

# ASSIGNMENT 5

## Algorithm for Study palnner with task remainder

Initial Setup

START PROGRAM and load any existing TASKS\_LIST from storage.

Enter the main program loop.

### 1. Main Loop & Menu Display

Get the CurrentDate from the system.

Display the main menu options: Add Task, View Schedule, Check Reminders, Mark Task Complete, Exit.

Get UserChoice.

### 2. Process: Add New Task (If UserChoice is 'Add Task')

Prompt the user to input the following details for the new task:

TaskName

DeadlineDate

Estimated Time (in hours, EstTime)

Priority (1=High, 2=Medium, 3=Low)

Create a new task record with IsComplete set to FALSE.

Add the new task record to the TASKS\_LIST.

Sort the entire TASKS\_LIST first by DeadlineDate (ascending) and then by Priority (ascending).

Output "Task added and schedule updated."

### 3. Process: View Daily Schedule (If UserChoice is 'View Schedule')

Initialize an empty SCHEDULE list and TOTAL\_STUDY\_HOURS to 0.

FOR EACH Task in the TASKS\_LIST:

a. IF Task's IsComplete is FALSE:

i. Determine TIME\_SLOT (e.g., 2 hours for High Priority, 1 hour for Medium, 0.5 hours for Low).

ii. Set TIME\_TO\_ALLOCATE to the minimum of TIME\_SLOT and the Task's EstTime remaining.

iii. IF TIME\_TO\_ALLOCATE is greater than 0:

\* Add TaskName and TIME\_TO\_ALLOCATE to the SCHEDULE list.

\* Increase TOTAL\_STUDY\_HOURS by TIME\_TO\_ALLOCATE.

Display the generated SCHEDULE and the TOTAL\_STUDY\_HOURS.

4. Process: Check Reminders (If UserChoice is 'Check Reminders')

Initialize REMINDERS\_SENT to 0.

FOR EACH Task in the TASKS\_LIST:

a. Calculate DaysUntilDeadline (Task.DeadlineDate - CurrentDate).

b. IF Task Priority is High (1) AND DaysUntilDeadline equals 3:

\* SEND a high-priority notification.

\* Increase REMINDERS\_SENT.

c. ELSE IF Task Priority is Medium (2) AND DaysUntilDeadline equals 5:

\* SEND a mid-term notification.

\* Increase REMINDERS\_SENT.

Output the count of REMINDERS\_SENT.

5. Process: Mark Task as Complete (If UserChoice is 'Mark Complete')

Prompt the user to input the TaskName to complete.

FOR EACH Task in the TASKS\_LIST:

a. IF Task's TaskName matches the input:

\* Set Task's IsComplete to TRUE.

\* Output confirmation and BREAK the loop.

6. Termination

IF UserChoice is 'Exit Program':

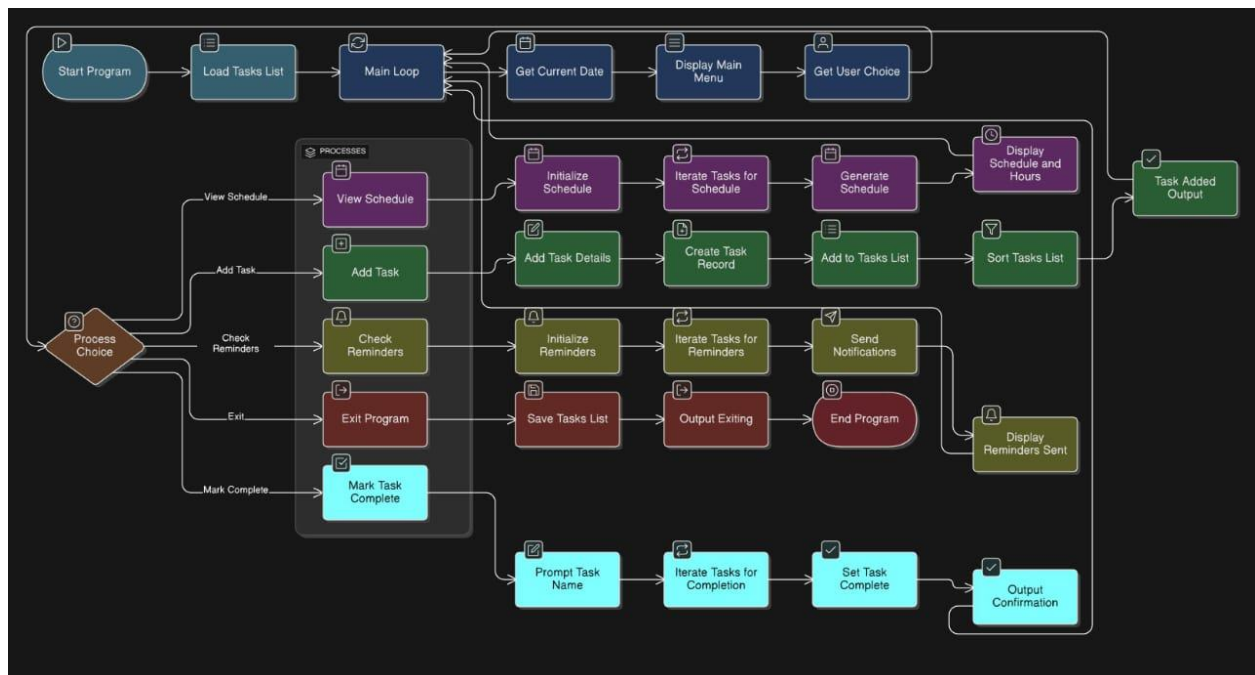
a. Save the current state of TASKS\_LIST to persistent storage.

b. Output "Exiting Program."

c. END PROGRAM.

IF UserChoice was not 'Exit Program', loop back to Step 3 to display the menu again

## Flowchart



# Linux Commnds

## 1. Pwd

```
MINGW64/c/Users/Dreesti
Dreesti@DESKTOP-F87BKA1 MINGW64 ~
$ pwd
/c/Users/Dreesti
Dreesti@DESKTOP-F87BKA1 MINGW64 ~
$ |
```

## 2. Ls -al

```
MINGW64/c/Users/Dreesti
Dreesti@DESKTOP-F87BKA1 MINGW64 ~
$ ls -al
total 6832
drwxr-xr-x 1 Dreesti 197121 0 Nov 11 19:42 ./
drwxr-xr-x 1 Dreesti 197121 0 Sep 12 20:07 ../
drwxr-xr-x 1 Dreesti 197121 0 May 7 2021 .android/
-rw-r--r-- 1 Dreesti 197121 192 Sep 3 11:50 .gitconfig
drwxr-xr-x 1 Dreesti 197121 0 Sep 16 2022 .idlerc/
drwxr-xr-x 1 Dreesti 197121 0 Oct 2 2023 .vscode/
drwxr-xr-x 1 Dreesti 197121 0 Oct 17 2024 '3D Objects'/
drwxr-xr-x 1 Dreesti 197121 0 Oct 17 2024 AppData/
-rwxr-xr-x 1 Dreesti 197121 32 Oct 17 2024 'Application Data' -> /c/Users/Dreesti/AppData/Roaming/
drwxr-xr-x 1 Dreesti 197121 0 Oct 17 2024 Contacts/
drwxr-xr-x 1 Dreesti 197121 60 Oct 17 2024 Cookies -> /c/Users/Dreesti/AppData/Local/Microsoft/Windows/DietCookies/
drwxr-xr-x 1 Dreesti 197121 0 Nov 22 13:36 Desktop/
drwxr-xr-x 1 Dreesti 197121 0 Nov 28 12:58 Documents/
drwxr-xr-x 1 Dreesti 197121 0 Nov 28 13:12 Downloads/
drwxr-xr-x 1 Dreesti 197121 0 Oct 17 2024 Favorites/
drwxr-xr-x 1 Dreesti 197121 0 Nov 28 11:46 IntelGraphicsProfiles/
drwxr-xr-x 1 Dreesti 197121 0 Oct 17 2024 Links/
-rwxr-xr-x 1 Dreesti 197121 30 Oct 17 2024 'Local Settings' -> /c/Users/Dreesti/AppData/Local/
drwxr-xr-x 1 Dreesti 197121 0 Aug 18 2020 MicrosoftEdgeBackups/
drwxr-xr-x 1 Dreesti 197121 0 Oct 17 2024 Music/
drwxr-xr-x 1 Dreesti 197121 26 Oct 17 2024 'My Documents' -> /c/Users/Dreesti/Documents/
-rw-r--r-- 1 Dreesti 197121 3670016 Nov 27 15:07 NTUSER.DAT
-rw-r--r-- 1 Dreesti 197121 65136 Oct 17 2024 NTUSER.DAT{b6adbfa2-8c89-11ef-ab74-c9ff36b776b6}.TN.b1f
-rw-r--r-- 1 Dreesti 197121 524288 Oct 17 2024 NTUSER.DAT{b6adbfa2-8c89-11ef-ab74-c9ff36b776b6}.TMContainer00000000000000000001.regtrans-ms
-rw-r--r-- 1 Dreesti 197121 524288 Oct 17 2024 NTUSER.DAT{b6adbfa2-8c89-11ef-ab74-c9ff36b776b6}.TMContainer00000000000000000002.regtrans-ms
-rwxr-xr-x 1 Dreesti 197121 68 Oct 17 2024 'Network' -> /c/Users/Dreesti/AppData/Roaming/Microsoft/Windows/Network_Shortcuts/
drwxr-xr-x 1 Dreesti 197121 0 Sep 8 19:48 'New folder'
drwxr-xr-x 1 Dreesti 197121 0 Nov 8 17:24 'New folder (2)'/
drwxr-xr-x 1 Dreesti 197121 0 Nov 11 15:35 'New folder (3)'/
drwxr-xr-x 1 Dreesti 197121 0 Sep 8 19:49 'New folder (4)'/
drwxr-xr-x 1 Dreesti 197121 0 Sep 8 19:58 'New folder (5)'/
drwxr-xr-x 1 Dreesti 197121 0 Jan 1 2021 'New_share/'
drwxr-xr-x 1 Dreesti 197121 0 Aug 4 2021 OneDrive/
drwxr-xr-x 1 Dreesti 197121 0 Nov 23 15:44 Pictures/
-rwxr-xr-x 1 Dreesti 197121 68 Oct 17 2024 'PrintHood' -> /c/Users/Dreesti/AppData/Roaming/Microsoft/Windows/Printer_Shortcuts/
drwxr-xr-x 1 Dreesti 197121 57 Oct 17 2024 Recent -> /c/Users/Dreesti/AppData/Roaming/Microsoft/Windows/Recent/
drwxr-xr-x 1 Dreesti 197121 0 Oct 17 2024 'Saved Games'/
drwxr-xr-x 1 Dreesti 197121 0 Oct 17 2024 Searches/
-rwxr-xr-x 1 Dreesti 197121 57 Oct 17 2024 'SendTo' -> /c/Users/Dreesti/AppData/Roaming/Microsoft/Windows/SendTo/
drwxr-xr-x 1 Dreesti 197121 61 Oct 17 2024 'Start Menu' -> /c/Users/Dreesti/AppData/Roaming/Microsoft/Windows/Start Menu/
drwxr-xr-x 1 Dreesti 197121 60 Oct 17 2024 'Templates' -> /c/Users/Dreesti/AppData/Roaming/Microsoft/Windows/Templates/
drwxr-xr-x 1 Dreesti 197121 0 Oct 17 2024 Videos/
-rw-r--r-- 1 Dreesti 197121 3118 Nov 11 19:41 abc.py
-rw-r--r-- 1 Dreesti 197121 338 Nov 11 19:42 calorie_log.txt
-rw-r--r-- 1 Dreesti 197121 703 Aug 20 2023 classll.py
-rw-r--r-- 1 Dreesti 197121 66 Jan 1 2021 initll.inl
-rw-r--r-- 1 Dreesti 197121 41 Jan 1 2021 initl.inl
```

## 3. Mkdir

```
Dreesti@DESKTOP-F87BKA1 MINGW64 ~
$ mkdir Assignment_05
Dreesti@DESKTOP-F87BKA1 MINGW64 ~
```

## 4. Cd

```
Dreesti@DESKTOP-F87BKA1 MINGW64 ~
$ mkdir Assignment_05
Dreesti@DESKTOP-F87BKA1 MINGW64 ~
$ cd Assignment_05
Dreesti@DESKTOP-F87BKA1 MINGW64 ~/Assignment_05
$
```

## 5. Touch

```
Dreesti@DESKTOP-F87BKA1 MINGW64 ~  
$ cd Assignment_05  
Dreesti@DESKTOP-F87BKA1 MINGW64 ~/Assignment_05  
$ touch report_draft.txt  
Dreesti@DESKTOP-F87BKA1 MINGW64 ~/Assignment_05  
$
```

## 6. Cp

```
Dreesti@DESKTOP-F87BKA1 MINGW64 ~/Assignment_05  
$ cp report_draft.txt backup.txt  
Dreesti@DESKTOP-F87BKA1 MINGW64 ~/Assignment_05  
$
```

## 7. mv

```
Dreesti@DESKTOP-F87BKA1 MINGW64 ~/Assignment_05  
$ mv backup.txt final_report.txt  
Dreesti@DESKTOP-F87BKA1 MINGW64 ~/Assignment_05  
$
```

## 8. chmod

```
Dreesti@DESKTOP-F87BKA1 MINGW64 ~/Assignment_05  
$ chmod 740 final_report.txt  
Dreesti@DESKTOP-F87BKA1 MINGW64 ~/Assignment_05  
$
```

## 9. ls -l final\_report.txt

```
Dreesti@DESKTOP-F87BKA1 MINGW64 ~/Assignment_05  
$ chmod 740 final_report.txt  
Dreesti@DESKTOP-F87BKA1 MINGW64 ~/Assignment_05  
$ ls -l final_report.txt  
-rw-r--r-- 1 Dreesti 197121 0 Nov 28 13:41 final_report.txt  
Dreesti@DESKTOP-F87BKA1 MINGW64 ~/Assignment_05  
$
```

## 10. cat

```
Dreesti@DESKTOP-F87BKA1 MINGW64 ~/Assignment_05  
$ cat report_draft.txt  
Dreesti@DESKTOP-F87BKA1 MINGW64 ~/Assignment_05  
$
```

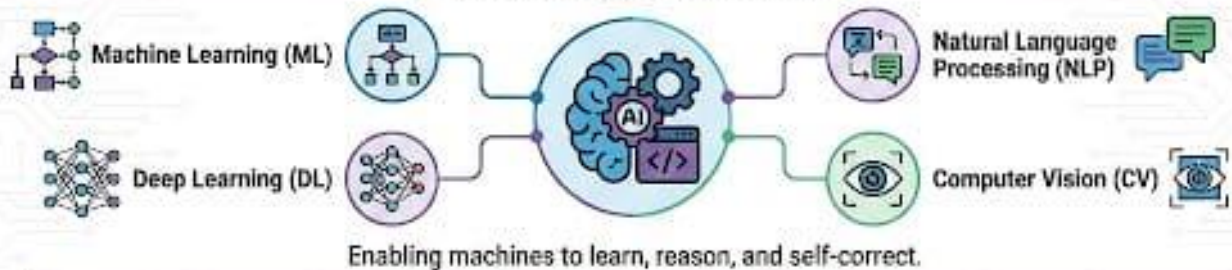
## Git-bash

```
user@laptop-name: ~/Documents/PMINGW64  
$ cd ~/Documents/PMINGW64/Assignment_05  
$ git init  
$ git add .  
$ git commit -m "Initial commit"  
$ git remote add origin https://github.com/yourusername/your-repo.git  
$ git push origin master  
$
```

## Infographic for Artificial Intelligence

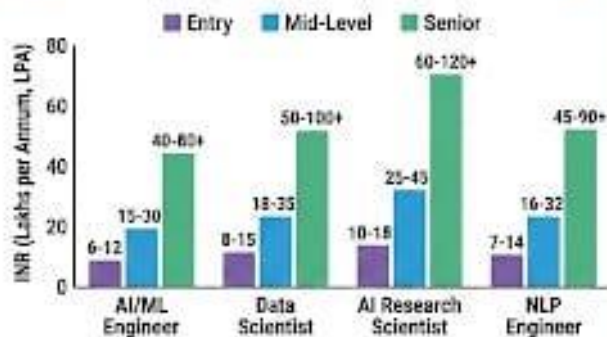
# ARTIFICIAL INTELLIGENCE: OVERVIEW, CAREERS, & REAL-WORLD APPLICATION (INDIA)

### TECHNOLOGY OVERVIEW



Core Functions: Data Ingestion -> Processing & Algorithms -> Model Training -> Inference & Action

### JOB ROLES & SALARY TRENDS



Salary Trends: Increasing demand, high growth potential

### CERTIFICATIONS (LINK TO TASK 4)



### INDIAN STARTUP EXAMPLE: NIRAMAI HEALTH ANALYTICS



# Career planning and professional readiness

## Smart goals

Short-Term Skill Acquisition (6 Months) S: Successfully complete the foundational courses and a practical project (e.g., a simple image classifier) using Python, TensorFlow, and essential libraries like NumPy/Pandas. M: Project repository uploaded to GitHub by (Month/Year - e.g., March 2026) with a README, and a minimum grade of 85% in the relevant semester courses.

Medium-Term Industry Readiness (18 Months) S: Secure and successfully complete a 6-week summer internship or a relevant industry project focused on Robotics simulation (e.g., using ROS - Robot Operating System). M: Internship completion certificate received by (Month/Year - e.g., June 2027), a positive evaluation report, and a detailed project presentation delivered.

Long-Term Career Launch (4 Years) S: Secure a full-time position as a Junior AI Engineer or Robotics Software Developer at a reputable technology firm (e.g., in the areas of computer vision or autonomous systems). M: Employment offer letter received within six months of graduation (by (Month/Year - e.g., July 2029)), with a salary package meeting industry standards for the role.

## Certification

Microsoft Certified: Azure AI Fundamentals (AI-900) Microsoft / Azure Validates core AI concepts, machine learning workloads, and essential cloud services (Azure), which are crucial for deploying scalable AI models in enterprise environments. 1-2 Months Study, ~\$99 USD Exam Fee

TensorFlow Developer Certificate Google / TensorFlow Confirms proficiency in building and training Machine Learning models using TensorFlow, the leading open-source framework for deep learning and neural networks. Essential for core AI development. 2-3 Months Study, ~\$100 USD Exam Fee

ROS (Robot Operating System) Certification Multiple (e.g., The Construct, official training partners) Though not a single official body, proficiency certificates in ROS are vital for robotics engineers. ROS is the middleware framework for creating complex robot applications. 3-4 Months Study, Varies based on course chosen.

## Career roadmap

Phase 1: Foundations (Year 1) 12 Months Focus: Data Structures & Algorithms (DSA), Core Programming (Python/C++), Discrete Mathematics, Introduction to Robotics and AI concepts. Milestones: Strong grasp of DSA, completion of two foundational Python projects, Active GitHub profile, LinkedIn Profile Screenshot (required for the assignment).

Phase 2: Specialization (Year 2) 12 Months Focus: Machine Learning (ML) Theory, Deep Learning (DL), Cloud Basics (Azure/AWS), Begin TensorFlow certification study. Milestones: Completion of AI-900 Certification, secure a small ML-focused project using a real dataset, begin open-source contributions.

Phase 3: Real-World Application (Year 3) 12 Months Focus: Robotics (ROS), Computer Vision, Internship/Major Industry Project, Participation in a national hackathon. Milestones: Complete 6-week summer internship, proof of hackathon participation/plan (required for the assignment), Advanced project portfolio for Robotics/Vision.

Phase 4: Placement & Launch (Year 4) 12 Months Focus: Technical interview preparation (DSA revision, System Design), Final Year Project, Job application submission, Networking. Milestones: Successful completion of the Final Year Project, achieve long-term SMART goal (securing a Junior AI/Robotics role).

## **Linkdin profile**





Prachi Yadav



## Prachi Yadav

Student at KR Manglam University

KR Manglam University  
Gurugram, Haryana, India

0 connections

Open to

Add section



Enhance profile

## Analytics

👁 Private to you



**0 profile views**

Update your profile to attract viewers.



**0 post impressions**

Start a post to increase engagement.

Past 7 days

## Hackathon Participation Plan: Robotics & AI Challenge

To demonstrate applied skills and collaboration, the medium-term career roadmap includes participation in a significant technical competition.

Chosen Hackathon Target

The target competition is a Robotics Simulation Challenge (e.g., a university-hosted event or a major industry hackathon like Smart India Hackathon or similar focused challenges).

Project Concept: Autonomous Warehouse Navigation

Goal: Develop an AI-driven script for a simulated robotic arm and mobile base (using ROS and Gazebo simulation environments) to efficiently navigate a virtual warehouse, identify objects via computer vision (OpenCV/YOLO), and move them to designated storage locations.

Technologies:

Robot Operating System (ROS): For communication and control of simulated components.

Python: Main programming language for logic and control.

OpenCV / TensorFlow Lite: For visual detection and object recognition.

Gazebo: The 3D robotics simulator environment.

Team Role: AI & Vision Specialist. My primary contribution will be developing the robust computer vision pipeline that processes the simulated camera feed to accurately locate and classify the required objects for manipulation by the arm.

Success Metric: Completing a defined number of picking and placement tasks within a 10-minute time limit in the simulation environment.

## Reflection

The process of completing this assignment has been a foundational exercise in both technical execution and strategic career planning. It provided a necessary bridge between theoretical knowledge and applied industry readiness.

One of the primary challenges faced was the troubleshooting of the Git Bash script execution. The unexpected interaction between Windows (CRLF) and Unix (LF) line endings required a deep dive into fundamental shell behavior and file formatting. This experience underscored a crucial lesson: that

successful software deployment depends not just on correct code syntax, but on understanding the underlying operating system environment. The iterative debugging process significantly improved my problem-solving skills and resilience when facing ambiguous errors.

Another key skill improved was structured career forecasting. Defining SMART goals forced a tangible and measurable plan for skill acquisition, moving beyond vague aspirations to actionable steps like obtaining the Azure AI Fundamentals certification by a specific deadline. The construction of the career roadmap clearly visualizes the transition from academic theory to industry application, ensuring my B.Tech specialization remains relevant and highly focused.

I will apply this learning by rigidly adhering to the defined roadmap, prioritizing the acquisition of skills like TensorFlow and ROS proficiency during the next academic year. The disciplined approach to using open-source tools, as practiced with Git Bash and the project setup script, will be a permanent fixture in my future professional workflow, ensuring every project I undertake begins with a standardized, automated, and scalable structure, preparing me directly for a role as a Junior AI Engineer.