

# Paavan Raj

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## EXPERIENCE

### Western Engineering Competition Leader      Sept 2017 - Present

- Manage the innovative engineering competition, drafting competition guidelines and problem to be solved by competitors
- Overlook event on the competition day, acting as a facilitator to enable participants to compete to their fullest potential

### Western Aero Design      Sept 2016 – Present

- Work with a team of 15 people to build a miniature airplane to compete at the national SAE Aero Design competition
- As a member of the aerodynamics team, test and model various wing configurations and shapes to achieve maximum lift and flight time
- Assist the controls team in designing and testing of the autonomous computer to maintain flight using PID feedback control and sensors
- Creating a drone to be used in monitoring the plane during flight time

### Western Engineering Robotics Team      Sept 2016 – Present

- Worked individually to build an autonomous bipedal walking robot
- Manually soldered surface mount components of Arduino based PCB for walking robot following various schematic circuit diagrams
- Teach new members of the club relevant skills such as soldering, reading schematic diagrams, Arduino, and C based programming

### Quality Assurance Specialist      July 2015 – Aug 2016 M&R Automation Ontario

- Inspection of parts to ensure that engineering specifications were met
- Used mills to machine parts for use in automated assembly lines
- Constructed mechanical subassemblies used in the main assembly
- Used knowledge of CAD modelling, Solidworks software, and geometry to assist machinists in fabrication of complicated parts

## PROJECTS

### Stark      April 2017

- Fully custom autonomous robot modelled in Solidworks and programmed using an Arduino microcontroller platform
- Utilises custom-made laser cut and 3D printed motor driven rack and pinion forklift system to remove obstructions and pick up objects

### Jarvis      February 2017

- Arduino based autonomous line tracking robot which uses three light sensors to follow a track and a servo controlled claw effector with a mounted photoresistor to move light emitting obstructions

## EDUCATION

### Western University Mechatronic Systems Engineering (BESc) 2015 – 2019

### Certified Solidworks Associate 2017

## TECHNICAL SKILLS

### Programming languages:

Arduino • C++ • Java  
JavaScript • HTML • CSS • C

### Tools:

Git • Visual Studio • Microsoft  
Office • Microcap • Eagle  
Solidworks • MATLAB  
Quartus • Processing • p5.js

### Laboratory instruments:

Soldering irons • Shop  
Machinery (mills, lathes,  
sanders, etc.) • Multimeter  
Oscilloscope • Protoboards

## COURSE WORK

Programming Fundamentals  
Mechatronics Systems Design  
Electrical Instrumentation  
Kinetic Analysis of Machines  
Electric Machine Analysis  
Control Systems Design  
AC and DC Circuit Analysis  
Material Selection and Design  
Finite Element Methods  
Microprocessor Selection

## CLUBS

DECA Western University  
Sign Language Association  
Western Magic Association  
Western Automotive Society