

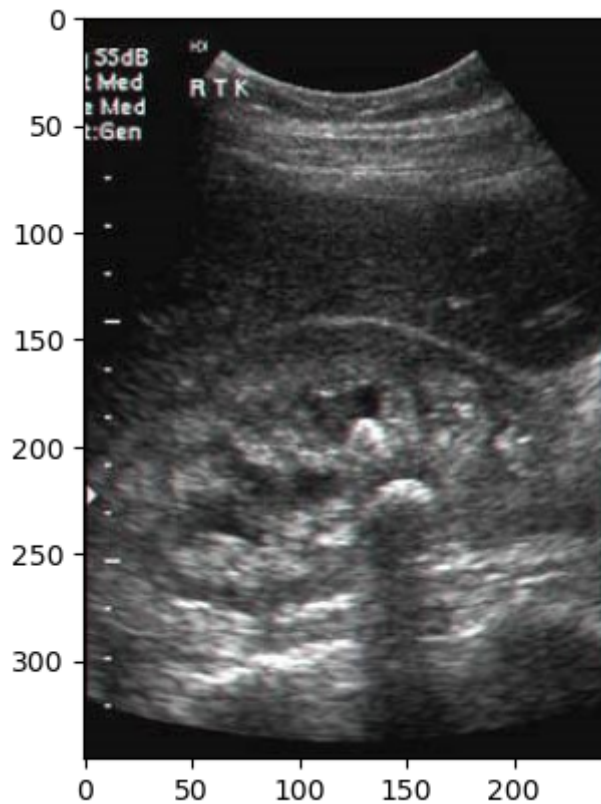
Kidney Stone Detection using Image Processing techniques like Gabor Filter, Histogram Equalization, Image Segmentation

```
In [15]: #Importing the required packages
import cv2
import argparse
import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline
from matplotlib import image as mpimg
```

```
In [19]: #Loading the Images
s = r'C:\Users\prabh\Desktop\Prabhath Personel\Digital Assignments\6th SEM\IVA PJ\Images'
image_no = '\image1.jpg'
s = s + image_no

img = cv2.imread(s,0)

image = mpimg.imread("C:/Users/prabh/Desktop/Prabhath Personel/Digital Assignments/6th SEM/IVA PJ/Images/image1.jpg")
plt.imshow(image)
plt.show()
```



```
In [8]: def build_filters():
#returns a list of kernels in several orientations
filters = []
ksize = 31
for theta in np.arange(0, np.pi, np.pi / 32):
    params = {'ksize': (ksize, ksize), 'sigma': 0.0225, 'theta': theta, 'lambda': 15.0,
              'gamma': 0.01, 'psi': 0, 'ktype': cv2.CV_32F}

    kern = cv2.getGaborKernel(**params)
    kern /= 1.5*kern.sum()
    filters.append((kern, params))
return filters

def process(img, filters):
#returns the img filtered by the filter list
accum = np.zeros_like(img)
for kern, params in filters:
```

```
fimg = cv2.filter2D(img, cv2.CV_8UC3, kern)
np.maximum(accum, fimg, accum)
return accum
```

```
In [9]: #Histogram Equalization
def Histeq(img):
    equ = cv2.equalizeHist(img)
    return equ
```

```
In [10]: #Gabor Filter
def GaborFilter(img):
    filters = build_filters()
    p = process(img, filters)
    return p
```

```
In [11]: #Laplacian Filter
def Laplacian(img,par):
    lap = cv2.Laplacian(img,cv2.CV_64F)
    sharp = img - par*lap
    sharp = np.uint8(cv2.normalize(sharp, None, 0 , 255, cv2.NORM_MINMAX))
    return sharp
```

```
In [12]: #Image Segmentation(Watersheds)
def Watershed(img):
    ret, thresh = cv2.threshold(img,0,255,cv2.THRESH_BINARY+cv2.THRESH_OTSU)

    # noise removal
    kernel = np.ones((3,3),np.uint8)
    opening = cv2.morphologyEx(thresh,cv2.MORPH_OPEN,kernel, iterations = 2)

    # sure background area
    sure_bg = cv2.dilate(opening,kernel,iterations=3)

    # Finding sure foreground area
    dist_transform = cv2.distanceTransform(opening,cv2.DIST_L2,5)
    ret, sure_fg = cv2.threshold(dist_transform,0.23*dist_transform.max(),255,0)

    # Finding unknown region
    sure_fg = np.uint8(sure_fg)
    unknown = cv2.subtract(sure_bg,sure_fg)

    # Marker Labelling
```

```

ret, markers = cv2.connectedComponents(sure_fg)

# Add one to all labels so that sure background is not 0, but 1
markers = markers+1

# Now, mark the region of unknown with zero
markers[unknown==255] = 0

img2 = cv2.imread(s,1)
img2 = cv2.medianBlur(img2,5)
markers = cv2.watershed(img2,markers)
img2[markers == -1] = [255,0,0]

return img2

if image_no=='\image1.jpg':
    img3 = Laplacian(img,0.239)

elif image_no=='\image2.jpg':
    img3 = GaborFilter(img)
    img3 = Histeq(img3)

elif image_no=='\image4.jpg':
    img3 = GaborFilter(img)

img3 = Watershed(img)

plt.imshow(img3,'gray')
plt.title('Marked')
plt.xticks([],plt.yticks([]))

```

Out[12]: (([], []), ([], []))

Marked

