# Introduction to General Relativity

AMATH 475

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## **Preface**

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## **Pre-Math**

### 0.1 Index notation

$$A = \begin{pmatrix} A^{1}_{1} & A^{1}_{2} \\ A^{2}_{1} & A^{2}_{2} \end{pmatrix} \qquad B = \begin{pmatrix} B^{1}_{1} & B^{1}_{2} \\ B^{2}_{1} & B^{2}_{2} \end{pmatrix}$$

$$(A \cdot B)^a{}_b = A^a{}_c B^c{}_b = B^c{}_b A^a{}_c$$
 sum over all possible  $c$ 

Identify followings:

$$\begin{split} B_{\kappa}{}^{\nu}A_{\mu}{}^{\kappa} &= A_{\mu}{}^{\kappa}B_{\kappa}{}^{\nu} = C_{\mu}{}^{\nu} = (A \cdot B)_{\mu}{}^{\nu} \\ A^{\kappa}{}_{\mu}B_{\kappa}{}^{\nu} &= D_{\mu}{}^{\nu} = (A^{T})_{\mu}{}^{\kappa}B_{\kappa}{}^{\nu} = (A^{T} \cdot B)_{\mu}{}^{\kappa} \\ A_{\kappa}{}^{\nu}B_{\mu}{}^{\kappa} &= E_{\mu}{}^{\nu} = (B \cdot A)_{\mu}{}^{\nu} \\ A^{\kappa}{}_{\mu}B^{\nu}{}_{\kappa} &= (A^{T})_{\mu}{}^{\kappa}(B^{T})_{\kappa}{}^{\nu} = \left((B \cdot A)^{T}\right)_{\mu}{}^{\nu} \end{split}$$

$$\mathbf{v} = v^1 \mathbf{e}_1 + v^2 \mathbf{e}_2$$
 { $\mathbf{e}_1, \mathbf{e}_2$ } Basis 1.

$$\mathbf{v} = v^a \mathbf{e}_a = v'^a \mathbf{e}_a'$$
  $\{\mathbf{e}_1', \mathbf{e}_2'\}$  Basis 2.

Change of basis matrix  $\Lambda$ 

$$\mathbf{e}'_a = \Lambda_a{}^b \mathbf{e}_b$$
$$v'^a = \tilde{\Lambda}^a{}_b v^b$$

$$v^{a}\mathbf{e}_{a} = v'^{a}\mathbf{e}'_{a}$$

$$= \tilde{\Lambda}^{a}{}_{b}v^{b}\Lambda_{a}{}^{c}\mathbf{e}_{c}$$

$$= \tilde{\Lambda}^{a}{}_{b}\Lambda_{a}{}^{c}v^{b}\mathbf{e}_{c}$$

$$= \underbrace{\left(\tilde{\Lambda}^{T}\right)_{b}^{a}\Lambda_{a}{}^{c}}_{\delta_{b}^{c}}v^{b}\mathbf{e}_{c}$$

$$= v^{b}\mathbf{e}_{b}$$

$$\Longrightarrow \left(\tilde{\Lambda}^{T}\right)_{b}^{a}\Lambda_{a}{}^{c} = \delta_{b}^{c}$$

$$\tilde{\Lambda}^{T} \cdot \Lambda = \mathbb{1}$$

 $\tilde{\Lambda}^T$  is the inverse transpose of  $\Lambda$ 

### covariant and contravariant object

A covariant object is an object that under change of basis transforms like the elements of a basis.  $\Lambda$ . (sub-indices)

A contravariant object transforms like components of vectors.  $(\tilde{\Lambda} = (\Lambda^T)^{-1})$ . (super-indices)

### 0.2 Vectors and one-forms

#### dual vector space

Let V be a vector space. A one-form is a linear map  $\omega: V \to \mathbb{R}$ .

The set of all one-forms on V (call  $V^*$ ) is a vector space as well called the dual vector space to V.

#### dual basis

Let  $\{\Upsilon_1, \Upsilon_2, \ldots\}$  (or  $\{\Upsilon_i\}$ ) be a basis of V so that any  $\mathbf{v} \in V$  can be written as  $\mathbf{v} = v^i \Upsilon_i$ .

We define the dual basis (of  $V^*$ ) to  $\{\Upsilon_i\}$  as  $\{\omega^i\}$  such that  $\omega^i(\Upsilon_j) = \delta_i^i$ .

### Proposition 0.1

The dual basis of  $V^*$  is actually a basis of  $V^*$ .

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