Practical-Machine-Learning-Project

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Introduction

Devices such as Jawbone Up, Nike FuelBand, and Fitbit enable humans to collect a large amount of data about their personal activity at a relatively inexpensive price. Using these devices, one thing that people regularly do is quantify how much of a particular activity they do, but they rarely quantify how well they do it.

In this project, we use data from the accelerometers on the belt, forearm, arm, and dumbell of 6 participants who were asked to perform barbell lifts first *correctly* and then *incorrectly* in 5 different ways. Our goal is to predict the manner in which they did the exercise by using the above data

The data for this project come from this source: http://groupware.les.inf.puc-rio.br/har (see the section on the Weight Lifting Exercise Dataset).

Data Preprocessing and Exploratory Analysis

Import the packages.

```
library (caret)
library (dplyr)
```

The training data for this project are available here:

https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv

The testing data are available here:

https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv

We download the data in the data folder.

```
# Check to see if the directory exists
if(!file.exists("./data")) {dir.create("data")}

# Download Training data
if(!file.exists("./data/pml-training.csv")) {
    url <- "https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv"
    download.file(url, destfile = "./data/pml-training.csv")
}

# Download Testing data
if(!file.exists("./data/pml-testing.csv")) {
    url <- "https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv"
    download.file(url, destfile = "./data/pml-testing.csv")
}</pre>
```

And, then read the data into a dataframe.

```
# Read Training data
training_csv <- read.csv("./data/pml-training.csv")

# Read Testing data
testing_csv <- read.csv("./data/pml-testing.csv")</pre>
```

Look at the dimensions of training data.

```
dim(training_csv)

## [1] 19622 160
```

Look at the dimensions of testing data.

```
dim(testing_csv)
```

Look at the structure of training data.

```
str(training_csv)
```

```
## 'data.frame': 19622 obs. of 160 variables:
## $ X
                         : int 1 2 3 4 5 6 7 8 9 10 ...
## $ user_name
                         : Factor w/ 6 levels "adelmo", "carlitos", ...: 2 2 2 2 2 2 2 2 2 2 ...
## $ raw_timestamp_part_1 : int 1323084231 1323084231 1323084232 1323084232 1323084232 1323084232 13230
84232 1323084232 1323084232 1323084232 ...
## $ raw_timestamp_part_2 : int 788290 808298 820366 120339 196328 304277 368296 440390 484323 484434
. . .
## $ cvtd_timestamp
                         : Factor w/ 20 levels "02/12/2011 13:32",..: 9 9 9 9 9 9 9 9 9 9 ...
                          : Factor w/ 2 levels "no", "yes": 1 1 1 1 1 1 1 1 1 1 ...
## $ new_window
                          : int 11 11 11 12 12 12 12 12 12 12 ...
## $ num window
## $ roll_belt
                        : num 1.41 1.41 1.42 1.48 1.48 1.45 1.42 1.42 1.43 1.45 ...
## $ pitch_belt
                        : num 8.07 8.07 8.07 8.05 8.07 8.06 8.09 8.13 8.16 8.17 ...
## $ yaw belt
                         : num -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 ...
## $ total_accel_belt : int 3 3 3 3 3 3 3 3 3 ...
## $ kurtosis_roll_belt : Factor w/ 397 levels "","-0.016850",..: 1 1 1 1 1 1 1 1 1 1 1 ...
## $ kurtosis_picth_belt : Factor w/ 317 levels "","-0.021887",..: 1 1 1 1 1 1 1 1 1 1 ...
: Factor w/ 395 levels "","-0.003095",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness_roll_belt.1 : Factor w/ 338 levels "","-0.005928",..: 1 1 1 1 1 1 1 1 1 1 ...
   $ skewness_yaw_belt : Factor w/ 2 levels "","#DIV/0!": 1 1 1 1 1 1 1 1 1 1 1 ...
                       : num NA NA NA NA NA NA NA NA NA ...
: int NA NA NA NA NA NA NA NA NA ...
: Factor w/ 68 levels "","-0.1","-0.2",...: 1 1 1 1 1 1 1 1 1 1 ...
## $ max_roll_belt
## $ max picth belt
## $ max_yaw_belt
## $ min_roll_belt
                        : num NA ...
## $ min_pitch_belt
## $ min_pitch_belt : int NA ...
## $ min_yaw_belt : Factor w/ 68 levels "","-0.1","-0.2",..: 1 1 1 1 1 1 1 1 1 1 1 ...
## $ amplitude_roll_belt : num NA ...
                        : int NA ...
## $ amplitude_yaw_belt : Factor w/ 4 levels "","#DIV/0!","0.00",..: 1 1 1 1 1 1 1 1 1 1 ...
: num NA ...
## $ stddev_roll_belt
## $ var_roll_belt
                         : num NA NA NA NA NA NA NA NA NA ...
                         : num NA ...
## $ avg pitch belt
## $ stddev_pitch_belt
## $ var pitch_belt
                         : num NA NA NA NA NA NA NA NA NA ...
## $ var_pitch_belt
                          : num NA NA NA NA NA NA NA NA NA ...
## $ avg_yaw_belt
                         : num NA NA NA NA NA NA NA NA NA ...
                        : num NA NA NA NA NA NA NA NA NA ...
## $ stddev_yaw_belt
## $ var yaw belt
                        : num NA NA NA NA NA NA NA NA NA ...
## $ gyros belt x
                        ## $ gyros belt y
                        : num 0 0 0 0 0.02 0 0 0 0 0 ...
## $ gyros belt z
                        : num -0.02 -0.02 -0.02 -0.03 -0.02 -0.02 -0.02 -0.02 -0.02 0...
                        : int -21 -22 -20 -22 -21 -21 -22 -22 -20 -21 ...
## $ accel_belt_x
## $ accel_belt_y
                        : int 4 4 5 3 2 4 3 4 2 4 ...
## $ accel_belt_z
                        : int 22 22 23 21 24 21 21 21 24 22 ...
##
  $ magnet belt x
                        : int -3 -7 -2 -6 -6 0 -4 -2 1 -3 ...
                        : int 599 608 600 604 600 603 599 603 602 609 ...
   $ magnet_belt_y
##
## $ magnet_belt_z
                         : int -313 -311 -305 -310 -302 -312 -311 -313 -312 -308 ...
                          ## $ roll arm
## $ pitch_arm
                        : num 22.5 22.5 22.5 22.1 22.1 22 21.9 21.8 21.7 21.6 ...
## $ yaw_arm
                        : int 34 34 34 34 34 34 34 34 34 34 ...
: num NA ...
## $ total_accel_arm
## $ var accel arm
                        : num NA NA NA NA NA NA NA NA NA ...
## $ avg roll arm
## $ stddev_roll_arm
                        : num NA NA NA NA NA NA NA NA NA ...
## $ var roll arm
                        : num NA NA NA NA NA NA NA NA NA ...
                        : num NA NA NA NA NA NA NA NA NA ...
## $ avg_pitch_arm
                        : num NA ...
## $ stddev pitch arm
                         : num NA ...
## $ var pitch arm
                         : num NA ...
## $ avg yaw arm
## $ stddev_yaw_arm
                         : num NA ...
## $ var_yaw_arm
                          : num NA NA NA NA NA NA NA NA NA ...
## $ gyros_arm_x
                          : num 0 -0.02 -0.02 -0.03 -0.03 -0.03 -0.03 -0.02 -0.03 -0.03 ...
## $ gyros_arm_y
## $ gyros_arm_z
                         : num -0.02 -0.02 -0.02 0.02 0 0 0 0 -0.02 -0.02 ...
```

```
## $ accel_arm_y
## $ accel_arm_z
## $ accel_arm_z
                                  : int 109 110 110 111 111 111 111 111 109 110 ...
                                 : int -123 -125 -126 -123 -123 -122 -125 -124 -122 -124 ...
                                : int -368 -369 -368 -372 -374 -369 -373 -372 -369 -376 ...
## $ magnet_arm_x
## $ magnet_arm_y
## $ magnet_arm_y
## $ magnet_arm_z
## $ magnet_arm_z
## $ magnet_arm_z
## $ kurtosis_roll_arm
## $ kurtosis_picth_arm
## $ kurtosis_picth_arm
## $ kurtosis_yaw_arm
## $ skewness_roll_arm
## $ skewness_roll_arm
## $ skewness_pitch_arm
## $ nax_roll_arm
 ## $ magnet_arm_x
                                : num NA ...
 ## $ max_picth_arm
                                 : int NA NA NA NA NA NA NA NA NA ...
## $ max_yaw_arm
 ## $ min roll arm
                                 : num NA NA NA NA NA NA NA NA NA ...
 ## $ min pitch arm
                                 : num NA NA NA NA NA NA NA NA NA ...
\mbox{\#\#} $ amplitude_yaw_arm : int NA ...
 ## $ roll_dumbbell
                                 : num 13.1 13.1 12.9 13.4 13.4 ...
                                 : num -70.5 -70.6 -70.3 -70.4 -70.4 ...
## $ pitch_dumbbell
## $ yaw_dumbbell
                                   : num -84.9 -84.7 -85.1 -84.9 -84.9 ...
 ## $ kurtosis roll dumbbell : Factor w/ 398 levels "","-0.0035","-0.0073",..: 1 1 1 1 1 1 1 1 1 1 ...
 ## $ kurtosis_picth_dumbbell : Factor w/ 401 levels "","-0.0163","-0.0233",..: 1 1 1 1 1 1 1 1 1 1 1 ...
## $ kurtosis_yaw_dumbbell : Factor w/ 2 levels "","#DIV/0!": 1 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness roll dumbbell : Factor w/ 401 levels "","-0.0082","-0.0096",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness_pitch_dumbbell : Factor w/ 402 levels "","-0.0053","-0.0084",..: 1 1 1 1 1 1 1 1 1 1 1 ...
 ## $ skewness yaw dumbbell : Factor w/ 2 levels "","#DIV/0!": 1 1 1 1 1 1 1 1 1 1 1 ...
 ## $ max_picth_dumbbell
                                 : num NA NA NA NA NA NA NA NA NA ...
## $ max_yaw_dumbbell
## $ min_roll_dumbbell
                                 : Factor w/ 73 levels "","-0.1","-0.2",...: 1 1 1 1 1 1 1 1 1 1 1 ...
                                 : num NA ...
## $ min_pitch_dumbbell : num NA ...
## $ min_yaw_dumbbell : Factor w/ 73 levels "","-0.1","-0.2",..: 1 1 1 1 1 1 1 1 1 1 ...
 [list output truncated]
 ##
```

It appears that there are a significant number of columns (*variables*) having mostly missing data in them. Let us remove the columns containing more than 50 % of their values as **NA** values.

Let us format the three timestamp columns.

It is observed from above that the *three* timestamp columns represents the same piece of information split up into three parts and hence, are redundant. Let us format these columns into *one* variable. First, drop the redundant columns.

Next, rename the timestamp variable.

```
## Rename the column to 'time_stamp'
training_csv_mod <- rename(training_csv_mod, timestamp = raw_timestamp_part_2)
testing_csv_mod <- rename(testing_csv_mod, timestamp = raw_timestamp_part_2)</pre>
```

Finally, we have to convert the time format back to numeric format for modelling.

```
## Convert back to numeric format for modelling
training_csv_mod$timestamp <- as.numeric(training_csv_mod$timestamp)
testing_csv_mod$timestamp <- as.numeric(testing_csv_mod$timestamp)
```

Now, check whether any column has near-zero variance.

```
# Check for near-zero variance predictors
names(training_csv_mod)[nearZeroVar(training_csv_mod, saveMetrics = T)$nzv]
```

```
## [1] "new_window"
```

```
names(testing_csv_mod)[nearZeroVar(testing_csv_mod, saveMetrics = T)$nzv]
```

```
## [1] "new_window"
```

This column will not be helpful during the modelling so let us drop it.

```
# Drop near-zero variance predictor
training_csv_mod <- training_csv_mod[, !nearZeroVar(training_csv_mod, saveMetrics = T)$nzv]
testing_csv_mod <- testing_csv_mod[, !nearZeroVar(testing_csv_mod, saveMetrics = T)$nzv]</pre>
```

Lastly, the first column x is just the index variable, so drop it.

```
# Drop the index variable
training_csv_mod <- training_csv_mod[, -which(names(training_csv_mod) == "X")]
testing_csv_mod <- testing_csv_mod[, -which(names(testing_csv_mod) == "X")]</pre>
```

Check the final dimensions of training and testing data.

```
# Final dimensions
dim(training_csv_mod)
```

```
## [1] 19622 56
```

```
dim(testing_csv_mod)
```

```
## [1] 20 56
```

Modelling

Set the seed for reproducibility.

```
set.seed(123)
```

Let us split the training data into *three* subsets for modelling, namely training_set (about 50 %) for model fitting, testing_set (about 20 %) for model tuning and validation_set (about 30 %) for model evaluation.

Let us fit a number of different models and compare them to find the most suitable model for our problem.

During modelling, we will use center and scale preprocessing on the data. We will also use repeated K-fold cross validation with k=3 number of folds and n=5 number of repetitions.

1. Decision tree

```
# For testing set
pred_t_rpart <- predict(fit_rpart, testing_set)

# For validation set
pred_v_rpart <- predict(fit_rpart, validation_set)</pre>
```

2. K-nearest neighbours

```
# For testing set
pred_t_knn <- predict(fit_knn, testing_set)

# For validation set
pred_v_knn <- predict(fit_knn, validation_set)</pre>
```

3. Support vector machine

```
# For testing set
pred_t_svmLinear <- predict(fit_svmLinear, testing_set)
# For validation set
pred_v_svmLinear <- predict(fit_svmLinear, validation_set)</pre>
```

Let us look at the accuracy of the above models on the testing_set.

```
# Decision tree
confusionMatrix(pred_t_rpart, testing_set$classe)$overall["Accuracy"]

## Accuracy
## 0.4910151

# K-nearest neighbours
confusionMatrix(pred_t_knn, testing_set$classe)$overall["Accuracy"]

## Accuracy
## 0.9538611

# Support vector machine
confusionMatrix(pred_t_svmLinear, testing_set$classe)$overall["Accuracy"]
```

From above, we see can see that the accuracy from the **K-nearest Neighbours** model is the highest among the given models (about 95 %).

We can use model stacking/ensemble technique to stack the above three models and improve the accuracy further.

Ensemble

Accuracy ## 0.8023312

For model stacking, we will again try different algorithms for the top layer and find the best model with respect to accuracy.

We will have to prepare a *stacked* dataframe consisting of the predictions from the above three models and the actual **classe** variable from the **testing_set**. We will use this for training.

We will use bootstraping with n=10 number of repetitions.

1. Bagged decision tree

```
pred_st_treebag <- predict(stacked_treebag, stacked_df_t)</pre>
```

2. Gradient boosting machine

```
pred_st_gbm <- predict(stacked_gbm, stacked_df_t)</pre>
```

3. Random forest

```
pred_st_rf <- predict(stacked_rf, stacked_df_t)</pre>
```

Let us look at the accuracy of the stacked models on the testing_set.

```
# Bagged decision tree
confusionMatrix(pred_st_treebag, testing_set$classe)$overall["Accuracy"]
```

```
## Accuracy
## 0.9565323
```

```
# Gradient boosting machine
confusionMatrix(pred_st_gbm, testing_set$classe)$overall["Accuracy"]
```

```
## Accuracy
## 0.9538611
```

```
# Random forest
confusionMatrix(pred_st_rf, testing_set$classe)$overall["Accuracy"]
```

```
## Accuracy
## 0.9558038
```

From above, we can see that the *stacked* model using **Bagged Decision Tree** model as the *top* layer is the most accurate. It is also observed that the increase in accuracy is **only incremental**.

We will use this model to calculate the Out-of-sample error.

Out-of-sample Error

We will prepare a stacked dataframe using validation_set similar to the previous step. We will use this for validation.

Let us check the out-of-sample error.

```
pred_sv_treebag <- predict(stacked_treebag, stacked_df_v)

oos_error <- round(((1 - confusionMatrix(pred_sv_treebag, validation_set$classe)$overall["Accuracy"]) * 100)
, 2)
print(paste0("The Out-of-sample error is ", oos_error, " %"))

## [1] "The Out-of-sample error is 5.1 %"</pre>
```

Finally, we will use the above model to predict the ${\tt classe}$ variable for ${\tt testing_csv_mod}$ dataset.

First, we will predict the base layer.

```
# Decision tree
prediction_rpart <- predict(fit_rpart, testing_csv_mod)

# K-nearest neighbours
prediction_knn <- predict(fit_knn, testing_csv_mod)

# Support vector machine
prediction_svmLinear <- predict(fit_svmLinear, testing_csv_mod)</pre>
```

Prepare the stacked dataframe.

```
prediction <- predict(stacked_treebag, stacked_prediction)
print(prediction)</pre>
```

```
## [1] C A B A A B D B A A D C B A E E A B B B ## Levels: A B C D E
```

The above predictions were submitted as part of the assignment.