

Digital Signal Processing

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Abstract—This manual provides a simple introduction to digital signal processing.

1 SOFTWARE INSTALLATION

Run the following commands

```
sudo apt-get update
sudo apt-get install libffi-dev libsndfile1 python3
-sciipy python3-numpy python3-matplotlib
sudo pip install cffi pysoundfile
```

2 DIGITAL FILTER

2.1 Download the sound file using

```
$ wget https://github.com/prajwal-3-14159/
EE3900_ma20btech11013/blob/main/
filter/sound_files/
filter_codes_Sound_Noise.wav
```

2.2 You will find a spectrogram at <https://academo.org/demos/spectrum-analyzer>. Upload the sound file that you downloaded in Problem 2.1 in the spectrogram and play. Observe the spectrogram. What do you find?

Solution: There are a lot of yellow lines between 440 Hz to 5.1 KHz. These represent the

synthesizer key tones. Also, the key strokes are audible along with background noise.

2.3 Write the python code for removal of out of band noise and execute the code.

Solution: Download the source code for the given problem from the link

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/problem_2-3.py
```

2.4 The output of the python script in Problem 2.3 is the audio file Sound_With_ReducedNoise.wav. Play the file in the spectrogram in Problem 2.2. What do you observe?

Solution: The key strokes as well as background noise is subdued in the audio. Also, the signal is blank for frequencies above 5.1 kHz.

3 DIFFERENCE EQUATION

3.1 Let

$$x(n) = \left\{ \underset{\uparrow}{1}, 2, 3, 4, 2, 1 \right\} \quad (3.1)$$

Sketch $x(n)$.

3.2 Let

$$y(n) + \frac{1}{2}y(n-1) = x(n) + x(n-2),$$

$$y(n) = 0, n < 0 \quad (3.2)$$

Sketch $y(n)$.

Solution: The C code for calculating the $y(n)$.

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/problem3-1_in_C/problem3_1.c
```

The python code for plotting the Fig. (3.1).

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
```


Solution:

$$a^n u(n) \stackrel{Z}{=} \sum_{n=0}^{\infty} (az^{-1})^n \quad (4.21)$$

$$= \frac{1}{1 - az^{-1}} \quad |z| > |a| \quad (4.22)$$

4.5 Let

$$H(e^{j\omega}) = H(z = e^{j\omega}). \quad (4.23)$$

Plot $|H(e^{j\omega})|$. Comment. $H(e^{j\omega})$ is known as the *Discrete Time Fourier Transform* (DTFT) of $h(n)$.

Solution: The following code plots the Fig. (4.1).

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/problem_5-2.py
```

Using (4.13), we observe that $|H(e^{j\omega})|$ is given by

$$|H(e^{j\omega})| = \left| \frac{1 + e^{-2j\omega}}{1 + \frac{1}{2}e^{-j\omega}} \right| \quad (4.24)$$

$$= \sqrt{\frac{(1 + \cos 2\omega)^2 + (\sin 2\omega)^2}{\left(1 + \frac{1}{2} \cos \omega\right)^2 + \left(\frac{1}{2} \sin \omega\right)^2}} \quad (4.25)$$

$$= \sqrt{\frac{2(1 + \cos 2\omega)}{\frac{5}{4} + \cos \omega}} \quad (4.26)$$

$$= \sqrt{\frac{2(2 \cos^2 \omega)}{\frac{5}{4} + \cos \omega}} \quad (4.27)$$

$$= \frac{4|\cos \omega|}{\sqrt{5 + 4 \cos \omega}} \quad (4.28)$$

Thus,

$$\left| H(e^{j(\omega+2\pi)}) \right| = \frac{4|\cos(\omega + 2\pi)|}{\sqrt{5 + 4 \cos(\omega + 2\pi)}} \quad (4.29)$$

$$= \frac{4|\cos \omega|}{\sqrt{5 + 4 \cos \omega}} \quad (4.30)$$

$$= |H(e^{j\omega})| \quad (4.31)$$

and so its fundamental period is 2π .

4.6 Express $h(n)$ in terms of $H(e^{j\omega})$.

Solution: We have,

$$H(e^{j\omega}) = \sum_{k=-\infty}^{\infty} h(k)e^{-j\omega k} \quad (4.32)$$

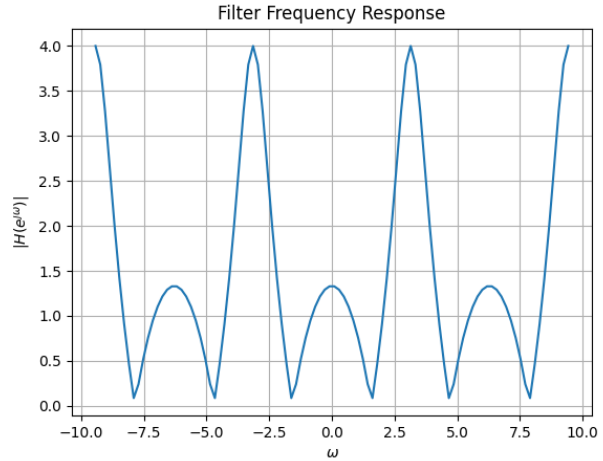


Fig. 4.1: Plot of $|H(e^{j\omega})|$ against ω

However,

$$\int_{-\pi}^{\pi} e^{j\omega(n-k)} d\omega = \begin{cases} 2\pi & n = k \\ 0 & \text{otherwise} \end{cases} \quad (4.33)$$

and so,

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} H(e^{j\omega}) e^{j\omega n} d\omega \quad (4.34)$$

$$= \frac{1}{2\pi} \sum_{k=-\infty}^{\infty} \int_{-\pi}^{\pi} h(k) e^{j\omega(n-k)} d\omega \quad (4.35)$$

$$= \frac{1}{2\pi} 2\pi h(n) = h(n) \quad (4.36)$$

which is known as the Inverse Discrete Fourier Transform. Thus,

$$h(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} H(e^{j\omega}) e^{j\omega n} d\omega \quad (4.37)$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{1 + e^{-2j\omega}}{1 + \frac{1}{2}e^{-j\omega}} e^{j\omega n} d\omega \quad (4.38)$$

5 IMPULSE RESPONSE

5.1 Using long division, compute $h(n)$ for $n < 5$ from $H(z)$.

Solution: We substitute $x := z^{-1}$, and write

$$\begin{array}{r} \frac{1}{2}x + 1 \bigg) \frac{2x - 4}{x^2 + 1} \\ \underline{-x^2 - 2x} \\ -2x + 1 \\ \underline{2x + 4} \\ 5 \end{array}$$

So,

$$H(z) = -4 + 2z^{-1} + \frac{5}{1 + \frac{1}{2}z^{-1}} \quad (5.1)$$

$$= -4 + 2z^{-1} + 5 \sum_{n=0}^{\infty} \left(-\frac{1}{2}\right)^n z^{-n} \quad (5.2)$$

$$= 1 - \frac{1}{2}z^{-1} + 5 \sum_{n=2}^{\infty} \left(-\frac{1}{2}\right)^n z^{-n} \quad (5.3)$$

Now,

$$= \sum_{n=0}^{\infty} \left(-\frac{1}{2}\right)^n z^{-n} + 4 \sum_{n=2}^{\infty} \left(-\frac{1}{2}\right)^n z^{-n} \quad (5.4)$$

$$= \sum_{n=-\infty}^{\infty} u(n) \left(-\frac{1}{2}\right)^n z^{-n} + \sum_{n=-\infty}^{\infty} u(n-2) \left(-\frac{1}{2}\right)^{n-2} z^{-n} \quad (5.5)$$

Therefore, from (4.1),

$$h(n) = \left(-\frac{1}{2}\right)^n u(n) + \left(-\frac{1}{2}\right)^{n-2} u(n-2) \quad (5.6)$$

5.2 Find an expression for $h(n)$ using $H(z)$, given that

$$h(n) \stackrel{\mathcal{Z}}{=} H(z) \quad (5.7)$$

and there is a one to one relationship between $h(n)$ and $H(z)$. $h(n)$ is known as the *impulse response* of the system defined by (3.2).

Solution: From (4.13),

$$H(z) = \frac{1}{1 + \frac{1}{2}z^{-1}} + \frac{z^{-2}}{1 + \frac{1}{2}z^{-1}} \quad (5.8)$$

$$\Rightarrow h(n) = \left(-\frac{1}{2}\right)^n u(n) + \left(-\frac{1}{2}\right)^{n-2} u(n-2) \quad (5.9)$$

using (4.20) and (4.7).

5.3 Sketch $h(n)$. Is it bounded? Convergent?

Solution: The following code plots the Fig. (5.1).

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/problem_5-2.py
```

We see that $h(n)$ is bounded. For large n , we

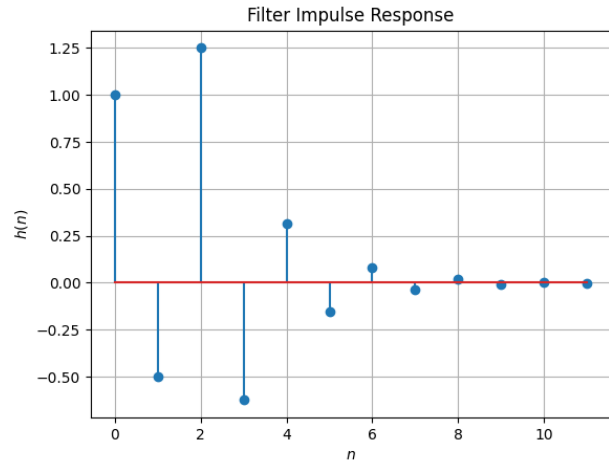


Fig. 5.1: $h(n)$ as the inverse of $H(z)$

see that

$$h(n) = \left(-\frac{1}{2}\right)^n + \left(-\frac{1}{2}\right)^{n-2} \quad (5.10)$$

$$= \left(-\frac{1}{2}\right)^n (4 + 1) = 5 \left(-\frac{1}{2}\right)^n \quad (5.11)$$

$$\Rightarrow \left| \frac{h(n+1)}{h(n)} \right| = \frac{1}{2} \quad (5.12)$$

and therefore, $\lim_{n \rightarrow \infty} \left| \frac{h(n+1)}{h(n)} \right| = \frac{1}{2} < 1$. Hence, we see that $h(n)$ converges.

5.4 The system with $h(n)$ is defined to be stable if

$$\sum_{n=-\infty}^{\infty} h(n) < \infty \quad (5.13)$$

Is the system defined by (3.2) stable for the impulse response in (5.7)?

Solution: Note that

$$\sum_{n=-\infty}^{\infty} h(n) = \sum_{n=-\infty}^{\infty} \left(-\frac{1}{2}\right)^n u(n) + \left(-\frac{1}{2}\right)^{n-2} u(n-2) \quad (5.14)$$

$$= 2 \left(\frac{1}{1 + \frac{1}{2}} \right) = \frac{4}{3} \quad (5.15)$$

Hence, the given system is stable. The limit is verified at

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/problem_5-3.py
```

5.5 Compute and sketch $h(n)$ using

$$h(n) + \frac{1}{2}h(n-1) = \delta(n) + \delta(n-2), \quad (5.16)$$

This is the definition of $h(n)$.

Solution: The following code plots the Fig. (5.2). Note, it is the same as Fig. (5.1).

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/problem_5-4.py
```

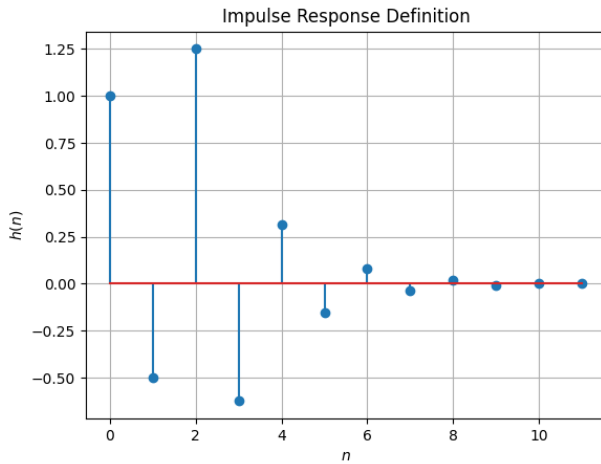


Fig. 5.2: $h(n)$ as the inverse of $H(z)$

5.6 Compute

$$y(n) = x(n) * h(n) = \sum_{k=-\infty}^{\infty} x(k)h(n-k) \quad (5.17)$$

Comment. The operation in (5.17) is known as *convolution*.

Solution: The following code plots Fig. (5.3). Note that this is the same as $y(n)$ in Fig. (3.1).

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/problem_5-5.py
```

We use Toeplitz matrices for convolution

$$\mathbf{y} = \mathbf{x} \otimes \mathbf{h} \quad (5.18)$$

$$\mathbf{y} = \begin{pmatrix} h_1 & 0 & \cdot & \cdot & \cdot & 0 \\ h_2 & h_1 & \cdot & \cdot & \cdot & 0 \\ h_3 & h_2 & h_1 & \cdot & \cdot & 0 \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & \cdot & \cdot & h_3 & h_2 & h_1 \\ 0 & \cdot & \cdot & \cdot & h_2 & h_1 \\ 0 & \cdot & \cdot & \cdot & 0 & h_1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \quad (5.19)$$

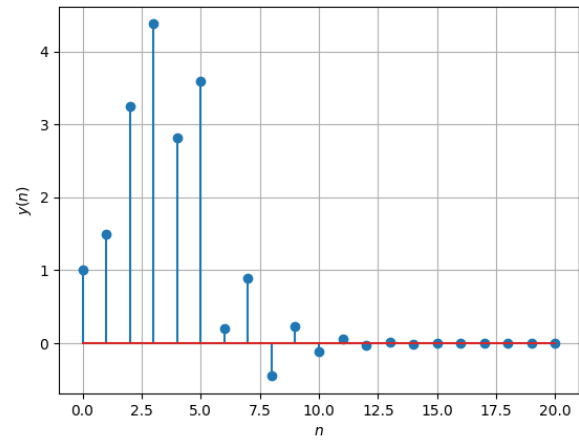


Fig. 5.3: $y(n)$ from the definition

5.7 Show that

$$y(n) = \sum_{k=-\infty}^{\infty} x(n-k)h(k) \quad (5.20)$$

Solution: From (5.17), we substitute $k := n-k$ to get

$$y(n) = \sum_{k=-\infty}^{\infty} x(k)h(n-k) \quad (5.21)$$

$$= \sum_{n-k=-\infty}^{\infty} x(n-k)h(k) \quad (5.22)$$

$$= \sum_{k=-\infty}^{\infty} x(n-k)h(k) \quad (5.23)$$

6 DFT AND FFT

6.1 Compute

$$X(k) \triangleq \sum_{n=0}^{N-1} x(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1 \quad (6.1)$$

and $H(k)$ using $h(n)$.

6.2 Compute

$$Y(k) = X(k)H(k) \quad (6.2)$$

6.3 Compute

$$y(n) = \frac{1}{N} \sum_{k=0}^{N-1} Y(k) \cdot e^{j2\pi kn/N}, \quad n = 0, 1, \dots, N-1 \quad (6.3)$$

Solution: The following code plots Fig. (6.1) and computes $X(k)$ and $Y(k)$. Note that this is the same as $y(n)$ in Fig. (3.1).

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/problem_6-3.py
```

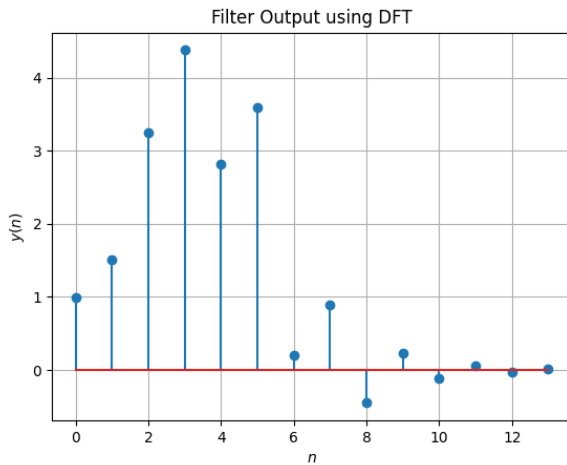


Fig. 6.1: $y(n)$ from the DFT

6.4 Repeat the previous exercise by computing $X(k)$, $H(k)$ and $y(n)$ through FFT and IFFT.

Solution: Download the code from

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/problem_6-4.py
```

Observe that Fig. (6.2) is the same as $y(n)$ in Fig. (3.1).

6.5 Wherever possible, express all the above equations as matrix equations.

Solution: We use the DFT Matrix, where $\omega =$

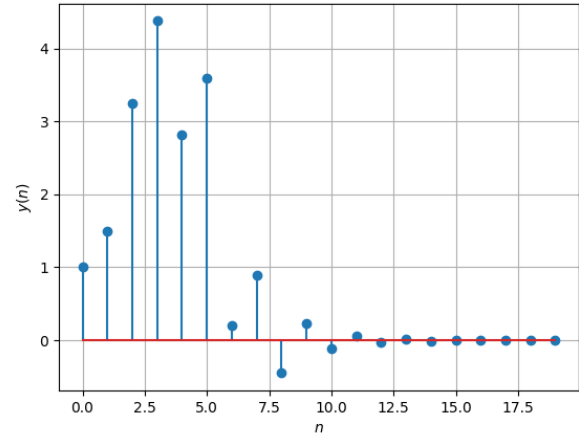


Fig. 6.2: $y(n)$ using FFT and IFFT

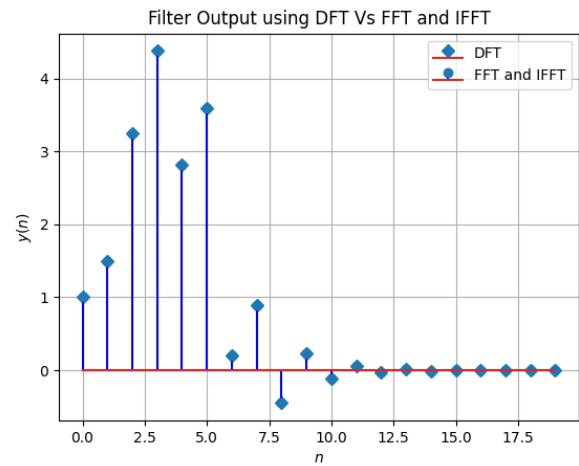


Fig. 6.3: $y(n)$ by DFT vs FFT and IFFT

$e^{-\frac{j2k\pi}{N}}$, which is given by

$$\mathbf{W} = \begin{pmatrix} \omega^0 & \omega^0 & \dots & \omega^0 \\ \omega^0 & \omega^1 & \dots & \omega^{N-1} \\ \vdots & \vdots & \ddots & \vdots \\ \omega^0 & \omega^{N-1} & \dots & \omega^{(N-1)(N-1)} \end{pmatrix} \quad (6.4)$$

i.e. $W_{jk} = \omega^{jk}$, $0 \leq j, k < N$. Hence, we can write any DFT equation as

$$\mathbf{X} = \mathbf{W}\mathbf{x} = \mathbf{x}\mathbf{W} \quad (6.5)$$

where

$$\mathbf{x} = \begin{pmatrix} x(0) \\ x(1) \\ \vdots \\ x(n-1) \end{pmatrix} \quad (6.6)$$

Using (6.3), the inverse Fourier Transform is given by

$$\mathbf{x} = \mathcal{F}^{-1}(\mathbf{X}) = \mathbf{W}^{-1}\mathbf{X} = \frac{1}{N}\mathbf{W}^H\mathbf{X} = \frac{1}{N}\mathbf{X}\mathbf{W}^H \quad (6.7)$$

$$\Rightarrow \mathbf{W}^{-1} = \frac{1}{N}\mathbf{W}^H \quad (6.8)$$

where H denotes hermitian operator. We can rewrite (6.2) using the element-wise multiplication operator as

$$\mathbf{Y} = \mathbf{H} \cdot \mathbf{X} = (\mathbf{W}\mathbf{h}) \cdot (\mathbf{W}\mathbf{x}) \quad (6.9)$$

The plot of $y(n)$ using the DFT matrix in Fig. (6.4) is the same as $y(n)$ in Fig. (3.1). Download the code using

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/problem_6-5.py
```

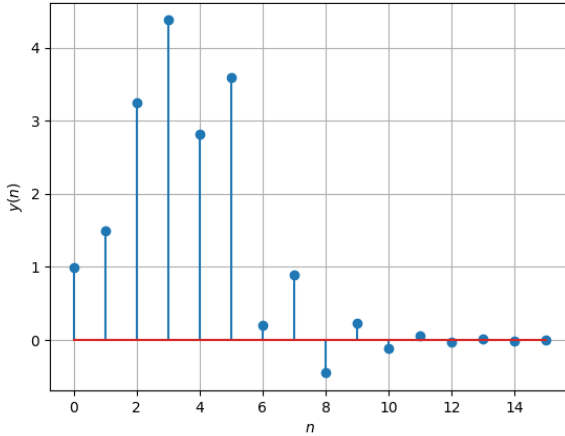


Fig. 6.4: $y(n)$ using the DFT matrix

7 FFT

7.1. The DFT of $x(n)$ is given by

$$X(k) \triangleq \sum_{n=0}^{N-1} x(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1 \quad (7.1)$$

7.2. Let

$$W_N = e^{-j2\pi/N} \quad (7.2)$$

Then the N -point DFT matrix is defined as

$$\mathbf{F}_N = [W_N^{mn}], \quad 0 \leq m, n \leq N-1 \quad (7.3)$$

where W_N^{mn} are the elements of \mathbf{F}_N .

7.3. Let

$$\mathbf{I}_4 = \begin{pmatrix} \mathbf{e}_4^1 & \mathbf{e}_4^2 & \mathbf{e}_4^3 & \mathbf{e}_4^4 \end{pmatrix} \quad (7.4)$$

be the 4×4 identity matrix. Then the 4 point DFT permutation matrix is defined as

$$\mathbf{P}_4 = \begin{pmatrix} \mathbf{e}_4^1 & \mathbf{e}_4^3 & \mathbf{e}_4^2 & \mathbf{e}_4^4 \end{pmatrix} \quad (7.5)$$

7.4. The 4 point DFT diagonal matrix is defined as

$$\mathbf{D}_4 = \text{diag}(W_8^0, W_8^1, W_8^2, W_8^3) \quad (7.6)$$

7.5. Show that

$$W_N^2 = W_{N/2} \quad (7.7)$$

Solution: We write

$$W_N^2 = \left(e^{-j\frac{2\pi}{N}}\right)^2 = e^{-j\frac{2\pi}{N/2}} = W_{N/2} \quad (7.8)$$

7.6. Show that

$$\mathbf{F}_4 = \begin{bmatrix} \mathbf{I}_2 & \mathbf{D}_2 \\ \mathbf{I}_2 & -\mathbf{D}_2 \end{bmatrix} \begin{bmatrix} \mathbf{F}_2 & 0 \\ 0 & \mathbf{F}_2 \end{bmatrix} \mathbf{P}_4 \quad (7.9)$$

Solution: Observe that for $n \in \mathbb{N}$, $W_4^{4n} = 1$ and $W_4^{4n+2} = -1$. Using (7.7),

$$\mathbf{D}_2 \mathbf{F}_2 = \begin{bmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{bmatrix} \begin{bmatrix} W_2^0 & W_2^1 \\ W_2^2 & W_2^3 \end{bmatrix} \quad (7.10)$$

$$= \begin{bmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{bmatrix} \begin{bmatrix} W_4^0 & W_4^1 \\ W_4^2 & W_4^3 \end{bmatrix} \quad (7.11)$$

$$= \begin{bmatrix} W_4^0 & W_4^0 \\ W_4^1 & W_4^3 \end{bmatrix} \quad (7.12)$$

$$\Rightarrow -\mathbf{D}_2 \mathbf{F}_2 = \begin{bmatrix} W_4^2 & W_4^6 \\ W_4^3 & W_4^9 \end{bmatrix} \quad (7.13)$$

and

$$\mathbf{F}_2 = \begin{pmatrix} W_2^0 & W_2^0 \\ W_2^0 & W_2^1 \end{pmatrix} \quad (7.14)$$

$$= \begin{pmatrix} W_4^0 & W_4^0 \\ W_4^0 & W_4^2 \end{pmatrix} \quad (7.15)$$

Hence,

$$\mathbf{W}_4 = \begin{pmatrix} W_4^0 & W_4^0 & W_4^0 & W_4^0 \\ W_4^0 & W_4^2 & W_4^1 & W_4^3 \\ W_4^0 & W_4^4 & W_4^2 & W_4^6 \\ W_4^0 & W_4^4 & W_4^3 & W_4^9 \end{pmatrix} \quad (7.16)$$

$$= \begin{bmatrix} \mathbf{I}_2 \mathbf{F}_2 & \mathbf{D}_2 \mathbf{F}_2 \\ \mathbf{I}_2 \mathbf{F}_2 & -\mathbf{D}_2 \mathbf{F}_2 \end{bmatrix} \quad (7.17)$$

$$= \begin{bmatrix} \mathbf{I}_2 & \mathbf{D}_2 \\ \mathbf{I}_2 & \mathbf{D}_2 \end{bmatrix} \begin{bmatrix} \mathbf{F}_2 & 0 \\ 0 & \mathbf{F}_2 \end{bmatrix} \quad (7.18)$$

Multiplying (7.18) by \mathbf{P}_4 on both sides, and noting that $\mathbf{W}_4 \mathbf{P}_4 = \mathbf{F}_4$ gives us (7.9).

7.7. Show that

$$\mathbf{F}_N = \begin{bmatrix} \mathbf{I}_{N/2} & \mathbf{D}_{N/2} \\ \mathbf{I}_{N/2} & -\mathbf{D}_{N/2} \end{bmatrix} \begin{bmatrix} \mathbf{F}_{N/2} & 0 \\ 0 & \mathbf{F}_{N/2} \end{bmatrix} \mathbf{P}_N \quad (7.19)$$

Solution: Observe that for even N and letting \mathbf{f}_N^i denote the i^{th} column of \mathbf{F}_N , from (7.12) and (7.13),

$$\begin{pmatrix} \mathbf{D}_{N/2} \mathbf{F}_{N/2} \\ -\mathbf{D}_{N/2} \mathbf{F}_{N/2} \end{pmatrix} = \begin{pmatrix} \mathbf{f}_N^2 & \mathbf{f}_N^4 & \dots & \mathbf{f}_N^N \end{pmatrix} \quad (7.20)$$

and

$$\begin{pmatrix} \mathbf{I}_{N/2} \mathbf{F}_{N/2} \\ \mathbf{I}_{N/2} \mathbf{F}_{N/2} \end{pmatrix} = \begin{pmatrix} \mathbf{f}_N^1 & \mathbf{f}_N^3 & \dots & \mathbf{f}_N^{N-1} \end{pmatrix} \quad (7.21) \quad 7.10.$$

Thus,

$$\begin{bmatrix} \mathbf{I}_2 \mathbf{F}_2 & \mathbf{D}_2 \mathbf{F}_2 \\ \mathbf{I}_2 \mathbf{F}_2 & -\mathbf{D}_2 \mathbf{F}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{I}_{N/2} & \mathbf{D}_{N/2} \\ \mathbf{I}_{N/2} & -\mathbf{D}_{N/2} \end{bmatrix} \begin{bmatrix} \mathbf{F}_{N/2} & 0 \\ 0 & \mathbf{F}_{N/2} \end{bmatrix} \\ = \begin{pmatrix} \mathbf{f}_N^1 & \dots & \mathbf{f}_N^{N-1} & \mathbf{f}_N^2 & \dots & \mathbf{f}_N^N \end{pmatrix} \quad (7.22)$$

and so,

$$\begin{bmatrix} \mathbf{I}_{N/2} & \mathbf{D}_{N/2} \\ \mathbf{I}_{N/2} & -\mathbf{D}_{N/2} \end{bmatrix} \begin{bmatrix} \mathbf{F}_{N/2} & 0 \\ 0 & \mathbf{F}_{N/2} \end{bmatrix} \mathbf{P}_N \\ = \begin{pmatrix} \mathbf{f}_N^1 & \mathbf{f}_N^2 & \dots & \mathbf{f}_N^N \end{pmatrix} = \mathbf{F}_N \quad (7.23)$$

7.8. Find

$$\mathbf{P}_4 \mathbf{x} \quad (7.24)$$

Solution: We have,

$$\mathbf{P}_4 \mathbf{x} = \begin{pmatrix} \mathbf{e}_4^1 & \mathbf{e}_4^3 & \mathbf{e}_4^2 & \mathbf{e}_4^4 \end{pmatrix} \begin{pmatrix} x(0) \\ x(1) \\ x(2) \\ x(3) \end{pmatrix} = \begin{pmatrix} x(0) \\ x(2) \\ x(1) \\ x(3) \end{pmatrix} \quad (7.25)$$

7.9. Show that

$$\mathbf{X} = \mathbf{F}_N \mathbf{x} \quad (7.26)$$

where \mathbf{x}, \mathbf{X} are the vector representations of $x(n), X(k)$ respectively.

Solution: Writing the terms of X ,

$$X(0) = x(0) + x(1) + \dots + x(N-1) \quad (7.27)$$

$$X(1) = x(0) + x(1)e^{-\frac{j2\pi}{N}} + \dots + x(N-1)e^{-\frac{j2(N-1)\pi}{N}} \quad (7.28)$$

\vdots

$$X(N-1) = x(0) + x(1)e^{-\frac{j2(N-1)\pi}{N}} + \dots + x(N-1)e^{-\frac{j2(N-1)(N-1)\pi}{N}} \quad (7.29)$$

Clearly, the term in the m^{th} row and n^{th} column is given by ($0 \leq m \leq N-1$ and $0 \leq n \leq N-1$)

$$T_{mn} = x(n)e^{-\frac{j2mn\pi}{N}} \quad (7.30)$$

and so, we can represent each of these terms as a matrix product

$$\mathbf{X} = \mathbf{F}_N \mathbf{x} \quad (7.31)$$

where $\mathbf{F}_N = \left[e^{-\frac{j2mn\pi}{N}} \right]_{mn}$ for $0 \leq m \leq N-1$ and $0 \leq n \leq N-1$.

7.10. Derive the following Step-by-step visualisation of 8-point FFTs into 4-point FFTs and so on

$$\begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ X(3) \end{bmatrix} = \begin{bmatrix} X_1(0) \\ X_1(1) \\ X_1(2) \\ X_1(3) \end{bmatrix} + \begin{bmatrix} W_8^0 & 0 & 0 & 0 \\ 0 & W_8^1 & 0 & 0 \\ 0 & 0 & W_8^2 & 0 \\ 0 & 0 & 0 & W_8^3 \end{bmatrix} \begin{bmatrix} X_2(0) \\ X_2(1) \\ X_2(2) \\ X_2(3) \end{bmatrix} \quad (7.32)$$

$$\begin{bmatrix} X(4) \\ X(5) \\ X(6) \\ X(7) \end{bmatrix} = \begin{bmatrix} X_1(0) \\ X_1(1) \\ X_1(2) \\ X_1(3) \end{bmatrix} - \begin{bmatrix} W_8^0 & 0 & 0 & 0 \\ 0 & W_8^1 & 0 & 0 \\ 0 & 0 & W_8^2 & 0 \\ 0 & 0 & 0 & W_8^3 \end{bmatrix} \begin{bmatrix} X_2(0) \\ X_2(1) \\ X_2(2) \\ X_2(3) \end{bmatrix} \quad (7.33)$$

4-point FFTs into 2-point FFTs

$$\begin{bmatrix} X_1(0) \\ X_1(1) \end{bmatrix} = \begin{bmatrix} X_3(0) \\ X_3(1) \end{bmatrix} + \begin{bmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{bmatrix} \begin{bmatrix} X_4(0) \\ X_4(1) \end{bmatrix} \quad (7.34)$$

$$\begin{bmatrix} X_1(2) \\ X_1(3) \end{bmatrix} = \begin{bmatrix} X_3(0) \\ X_3(1) \end{bmatrix} - \begin{bmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{bmatrix} \begin{bmatrix} X_4(0) \\ X_4(1) \end{bmatrix} \quad (7.35)$$

$$\begin{bmatrix} X_2(0) \\ X_2(1) \end{bmatrix} = \begin{bmatrix} X_5(0) \\ X_5(1) \end{bmatrix} + \begin{bmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{bmatrix} \begin{bmatrix} X_6(0) \\ X_6(1) \end{bmatrix} \quad (7.36)$$

$$\begin{bmatrix} X_2(2) \\ X_2(3) \end{bmatrix} = \begin{bmatrix} X_5(0) \\ X_5(1) \end{bmatrix} - \begin{bmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{bmatrix} \begin{bmatrix} X_6(0) \\ X_6(1) \end{bmatrix} \quad (7.37)$$

$$P_8 \begin{bmatrix} x(0) \\ x(1) \\ x(2) \\ x(3) \\ x(4) \\ x(5) \\ x(6) \\ x(7) \end{bmatrix} = \begin{bmatrix} x(0) \\ x(2) \\ x(4) \\ x(6) \\ x(1) \\ x(3) \\ x(5) \\ x(7) \end{bmatrix} \quad (7.38)$$

$$P_4 \begin{bmatrix} x(0) \\ x(2) \\ x(4) \\ x(6) \end{bmatrix} = \begin{bmatrix} x(0) \\ x(4) \\ x(2) \\ x(6) \end{bmatrix} \quad (7.39)$$

$$P_4 \begin{bmatrix} x(1) \\ x(3) \\ x(5) \\ x(7) \end{bmatrix} = \begin{bmatrix} x(1) \\ x(5) \\ x(3) \\ x(7) \end{bmatrix} \quad (7.40)$$

Therefore,

$$\begin{bmatrix} X_3(0) \\ X_3(1) \end{bmatrix} = F_2 \begin{bmatrix} x(0) \\ x(4) \end{bmatrix} \quad (7.41)$$

$$\begin{bmatrix} X_4(0) \\ X_4(1) \end{bmatrix} = F_2 \begin{bmatrix} x(2) \\ x(6) \end{bmatrix} \quad (7.42)$$

$$\begin{bmatrix} X_5(0) \\ X_5(1) \end{bmatrix} = F_2 \begin{bmatrix} x(1) \\ x(5) \end{bmatrix} \quad (7.43)$$

$$\begin{bmatrix} X_6(0) \\ X_6(1) \end{bmatrix} = F_2 \begin{bmatrix} x(3) \\ x(7) \end{bmatrix} \quad (7.44)$$

Solution: We write out the values of performing an 8-point FFT on \mathbf{x} as follows.

$$X(k) = \sum_{n=0}^7 x(n) e^{-\frac{j2k\pi n}{8}} \quad (7.45)$$

$$= \sum_{n=0}^3 \left(x(2n) e^{-\frac{j2k\pi n}{4}} + e^{-\frac{j2k\pi}{8}} x(2n+1) e^{-\frac{j2k\pi n}{4}} \right) \quad (7.46)$$

$$= X_1(k) + e^{-\frac{j2k\pi}{4}} X_2(k) \quad (7.47)$$

where \mathbf{X}_1 is the 4-point FFT of the even-numbered terms and \mathbf{X}_2 is the 4-point FFT of the odd numbered terms. Noticing that for $k \geq 4$,

$$X_1(k) = X_1(k-4) \quad (7.48)$$

$$e^{-\frac{j2k\pi}{8}} = -e^{-\frac{j2(k-4)\pi}{8}} \quad (7.49)$$

we can now write out $X(k)$ in matrix form as in (7.32) and (7.33). We also need to solve the

two 4-point FFT terms so formed.

$$X_1(k) = \sum_{n=0}^3 x_1(n) e^{-\frac{j2k\pi n}{8}} \quad (7.50)$$

$$= \sum_{n=0}^1 \left(x_1(2n) e^{-\frac{j2k\pi n}{4}} + e^{-\frac{j2k\pi}{8}} x_2(2n+1) e^{-\frac{j2k\pi n}{4}} \right) \quad (7.51)$$

$$= X_3(k) + e^{-\frac{j2k\pi}{4}} X_4(k) \quad (7.52)$$

using $x_1(n) = x(2n)$ and $x_2(n) = x(2n+1)$. Thus we can write the 2-point FFTs

$$\begin{bmatrix} X_3(0) \\ X_3(1) \end{bmatrix} = F_2 \begin{bmatrix} x(0) \\ x(4) \end{bmatrix} \quad (7.53)$$

$$\begin{bmatrix} X_4(0) \\ X_4(1) \end{bmatrix} = F_2 \begin{bmatrix} x(2) \\ x(6) \end{bmatrix} \quad (7.54)$$

Using a similar idea for the terms X_2 ,

$$\begin{bmatrix} X_5(0) \\ X_5(1) \end{bmatrix} = F_2 \begin{bmatrix} x(1) \\ x(5) \end{bmatrix} \quad (7.55)$$

$$\begin{bmatrix} X_6(0) \\ X_6(1) \end{bmatrix} = F_2 \begin{bmatrix} x(3) \\ x(7) \end{bmatrix} \quad (7.56)$$

But observe that from (7.25),

$$\mathbf{P}_8 \mathbf{x} = \begin{pmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{pmatrix} \quad (7.57)$$

$$\mathbf{P}_4 \mathbf{x}_1 = \begin{pmatrix} \mathbf{x}_3 \\ \mathbf{x}_4 \end{pmatrix} \quad (7.58)$$

$$\mathbf{P}_4 \mathbf{x}_2 = \begin{pmatrix} \mathbf{x}_5 \\ \mathbf{x}_6 \end{pmatrix} \quad (7.59)$$

where we define $x_3(k) = x(4k)$, $x_4(k) = x(4k+2)$, $x_5(k) = x(4k+1)$, and $x_6(k) = x(4k+3)$ for $k = 0, 1$.

For

$$\mathbf{x} = \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 2 \\ 1 \end{pmatrix} \quad (7.60)$$

compute the DFT using (7.26)

Solution: Download the Python code from

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/problem_7-11.py
```

and run it using

```
$ python3 problem_7-11.py
```

7.12. Repeat the above exercise using the FFT after zero padding x .

7.13. Write a C program to compute the 8-point FFT.
Solution: The C code for the above two problems can be downloaded from

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/8pt_fft.c
```

8 EXERCISES

Answer the following questions by looking at the python code in Problem 2.3.

8.1 The command

```
output_signal = signal.lfilter(b, a,
input_signal)
```

in Problem 2.3 is executed through the following difference equation

$$\sum_{m=0}^M a(m)y(n-m) = \sum_{k=0}^N b(k)x(n-k) \quad (8.1)$$

where the input signal is $x(n)$ and the output signal is $y(n)$ with initial values all 0. Replace **signal.filtfilt** with your own routine and verify.

Solution: The implementation is at

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/problem_8-1.py
```

8.2 Repeat all the exercises in the previous sections for the above a and b .

Solution: For the given values, the difference

equation is

$$\begin{aligned} y(n) - (4.44)y(n-1) + (8.78)y(n-2) \\ - (9.93)y(n-3) + (6.90)y(n-4) \\ - (2.93)y(n-5) + (0.70)y(n-6) \\ - (0.07)y(n-7) = (5.02 \times 10^{-5})x(n) \\ + (3.52 \times 10^{-4})x(n-1) + (1.05 \times 10^{-3})x(n-2) \\ + (1.76 \times 10^{-3})x(n-3) + (1.76 \times 10^{-3})x(n-4) \\ + (1.05 \times 10^{-3})x(n-5) + (3.52 \times 10^{-4})x(n-6) \\ + (5.02 \times 10^{-5})x(n-7) \end{aligned} \quad (8.2)$$

From (8.1), we see that the transfer function can be written as follows

$$H(z) = \frac{\sum_{k=0}^N b(k)z^{-k}}{\sum_{k=0}^M a(k)z^{-k}} \quad (8.3)$$

$$= \sum_i \frac{r(i)}{1 - p(i)z^{-1}} + \sum_j k(j)z^{-j} \quad (8.4)$$

where $r(i)$, $p(i)$, are called residues and poles respectively of the partial fraction expansion of $H(z)$. $k(i)$ are the coefficients of the direct polynomial terms that might be left over. We can now take the inverse z -transform of (8.4) and get using (4.20),

$$h(n) = \sum_i r(i)[p(i)]^n u(n) + \sum_j k(j)\delta(n-j) \quad (8.5)$$

Substituting the values,

$$\begin{aligned} h(n) = & [(2.76)(0.55)^n \\ & + (-1.05 - 1.84j)(0.57 + 0.16j)^n \\ & + (-1.05 + 1.84j)(0.57 - 0.16j)^n \\ & + (-0.53 + 0.08j)(0.63 + 0.32j)^n \\ & + (-0.53 - 0.08j)(0.63 - 0.32j)^n \\ & + (0.20 + 0.004j)(0.75 + 0.47j)^n \\ & + (0.20 - 0.004j)(0.75 - 0.47j)^n]u(n) \\ & + (-6.81 \times 10^{-4})\delta(n) \end{aligned} \quad (8.6)$$

The values $r(i)$, $p(i)$, $k(i)$ and thus the impulse response function are computed and plotted at

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/problem_8-2-1.py
```

The filter frequency response is plotted at

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/problem_8-2-2.py
```

Observe that for a series $t_n = r^n$, $\frac{t_{n+1}}{t_n} = r$. By the ratio test, t_n converges if $|r| < 1$. We note that observe that $|p(i)| < 1$ and so, as $h(n)$ is the sum of convergent series, we see that $h(n)$ converges. From Fig. (8.1), it is clear that $h(n)$ is bounded. From (4.1),

$$\sum_{n=0}^{\infty} h(n) = H(1) = 1 < \infty \quad (8.7)$$

Therefore, the system is stable. From Fig. (8.1), $h(n)$ is negligible after $n \geq 64$, and we can apply a 64-bit FFT to get $y(n)$. The following code uses the DFT matrix to generate $y(n)$ in Fig. (8.3).

```
$ wget https://raw.githubusercontent.com/
prajwal-3-14159/
EE3900_ma20btech11013/main/filter/
codes/problem_8-2-3.py
```

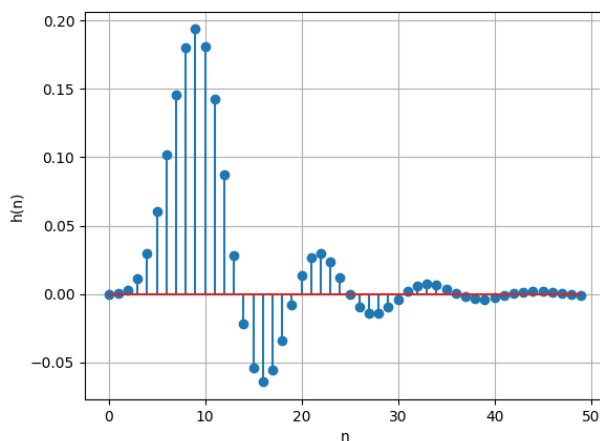


Fig. 8.1: Plot of $h(n)$

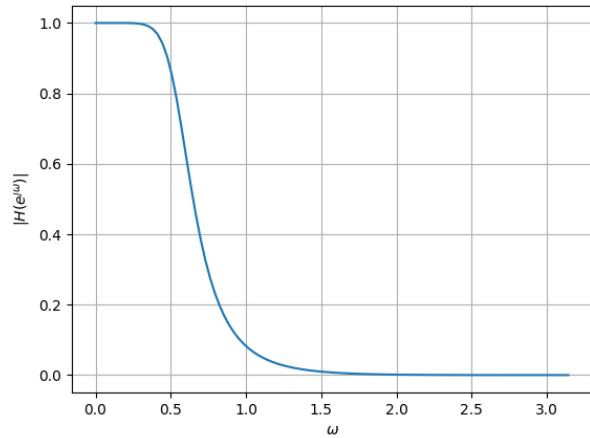


Fig. 8.2: Filter frequency response

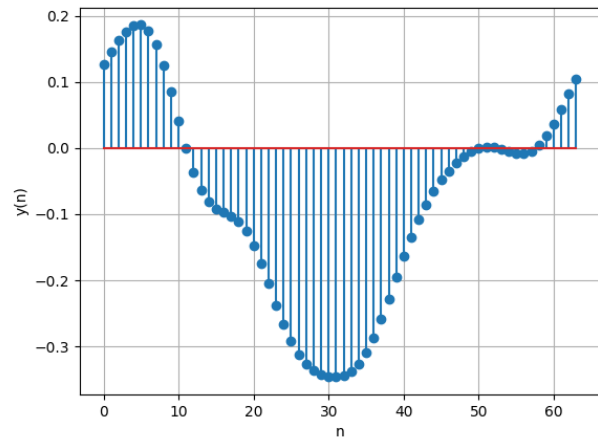


Fig. 8.3: Plot of $y(n)$

8.5 Modifying the code with different input parameters and to get the best possible output.

Solution: A better filtering was found on setting the order of the filter to be 7.

8.3 What is the sampling frequency of the input signal?

Solution: Sampling frequency $f_s = 44.1$ kHz.

8.4 What is type, order and cutoff frequency of the above Butterworth filter?

Solution: The given Butterworth filter is low pass with order 4 and cutoff frequency 4 kHz.