

Paul Prince's MPX

R1

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Chapter 1

Introduction

1.1 Repository

Version-control information is managed by Git, and hosted by GitHub: <https://github.com/pprince/cs450>

1.2 Documentation

Documentation for developers is generated by Doxygen; for detailed information about the files, functions, data structures, etc. that make up MPX and how they relate to each other, refer to:

- "MPX Programmer's Manual"

which can be found in the doc/ directory. Also, in the same directory, you can find the current version of:

- "MPX User's Manual"

Todo

Generally, documentation is incomplete.

Todo

Generally, we need to make lines break cleanly at 80-columns; Doxygen forces such line-breaks on us in the LaTeX output, but our source code frequently uses longer lines (making the PDF version of the developer manual very ugly!

Chapter 2

Todo List

page [Introduction](#) Generally, documentation is incomplete.

Generally, we need to make lines break cleanly at 80-columns; Doxygen forces such line-breaks on us in the LaTeX output, but our source code frequently uses longer lines (making the PDF version of the developer manual very ugly!

File [mpx_cmds.c](#) We should typedef structs (particularly struct [mpx_command](#)).

Chapter 3

Bug List

Global `add_command(char *name, void(*function)(int argc, char *argv[]))` This function doesn't check for failure to allocate memory for the new command struct.

Global `mpx_shell(void)` A command should be able to depend on `argv[argc] == NULL`, but we do not currently implement this feature.

Chapter 4

Data Structure Documentation

4.1 `date_rec` Struct Reference

Data Fields

- `int month`
- `int day`
- `int year`

The documentation for this struct was generated from the following file:

- `mpx/mpx_supt.h`

4.2 `mpx_command` Struct Reference

Node type for a singly-linked list of MPX commands.

```
#include <mpx_cmds.h>
```

Data Fields

- `char * name`
- `void(* function)(int argc, char *argv[])`
- `struct mpx_command * next`

4.2.1 Detailed Description

Node type for a singly-linked list of MPX commands.

The documentation for this struct was generated from the following file:

- `mpx/mpx_cmds.h`

4.3 params Struct Reference

Data Fields

- `int op_code`
- `int device_id`
- `char * buf_p`
- `int * count_p`

The documentation for this struct was generated from the following file:

- `mpx/mpx_supt.c`

4.4 pcb_queue_node Struct Reference

Data Fields

- `struct pcb_queue_node * next`
Pointer to the next PCB node in the queue.
- `struct pcb_queue_node * prev`
Pointer to the previous PCB node in the queue.
- `pcb_t * pcb`
Pointer to the actual PCB associated with this node.

4.4.1 Field Documentation

4.4.1.1 `struct pcb_queue_node* next`

Pointer to the next PCB node in the queue.

4.4.1.2 `struct pcb_queue_node* prev`

Pointer to the previous PCB node in the queue.

4.4.1.3 `pcb_t* pcb`

Pointer to the actual PCB associated with this node.

The documentation for this struct was generated from the following file:

- `mpx/pcb.h`

4.5 `pcb_queue_t` Struct Reference

PCB queue; represents a queue of processes.

```
#include <pcb.h>
```

Data Fields

- `pcb_queue_node_t * head`
Pointer to the first element in the queue.
- `pcb_queue_node_t * tail`
Pointer to the last element in the queue.
- unsigned int `length`
Number of elements in the queue.

4.5.1 Detailed Description

PCB queue; represents a queue of processes.

4.5.2 Field Documentation

4.5.2.1 `pcb_queue_node_t* head`

Pointer to the first element in the queue.

4.5.2.2 `pcb_queue_node_t* tail`

Pointer to the last element in the queue.

4.5.2.3 `unsigned int length`

Number of elements in the queue.

The documentation for this struct was generated from the following file:

- `mpx/pcb.h`

4.6 `pcb_t` Struct Reference

Process control block structure.

```
#include <pcb.h>
```

Data Fields

- `char name [MAX_ARG_LEN+1]`
Name of the process (i.e., its argv[0] in unix-speak).
- `process_class_t class`
Process class (differentiates applications from system processes).
- `int priority`
Process priority.
- `process_state_t state`
Process state (Ready, Running, or Blocked).
- `unsigned char * stack_top`
Pointer to the top of this processes's stack.
- `unsigned char * stack_base`
Pointer to the bottom of this processes's stack.
- `int memory_size`
Memory size ...
- `unsigned char * load_address`

Load address ...

- unsigned char * [exec_address](#)

Execution address ...

4.6.1 Detailed Description

Process control block structure.

4.6.2 Field Documentation

4.6.2.1 char name[MAX_ARG_LEN+1]

Name of the process (i.e., its argv[0] in unix-speak).

4.6.2.2 process_class_t class

Process class (differentiates applications from system processes).

4.6.2.3 int priority

Process priority.

Higher numerical value = higher priority.

Valid values are -128 through 127 (inclusive).

4.6.2.4 process_state_t state

Process state (Ready, Running, or Blocked).

4.6.2.5 unsigned char* stack_top

Pointer to the top of this processes's stack.

4.6.2.6 unsigned char* stack_base

Pointer to the bottom of this processes's stack.

4.6.2.7 int memory_size

Memory size ...

will be used in R3 and R4.

4.6.2.8 unsigned char* load_address

Load address ...

will be used in R3 and R4.

4.6.2.9 unsigned char* exec_address

Execution address ...

will be used in R3 and R4.

The documentation for this struct was generated from the following file:

- [mpx/pcb.h](#)

Chapter 5

File Documentation

5.1 mpx/mpx.c File Reference

MPX `main()` function.

```
#include "mpx_supt.h"
#include "mpx_util.h"
#include "mpx_sh.h"
#include "mpx_cmds.h"
#include "mpx_pcb.h"
```

Functions

- void `main` (int argc, char *argv[])
This is the start-of-execution for the MPX executable.

5.1.1 Detailed Description

MPX `main()` function.

Author

Paul Prince <paul@littlebluetech.com>

Date

2011

This file contains the start-of-execution, i.e. function `main()`, for MPX, and also the top-level Doxygen documentation that becomes the introductory sections of the developer's manual.

5.1.2 Function Documentation

5.1.2.1 `void main (int argc, char * argv[])`

This is the start-of-execution for the MPX executable.

```
{
    sys_init( MODULE_R1 ); /* System-specific initialization.      */

    init_commands();      /* Initialization for MPX user commands. */
    init_pcb_queues();    /* Initialization for PCB queues.        */

    mpx_shell();          /* Execute the command-handler loop.     */

    /* mpx_shell() should never return, so if we get here, then
     * we should exit with error status (but don't actually...). */
    printf("FATAL ERROR: mpx_shell() returned! That shouldn't happen...\n");
    sys_exit();           /* Terminate, after doing MPX-specific cleanup. */
}
```

5.2 mpx/mpx_cmds.c File Reference

MPX shell commands (help, ls, exit, etc.)

```
#include "mpx_cmds.h"
#include "mpx_supt.h"
#include "mpx_util.h"
#include <string.h>
```

Functions

- void `add_command` (char *name, void(*function)(int argc, char *argv[]))
Adds a command to the MPX shell.
- void `dispatch_command` (char *name, int argc, char *argv[])
Runs the shell command specified by the user, if it is valid.
- void `mpxcmd_commands` (int argc, char *argv[])
- void `mpxcmd_date` (int argc, char *argv[])

- void **mpxcmd_exit** (int argc, char *argv[])
- void **mpxcmd_help** (int argc, char *argv[])
- void **mpxcmd_version** (int argc, char *argv[])
- void **mpxcmd_ls** (int argc, char *argv[])
- void **init_commands** (void)

Variables

- static struct [mpx_command](#) * [list_head](#) = NULL
A linked-list of MPX shell commands.

5.2.1 Detailed Description

MPX shell commands (help, ls, exit, etc.)

Author

Paul Prince <paul@littlebluetechnology.com>

Date

2011

This file implements each of the user commands for MPX.

Todo

We should typedef structs (particularly struct [mpx_command](#)).

5.2.2 Function Documentation

5.2.2.1 void add_command (char * *name*, void(*) (int argc, char *argv[]) *function*)

Adds a command to the MPX shell.

Bug

This function doesn't check for failure to allocate memory for the new command struct.

Parameters

in	<i>name</i>	The command name that will be made available in the shell.
in	<i>function</i>	The C function which will implement the shell command.

```

{
    /* Temporary variable for iterating through the list of commands. */
    struct mpx_command *this_command;

    /* Allocate space for the new command structure. */
    struct mpx_command *new_command =
        (struct mpx_command *)sys_alloc_mem(sizeof(struct mpx_command));
    new_command->name = (char *)sys_alloc_mem(MAX_ARG_LEN+1);
    /* Initialize the structure. */
    strcpy( new_command->name, name );
    new_command->function = function;
    new_command->next = NULL;

    /* Insert the new command into the linked-list of commands. */
    this_command = list_head;
    if ( this_command == NULL ) {
        list_head = new_command;
    } else {
        while ( this_command->next != NULL ){
            this_command = this_command->next;
        }
        this_command->next = new_command;
    }
}

```

5.2.2.2 void dispatch_command (char * name, int argc, char * argv[])

Runs the shell command specified by the user, if it is valid.

This function checks to see if the shell command given unambiguously matches a valid MPX shell command, and if so, runs that command (passing the provided argc and argv through).

This dispatcher allows abbreviated commands; if the requested command matches multiple (or zero) valid MPX shell commands, the user is alerted.

Attention

Produces output (via printf)!

```

{

    /* Temporary variable for iterating through the list of commands. */
    struct mpx_command *this_command = list_head;

    /* Temporary variables to keep track of matching command names. */
    int num_matches = 0;
    struct mpx_command *first_match;

    /* Iterate through the linked list of commands, */
    while( this_command != NULL ) {

        /* Check to see if the given command is a valid abbrev. for the c

```

```

current command from the list */
    if( strcmp( this_command->name, name, strlen(name) ) == 0 ) {
        /* If so, keep track of how many matches thus far, */
        num_matches++;
        if (num_matches == 1) {
            /* This is the first match in the list for the gi
ven command. */
            first_match = this_command;
        } else if (num_matches == 2) {
            /* This is the first duplicate match in the list;

            * Print out the 'ambiguous command' header,
            * plus the first AND current ambiguous commands.

        */
            printf("Ambiguous command: %s\n", name);
            printf("    Matches:\n");
            printf("        %s\n", first_match->name);
            printf("        %s\n", this_command->name);
        } else {
            /* This is a subsequent duplicate match;
            * by this time, the header etc. has already been
            * so we only need to print out the current comma
nd name. */
            printf("        %s\n", this_command->name);
        }
    }

    this_command = this_command->next;
}

/* If we got a command name that matches unambiguously, run that command.
*/
if ( num_matches == 1 ){
    first_match->function(argc, argv);
}

/* Otherwise, if we got no matches at all, say so. */
if ( num_matches == 0 ){
    printf("ERROR: Invalid command name.\n");
    printf("Type \"commands\" to see a list of valid commands.\n");
}
}

```

5.2.2.3 void mpxcmd_date (int argc, char * argv[])

< Temp. storage for the return value of sys_ functions.

< Structure to hold a date (day, month, and year). Will be used for both getting and setting the MPX system date.

```

{
    int retval;
    date_rec date;

```

```

    if ( argc == 1 ){
        sys_get_date(&date);
        printf("Current MPX system date (yyyy-mm-dd): %04d-%02d-%02d\n",
date.year, date.month, date.day);
        return;
    }

    if ( argc == 4 ){

        date.year  = atoi(argv[1]);
        date.month = atoi(argv[2]);
        date.day   = atoi(argv[3]);

        if ( ! mpx_validate_date(date.year, date.month, date.day) ) {
            printf("ERROR: Invalid date specified; MPX system date is
unchanged.\n");
            printf("          Valid dates are between 1900-01-01 and 299
9-12-31, inclusive.\n");
            return;
        }

        retval = sys_set_date(&date);
        if ( retval != 0 ) {
            printf("ERROR: sys_set_date() returned an error.\n");
            return;
        }

        printf("The MPX system date has been changed.\n");
        return;
    }

    printf("ERROR: Wrong number of arguments to 'date'.\n");
    printf("          Type 'help date' for usage information.\n");
}

```

5.2.3 Variable Documentation

5.2.3.1 struct mpx_command* list_head = NULL [static]

A linked-list of MPX shell commands.

5.3 mpx/mpx_sh.c File Reference

MPX Shell, aka Command Handler.

```

#include "mpx_sh.h"
#include "mpx_supt.h"
#include "mpx_util.h"

```

```
#include "mpx_cmds.h"
#include <string.h>
```

Functions

- void `mpx_setprompt` (char *new_prompt)
Sets the current prompt to whatever string is given.
- void `mpx_shell` (void)
This function implements the MPX shell (command-line user interface).

Variables

- static char * `mpx_prompt_string` = NULL
The current prompt string.

5.3.1 Detailed Description

MPX Shell, aka Command Handler. This file implements the user interface for MPX.

5.3.2 Function Documentation

5.3.2.1 void mpx_setprompt (char * new_prompt)

Sets the current prompt to whatever string is given.

If new_prompt is NULL, this is a no-op.

```
    {
    if (new_prompt == NULL) return;
    if (mpx_prompt_string != NULL) {
        sys_free_mem(mpx_prompt_string);
    }
    mpx_prompt_string = (char *) sys_alloc_mem(strlen(new_prompt)+1);
    strcpy(mpx_prompt_string, new_prompt);
}
```

5.3.2.2 void mpx_shell (void)

This function implements the MPX shell (command-line user interface).

[mpx_shell\(\)](#) never returns!

Bug

A command should be able to depend on `argv[argc] == NULL`, but we do not currently implement this feature.

```
{

/* A buffer to hold the command line input by the user.
 * We include space for the \r, \n, and \0 characters, if any. */
char cmdline[ MAX_CMDLINE_LEN+2 ];

/* Buffer size argument for passing to sys_req(). */
int line_buf_size = MAX_CMDLINE_LEN;

/* Used to capture the return value of sys_req(). */
int err;

/* argc to be passed to MPX command; works just like the one passed to main(). */
int argc;
/* argv array to be passed to MPX command; works almost just like the one
passed to main().
 *
 * But there is one caveat: argv[argc] is undefined in my implementation,
not guaranteed to be NULL. */
char **argv;

/* Temporary pointer for use in string tokenization. */
char *token;

/* Delimiters that separate arguments in the MPX shell command-line environment. */
char *delims = "\t \n";

/* An index for use in for(;;) loops. */
int i;
/* An index for use in nested for(;;) loops. */
int j;

/* We must initialize the prompt string. */
mpx_setprompt(MPX_DEFAULT_PROMPT);

/* Loop Forever; this is the REPL. */
/* This loop terminates only via the MPX 'exit' command. */
for(;;) {
    /* Output the current MPX prompt string. */
    printf("%s", mpx_prompt_string);

    /* Read in a line of input from the user. */
    sys_req( READ, TERMINAL, cmdline, &line_buf_size );
}
```



```

        /* Remove trailing newline. */
        mpx_chomp(cmdline);

        /* Allocate space for the argv argument that is to be sent to an
        MPX command. */
        argv = (char **)sys_alloc_mem( sizeof(char**) * (MAX_ARGS+1) ); /
    * +1 for argv[0] */
        for( i=0; i < MAX_ARGS+1; i++ ){                                /
    * +1 for argv[0] */
            argv[i] = sys_alloc_mem(MAX_ARG_LEN+1);                      /
    * +1 for \0 */
        }

        /* Tokenize the command line entered by the user, and set argc. *
        /
        /* 0 is a special value here for argc; a value > 0 after the for
        loop indicates
        * that tokenizing was successful and that argc and argv contain
        valid data.
        *
        ***** NOTE:  argc includes argv[0], but MAX_ARGS does not! ***
        **/

        argc = 0; token = NULL;

        for( i=0; i < MAX_ARGS+1; i++ ){

            if (i==0) {
                token = strtok( cmdline, delims );
            } else {
                token = strtok( NULL, delims );
            }

            if (token == NULL) {
                /* No more arguments. */
                break;
            }

            if (strlen(token) > MAX_ARG_LEN) {
                /* This argument is too long. */
                printf("ERROR: Argument too long. MAX_ARG_LEN is
%d.\n", MAX_ARG_LEN);
                argc = 0;
                break;
            }

            argc++;
            strcpy( argv[i], token );
        }

        if ( strtok( NULL, delims ) != NULL ){
            /* Too many arguments. */
            printf("ERROR: Too many arguments. MAX_ARGS is %d.\n", MA
X_ARGS);
            continue;

```

```

    }

    if ( argc <= 0 ) {
        /* Blank command; just re-print the prompt. */
        continue;
    }

    /* Run the command, or print an error if it is invalid. */
    dispatch_command( argv[0], argc, argv );

    /* Free the memory for the dynamically-allocated *argv[] */
    for( i=0; i < MAX_ARGS+1; i++ ){
        sys_free_mem( argv[i] );
    }
    sys_free_mem( argv );
}
}

```

5.3.3 Variable Documentation

5.3.3.1 `char* mpx_prompt_string = NULL` [static]

The current prompt string.

5.4 mpx/mpx_util.c File Reference

Various utility functions used by all of MPX.

```

#include "mpx_util.h"
#include "mpx_supt.h"
#include <string.h>
#include <stdio.h>

```

Functions

- int `mpx_chomp` (char *str)
Removes trailing newline, if any.
- int `mpx_validate_date` (int year, int month, int day)
- int `mpx_cat` (char *file_name)

5.4.1 Detailed Description

Various utility functions used by all of MPX. This file contains the functions etc. to implement the user interface for MPX.

5.4.2 Function Documentation

5.4.2.1 `int mpx_chomp (char * str)`

Removes trailing newline, if any.

This function checks to see if the last character in a string is a newline, and, if so, removes it. Otherwise, the string is left unchanged.

The input must be a valid (allocated and null-terminated) C string, otherwise the results are undefined (but will most likely result in a segmentation fault / protection fault).

Returns the number of characters removed from the string.

Parameters

<i>str</i>	The string to chomp.
------------	----------------------

```

    {
        if( strlen(str) > 0 ){
            if( str[ strlen(str)-1 ] == '\n' ){
                str[ strlen(str)-1 ] = '\0';
                return 1;
            }
        }
        return 0;
    }

```

5.5 mpx/pcb.c File Reference

PCBs, process queues, and functions to operate on them.

```

#include "pcb.h"
#include "mpx_supt.h"
#include "mpx_util.h"

```

Functions

- void [init_pcb_queues](#) (void)
Must be called before using any other PCB or queue functions.

- `pcb_t * allocate_pcb (void)`
Allocates memory for a new PCB, but does not initialize it.
- `pcb_t * setup_pcb (char *name, int priority, process_class_t class)`
Creates a new PCB object and initializes its fields.
- `pcb_t * find_pcb_in_queue (char *name, pcb_queue_t *queue)`
Search the given queue for the named process.
- `pcb_t * find_pcb (char *name)`
Finds a process.

Variables

- static `pcb_queue_t queue_ready`
- static `pcb_queue_t queue_blocked`
- static `pcb_queue_t queue_susp_ready`
- static `pcb_queue_t queue_susp_blocked`

5.5.1 Detailed Description

PCBs, process queues, and functions to operate on them.

Author

Paul Prince <paul@littlebluetech.com>

Date

2011

5.5.2 Function Documentation

5.5.2.1 void init_pcb_queues (void)

Must be called before using any other PCB or queue functions.

```
{
    queue_ready.head      = NULL;
    queue_ready.tail      = NULL;
    queue_ready.length    = 0;

    queue_blocked.head    = NULL;
```

```

queue_blocked.tail          = NULL;
queue_blocked.length        = 0;

queue_susp_ready.head       = NULL;
queue_susp_ready.tail       = NULL;
queue_susp_ready.length     = 0;

queue_susp_blocked.head     = NULL;
queue_susp_blocked.tail     = NULL;
queue_susp_blocked.length   = 0;
}

```

5.5.2.2 pcb_t* allocate_pcb (void)

Allocates memory for a new PCB, but does not initialize it.

This function will also allocate memory for the stack and initialize the stack_top and stack_base members.

Returns

Returns a pointer to the new PCB, or NULL if an error occurred.

```

{
    /* Pointer to the new PCB we will allocate. */
    pcb_t *new_pcb;

    /* Allocate memory for the PCB. */
    new_pcb = (pcb_t *)sys_alloc_mem(sizeof(pcb_t));
    if ( new_pcb == NULL ) {
        /* Error allocating memory for the PCB. */
        return NULL;
    }

    /* Allocate memory for the PCB's stack. */
    new_pcb->stack_base = (unsigned char *)sys_alloc_mem(STACK_SIZE);
    if ( new_pcb->stack_base == NULL ) {
        /* Error allocating memory for the PCB's stack. */
        sys_free_mem(new_pcb);
        return NULL;
    }

    /* Initialize stack_top member. */
    new_pcb->stack_top = new_pcb->stack_base + STACK_SIZE;

    return new_pcb;
}

```

5.5.2.3 pcb_t* setup_pcb (char * name, int priority, process_class_t class)

Creates a new PCB object and initializes its fields.

Returns

Returns a pointer to the new PCB, or NULL if an error occurred.

Parameters

<i>name</i>	Name of the new process. Must be unique among all processes.
<i>priority</i>	Priority of the process. Must be between -127 and 128 (incl.)
<i>class</i>	Class of the process; one of APPLICATION or SYSTEM.

```

{
    /* Loop index. */
    int i;

    /* Pointer to the new PCB we're creating. */
    pcb_t *new_pcb;

    /* Check that arguments are valid. */
    if ( find_pcb(name) != NULL ) {
        /* Name is not unique. */
        return NULL;
    }
    if ( strlen(name) > MAX_ARG_LEN || name == NULL ) {
        /* Invalid name. */
        return NULL;
    }
    if ( priority < -127 || priority > 128 ) {
        /* Value of priority is out of range. */
        return NULL;
    }
    if ( class != APPLICATION && class != SYSTEM ) {
        /* Invalid class specified. */
        return NULL;
    }

    /* Allocate the new PCB. */
    new_pcb = allocate_pcb();
    if (new_pcb == NULL) {
        /* Allocation error. */
        return NULL;
    }

    /* Set the given values. */
    new_pcb->priority = priority;
    new_pcb->class = class;
    strcpy( new_pcb->name, name );

    /* Set other default values. */
    new_pcb->state = READY;
    new_pcb->memory_size = 0;
    new_pcb->load_address = NULL;
    new_pcb->exec_address = NULL;
}

```

```

    /* Initialize the stack to 0's. */
    for (i=0; i<STACK_SIZE; i++) {
        *(new_pcb->stack_base + i) = (unsigned char)0;
    }

    return new_pcb;
}

```

5.5.2.4 `pcb_t* find_pcb_in_queue(char * name, pcb_queue_t * queue)` [private]

Search the given queue for the named process.

Returns

Returns a pointer to the PCB, or NULL if not found or error.

Parameters

<i>name</i>	The name of the process to find.
<i>queue</i>	The PCB queue in which to search for the process.

```

{
    pcb_queue_node_t *this_queue_node = queue->head;

    while (this_queue_node != NULL) {
        if ( strcmp( this_queue_node->pcb->name, name) == 0 ) {
            return this_queue_node->pcb;
        }
    }

    /* If we get here, we didn't find the process. */
    return NULL;
}

```

5.5.2.5 `pcb_t* find_pcb(char * name)`

Finds a process.

Searches all process queues.

Returns

Returns a pointer to the PCB, or NULL if not found or error.

Parameters

<i>name</i>	The name of the process to find.
-------------	----------------------------------

```

{
    /* Pointer to the requested PCB, if we find it. */
    pcb_t *found_pcb;

    /* Validate arguments. */
    if ( name == NULL || strlen(name) > MAX_ARG_LEN ) {
        /* Invalid process name. */
        return NULL;
    }

    /* Search for the PCB. If we find it, return it. */
    if ( found_pcb = find_pcb_in_queue( name, &queue_ready ) ) {
        return found_pcb;
    }
    if ( found_pcb = find_pcb_in_queue( name, &queue_blocked ) ) {
        return found_pcb;
    }
    if ( found_pcb = find_pcb_in_queue( name, &queue_susp_ready ) ) {
        return found_pcb;
    }
    if ( found_pcb = find_pcb_in_queue( name, &queue_susp_blocked ) ) {
        return found_pcb;
    }

    /* If we get here, the process was not found. */
    return NULL;
}

```

5.6 mpx/pcb.h File Reference

PCBs, process queues, and functions to operate on them.

```
#include "mpx_util.h"
```

Data Structures

- struct `pcb_t`
Process control block structure.
- struct `pcb_queue_node`
- struct `pcb_queue_t`
PCB queue; represents a queue of processes.

Defines

- #define `STACK_SIZE` 1024
Amount of stack space to allocate for each process (in bytes).

Typedefs

- typedef struct [pcb_queue_node](#) **pcb_queue_node_t**

Enumerations

- enum [process_state_t](#) {
 RUNNING, READY, BLOCKED, SUSP_READY,
 SUSP_BLOCKED }
 Type for variables that hold the state of a process.
- enum [process_class_t](#) { **APPLICATION, SYSTEM** }
 Type for variables that hold the class of a process.

Functions

- void [init_pcb_queues](#) (void)
 Must be called before using any other PCB or queue functions.
- [pcb_t](#) * [setup_pcb](#) (char *name, int priority, [process_class_t](#) class)
 Creates a new PCB object and initializes its fields.
- [pcb_t](#) * [find_pcb](#) (char *name)
 Finds a process.

5.6.1 Detailed Description

PCBs, process queues, and functions to operate on them.

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Date

2011

5.6.2 Define Documentation

5.6.2.1 `#define STACK_SIZE 1024`

Amount of stack space to allocate for each process (in bytes).

5.6.3 Enumeration Type Documentation

5.6.3.1 `enum process_state_t`

Type for variables that hold the state of a process.

```
{  
  
    RUNNING,  
    READY,  
    BLOCKED,  
    SUSP_READY,  
    SUSP_BLOCKED  
}  
} process_state_t;
```

5.6.3.2 `enum process_class_t`

Type for variables that hold the class of a process.

```
{  
  
    APPLICATION,  
    SYSTEM  
}  
} process_class_t;
```

5.6.4 Function Documentation

5.6.4.1 `void init_pcb_queues (void)`

Must be called before using any other PCB or queue functions.

```
{  
    queue_ready.head           = NULL;  
    queue_ready.tail           = NULL;  
    queue_ready.length         = 0;  
  
    queue_blocked.head         = NULL;  
    queue_blocked.tail         = NULL;  
}
```

```

    queue_blocked.length      = 0;

    queue_susp_ready.head     = NULL;
    queue_susp_ready.tail     = NULL;
    queue_susp_ready.length   = 0;

    queue_susp_blocked.head    = NULL;
    queue_susp_blocked.tail    = NULL;
    queue_susp_blocked.length  = 0;
}

```

5.6.4.2 `pcb_t* setup_pcb (char * name, int priority, process_class_t class)`

Creates a new PCB object and initializes its fields.

Returns

Returns a pointer to the new PCB, or NULL if an error occurred.

Parameters

<i>name</i>	Name of the new process. Must be unique among all processes.
<i>priority</i>	Priority of the process. Must be between -127 and 128 (incl.)
<i>class</i>	Class of the process; one of APPLICATION or SYSTEM.

```

{
    /* Loop index. */
    int i;

    /* Pointer to the new PCB we're creating. */
    pcb_t *new_pcb;

    /* Check that arguments are valid. */
    if ( find_pcb(name) != NULL ) {
        /* Name is not unique. */
        return NULL;
    }
    if ( strlen(name) > MAX_ARG_LEN || name == NULL ) {
        /* Invalid name. */
        return NULL;
    }
    if ( priority < -127 || priority > 128 ) {
        /* Value of priority is out of range. */
        return NULL;
    }
    if ( class != APPLICATION && class != SYSTEM ) {
        /* Invalid class specified. */
        return NULL;
    }

    /* Allocate the new PCB. */

```

```

new_pcb = allocate_pcb();
if (new_pcb == NULL) {
    /* Allocation error. */
    return NULL;
}

/* Set the given values. */
new_pcb->priority    = priority;
new_pcb->class       = class;
strcpy( new_pcb->name, name );

/* Set other default values. */
new_pcb->state       = READY;
new_pcb->memory_size = 0;
new_pcb->load_address = NULL;
new_pcb->exec_address = NULL;

/* Initialize the stack to 0's. */
for (i=0; i<STACK_SIZE; i++) {
    *(new_pcb->stack_base + i) = (unsigned char)0;
}

return new_pcb;
}

```

5.6.4.3 pcb_t* find_pcb (char * name)

Finds a process.

Searches all process queues.

Returns

Returns a pointer to the PCB, or NULL if not found or error.

Parameters

<i>name</i>	The name of the process to find.
-------------	----------------------------------

```

{
    /* Pointer to the requested PCB, if we find it. */
    pcb_t *found_pcb;

    /* Validate arguments. */
    if ( name == NULL || strlen(name) > MAX_ARG_LEN ) {
        /* Invalid process name. */
        return NULL;
    }

    /* Search for the PCB. If we find it, return it. */
    if ( found_pcb = find_pcb_in_queue( name, &queue_ready ) ) {

```

```
        return found_pcb;
    }
    if ( found_pcb = find_pcb_in_queue( name, &queue_blocked ) ) {
        return found_pcb;
    }
    if ( found_pcb = find_pcb_in_queue( name, &queue_susp_ready ) ) {
        return found_pcb;
    }
    if ( found_pcb = find_pcb_in_queue( name, &queue_susp_blocked ) ) {
        return found_pcb;
    }

    /* If we get here, the process was not found. */
    return NULL;
}
```

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