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- How can we characterize this variable?
- Is the game fair for the player depending on the values of x,  $G_1$ ,  $G_2$  and  $G_3$ ?

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• random experiment : this is an experiment with an uncertain outcome prior to its execution

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### Remark:

 $X(\Omega)$ : this is the set of all attainable values for the random variable X.

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#### Remark:

For a given random experiment, it is possible to define several random variables. For example, on the previous example, we can also consider:

$$\left\{ egin{array}{ll} Y:\Omega 
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#### Remark

 $\{X = G_1\}$  is an event since this is a part of  $\Omega$  since:

$${X = G_1} = {x \in \Omega, X(\omega) = G_1}$$

### come back onto the first example:

• We have  $X(\Omega)=\{G_1,\ G_2,\ G_3\}$  (not to be confused with  $\Omega=\{(a,b),\ a,b\in\{1,\ldots,6\}\}$  a the issue of the blue die and b of the green)

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#### Remark

Another method to compute  $P(X = G_3)$  is

$$P(X = G_3) = 1 - P(X = G_1) - P(X = G_2)$$

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To answer the last question, we need to compute the expectation.

#### **Definition**

Let X a discrete random variable.

When the expectation exists, we denote it  $\mathbb{E}[X]$ , and its formula is:

$$\mathbb{E}[X] = \sum_{k \in X(\Omega)} k.P(X = k)$$

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#### Remark

What are the conditions for the existence of the expectation? The expectation of X exists if X is a integrable variable, which means :

$$\mathbb{E}[|X|] = \sum_{k \in X(\Omega)} |k| . P(X = k) < +\infty$$

Xintegrable can be denoted  $X \in L^1$ .

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- $\mathbb{E}[X]$  is a real, not a random quantity.

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- since  $X(\Omega)$  is a finite set, we are sure about the existence of the expectation
- So we have:

$$\mathbb{E}[X] = G_1.\frac{1}{36} + G_2.\frac{10}{36} + G_3.\frac{25}{36}$$

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• let take x=2,  $G_1=10$ ,  $G_2=5$  et  $G_3=0$ , then  $\mathbb{E}[X]=\frac{60}{36}<2$ . The expectation being negative, thus the game is biased against the player.

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- let take x=2,  $G_1=30$ ,  $G_2=5$  et  $G_3=0$ , then  $\mathbb{E}[X]=\frac{80}{36}>2$ . The expectation being positive, thus the game is favorable to the player.

### **Proposition**

Let X an integrable discrete random variable.

Let h a real function.

Consider Y = h(X).

We assume that h has properties to ensure the existence of the expectation for Y.

Then:

$$\mathbb{E}[Y] = \sum_{k \in X(\Omega)} h(k).P(X = k)$$

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#### Remark

The interest of this formula is that it is possible to compute the expectation for h(X) without having to dtermine the distribution of h(X).

Consider the variable X whose distribution is:

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Consider the variable Y given by

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What is the expectation for Y?

By applying the transfert formula with  $h(x) = x^2$ , we get:

$$\mathbb{E}[Y] = \sum_{k \in X(\Omega)} k^2 \cdot P(X = k) = (-2)^2 \cdot \frac{1}{2} + (0)^2 \cdot \frac{1}{4} + (1)^2 \cdot \frac{1}{4} = \frac{9}{4}$$

#### Definition

Consider a discrete random variable X

When the variance exists, we denote it  $\mathbb{V}[X]$ , and its formula is :

$$\mathbb{V}[X] = \mathbb{E}[(X - \mathbb{E}[X])^2]$$

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#### Remark

What are the conditions for the existence of the variance? The variance of X exists if X is a squared integrable variable, i.e.:

$$\mathbb{E}[X^2] = \sum_{k \in X(\Omega)} k^2 . P(X = k) < +\infty$$

X squared integrable variable is written  $X \in L^2$ .

## **Properties**

Because we deal with probabilities, we have:

$$L^2 \subset L^1$$

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## **Properties**

The previous formula for the variance is the definition, in practice we use more:

$$\mathbb{V}[X] = \mathbb{E}[X^2] - (\mathbb{E}[X])^2$$

with  $\mathbb{E}[X^2] = \sum_{k \in X(\Omega)} k^2.P(X=k)$  (transfert formula)

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- $\mathbb{V}[X]$  a non random quantity

# **Properties**

Consider X and Y two discrete random variables in  $L^2$ . Consider  $\lambda \in \mathbb{R}$ .

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- $\mathbb{V}[X + \lambda] = \mathbb{V}[X]$
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- $\mathbb{V}[X]$  a non random quantity
- $V[X] \ge 0$

Let consider a variable X whose distribution is given by:

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By using the practical formula for the variance :

$$\mathbb{V}[X] = \mathbb{E}[X^2] - (\mathbb{E}[X])^2 = \frac{9}{4} - ((-2) \cdot \frac{1}{2} + 0 * \frac{1}{4} + 1 \cdot \frac{1}{4})^2 = \frac{9}{4} - \frac{9}{16} = \frac{27}{16}$$

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- La variance is the centered moment of order 2 for X
- The centered moment of order 1 for X has no sense since is it equal to 0
- Let X an integrable random variable.
   Then Y = X E[X] is a centered variable, which means that its expectation is equal to 0.

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#### **Definition**

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The distribution function for X, denoted  $F_X$ , is the function given by:

$$\forall t \in \mathbb{R}, \ F_X(t) = P(X \leq t)$$

#### Remark

Be careful, there exists another definition which is the english one:

$$\forall t \in \mathbb{R}, \ F_X(t) = P(X < t)$$

Those txo definitions do not provide the same results for discrete random variables.

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- is a right continuous function

Consider the variable X whose distribution is :

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the distribution function for X is given by

$$F_X(t) = \begin{cases} 0 & \text{if } t < -2\\ \frac{1}{2} & \text{if } -2 \le t < 0\\ \frac{3}{4} & \text{if } 0 \le t < 1\\ 1 & \text{if } 1 < t \end{cases}$$

• If 
$$t<-2$$
, then  $\{X\leq t\}=\emptyset$  and  $F_X(t)=0$ 

- If t < -2, then  $\{X \le t\} = \emptyset$  and  $F_X(t) = 0$
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- If  $1 \le t$ , then  $\{X \le t\} = \{-2; 0; 1\}$  and  $F_X(t) = P(X = -2) + P(X = 0) + P(X = 1) = 1$

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- let k a point of discontinuity, then P(X = k) is the difference between the two consecutive steps around k

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