

%----- Matlab command window – commands to be entered :
%----- (for the first four questions from Matlab tutorial sheet and block diagram reduction (Tut1 %-
%----- problem a)

clc;
clear all;

%----- for differential equation solution-----

syms x
x= dsolve ('D2x=-5*Dx-3*x+7', 'x(0)=0', 'Dx(0)=1')

%----- residues poles -----

% for residues poles pf expansion: inverse Laplace transform

syms s
num = [5 7 8 30];
den = [1 15 62 85 25];
[r,p,k]=residue(num,den)

% -----for laplace transform-----

syms t u
f=7*heaviside(t)+5*exp(-3*t);
F=laplace(f)
pretty (F)

% -----for inverse laplace transform-----

syms s t u

F=7/(s^2+3*s+2);

%F=5/(s + 3) + (7*u)/s^2;

f=ilaplace(F)

%-----pole zero plot from tf-----

num = [5 7 8 30];

den = [1 15 62 85 25];

sys=tf(num,den)

p=pole(sys)

z=zero(sys)

pzmap(sys)

[z,p,k] = tf2zp(num,den)

%----- tf from pole zero-----

z = [1 0]'; %should be a column vector

%p = roots([1 0.01 1]);

p=[3 4];

k = 10;

[num,den] = zp2tf(z,p,k)

sys=tf(num,den)

pzmap(sys)

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%----- block diagram reduction -----
%----- ( for Tut 1 problem (a) )-----

clc;
syms g1 g2 g3 g4 h1 h2 h3;
M=[ 1  0  0  0  0  0 -h1  0  0  0  0  0;

    1  1  0  0  0  0  0  0  0  0  0 -1;

    0 -g1 1  0  0  0  0  0  0  0  0  0;

    0  0  0  1  0  0  0  0 -h3  0  0;

    0  0 -1 -1  1  0  0  0  0  0  0;

    0  0  0  0 -g2 1  0  0  0  0  0;

    0  0  0  0  0 -1  1  1  0  0  0;

    0  0  0  0  0  0  0  1  0 -h2  0;

    0  0  0  0  0  0 -g3  0  1  0  0;

    0  0  0  0  0  0  0  0 -g4  1  0];

N=rref(M);
Sol = - N(10,11)

```