

# Pol Rosello

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## PERSONAL PROFILE

Software engineer interested in the research and development of autonomous real-time systems, particularly in environments with limited computational resources.

## EDUCATION

**Stanford University**, School of Engineering, Stanford, CA (4.11 GPA)

Master of Science in Computer Science

*June 2017*

**Cornell University**, College of Engineering, Ithaca, NY (3.90 GPA)

Bachelor of Science in Electrical and Computer Engineering

*May 2015*

Bachelor of Science in Computer Science

*May 2015*

## WORK EXPERIENCE

**Software Engineer II**

*Sept 2017 – present*

*SpaceX, Hawthorne, CA*

*Summer 2015, Summer 2016 (intern)*

Lead developer on laser-based inter-satellite communication system R&D project.

Lead fairing recovery developer for 2 years leading up to successful catch. Implemented GNC algorithms on a constrained system while adapting firmware for two major avionics architecture redesigns. Supported rapid software development and test to enable progress every flight.

Implemented fault-tolerance improvements to IMU inertial propagation algorithm, reducing likelihood of autonomous flight termination.

Developed an FPGA-based, highly-accurate six-axis accelerometer and gyroscope sensor and fault simulator for in-house IMU. Used in closed-loop, real-time mission simulations.

**Graduate Researcher**

*Jan 2017 – June 2017*

*Stanford Intelligent Systems Laboratory, Stanford University*

Developed a novel multi-agent reinforcement learning formulation of multi-object tracking, leading to a 2018 AAMAS conference publication. Research in autonomous driving funded by SAIC.

**Undergraduate Researcher**

*Jan 2014 – Dec 2014*

*Batten Group, Cornell University*

Writing and optimizing benchmark applications for a novel high-performance, energy-efficient parallel computing microarchitecture by mapping them to a research ISA. Contributions acknowledged in two 2014 IEEE MICRO papers.

**Software Engineering Intern**

*Jun 2014 – Aug 2014*

*Cisco Systems, San Jose, CA*

Developed suites in C# to automate the zero-touch deployment, tunnel provisioning, and firmware upgrades of field routers; automated testing of the front-end functionality of the product.

**Teaching Assistant**

*Aug 2013 – Dec 2014*

*Cornell University*

Held office hours and review sessions, graded student projects and exams for ECE 4750/CS 4420:

Computer Architecture (Fall 2014), ECE 3140/CS 3420: Embedded Systems (Spring 2014) and

CS 2110: Object-Oriented Programming and Data Structures (Fall 2013).

**Research Assistant**

*Oct 2012 – May 2013*

*Molnar Group, Cornell University*

Programmed an FPGA and designed a printed circuit board as a testing platform for a very low power, very low noise multi-electrode array (MEA) for electrophysiological neural recordings.

## RELEVANT SKILLS

**Coursework:** Embedded Systems • Computer Architecture • Machine Learning • AI •

Design with Microcontrollers • Computer Vision • Signal Processing • Neural Networks •

Reinforcement Learning • Natural Language Processing • Discrete Mathematics

**Technologies:** C/C++ • Python/SciPy • ARM • Verilog • OpenCV • OCaml

## PUBLICATIONS AND AWARDS

Rosello, P., & Kochenderfer, M. “Multi-Agent Reinforcement Learning for Multi-Object Tracking.”

In *International Conference on Autonomous Agents and Multiagent Systems (AAMAS)*, 2018.

Cornell College of Engineering Jacobs Scholar