# Unit 4: Singular Value Decomposition

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# Summary

- Eigenspaces
- Singular Value Decomposition
- **3** Singular Values of an  $m \times n$  Matrix Singular Value Decomposition
- 4 Examples
- 6 Four fundamental subspaces of a matrix

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# Spectrum

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Eigenspaces

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## Eigenspace

The set of all eigenvectors corresponding to an eigenvalue of a matrix together with the zero vector is called the **Eigenspace** associated with the eigenvalue.

The **Eigenspace** associated with an eigenvalue of a matrix is a vector space.

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Examples

**Proof.** If v and w are eigenvectors associated with the same eigenvalue  $\lambda$ , then

$$A(v+w) = Av + Aw = \lambda v + \lambda w = \lambda(v+w)$$

The **Eigenspace** associated with an eigenvalue of a matrix is a vector space.

**Proof.** If v and w are eigenvectors associated with the same eigenvalue  $\lambda$ , then

$$A(v+w) = Av + Aw = \lambda v + \lambda w = \lambda(v+w)$$

and for any real number c,

$$A(cv) = c(Av) = c(\lambda v) = \lambda(cv).$$



Let A be a symmetric  $n \times n$  matrix. By spectral decomposition theorem,

$$A = V\Lambda V^T, \tag{1}$$

where  $\Lambda$  is the diagonal matrix of eigenvalues  $\lambda_i$ 's arranged in decreasing order and V is the  $n \times n$ orthogonal matrix of the eigenvectors associated with the eigenvalues  $\lambda_i$ 's.

From Equation 1, we get

Eigenspaces

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$$A = (u_1 \dots u_n) \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix} \begin{pmatrix} u_1^T \\ \vdots \\ u_n^T \end{pmatrix}$$

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$$= (\lambda_1 u_1 \dots \lambda_n u_n) \begin{pmatrix} u_1^T \\ \vdots \\ u_n^T \end{pmatrix}$$
$$= \sum_{i=1}^n \lambda_i u_i u_i^T.$$

Examples

Thus, we have expressed the matrix A as a sum of n terms, each of which is the outer product of an eigenvector with its transpose, and is scaled by its associated eigenvalue.

Equation (1) gives the spectral decomposition of the matrix A, also called the **Eigenvalue Decomposition** (EVD).

The spectral decomposition theorem of a symmetric matrix A can be restated as follows:

#### Theorem

Eigenspaces

If an  $n \times n$  matrix A is symmetric, then A is orthogonally diagonalizable.

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#### Theorem

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#### Proof.

If A is orthogonally diagonalizable, then

$$A^{T} = (PDP^{T})^{T} = P^{TT}D^{T}P^{T} = PDP^{T} = A.$$

Thus, A is symmetric.



# Singular Value Decomposition

and square, such that

Eigenspaces

$$A = V\Lambda V^T.$$

We have seen that symmetric matrices are always (orthogonally) diagonalizable. That is, for any symmetric matrix  $A \in \mathbb{R}^{n \times n}$ , there exist an orthogonal matrix  $V = (v_1 \dots v_n)$  and a diagonal matrix  $\Lambda = \operatorname{diag}(\lambda_1, \ldots, \lambda_n)$ , both real and square, such that

$$A = V\Lambda V^T$$
.

### What about general rectangular matrices?

We have seen that symmetric matrices are always (orthogonally) diagonalizable. That is, for any symmetric matrix  $A \in \mathbb{R}^{n \times n}$ , there exist an orthogonal matrix  $V = (v_1 \dots v_n)$  and a diagonal matrix  $\Lambda = \operatorname{diag}(\lambda_1, \ldots, \lambda_n)$ , both real and square, such that

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# What about general rectangular matrices?

Let's now consider the generalization of the spectral theorem to an arbitrary  $m \times n$  matrix A. The singular value decomposition is based on the following property of the ordinary diagonalization that can be imitated for rectangular matrices:

Examples

If 
$$Ax = \lambda x$$
 and  $||x|| = 1$ , then  $||Ax|| = ||\lambda x|| = ||\lambda|||x|| = |\lambda|$ .

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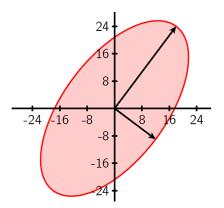
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# Example

If  $A = \begin{pmatrix} 2 & 1 \\ 2 & 5 \end{pmatrix}$ , then the linear transformation  $x \mapsto Ax$  maps the unit circle  $\{x : ||x|| = 1\}$  in  $\mathbb{R}^2$  onto an ellipse in  $\mathbb{R}^2$ , shown in the figure. Find a unit vector x at which the length ||Ax|| is maximized, and compute this maximum length.



**Solution.** The quantity  $||Ax||^2$  is maximized at the same x that maximizes ||Ax||, and  $||Ax||^2$  is easier to study. Observe that

$$||Ax||^2 = (Ax)^T (Ax) = x^T A^T Ax = x^T (A^T A)x.$$

Also,  $A^T A$  is a symmetric matrix, since  $(A^T A)^T = A^T A^{TT} = A^T A$ .

to maximize: 
$$x^T(A^TA)x$$
  
subject to:  $||x|| = 1$ .

We know that the maximum value is the greatest eigenvalue  $\lambda_1$  of  $A^TA$ . Also, the maximum value is attained at a unit eigenvector of  $A^TA$  corresponding to  $\lambda_1$ .

For the matrix A in this example,

$$A^T A = \begin{pmatrix} 2 & 2 \\ 1 & 5 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 2 & 5 \end{pmatrix} = \begin{pmatrix} 8 & 12 \\ 12 & 26 \end{pmatrix}.$$

The eigenvalues of  $A^TA$  are

$$\lambda_1 = 32, \lambda_2 = 2.$$

Corresponding unit eigenvectors are, respectively,

$$v_1 = \frac{1}{\sqrt{5}} \begin{pmatrix} 1 \\ 2 \end{pmatrix}, v_2 = \frac{1}{\sqrt{5}} \begin{pmatrix} -2 \\ 1 \end{pmatrix}.$$

The maximum value of  $||Ax||^2$  is 32, attained when x is the unit vector  $v_1$ . The vector  $Av_1$  is a point on the ellipse in the above figure farthest from the origin, namely,

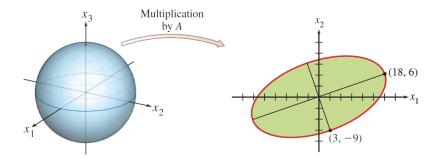
$$Av_1 = \begin{pmatrix} 2 & 1 \\ 2 & 5 \end{pmatrix} \frac{1}{\sqrt{5}} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \frac{1}{\sqrt{5}} \begin{pmatrix} 4 \\ 12 \end{pmatrix}.$$

Therefore, for ||x|| = 1, the maximum value of ||Ax|| is  $||Av_1|| = \sqrt{32} = 4\sqrt{2}.$ 

This description of  $v_1$  and  $|\lambda_1|$  has an analogue for rectangular matrices that will lead to the singular value decomposition.

## Example

If  $A = \begin{pmatrix} 4 & 11 & 14 \\ 8 & 7 & -2 \end{pmatrix}$ , then the linear transformation  $x \mapsto Ax$  maps the unit sphere  $\{x: ||x|| = 1\}$  in  $\mathbb{R}^3$  onto an ellipse in  $\mathbb{R}^2$ , shown in the figure. Find a unit vector x at which direction the length ||Ax|| is maximized, and compute this maximum length.



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We know that the maximum value is the greatest eigenvalue  $\lambda_1$  of  $A^TA$ . Also, the maximum value is attained at a unit eigenvector of  $A^TA$  corresponding to  $\lambda_1$ .

For the matrix A in this example,

$$A^{T}A = \begin{pmatrix} 4 & 8 \\ 11 & 7 \\ 14 & -2 \end{pmatrix} \begin{pmatrix} 4 & 11 & 14 \\ 8 & 7 & -2 \end{pmatrix} = \begin{pmatrix} 80 & 100 & 40 \\ 100 & 170 & 140 \\ 40 & 140 & 200 \end{pmatrix}.$$

Eigenspaces

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The eigenvalues of  $A^TA$  are

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The eigenvalues of  $A^TA$  are

$$\lambda_1 = 360, \lambda_2 = 90, \lambda_3 = 0.$$

Corresponding unit eigenvectors are, respectively,

$$v_1 = \begin{pmatrix} 1/3 \\ 2/3 \\ 2/3 \end{pmatrix}, v_2 = \begin{pmatrix} -2/3 \\ -1/3 \\ 2/3 \end{pmatrix}, v_3 = \begin{pmatrix} 2/3 \\ -2/3 \\ 1/3 \end{pmatrix}.$$

The maximum value of  $||Ax||^2$  is 360, attained when x is the unit vector  $v_1$ .

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$$Av_1 = \begin{pmatrix} 4 & 11 & 14 \\ 8 & 7 & -2 \end{pmatrix} \begin{pmatrix} 1/3 \\ 2/3 \\ 2/3 \end{pmatrix} = \begin{pmatrix} 18 \\ 6 \end{pmatrix}.$$

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Therefore, for ||x|| = 1, the maximum value of ||Ax|| is  $||Av_1|| = \sqrt{360} = 6\sqrt{10}$ .

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- The effect of A on the unit sphere in  $\mathbb{R}^3$  is related to the quadratic form  $x^T(A^TA)x$ .
- To decompose an  $m \times n$ , it is worthwhile to study  $A^T A$  or  $AA^T$ . Both are symmetric square matrices and can be orthogonally diagonalized, as we know.

# Singular Values of an $m \times n$ Matrix

Since matrix products of the form  $A^TA$  will play an important role in our further work, we now give some basic properties of  $A^TA$ .

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Examples

#### Theorem.

Let A be an  $m \times n$  matrix. Then

- $\mathbf{0}$   $A^T A$  is a square matrix.
- $\mathbf{a}$   $A^TA$  is symmetric and so it is orthogonally diagonalizable.
- $\bullet$  All the eigenvalues of  $A^TA$  are non-negative.

**Proof.** Let A be an  $m \times n$  matrix. Then

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2. We observe that

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This shows that  $A^TA$  is symmetric. Then by the spectral decomposition theorem,  $A^TA$  is orthogonally diagonalizable.

By (2), the matrix  $A^TA$  is symmetric and can be orthogonally diagonalized.

Four fundamental subs

 $\lambda_1, ..., \lambda_n$  be the associated eigenvalues of  $A^T A$ .

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Examples

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## Singular values

The square roots of the eigenvalues of  $A^TA$  are called the **singular values** of A.

If  $\lambda_1, ..., \lambda_n$  be the eigenvalues of  $A^T A$ , then the corresponding singular values of A are denoted by  $\sigma_1, \sigma_2, ..., \sigma_n,$ 

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Eigenspaces

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#### $\mathbf{Problem}$

The singular values of A are the lengths of the vectors  $Av_1, ..., Av_n$ .

## Example.

Find the singular values of the matrix

$$\begin{pmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{pmatrix}$$

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Solution.

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The first step is to find the eigenvalues of the matrix  $A^T A$ .

We have

$$A^{T}A = \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}.$$

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Eigenspaces

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so the eigenvalues of  $A^TA$  are  $\lambda_1=3$  and  $\lambda_2=1$ and the singular values of A in order of decreasing size are

$$\sigma_1 = \sqrt{\lambda_1} = \sqrt{3},$$
  

$$\sigma_2 = \sqrt{\lambda_2} = \sqrt{1} = 1.$$

#### Theorem

If A is an  $m \times n$  matrix, then  $A^T A$  and  $AA^T$  have the same nonzero eigenvalues.

## If A is an $m \times n$ matrix, then $A^T A$ and $AA^T$ have the same nonzero eigenvalues.

**Proof.** Suppose A is an  $m \times n$  matrix, and suppose that  $\lambda$  is a nonzero eigenvalue of  $A^TA$ . Then there exists a nonzero vector  $x \in \mathbb{R}^n$  such  $(A^T A)x = \lambda x.$ 

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$$A(A^{T}A)x = A\lambda x$$
  

$$\Rightarrow (AA^{T})(Ax) = \lambda(Ax).$$

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Since  $\lambda \neq 0$  and  $x \neq 0$ ,  $\lambda x \neq 0$ , and thus,  $(A^TA)x \neq 0$ ; thus  $A^T(Ax) \neq 0$ , implying that  $Ax \neq 0$ .

Eigenspaces

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- For a symmetric matrix, the number of its nonzero eigenvalues is its rank.
- To obtain a similar result for the rank of an  $m \times n$  matrix A, not necessarily square, we arrange the eigenvalues of  $A^TA$  in decreasing order:

 $\lambda_1 > \cdots > \lambda_n > 0$ .

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Thus, by definition, the corresponding singular values of A follow the same order:

$$\sigma_1 \geq \cdots \geq \sigma_n$$
.

The decomposition of A involves an  $m \times n$ "diagonal" matrix  $\Sigma$  of the form

where D is an  $r \times r$  diagonal matrix for some r not exceeding the smaller of m and n. (If requals m or n or both, some or all of the zero matrices do not appear.)

# Let A be an $m \times n$ matrix with rank r. Then there exists an $m \times n$ matrix $\Sigma$ as in the above

Examples

for which the diagonal entries in D are the first r  $singular\ values\ of\ A,$ 

$$\sigma_1 \ge \cdots \ge \sigma_r > 0$$

and there exist an  $m \times m$  orthogonal matrix U and an  $n \times n$  orthogonal matrix V such that

$$A = U\Sigma V^T.$$

Any factorization  $A = U\Sigma V^T$ , with U and V orthogonal,  $\Sigma$  as in the above, and positive diagonal entries in D, is called a singular value decomposition (or SVD) of A.

Examples

The matrices U and V are not uniquely determined by A, but the diagonal entries of  $\Sigma$ are necessarily the singular values of A.

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The matrices U and V are not uniquely determined by A, but the diagonal entries of  $\Sigma$ are necessarily the singular values of A. The columns of U in such a decomposition are called **left singular vectors** of A, and the columns of V are called **right singular vectors** 

## Geometry

The theorem allows to decompose the action of A on a given input vector as a three-step process. To get Ax, where x in  $\mathbb{R}^n$ , we first form  $\tilde{x} := V^Tx$ in  $\mathbb{R}^n$ . Since V is an orthogonal matrix,  $V^T$  is also orthogonal, and  $\tilde{x}$  is just a rotated version of x, which still lies in the input space. Then we act on the rotated vector  $\tilde{x}$  by scaling its elements.

Examples 

Precisely, the first r elements of  $\tilde{x}$  are scaled by the singular values  $\sigma_1, \ldots, \sigma_r$ ; the remaining n-relements are set to zero. This step results in a new vector  $\tilde{y}$  which now belongs to the output space  $\mathbb{R}^m$ . The final step consists in rotating the vector  $\tilde{y}$  by the orthogonal matrix U, which results in  $y = U\tilde{y} = Ax$ .

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Examples

Corollary (EVD in terms of outer poducts). The equation  $A = U\Sigma V^T$  can be written as  $A = \sigma_1 u_1 v_1^T + \dots + \sigma_r u_r v_r^T.$ 

## Step 1. Find the eigenvalues

$$\lambda_1 \ge \cdots \ge \lambda_n \ge 0.$$

Examples

of  $A^T A$ . Put  $\sigma_i = \sqrt{\lambda_i}$  for  $j = 1, \dots, r$  (r the largest index with  $\lambda_i > 0$ ). Take

$$D = \operatorname{diag}(\sigma_1, \ldots, \sigma_n)$$

and extend D to an  $m \times n$  matrix  $\Sigma$  with the block D at its upper left corner, zeros elsewhere. **Step 2.** Find unit eigenvectors  $v_1, \ldots v_n$ corresponding ing to  $\lambda_i$ . Take V to be the  $n \times n$ (orthonormal) matrix with  $v_j$  as its j-th column.

Examples

(orthonormal) matrix with  $v_i$  as its j-th column.

**Step 3.** For  $j = 1, \ldots, r$ , put  $u_j = \frac{1}{\sigma_i} A v_j$ . Then  $\{u_1,\ldots,u_r\}$  is an orthonormal set in  $\mathbb{R}^m$ . Extend it to an orthonormal basis  $\{u_1,\ldots,u_m\}$  of  $\mathbb{R}^m$ . Take U to be the  $m \times m$  orthogonal matrix with  $u_i$  as its j-th column.

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Step 4. Check that

$$U\Sigma V^T = A.$$

Let A be an  $m \times n$  matrix and let  $B = \{v_1, v_2, \dots, v_n\}$  be an orthonormal basis of n consisting of eigenvectors of  $A^TA$ , with corresponding eigenvectors  $\lambda_1, \lambda_2, \dots, \lambda_n$ . Then  $Av_i$  is orthogonal to  $Av_i$  for  $i \neq j$ .

Since B is an orthonormal basis of  $\mathbb{R}^n$ , if  $i \neq j$ , then

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$$= \lambda_j v_i^T v_j$$

$$= 0.$$

## **Examples**

Find the SVD of the matrix:

$$A = \begin{pmatrix} 2 & -2 \\ 1 & 1 \end{pmatrix}.$$

#### Solution.

Step 1. We have

$$A^{T}A = \begin{pmatrix} 2 & 1 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} 2 & -2 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 5 & -3 \\ -3 & 5 \end{pmatrix}.$$

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$$\begin{vmatrix} 5 - \lambda & -3 \\ -3 & 5 - \lambda \end{vmatrix} = (5 - \lambda)^2 - 9.$$

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Clearly, the eigenvalues of  $A^TA$  are 8 and 2. So its singular values are  $\sigma_1 = 2\sqrt{2}$  and  $\sigma_2 = \sqrt{2}$ , and

$$\Sigma = \begin{pmatrix} 2\sqrt{2} & 0\\ 0 & \sqrt{2} \end{pmatrix}.$$

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$$v_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1\\1 \end{pmatrix}.$$

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Thus,

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Thus,

$$U = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}.$$

**Step 4.** Check if we got the SVD of A:

$$U\Sigma V^T = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 2\sqrt{2} & 0 \\ 0 & \sqrt{2} \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} -1 & 1 \\ 1 & 1 \end{pmatrix}$$

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$$= \begin{pmatrix} 2 & -2 \\ 1 & 1 \end{pmatrix}$$
$$= A.$$

## Example (Rectangular matrix):

Find the SVD of the matrix:

$$A = \begin{pmatrix} 1 & -1 \\ -2 & 2 \\ 2 & -2 \end{pmatrix}.$$

Solution.

Step 1. We have

$$A^{T}A = \begin{pmatrix} 1 & -2 & 2 \\ -1 & 2 & -2 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ -2 & 2 \\ 2 & -2 \end{pmatrix} = 9 \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}.$$

Examples

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Clearly, the eigenvalues of B are 2 and 0. So, the eigenvalues of  $A^T A$  are  $\lambda_1 = 18$  and  $\lambda_2 = 0$ .

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So.

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Thus,

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**Step 3.** We now find U. We have

$$u_{1} = \frac{1}{\sigma_{1}} A v_{1}$$

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Examples

$$u_1 \cdot x = 0$$

$$\Rightarrow \frac{1}{3}(1 - 2 \ 2) \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 0$$

$$\Rightarrow x - 2y + 2z = 0.$$

The vectors satisfying the last equation are

$$w_2 = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}, \quad w_3 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}.$$

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Eigenspaces

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Examples

We now use Gram-Schmidt orthonormalisation method. Put

$$u_2 = \frac{1}{\sqrt{5}} \begin{pmatrix} 2\\1\\0 \end{pmatrix}.$$

$$w_3 - (w_3 \cdot u_2)u_2 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} - \frac{1}{5} \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -2/5 \\ 4/5 \\ 1 \end{pmatrix}.$$

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Thus.

$$U=(u_1\ u_2\ u_3).$$

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Thus,

$$U = (u_1 \ u_2 \ u_3).$$

Finally, check that  $U\Sigma V^T = A$ . Step 4.

# Four fundamental subspaces of a matrix

Suppose that A is an  $m \times n$  matrix that maps vectors in  $\mathbb{R}^n$  to vectors in  $\mathbb{R}^m$ .

Four fundamental subs

Suppose that A is an  $m \times n$  matrix that maps vectors in  $\mathbb{R}^n$  to vectors in  $\mathbb{R}^m$ . The four fundamental subspaces of A, two in  $\mathbb{R}^n$  and two in  $\mathbb{R}^m$ , are:

Column space, Row space, Null space, Left null space

Column space of A is the span of the columns of A. In symbols,

$$Col(A) = \{Ax : x \in \mathbb{R}^n\}.$$

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## Row space

**Row space** of A is the span of the rows of A. In symbols,

$$Row(A) = \{A^T y : y \in \mathbb{R}^m\}$$

**Null space** of A is denoted by Null(A) and is defined by

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## Left null space

**Left null space** of A, the set of all y for which  $A^T y = 0$ . In symbols,

$$Null(A^T) = \{ y \in \mathbb{R}^m : A^T y = 0 \}.$$

#### Dimension and rank.

We know that the dimension of a subspace is the number of linearly independent vectors required to span that space.

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## Fundamental Theorem of Linear Algebra

The dimension of the row space is equal to the dimension of the column space.

In other words, the number of linearly independent rows is equal to the number of linearly independent columns. Hence  $\dim \text{Row}(A) = \dim \text{Col}(A).$ 

The rank of a matrix is this number of linearly independent rows or columns.

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The following theorem gives relationships among them.

#### Theorem

Let A be an  $m \times n$  matrix. Then

- $Null(A) = Row(A)^{\perp}.$
- $\mathbf{O}$  Null $(A^T) = \operatorname{Col}(A)^{\perp}$ .

(a) Let A be an  $m \times n$  matrix.

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(a) Let A be an  $m \times n$  matrix. Assume that  $x \in \text{Null}(A)$ . Then Ax = 0. Now, let  $A^T y \in \text{Row}(A)$ . Then  $(A^T y) \cdot x = (A^T y)^T x = (y^T A) x = y^T (Ax) = 0.$ 

Examples

(a) Let A be an  $m \times n$  matrix. Assume that  $x \in \text{Null}(A)$ . Then Ax = 0. Now, let  $A^Ty \in \text{Row}(A)$ . Then

$$(A^T y) \cdot x = (A^T y)^T x = (y^T A) x = y^T (Ax) = 0.$$

Since  $A^T y$  is an arbitrary vector in  $\operatorname{Row}(A)$ ,  $x \perp \operatorname{Row}(A) \Rightarrow x \in \operatorname{Row}(A)^{\perp}$ .

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(a) Let A be an  $m \times n$  matrix. Assume that  $x \in \text{Null}(A)$ . Then Ax = 0. Now, let  $A^T y \in \text{Row}(A)$ . Then  $(A^T y) \cdot x = (A^T y)^T x = (y^T A) x = y^T (Ax) = 0.$ 

Since  $A^T y$  is an arbitrary vector in Row(A),  $x \perp \text{Row}(A) \Rightarrow x \in \text{Row}(A)^{\perp}$ .

Moreover,  $x \in \text{Null}(A)$  is arbitrary. Therefore,  $Null(A) \subseteq Row(A)^{\perp}$ .

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On the other hand, let  $x \in \text{Row}(A)^{\perp}$ . Then for any  $A^T y \in \text{Row}(A)$ , we have

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Examples

Since  $A^T y \in \text{Row}(A)$  is arbitrary, we can choose  $y \neq 0$  and so,  $y^T \neq 0$ . Therefore, we must have Ax = 0

That means,  $x \in \text{Null}(A)$ .

On the other hand, let  $x \in \text{Row}(A)^{\perp}$ . Then for any  $A^T y \in \text{Row}(A)$ , we have

$$0 = (A^{T}y) \cdot x = (A^{T}y)^{T}x = (y^{T}A)x = y^{T}(Ax).$$

Examples

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## Proof...

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Hence

$$Null(A) = Row(A)^{\perp}$$
.

Eigenspaces EVD

(b) Substitute  $A^T$  for A in part (a) and note that  $Row(A^T) = Col(A)$ .

Four fundamental subs

(b) Substitute  $A^T$  for A in part (a) and note that  $Row(A^T) = Col(A)$ .

## Theorem

Eigenspaces

Let A be an  $m \times n$  matrix  $A = U\Sigma V^T$  be any SVD for A where U and V are orthogonal of size  $m \times m$  and  $n \times n$  respectively, and rank A = r.

Also, let

$$\begin{pmatrix} D & 0 \\ 0 & D \end{pmatrix}.$$

where  $D = \operatorname{diag}(\lambda_1, ..., \lambda_r)$  with each  $\lambda_i > 0$ .

Eigenspaces

If  $U = \{u_1 \dots u_r \dots u_m\}$  and  $V = \{v_1 \dots v_r \dots v_n\}$ are orthonormal bases for  $\mathbb{R}^m$  and  $\mathbb{R}^n$ respectively, then

- $\{u_1 \dots u_r\}$  is an orthonormal basis of Col A
- $\{u_{r+1} \dots u_m\}$  is an orthonormal basis of Null  $A^T$
- $\{v_{r+1} \dots v_n\}$  is an orthonormal basis of Null A
- $\{v_1 \dots v_r\}$  is an orthonormal basis of Row A

## Principal Component Analysis

**Qustion:** What does PCA compute and then what is PCA doing with the knowledge of SVD?

Qustion: What does PCA compute and then what is PCA doing with the knowledge of SVD? Consider a real-valued data matrix X that is  $n \times p$  where n is the number of samples and p is the number of features. Its SVD is  $X = U\Sigma V^T$ 

$$X^T X = (U \Sigma V^T)^T (U \Sigma V^T)$$

$$X^{T}X = (U\Sigma V^{T})^{T}(U\Sigma V^{T})$$
$$= V\Sigma^{T}U^{T}U\Sigma V^{T}$$

$$\begin{split} X^T X &= (U \Sigma V^T)^T (U \Sigma V^T) \\ &= V \Sigma^T U^T U \Sigma V^T \\ &= V \Sigma^T \Sigma V^T \end{split}$$

$$X^{T}X = (U\Sigma V^{T})^{T}(U\Sigma V^{T})$$
$$= V\Sigma^{T}U^{T}U\Sigma V^{T}$$
$$= V\Sigma^{T}\Sigma V^{T}$$
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Examples

the context of the SVD decomposition:

$$X^{T}X = (U\Sigma V^{T})^{T}(U\Sigma V^{T})$$
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We already know that V and  $V^T$  are just rotation matrices, while U disappears because  $U^TU = I$ . And even without knowing about eigenvectors or eigenvalues, we can see what PCA is doing by understanding SVD: it is diagonalizing the covariance matrix of X.

Eigenspaces EVD

Now consider the covariance matrix of X, namely  $X^TX$ , in the context of the SVD decomposition:

$$X^{T}X = (U\Sigma V^{T})^{T}(U\Sigma V^{T})$$
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We already know that V and  $V^T$  are just rotation matrices, while U disappears because  $U^TU = I$ . And even without knowing about eigenvectors or eigenvalues, we can see what PCA is doing by understanding SVD: it is diagonalizing the covariance matrix of X. So PCA is finding the major axes along which our data varies.