

PSB1

Given: 2 "mystery" bodies rotating about a primary center
in 5:2 ratio

Take Jupiter with asteroid A and C in same plane
relative to Sun.

- Find:
- Jupiter is circular orbit, 5.2 AU. A is in short period 3:2 resonance. Let C be circular in long period 3:4 resonance. Determine P_A , P_C of all 3 bodies.
 - Define initial time and plot bodies. Mark location of A and C at time when Jupiter $t = nP_J$ $n = 0, 0.15, 0.5, 0.75, \dots$. Mark motion of each body.
 - Define rotating frame for Jupiter. Identify Sun as origin. Develop transformation matrix. Plot A and C in rotating frame from mark A and C the same time as (b).
 - redo (b) and (c) and assume eccentricity of $e = 0.2, 0.3, 0.4$. Initial time A and C at perihelion. Mark perihelion and apocenter in rotating frame. Are resonances interior or exterior?
 - Assume perihelia 180 degrees out of phase. Repeat plots. Does relative perihelia change the motion. What conditions does A and C pass closest; are bodies located when this pass occurs?
 - Try some higher order resonances and some higher e ?

Solution:

$$a) \frac{P_A}{P_J} = \frac{P_J}{P_C} = \sqrt{\frac{a_J^3}{a_C^3}} = \frac{3}{2} \quad \therefore a_A^3 = \frac{4a_J^3}{9}$$

$$\text{Note } a_J = 7.7834 \times 10^9$$

$$\therefore \frac{a_A^3}{a_J^3} = \frac{9}{16} \quad \therefore a_A^3 = \frac{16a_J^3}{9}$$

$$P_A = \frac{2\pi}{\sqrt{M/a_A^3}} = 3.7421 \times 10^8 \text{ s}$$

$$= 11.8662 \text{ years}$$

$$P_C = \frac{2\pi}{\sqrt{M/a_C^3}} = 2.4947 \times 10^8 \text{ s}$$

$$= 7.9108 \text{ years}$$

$$P_C = \frac{2\pi}{\sqrt{M/a_C^3}} = 4.9895 \times 10^8 \text{ s}$$

$$= 15.8216 \text{ years}$$

Continued...

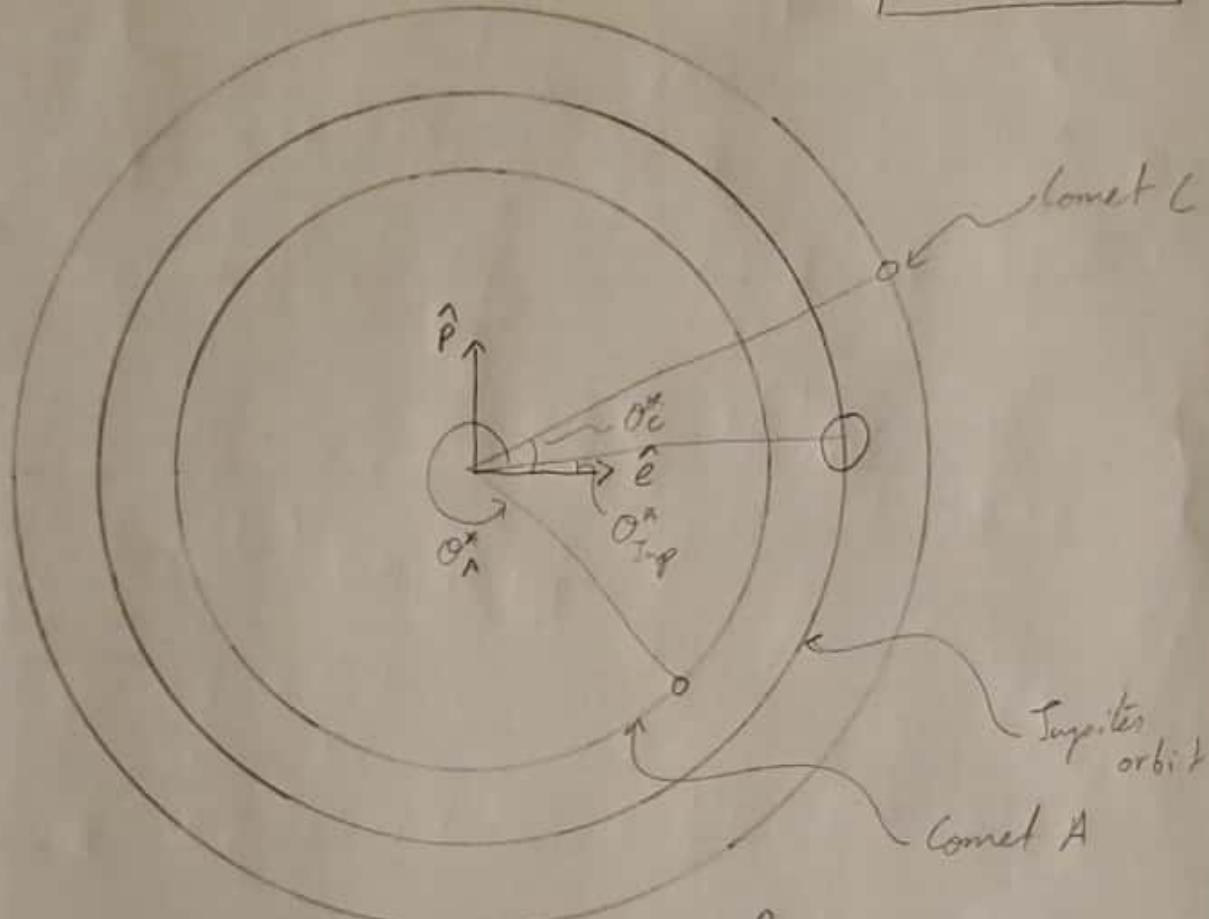
$$n = \sqrt{\frac{M}{a_3}}$$

$$\therefore n_A = \boxed{2.5186 \times 10^{-8} \frac{1}{s}}$$

$$n_c = \boxed{1.2593 \times 10^{-8} \frac{1}{s}}$$

$$n_J = \boxed{1.6790 \times 10^{-8} \frac{1}{s}}$$

6)



Steps: $t = nP \Rightarrow n(t - t_p)^\circ = E - e \sin E = m$

once you have $E = n(t - t_p) = m$

Now you can find θ^* $\tan \frac{\theta^*}{2} = \left(\frac{1+e}{1-e} \right)^{\frac{1}{2}} \tan \left(\frac{E}{2} \right)$

$$\therefore \tan \left(\frac{\theta^*}{2} \right) = \tan \left(\frac{E}{2} \right)$$

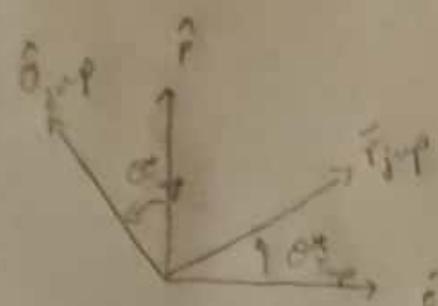
$$\therefore \theta^* = E$$

See plots ahead Figure 1

Satellite Problem

Continued

c) Inertial frame $\hat{e}_r, \hat{e}_{\theta}, \hat{e}_{\phi}$ and Jupiter frame $\hat{e}_{J^3}, \hat{e}_{J^2}, \hat{e}_{J^1}$



$$C^{I^3} = \begin{bmatrix} \cos \theta_{J^3} & \sin \theta_{J^3} \\ \sin \theta_{J^3} & \cos \theta_{J^3} \end{bmatrix}$$

[See plot Figure 2]

d) Steps for inertial frame

$$i) t = n P \Rightarrow n(t - k_p) = E - e \sin E = M$$

ii) Once we have E or eccentric anomaly we can find true anomaly

$$iii) \tan\left(\frac{\Omega}{2}\right) = \left(\frac{1+e}{1-e}\right)^{1/2} \tan\left(\frac{E}{2}\right)$$

$$iv) r = \frac{a(1-e^2)}{1+e \cos \Omega} \text{ or radial distance in Inertial frame}$$

$$v) \vec{r}^I = [r \cos \Omega^* \hat{e}_r + r \sin \Omega^* \hat{e}_\theta] \text{ or } [\text{See plot Figures 3, 5, 7}]$$

Repeat for Jupiter ($e=0$), Asteroid A, Comet C

Steps for rotating frame

follow till step (5) as in previous one

then

$$\vec{r}^I = C^{II} \vec{r}^I \text{ or } [\text{See plots Figure 4, 6, 8}]$$

Note Ω^* in C^{II} is Ω^* in O_{Jupiter}^*

Loops on the outside for 3:2 is the Interior resonance and
the loops inside for 3:6 is the Exterior resonance

Continued...

Out of Phase 180°

Same steps as in phase but for comet and asteroid add $180^\circ + \theta^*$ into step (4)

$$\begin{aligned} \therefore 4) \quad r = \frac{a(1-e^2)}{1+\cos(180+\theta^*)} &= \frac{a(1-e^2)}{1+\cos(180)\cos(\theta^*)-\sin(180)\sin(\theta^*)} \\ &= \frac{a(1-e^2)}{1-\cos(\theta^*)} \end{aligned}$$

See plots Figures 9, 11, 13

Out of phase rotating

Same procedure as out of phase but add in the rotation matrix

$$\bar{r}^I = C^{II} \bar{r}^I \quad \leftarrow \quad \boxed{\text{See plots Figures 10, 12, 14}}$$

The relative shape of the orbit in the rotating frame does not change. It is just rotated by 180° .

Note, the apocenter is now near Jupiter so Jupiter has a longer time to influence the orbit. Which may affect our assumptions and the model.

A and C are closest near their respective pericentres. The two bodies do not always align at this point but they would align every 4th orbit of C.

- (e) For higher eccentricities I tried 0.6 and 0.9
With resonance of A $\Rightarrow 4:5$ and C $\Rightarrow 5:7$; and A $\Rightarrow 5:3$ and C $\Rightarrow 7:4$

With higher eccentricities the orbit paths overlay each other. Thus influencing each other. This may make system unstable.
See plots ahead

Problem B1

Part (b)

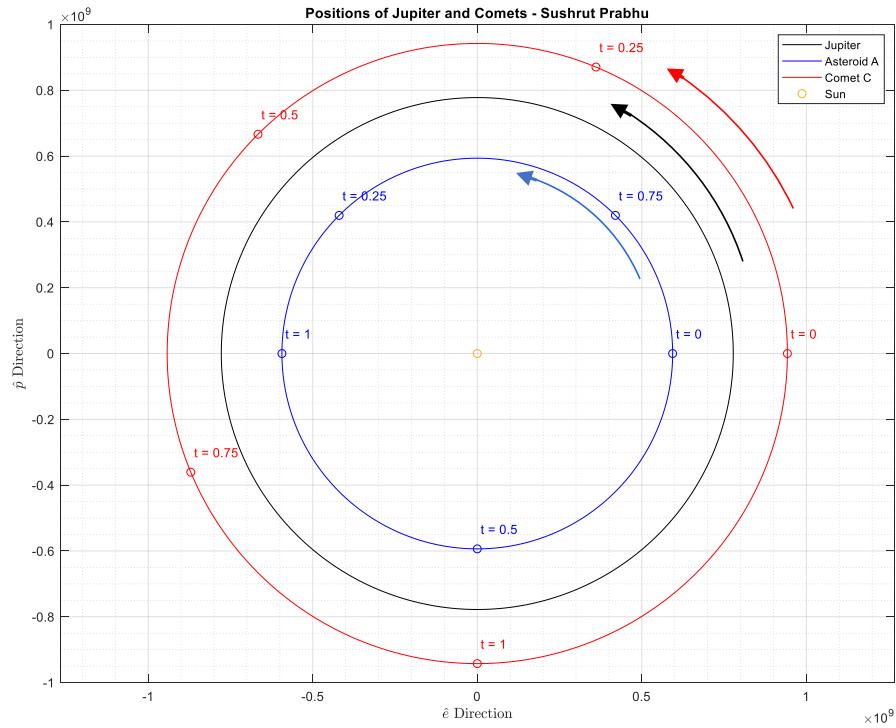


Figure 1: Circular orbit around the Sun in the inertial frame.

Part (c)

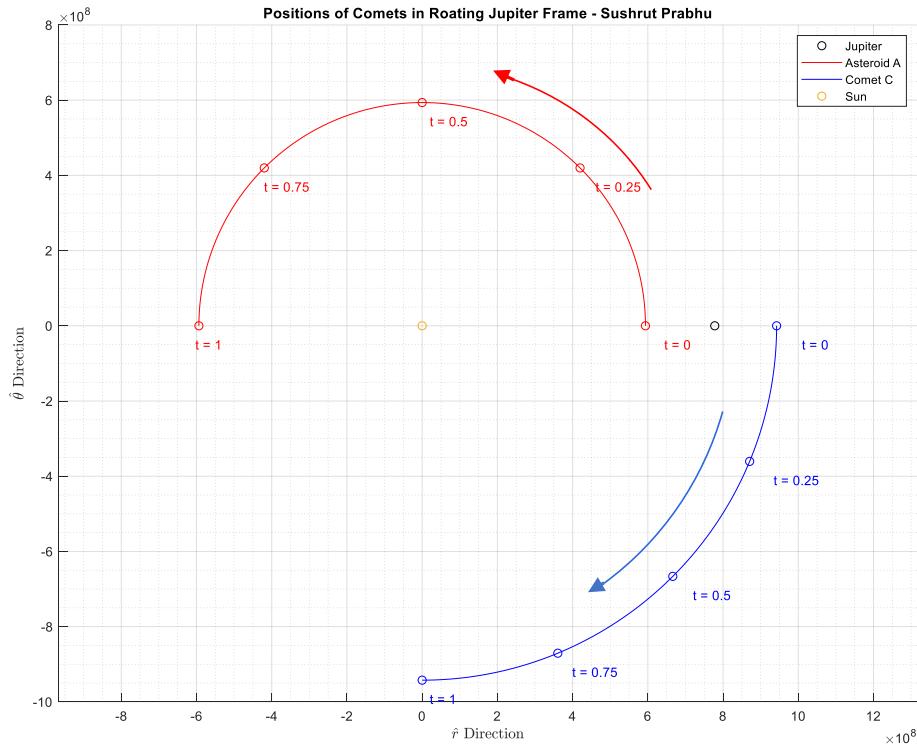


Figure 2: Circular orbit around Sun from Jupiter's rotating frame.

Part (d i)

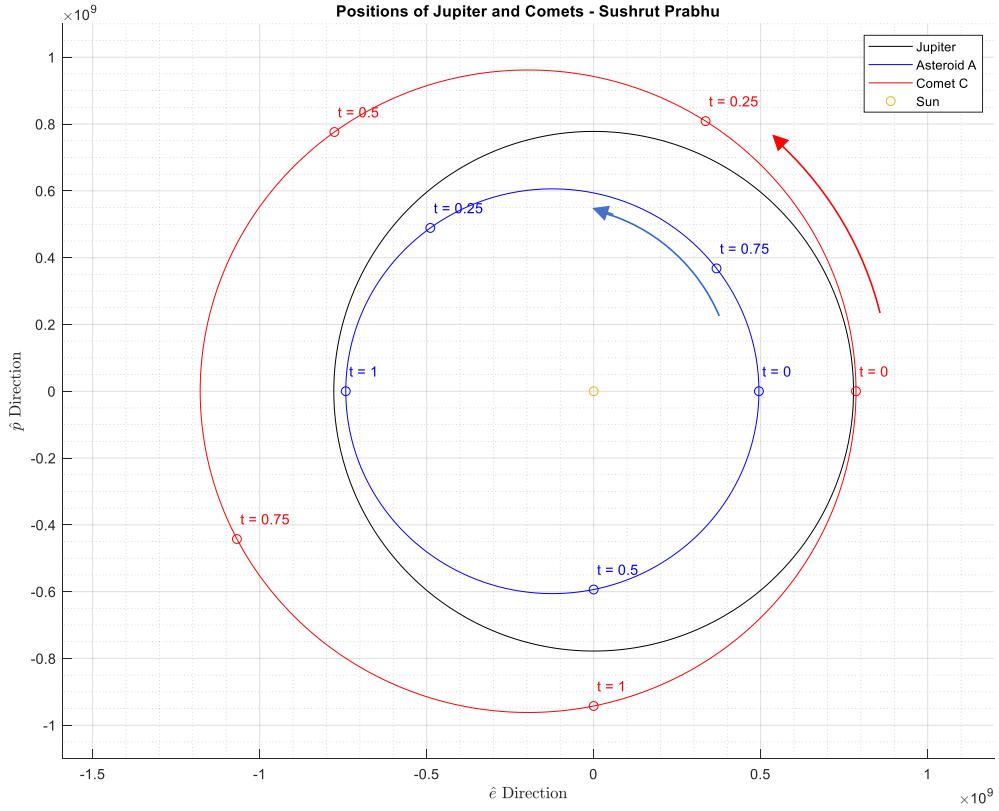


Figure 3: Eccentric orbit of 0.2 for asteroid and comet in the inertial frame.

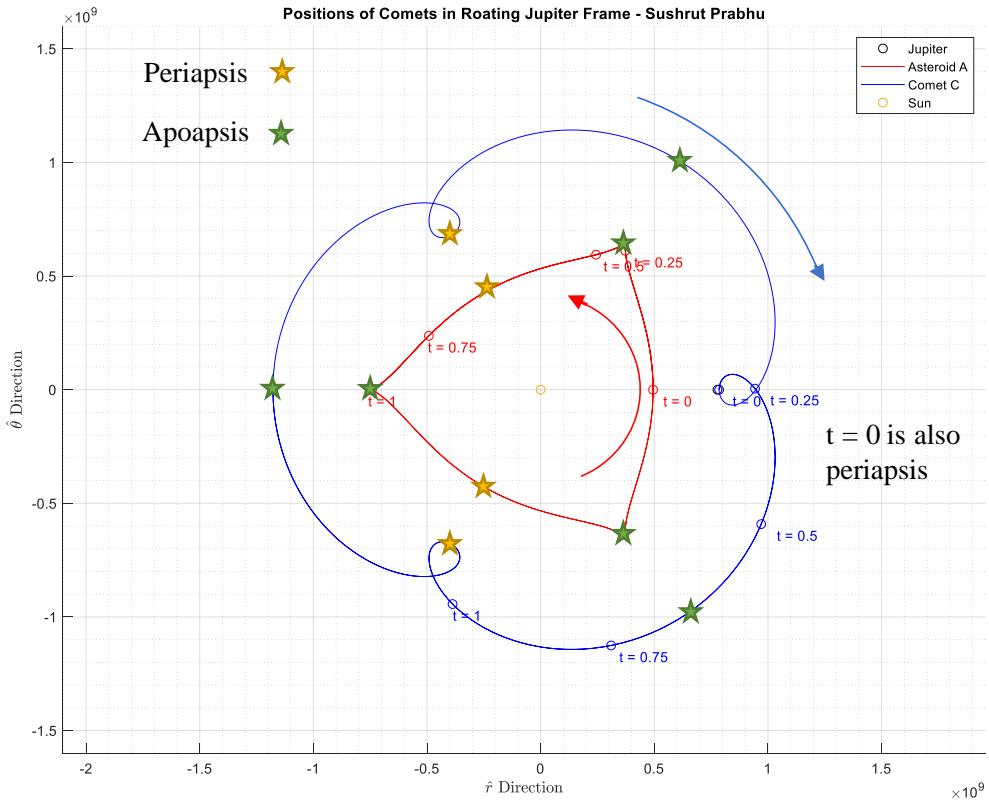


Figure 4: Eccentric orbit of 0.2 for asteroid and comet in the rotating Jupiter frame.

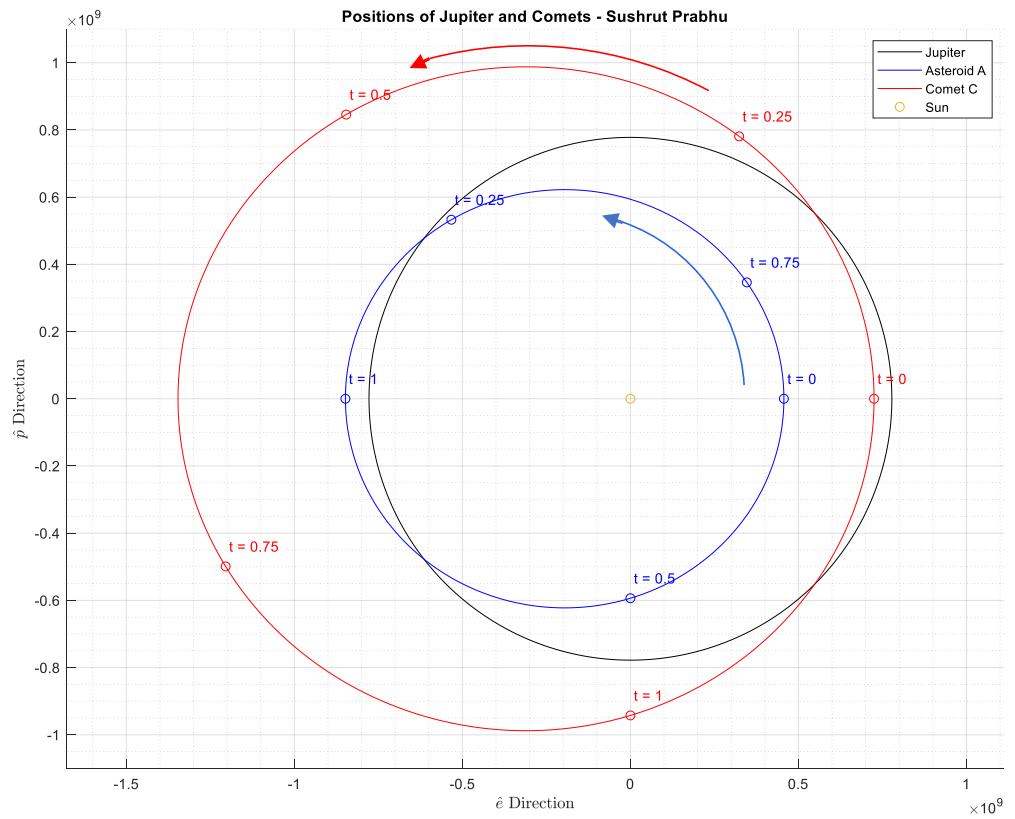


Figure 5: Eccentric orbit of 0.3 for asteroid and comet in the inertial frame.

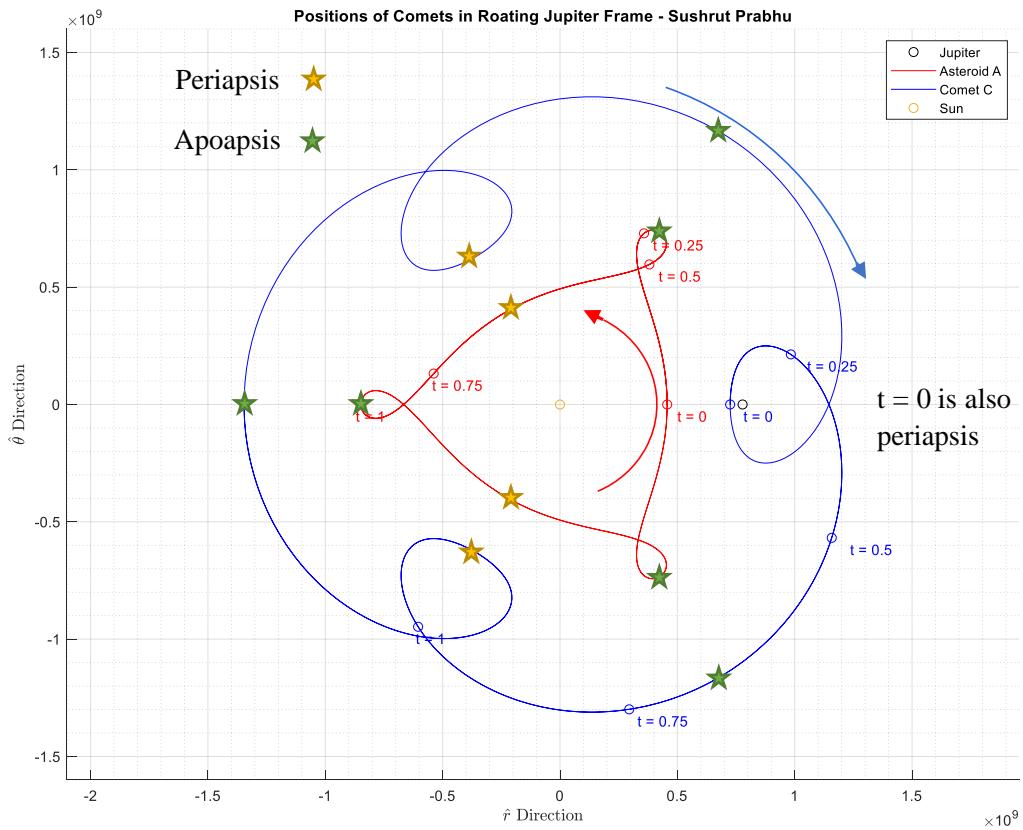


Figure 6: Eccentric orbit of 0.3 for asteroid and comet in the rotating Jupiter frame.

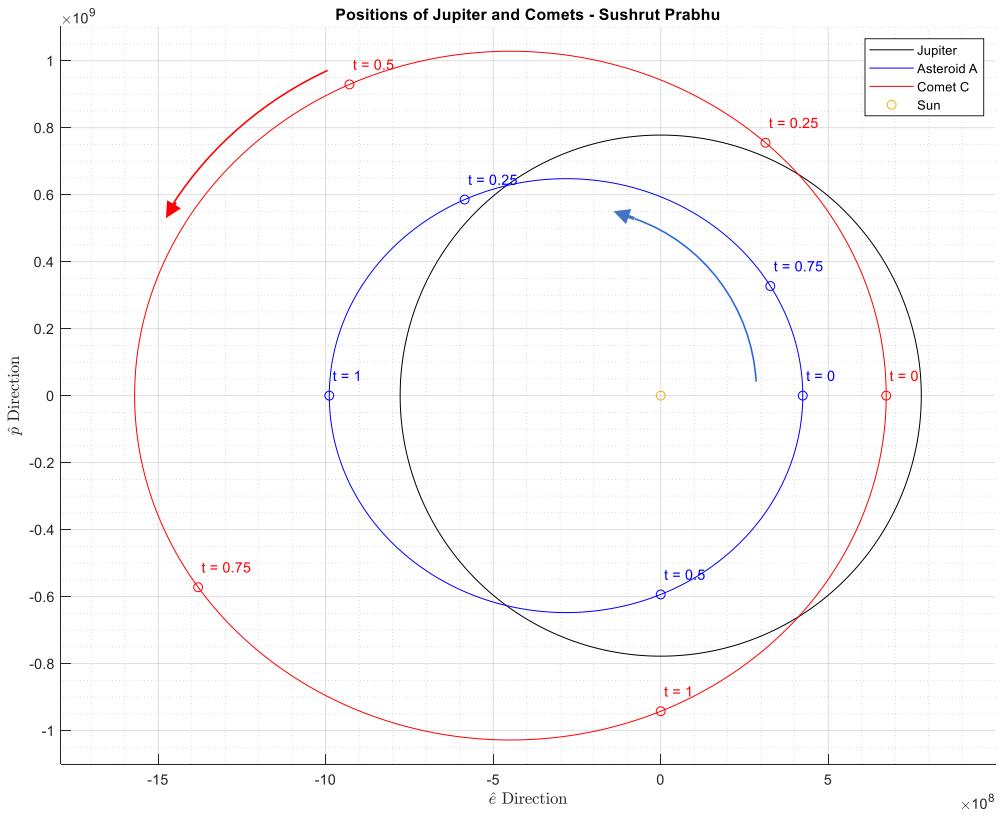


Figure 7: Eccentric orbit of 0.4 for asteroid and comet in the inertial frame.

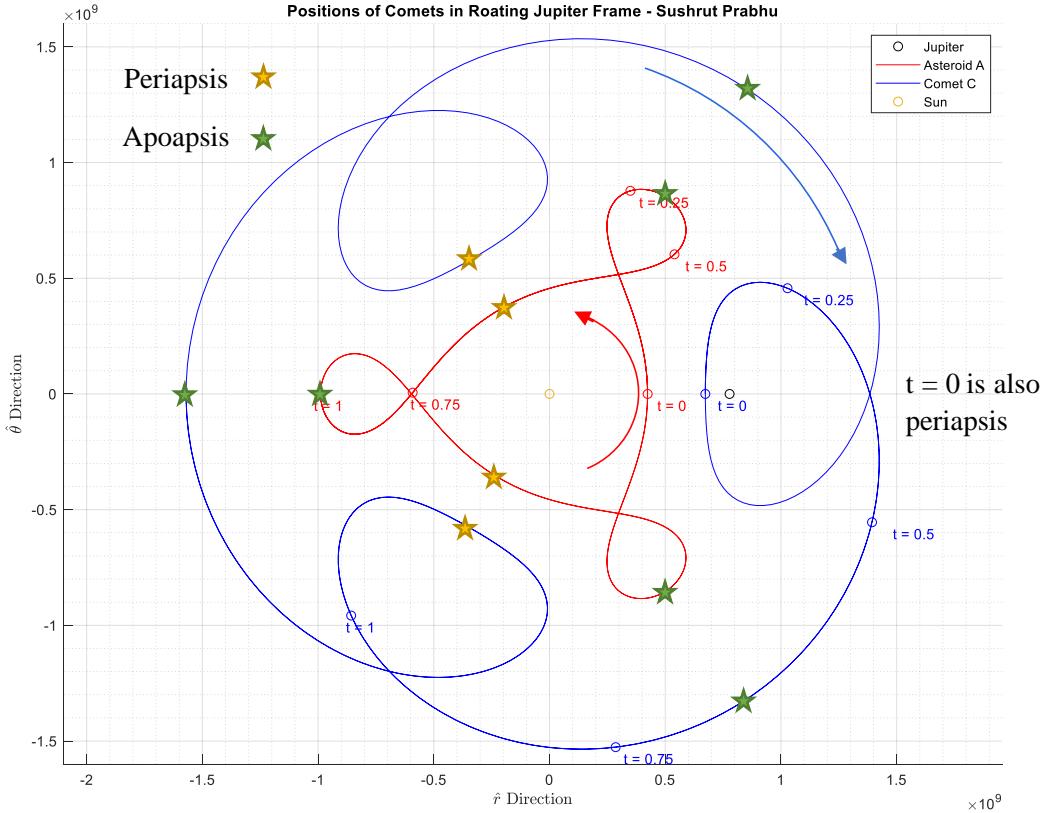


Figure 8: Eccentric orbit of 0.4 for asteroid and comet in the rotating Jupiter frame.

Part (d ii)

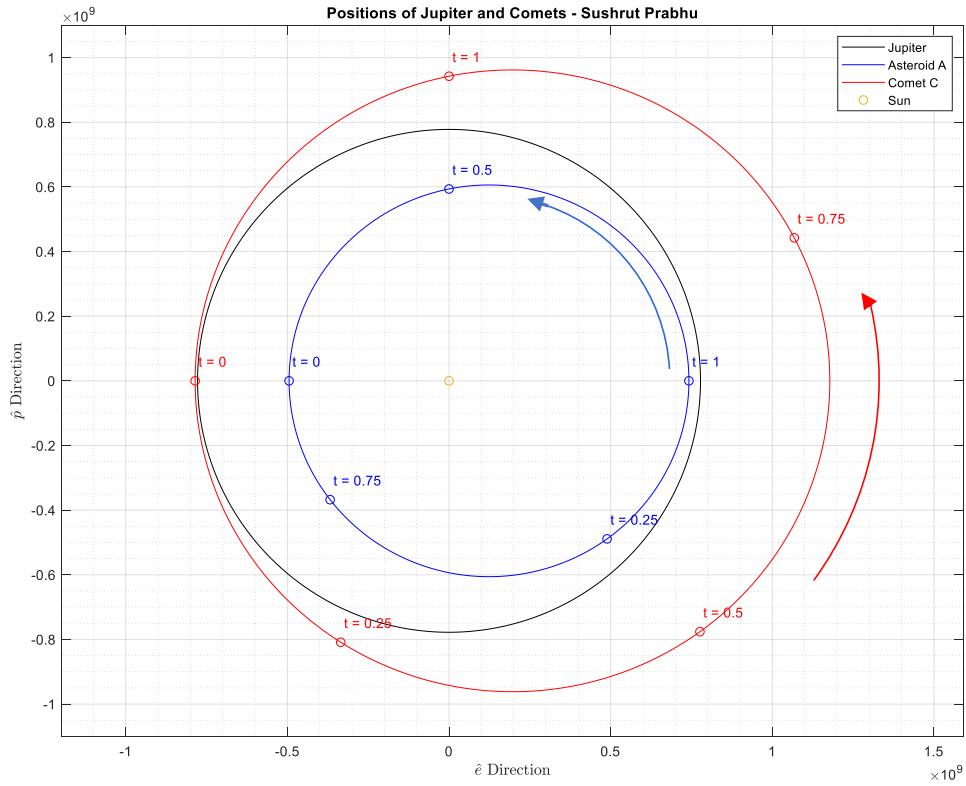


Figure 9: Eccentric orbit of 0.2 for asteroid and comet in the inertial frame 180° out of phase.

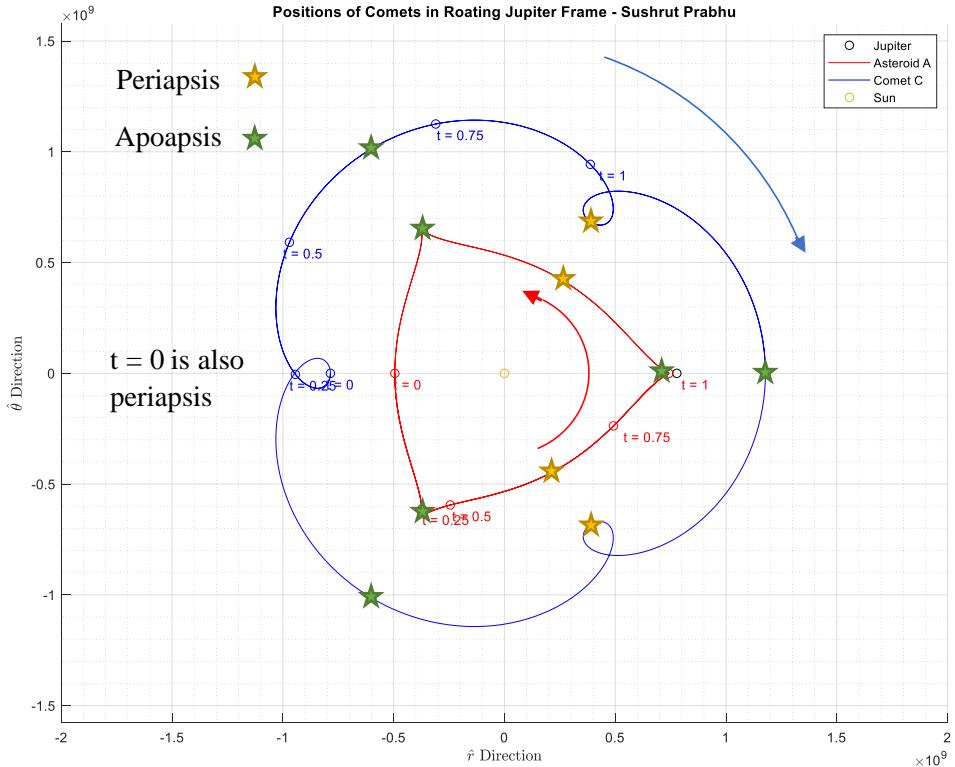


Figure 10: Eccentric orbit of 0.2 for asteroid and comet in the rotating Jupiter frame 180° out of phase.

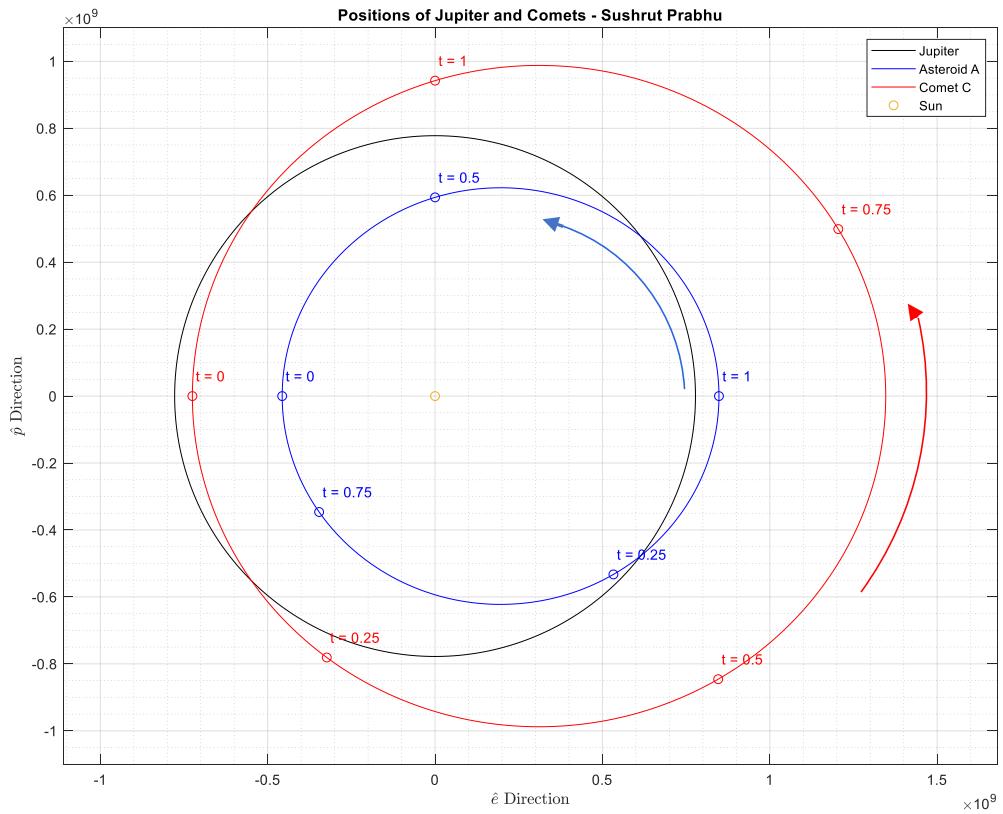


Figure 11: Eccentric orbit of 0.3 for asteroid and comet in the inertial frame 180° out of phase.

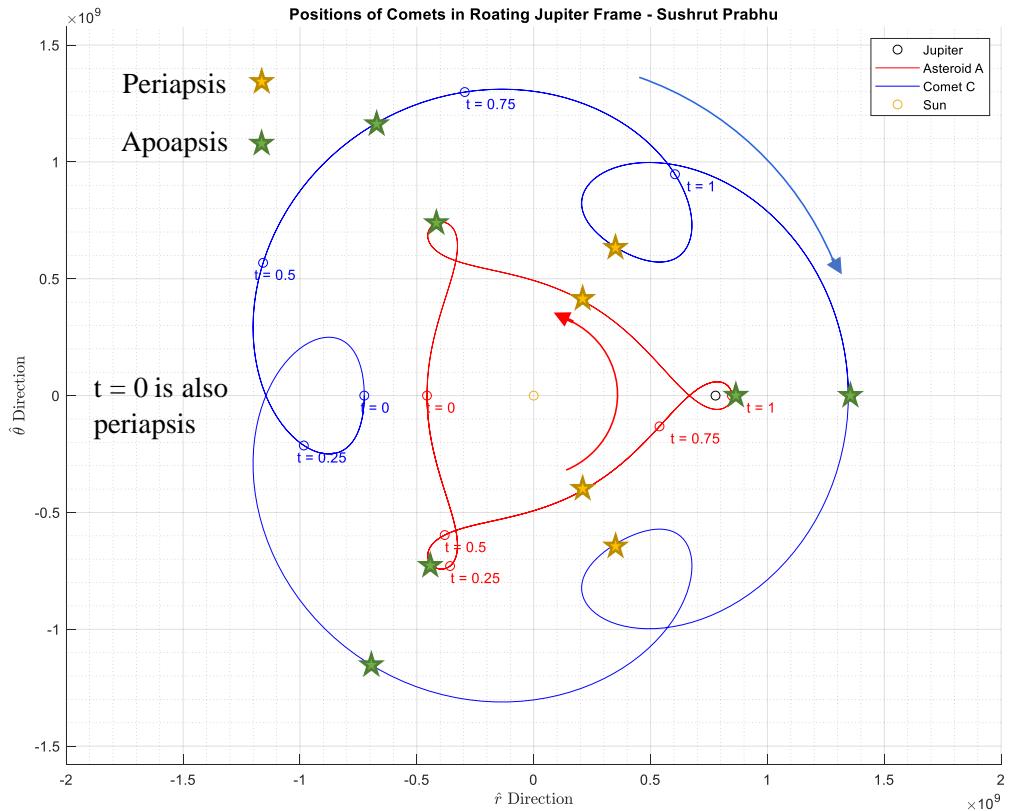


Figure 12: Eccentric orbit of 0.2 for asteroid and comet in the rotating Jupiter frame 180° out of phase.

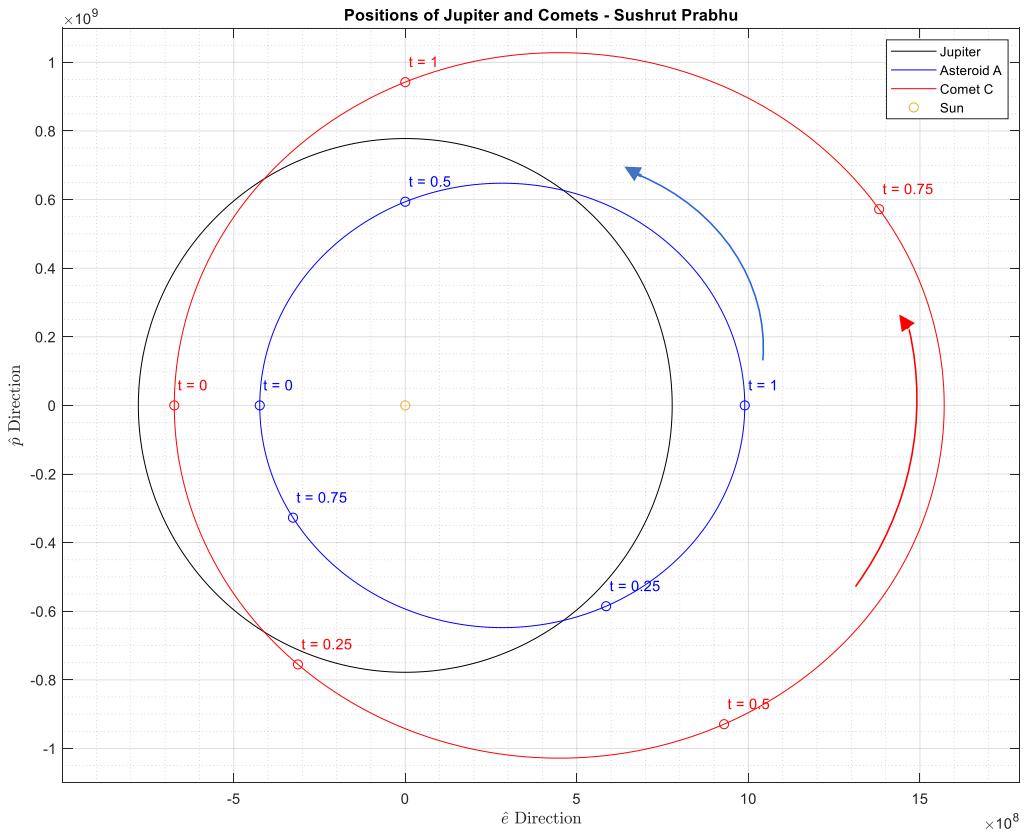


Figure 13: Eccentric orbit of 0.4 for asteroid and comet in the inertial frame 180° out of phase.

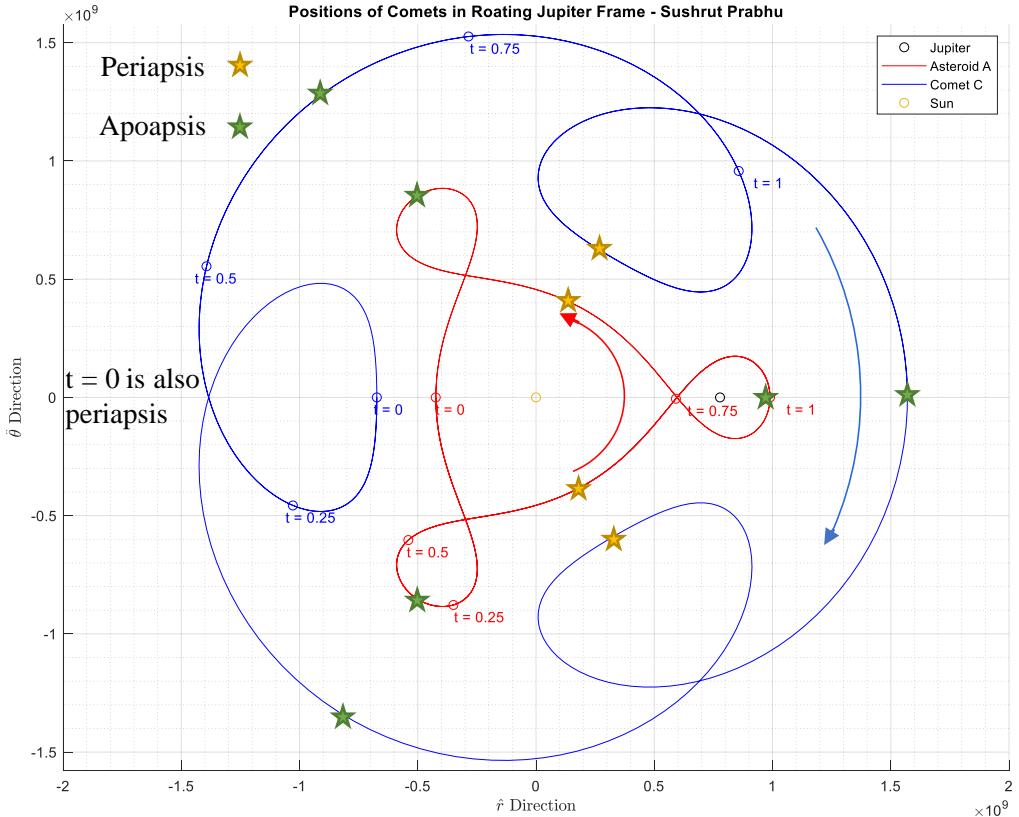


Figure 14: Eccentric orbit of 0.2 for asteroid and comet in the rotating Jupiter frame 180° out of phase.

Part (e)

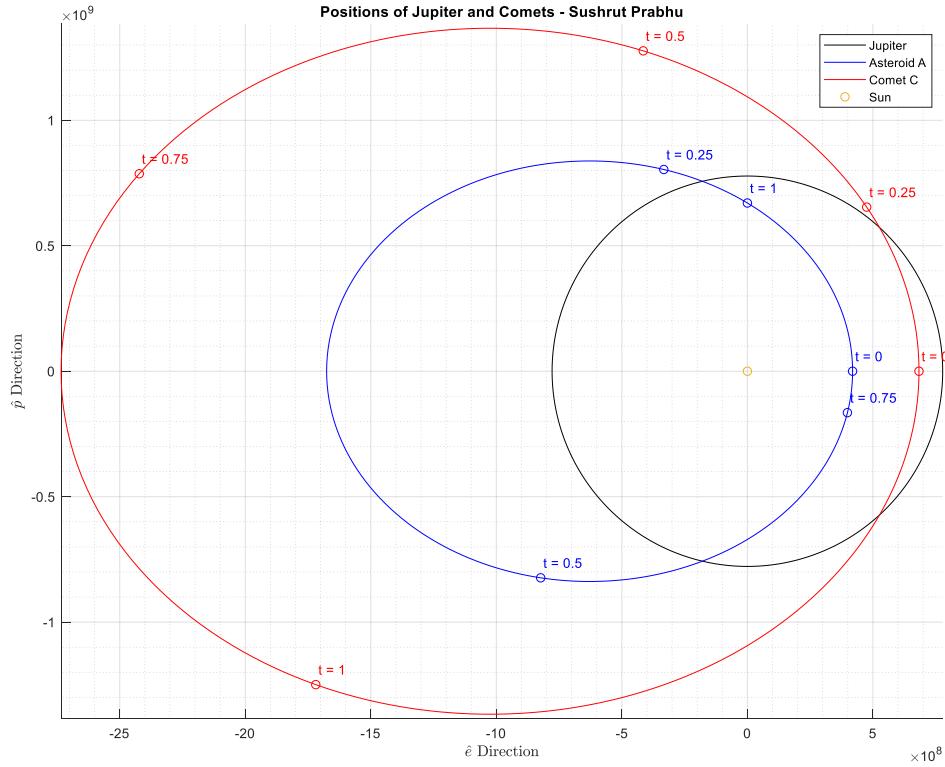


Figure 15: Eccentric orbit of ___ for asteroid and comet in the inertial frame with ___ and ___ resonance.

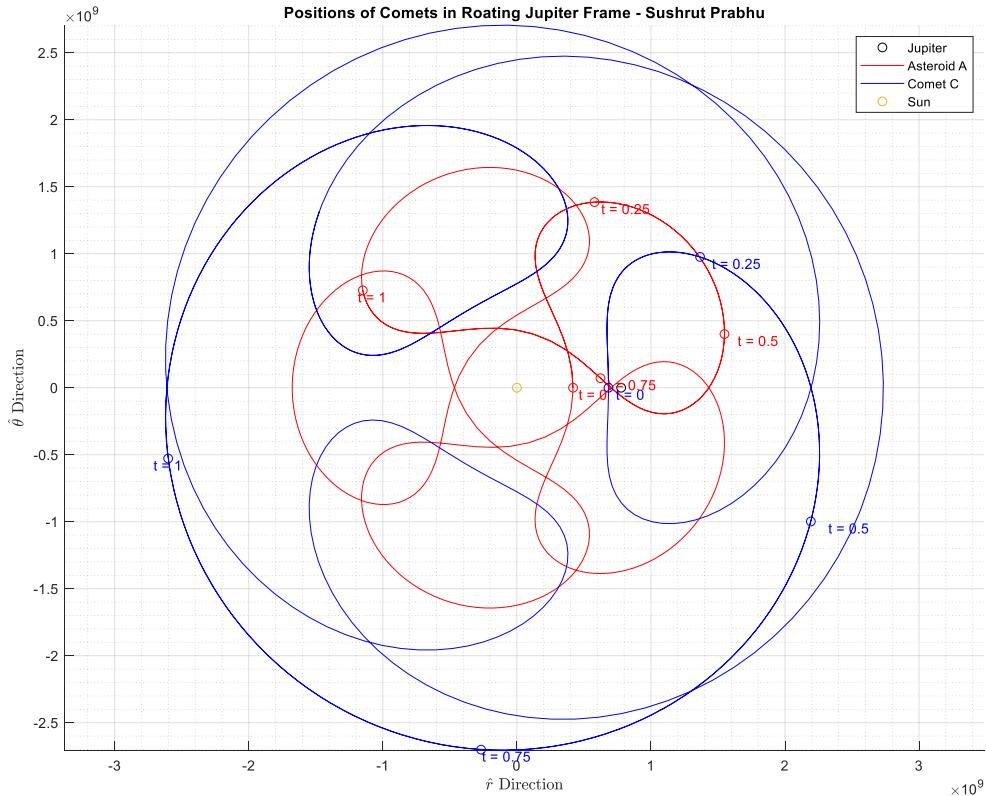


Figure 16: Eccentric orbit of ___ for asteroid and comet in the rotating Jupiter frame with ___ and ___ resonance.

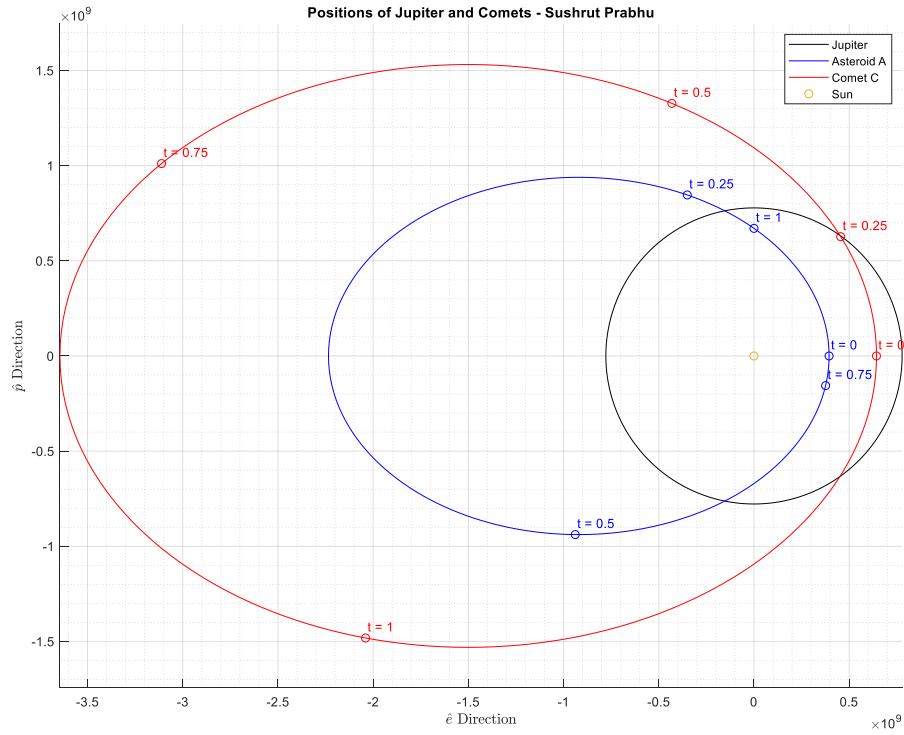


Figure 17: Eccentric orbit of 0.6 for asteroid and comet in the inertial frame with ___ and ___ resonance.

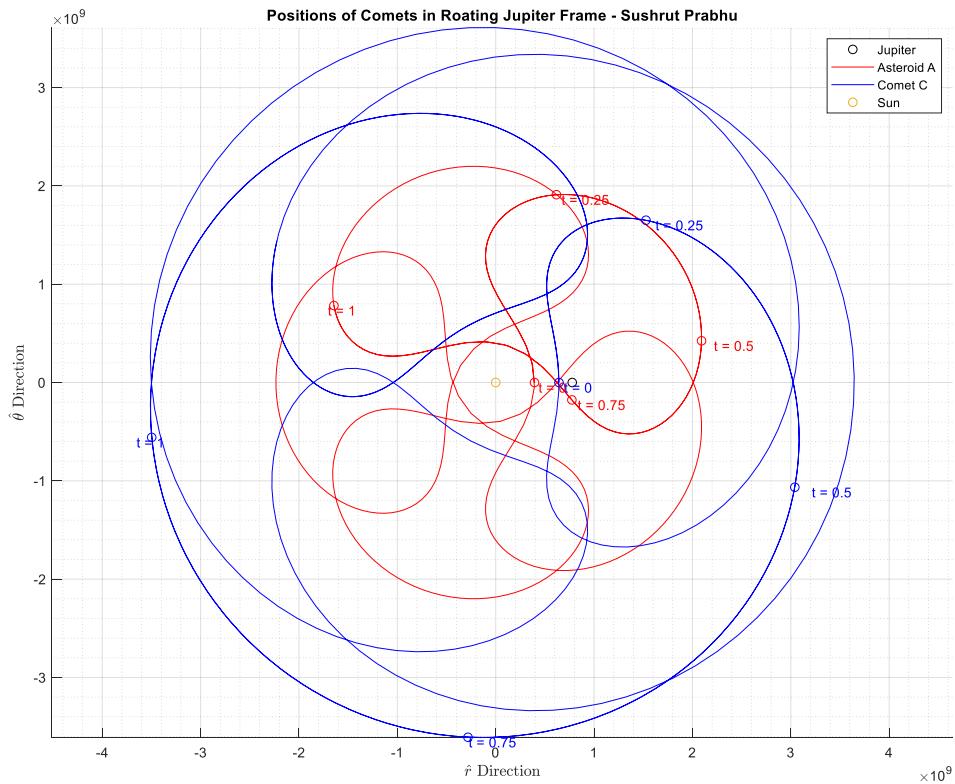


Figure 18: Eccentric orbit of ___ for asteroid and comet in the rotating Jupiter frame with ___ and ___ resonance.

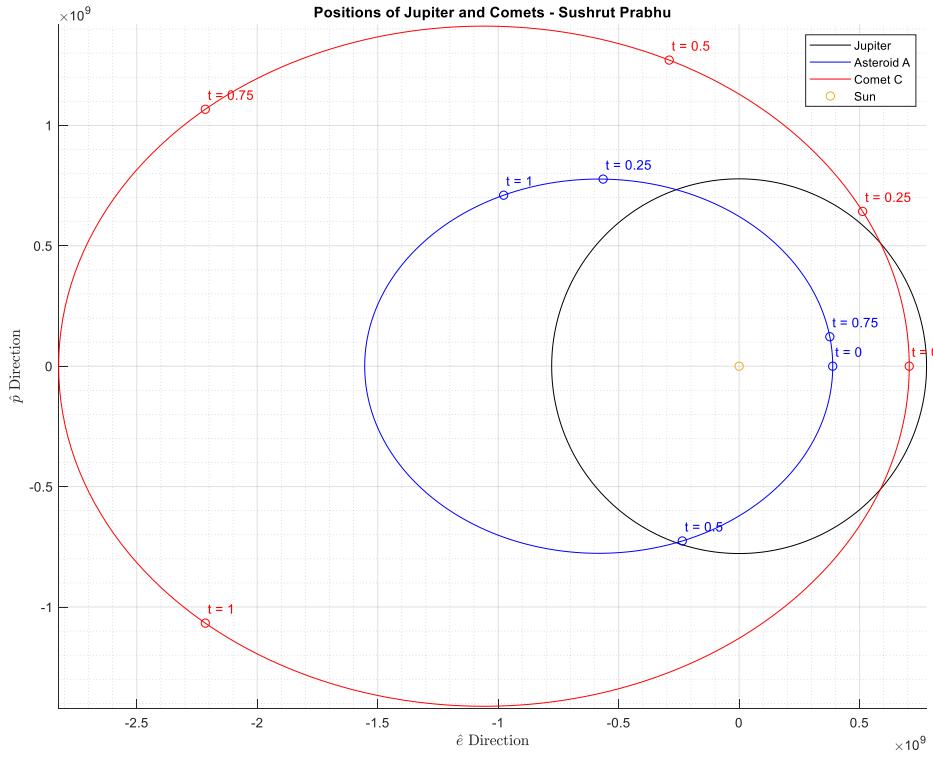


Figure 19: Eccentric orbit of 0.6 for asteroid and comet in the inertial frame with ___ and ___ resonance.

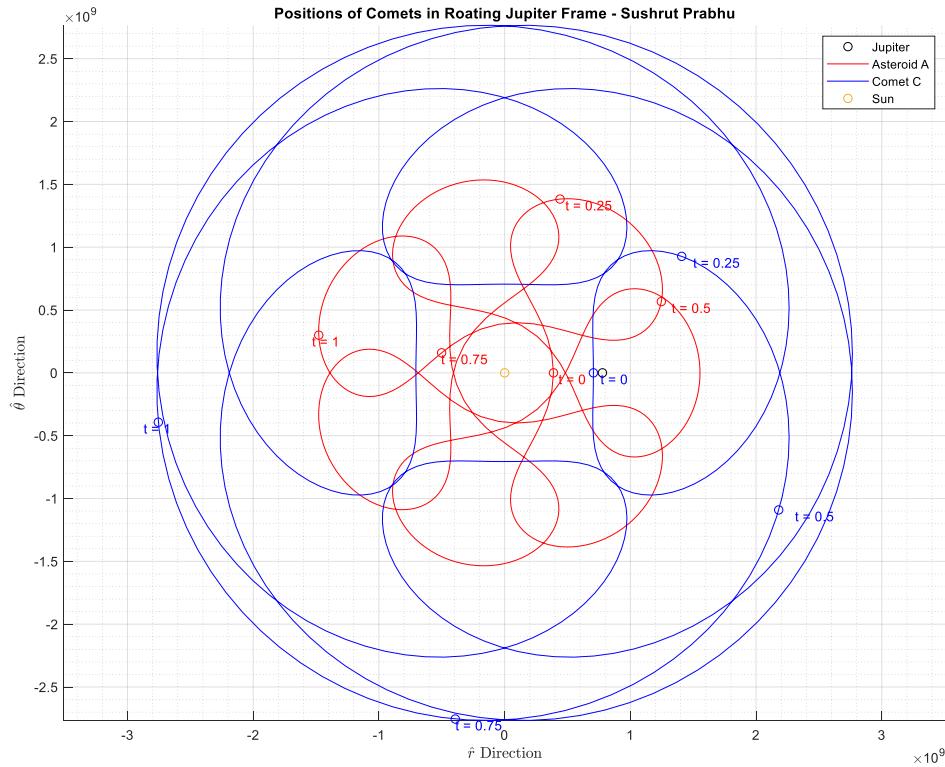


Figure 20: Eccentric orbit of ___ for asteroid and comet in the rotating Jupiter frame with ___ and ___ resonance.

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PSB1

```
clear
close all
clc
```

PSB1 Part a

Constants

```
SS = SolarS;
miu_S = SS.mSun;

% Jupiter
a_jup = 5.2 * SS.dEarth;
Per_jup = 2*pi/sqrt(miu_S/a_jup^3);
n_jup = sqrt(miu_S/a_jup^3);

% Comet A
a_A = (4*a_jup^3/9)^(1/3);
Per_A = 2*pi/sqrt(miu_S/a_A^3);
Per_A_years = Per_A/3600/24/365;
n_A = sqrt(miu_S/a_A^3);

% Comet B
a_C = (16*a_jup^3/9)^(1/3);
Per_C = 2*pi/sqrt(miu_S/a_C^3);
Per_C_years = Per_C/3600/24/365;
n_C = sqrt(miu_S/a_C^3);

frac = [0, .25, .5, .75, 1];
frac2 = {"t = 0"; "t = 0.25"; "t = 0.5"; "t = 0.75"; "t = 1"};
for n = 1:length(frac)
    t_jup = Per_jup*frac(n);

    thst_A(n) = rad2deg(t_jup * n_A);
    thst_C(n) = rad2deg(t_jup * n_C);
end

trueanom = 0:360;

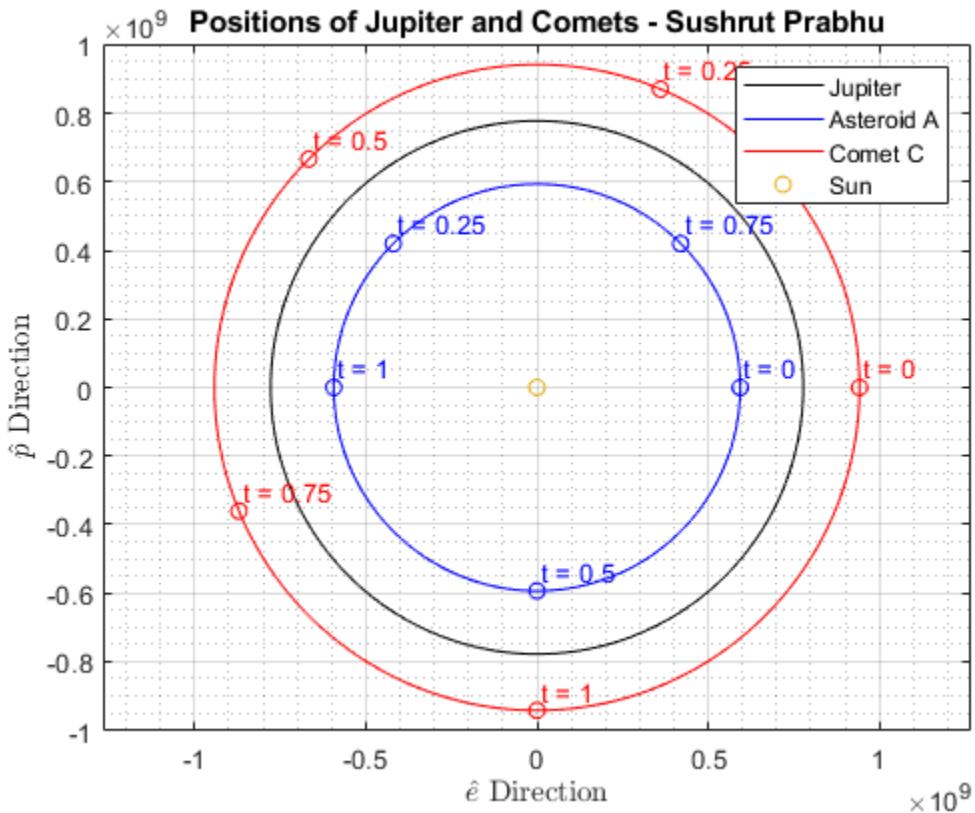
figure
```

```

pl_orbit(trueanom, a_jup, 0, "-k", 1, "", "", 0)
hold on
pl_orbit(trueanom, a_A, 0, "-b", 1, "", "", 0)
pl_orbit(trueanom, a_C, 0, "-r", 1, "", "", 0)
plot(0, 0, 'O', 'Color',[0.9290, 0.6940, 0.1250])
pl_orbit(thst_A, a_A, 0, "ob", 2, frac2, "Blue", 0)
pl_orbit(thst_C, a_C, 0, "or", 2, frac2, "Red", 0)
xlabel('$$\hat{e}$$ Direction', 'Interpreter', 'Latex')
ylabel('$$\hat{p}$$ Direction', 'Interpreter', 'Latex')
title('Positions of Jupiter and Comets - Sushrut Prabhu')
grid on
grid minor
axis equal
legend('Jupiter', 'Asteroid A', 'Comet C', 'Sun')

ylim([-1 1]*10^9)

```



Part (b)

```

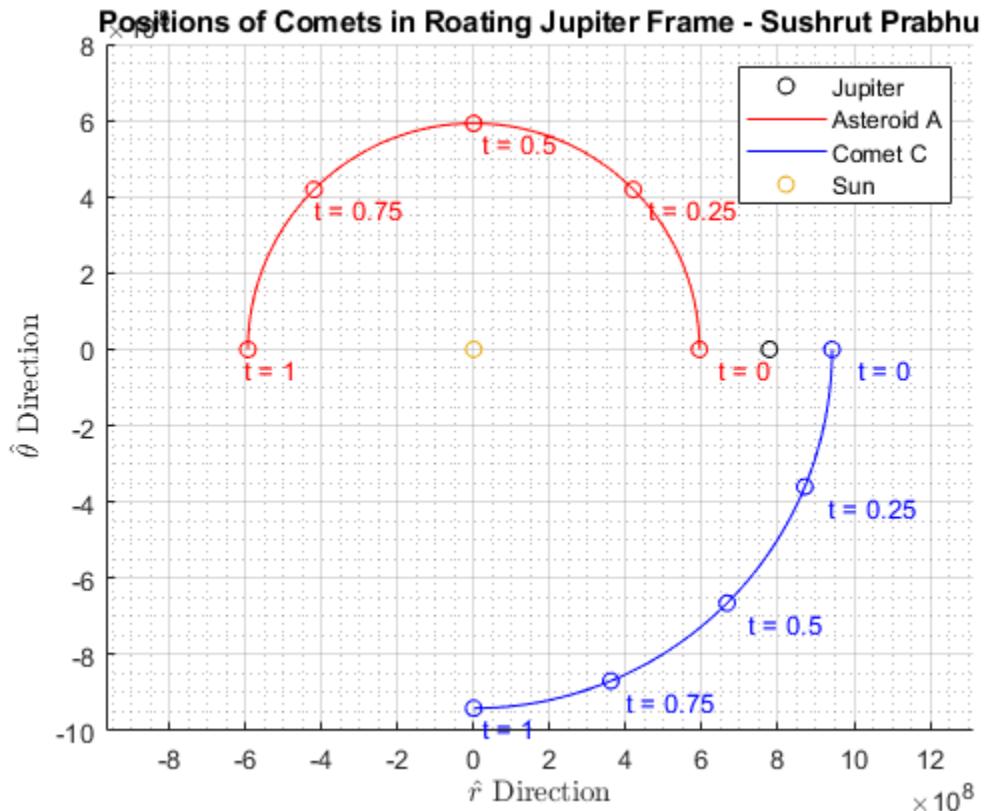
figure
hold on
plot(a_jup, 0, 'Ok')
pl_rot_orbit(Per_jup, n_jup, n_A, a_A, 0, '-r', 1, "", "", 0)
pl_rot_orbit(Per_jup, n_jup, n_C, a_C, 0, '-b', 1, "", "", 0)
plot(0, 0, 'O', 'Color',[0.9290, 0.6940, 0.1250])
pl_rot_orbit(frac*Per_jup, n_jup, n_A, a_A, 0, "or", 2, frac2, "Red", 0)

```

```

pl_rot_orbit(frac*Per_jup, n_jup, n_C, a_C, 0, 'ob', 2,
    frac2, "Blue",0)
xlabel('$$\hat{r}$$ Direction','Interpreter','Latex')
ylabel('$$\hat{\theta}$$ Direction','Interpreter','Latex')
title('Positions of Comets in Roating Jupiter Frame - Sushrut Prabhu')
grid on
grid minor
axis equal
legend('Jupiter','Asteroid A', 'Comet C','Sun')
ylim([-1 .8]*10^9)

```



Part c

```

ecc = [0.2 0.3 0.4];

for m = 1:length(ecc)
    ecc_A = ecc(m);
    p_A = a_A*(1-ecc_A^2);

    ecc_C = ecc(m);
    p_C = a_A*(1-ecc_C^2);

    for n = 1:length(frac)
        t_jup = Per_jup*frac(n);

```

```

        thst_A(n) = rad2deg(t_jup * n_A);
        thst_C(n) = rad2deg(t_jup * n_C);
    end

trueanom = 0:360;

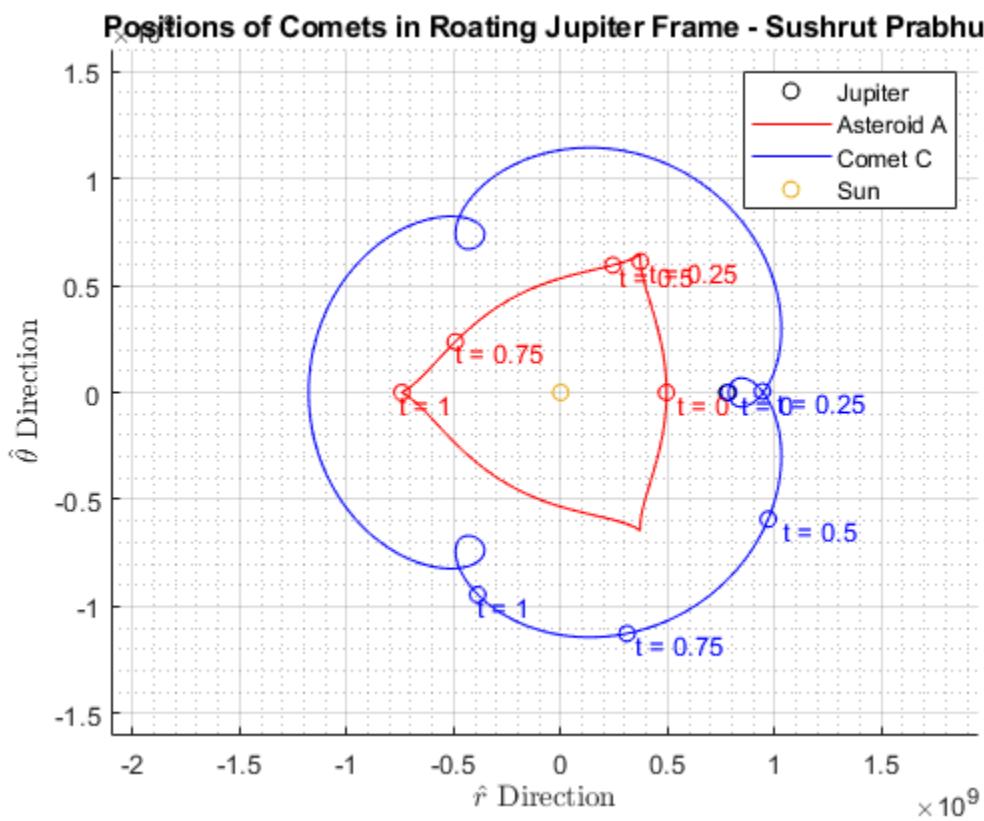
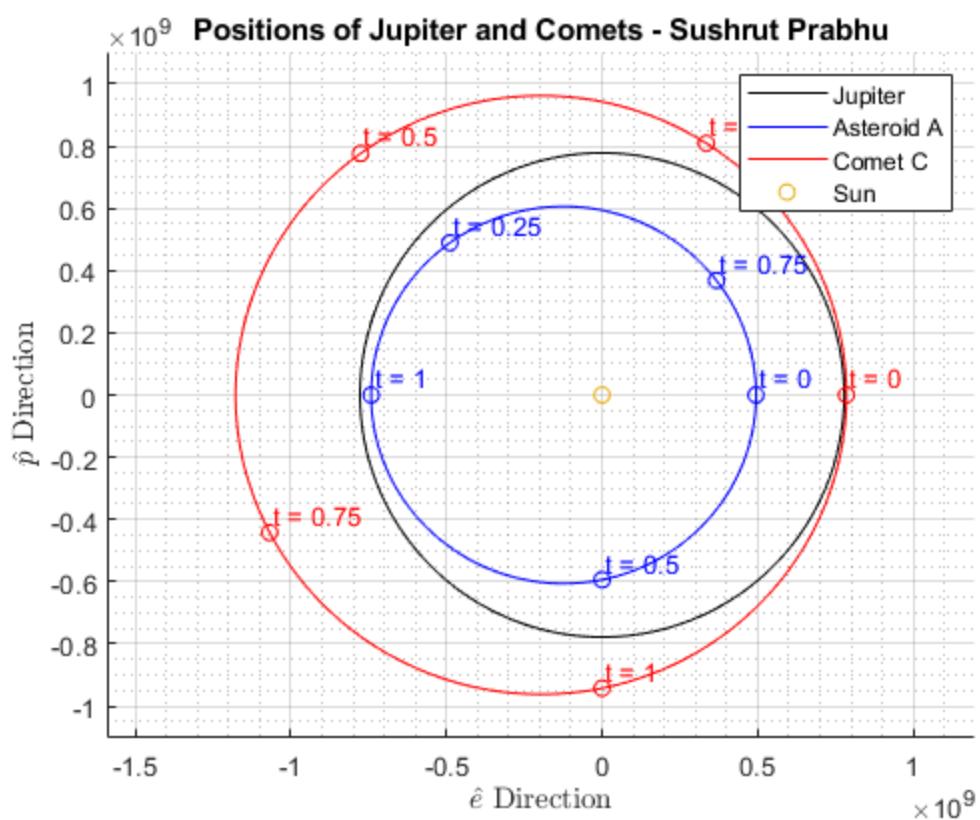
% Inertial Frame
figure
hold on
pl_orbit(trueanom, a_jup, 0, "-k", 1, "", "", 0)
pl_orbit(trueanom, a_A, ecc_A, "-b", 1, "", "", 0)
pl_orbit(trueanom, a_C, ecc_C, "-r", 1, "", "", 0)
plot(0, 0, 'O', 'Color',[0.9290, 0.6940, 0.1250])
pl_orbit(thst_A, a_A, ecc_A, "ob", 2, frac2, "Blue", 0)
pl_orbit(thst_C, a_C, ecc_C, "or", 2, frac2, "Red", 0)
xlabel('$$\hat{e}$$ Direction','Interpreter','Latex')
ylabel('$$\hat{p}$$ Direction','Interpreter','Latex')
title('Positions of Jupiter and Comets - Sushrut Prabhu')
grid on
grid minor
axis equal
legend('Jupiter','Asteroid A', 'Comet C', 'Sun')

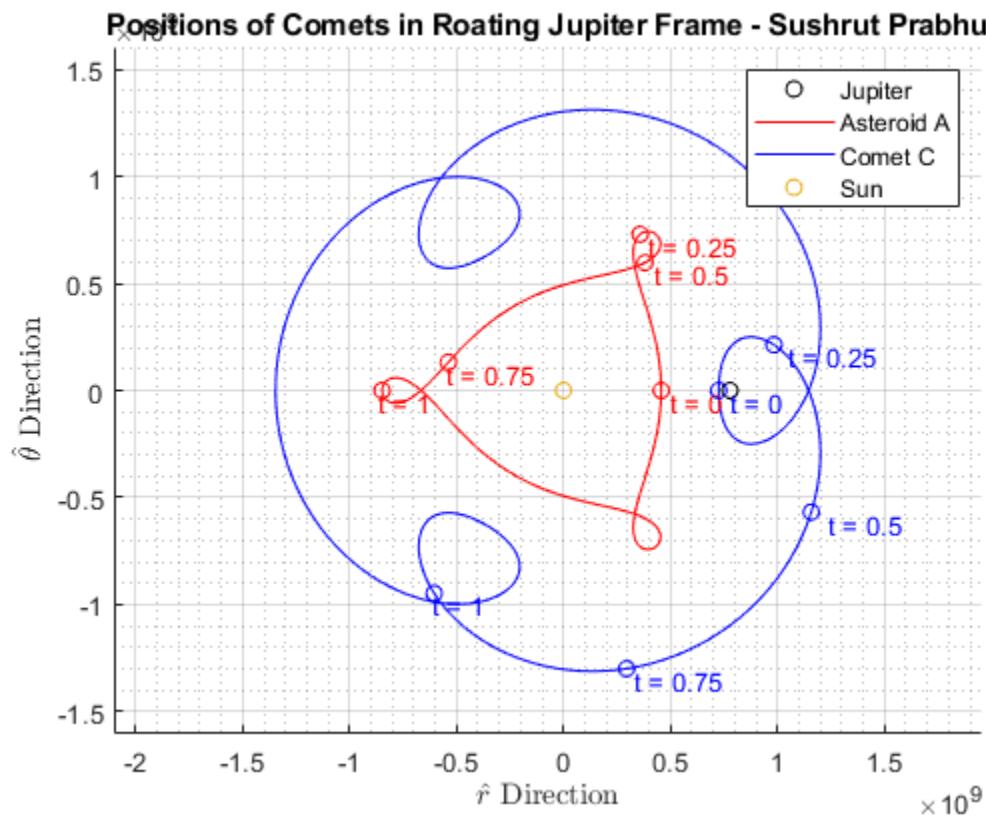
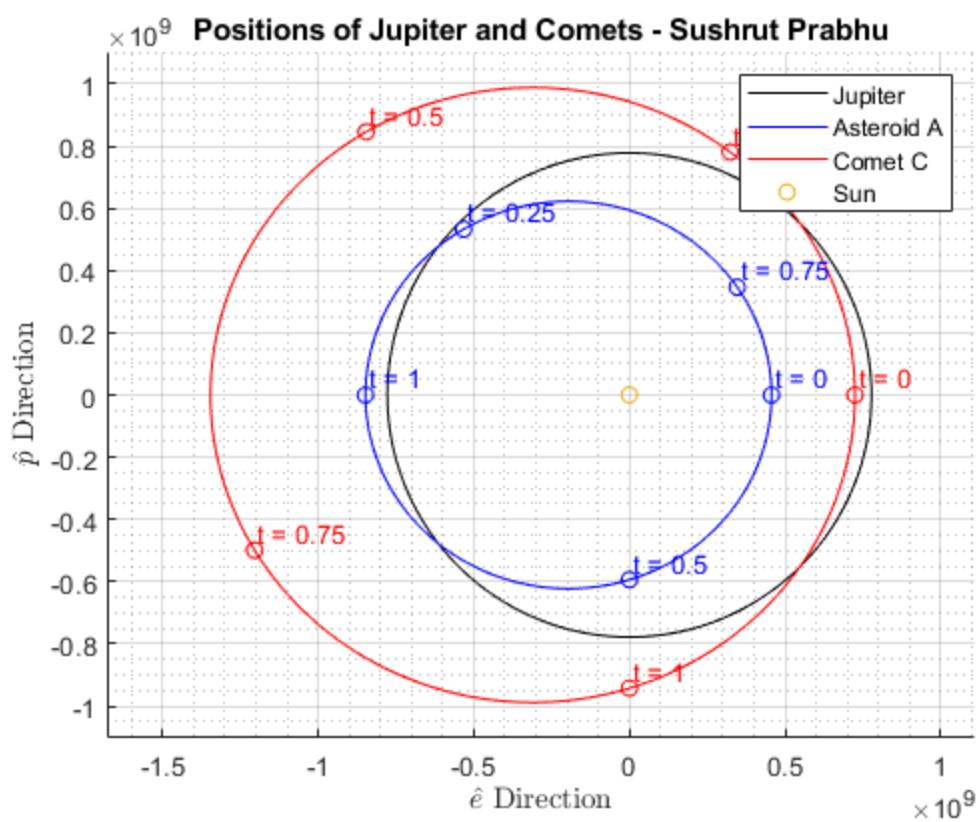
ylim([-1.1 1.1]*10^9)

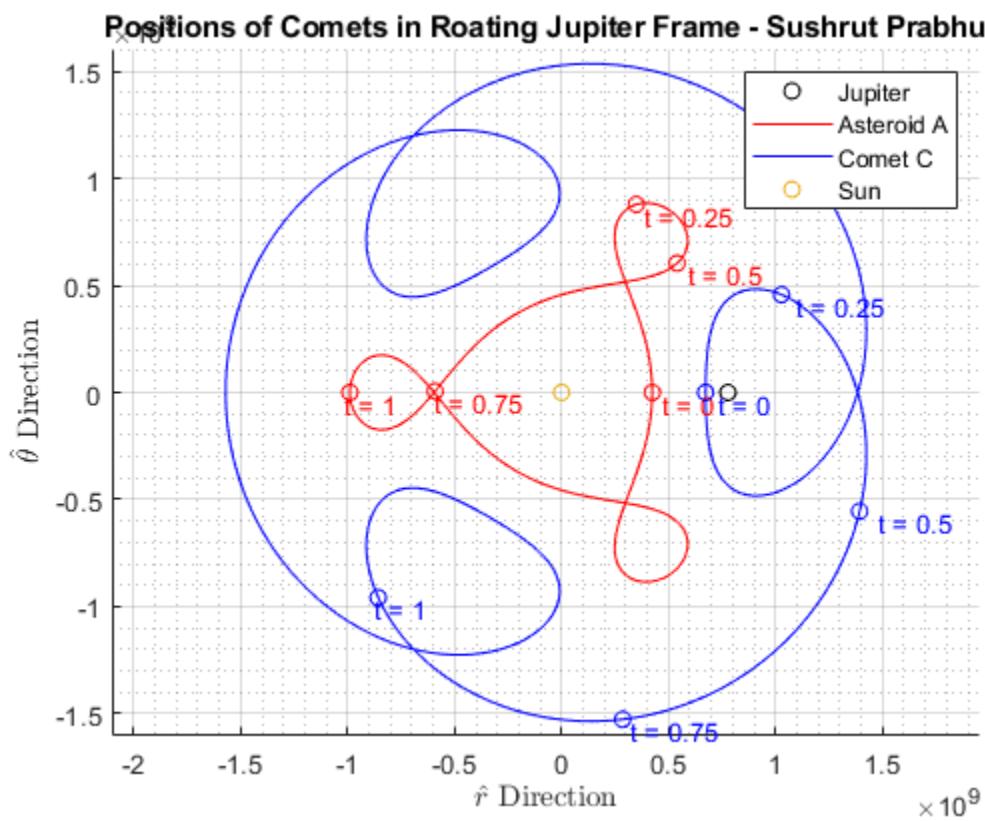
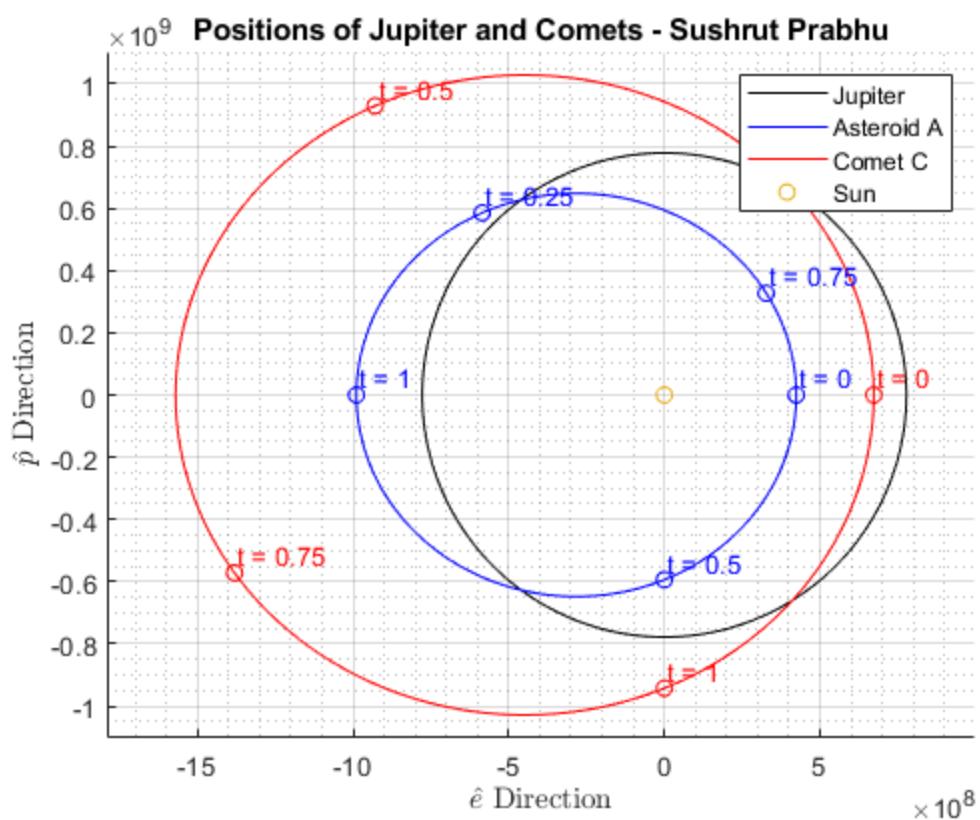
% Jupiter Rotating Frame
figure
hold on
plot(a_jup, 0, 'Ok')
pl_rot_orbit(Per_jup*5, n_jup, n_A, a_A, ecc_A, '-r', 1, "", "", 0)
pl_rot_orbit(Per_jup*6, n_jup, n_C, a_C, ecc_C, '-b', 1, "", "", 0)
plot(0, 0, 'O', 'Color',[0.9290, 0.6940, 0.1250])
pl_rot_orbit(frac*Per_jup, n_jup, n_A, a_A, ecc_A, 'or', 2,
frac2, "Red", 0)
pl_rot_orbit(frac*Per_jup, n_jup, n_C, a_C, ecc_C, 'ob', 2,
frac2, "Blue", 0)
xlabel('$$\hat{r}$$ Direction','Interpreter','Latex')
ylabel('$$\hat{\theta}$$ Direction','Interpreter','Latex')
title('Positions of Comets in Roating Jupiter Frame - Sushrut
Prabhu')
grid on
grid minor
axis equal
legend('Jupiter','Asteroid A', 'Comet C', 'Sun')

ylim([-1.6 1.6]*10^9)
end

```







Out of phase

```
for m = 1:length(ecc)
    ecc_A = ecc(m);
    p_A = a_A*(1-ecc_A^2);

    ecc_C = ecc(m);
    p_C = a_A*(1-ecc_C^2);

for n = 1:length(frac)
    t_jup = Per_jup*frac(n);

    thst_A(n) = rad2deg(t_jup * n_A);
    thst_C(n) = rad2deg(t_jup * n_C);
end

trueanom = 0:360;

% Inertial Frame
figure
hold on
pl_orbit(trueanom, a_jup, 0, "-k", 1, "", "", 0)
pl_orbit(-180:180, a_A, ecc_A, "-b", 1, "", "", 180)
pl_orbit(-180:180, a_C, ecc_C, "-r", 1, "", "", 180)
plot(0, 0, 'O', 'Color',[0.9290, 0.6940, 0.1250])
pl_orbit(thst_A, a_A, ecc_A, "ob", 2, frac2, "Blue", 180)
pl_orbit(thst_C, a_C, ecc_C, "or", 2, frac2, "Red", 180)
xlabel('$$\hat{e}$$ Direction','Interpreter','Latex')
ylabel('$$\hat{p}$$ Direction','Interpreter','Latex')
title('Positions of Jupiter and Comets - Sushrut Prabhu')
grid on
grid minor
axis equal
legend('Jupiter', 'Asteroid A', 'Comet C', 'Sun')

ylim([-1.1 1.1]*10^9)

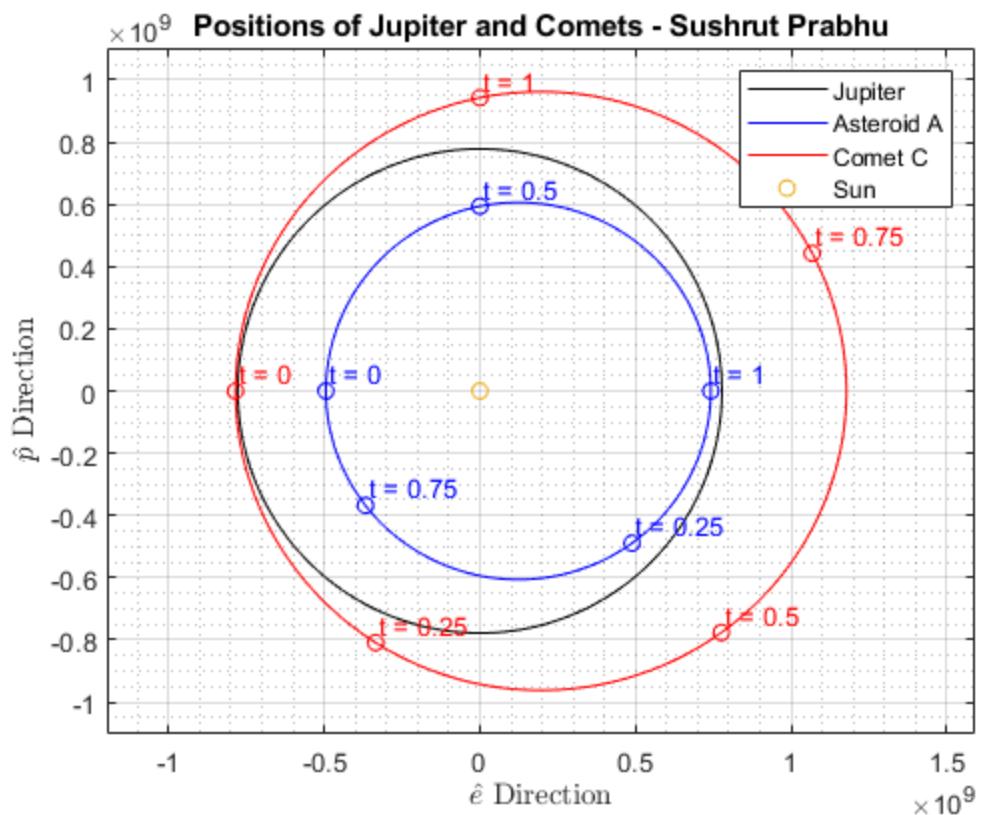
% Jupiter Rotating Frame
figure
hold on
plot(a_jup, 0, 'Ok')
pl_rot_orbit(Per_jup*5, n_jup, n_A, a_A, ecc_A, '-r',
1, "", "", 180)
pl_rot_orbit(Per_jup*6, n_jup, n_C, a_C, ecc_C, '-b',
1, "", "", 180)
plot(0, 0, 'O', 'Color',[0.9290, 0.6940, 0.1250])
pl_rot_orbit(frac*Per_jup, n_jup, n_A, a_A, ecc_A, 'or',
2, frac2, "Red", 180)
pl_rot_orbit(frac*Per_jup, n_jup, n_C, a_C, ecc_C, 'ob',
2, frac2, "Blue", 180)
xlabel('$$\hat{r}$$ Direction','Interpreter','Latex')
ylabel('$$\hat{\theta}$$ Direction','Interpreter','Latex')
```

```

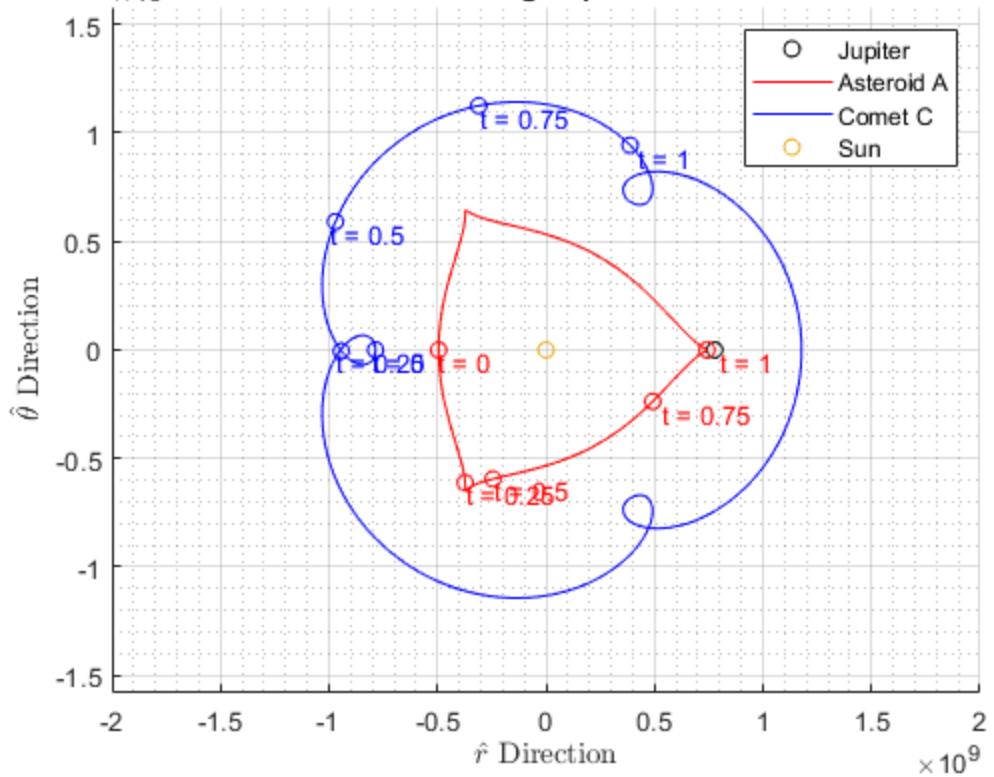
title('Positions of Comets in Roating Jupiter Frame - Sushrut
Prabhu')
grid on
grid minor
axis equal
legend('Jupiter', 'Asteroid A', 'Comet C', 'Sun')

xlim([-2 2]*10^9)
end

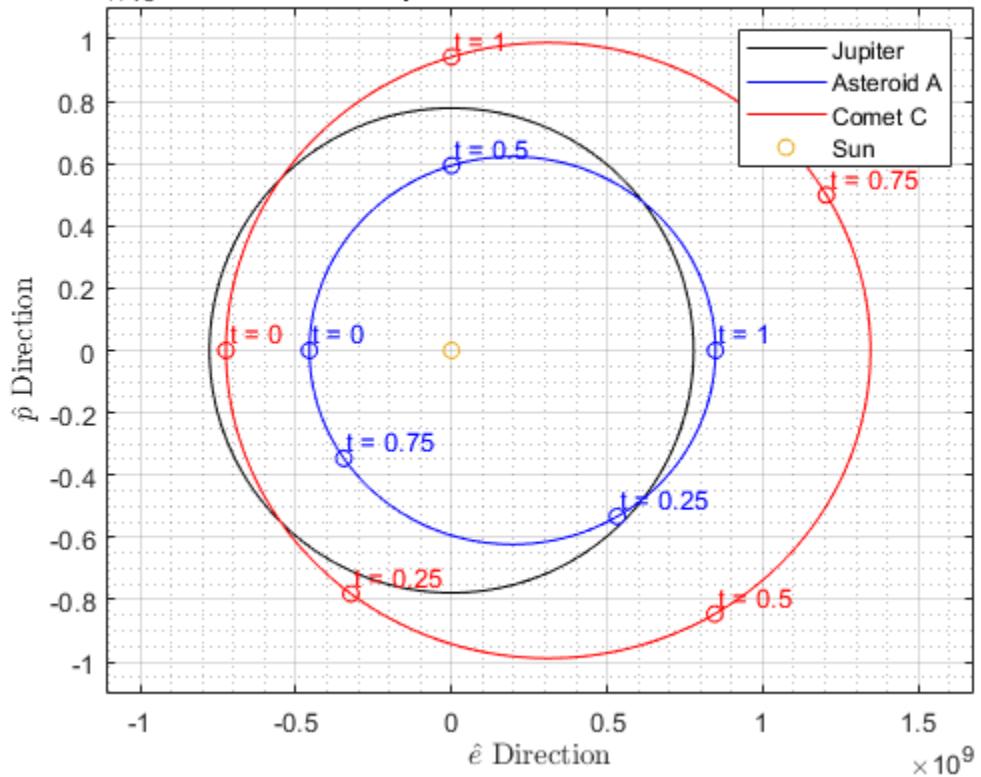
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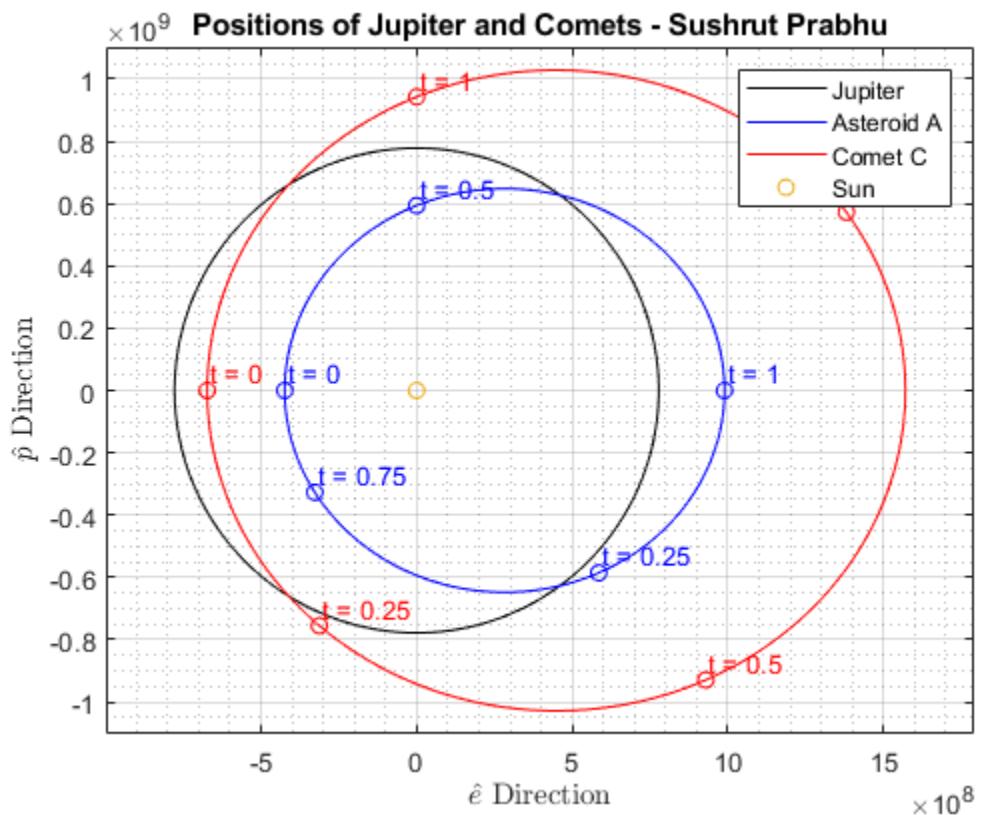
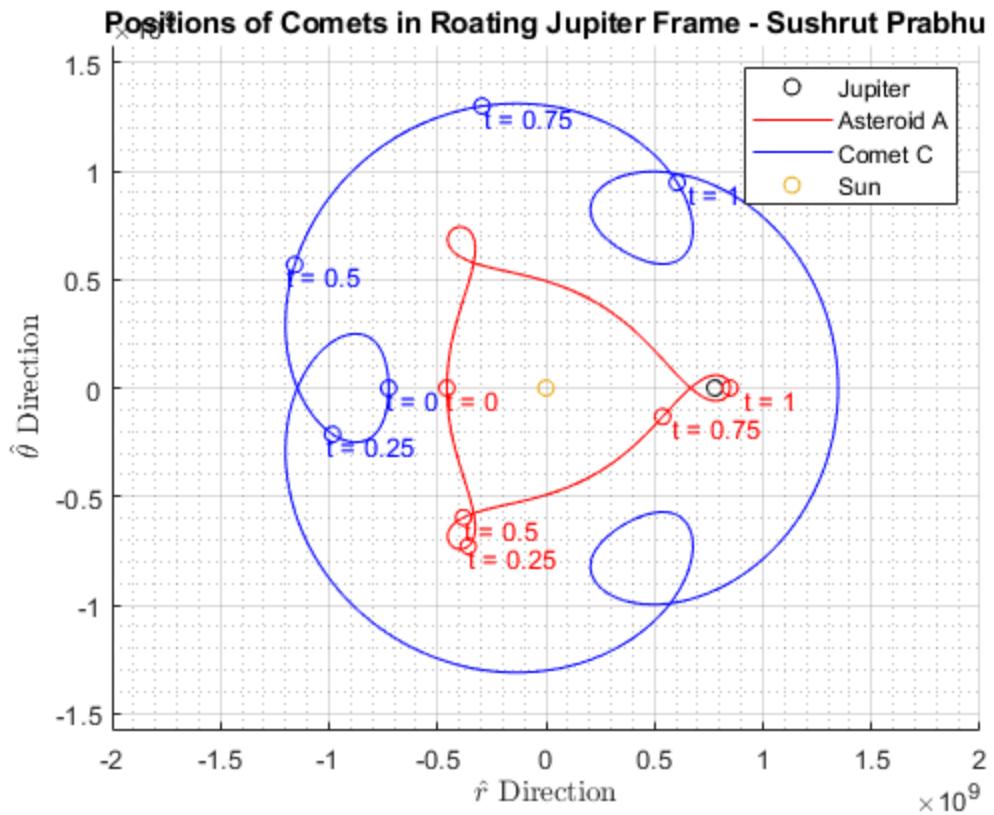


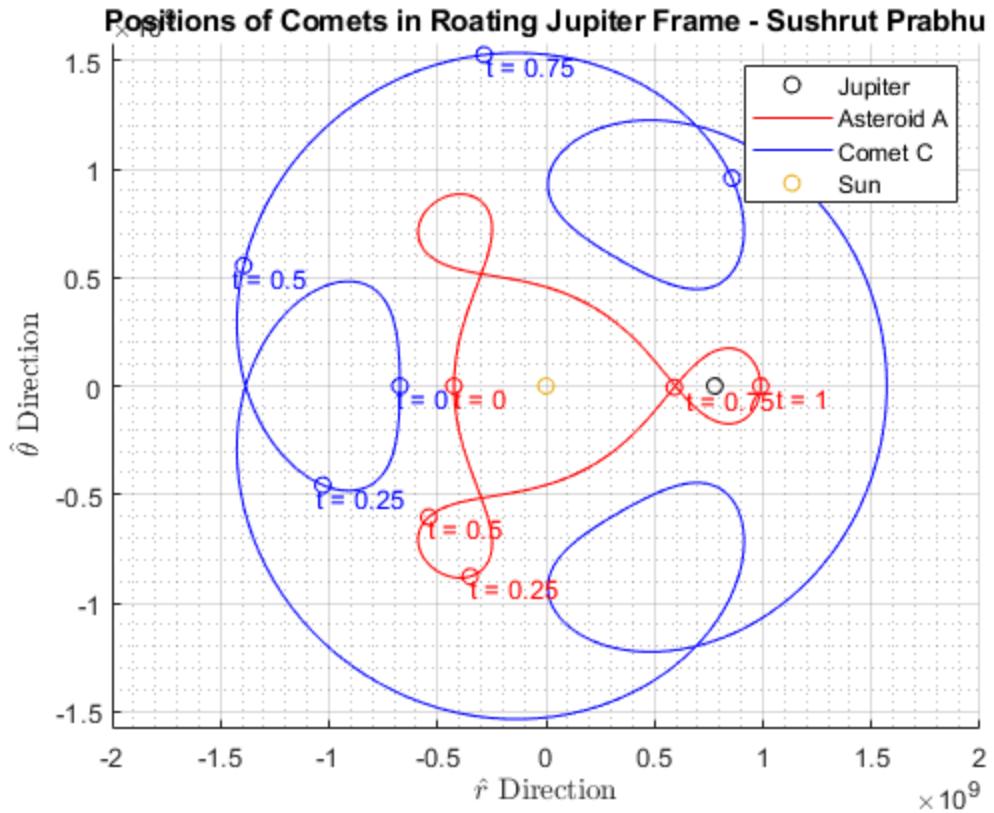
Positions of Comets in Roating Jupiter Frame - Sushrut Prabhu



Positions of Jupiter and Comets - Sushrut Prabhu







Part (e)

```

ecc = [0.1 0.9];

res1 = 5/7;
res2 = 7/4;

% Comet A
a_A = (res1^2 *a_jup^3)^(1/3);
Per_A = 2*pi/sqrt(miu_S/a_A^3);
Per_A_years = Per_A/3600/24/365;
n_A = sqrt(miu_S/a_A^3);

% Comet B
a_C = (res2^2 *a_jup^3)^(1/3);
Per_C = 2*pi/sqrt(miu_S/a_C^3);
Per_C_years = Per_C/3600/24/365;
n_C = sqrt(miu_S/a_C^3);

for m = 1:length(ecc)
    ecc_A = ecc(m);
    p_A = a_A*(1-ecc_A^2);

    ecc_C = ecc(m);

```

```

p_C = a_A*(1-ecc_C^2);

for n = 1:length(frac)
    t_jup = Per_jup*frac(n);

    thst_A(n) = rad2deg(t_jup * n_A);
    thst_C(n) = rad2deg(t_jup * n_C);
end

trueanom = 0:360;

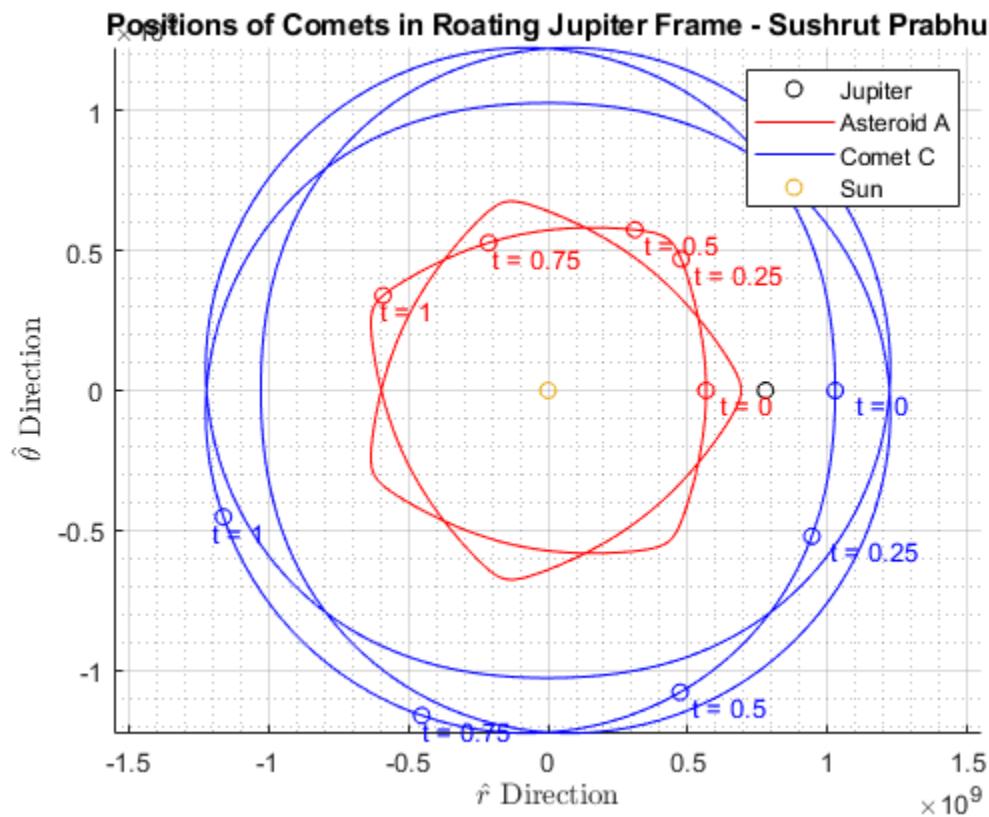
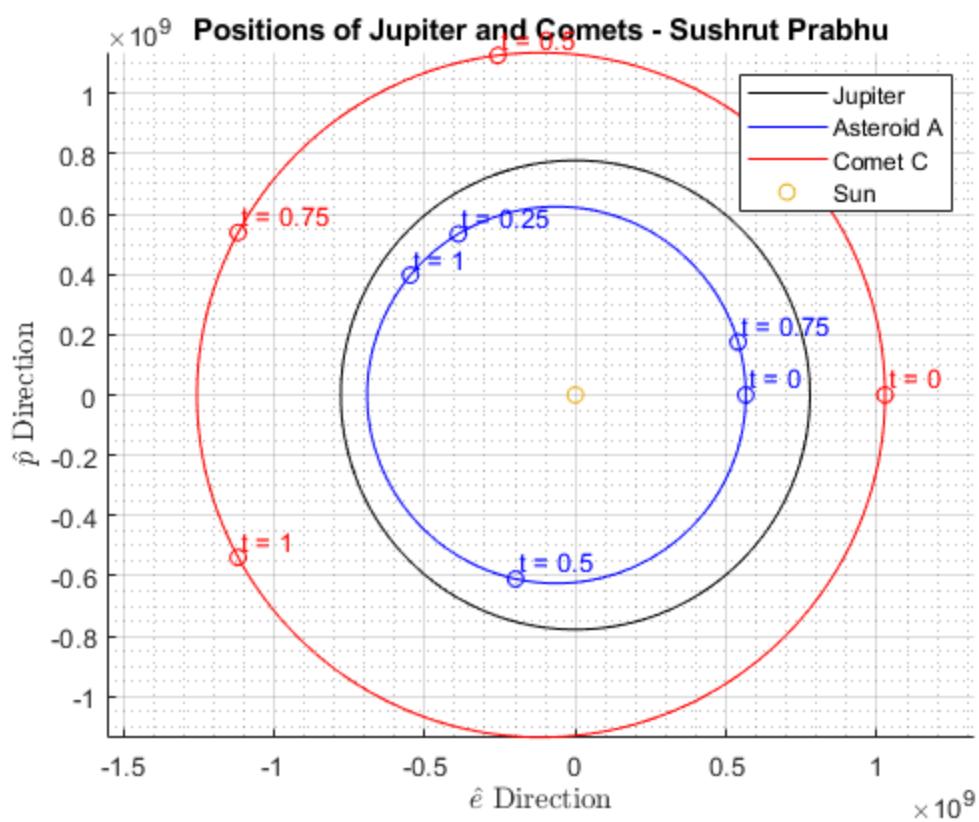
% Inertial Frame
figure
hold on
pl_orbit(trueanom, a_jup, 0, "-k", 1, "", "", 0)
pl_orbit(trueanom, a_A, ecc_A, "-b", 1, "", "", 0)
pl_orbit(trueanom, a_C, ecc_C, "-r", 1, "", "", 0)
plot(0, 0, 'O', 'Color',[0.9290, 0.6940, 0.1250])
pl_orbit(thst_A, a_A, ecc_A, "ob", 2, frac2, "Blue", 0)
pl_orbit(thst_C, a_C, ecc_C, "or", 2, frac2, "Red", 0)
xlabel('$\hat{e}$ Direction', 'Interpreter', 'Latex')
ylabel('$\hat{p}$ Direction', 'Interpreter', 'Latex')
title('Positions of Jupiter and Comets - Sushrut Prabhu')
grid on
grid minor
axis equal
legend('Jupiter', 'Asteroid A', 'Comet C', 'Sun')

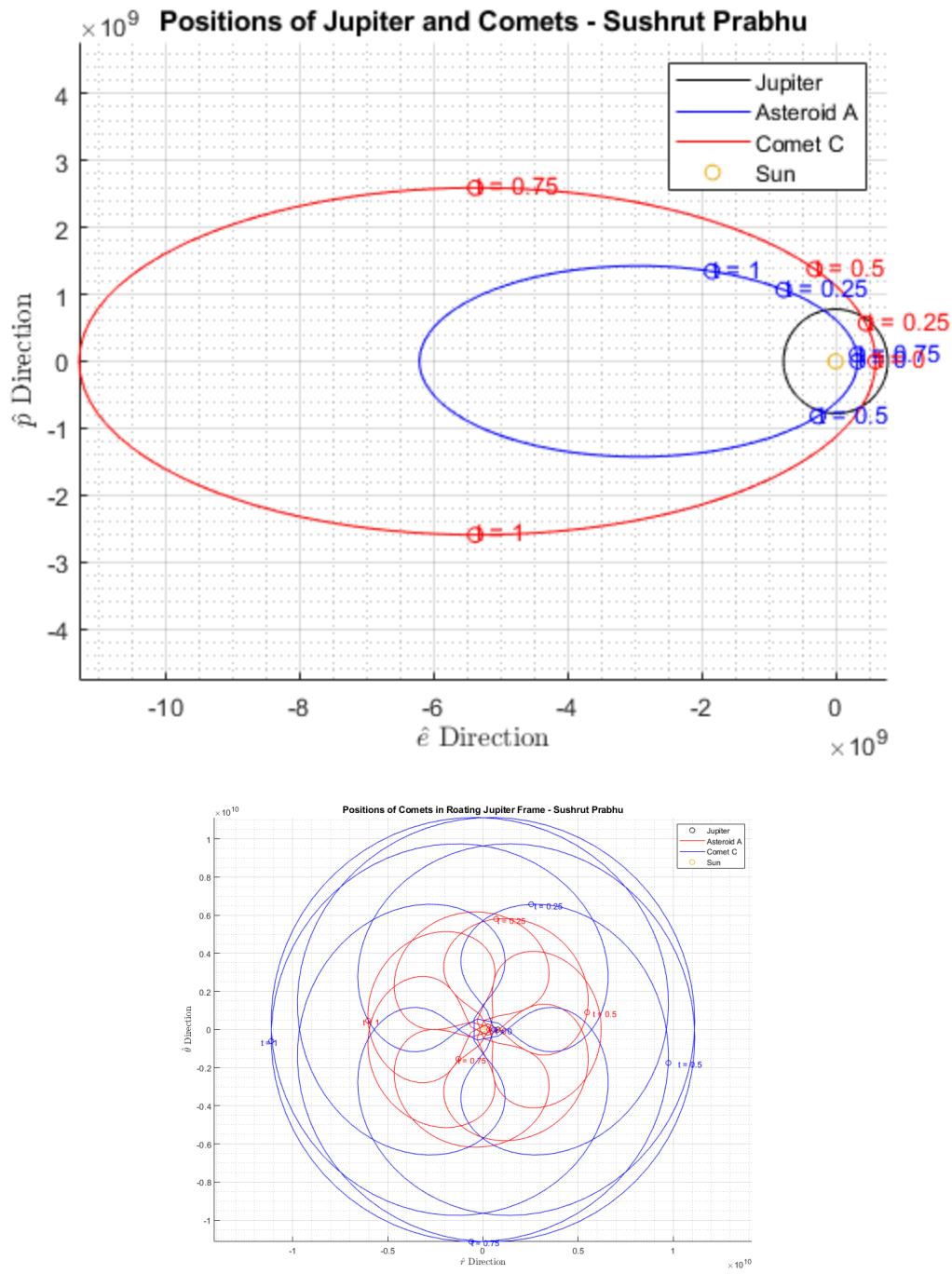
% Jupyter Notebook Specific
% ylim([-1.1 1.1]*10^9)

% Jupiter Rotating Frame
figure
hold on
plot(a_jup, 0, 'Ok')
pl_rot_orbit(Per_jup*5, n_jup, n_A, a_A, ecc_A, '-r', 1, "", "", 0)
pl_rot_orbit(Per_jup*7, n_jup, n_C, a_C, ecc_C, '-b', 1, "", "", 0)
plot(0, 0, 'O', 'Color',[0.9290, 0.6940, 0.1250])
pl_rot_orbit(frac*Per_jup, n_jup, n_A, a_A, ecc_A, 'or', 2,
frac2, "Red", 0)
pl_rot_orbit(frac*Per_jup, n_jup, n_C, a_C, ecc_C, 'ob', 2,
frac2, "Blue", 0)
xlabel('$\hat{r}$ Direction', 'Interpreter', 'Latex')
ylabel('$\hat{\theta}$ Direction', 'Interpreter', 'Latex')
title('Positions of Comets in Roating Jupiter Frame - Sushrut
Prabhu')
grid on
grid minor
axis equal
legend('Jupiter', 'Asteroid A', 'Comet C', 'Sun')

% Jupyter Notebook Specific
% ylim([-1.6 1.6]*10^9)
end

```





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Solar Systems Constants

Constants

```
classdef SolarS
    properties
        % Distances from Sun/ planet to planet/ Moon
        dMercury = 57909226.542
        dVenus = 108209474.537
        dEarth = 149597870.7
        dMars = 227943816.693
        dJupiter = 778340816.693
        dSaturn = 1426666414.180
        dM_E = 384400
        dMoon = 384400+149597870.7
        dPluto = 5906440596.5288
        dTitan_S = 1221865
        dPhobos_M = 9376;
        dEuropa_J = 671100
        dOberon_U = 583500
        dTriton_N = 354759
        dCharon_P = 17536

        % Mass of Planet/Star/ Moon (G*m)
        mSun = 132712440017.99
        mVenus = 324858.5988
        mEarth = 398600.4415
        mMars = 42828.3142
        mJupiter = 126712767.8578
        mSaturn = 37940626.0611
        mUranus = 5794549.0070719
        mNeptune = 6836534.06387
        mPluto = 981.600887707;

        mMoon = 4902.8011
        mTitan = 8979.766
        mPhobos = 7.11328968e-04
        mEuropa = 3203.31978
        mOberon = 192.4249
        mTriton = 1427.8589
        mCharon = 103.2187

        % Radius of Moon/Planet
        rEarth = 6378.136;
        rMars = 3397.00;
        rMoon = 1738.10;
        rSaturn = 60268.00;
        rJupiter = 71492.00;
        % Eccentricity of Planets
        eEarth = 0.01671022
        eSaturn = 0.05386179
```

```
    end
end

ans =  
  
Solars with properties:  
  
dMercury: 5.7909e+07  
dVenus: 1.0821e+08  
dEarth: 1.4960e+08  
dMars: 2.2794e+08  
dJupiter: 7.7834e+08  
dSaturn: 1.4267e+09  
dM_E: 384400  
dMoon: 1.4998e+08  
dPluto: 5.9064e+09  
dTitan_S: 1221865  
dPhobos_M: 9376  
dEuropa_J: 671100  
dOberon_U: 583500  
dTriton_N: 354759  
dCharon_P: 17536  
mSun: 1.3271e+11  
mVenus: 3.2486e+05  
mEarth: 3.9860e+05  
mMars: 4.2828e+04  
mJupiter: 1.2671e+08  
mSaturn: 3.7941e+07  
mUranus: 5.7945e+06  
mNeptune: 6.8365e+06  
mPluto: 981.6009  
mMoon: 4.9028e+03  
mTitan: 8.9798e+03  
mPhobos: 7.1133e-04  
mEuropa: 3.2033e+03  
mOberon: 192.4249  
mTriton: 1.4279e+03  
mCharon: 103.2187  
rEarth: 6.3781e+03  
rMars: 3397  
rMoon: 1.7381e+03  
rSaturn: 60268  
rJupiter: 71492  
eEarth: 0.0167  
eSaturn: 0.0539
```

Mean Anomaly to Eccentric Anomaly

```
function [E_n,n]= M2E_NRm(M,ecc,err_tol)

err = 1;
E_n = M;      % Initial guess for eccentric anomaly guess
n = 1;

% Newton Raphson method to solve for Eccentric anomaly
while err> err_tol
    E_n1 = E_n - (E_n-ecc*sin(E_n)-M)/(1-ecc*cos(E_n));
    err = abs(E_n1-E_n);
    E_n = E_n1;
    n = n+1;
end

E_n = rad2deg(E_n);
end
```

Not enough input arguments.

```
Error in M2E_NRm (line 5)
E_n = M;      % Initial guess for eccentric anomaly guess
```

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```

%%%%%%%%%%%%%
% Plot Inertial Frame
%
% Input:
% trueanom - array of true anomaly 0->360
% p - Semi-latus Rectum
% ecc - eccentricity
% rE - Radius of Earth
% title_n - Plot title you desire
%
%%%%%%%%%%%%%
function pl_orbit(trueanom, p, ecc, style, type, text_inp, style2,
shift)

```

Plot Orbit

```

r = p ./ (1 + ecc*cosd(trueanom));
epos = r.*cosd(trueanom);
ppos = r.*sind(trueanom);

if shift > 0
    ep_new = cosd(shift)*epos + sind(shift)*ppos;
    pp_new = -sind(shift)*epos + cosd(shift)*ppos;

    epos = ep_new;
    ppos = pp_new;
end

plot(epos,ppos, style)

if type == 2
    for n = 1:length(epos)
        text(epos(n)+1*10^7,ppos(n)+6*10^7, text_inp{n}, 'Color',
style2)
    end
end

Not enough input arguments.

Error in pl_orbit (line 15)
r = p ./ (1 + ecc*cosd(trueanom));

```

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Plot rotating frame

```
function pl_rot_orbit(time_end, n_rot, n, p, ecc, style, type,
text_inp, style2, shift)
```

Plot Orbit

```
if type == 2
    time = time_end;
else
    time = linspace(0,time_end,500);
end

thst_rot = n_rot*time*180/pi;

% True anomaly of Comet
for m = 1:length(time)
    M = n*time(m);
    E = M2E_NRM(M,ecc,10^-12);
    thst(m) = 2*atan2(sqrt((1+ecc)/(1-ecc)), tand(E/2));
end

r = p ./ (1+ecc*cosd(thst)); % Radial distance to comet

epos = r.*cosd(thst); % Intertial e position to
Comet
ppos = r.*sind(thst); % Intertial p position to
Comet

% 180 degree shift if required
if shift > 0
    ep_new = cosd(shift)*epos + sind(shift)*ppos;
    pp_new = -sind(shift)*epos + cosd(shift)*ppos;

    epos = ep_new;
    ppos = pp_new;
end

% DCM to change from inertial to rotating
for n = 1:length(epos)
    rth_rot(:,n) = [cosd(thst_rot(n)) sind(thst_rot(n)); -sind(thst_rot(n)) cosd(thst_rot(n))] * [epos(n); ppos(n)];
end

plot(rth_rot(1,:),rth_rot(2,:), style)
if type == 2
    for n = 1:length(epos)
        text(rth_rot(1,n)*1.05+2*10^7,rth_rot(2,n)-5*10^7,
text_inp{n}, 'Color', style2)
    end
end
```

Not enough input arguments.

*Error in pl_rot_orbit (line 5)
if type == 2*

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Problem P.2

Given: A relative positions of 3 masses with spherically symmetric gravity fields are represented in following figure.

Find: a) Assumption for restricted 3-body problem, derive differential equations that govern P_3 with respect to body center.

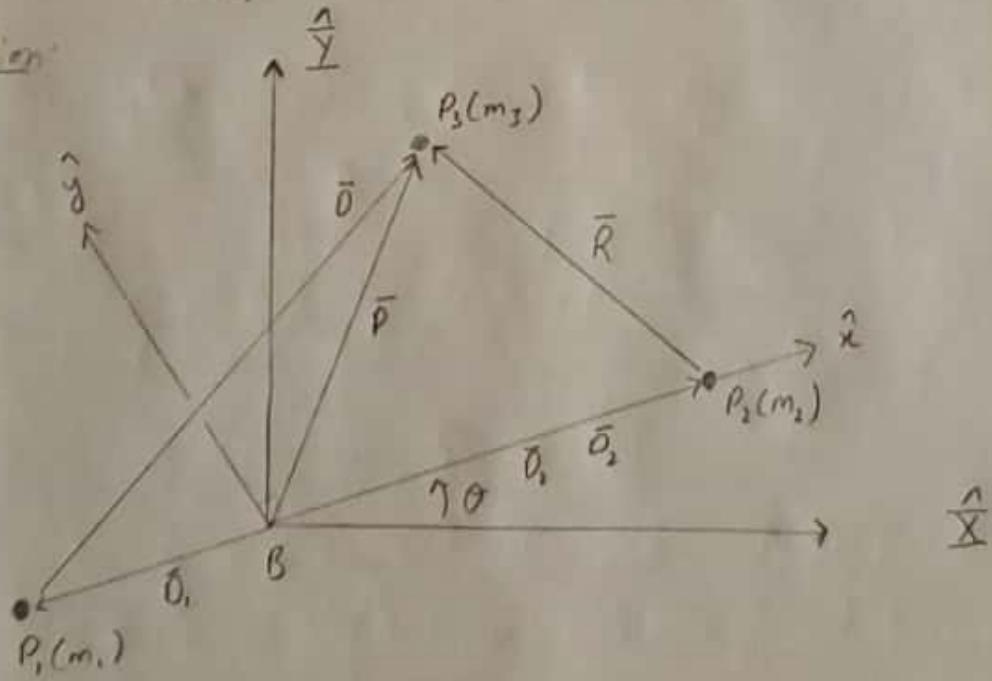
b) Compare dimensional values for characteristic quantities corresponding to distance, mass, and time in following systems:

- i) Sun - Earth
- ii) Earth-Moon
- iii) Sun-Jupiter
- iv) Saturn-Titan
- v) Sun-Mars
- vi) Mars-Phobos
- vii) Jupiter-Europa
- viii) Uranus-Oberon
- ix) Neptune-Triton
- x) Pluto-Charon

Do any of the characteristic quantities reflect physical proportion?

c) Take the relationships from (a) and derive classical set of non-dimensional equations. Does your set match the given in class?

Solution:



- i) The mass of body 3 is much less than body 1, 2. Which means that we can assume that the mass P_3 doesn't influence the motion of P_1 or P_2 .

Continued...

- 2) Due to the infinitesimal mass of P_3 compared P_1 and P_2
we can assume P_1 and P_2 has a conic solution
- 3) In most cases we can assume a circular orbit, so
let us assume a circular orbit for P_1 and P_2

These assumptions result to:

$\dot{\theta}$ is constant due to circular orbit of the primaries

$$m_3 \ddot{r}_3 = -G \frac{m_1 m_2}{|\bar{r}|^3} \bar{r} \quad \text{Law of Gravitation}$$

Let us derive the \ddot{r}

Note: $\dot{\theta}=0$ because orbit is circular

$$\bar{r} = \bar{p} = x\hat{x} + y\hat{y} + z\hat{z}$$

$$\frac{d\bar{r}}{dt} = \dot{\bar{p}} = \dot{\theta}\hat{z} \times \bar{p} = \dot{\theta}\hat{z}(x\hat{x} + y\hat{y} + z\hat{z})$$

$$\frac{d\bar{r}}{dt} = \dot{\bar{p}} = \dot{\theta}\hat{z} \times \hat{y} - \dot{\theta}y\hat{x}$$

$$\therefore \frac{d^2\bar{r}}{dt^2} = \ddot{\bar{p}} = \ddot{\theta}\hat{z} \times \hat{y} + \dot{\theta}\hat{z}\hat{y} - \dot{\theta}y\hat{x} - \dot{\theta}y\hat{x} + \dot{\theta}\hat{z} \times \frac{d\bar{r}}{dt}$$

$$= \ddot{\bar{p}} + \dot{\theta}\hat{x}\hat{y} + \dot{\theta}\hat{x}\hat{y} - \dot{\theta}y\hat{x} - \dot{\theta}y\hat{x}$$

$$+ \dot{\theta}\hat{z} \times (x\hat{x} + y\hat{y} + z\hat{z} + \dot{\theta}\hat{x}\hat{y} - \dot{\theta}y\hat{x})$$

$$= \ddot{\bar{p}} + \ddot{\theta}\hat{y} + \dot{\theta}\hat{x}\hat{y} - \ddot{\theta}y\hat{x} - \dot{\theta}y\hat{x} + \dot{\theta}\hat{x}\hat{y} + \dot{\theta}\hat{y}\hat{z} \\ - \dot{\theta}x\hat{x} - \dot{\theta}y\hat{y}$$

$$\therefore \frac{d^2\bar{r}}{dt^2} = \ddot{\bar{p}} + 2\dot{\theta}\hat{x}\hat{y} - 2\dot{\theta}y\hat{x} + \dot{\theta}^2x\hat{x} - \dot{\theta}^2y\hat{y}$$

See next page for break down

Continued ...

$$\begin{aligned}\hat{x} &\Rightarrow \ddot{x} - 2\dot{\theta}\dot{y} - \dot{\theta}^2 x \\ \hat{y} &\Rightarrow \ddot{y} + 2\dot{\theta}\dot{x} - \dot{\theta}^2 y \\ \hat{z} &\Rightarrow \ddot{z}\end{aligned}$$

Now let us equate kinematics and dynamics

$$\therefore m_1 \frac{d^2 \bar{r}}{dt^2} = - \frac{Gm_1 m_2}{|\bar{r}|^3} \bar{r} - \frac{Gm_1 m_2}{|\bar{r}|^3} \bar{r}$$

$$\therefore \ddot{x} - 2\dot{\theta}\dot{y} - \dot{\theta}^2 x = - \frac{Gm_1}{|\bar{r}|^3} \bar{r} \cdot \hat{x} - \frac{Gm_2}{|\bar{r}|^3} \bar{r} \cdot \hat{x}$$

$$\therefore \ddot{y} + 2\dot{\theta}\dot{x} - \dot{\theta}^2 y = - \frac{Gm_1}{|\bar{r}|^3} \bar{r} \cdot \hat{y} - \frac{Gm_2}{|\bar{r}|^3} \bar{r} \cdot \hat{y}$$

$$\therefore \ddot{z} = - \frac{Gm_1}{|\bar{r}|^3} \bar{r} \cdot \hat{z} - \frac{Gm_2}{|\bar{r}|^3} \bar{r} \cdot \hat{z}$$

On RHS we only take \hat{x} , \hat{y} , or \hat{z} components

b) Characteristic Quantities

$$l^* = D_1 + D_2$$

$$m^* = m_1 + m_2$$

$$t^* = \left[\frac{(D_1 + D_2)^3}{G(m_1 + m_2)} \right]^{1/2}$$

	l^* (km)	m^* (kg)	t^* (s)
1) Sun-Earth	1.496×10^8	1.9886×10^{30}	5.0226×10^6
2) Earth-Moon	3.844×10^5	6.0461×10^{24}	3.7519×10^5
3) Sun-Jupiter	7.7834×10^8	1.9905×10^{30}	5.9519×10^7
4) Saturn-Jupiter	1.2219×10^8	5.6864×10^{26}	2.1952×10^5
5) Sun-Mars	2.2914×10^8	1.9886×10^{30}	9.4468×10^6

gravitational constant

Continued

	r^* (km)	m^* (kg)	t^* (s)
6) Mars - Phobos	7.376×10^3	6.4174×10^{23}	4.3869×10^2
7) Jupiter - Europa	6.711×10^5	1.8987×10^{27}	4.8839×10^4
8) Uranus - Oberon	5.835×10^5	8.6828×10^{25}	1.8516×10^5
9) Neptune - Triton	3.54789×10^5	1.0246×10^{16}	8.0805×10^4
10) Pluto - Charon	1.7536×10^4	1.6255×10^{22}	7.0505×10^4

t^* is close to the formulation of Period. So $2\pi t^*$ gives the orbital period of the these systems.

r^* is just the radial distance on the semi major axis between two bodies. $r = a$ because we assume motion to be circular.

m^* is the M we used in our previous notation

c) Now let us go back to the differential equations we derived. But first we need to define some non-dimensional quantities

$$\text{let } \frac{m_2}{m^*} = \lambda \quad \text{①} \quad \text{Then } m_1 + m_2 = m_1 + \lambda M^* = m^* \\ \therefore \frac{m_1}{m^*} = 1 - \lambda \quad \text{②}$$

$$\bar{d}_i = \frac{\bar{D}_i}{C} \quad \text{where } i=1,2 \quad \text{Note: } \bar{d}_i \text{ is not the same as } \bar{d}$$

$$\bar{r} = \frac{\bar{R}}{C}, \quad \bar{d} = \frac{\bar{D}}{C}$$

$$a = \frac{\bar{a}}{C} = 1 \text{ b/c because of a circular orbit} \\ a \text{ is the nondimensional } \rightarrow \text{semi-major axis}$$

continued ...

$$G = \frac{\tilde{G}}{(l^*)^3} m^*(t^*)^2 = 1 \quad \text{non dimensional gravitational constant}$$

$$\dot{\theta} = N = \left[\frac{\tilde{G}(m_2 + m_1)}{a^3} \right]^{1/2} = \left[\frac{\tilde{G} m^*}{(a l^*)^3} \right]^{1/2} = \left[\frac{\tilde{G} m^*}{(l^*)^3} \right]^{1/2}$$

$$n = N t^* = 1 \quad \text{Nondimensional mean motion}$$

$$\bar{\rho} = \frac{\tilde{\rho}}{l^*} \quad \tau = \frac{t}{l^*} \quad \therefore \dot{\bar{\rho}} = \frac{\dot{\tilde{\rho}}}{l^*} t^* \quad \ddot{\bar{\rho}} = \frac{\ddot{\tilde{\rho}}}{l^*} (t^*)^2$$

$$\therefore \bar{\rho}'' = -\frac{\tilde{G} m_1}{D^3} \bar{D} - \frac{\tilde{G} m_2}{R^3} \bar{R}$$

$$\begin{aligned} \text{RHS} &\rightarrow -\frac{\left[\frac{(l^*)^3}{m^*(t^*)^2}\right]\left[(1-\mu)m^*\right]\left[\bar{d}l^*\right]}{(|\bar{d}|l^*)^3} - \frac{\left[\frac{(l^*)^3}{m^*(t^*)^2}\right][\mu m]\left[\bar{r}l^*\right]}{(|\bar{r}|l^*)^3} \\ &= \frac{(1-\mu)l^*}{(t^*)^2} \frac{\bar{d}}{|\bar{d}|^3} - \frac{\mu l^*}{(t^*)^2} \frac{\bar{r}}{|\bar{r}|^3} \end{aligned}$$

Now recall we derived LHS in part (a)

$$\begin{aligned} &\bar{\rho}'' + 2\dot{\theta} \bar{i} \cdot \hat{y} - 2\dot{\theta} \bar{j} \cdot \hat{x} - \dot{\theta}^2 \hat{x} \cdot \hat{x} - \dot{\theta}^2 \bar{y} \cdot \hat{y} \\ &= \left[\frac{\ddot{\bar{\rho}} l^*}{(t^*)^2} \right] + 2\left[\frac{n}{t^*} \right] \left[\frac{x}{l^*} \right] \hat{y} - 2\left[\frac{n}{t^*} \right] \left[\frac{y}{l^*} \right] \hat{x} - \left[\frac{n}{t^*} \right]^2 \hat{x} \cdot \hat{x} \\ &\quad - \left[\frac{n}{t^*} \right]^2 \hat{y} \cdot \hat{y} \\ &= \frac{\ddot{\bar{\rho}} l^*}{(t^*)^2} + \frac{2n \dot{x} \bar{i}}{(t^*)^2} \hat{j} - \frac{2n \dot{y} \bar{i}}{(t^*)^2} \hat{x} - \frac{n^2 x \dot{x} \hat{x}}{(t^*)^2} - \frac{n^2 y \dot{y} \hat{y}}{(t^*)^2} \end{aligned}$$

Continue...

Combine LHS and RHS, note $(\vec{t}^*)^2$ can be cancelled on both sides and so can \vec{t}^* :

$$\ddot{\vec{r}} + 2\vec{x}\hat{y} - 2\vec{y}\hat{x} - n^2\vec{x}\hat{x} - n^2\vec{y}\hat{y} = \frac{(1-\mu)\vec{d}}{|\vec{d}|^3} - \frac{\mu\vec{r}}{|\vec{r}|^3}$$

Now let us define \bar{d} and \bar{r}

$$\text{definition of c.m. } \Rightarrow m_1\bar{D}_1 + m_2\bar{D}_2 = 0$$

$$\frac{m_1}{m}\bar{D}_1 + \frac{m_2}{m}\bar{D}_2 = 0 \Rightarrow (1-\mu)\bar{D}_1 = -\mu\bar{D}_2$$

$$\therefore \frac{\bar{D}_1}{\bar{D}_2} = \frac{\mu}{(\mu-1)} \quad \therefore \bar{D}_1 = \mu \quad \bar{D}_2 = \mu-1$$

$$\bar{d} = \bar{d}_1 + \bar{D}_1 = (x+\mu) \hat{x} + y \hat{y} + z \hat{z}$$

$$\bar{r} = \bar{d}_2 + \bar{R} = (x+\mu-1) \hat{x} + y \hat{y} + z \hat{z}$$

Now let us split everything into individual components

$$\ddot{x} - 2n\vec{y}\hat{x} - n^2\vec{x}\hat{x} = -\frac{(1-\mu)(x+\mu)}{d^3} - \frac{\mu(x-1+\mu)}{r^3}$$

$$\ddot{y} + 2n\vec{x}\hat{y} - n^2\vec{y}\hat{y} = -\frac{(1-\mu)y}{d^3} - \frac{\mu y}{r^3}$$

$$\ddot{z} = -\frac{(1-\mu)z}{d^3} - \frac{\mu z}{r^3}$$

$$\text{Note } d = |\vec{d}| = ((x+\mu)^2 + y^2 + z^2)^{1/2}$$

$$r = |\vec{r}| = ((x+\mu-1)^2 + y^2 + z^2)^{1/2}$$

Equation is exactly the same as notes

PSB2

```
clear
close all
clc

SS = SolarS;
systems = {'Sun-Earth', 'Earth-Moon', 'Sun-Jupiter', 'Saturn-
Titan', 'Sun-Mars', 'Mars-Phobos', 'Jupiter-Europa', 'Uranus-
Oberon', 'Netune-Triton', 'Pluto-Charon'};
param = {'-', 'l* (km)', 'm* (kg)', 't* (s)'};
G = 6.6738*10^-20;

dim_vals = num2cell(zeros(10,3));
dim_vals = [param; systems',dim_vals];

[dim_vals{2,2}, dim_vals{2,3}, dim_vals{2,4}] =
charE(SS.dEarth,0,SS.mSun/G,SS.mEarth/G);
[dim_vals{3,2}, dim_vals{3,3}, dim_vals{3,4}] =
charE(SS.dM_E,0,SS.mMoon/G,SS.mEarth/G);
[dim_vals{4,2}, dim_vals{4,3}, dim_vals{4,4}] =
charE(SS.dJupiter,0,SS.mSun/G,SS.mJupiter/G);
[dim_vals{5,2}, dim_vals{5,3}, dim_vals{5,4}] =
charE(SS.dTitan_S,0,SS.mSaturn/G,SS.mTitan/G);
[dim_vals{6,2}, dim_vals{6,3}, dim_vals{6,4}] =
charE(SS.dMars,0,SS.mSun/G,SS.mMars/G);
[dim_vals{7,2}, dim_vals{7,3}, dim_vals{7,4}] =
charE(SS.dPhobos_M,0,SS.mPhobos/G,SS.mMars/G);
[dim_vals{8,2}, dim_vals{8,3}, dim_vals{8,4}] =
charE(SS.dEuropa_J,0,SS.mJupiter/G,SS.mEuropa/G);
[dim_vals{9,2}, dim_vals{9,3}, dim_vals{9,4}] =
charE(SS.dOberon_U,0,SS.mUranus/G,SS.mOberon/G);
[dim_vals{10,2}, dim_vals{10,3}, dim_vals{10,4}] =
charE(SS.dTriton_N,0,SS.mNeptune/G,SS.mTriton/G);
[dim_vals{11,2}, dim_vals{11,3}, dim_vals{11,4}] =
charE(SS.dCharon_P,0,SS.mPluto/G,SS.mCharon/G);

dim_vals

dim_vals =
11×4 cell array

Columns 1 through 2

{'-' }      {'l* (km)' }
{'Sun-Earth'} {[1.495978707000000e+08]}
{'Earth-Moon'} {[384400]}
{'Sun-Jupiter'} {[7.783408166930000e+08]}
{'Saturn-Titan'} {[1221865]}
{'Sun-Mars'} {[2.279438166930000e+08]}
```

```
{'Mars-Phobos'} {[ 9376 ]}  
{'Jupiter-Europa'} {[ 671100 ]}  
{'Uranus-Oberon'} {[ 583500 ]}  
{'Neptune-Triton'} {[ 354759 ]}  
{'Pluto-Charon'} {[ 17536 ]}
```

Columns 3 through 4

```
{'m* (kg)'} {[ 1.988564814924503e+30 ]}  
{[ 6.046079334112500e+24 ]}  
{[ 1.990457502260298e+30 ]}  
{[ 5.686356472639275e+26 ]}  
{[ 1.988559484046633e+30 ]}  
{[ 6.417380639415171e+23 ]}  
{[ 1.898707950157032e+27 ]}  
{[ 8.682821528921902e+25 ]}  
{[ 1.024597968589110e+26 ]}  
{[ 1.625490107145854e+22 ]}  
't* (s)' {[ 5.022635348655218e+06 ]}  
{[ 3.751902586518695e+05 ]}  
{[ 5.957878742866884e+07 ]}  
{[ 2.192457595655987e+05 ]}  
{[ 9.446824268941369e+06 ]}  
{[ 4.386932017240478e+03 ]}  
{[ 4.883882198292967e+04 ]}  
{[ 1.851587582503429e+05 ]}  
{[ 8.080473196142506e+04 ]}  
{[ 7.050453393398008e+04 ]}
```

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Problem B3:

Given locations of the equilibrium points in any 3-body system

$$\bar{F}\bar{U} = \bar{0}$$

Find: a) Show that the coordinates of the equilibrium point L_2 on the far side of smaller primary is

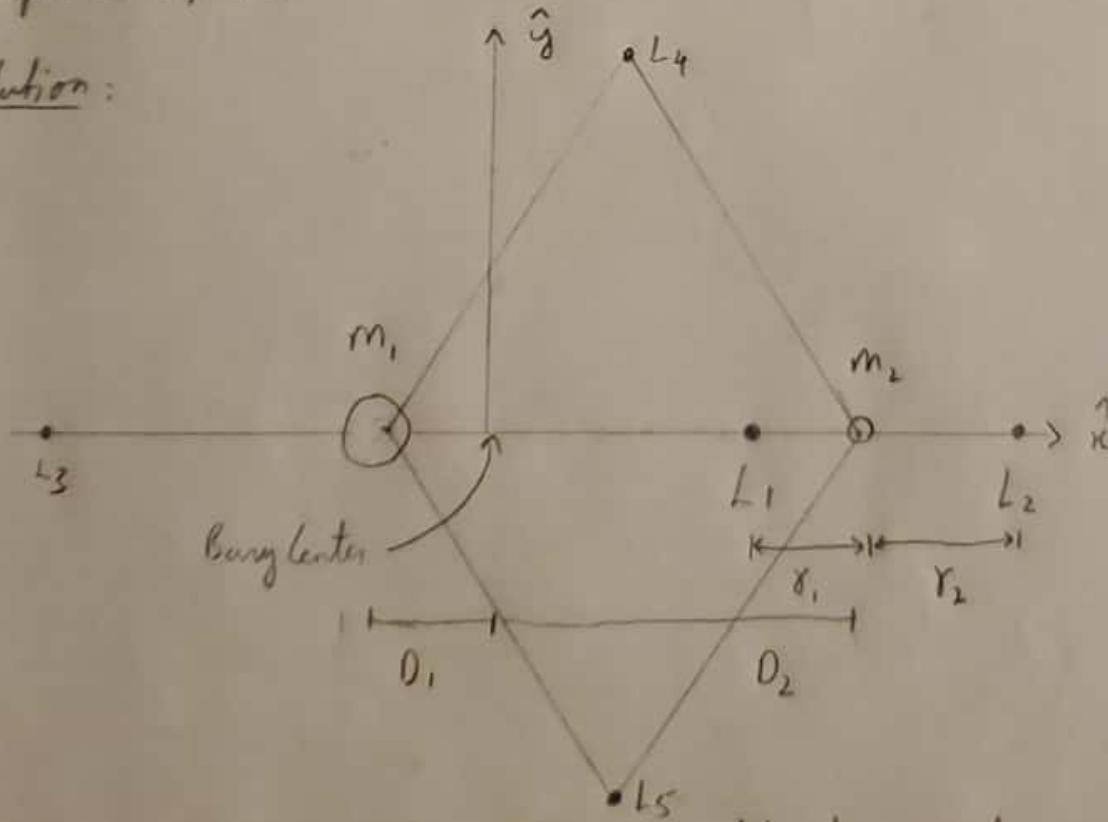
$$x_2 = 1 - \mu + Y_2, \quad y_2 = z_2 = 0$$

$$\text{and } Y_2 \Rightarrow \frac{1-\mu}{(1+Y_2)} + \frac{\mu}{Y_2^2} = 1 - \mu + Y_2$$

- b) Solve equation using Newton Raphson and derive update equations
What is L_2 for Earth-Moon, Sun-Earth, Jupiter-Europa, Saturn-Titan, Pluto-Charon. (L_2 and Y_2 in dim and non-dim)
- c) For libration points L_1 and L_3 , find r_1 and Y_3 . Derive new update equation.

Solution:

a)



Note in the previous problem we defined non-dimensional from barycenter to m_1 and m_2

Continued...

$$-D_1 m_1 + D_2 m_2 = 0 \quad \leftarrow \text{Definition of C.M., careful of direction}$$

$$\therefore D_1 \frac{m_1}{m_*} + D_2 \frac{m_2}{m_*} = 0 \quad \begin{aligned} &\text{Note when deriving 3-body EOM} \\ &\text{we defined } \frac{m_1}{m_*} = 1-\mu \text{ and} \end{aligned}$$

$$\therefore D_1(1-\mu) = +D_2\mu$$

$$\therefore \frac{D_1}{D_2} = \frac{+\mu}{1-\mu} \quad \text{that } \frac{m_2}{m_*} = \mu$$

Thus point L_2 on the previous figure can be written as follows:

$$x_2 = 1 - \mu + r_2 \quad \text{and} \quad y = z = 0$$

Now we also define V^* in the notes as the pseudo potential

$$V^* = \frac{(1-\mu)}{d} + \frac{\mu}{r} + \frac{1}{2} n^2 (x^2 + y^2) \quad \begin{aligned} d &= [(x+\mu)^2 + y^2 + z^2]^{1/2} \\ r &= [(x-1+\mu)^2 + y^2 + z^2]^{1/2} \end{aligned}$$

$$\therefore \bar{\nabla} V^* = \frac{\partial V^*}{\partial x} \hat{x} + \frac{\partial V^*}{\partial y} \hat{y} + \frac{\partial V^*}{\partial z} \hat{z} = \bar{0}$$

$$\hat{x} \Rightarrow \frac{\partial V}{\partial x} = \frac{(1-\mu)(x+\mu)}{d^3} - \frac{\mu(x-1+\mu)}{r^3} + n^2 x = 0$$

$$\hat{y} \Rightarrow \frac{\partial V}{\partial y} = -\frac{(1-\mu)y}{d^3} - \frac{\mu y}{r^3} + n^2 y = 0$$

$$\hat{z} \Rightarrow \frac{\partial V}{\partial z} = -\frac{(1-\mu)z}{d^3} - \frac{\mu z}{r^3} = 0$$

Continued...

$$\therefore y = 2 = 0 \quad \therefore \hat{x} \Rightarrow \frac{(1-\mu)(\mu+\mu)}{d^3} - \frac{\mu(\mu-1+\mu)}{r^3} + 1 - \mu + Y_2 = 0$$

$$Y_2 = 1 - \mu + Y_2$$

$$\therefore -\frac{(1-\mu)(1-\mu+Y_2+\mu)}{((1-\mu+Y_2+\mu)^2)^{1/2}} - \frac{\mu(1-\mu+Y_2-1+\mu)}{((1-\mu+Y_2-1+\mu)^2)^{1/2}} + 1 - \mu + Y_2 = 0$$

$$\therefore -\frac{(1-\mu)(1+Y_2)}{(1+Y_2)^{3/2}} - \frac{\mu Y_2}{Y_2^{3/2}} + 1 - \mu + Y_2 = 0$$

$$\therefore \boxed{\frac{(1-\mu)}{(1+Y_2)^2} + \frac{\mu}{Y_2^2} = 1 - \mu + Y_2}$$

$$\boxed{Y_2 = 1 - \mu + Y_2}$$

b) Let us start with the Y_2 relationship. We can turn it into a polynomial, which is easier to solve and plot.

$$\frac{(1-\mu)}{(1+Y_2)^2} + \frac{\mu}{Y_2^2} = 1 - \mu + Y_2$$

$$\therefore (1-\mu)Y_2^2 + \mu(1+Y_2)^2 = (1-\mu+Y_2)(1+Y_2)^2 Y_2^2$$

$$\text{LHS: } Y_2^2 + 2\mu Y_2 + \mu$$

$$\text{RHS: } Y_2^5 + Y_2^4(3-\mu) + Y_2^3(3-2\mu) + Y_2^2(1-\mu)$$

\therefore combine RHS and LHS

$$\therefore 0 = Y_2^5 + Y_2^4(3-\mu) + Y_2^3(3-2\mu) - \mu Y_2^2 - 2Y_2\mu - \mu = f(Y_2)$$

Now let solve for $f(Y_2) = 0$ using Newton Raphson

Continued...

$$\cdot f'(Y_2) = 5Y_2^4 + 4Y_2^3(3-m) + 3Y_2^2(3-2m) - 2mY_2 - 2m$$

Newton-Raphson:

$$Y_{2,n+1} = Y_n - \frac{f(Y_{2,n})}{f'(Y_{2,n})}$$

Once we have Y_2 we can get x_2 , and then dimensionize them using L^*

Note: The $f(Y_2)$ is a 5th order polynomial so there are 5 solutions. We want the real solution. It is smart to plot the equations to check to confirm the number of roots as the Newton-Raphson method may not locally converge.

Secondly: it is smart to check for 0 you cannot use.

Set $f'(Y_2) = 0$ \therefore the Y_2 which is a root of $f'(Y_2)$ will cause a division error

Note x_0 also cannot be $0 = Y_n - \frac{f(Y_{2,n})}{f'(Y_{2,n})}$

This x_0 will only produce a trivial solution.

	Sun Earth	Earth Moon	Saturn Titan	Jupiter Europa	Pluto (Charon)
r_2 (-)	0.010037	0.167833	0.043492	0.0204864	0.3530021
L_2 (-)	1.01003	1.155682	1.043255	1.0204612	1.257854
r_2 (km)	1.5015×10^6	6.45149×10^4	5.314144×10^4	1.37484×10^4	6.19024×10^3
L_2 (km)	1.51099×10^2	4.44244×10^5	1.274717×10^6	6.94832×10^5	2.70577×10^4

Continued...

c) We can use the same method for γ_1 and γ_3

Note for both have $y = z = 0$, so we only worry about direction in x -direction

$$\therefore \dot{x}_1 = 1 - \mu - \gamma_1$$

$$\frac{d\dot{x}}{dx} = 0 \Rightarrow -\frac{(1-\mu)(x+\mu)}{\left[(x+\mu)^2\right]^{3/2}} - \frac{\mu(x-1+\mu)}{\left[\left(x-1+\mu\right)^2\right]^{3/2}} + \mu^2 x^2$$

$$\therefore \frac{(1-\mu)(1-\mu-\gamma_1+\mu)}{(1-\mu-\gamma_1+\mu)^3} + \frac{\mu(1-\mu-\gamma_1+\mu)}{(1-\mu-\gamma_1+\mu)^3} = 1 - \mu - \gamma_1$$

$$\therefore \frac{(1-\mu)(1-\gamma_1)}{(1-\gamma_1)^3} + \frac{\mu(1-\gamma_1)}{(1-\gamma_1)^3} = 1 - \mu - \gamma_1$$

$$\therefore \frac{(1-\mu)}{(1-\gamma_1)^2} + \frac{\mu}{\gamma_1^2} = 1 - \mu - \gamma_1 \quad \text{Now we have the same form as before}$$

Let us get the $f(\gamma_1) = 0$

$$\therefore (1-\mu)\gamma_1^2 + \mu(1-\gamma_1)^2 = (1-\mu-\gamma_1)(1-\gamma_1)^2 \gamma_1^2$$

$$\therefore \text{LHS: } \gamma_1^2 - 2\mu\gamma_1 + \mu$$

$$\text{RHS: } -\gamma_1^5 + \gamma_1^4(3-\mu) + \gamma_1^3(2\mu-3) + \gamma_1^2(1-\mu)$$

$$f(\gamma_1) = -\gamma_1^5 + \gamma_1^4(3-\mu) + \gamma_1^3(2\mu-3) - \mu\gamma_1^2 + 2\mu\gamma_1 - \mu$$

$$f'(\gamma_1) = -5\gamma_1^4 + 4\gamma_1^3(3-\mu) + 3\gamma_1^2(2\mu-3) - 2\mu\gamma_1 + 2\mu$$

Now we can use the Newton-Raphson on the equation

$$\gamma_{1,n+1} = \gamma_{1,n} - \frac{f(\gamma_{1,n})}{f'(\gamma_{1,n})}$$

Continued.

	Sun Earth	Earth Moon	Saturn Titan	Jupiter Europa	Pluto Charon
$\gamma_1 (-)$	0.010037	0.167833	0.043492	0.0204864	0.355002
$L_1 (-)$	0.99996	0.8200167	0.9562715	0.9794882	0.551849
$Y_1 (\text{km})$	1.50153×10^6	6.45149×10^4	5.314144×10^4	1.374248×10^6	6.19025×10^5
$L_1 (\text{km})$	1.480959×10^9	3.15214×10^5	1.68434×10^6	6.57334×10^5	9.67723×10^5

we follow the same sort of steps for γ_3

$$x_3 = -\mu - \gamma_3 \quad \text{again } y = z = 0$$

$$\frac{dV}{dx} = 0 = \frac{-(1-\mu)(x+\mu)}{[(x+\mu)^2]^{\frac{1}{2}} r^3} - \frac{\mu(x-1+\mu)}{[(x-1+\mu)^2]^{\frac{1}{2}} r^3} + n^2 x$$

$$\therefore \frac{-(1-\mu)(-\mu - \gamma_3 + \mu)}{(-\mu - \gamma_3 + \mu)^2} - \frac{\mu(-\mu - \gamma_3 - 1 + \mu)}{(-\mu - \gamma_3 - 1 + \mu)^2} = \mu + \gamma_3$$

$$\therefore -\frac{(1-\mu)}{\gamma_3^2} - \frac{\mu}{(\gamma_3 + 1)^2} = \mu + \gamma_3$$

Now turn the equation above into a polynomial $f(\gamma_3)$

$$-(1-\mu)(\gamma_3 + 1)^2 - \mu \gamma_3^2 = (\mu + \gamma_3)(\gamma_3 + 1)^2 \gamma_3^2$$

$$\text{LHS} : -[\gamma_3^2 + \gamma_3(2-2\mu) - \mu + 1]$$

$$\text{RHS} : \gamma_3^5 + \gamma_3^4(\mu+2) + \gamma_3^3(2\mu+1) + \mu \gamma_3^2$$

$$\therefore \text{RHS} - \text{LHS} = f(\gamma_3) = \gamma_3^5 + \gamma_3^4(\mu+2) + \gamma_3^3(2\mu+1) + \gamma_3^2(\mu+1) \\ + \gamma_3(2-2\mu) - \mu + 1$$

$$f'(\gamma_3) = 5\gamma_3^4 + 4\gamma_3^3(\mu+2) + 3\gamma_3^2(2\mu+1) + 2\gamma_3(\mu+1) \\ + 2 - 2\mu$$

Continued...

Turn the previous 2 equations into Newton-Raphson method

$$\therefore \gamma_{3,n+1} = \gamma_{3,n} - \frac{f(\gamma_{3,n})}{f'(\gamma_{3,n})}$$

	Sun Earth	Earth Moon	Saturn Titan	Jupiter Europa	Pluto Charon
$\gamma_3 (-)$	1.0100371	1.67832755	-1.04349207	1.0204865	1.3530021
$L_3 (-)$	-1.010040	-1.1799833	-1.0437287	-1.0205118	-1.448150
$\gamma_3 (\text{km})$	1.51099×10^8	4.489149×10^5	1.27501×10^6	6.84848×10^6	2.3762×10^4
$L_3 (\text{km})$	1.51100×10^8	-4.53586×10^5	-1.275296×10^6	-6.84865×10^6	-2.5395×10^4

Note: So equation did blow up at times due to initial condition chosen.

PSB3

```
clear
close all
clc
```

PSB3 Part b

```
SS = SolarS;
systems = {'-', 'Sun-Earth', 'Earth-Moon', 'Saturn-Titan', 'Jupiter-
Europa', 'Pluto-Charon'};
param = {'l* (km)', 'm* (kg)', 'mIU' , 'gamma_2 (-)', 'L_2 (-)', 'gamma_2
(km)', 'L_2 (km)', 'gamma_1 (-)', 'L_1 (-)', 'gamma_1 (km)', 'L_1
(km)', 'gamma_3 (-)', 'L_3 (-)', 'gamma_3 (km)', 'L_3 (km)' };
G = 6.6738*10^-20;

dim_vals = num2cell(zeros(15,5));
dim_vals = [systems; param',dim_vals];

% Solution

[dim_vals{2,2}, dim_vals{3,2}, ~] = charE(SS.dEarth,0,SS.mSun/
G,SS.mEarth/G); % Earth Sun
[dim_vals{2,3}, dim_vals{3,3}, ~] = charE(SS.dM_E,0,SS.mMoon/
G,SS.mEarth/G); % Earth Moon
[dim_vals{2,4}, dim_vals{3,4}, ~] = charE(SS.dTitan_S,0,SS.mSaturn/
G,SS.mTitan/G); % Saturn Titan
[dim_vals{2,5}, dim_vals{3,5}, ~] = charE(SS.dEuropa_J,0,SS.mJupiter/
G,SS.mEuropa/G); % Jupiter Europa
[dim_vals{2,6}, dim_vals{3,6}, ~] = charE(SS.dCharon_P,0,SS.mPluto/
G,SS.mCharon/G); % Pluto Charon

dim_vals{4,2} = SS.mEarth/dim_vals{3,2}/G;
dim_vals{4,3} = SS.mMoon/dim_vals{3,3}/G;
dim_vals{4,4} = SS.mTitan/dim_vals{3,4}/G;
dim_vals{4,5} = SS.mEuropa/dim_vals{3,5}/G;
dim_vals{4,6} = SS.mCharon/dim_vals{3,6}/G;

for n = 2:6
    % Lagrange Point 2
    dim_vals{5,n} = abs(L2_NRmethod(dim_vals{4,n}*1.1,dim_vals{4,n},
10^-8));
    dim_vals{6,n} = 1-dim_vals{4,n} + dim_vals{5,n};
    dim_vals{7,n} = dim_vals{5,n}*dim_vals{2,n};
    dim_vals{8,n} = dim_vals{6,n}*dim_vals{2,n};

    % Lagrange Point 1
    dim_vals{9,n} = abs(L1_NRmethod(dim_vals{4,n}*.7,dim_vals{4,n},
10^-8));
    dim_vals{10,n} = 1-dim_vals{4,n} + dim_vals{9,n};
    dim_vals{11,n} = dim_vals{9,n}*dim_vals{2,n};
```

```

dim_vals{12,n} = dim_vals{10,n}*dim_vals{2,n};

% Lagrange Point 3
dim_vals{13,n} = abs(L3_NRMETHOD(-.9,dim_vals{4,n}, 10^-8,""));
dim_vals{14,n} = dim_vals{4,n} - dim_vals{13,n};
dim_vals{15,n} = dim_vals{13,n}*dim_vals{2,n};
dim_vals{16,n} = dim_vals{14,n}*dim_vals{2,n};
end

```

dim_vals

dim_vals =

16×6 cell array

Columns 1 through 4

{'-'}	{'Sun-Earth'}	{'Earth-Moon'}
{'Saturn-Titan'}		
{'1* (km)'}	{[1.4960e+08]}	{[384400]}
1221865]		
{'m* (kg)'}	{[1.9886e+30]}	{[6.0461e+24]}
5.6864e+26]		
{'m _i '}	{[3.0035e-06]}	{[0.0122]}
2.3662e-04]		
{'gamma_2 (-)'}]	{[0.0100]}	{[0.1678]}
0.0435]		
{'L_2 (-)'}	{[1.0100]}	{[1.1557]}
1.0433]		
{'gamma_2 (km)'}	{[1.5015e+06]}	{[6.4515e+04]}
5.3141e+04]		
{'L_2 (km)'}	{[1.5110e+08]}	{[4.4424e+05]}
1.2747e+06]		
{'gamma_1 (-)'}	{[0.0100]}	{[0.1678]}
0.0435]		
{'L_1 (-)'}	{[1.0100]}	{[1.1557]}
1.0433]		
{'gamma_1 (km)'}	{[1.5015e+06]}	{[6.4515e+04]}
5.3141e+04]		
{'L_1 (km)'}	{[1.5110e+08]}	{[4.4424e+05]}
1.2747e+06]		
{'gamma_3 (-)'}	{[1.0100]}	{[1.1678]}
1.0435]		
{'L_3 (-)'}	{[-1.0100]}	{[-1.1557]}
-1.0433]		
{'gamma_3 (km)'}	{[1.5110e+08]}	{[4.4891e+05]}
1.2750e+06]		
{'L_3 (km)'}	{[-1.5110e+08]}	{[-4.4424e+05]}
{[-1.2747e+06]}		

Columns 5 through 6

```
{'Jupiter-Europa'}      {'Pluto-Charon'}
{[ 671100]}             {[ 17536]}
{[ 1.8987e+27]}         {[ 1.6255e+22]}
{[ 2.5280e-05]}         {[ 0.0951]}
{[ 0.0205]}              {[ 0.3530]}
{[ 1.0205]}              {[ 1.2579]}
{[ 1.3748e+04]}         {[ 6.1902e+03]}
{[ 6.8483e+05]}         {[ 2.2058e+04]}
{[ 0.0205]}              {[ 0.3530]}
{[ 1.0205]}              {[ 1.2579]}
{[ 1.3748e+04]}         {[ 6.1902e+03]}
{[ 6.8483e+05]}         {[ 2.2058e+04]}
{[ 1.0205]}              {[ 1.3530]}
{[ -1.0205]}             {[ -1.2579]}
{[ 6.8485e+05]}         {[ 2.3726e+04]}
{[ -6.8483e+05]}        {[ -2.2058e+04]}
```

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Gamma1 Newton Rhapsom

```
function g1_n1 = L1_NRmethod(g1_n, miu, acc)

err = acc*2;
n = 1;

while (err > acc)

    fn = -g1_n^5 + g1_n^4 * (3-miu) + g1_n^3 * (2*miu-3) + g1_n^2 * (-
miu) + 2*miu*g1_n - miu;
    fn_p = -5*g1_n^4 + 4*g1_n^3 * (3-miu) + 3*g1_n^2 * (2*miu-3) +
2*g1_n*(-miu) + 2*miu;

    g1_n1 = g1_n - fn/fn_p;

    err = abs(g1_n1-g1_n)/abs(g1_n);
    g1_n = g1_n1;
    n = n+1;

end

end
```

Not enough input arguments.

Error in L1_NRmethod (line 4)
err = acc*2;

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Gamma2 Newton Rhaps

```
function g2_n1 = L2_NRmethod(g2_n, miu, acc)

err = acc*2;
n = 1;

while (err > acc)

    fn = g2_n^5 + g2_n^4 * (3-miu) + g2_n^3 * (3-2*miu) - miu*g2_n^2 -
2*miu*g2_n - miu;
    fn_p = 5*g2_n^4 + 4*g2_n^3 * (3-miu) + 3*g2_n^2 * (3-2*miu) -
2*g2_n*miu - 2*miu;

    g2_n1 = g2_n - fn/fn_p;

    err = abs(g2_n1-g2_n)/abs(g2_n);
    g2_n = g2_n1;
    n = n+1;

end

end
```

Not enough input arguments.

Error in L2_NRmethod (line 4)
err = acc*2;

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Gamma3 Newton Rhapsom

```
function g3_n1 = L3_NRmethod(g3_n, miu, acc, pl)

err = [acc*2];
n = 1;

while (err(end) > acc)

    fn = g3_n^5 + g3_n^4 *(miu+2) + g3_n^3 * (2*miu + 1) + g3_n^2
    *(miu + 1) + g3_n*(2-2*miu) - miu + 1;
    fn_p = 5*g3_n^4 + 4*g3_n^3 *(miu+2) + 3*g3_n^2 * (2*miu + 1) +
    2*g3_n*(miu+1) - 2*miu + 2;

    g3_n1 = g3_n - fn/fn_p;

    err(n) = abs(g3_n1-g3_n)/abs(g3_n);

    if pl == "plot"
        g3_nvec(n) = g3_n;
    end
    g3_n = g3_n1;
    n = n+1;

    if n > 400
        err(end) = acc/10;
    end
end

if pl == "plot"
    figure
    plot(1:n-1,g3_nvec, '-k')
    grid on
    grid minor
    title('gamma value for each Iteration of Newton Rhapsom')
    xlabel('n')
    ylabel('gamma')

    figure
    plot(1:n-2,err(1:end-1), '-r')
    grid on
    grid minor
    title('Error for each Iteration of Newton Rhapsom')
    xlabel('n')
    ylabel('Error')
end
end
```

Not enough input arguments.

```
Error in L3_NRmethod (line 4)
err = [acc^2];
```

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L3 Plot

To check for other convergences

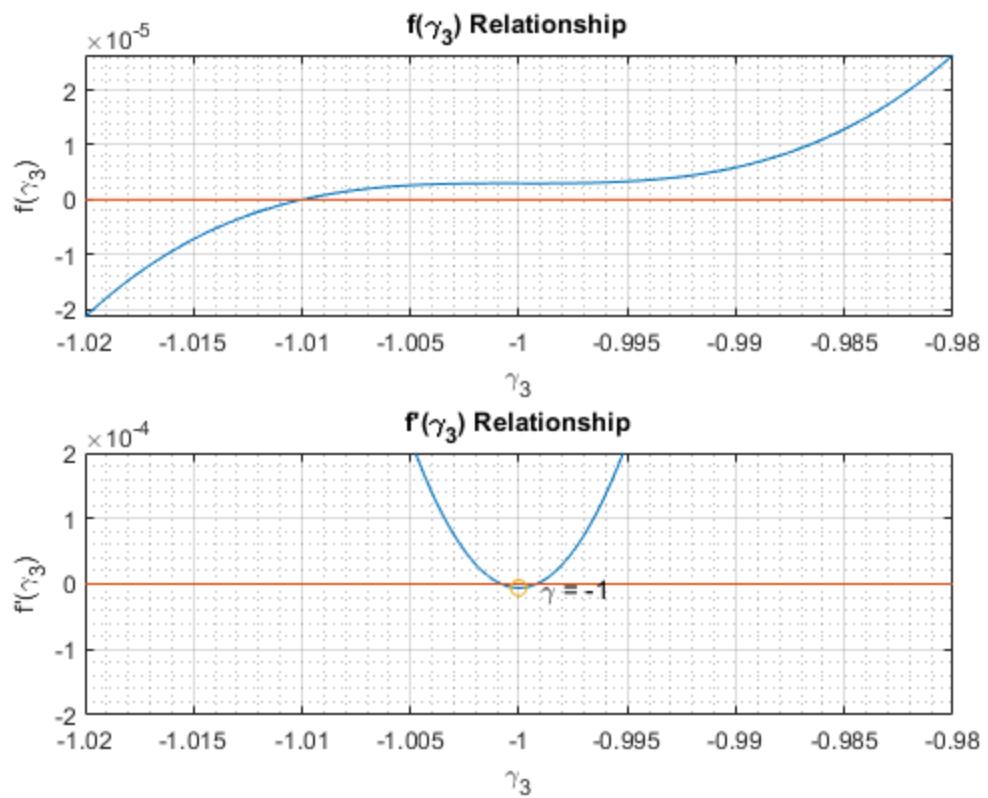
```
clear
close all
clc

miu = 3.0035e-06;

g3 = linspace(-1.02,-.98,1000);
fn = g3.^5 + g3.^4 *(miu+2) + g3.^3 * (2*miu + 1) + g3.^2 *(miu + 1) +
g3*(2-2*miu) - miu + 1;
fn_p = 5*g3.^4 + 4*g3.^3 *(miu+2) + 3*g3.^2 * (2*miu + 1) + 2*g3*(miu
+1) - 2*miu + 2;

subplot(2,1,1)
plot(g3,fn)
hold on
plot(g3,zeros(size(g3)))
xlim([-1.02, -.98])
title('f(\gamma_3) Relationship')
xlabel('\gamma_3')
ylabel('f(\gamma_3)')
grid on
grid minor

subplot(2,1,2)
plot(g3,fn_p)
hold on
plot(g3,zeros(size(g3)))
plot(g3(find(min(fn_p)==fn_p)),min(fn_p), 'o')
ylim([- .2 .2]*10^-3)
xlim([-1.02, -.98])
title('f'(\gamma_3) Relationship')
text(g3(find(min(fn_p)==fn_p))* .999,min(fn_p)* .9,[ '\gamma = ' ,
num2str(g3(find(min(fn_p)==fn_p))))])
xlabel('\gamma_3')
ylabel('f'(\gamma_3)')
grid on
grid minor
```



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