

(a)

$$E_N(V) \leq E_L(V)$$

Proof:

$$L(x_i^{(k)}; V) = V_k \alpha_i^{(k)}$$

Suppose we define  $\alpha_i = \begin{bmatrix} \alpha_i^{(k)} \\ 0 \\ \vdots \\ 0 \end{bmatrix}$ .

The first  $k$  rows of vector  $\alpha_i$  are the same as  $\alpha_i^{(k)}$  and the rest are 0. In this notation,

$$L(x_i^{(k)}; V) = V \alpha_i \text{ where } V \text{ is the entire}$$

basis matrix.

$$N(x_i^{(k)}; V) = V \beta_i \text{ where } \beta_i = \arg \min_{c_i \text{ s.t. } c_i \text{ has at most } k \text{ non-zero components}} \|x_i - V c_i\|^2$$

By def<sup>n</sup> of  $\beta_i$ ,

$$\|x_i - V \beta_i\|^2 \leq \|x_i - V c_i\|^2 \quad \forall c_i \text{ such that above condition is satisfied.}$$

Since  $\alpha_i$  is a special kind of  $c_i$  s.t. only the first  $k$  components are non-zero, reconstruction error using non-linear method is lower or equal.

$$\therefore \|x_i - N(x_i^{(k)}; V)\|^2 \leq \|x_i - L(x_i^{(k)}; V)\|^2$$

On summing on both sides over all points,

$$E_N(V) \leq E_L(V)$$

(b)

Here we have  $N > d$  and the covariance matrix  $C$  is of size  $d \times d$ . Furthermore,  $V$  ~~is~~ forms a basis matrix for a  $d$ -dimensional vector space.

$$\therefore \text{ let } x_i = V d_i \quad \text{where} \\ d_i \in \mathbb{R}^{d \times 1}$$

$$\text{and } \alpha_i = V^T x_i.$$

Now for each  $x_i$ , we want to ~~sum~~ find a  $c_i$  s.t.

$\|x_i - V c_i\|^2$  is minimised.

Putting  $x_i = V d_i$ ,

$$\begin{aligned} \|V d_i - V c_i\|^2 &= \|V (d_i - c_i)\|^2 \\ &= (d_i - c_i)^T V^T V (d_i - c_i) \\ &= (d_i - c_i)^T (d_i - c_i) \\ &= \|d_i - c_i\|^2 = \sum_{j=1}^d (d_{ij} - c_{ij})^2 \end{aligned}$$

To minimize this, we need to consider the  $K$  largest absolute values in  $d_i$  and use them as our  $c_i$  with the remaining positions having 0.

Since we want to minimize the sum of squares, it will be smallest only when the largest  $K$  terms do not contribute to this. That happens when ~~the~~  $c_i$  has the  $K$  largest terms in terms of magnitude of  $d_i$ .

To do this, we need to sort each  $d_i$  according to magnitude. This takes  $O(d \log d)$ . For  $N$  points  $O(N d \log d)$  complexity does the job.

(c)

It is possible to construct a  $W$  such that  $E_N(W) < E_N(V)$ . Consider the following scenario.

$$x_1 = [-1; 10; 0.3]^T$$

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$$x2 = [-0; 12; -1.3]^T$$

$$x3 = [-0.1; -3; 2.12]^T$$

$$x4 = [-0; 2.33; -3.31]^T$$

$$W =$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

The approximation errors are on doing a degree 1 approximation i.e.  $k = 1$ :

V	12.939904
W	12.713300

The approximation errors are on doing a degree 2 approximation i.e.  $k = 2$ :

V	0.287779
W	0.100000

The associated code to test this has been placed in the `code` folder.