

Languages and Algorithms for Artificial Intelligence (Third Module)

Between the Feasible and the Unfeasible

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The Border Between the Tractable and the Intractable

- ▶ Up to now, we have encountered (essentially speaking) two complexity classes, namely:
 - ▶ **P**, which contains those problems which can be solved in polynomial time, so the **tractable** ones.
 - ▶ **EXP**, which contains the whole of **P**, but also some problems which *cannot* be solved in polynomial time, intrinsically requiring exponential time (and as such, **intractable**).

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- ▶ It's now time to study the “border” between tractability and intractability:
 - ▶ Between **P** and **EXP**, one can define *many other* classes. i.e. there are many ways of defining a class **A** such that

$$\mathbf{P} \subseteq \mathbf{A} \subseteq \mathbf{EXP}$$

- ▶ This is a formidable tool to classify those problems in **EXP** for which *we do not know* whether they are in **P** (and there are *so many* of them).

Creating vs. Verifying

- Very often, the language we would like to classify can be written as follows:

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where $p : \mathbb{N} \rightarrow \mathbb{N}$ and \mathcal{A} is a set of pairs of strings.

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- In other words, the elements of \mathcal{L} are those strings for which we can find a *certificate* y (of polynomial length) such that the pair (x, y) passes the *test* $\mathcal{A} \subseteq \{0, 1\}^* \times \{0, 1\}^*$.

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 - ▶ *Not necessarily*: given x , we can check whether $x \in \mathcal{L}$ by $(x, y) \in \mathcal{A}$ for all possible y such that $|y| \leq p(|x|)$, of which however there are *exponentially* many.
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 - ▶ Of course this does *not* rule out other strategies to decide \mathcal{L} .
- ▶ The *take-away message* is thus the following: **crafting** a solution for the problem x (i.e., finding y) can potentially be more difficult than just **checking** y to be a solution to x .

The Complexity Class **NP**

- ▶ A language $\mathcal{L} \subseteq \{0, 1\}^*$ is in the class **NP** iff there exist a polynomial $p : \mathbb{N} \rightarrow \mathbb{N}$ and a polynomial time TM \mathcal{M} such that

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 - ▶ M is said to be the **verifier** for \mathcal{L} .
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- ▶ Differently from **P** and **EXP**, the class **NP** does not have a natural counterpart as a class of *functions*.

Theorem

$$\mathbf{P} \subseteq \mathbf{NP} \subseteq \mathbf{EXP}$$

Examples Problems in NP

1. Maximum Independent Set

- In its decision form, it asks whether a pair (\mathbb{G}, k) of an undirected graph and a natural number $k \in \mathbb{N}$ is such that $\mathbb{G} = (V, E)$ admits an independent set $W \subseteq V$ of cardinality at least k .

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- ▶ **Certificate:** again, the certificate here is just I : checking whether $\sum_{i \in I} n_i = k$ just amounts to some additions and comparisons.

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4. Factoring

- ▶ Given three numbers n, m, l , it asks whether n has a prime factor in the interval $[m, l]$.
- ▶ Certificate: it can be taken to be the prime number p : checking that $p \in [m, l]$ and that p divides n is easy.

Instead, checking that p is prime requires a lot of work, but can indeed be done in polynomial time.

Examples Problems in NP

3. Decisional Linear Programming

- ▶ Given a sequence of m linear inequalities with rational coefficients over n variables (i.e. inequalities of the form $\sum_{i=1}^n a_i x_i \leq b$, where the coefficients a_1, \dots, a_n, b are in \mathbb{Q}), decide whether there is a rational assignment to the variables x_1, \dots, x_n which makes all the inequalities true.

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- ▶ Certificate: again, the assignments suffices.

Examples Problems in \mathbf{NP}

- ▶ Some of the aforementioned problems are also in \mathbf{P} :
 - ▶ *Decisional linear programming* can be proved to be in \mathbf{P} thanks to, e.g., the Ellipsoid algorithm.
 - ▶ The *composite numbers* problem can be proved itself to be in \mathbf{P} , thanks to a breakthrough recent result, namely the so-called AKS algorithm.

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 - ▶ The *composite numbers* problem can be proved itself to be in **P**, thanks to a breakthrough recent result, namely the so-called AKS algorithm.
- ▶ All the other problems are currently **not known** to be in **P**.
 - ▶ Are they all equivalent in terms of their inherent computational difficulty?
 - ▶ Is there any way isolate those problems in **NP** whose difficulty is maximal, i.e. they are at least as hard as all other problems in **NP**?

Nondeterministic Turing Machines

- ▶ The class **NP** can also be defined using a variant of Turing machines, called the *nondeterministic* Turing machines (NDTM for short).
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- ▶ The only differences between a NDTM and an ordinary TM is that the former has:
 - ▶ Two transition functions δ_0 and δ_1 rather than just one. *At every step*, the machine chooses nondeterministically one between the two transition functions and proceed according to it
 - ▶ A special state q_{accept} .

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 - ▶ A special state q_{accept} .
- ▶ We say that a NDTM M :
 - ▶ **Accepts** the input $x \in \{0, 1\}^*$ iff *there exists* one among the many possible evolutions of the machine M when fed with x which makes it reaching q_{accept} .
 - ▶ **Rejects** the input $x \in \{0, 1\}^*$ iff *none* of the aforementioned evolutions leads to q_{accept} .

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Time-Bounded NDTMs

- ▶ We say that a NDTM M *runs in time* $T : \mathbb{N} \rightarrow \mathbb{N}$ iff for every $x \in \{0, 1\}^*$ and for every possible nondeterministic evolution, M reaches either the halting state or q_{accept} within $c \cdot T(|x|)$ steps, where $c > 0$.

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- ▶ For every function $T : \mathbb{N} \rightarrow \mathbb{N}$ and $\mathcal{L} \subseteq \{0, 1\}^*$, we say that $\mathcal{L} \in \mathbf{NDTIME}(T(n))$ iff there is a NDTM M working in time T and such that $M(x) = 1$ iff $x \in \mathcal{L}$.

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- ▶ All this being said, NDTMs, contrarily to TMs, are *not* meant to model any form of physically realisable machine.

Thank You!

Questions?