Signal Processing in Quantum Mechanics



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Presentation Overview

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Introduction

Signal Processing

Signal is a function that conveys information about the behaviour of a system.

- Common operations on signals:
 - Scaling, Addition, and Subtraction
 - Delays, Phase Changes
 - Filtering and Feedback



Introduction

Signal Processing

- ► Control Blocks often perform following operations:
 - Scaling
 - Delays
 - Filtering



Introduction

Signal Processing

- Signals often representable as sum of many sinusoids
- Signals commonly represented in Frequency Domain
- Laplace Transform commonly used for Frequency Domain form

$$\mathcal{L}{f(t)} \to F(s)$$



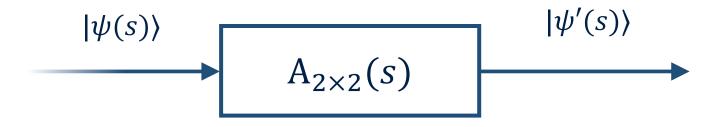
Developing Quantum Control Blocks

- We use Quantum Operators as Quantum Control Blocks
- Quantum States are input and output signals



Mathematical Notation

- Quantum Transfer Functions represent Quantum Control Blocks
- Quantum Transfer Functions are operator matrices

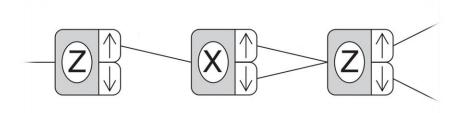


$$|\psi'(s)\rangle = A(s)|\psi(s)\rangle$$

Projection Blocks

- Projection Blocks represent act of observing the quantum state
- Observers are used to predictably alter quantum state

$$|\psi'(t)\rangle = \frac{P_{\pm n}|\psi(t)\rangle}{\sqrt{\langle\psi(t)|P_{\pm n}|\psi(t)\rangle}}$$



Projection Blocks

- Can be used to prepare an input signal to a certain state
- Example: Given an arbitrary input, we want an output signal of state $|\psi'(t)\rangle = |-\rangle$

$$|\psi(t)\rangle = k_1|+\rangle + k_2|-\rangle \rightarrow |\psi'(t)\rangle = |-\rangle$$

$$|\psi(s)\rangle = \frac{k_1}{s}|+\rangle + \frac{k_2}{s}|-\rangle \rightarrow |\psi'(s)\rangle = \frac{k_2}{s}|-\rangle$$

$$|\psi'(s)\rangle = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} |\psi(s)\rangle$$

$$\mathbf{T}(s) = \mathbf{P}_{-s}$$

Projection Blocks

- Disadvantage: Projection Blocks do not guarantee an output
- Projection Blocks behave similar to traditional filters

$$|\psi(t)\rangle = k_1|+\rangle + k_2|-\rangle \rightarrow |\psi'(t)\rangle = |-\rangle$$

$$|\psi(s)\rangle = \frac{k_1}{s}|+\rangle + \frac{k_2}{s}|-\rangle \rightarrow |\psi'(s)\rangle = \frac{k_2}{s}|-\rangle$$

$$|\psi'(s)\rangle = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} |\psi(s)\rangle$$

$$\mathbf{T}(s) = \mathbf{P}_{-s}$$

Projection Blocks

- What if a projection block has no output?
- We defined a Zero Signal to indicate absence of a quantum state

$$|\psi(s)\rangle = \frac{k_1}{s}|+\rangle \qquad |\psi'(s)\rangle = 0|+\rangle + 0|-\rangle$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

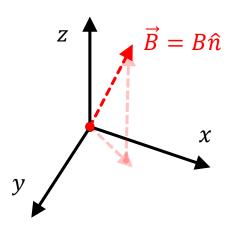


High Pass Filter

Precession Blocks

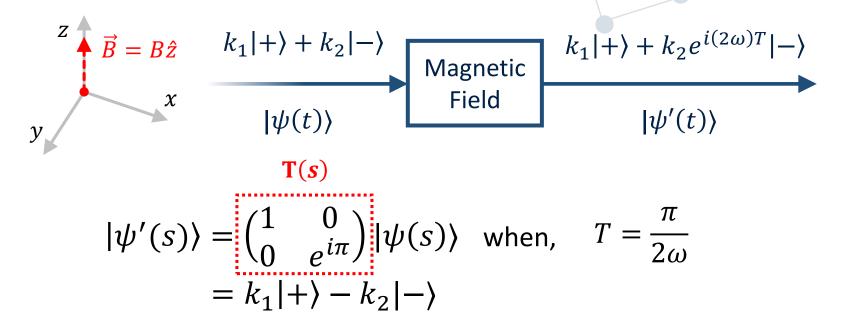
- Precession Blocks represent time-evolution under influence of magnetic fields
- Magnetic fields of strength B in direction \hat{n} applied for time T used to modify relative phase

$$|\psi'(T)\rangle = k_1 e^{-i\omega T} |E_1\rangle + k_2 e^{i\omega T} |E_2\rangle$$



Precession Blocks: Phase Changer

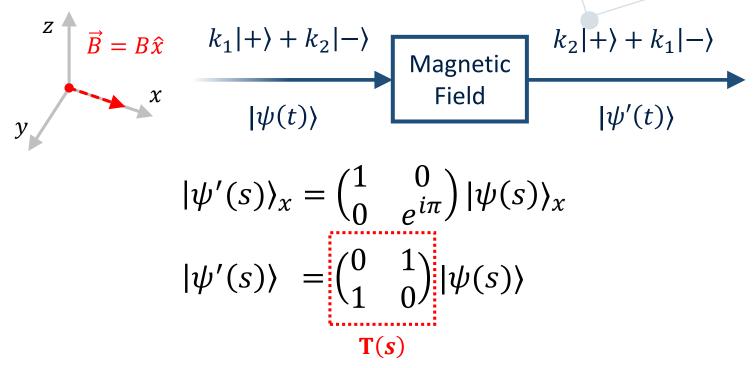
Phase Changer is used to modify relative phase of an input state



• Since $\omega = \frac{Be^-}{m_e^-} \gg \pi$, the time $T \approx 0$ and delays can be ignored

Precession Blocks: Amplitude Reversal

► Amplitude Reversal is used to implement quantum NOT gates



Minuscule delays are ignored in favor of simplicity

Signal Filtering

Filtering in traditional control systems refers to filtering frequency components



Filtering in our context refers to removing super-position

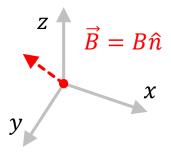
$$|\psi(s)\rangle = \frac{k_1}{s}|+\rangle + \frac{k_2}{s}|-\rangle$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$|\psi'(s)\rangle = \frac{k_2}{s}|-\rangle$$

Signal Phase Changes

Phase Changer is used to modify relative phase of an input state



$$\begin{array}{c|c} k_1|E_1\rangle + k_2|E_2\rangle \\ \hline & \begin{pmatrix} 1 & 0 \\ 0 & e^{e^{i(2\omega)T}} \end{pmatrix} & |\psi'(t)\rangle \\ \hline \\ |\psi(t)\rangle & |\psi'(t)\rangle \\ \end{array}$$

Signal Scaling

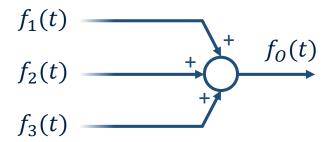
 Scaling in traditional control systems refers to changing signal magnitude



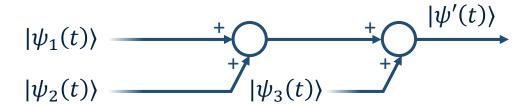
 Quantum states are always of a unit magnitude; scaling is not required

Summing Junction

Summing Junctions in traditional control systems are used to add multiple, different signals

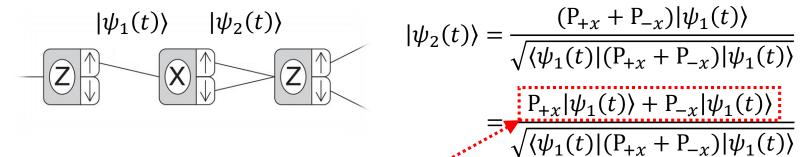


Summing Junctions are binary operations in our context



Summing Junction: Derivation

Concept of Quantum Summing junctions originates from the following case:

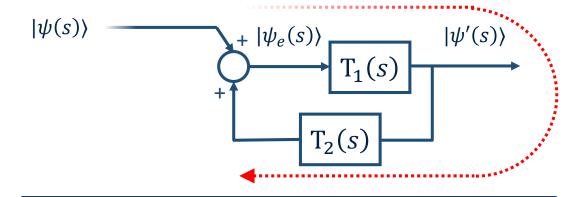


- Multiply input by appropriate operators
- Retain the global phase of different terms before summation

Signal Feedback, Summing Junction

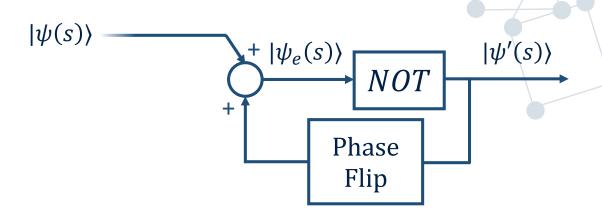
Signal Feedback involves using the output as a part of the input signal itself

$$|\psi_{e_{(i+1)}}(t)\rangle = I|\psi(s)\rangle + T_2(s)T_1(s)|\psi_{e_{(i)}}(t)\rangle$$



$$|\psi'(s)\rangle = (I - T_1(s)T_2(s))^{-1}(T_1(s))|\psi(s)\rangle$$

Signal Feedback: Example

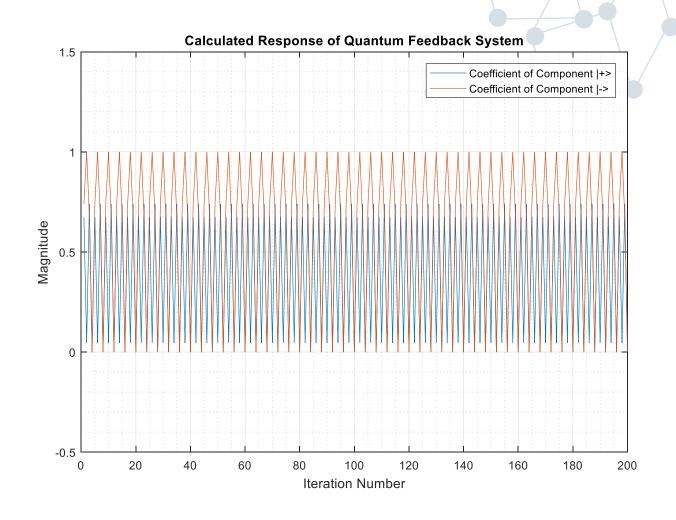


$$k_1|+\rangle + k_2|-\rangle$$
 $T_1(s)$
 $k_2|+\rangle + k_1|-\rangle$
 $k_1|+\rangle + k_2|-\rangle$
 $T_2(s)$
 $k_1|+\rangle - k_2|-\rangle$

 $T_1(s)$ is a **NOT** gate $T_2(s)$ is a **Phase Flip**

$$|\psi'(s)\rangle = (I - T_1(s)T_2(s))^{-1}(T_1(s))|\psi(s)\rangle$$

Signal Feedback: Simulation of a Quantum Feedback System





Questions?

References

- ▶ [1] David H. McIntyre, "Quantum Mechanics: A Paradigms Approach", Pearson, 2012
- [2] Lucas V. Barbosa, "Fourier Series", Wikimedia

https://en.wikipedia.org/wiki/Fourier_series