Logic Programming languages

Logic Programming Languages

Preliminaries

Syntax

 Syntax: extended Backus-Naur form (EBNF) for notation of production rules

Name:
$$G, H := A \mid B$$
, Condition

- capital letters: syntactical entities
- symbols G and H defined: with name Name.
- ► Condition holds: G and H can be of the form A or B

Semantics

Operational (Procedural) Semantics

State transition system (refined calculus)

Declarative Semantics

Logical reading of program as theory, i.e. set of formulae of first-order logic

Operational vs. Declarative Semantics

- Soundness
- Completeness

Simple State Transition System

- \bullet (S, \mapsto)
 - S set of states
 - ▶ → binary relation over states: *transition relation*
 - ▶ (state) transition from S_1 to S_2 possible if (some given) condition holds, i.e. S_1 and S_2 are in relation \mapsto , written $S_1 \mapsto S_2$
- distinguished subsets of S: initial and final states
- $S_1 \mapsto S_2 \mapsto \ldots \mapsto S_n$ derivation (computation)
- $\bullet \mapsto^*$ reflexive-transitive closure of \mapsto

Reduction is synonym for transition

Transition Rules

ullet The relation \mapsto is defined by using transition rules of the form

$$\begin{array}{ll} \mathsf{IF} & \textit{Condition} \\ \mathsf{THEN} & \textit{S} \mapsto \textit{S}'. \end{array}$$

- (state) transition (reduction, derivation step, computation) from S to S' possible if the condition Condition holds
- straightforward to concretize a calculus ("⊢") into a state transition system ("⊢")

Operational (Procedural) Semantics

Refined Calculus

Triple (Σ, \equiv, T)

- \bullet Σ : signature for a first-order logic language
- ≡: congruence (equivalence relation) on states
- $T = (S, \mapsto)$: simple state transition system states S represent logical expressions over the signature Σ

Congruence

- states which are considered equivalent for purpose of computation
- congruence instead of modeling with additional transition rules
- formally congruence is equivalence relation compatible with the structure:

$$\begin{array}{ll} \text{(Reflexivity)} & A \equiv A \\ \text{(Symmetry)} & \text{If } A \equiv B \text{ then } B \equiv A \\ \text{(Transitivity)} & \text{If } A \equiv B \text{ and } B \equiv C \text{ then } A \equiv C \end{array}$$

Example:

$$(X=3)\equiv (3=X)$$

Congruence

$$\begin{array}{ccccc} \textit{Commutativity:} & \textit{G}_1 \land \textit{G}_2 & \equiv & \textit{G}_2 \land \textit{G}_1 \\ \textit{Associativity:} & \textit{G}_1 \land (\textit{G}_2 \land \textit{G}_3) & \equiv & (\textit{G}_1 \land \textit{G}_2) \land \textit{G}_3 \\ \textit{Identity:} & \textit{G} \land \top & \equiv & \textit{G} \\ \textit{Absorption:} & \textit{G} \land \bot & \equiv & \bot \\ \end{array}$$

derived from tautologies

Transition Rules for Resolution Calculus (1)

- state: set of clauses
- initial state: clauses representing the theory and the negated consequence
- final state: contains the empty clause

Transition Rules for Resolution Calculus. Propositional Logic

Resolvent

IF
$$R \lor A \in S$$
 and $R' \lor \neg A \in S$ for some atom A
THEN $S \mapsto S \cup \{F\}$ where $F = R \lor R'$ is called Resolvent.

Factor

```
IF R \lor L \lor L \in S for some literla L
THEN S \mapsto S \cup \{F\} where F = R \lor L is called Factor
```

Transition Rules for Resolution Calculus. FOI

Resolvent

IF $R \lor A \in S$ and $R' \lor \neg A \in S$ and σ is a most general unifier for the atoms A and A', THEN $S \mapsto S \cup \{F\}$ where $F = (R \lor R')\sigma$ is called Resolvent.

Factor

IF $R \lor L \lor L' \in S$ and σ is a most general unifier for the literals L and L', THEN $S \mapsto S \cup \{F\}$ where $F = (R \lor L)\sigma$ is called Factor

Logic Programming

A logic program is a set of axioms, or rules, defining relationships between objects. A computation of a logic program is a deduction of consequences of the program. A program defines a set of consequences, which is its meaning. The art of logic programming is constructing concise and elegant programs that have desired meaning.

Sterling and Shapiro: The Art of Prolog, Page 1.

LP Syntax

- goal:
 - empty goal \top (top) or \bot (bottom), or
 - ► atom, or
 - conjunction of goals
- (Horn) clause: $A \leftarrow G$
 - ▶ head A: atom
 - ▶ body G: goal
- Naming conventions
 - fact: clause of form $A \leftarrow \top$
 - rule: all others
- (logic) program: finite set of Horn clauses
- predicate symbol defined: it occurs in head of a clause

LP Calculus – Syntax

```
Atom: A, B ::= p(t_1, ..., t_n), n \ge 0

Goal: G, H ::= T \mid \bot \mid A \mid G \land H

Clause: K ::= A \leftarrow G

Program: P ::= K_1 ... K_m, m \ge 0
```

LP Calculus – State Transition System

- state $\langle G, \theta \rangle$
 - ► G: goal
 - \triangleright θ : substitution
- initial state $\langle G, \epsilon \rangle$
- successful final state $\langle \top, \theta \rangle$
- failed final state $\langle \bot, \epsilon \rangle$

Derivations, Goals

Derivation is

- successful: its final state is successful
- failed: its final state is failed
- *infinite*: if there are an infinite sequence of states and transitions $S_1 \mapsto S_2 \mapsto S_3 \mapsto \dots$

Goal G is

- successful: it has a successful derivation starting with $\langle G, \epsilon \rangle$
- ullet finitely failed: has only failed derivations starting with $\langle {\cal G}, \epsilon \;
 angle$

Logical Reading, Answer

- If $\langle G, \epsilon \rangle \mapsto^* \langle H, \theta \rangle$ then the *logical reading* of $\langle H, \theta \rangle$ is
 - $\rightarrow \exists \bar{X}(H\theta)$
 - where \bar{X} are the variables which occur in $H\theta$ but not in G
- Computed answer substitution (cas) of a goal G is defined as: a substitution θ such that there exists with successful derivation $\langle G, \epsilon \rangle \mapsto^* \langle \top, \theta \rangle$

G is also called *initial goal* or *query*

Operational Semantics

Unfold

If $(B \leftarrow H)$ is a fresh variant of a clause in P and β is the most general unifier of B and $A\theta$

then $\langle A \wedge G, \theta \rangle \mapsto \langle H \wedge G, \theta \beta \rangle$

Failure

If there is no clause $(B \leftarrow H)$ in P

with a unifier of B and $A\theta$ then $\langle A \wedge G, \theta \rangle \mapsto \langle \bot, \epsilon \rangle$

Non-determinism

The **Unfold** transition exhibits two kinds of non-determinism.

- don't-care non-determinism:
 - ▶ any atom in $A \land G$ can be chosen as the atom A according to the congruence defined on states
 - ▶ affects length of derivation (infinitely in the worst case)
- don't-know non-determinism:
 - ▶ any clause $(B \leftarrow H)$ in P for which B and $A\theta$ are unifiable can be chosen
 - determines the computed answer of derivation

Unfold with Case Splitting

UnfoldSplit

```
If (B_1 \leftarrow H_1), \dots, (B_n \leftarrow H_n) are fresh variants of all those clauses in P for which B_i \ (1 \le i \le n) is unifiable with A\theta and \beta_i is the most general unifier of B_i and A\theta \ (1 \le i \le n) then \langle A \land G, \theta \mapsto \rangle \ \langle H_1 \land G, \theta \beta_1 \ \rangle \ \dots \ \langle H_n \land G, \theta \beta_n \ \rangle
```

SLD Resolution

- selection strategy: textual order of clauses and atoms in a program
- (chronological) backtracking (backtrack search)
- left-to-right, depth-first exploration of the search tree
- efficient implementation using a stack-based approach
- can get trapped in infinite derivations (but breadth-first search far too inefficient)

Example - Accessibility in DAG

```
edge(a,b) \leftarrow \top (e1)
edge(a,c) \leftarrow \top (e2)
edge(b,d) \leftarrow \top (e3)
edge(c,d) \leftarrow \top (e4)
edge(d,e) \leftarrow \top (e5)
path(Start,End) \leftarrow edge(Start,End) (p1)
path(Start,End) \leftarrow edge(Start,Node) \land path(Node,End) (p2)
```

Note: e1 en and p1, p2 are names of rules in the metalanguage, they are part of the LP syntax.

 $\mapsto \text{(e3) } \langle \top, \{S \mapsto b, E \mapsto d, Y \mapsto d\} \rangle$

With the second rule *p2* for path selected:

$$\begin{array}{c} \langle \mathtt{path}(\mathtt{b},\mathtt{Y}),\varepsilon \; \rangle \\ \mapsto \; (_{\rho 2}) \; \langle \mathtt{edge}(\mathtt{S},\mathtt{N}) \wedge \mathtt{path}(\mathtt{N},\mathtt{E}), \{\mathtt{S} \mapsto \mathtt{b},\mathtt{E} \mapsto \mathtt{Y}\} \; \rangle \\ \mapsto \; (_{e3}) \; \langle \mathtt{path}(\mathtt{N},\mathtt{E}), \{\mathtt{S} \mapsto \mathtt{b},\mathtt{E} \mapsto \mathtt{Y},\mathtt{N} \mapsto \mathtt{d}\} \; \rangle \\ \mapsto \; (_{\rho 1}) \; \langle \mathtt{edge}(\mathtt{N},\mathtt{E}), \{\mathtt{S} \mapsto \mathtt{b},\mathtt{E} \mapsto \mathtt{Y},\mathtt{N} \mapsto \mathtt{d}\} \; \rangle \\ \mapsto \; (_{e5}) \; \langle \top, \{\mathtt{S} \mapsto \mathtt{b},\mathtt{E} \mapsto \mathtt{e},\mathtt{N} \mapsto \mathtt{d},\mathtt{Y} \mapsto \mathtt{e}\} \; \rangle \end{array}$$

Example - Accessibility in DAG (cont 2)

$$\begin{array}{cccc}
a & \longrightarrow & b \\
\downarrow & & \downarrow \\
c & \longrightarrow & d & \longrightarrow
\end{array}$$

Partial search tree:

As exercise

Example - Accessibility in DAG (cont 2)
$$\begin{array}{cccc}
a & \longrightarrow & b \\
\downarrow & & \downarrow \\
c & \longrightarrow & d & \longrightarrow & e
\end{array}$$

With the first rule:

$$\begin{array}{c} & \langle \texttt{path}(\texttt{f},\texttt{g}),\varepsilon \; \rangle \\ \mapsto \; (_{p1}) & \langle \texttt{edge}(\texttt{S},\texttt{E}), \{\texttt{S} \mapsto \texttt{f},\texttt{E} \mapsto \texttt{g}\} \; \rangle \\ \mapsto & \langle \bot,\varepsilon \; \rangle \end{array}$$

With the second rule (and special selection) we get an infinite derivation:

$$\begin{array}{c} \langle \mathtt{path}(\mathtt{f},\mathtt{g}),\varepsilon \ \rangle \\ \mapsto {}_{(\rho 2)} \ \langle \mathtt{path}(\mathtt{N},\mathtt{E}) \land \mathtt{edge}(\mathtt{S},\mathtt{N}), \{\mathtt{S} \mapsto \mathtt{f},\mathtt{E} \mapsto \mathtt{g}\} \ \rangle \\ \mapsto {}_{(\rho 2)} \ \langle \mathtt{edge}(\mathtt{S},\mathtt{N}) \land \mathtt{edge}(\mathtt{N},\mathtt{N1}) \land \mathtt{path}(\mathtt{N1},\mathtt{E}), \{\mathtt{S} \mapsto \mathtt{f},\mathtt{E} \mapsto \mathtt{g}\} \ \rangle \end{array}$$

Declarative Semantics

- *implication* ($G \rightarrow A$): Horn clause, definite clause
- logical reading of a program P: universal closure of the conjunction of the clauses of P, written P^{\rightarrow}
- only positive information can be derived
- "complete" P^{\rightarrow} :
 - keep necessary conditions (implications)
 - add corresponding sufficient conditions (implications in the other direction)

Example:

In DAG with nodes a, b, c, d, e: $P^{\rightarrow} \not\models$ path $(f,g)=P^{\rightarrow} \not\models \neg path(f,g)$ In completed logical reading,

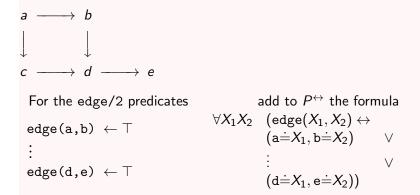
Completion of $P: P^{\leftrightarrow}$

For each
$$p/n$$
 in P add to P^{\leftrightarrow} the formula $p(\overline{t}_1) \leftarrow G_1 \quad \forall \overline{X} \ (p(\overline{X}) \leftrightarrow \exists \overline{Y}_1 \ (\overline{t}_1 \doteq \overline{X} \wedge G_1) \quad \lor \\ \vdots \qquad \vdots \qquad \vdots \qquad \qquad \vdots \qquad \qquad \forall \overline{Y}_m \ (\overline{t}_m \doteq \overline{X} \wedge G_m)),$

- \bar{X} : pairwise distinct fresh variables
- \bar{t}_i : terms
- \bar{Y}_i : variables occurring in G_i and t_i

Add $\forall \bar{X} \neg p(\bar{X})$ to P^{\leftrightarrow} for all undefined predicate symbols p in P.

Example - Logical Reading



Example - Logical Reading (2)

For the path/2 predicates

add to P^{\leftrightarrow} the formula

$$\begin{array}{lll} \forall X_1X_2(\operatorname{path}(X_1,X_2) \leftrightarrow \\ \exists Y_{11}Y_{12} \ (Y_{11} \stackrel{...}{=} X_1, Y_{12} \stackrel{...}{=} X_2 \\ \land \operatorname{edge}(\operatorname{Start},\operatorname{End}) & \exists Y_{21}Y_{22}Y_{23} \ (Y_{21} \stackrel{...}{=} X_1, Y_{22} \stackrel{...}{=} X_2 \\ \land \operatorname{edge}(Y_{21}, Y_{22}) & \land \operatorname{edge}(Y_{21}, Y_{23}) \\ \land \operatorname{path}(\operatorname{Start},\operatorname{Node}) & \land \\ \operatorname{path}(\operatorname{Node},\operatorname{End}) & & \leftrightarrow \\ \operatorname{edge}(X_1, X_2) \vee \\ & (\exists Y \ \operatorname{edge}(X_1, Y) \vee \operatorname{path}(Y, X_2))) \end{array}$$

Clark's Equality Theory (CET)

 $(\top \rightarrow X \stackrel{.}{=} X)$ $(X \stackrel{.}{=} Y \rightarrow Y \stackrel{.}{=} X)$

Universal closure of the formulae

Reflexivity

Symmetry

Transitivity
$$(X \stackrel{.}{=} Y \land Y \stackrel{.}{=} Z \to X \stackrel{.}{=} Z)$$

Compatibility $(X_1 \stackrel{.}{=} Y_1 \land \ldots \land X_n \stackrel{.}{=} Y_n \to f(X_1, \ldots, X_n) \stackrel{.}{=} f(Y_1)$
Decomposition $(f(X_1, \ldots, X_n) \stackrel{.}{=} f(Y_1, \ldots, Y_n) \to X_1 \stackrel{.}{=} Y_1 \land \ldots \land Y_n) \stackrel{.}{=} g(Y_1, \ldots, Y_n) \to X_1 \stackrel{.}{=} f(Y_n) \hookrightarrow X_n \hookrightarrow$

(Σ signature with infinitely many functions, including at least one constant)

Unifiable in CET

Terms s and t are unifiable if and only if

$$CET \models \exists (t \doteq s).$$

Acyclicity

Examples:

 $X \doteq X$ is unifiable but *not*:

- X = f(X)
- $X \doteq p(A, f(X, a))$
- $X \doteq Y \wedge X \doteq f(Y)$

Soundness and Completeness

Soundness:

If θ is a computed answer of G, then $P^{\leftrightarrow} \cup CET \models \forall G\theta$.

Completeness:

If $P^{\leftrightarrow} \cup CET \models \forall G\theta$, then a computed answer σ of G exists, such that $\theta = \sigma\beta$.

(P logic program, G goal, θ substitution)

Failed Derivations

Fair Derivation:

Either fails or each atom appearing in the derivation is selected after finitely many reductions.

Soundness and Completeness:

Any fair derivation starting with $\langle {\it G}, \epsilon \; \rangle \;\;$ fails finitely if and only if

$$P^{\leftrightarrow} \cup CET \models \neg \exists G.$$

Remarks:

- not valid without CET
- SLD resolution not fair

(P logic program, G goal)