

# 4 Quadratic Forms II: Symmetric bi-linear functions

Prof.Dr.P.M.Bajracharya

School of Mathematical Sciences

T.U., Kirtipur

April 25, 2024

# Summary

- ① Symmetric bi-linear functions
- ② Change of Variable in a Quadratic Form
- ③ Connections with conic sections

# Symmetric bi-linear functions

- We know that any matrix can be viewed as a representation of a linear transformation with respect to a basis.

- We know that any matrix can be viewed as a representation of a linear transformation with respect to a basis.
- We can also associate to any symmetric matrix something that is known as a **symmetric bilinear transformation**.

Let's start with the definition.

## Symmetric bilinear function

Let  $V$  be a vector space, e.g.,  $\mathbb{R}^2$ . Then a **symmetric bilinear function** on  $V$  is defined as a mapping  $B : V \times V \rightarrow \mathbb{R}$  such that for any  $u, v, w \in V$

$$(a) \quad B(u, v) = B(v, u)$$

$$(b) \quad \forall a, b \in \mathbb{R} \quad B(au + bv, w) = aB(u, w) + bB(v, w).$$

## Remark.

- ① The first condition says that  $B$  is symmetric in its two arguments.
- ② By combining these two conditions we also have that  $B$  is linear in its second argument.

Suppose that  $A$  is an  $n \times n$  matrix. For  $v, w \in \mathbb{R}^n$  we will define the function

$$f(v, w) = v^T A w \in \mathbb{R}.$$



Suppose that  $A$  is an  $n \times n$  matrix. For  $v, w \in \mathbb{R}^n$  we will define the function

$$f(v, w) = v^T A w \in \mathbb{R}.$$

The next two theorems asserts that this is a bilinear form, which might give us a hint to a similarity between this bilinear form and the linear transformations.

## Theorem (Symmetricity)

If  $A$  is a symmetric  $n \times n$  matrix, and  $B_A(v, w) = v^T A w$ , then

$$B_A(v, w) = B_A(w, v).$$

## Proof.

(a) We know that  $v^T Aw \in \mathbb{R}$ . So,  
$$v^T Aw = (v^T Aw)^T.$$

This implies that

$$\begin{aligned} B_A(v, w) &= (v^T Aw)^T \\ &= (Aw)^T v \\ &= w^T A^T v \\ &= w^T Av \quad (\text{because } A \text{ is symmetric}) \\ &= B_A(w, v). \end{aligned}$$



## Theorem (Linearity)

If  $A$  is a symmetric  $n \times n$  matrix and  $B_A(v, w) = v^T A w$ , then  $B_A(v, w)$  is linear in the first variable  $v$ .

**Proof.** For any real number  $a$

$$\begin{aligned}B_A(av, w) &= (av)^T Aw \\&= a(v)^T Aw \\&= a(v^T Aw) \\&= aB_A(v, w).\end{aligned}$$

**Proof...** Also,

$$\begin{aligned}B_A(u + v, w) &= (u + v)^T Aw \\&= (u^T + v^T)Aw \\&= u^T Aw + v^T Aw \\&= B_A(u, w) + B_A(v, w).\end{aligned}$$

Therefore,  $B_A(v, w) = v^T Aw$  is linear in the first variable  $v$ . □

The next theorem claims that a symmetric bilinear function can uniquely be expressed as a product of three matrices.

### Theorem.

If  $B$  is a symmetric bilinear function on  $\mathbb{R}^n$ , then it is of the form  $B = B_A(v, w) = v^T A w$ , for some unique symmetric matrix  $A$ .

**Proof.**

Let  $v = \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}, w = \begin{pmatrix} w_1 \\ \vdots \\ w_n \end{pmatrix} \in \mathbb{R}^n$ . Then we can

write

$$v = \sum_{i=1}^n v_i e_i, \quad w = \sum_{j=1}^n w_j e_j,$$

where  $\{e_1, \dots, e_n\}$  is a basis for  $\mathbb{R}^n$ .



**Proof...** Using the properties of bilinear functions, we have

$$\begin{aligned}
 B(v, w) &= B\left(\sum_{i=1}^n v_i e_i, \sum_{j=1}^n w_j e_j\right) \\
 &= \sum_{i=1}^n v_i \sum_{j=1}^n w_j B(e_i, e_j)
 \end{aligned}$$

# Proof...

$$\begin{aligned}
 B(v, w) &= \sum_{i=1}^n v_i \sum_{j=1}^n B(e_i, e_j) w_j \\
 &= \sum_{i=1}^n v_i \begin{pmatrix} B(e_1, e_1) & \cdots & B(e_1, e_n) \\ \vdots & \vdots & \vdots \\ B(e_n, e_1) & \cdots & B(e_n, e_n) \end{pmatrix} \begin{pmatrix} w_1 \\ \vdots \\ w_n \end{pmatrix}
 \end{aligned}$$

# Proof...

$$\begin{aligned}
 B(v, w) &= \sum_{i=1}^n v_i \sum_{j=1}^n B(e_i, e_j) w_j \\
 &= \sum_{i=1}^n v_i \begin{pmatrix} B(e_1, e_1) & \cdots & B(e_1, e_n) \\ \vdots & \ddots & \vdots \\ B(e_n, e_1) & \cdots & B(e_n, e_n) \end{pmatrix} \begin{pmatrix} w_1 \\ \vdots \\ w_n \end{pmatrix} \\
 &= (v_1 \ \dots \ v_n) \begin{pmatrix} B(e_1, e_1) & \cdots & B(e_1, e_n) \\ \vdots & \ddots & \vdots \\ B(e_n, e_1) & \cdots & B(e_n, e_n) \end{pmatrix} \begin{pmatrix} w_1 \\ \vdots \\ w_n \end{pmatrix}
 \end{aligned}$$

# Proof...

$$\begin{aligned}
 B(v, w) &= \sum_{i=1}^n v_i \sum_{j=1}^n B(e_i, e_j) w_j \\
 &= \sum_{i=1}^n v_i \begin{pmatrix} B(e_1, e_1) & \cdots & B(e_1, e_n) \\ \vdots & \ddots & \vdots \\ B(e_n, e_1) & \cdots & B(e_n, e_n) \end{pmatrix} \begin{pmatrix} w_1 \\ \vdots \\ w_n \end{pmatrix} \\
 &= (v_1 \ \dots \ v_n) \begin{pmatrix} B(e_1, e_1) & \cdots & B(e_1, e_n) \\ \vdots & \ddots & \vdots \\ B(e_n, e_1) & \cdots & B(e_n, e_n) \end{pmatrix} \begin{pmatrix} w_1 \\ \vdots \\ w_n \end{pmatrix}
 \end{aligned}$$

Setting  $A = (B(e_i, e_j))_{n \times n}$ , we have

$$B = v^T A w.$$

**Proof...** To prove the uniqueness of the matrix  $A$ , we assume that there is another matrix  $C$  such that

$$B = v^T C w.$$

**Proof...** To prove the uniqueness of the matrix  $A$ , we assume that there is another matrix  $C$  such that

$$B = v^T C w.$$

Then

$$v^T A w - v^T C w = 0 \Rightarrow v^T (A - C) w = 0$$

**Proof...** To prove the uniqueness of the matrix  $A$ , we assume that there is another matrix  $C$  such that

$$B = v^T C w.$$

Then

$$v^T A w - v^T C w = 0 \Rightarrow v^T (A - C) w = 0$$

Put  $D = A - C$ .

**Proof...** To prove the uniqueness of the matrix  $A$ , we assume that there is another matrix  $C$  such that

$$B = v^T C w.$$

Then

$$v^T A w - v^T C w = 0 \Rightarrow v^T (A - C) w = 0$$

Put  $D = A - C$ . Thus, for any  $v, w \in \mathbb{R}^n$

$$v^T D w = 0.$$



**Proof...** In particular, if we choose  $v, w \in \mathbb{R}^n$  such that  $v_i = w_i = 1$  for all  $i \in \{1, \dots, n\}$ , then we still have

$$v^T D w = 0.$$

**Proof...** In particular, if we choose  $v, w \in \mathbb{R}^n$  such that  $v_i = w_i = 1$  for all  $i \in \{1, \dots, n\}$ , then we still have

$$v^T D w = 0.$$

This implies that

$$\sum_{i=1}^n v_i \sum_{j=1}^n D_{ij} w_j = 0$$

**Proof...** In particular, if we choose  $v, w \in \mathbb{R}^n$  such that  $v_i = w_i = 1$  for all  $i \in \{1, \dots, n\}$ , then we still have

$$v^T D w = 0.$$

This implies that

$$\begin{aligned} \sum_{i=1}^n v_i \sum_{j=1}^n D_{ij} w_j &= 0 \\ \Rightarrow \sum_{i=1}^n \sum_{j=1}^n v_i D_{ij} w_j &= 0. \end{aligned}$$

**Proof...** We now see that  $v_i D_{ij} w_j = D_{ij}$  for all  $i \in \{1, \dots, n\}$ .

**Proof...** We now see that  $v_i D_{ij} w_j = D_{ij}$  for all  $i \in \{1, \dots, n\}$ . Therefore, we must have

$$D_{ij} = 0 \quad \text{for all } i \in \{1, \dots, n\}.$$

**Proof...** We now see that  $v_i D_{ij} w_j = D_{ij}$  for all  $i \in \{1, \dots, n\}$ . Therefore, we must have

$$D_{ij} = 0 \quad \text{for all } i \in \{1, \dots, n\}.$$

That means,

$$D = 0$$

**Proof...** We now see that  $v_i D_{ij} w_j = D_{ij}$  for all  $i \in \{1, \dots, n\}$ . Therefore, we must have

$$D_{ij} = 0 \quad \text{for all } i \in \{1, \dots, n\}.$$

That means,

$$\begin{aligned} D &= 0 \\ \Rightarrow A - C &= 0 \end{aligned}$$

**Proof...** We now see that  $v_i D_{ij} w_j = D_{ij}$  for all  $i \in \{1, \dots, n\}$ . Therefore, we must have

$$D_{ij} = 0 \quad \text{for all } i \in \{1, \dots, n\}.$$

That means,

$$D = 0$$

$$\Rightarrow A - C = 0$$

$$\Rightarrow A = C.$$





# Change of Variable in a Quadratic Form

- In some cases, quadratic forms are easier to use when they have no cross-product terms – that is, when the matrix of the quadratic form is a diagonal matrix.
- Fortunately, the cross-product term can be eliminated by making a suitable change of variable.

If  $x \in \mathbb{R}^n$ , then a change of variable is an equation of the form

$$x = Py, \text{ or equivalently, } y = P^{-1}x,$$

where  $P$  is an invertible matrix and  $y$  is a new variable vector in  $\mathbb{R}^n$ . Here  $y$  is the coordinate vector of  $x$  relative to the basis of  $\mathbb{R}^n$  determined by the columns of  $P$ .

## Example

Consider the quadratic form

$$Q(x) = x_1^2 - 8x_1x_2 - 5x_2^2. \quad (1)$$

1. Determine the matrix  $A$  of Quadratic Form (1).
2. Find the matrix  $V$  of the eigenvectors of  $A$ .
3. Make a change of variable in (1)

$$x = Py, \text{ where } x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \text{ and } y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}.$$

Find (1) in terms of  $y$ .

## Example ...

4. Compute  $Q(x)$  for  $x = (2, -2)$ .
5. Compute  $Q(x)$  for  $x = (2, -2)$  using new variable  $y$ .

**Solution.** The matrix of the quadratic form is

$$A = \begin{pmatrix} 1 & -4 \\ -4 & -5 \end{pmatrix}$$

The first step is to orthogonally diagonalize  $A$ . Its eigenvalues turn out to be  $\lambda = 3$  and  $\lambda = 7$ . Associated unit eigenvectors are

$$\lambda = 3 : \begin{pmatrix} 2/\sqrt{5} \\ -1/\sqrt{5} \end{pmatrix}; \quad \lambda = 7 : \begin{pmatrix} 1/\sqrt{5} \\ 2/\sqrt{5} \end{pmatrix}.$$

These vectors are orthogonal (because they correspond to distinct eigenvalues) and so provide an orthonormal basis for  $\mathbb{R}^2$ .

Let

$$P = \begin{pmatrix} 2/\sqrt{5} & -1/\sqrt{5} \\ 1/\sqrt{5} & 2/\sqrt{5} \end{pmatrix}, \quad D = \begin{pmatrix} 3 & 0 \\ 0 & -7 \end{pmatrix}.$$

Then  $A = PDP^{-1}$  and  $D = P^{-1}AP = P^TAP$ , as pointed out earlier. A suitable change of variable is

$$x = Py, \text{ where } x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \text{ and } y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}.$$

Then

$$\begin{aligned} x_1^2 - 8x_1x_2 - 5x_2^2 &= x^T Ax = (Py)^T A(Py) \\ &= y^T P^T APy = y^T Dy \\ &= 3y_1^2 - 7y_2^2. \end{aligned}$$



To illustrate the meaning of the equality of quadratic forms in Example 4, we can compute  $Q(x)$  for  $x = (2, -2)$  using the new quadratic form. First, since  $x = Py$ ,

$$y = P^{-1}x = P^T x$$

so

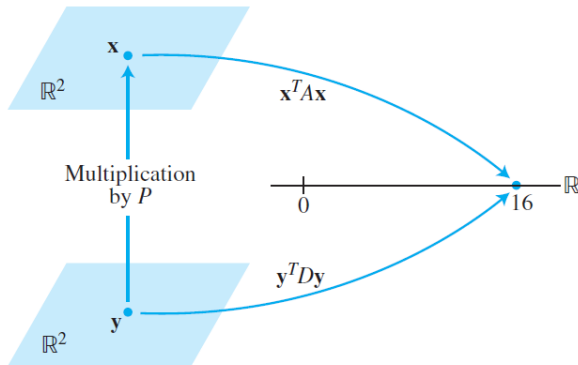
$$y = \begin{pmatrix} 2/\sqrt{5} & -1/\sqrt{5} \\ 1/\sqrt{5} & 2/\sqrt{5} \end{pmatrix} \begin{pmatrix} 2 \\ -2 \end{pmatrix} = \begin{pmatrix} 6/\sqrt{5} \\ -2/\sqrt{5} \end{pmatrix}$$

Hence

$$\begin{aligned} 3y_1^2 - 7y_2^2 &= 3(6/\sqrt{5})_1^2 - 7(-2/\sqrt{5})^2 \\ &= 3(36/5) - 7(4/5) \\ &= 80/5 = 16. \end{aligned}$$



This is the value of  $Q(x)$  in Example 3 when  $x = (2, -2)$ . See Figure



**Figure:** Change of variable in  $x^T A x$ .

From the previous discussion, we can rewrite the above example as follows:

## Example

- Make a change of variable that transforms the quadratic form

$$Q(x) = x_1^2 - 8x_1x_2 - 5x_2^2$$

into a quadratic form with no cross-product term.

- Compute  $Q(x)$  for  $x = (2, -2)$ .
- Compute  $Q(x)$  for  $x = (2, -2)$  using new variable  $y$ .

We can now state the theorem on the change of variable in a quadratic form.

## The Principal Axes Theorem

Let  $A$  be an  $n \times n$  symmetric matrix. Then there is an orthogonal matrix  $P$  such that the mapping defined by

$$x = Py$$

transforms the quadratic form  $x^T Ax$  into a quadratic form  $y^T Dy$  with no cross-product term.

The columns of  $P$  in the theorem are called the **principal axes** of the quadratic form  $x^T Ax$ . The vector  $y$  is the coordinate vector of  $x$  relative to the orthonormal basis of  $\mathbb{R}^n$  given by these principal axes.

**Proof.** Let  $A$  be an  $n \times n$  symmetric matrix. Then by the spectral theorem there is an orthogonal matrix  $P$  of eigenvectors of  $A$ . such that

$$P^T A P = \Lambda,$$

where  $\Lambda$  is the diagonal matrix of eigenvalues of  $A$ . Since  $P$  is orthogonal,

$$P^{-1} = P^T.$$

**Proof...** Put

$$x = Py.$$

Then

$$\begin{aligned} x^T A x &= (Py)^T A (Py) \\ &= y^T P^T A P y \\ &= y^T (P^T A P) y \\ &= y^T \Lambda y. \end{aligned}$$

Since  $\Lambda$  is a diagonal matrix, the quadratic form  $y^T \Lambda y$  does not contain cross-product terms.  $\square$