

# Linear multistep methods

# Initial value problem (IVP)

Given an ODE,

$$\dot{u} = f(t, u), \quad u(0) = u_0$$

Define a mesh

$$0 = t_0 < t_1 < t_2 < \cdots < t_{n-1} < t_N = T$$

Define a *mesh function*  $y_n$

$$y_n \approx u(t_n), \quad n = 0, 1, \dots, N$$

$y_n$  satisfies a discretized form of the ODE.

# Linear multistep methods

*A linear  $s$ -step method is*

$$\frac{a_0 y_n + a_1 y_{n-1} + \cdots + a_s y_{n-s}}{\tau} = b_0 f_n + b_1 f_{n-1} + \cdots + b_s f_{n-s}$$

for  $n = s, s+1, \dots$

Here

$$f_n \equiv f(t_n, y_n),$$

$\tau$  is the step size,

$a_k$  and  $b_k, k = 0, \dots, s$  are  $n$ -independent.

# Linear multistep methods

$$\frac{a_0 y_n + a_1 y_{n-1} + \cdots + a_s y_{n-s}}{\tau} = b_0 f_n + b_1 f_{n-1} + \cdots + b_s f_{n-s}$$

for  $n = s, s+1, \dots$

Start from  $n = s$ , then solve for  $y_n$  given  $y_{n-1}, y_{n-2}, \dots, y_{n-s}$ .

Need  $s$  initial conditions. Take

$$y_0 = u_0$$

find  $y_1, \dots, y_{s-1}$  via e.g. a Runge-Kutta method.

# Linear multistep methods

$$\frac{a_0 y_n + a_1 y_{n-1} + \cdots + a_s y_{n-s}}{\tau} = b_0 f_n + b_1 f_{n-1} + \cdots + b_s f_{n-s}$$

for  $n = s, s+1, \dots$

- ▶ Unlike RK methods, only evaluate the r.h.s. at  $t_n$ .
- ▶ If  $b_0 = 0$ , the method is explicit. Otherwise, it is implicit.
- ▶ Without loss of generality, assume

$$\sum_{k=0}^s b_k = 1$$

# Families of linear multistep methods

## Adams methods

Take  $a_0 = -a_1 = 1$ ,  $a_k = 0$  for  $k > 1$ .

$$\frac{y_n - y_{n-1}}{\tau} = \sum_{k=0}^s b_k y_{n-k}$$

Select  $b_k$  coefficients to maximize the approximation order.

**Adams-Bashforth schemes** Take  $b_0 = 0$ .

Max order is  $s$ .

$s = 1$  is the Euler scheme.

**Adams-Moulton schemes** For  $b_0 \neq 0$ , methods are implicit.

Max order is  $s + 1$ .

$s = 1$  is the implicit Euler scheme.

# Families of linear multistep methods : BDF

## Backwards differentiation formulas (BDF)

- ▶ Take  $b_0 = 1$ .
- ▶ Approximate the derivative by an  $s$ -point finite difference formula.

$$s = 1 \quad y_n - y_{n-1} = \tau f_n$$

$$s = 2 \quad \frac{3}{2}y_n - 2y_{n-1} + \frac{1}{2}y_{n-2} = \tau f_n$$

...

# Zero-stability of linear multistep methods



# Stability of ODEs and numerical schemes

Suppose that the IVP is stable.

$$\dot{u} = f(t, y), \quad u(0) = u_0$$

What are the conditions for the numerical scheme to be stable?

$$\frac{a_0 y_n + a_1 y_{n-1} + \cdots + a_s y_{n-s}}{\tau} = b_0 f_n + b_1 f_{n-1} + \cdots + b_s f_{n-s}$$

Note that it needs  $s$  initial conditions. It might admit extra, spurious solutions.

# Zero-stability of LMM

Only consider a homogenous equation,

$$\dot{u} = 0$$

Its discretized version reads

$$a_0 y_n + a_1 y_{n-1} + \cdots + a_s y_{n-s} = 0$$

If a method is not zero-stable, it is not usable.

# Zero-stability of LMM

For a homogenous recurrence relation of order  $s$

$$a_0 y_n + a_1 y_{n-1} + \cdots + a_s y_{n-s} = 0$$

Look for solutions in the form

$$y_n = q^n$$

Characteristic polynomial

$$a_0 q^s + a_1 q^{s-1} + \cdots + a_s = 0$$

A root of the CP defines a particular solution.

# Zero-stability of LMM

For a homogenous recurrence relation of order  $s$

$$a_0 y_n + a_1 y_{n-1} + \cdots + a_s y_{n-s} = 0$$

- ▶ A simple root,  $q$ , of the C.P. defines a particular solution

$$y_n = q^n$$

- ▶ A root of multiplicity  $r$  defines particular solutions

$$y_n = q^n, nq^n, n^2q^n, \cdots, n^{r-1}q^n$$

# Zero-stability of LMM

A method is zero-stable if and only if the *root condition* is satisfied:

- ▶ All roots of the characteristic polynomial have  $|q| \leq 1$ .
- ▶ All roots with  $|q| = 1$  are simple.

# Convergence of LMM

Let

- ▶  $|\partial f(t, u)/\partial u| < L$  for  $0 \leq t \leq T$
- ▶ the root condition is satisfied.

Then, for all  $n \geq s$ ,

$$|y_n - u(t_n)| \leq M \left( \max_{k < s} |y_k - u(t_k)| + \max_k |\psi_k| \right)$$

where  $M = M(L, T)$  does not depend on  $n$ .