

7.1 Glossary of Notation

- **Y**: A $n \times p$ matrix containing all multivariate skew-normal regression outcomes such that y_{ij} is the j^{th} outcome observed for subject i , where $i = 1, \dots, n$ and $j = 1, \dots, p$.
- **X**: A $n \times m$ matrix containing all multivariate skew-normal regression covariates such that x_{ij} is the j^{th} covariate value for subject i .
- **B**: A $m \times p$ matrix containing all multivariate skew-normal regression coefficients such that $\mathbf{B} = [\beta_1, \dots, \beta_p]$, where β_{ij} is interpreted as the effect of covariate i on outcome j for $i = 1, \dots, m$ and $j = 1, \dots, p$.
- **E**: A $n \times p$ matrix of error terms in the multivariate skew-normal regression model component. **E** is made up of row vectors $\epsilon_i = (\epsilon_{i1}, \dots, \epsilon_{ip})$, where $\epsilon_i \stackrel{iid}{\sim} N_p(0, \Sigma)$ for $i = 1, \dots, n$.
- **Σ**: A $p \times p$ covariance matrix that defines the correlation between the p multivariate normal outcomes.
- **Ω**: A $p \times p$ covariance scale matrix that defines the correlation between the p multivariate skew-normal outcomes.
- **ψ**: A $p \times 1$ vector containing the skewness parameter for each outcome.
- **α**: A $p \times 1$ vector containing the skewness parameter for each outcome.
- **t**: A $n \times 1$ vector of truncated normal random effects used in the stochastic representation of the multivariate skew-normal distribution. For $i = 1, \dots, n$, $t_i \stackrel{iid}{\sim} T_{[0, \infty)(0, 1)}$
- **X***: A $n \times (m + 1)$ matrix constructed by column binding **t** to **X**
- **B***: A $(m + 1) \times p$ matrix constructed by row binding ψ^T to **B**.

7.2 Derivation of Full Conditional Distributions

7.2.1 Multivariate Skew-Normal Regression. Without loss of generality, we derive the full conditional distributions for the multivariate skew-normal regression model component under the assumption that all observations belong to a single cluster. To make the extension to the case where more than one cluster is specified, simply apply these distributional forms to cluster specific parameters and data.

The multivariate skew-normal regression model can be written as follows.

$$\mathbf{Y} = \mathbf{X}\mathbf{B} + \mathbf{t}\boldsymbol{\psi}^T + \mathbf{E} = \mathbf{X}^*\mathbf{B}^* + \mathbf{E}$$

For convenience, we define \mathbf{X}^* as a $n \times (m+1)$ matrix constructed by column binding \mathbf{t} to \mathbf{X} , and \mathbf{B}^* as a $(m+1) \times p$ matrix constructed by row binding $\boldsymbol{\psi}^T$ to \mathbf{B} . We assume that $t_i \stackrel{iid}{\sim} T_{[0,\infty)}(0,1)$ and that \mathbf{E} is made of row vectors $\boldsymbol{\epsilon}_i = (\epsilon_{i1}, \dots, \epsilon_{ip})$ for $i = 1, \dots, n$, where $\boldsymbol{\epsilon}_i \stackrel{iid}{\sim} N_p(0, \boldsymbol{\Sigma})$.

The conditional likelihood for this model is given below.

$$p(\mathbf{Y}|\mathbf{X}^*, \mathbf{B}^*, \boldsymbol{\Sigma}) \propto |\boldsymbol{\Sigma}|^{-n/2} \exp \left\{ -\frac{1}{2} \text{tr}(\mathbf{Y} - \mathbf{X}^*\mathbf{B}^*)^T (\mathbf{Y} - \mathbf{X}^*\mathbf{B}^*) \boldsymbol{\Sigma}^{-1} \right\}$$

We choose conjugate priors for \mathbf{B}^* and $\boldsymbol{\Sigma}$ as follows.

$$\boldsymbol{\Sigma} \sim \text{inverse-Wishart}(\mathbf{V}_0, \nu_0)$$

$$\mathbf{B}^*|\boldsymbol{\Sigma} \sim MN_{(m+1) \times p}(\mathbf{B}_0^*, \mathbf{L}_0^{-1}, \boldsymbol{\Sigma})$$

We now derive the joint posterior distribution of the parameters \mathbf{B}^* and $\boldsymbol{\Sigma}$.

$$\begin{aligned} p(\mathbf{B}^*, \boldsymbol{\Sigma}|\mathbf{X}^*, \mathbf{Y}) &\propto p(\mathbf{Y}|\mathbf{X}^*, \mathbf{B}^*, \boldsymbol{\Sigma})p(\mathbf{B}^*|\boldsymbol{\Sigma})p(\boldsymbol{\Sigma}) \\ &\propto |\boldsymbol{\Sigma}|^{-n/2} \exp \left\{ -\frac{1}{2} \text{tr}((\mathbf{Y} - \mathbf{X}^*\mathbf{B}^*)^T (\mathbf{Y} - \mathbf{X}^*\mathbf{B}^*) \boldsymbol{\Sigma}^{-1}) \right\} \\ &\times |\boldsymbol{\Sigma}|^{-m/2} \exp \left\{ -\frac{1}{2} \text{tr}((\mathbf{B}^* - \mathbf{B}_0^*)^T \mathbf{L}_0 (\mathbf{B}^* - \mathbf{B}_0^*) \boldsymbol{\Sigma}^{-1}) \right\} \\ &\times |\boldsymbol{\Sigma}|^{(\nu_0+p+1)/2} \exp \left\{ -\frac{1}{2} \text{tr}(\mathbf{V}_0 \boldsymbol{\Sigma}^{-1}) \right\} \end{aligned}$$

7.2.2 Multinomial Logit Regression.

7.2.3 Multivariate Normal Conditional Imputation. The multivariate normal conditional imputation derivations are given for a single cluster without loss of generality. In practice, the data and parameters in this section would be replaced by cluster specific estimates in the case of clustering.

For a given observation vector $\mathbf{y} \sim N_p(\boldsymbol{\mu}, \boldsymbol{\Sigma})$, we allow for missingness in at most $p - 1$ of the multivariate outcomes through the use of a conditional imputation step embedded within our Gibbs sampler. Suppose \mathbf{y} contains q missing observations and can be partitioned into two vectors \mathbf{y}_1 and \mathbf{y}_2 such that \mathbf{y}_1 is a $q \times 1$ vector of missing observations and \mathbf{y}_2 is a $(p - q) \times 1$ vector of complete observations. Similarly, partition $\boldsymbol{\mu}$ and $\boldsymbol{\Sigma}$ as follows.

$$\boldsymbol{\mu} = \begin{bmatrix} \boldsymbol{\mu}_1 \\ \boldsymbol{\mu}_2 \end{bmatrix} \quad \boldsymbol{\Sigma} = \begin{bmatrix} \boldsymbol{\Sigma}_{11} & \boldsymbol{\Sigma}_{12} \\ \boldsymbol{\Sigma}_{21} & \boldsymbol{\Sigma}_{22} \end{bmatrix}$$

We will use these quantities to derive the conditional distribution $f(\mathbf{y}_1|\mathbf{y}_2, \boldsymbol{\mu}, \boldsymbol{\Sigma})$.

$$\begin{aligned} f(\mathbf{y}_1|\mathbf{y}_2, \boldsymbol{\mu}, \boldsymbol{\Sigma}) &\propto f(\mathbf{y}_1, \mathbf{y}_2|\boldsymbol{\mu}, \boldsymbol{\Sigma}) \\ &\propto \exp \left\{ -\frac{1}{2}(\mathbf{y} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{y} - \boldsymbol{\mu}) \right\} \\ &= \exp \left\{ -\frac{1}{2} \begin{bmatrix} \mathbf{y}_1 - \boldsymbol{\mu}_1 \\ \mathbf{y}_2 - \boldsymbol{\mu}_2 \end{bmatrix}^T \boldsymbol{\Sigma}^{-1} \begin{bmatrix} \mathbf{y}_1 - \boldsymbol{\mu}_1 \\ \mathbf{y}_2 - \boldsymbol{\mu}_2 \end{bmatrix} \right\} \\ &= \exp \left\{ -\frac{1}{2} \begin{bmatrix} \mathbf{y}_1 - \boldsymbol{\mu}_1 \\ \mathbf{y}_2 - \boldsymbol{\mu}_2 \end{bmatrix}^T \begin{bmatrix} \boldsymbol{\Sigma}_{11} & \boldsymbol{\Sigma}_{12} \\ \boldsymbol{\Sigma}_{21} & \boldsymbol{\Sigma}_{22} \end{bmatrix}^{-1} \begin{bmatrix} \mathbf{y}_1 - \boldsymbol{\mu}_1 \\ \mathbf{y}_2 - \boldsymbol{\mu}_2 \end{bmatrix} \right\} \\ &= \exp \left\{ -\frac{1}{2} \begin{bmatrix} \mathbf{y}_1 - \boldsymbol{\mu}_1 \\ \mathbf{y}_2 - \boldsymbol{\mu}_2 \end{bmatrix}^T \begin{bmatrix} \boldsymbol{\Sigma}_{11}^* & \boldsymbol{\Sigma}_{12}^* \\ \boldsymbol{\Sigma}_{21}^* & \boldsymbol{\Sigma}_{22}^* \end{bmatrix} \begin{bmatrix} \mathbf{y}_1 - \boldsymbol{\mu}_1 \\ \mathbf{y}_2 - \boldsymbol{\mu}_2 \end{bmatrix} \right\} \\ &= \exp \left\{ -\frac{1}{2} [(\mathbf{y}_1 - \boldsymbol{\mu}_{cond})^T \boldsymbol{\Sigma}_{cond}^{-1}(\mathbf{y}_1 - \boldsymbol{\mu}_{cond})] \right\} \\ &\Rightarrow \mathbf{y}_1|\mathbf{y}_2, \boldsymbol{\mu}, \boldsymbol{\Sigma} \sim N_q(\boldsymbol{\mu}_{cond}, \boldsymbol{\Sigma}_{cond}) \end{aligned}$$

$$\boldsymbol{\mu}_{cond} = \boldsymbol{\mu}_1 + \boldsymbol{\Sigma}_{12}\boldsymbol{\Sigma}_{22}^{-1}(\mathbf{y}_2 - \boldsymbol{\mu}_2), \quad \boldsymbol{\Sigma}_{cond} = \boldsymbol{\Sigma}_{11} - \boldsymbol{\Sigma}_{12}\boldsymbol{\Sigma}_{22}^{-1}\boldsymbol{\Sigma}_{21}$$

The blockwise inversion formula was used to invert Σ according to the following reparameterizations.

$$\Sigma_{11}^* = \Sigma_{11}^{-1} + \Sigma_{11}^{-1} \Sigma_{12} (\Sigma_{22} - \Sigma_{21} \Sigma_{11}^{-1} \Sigma_{12})^{-1} \Sigma_{21} \Sigma_{11}^{-1}$$

$$\Sigma_{12}^* = -\Sigma_{11} \Sigma_{12} (\Sigma_{22} - \Sigma_{21} \Sigma_{11}^{-1} \Sigma_{12})^{-1}$$

$$\Sigma_{21}^* = -(\Sigma_{22} - \Sigma_{21} \Sigma_{11}^{-1} \Sigma_{12})^{-1} \Sigma_{21} \Sigma_{11}^{-1}$$

$$\Sigma_{22}^* = (\Sigma_{22} - \Sigma_{21} \Sigma_{11}^{-1} \Sigma_{12})^{-1}$$