Model-based Statistical Learning

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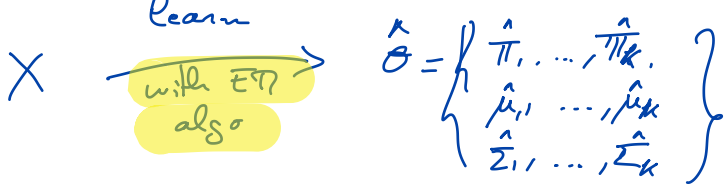
EM algorithm for GMM:

The goal of the first step is to find the best mixture parameter estimates for the data at hand:



The EM algorithm will optimize iteratively the likelihood of this model without directly optimize the function.

Starting with the GMM model, we can write the log. likelihood of the model:

$$\mathcal{L}(x;\theta) = \log\left(\prod_{i=1}^{n} p(x_i;\theta)\right)$$

$$= \log\left(\prod_{i=1}^{n} \sum_{k=1}^{K} \pi_k \mathcal{N}(x_i;\mu_k,\Sigma_k)\right)$$

$$= \sum_{i=}^{n} \log\left(\sum_{k=1}^{K} \pi_k \mathcal{N}(x_i;\mu_k,\Sigma_k)\right)$$

We see here that it is totally possible to evaluate $\mathcal{L}(x;\theta)$ for specific values of x and θ, but the direct optimization is really difficult due to the $\log(\Sigma_k)$

The EM algorithm

The idea of the EM algorithm is to introduce an extra and non-observed (latent) variable Y, encoding the group memberships. Estimating both θ and Y from X is finally easier than just estimating θ from X.

$Y_i \in \{0,1\}^K \Rightarrow Y_i = (0,0,1,0) \Rightarrow x_i$ belongs to the 3rd cluster

$$\begin{cases} Y \sim \mathcal{M}(1;\pi) \\ X \mid Y_k \sim \mathcal{N}(\mu_k, \Sigma_k) \end{cases}$$

integrate over Y $\Rightarrow$ $p(x) = \sum_{k=1}^{K} \pi_k \mathcal{N}(x;\mu_k,\Sigma_k)$

This allows us to write another log-likelihood, called the complete data log-likelihood, of the couple (X, Y):

$$= \sum_{i=1}^{n} \log p((x_i, y_i); \theta)$$

$$\mathcal{L}_c(x, y, \theta) = \sum_{i=1}^{n} \left[\log p(y_i | x_i; \theta) + \log p(x_i; \theta) \right]$$

$$= \mathcal{L}(x; \theta) + \sum_{i=1}^{n} \log p(y_i | x_i; \theta)$$

$$\Rightarrow \mathcal{L}(x; \theta) = \mathcal{L}_c(x, y; \theta) - \sum_{i=1}^{n} \log p(y_i | x_i; \theta)$$

$$\Rightarrow \mathcal{L}_c \leq \mathcal{L}$$

The EM algorithm

Rmk: we see here that $\mathcal{L}_c$ is a lower bound of $\mathcal{L}$ and optimizing $\mathcal{L}_c$ over Θ will automatically lead in the the optimization of $\mathcal{L}$.

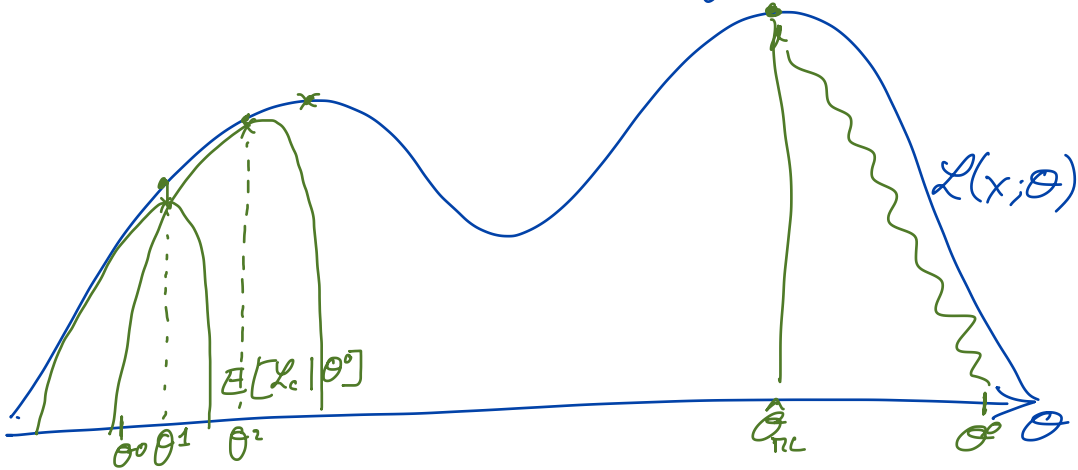
Thanks to this remark, Dempster, Laird and Rubin proposed in 1977 the EM algorithm:

- E step: the E step aims at calculating the expected complete log-likelihood:

$$Q(\theta;\theta^*) = E[\mathcal{L}_c(x;y;\theta) \mid x;\theta^*]$$

- M step: the M step aims at maximizing this function $Q(\theta;\theta^*)$ over θ to provide a new value for θ^*

Theorem: the sequence of estimates (θ^t) over the iterations of the EM algorithm is converging toward a local maximum of the log-likelihood.



The EM algorithm for GMM

In practice:

1) to avoid being trapped in a local maximum, we usually do several (10) different random initializations and we keep afterward the $\hat{\theta}_{EM}$ with the highest likelihood.

2) to stop the algorithm, we just monitor the evolution of the log. likelihood and we stop when a plateau is detected

The EM algorithm for GMM

Starting with the E step, we need to focus on

$$Q(\theta, \theta^{(t)}) = E\left[\mathcal{L}_c(X, Y; \theta) \mid \theta^{(t)}, X\right]$$

and

$$\mathcal{L}_c(X, Y; \theta) = \sum_{i=1}^{n} \log p(x_i, y_i; \theta)$$

$$= \sum_{i=1}^{n} \log \left[\sum_{k=1}^{K} y_{ik} \pi_k \mathcal{N}(x_i; \mu_k, \Sigma_k) \right]$$

$$= \sum_{i=1}^{n} \sum_{k=1}^{K} y_{ik} \log \left(\pi_k \mathcal{N}(x_i; \mu_k, \Sigma_k) \right)$$

and thefore :

$$E[\mathcal{L}_c(x,y|\theta)|\theta^*;X] = \sum_{i=1}^{n}\sum_{k=1}^{K} E[y_{ik}|\theta^*,X] \log\left(\pi_k \mathcal{N}(x_i;\mu_k,\Sigma_k)\right)$$

and $E[y_{ik}|\theta^*;X] = P(y_{ik}=1|x,\theta^*)$

$$\overset{\text{Bayes}}{=} \frac{P(y_{ik}=1|\theta^*)P(x_i|y_{ik}=1;\theta^*)}{p(x)}$$

$$\propto \pi_k^* \times \mathcal{N}(x_i;\mu_k^*,\Sigma_k^*)$$

Let's call $t_{ik} = E[y_{ik}|\theta^*;X]$

$$\Rightarrow E[\mathcal{L}_c(x,y;\theta)|\theta^*;X] = \sum_{i=1}^{n}\sum_{k=1}^{K} t_{ik} \log \pi_k \mathcal{N}(x_i;\mu_k,\Sigma_k)$$

The EM algorithm for GMM

In the π step, we just have to optimize in θ the $E[\mathcal{L}_c(x,y;\theta)|\theta^*;x)$:

$$\max_\theta \underbrace{E[\mathcal{L}_c(x,y;\theta)|\theta^*,x]}_{Q(\theta,\theta^*)} = \sum_{i=1}^{n}\sum_{k=1}^{K} t_{ik}\log \pi_k \mathcal{N}(x_i;\mu_k,\Sigma_k)$$

- Finding the update for π_k:

$$\frac{\partial}{\partial \pi_k} Q(\theta;\theta^{(t)}) = \frac{\partial}{\partial \pi_k}\left[\sum_i\sum_k t_{ik}\left[\log \pi_k + \log \mathcal{N}(x_i;\dots)\right]\right]$$