Assume the graph G = (V, E) isn't (f + 1)-connected. Then there exists a set of f processes which if removed would disconnect the graph. Let G' be the graph after these processes are removed. Let p_i be a process in G', and let V_1 (respectively, V_2) be the set of processes in G' which do (respectively, do not) have a path to p_i in G'.

If there exists a path between a process $p_k \in V_2$ and a process $p_j \in V_1$, then the concatenation of that path with the path from p_j to p_i would be a path from p_k to p_i , which is a contradiction because $p_k \in V_2$. Therefore no messages can pass between V_1 and V_2 .

Assume there exists a consensus algorithm that works in this case. If all processes in V_1 have input 0, then the algorithm must require them to output 0, because of the possibility (which is impossible for V_1 to refute) that all processes in V_2 also have input 0. Similarly, all processes in V_2 would have to output 1 if all of their inputs are 1. But then the algorithm would fail if all processes in V_1 have input 0 and all processes in V_2 have input 1, so no valid algorithm exists.

Now assume the graph G = (V, E) is (f + 1)-connected. For each process p_i with input x_i , let m_i be a message saying that p_i 's input value is x_i .

Algorithm 1 p_i 's Instructions in Round r

- 1: **if** r=1 **then** broadcast m_i .
- 2: **else** broadcast all messages m_j that you just received for the first time.
- 3: end if
- 4: $n \leftarrow$ the number of processes p_j for which you've received m_j .
- 5: if r > n + 10 then output the minimum value of x_i that you've seen.
- 6: end if \triangleright The +10 is insurance against off by one errors in my analysis.

First I assume that each process executes the above instructions even after outputting a value, and then I prove that this assumption isn't necessary.

Lemma 1. Let p_s and p_t be processes that don't crash. If a message m_i reaches p_s , then m_i will also reach p_t .

Proof. Since G is (f+1)-connected and there are at most f crashes, there exists a path P from p_s to p_t in which no processes crash. If m_i doesn't propagate along P after reaching p_s , it's because m_i found a faster way to reach p_t , and no process sends the same message twice.

Lemma 2. Let p_t be a process that outputs a value. p_t will receive no messages after doing so.

Proof. Let S be the set of n processes that p_t knows of when it outputs a value. Assume there exists $p_s \in V - S$ such that there exists a path P from p_s to p_t along which m_s can propagate (i.e. no process in P crashes before it can send m_s at the appropriate time.) Without loss of generality assume that P is non-self-intersecting, and therefore finite. Let p_μ be the last process in P in V - S, and let P' be the subpath of P from p_μ to p_t . All but one element of P' is in P, so $P' \in P'$ is traversable when P reaches