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# DOTPly: Semi-automatic Framework for Semantic Annotation of 3D Point Cloud

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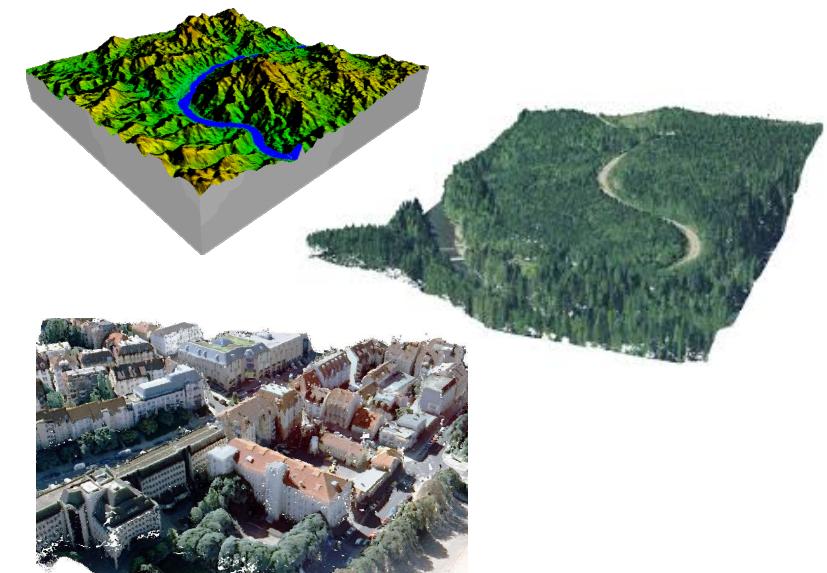


# Background

- Development of IoT Sensing Technology for Capturing the Real World



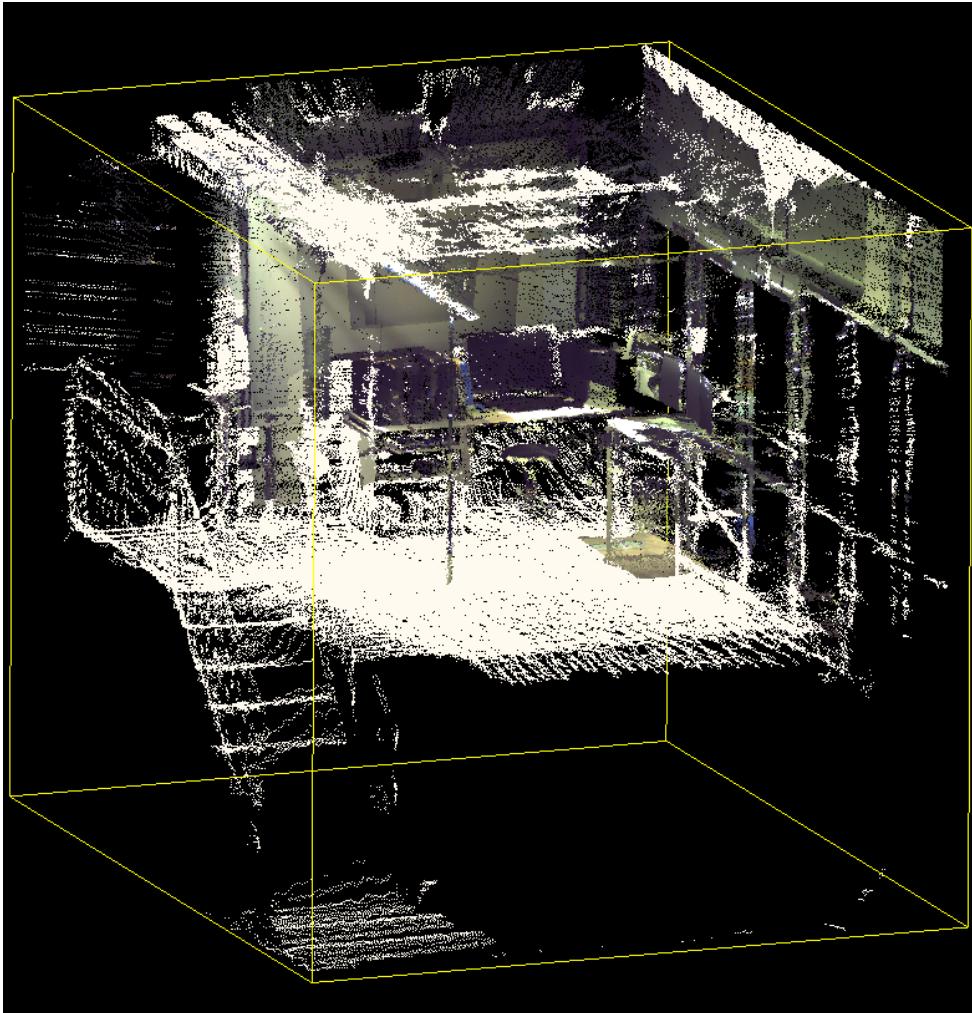
State-of-the-art Sensing Devices



3D High Definition Data

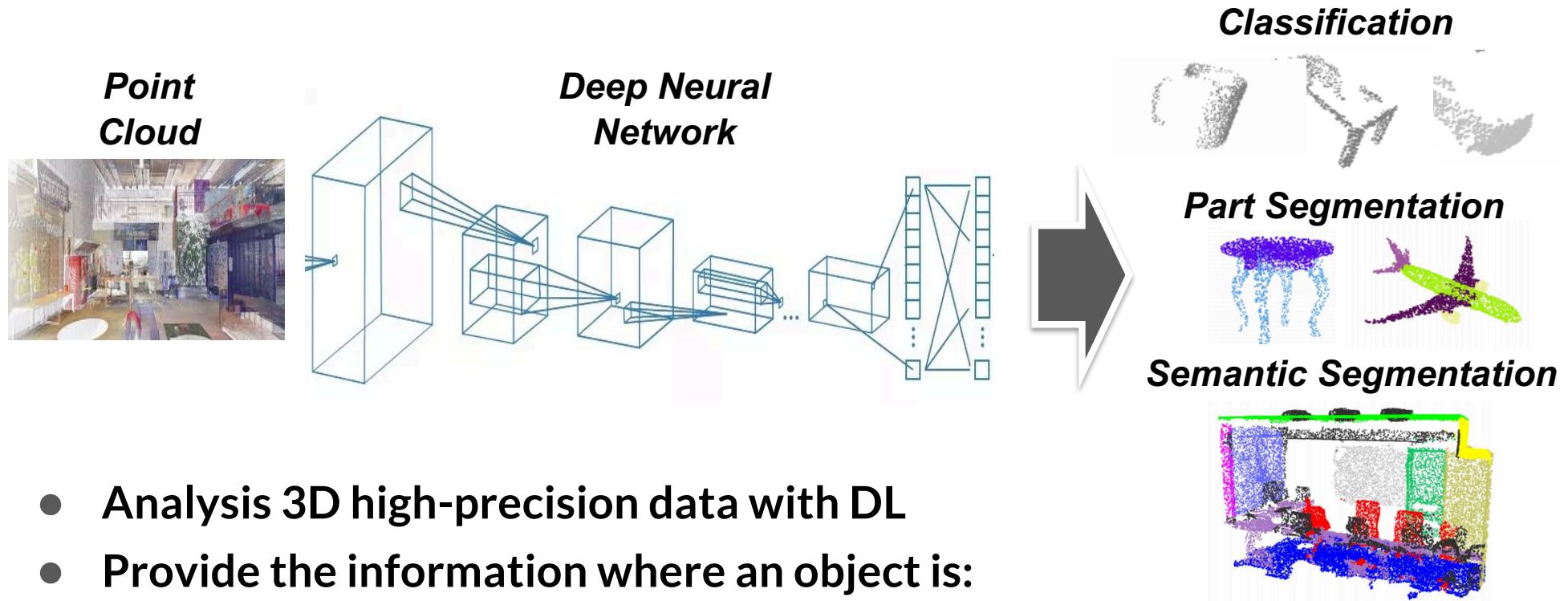
- Recently, there is a tremendous increase in the point cloud data due to the increase in the use of **3D scanners**.
- 3D data is usually generated as a stream of points by mounting 3D scanners on drones, cars or on some stationary platform.

# Example: Colored Point Clouds



AIST waterfront Annex2 Building Laboratory PC Room (1.5 floor)

# Deep Learning with Point Cloud Data



- Analysis 3D high-precision data with DL
- Provide the information where an object is:
  - City modeling
    - Forest planning and management, Digital Elevation Models construction
  - Disaster management
    - Forest fire management, Flood modeling, River surveying
  - Autonomous driving
    - Traffic monitoring, Transport management

# Motivation

- **Lack of Supervised Training Data**
  - To exploit deep learning techniques into point cloud data
    - ***Training data is always essential*** for applying DL
  - However,
    - There are not many annotated (supervised) point cloud data
      - Only for autonomous driving: car, pedestrian, cyclist, and so on.
      - Ex) KITTI<sup>1</sup>, Ford Campus LiDAR dataset<sup>2</sup>, Stanford Track Collection<sup>3</sup>
    - It is very difficult to make supervised data using traditional method
      - Too huge size (i.e., hard to control)
      - Complex to control 3-dimension axis (i.e., costly works)
      - Difficult to employ machine learning techniques (i.e., low accuracy)

<sup>1</sup>KITTI (*Karlsruhe Institute of Technology and Toyota Technological Institute*), <http://www.cvlibs.net/datasets/kitti/>

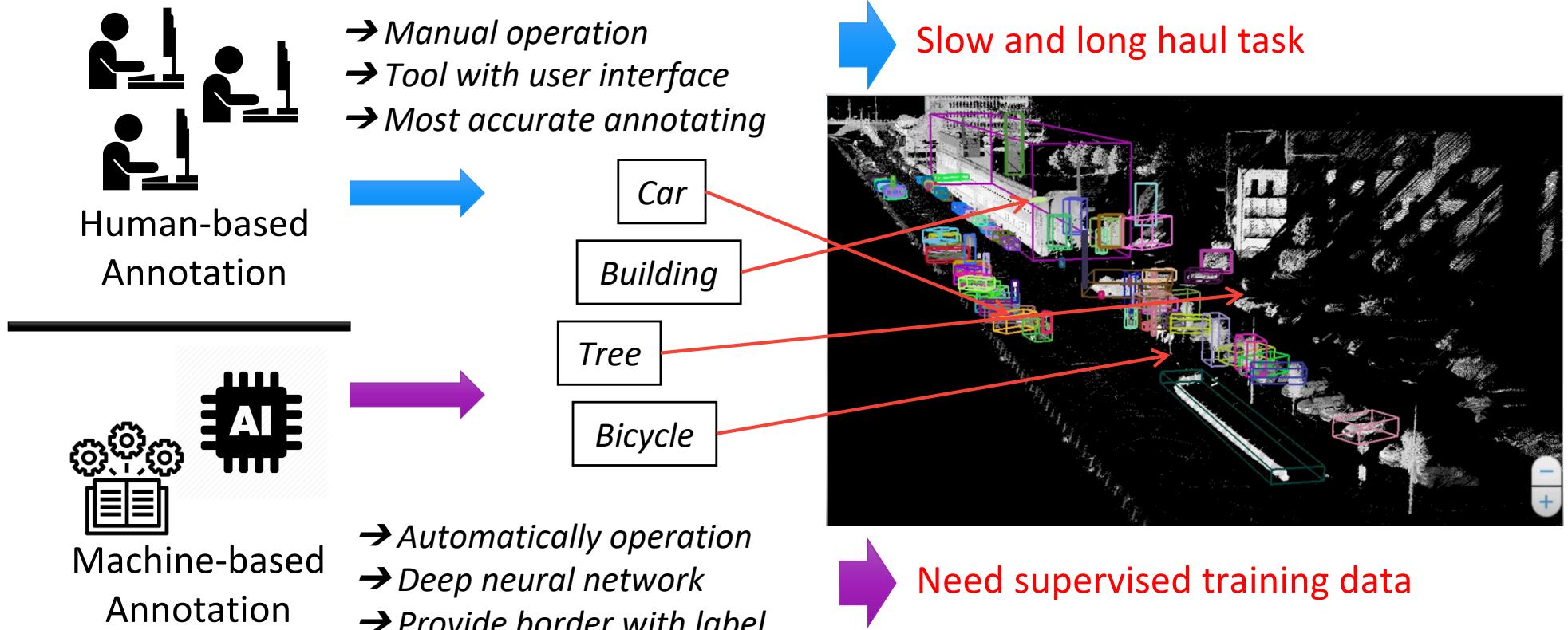
<sup>2</sup>Ford Campus LiDAR dataset, <http://robots.engin.umich.edu/SoftwareData/Ford>

<sup>3</sup>Stanford Track Collection, <http://www.youtube.com/embed/blif9hSR1O4?rel=0>

# Annotation of Point Cloud Data

- What is annotation?

- The process by which a computer system automatically/manually assigns metadata in the form of captioning or keywords
- This is most essential task for utilizing point cloud data



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# Thank you for your attention!

