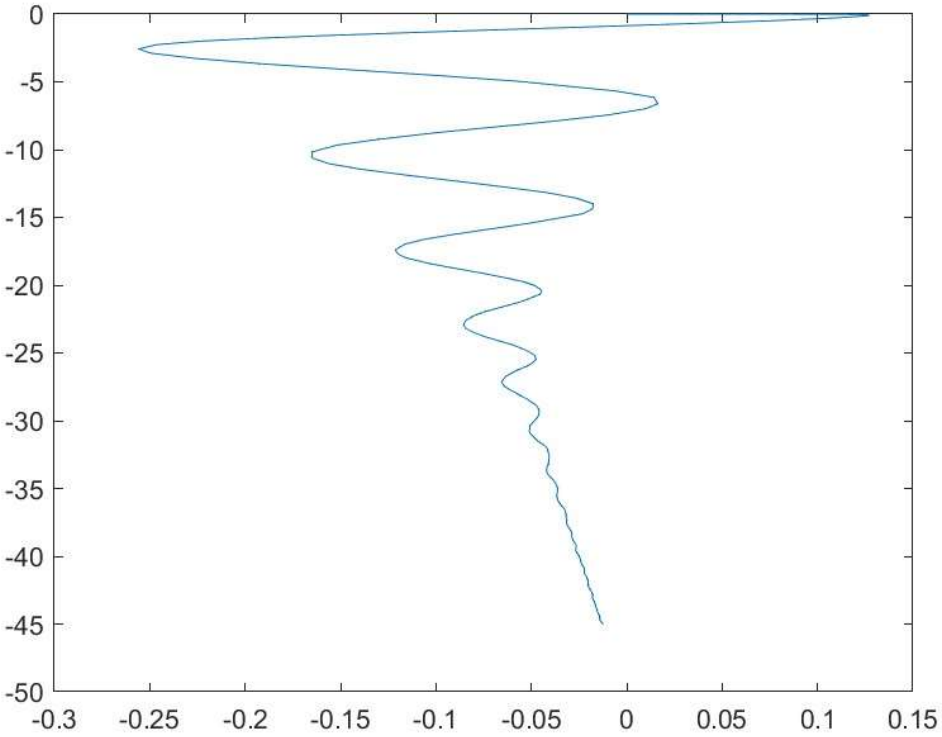
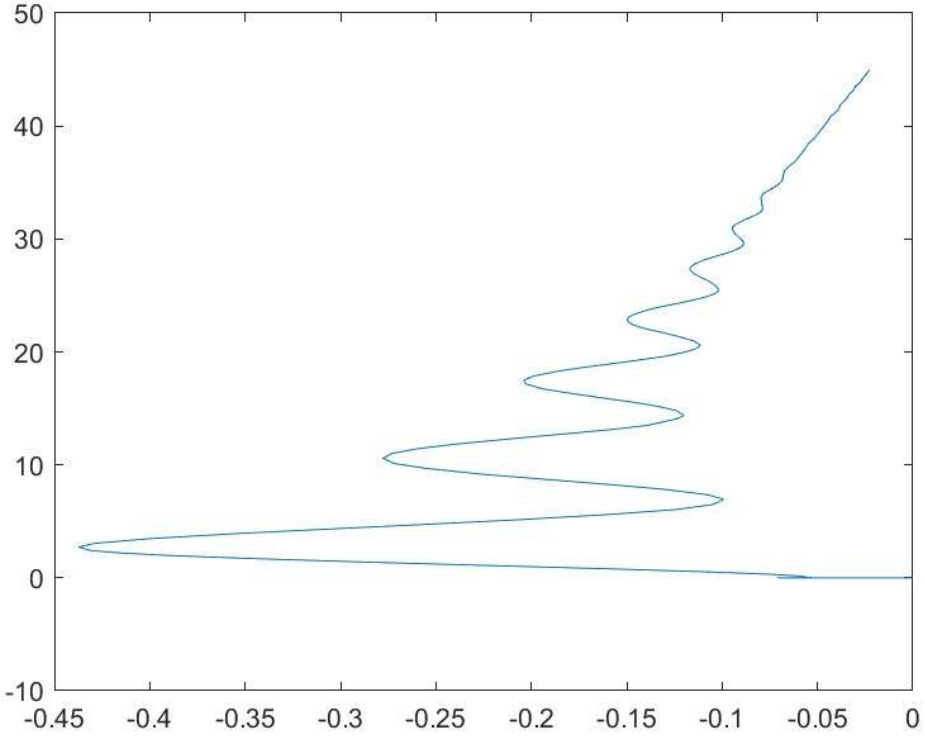
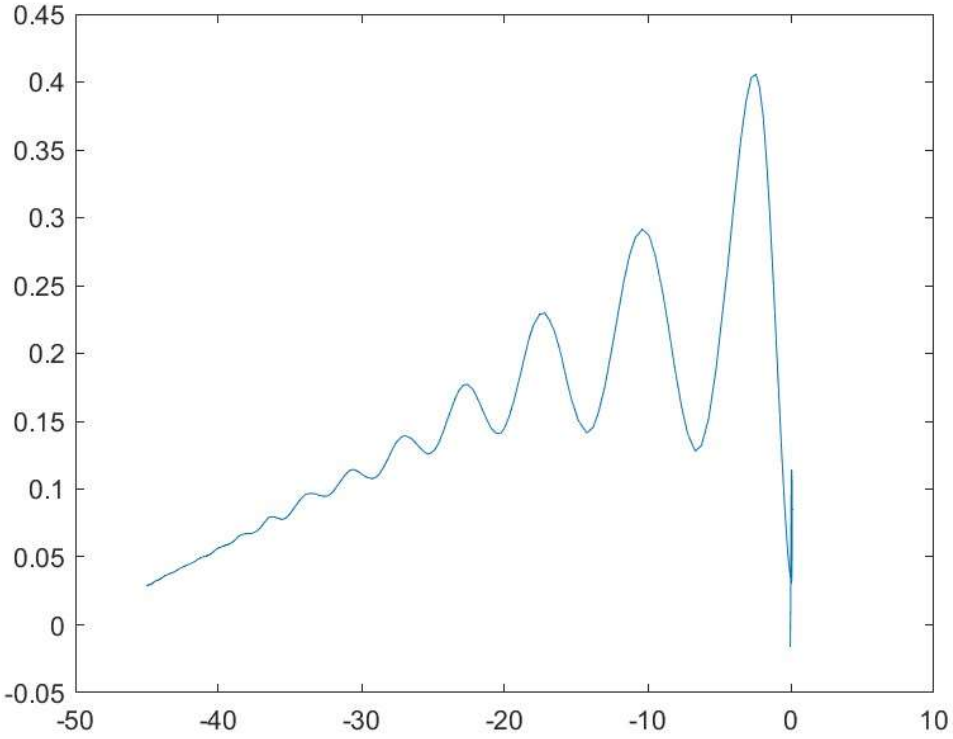
Non-Linear Controller



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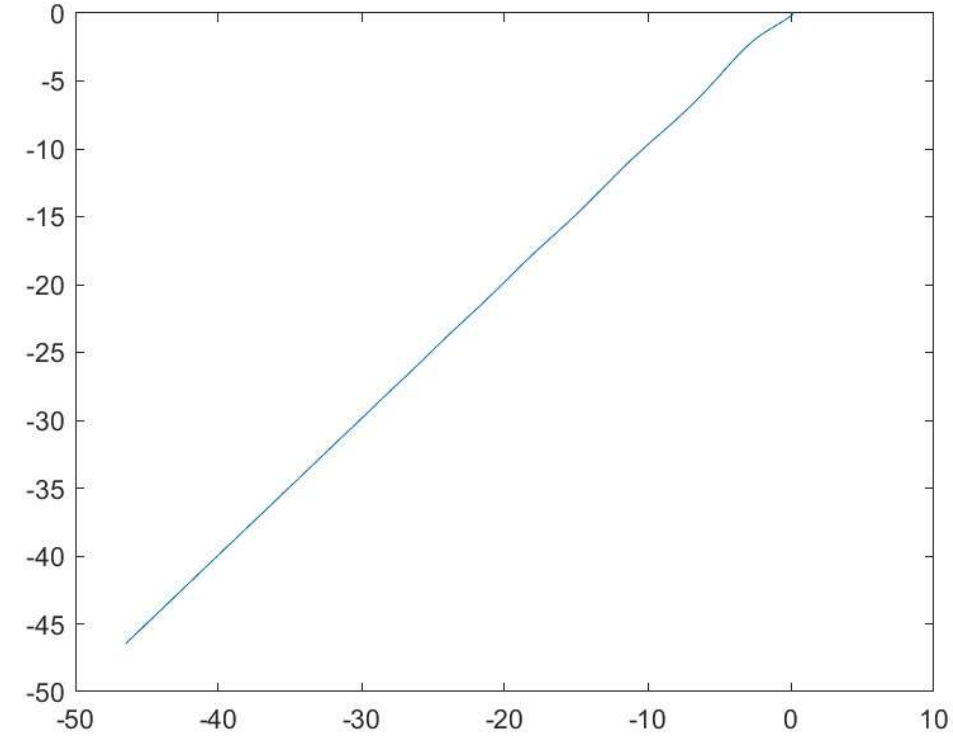
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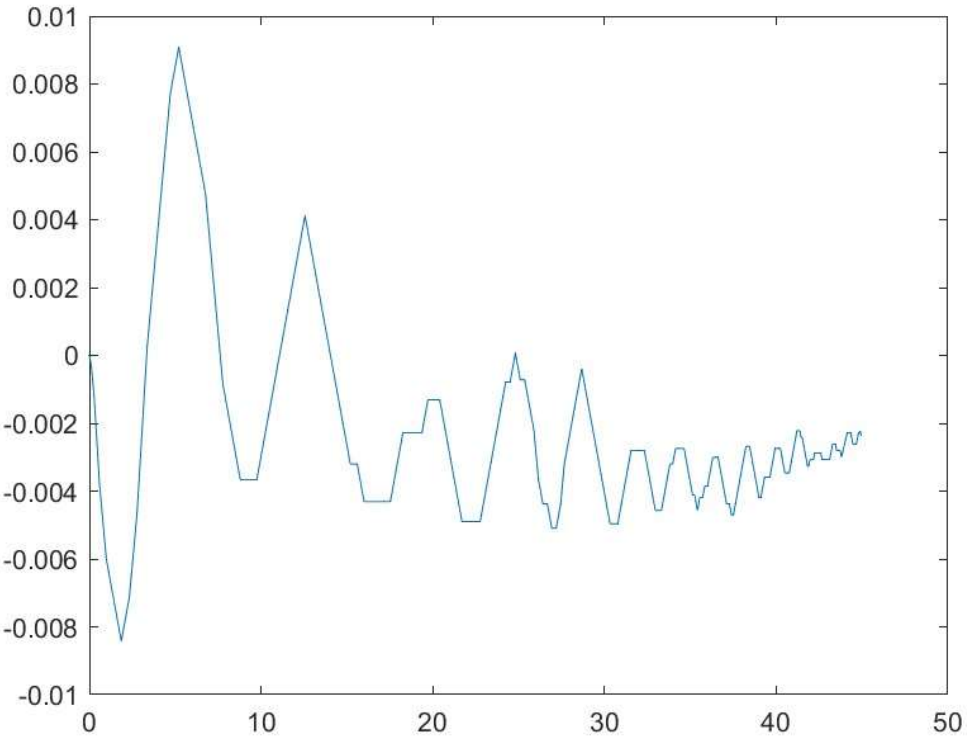
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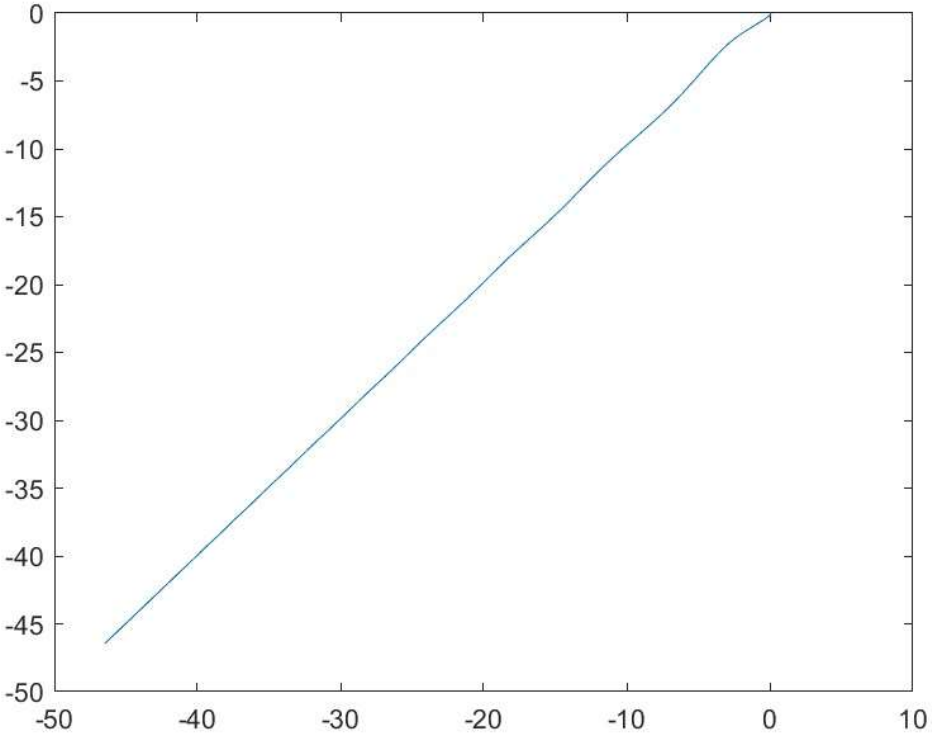
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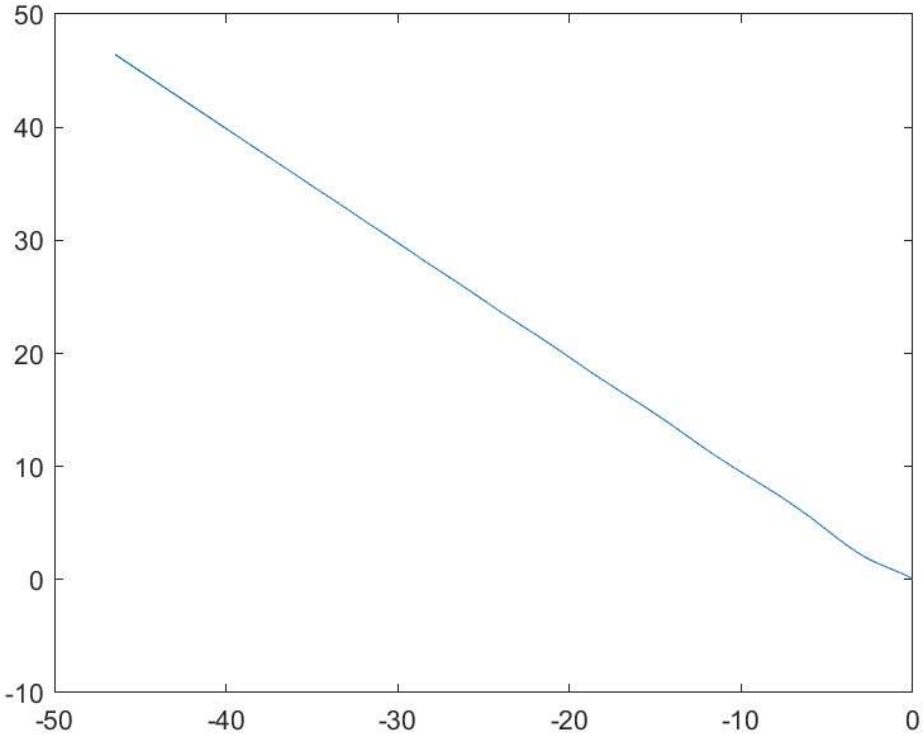
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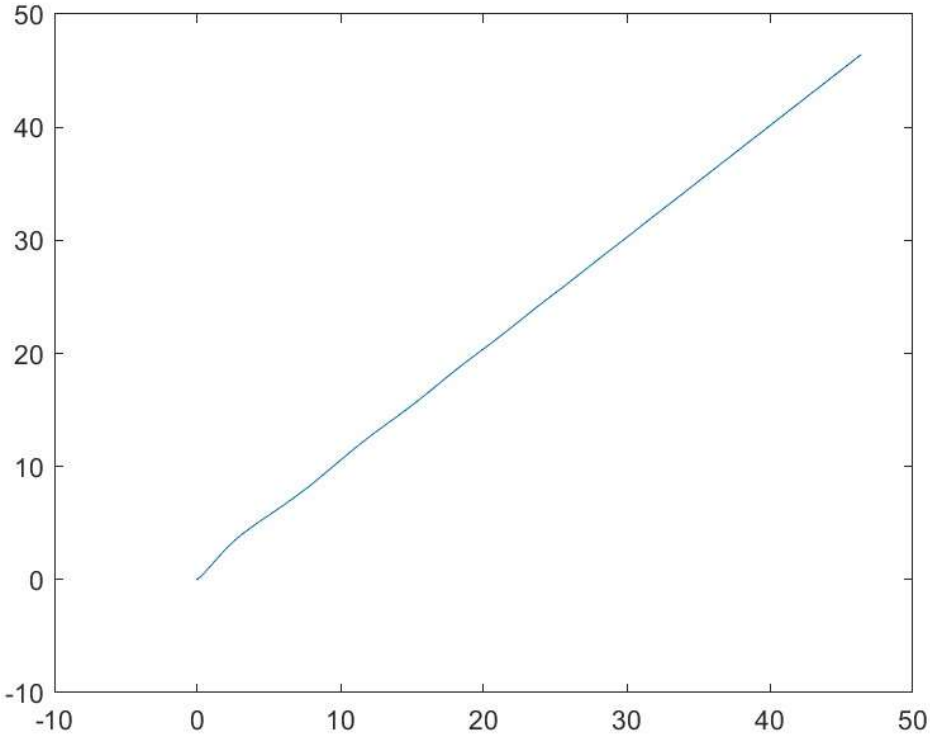
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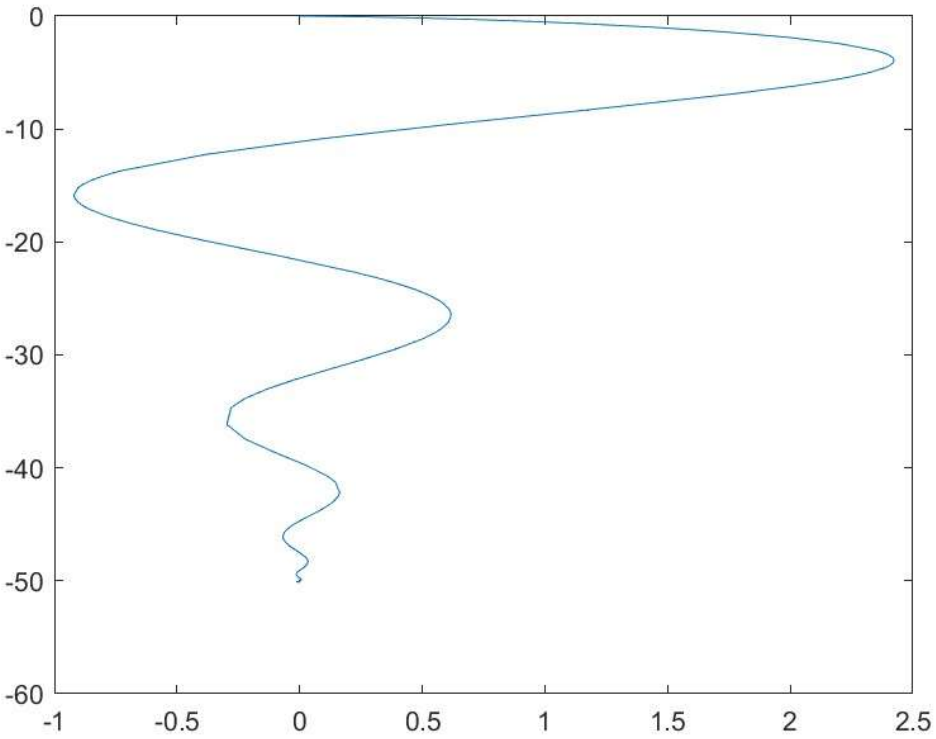
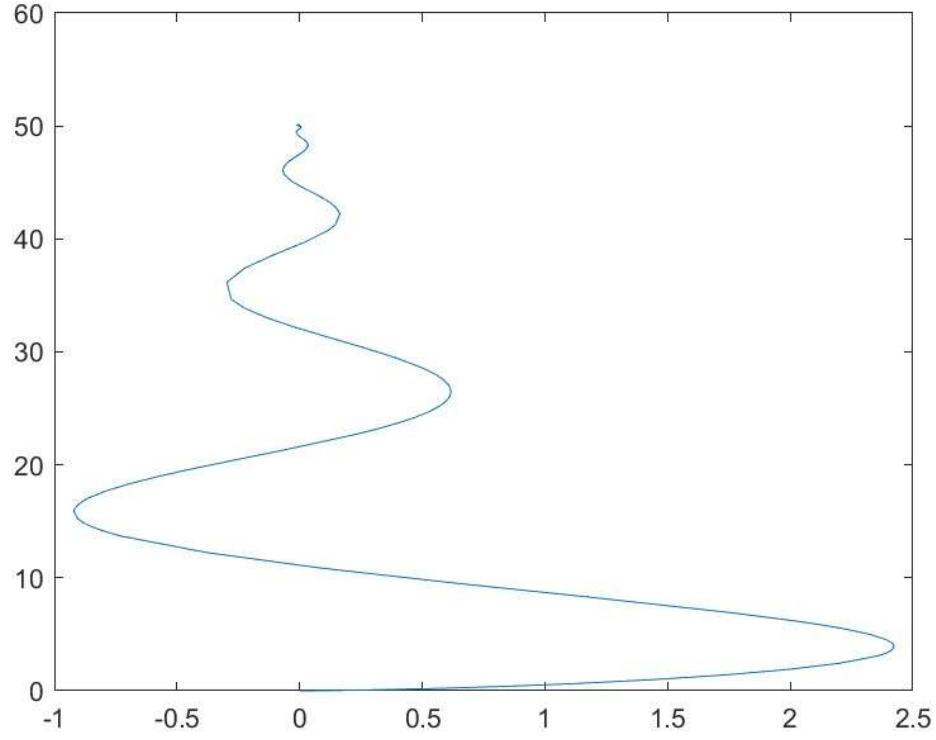
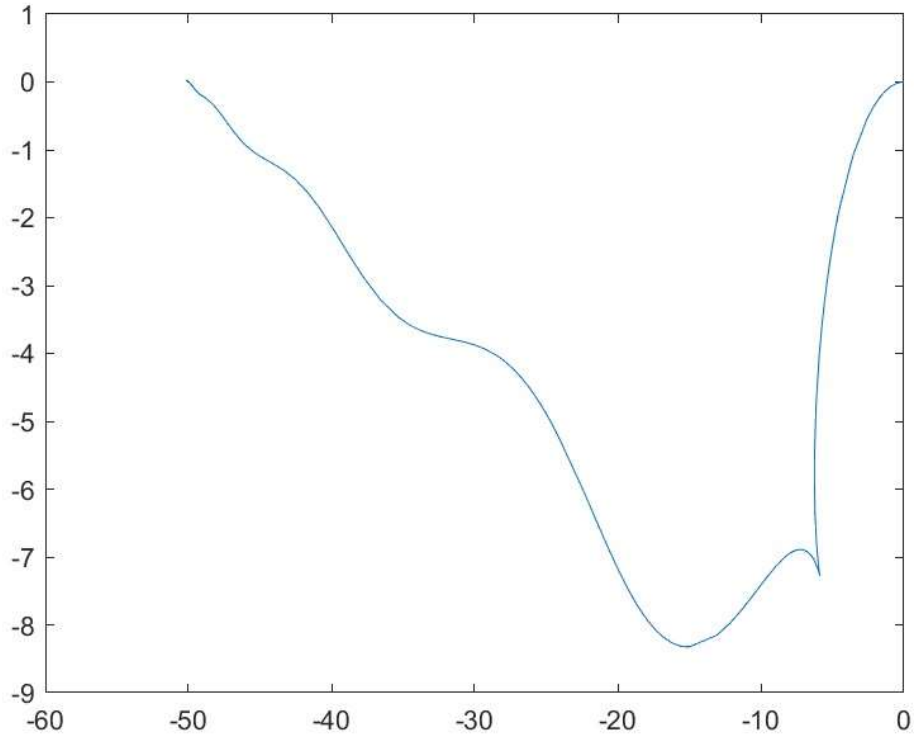
Non-Linear Controller From Simulink



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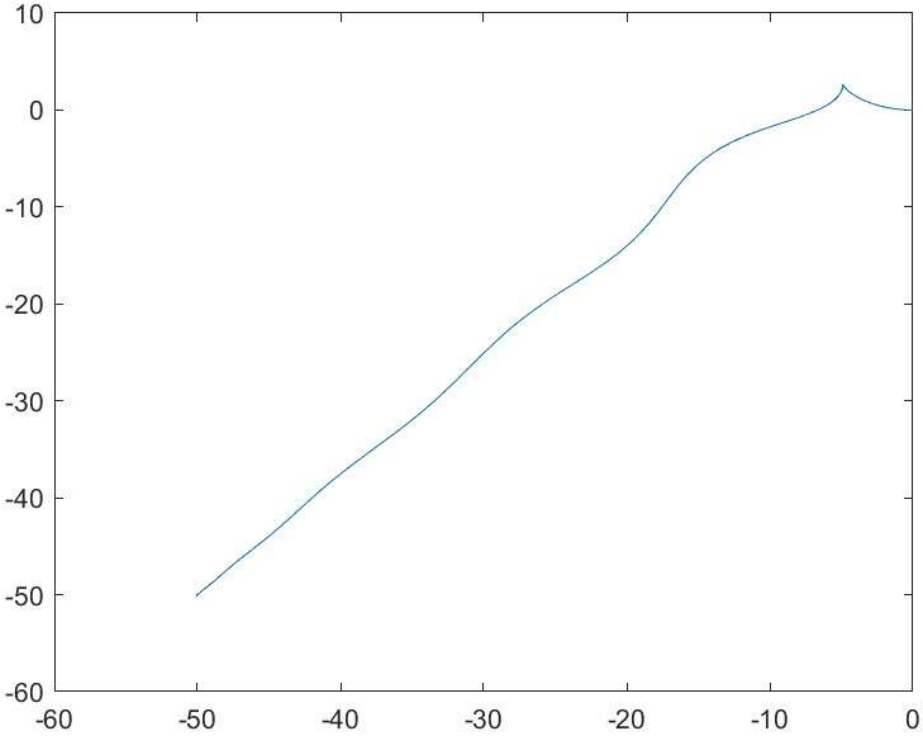
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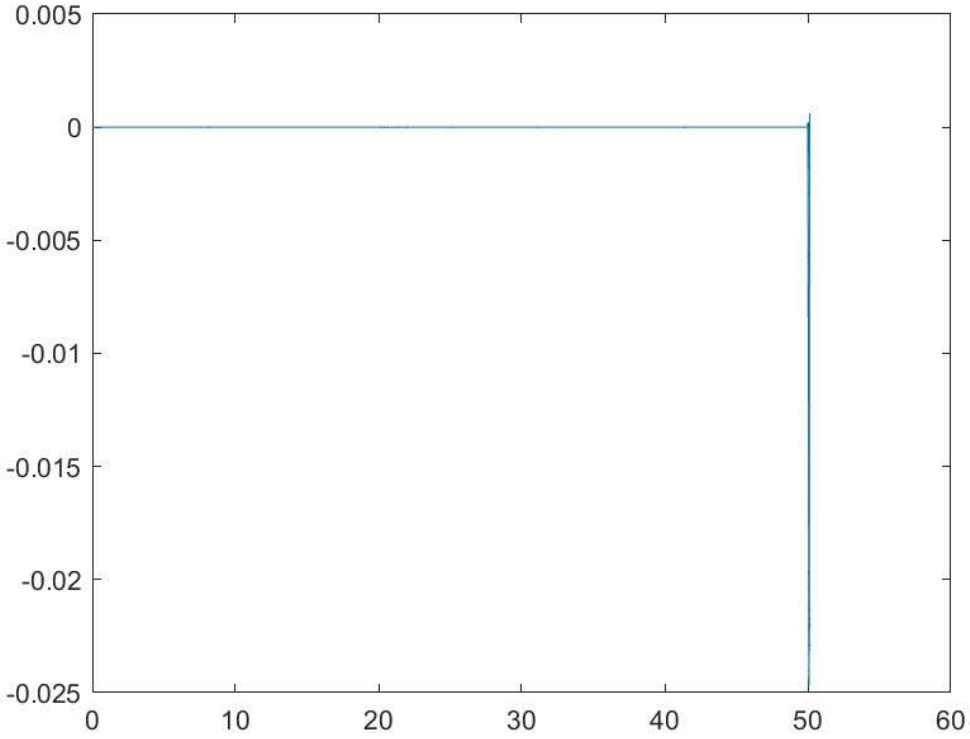
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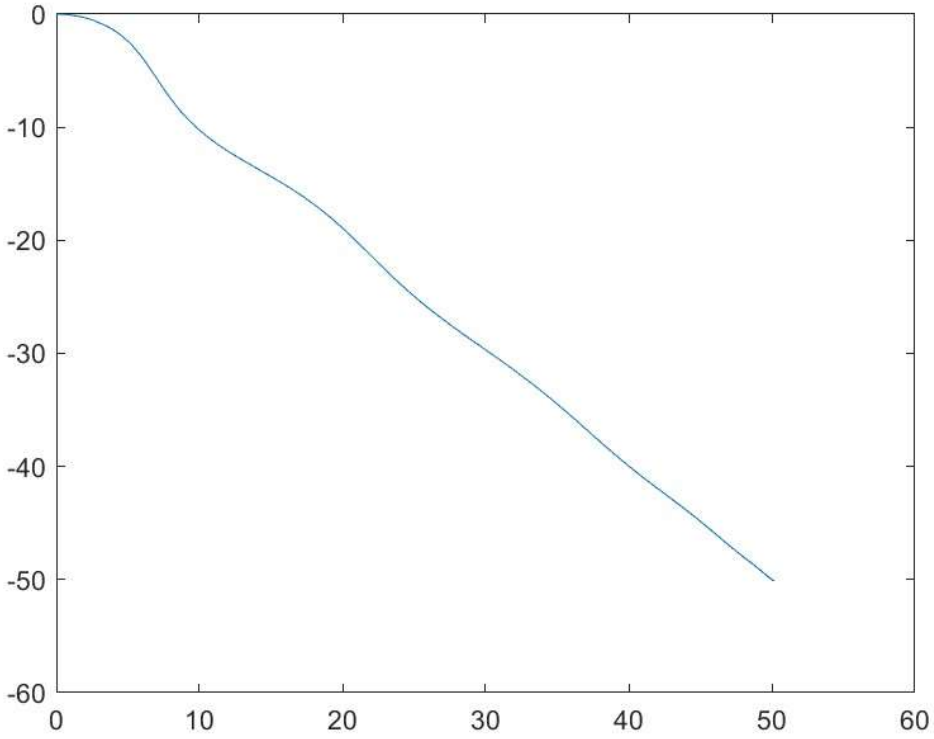
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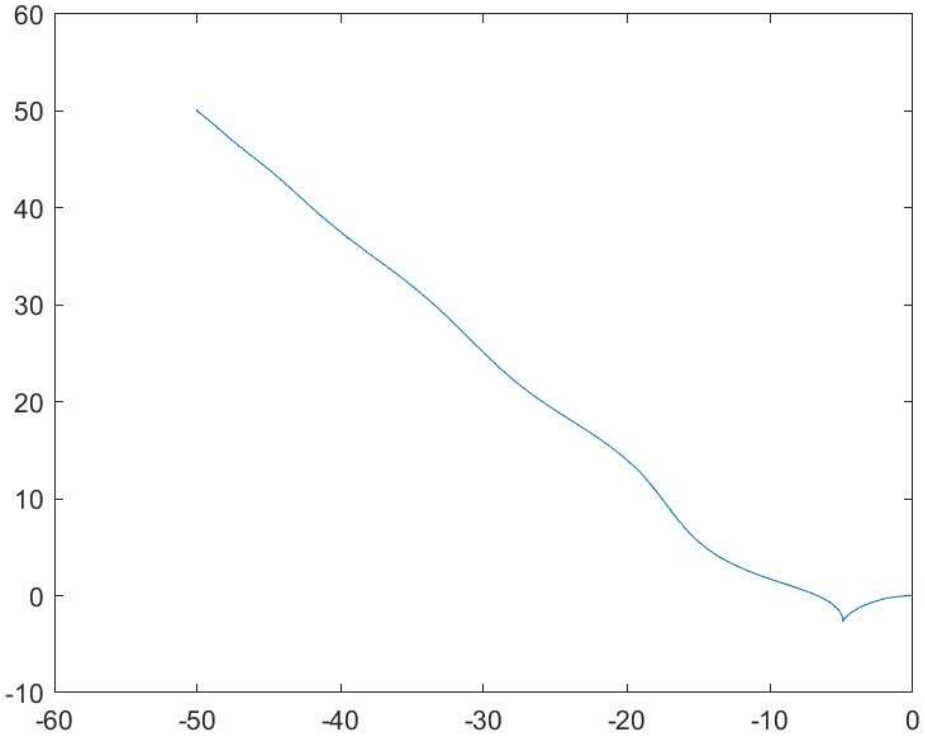
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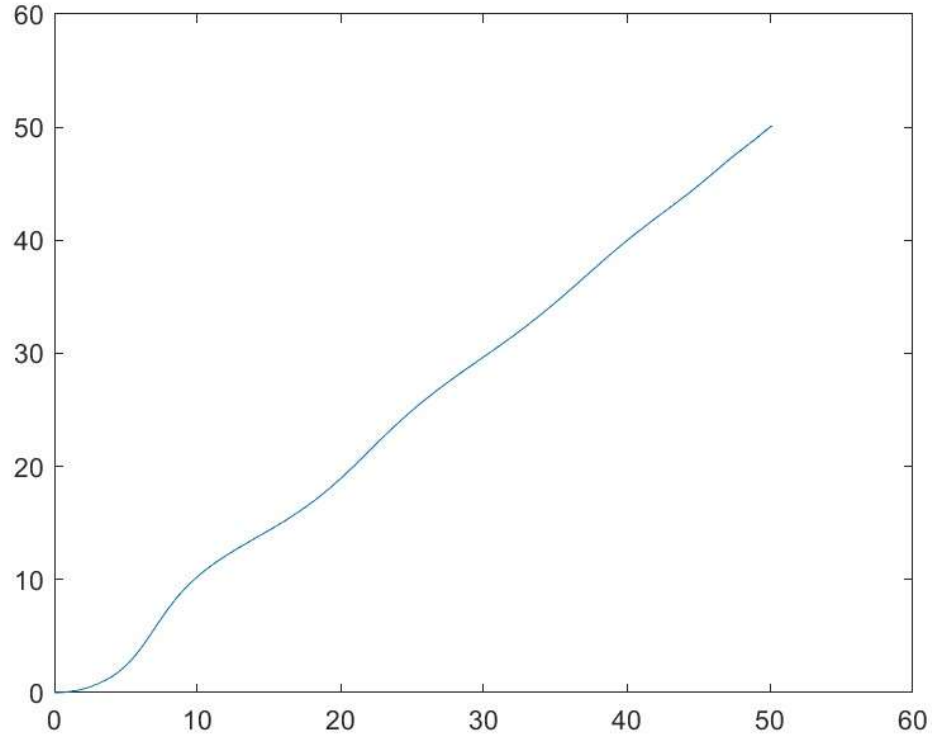
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