Real-time Scheduling

Types of Deadlines:

- Hard-deadline: Must be met to prevent damage/error, or for output to make sense.
- Soft-deadline: Deadline, if not met, will provide results that are semi-relevant.

Types of Tasks:

• Periodic Tasks:

- Tasks that happen at regule intervals
- Generally hard-deadlines e.g.
- \circ Ck is the computation time, and Tk is the period.
 - The system is *overloaded* when:

Aperiodic:

- Tasks with no period. Generally occurr in response to some random event.
- Generally soft-deadlines, because difficult to guarantee completion.
- Must not interfere with hard-deadlines of other processes.

Sporadic Tasks:

- Aperiodic tasks with hard-deadlines.
- Requires protocal ensuring there's atleast Tk time b/w consecutive occurrence of task.
- Sporadic tasks can overload systems
 - Some not even scheduled if impossible to meet deadlines.

Task Scheduling Algorithms:

NOTE: 'pre-emptive' means the currently running process can be interrupted by another process.

• Earliest Deadline First:

- Choose task with soonest deadline
- Break tie using random selection
- If a schedule fulfills all deadlines exist, it'll be produced
- Higher priority task generated in real-time with pre-empt current task

• Least Slack First:

- Slack: how long a process can with before being scheduled to meet its deadline.
- Slack gives indication of which tasks in danger of missing deadline(s).
- We prefer tasks to start as early as possible.

Commercial Task Scheduling:

• UNIX:

- Multi-level, pre-emptive (i.e. stopped after time-slice expiration), Round-robin on each level.
- Default time-slice duration is 1s.
- **Priority:** lower the value, higher the priority.
 - CPU utilization at time-slice no. *i* is calculated as:
 - Priority at interval *i* calculated as:
 - Bj is the initial priority that process was started with
 - Nj is the 'nice' value that can be modified.
 - *CPUj* and *N* values are limited s.t. the no user process has higher priority than UNIX's system processes.

Windows:

o Priority-based, pre-emptive scheduling

- Process runs long as its pre-empted, blocked, terminated, or time-slice expires
- Scheduler/Dispatcher maintains a queue to each priority level (32 different levels).
 - ...and goes through them from highest-to-lowest
- **Priority:** higher the value, higher the priority.
 - User can change priority level of a process to:
 - Realtime
 - High
 - Above Normal
 - Normal (a process is *usually* here)
 - Below Normal
 - Low
 - A pre-*empted* process' priority will be lowered (*unless* it's realtime)
- Higher priority given to foreground task(s), and the task atop in the UI.
 - Task on the *top* of the UI also gets *longer* time-slices.