

# Sahib Singh Dhanjal

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## Education

MS: Robotics, Automation and Mechatronics (GPA - 3.7/4.0) - University of Michigan, Ann Arbor

Sep '17 – Present

B.E(Hons): Mechanical Engineering (GPA – 9.05 /10) (Ranked top 10 in batch) – BITS, Pilani (#5 in India)

Aug '12 – Jun '16

## Skills

Languages: Python, C/C++, JavaScript (Proficient); MATLAB, Java, HTML, CSS, Latex (working knowledge)

Technologies: Git, Machine Learning (ConvNetJS, SciKit, TensorFlow, Keras), Robot Operating System (Indigo, Hydro), OpenCV

Software: Solidworks, ANSYS, Fritzing, Adobe Creative Suite, Microsoft Office Suite, Processing

Fabrication: Skilled in mechanical design, fabrication and prototyping. Comfortable in circuit design and testing procedures.  
Strong implementation skills (have solved 400+ problems on various online judges)

## Work Experience

ExxonMobil Chemicals | Sales Assistant – South Asia

Jun '16 – Jul '17

- Handled India and subcontinent operations for EM's largest global distributor. Managed portfolio of 12 customers
- Implemented custom dashboard which led to increase in sales performance by 15% and the analytics efficiency by 65%

PEPL Lab, University of Michigan | Search Engine Optimization

Oct '17 – Nov '17

TATA Steel | Quality Control Intern

May '14 – Jul '14

## Projects

SLAM in autonomous maritime systems

Jan'17 – Current

- SLAM stack being implemented on top of ROS Hydro for the RobotX Competition held in Dec '18
- Sensor fusion algorithm being implemented for Velodyne VLP-16, Ladybug-5 and GPS/IMU module based on open-source Apollo library
- Keywords – SLAM, Path Planning, Sensor Fusion, ROS

Robot Kinematics Simulator and Motion Planner

Sep '17 – Dec '17

- Forward kinematics using matrix stack & DH convention implemented based on URDF structure of the robot (model for Fetch available)
- Inverse Kinematics simulated using cyclic coordinate descent and gradient descent using manipulator jacobian implemented
- RRT/ RRT-Connect/ RRT-Star planner implemented for high dimensional motion/ trajectory planning
- Keywords – Serial Manipulation, Trajectory Planning, Simulator, Fetch

SLAM and autonomous exploration in differential drive robot

Oct '17 – Dec '17

- Implemented the occupancy grid mapping algorithm, action model, sensor model, and particle filter for SLAM (in C/C++)
- Implemented Yamauchi's autonomous exploration algorithm on the robot
- Localization results within 5% accuracy of the ground truth. Keywords – SLAM, LiDAR, Mapping, Localization

Vision based autonomous 4-DOF dynamixel robotic manipulator

Sep '17 – Oct '17

- Developed a block detection system in OpenCV on images and depth-maps streamed from an overhead Microsoft Kinect
- Processed data was used to manipulate a 4-DOF dynamixel arm autonomously to complete tasks such as block stacking based on color and building 5-level pyramids. Keywords – OpenCV, Kinect, LCM, serial manipulation, Object Detection

Path planning and multi-robot autonomous exploration on Turtlebot

Dec'15 – May '16

- Path Planning / Navigation stack developed for Turtlebot on ROS Indigo
- Python simulator developed for simulation of multi-robot autonomous exploration and path planning algorithms
- Simulation of autonomous multi-robot exploration in Gazebo. Project was sponsored by DRDO, India
- Keywords – ROS, navigation, exploration, multi-robot, path planning, A\*, JPS, Yamauchi, Burgard exploration

Formula Student – FSAE Italy

Oct '12 – Sep '14

- Responsible for design and fabrication of a suspension package for a formula student prototype
- Worked on bell crank geometry, double wishbone suspension design, dynamic roll center migration, spring and roll rates for the car, anti-dive and anti-squat parameters for the car
- Team achieved a global 8<sup>th</sup> place in Design out of 47 teams in FSAE Italy '14
- Keywords – Suspension design, SolidWorks, ANSYS

### Gesture controlled robotic arm

Oct '14 – Dec '14

- Gesture controlled 4-DOF serial manipulator fabricated to augment human capability
- The arm was controlled using 2 Arduino UNOs, IMUs for gesture tracking and an XBee module for wireless communication

### Design/ fabrication of an autonomous white-board cleaner

May '15 – Jun '15

- Autonomous serial manipulator fabricated which was capable of wiping boards of numerous sizes
- Research paper on this work presented at IEEE UPCON '15

### SVM based Spam-Mail Classifier

Oct '15 – Dec '15

- Spam mail classifier based on Support Vector Machine modeled in MATLAB with accuracy in classification of 96.3%

## Coursework

**Graduate/ Undergraduate:** Design & Analysis of Algorithms, Computer Vision, Mobile Robotics, Machine Learning, Robot Kinematics & Dynamics

**Online/ Self:** Deep Learning, Self-Driving Cars, Data Structures and Algorithms, Intro to Networks, Artificial Intelligence for Robotics

## Positions of Responsibility

- *CoStAA (Techfest Coordinator)*, APOGEE'15, Annual tech fest of BITS Pilani
- *Festival Coordinator*, Aarohan'15, an outreach initiative by BITS Pilani
- *Department Coordinator*, Department of Visual Media, BITS Pilani
- *Marketing Head*, Inspired Karters, BITS Pilani
- *Vehicle Dynamics Head*, Inspired Karters, BITS Pilani

## Achievements

- Placed 8<sup>th</sup> in ACM ICPC Amritapuri Regional '13 and 12<sup>th</sup> in ACM ICPC Calcutta Regional '14
- AIR# 6350 out of 1,500,000 applicants in IIT-JEE 2012, India's most competitive engineering exam (~2% acceptance rate)
- Won Track-O-Mania (a line following bot competition), iStrike (Vision based autonomous bot competition), APOGEE '14
- Won Junkyard Wars, APOGEE '15
- Won iBOSM '14 soccer and volleyball tournament and represented East Singhbhum district soccer team
- Cleared Regional Maths Olympiad 2010

## Extra - Curricular

- Taught Robotics, Algorithms, and Mechanical Engineering on Chegg Tutors
  - Front-end developer for main-site APOGEE'15
  - Webmaster for APOGEE'15 and Aarohan'15
  - Lead web-developer for the Formula Student team - Inspired Karters, BITS Pilani
  - Animator and web-designer, Department of Visual Media, BITS Pilani
  - 2<sup>nd</sup> in BITS Premiere Soccer League
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